

## ***CHAPTER 1***

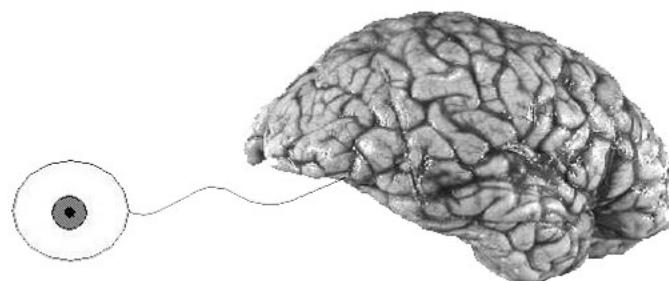
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# **VISUAL PERCEPTION AND IMAGE REPRESENTATION**

# ***Visual Perception***

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- The Human Visual System (HVS)
  - Vision is our most powerful sense
  - Enables us to gather information and learn through observation
  - Allows to interact with the environment without any physical contact
  - HVS consists of two primary components
    - The eye (receiving sensor)
    - The brain (processor)Both are connected by the optic nerve

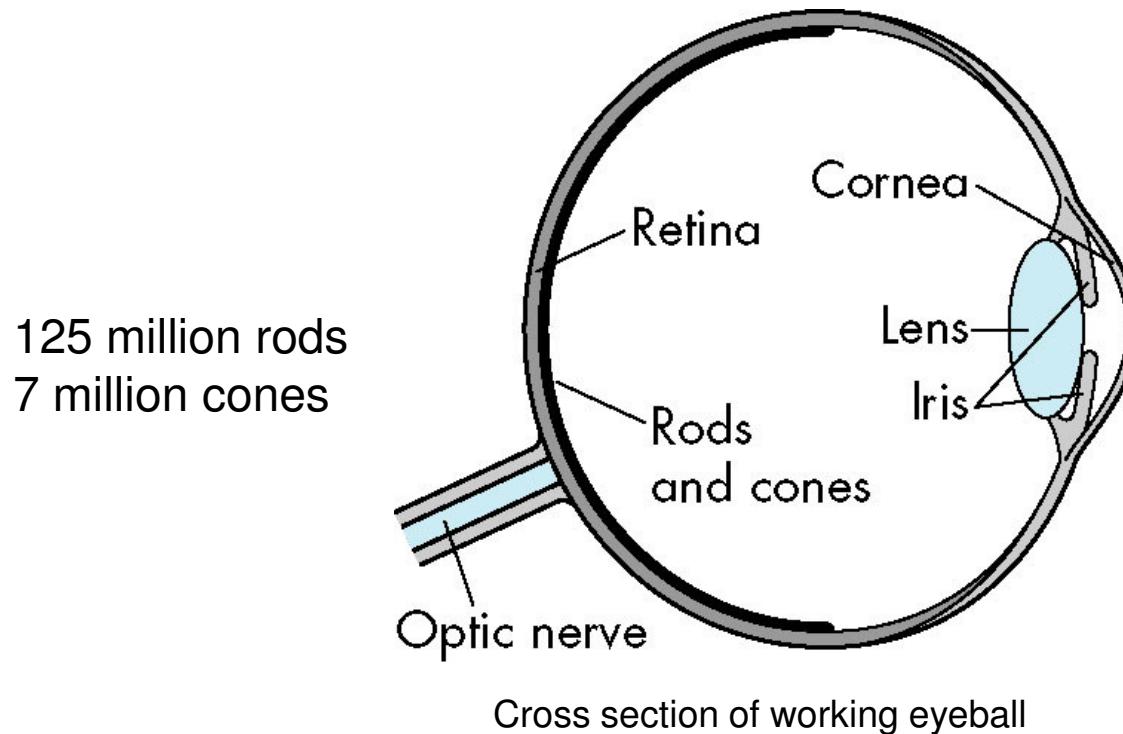


# **Visual Perception**

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How are images converted into information by the viewer?

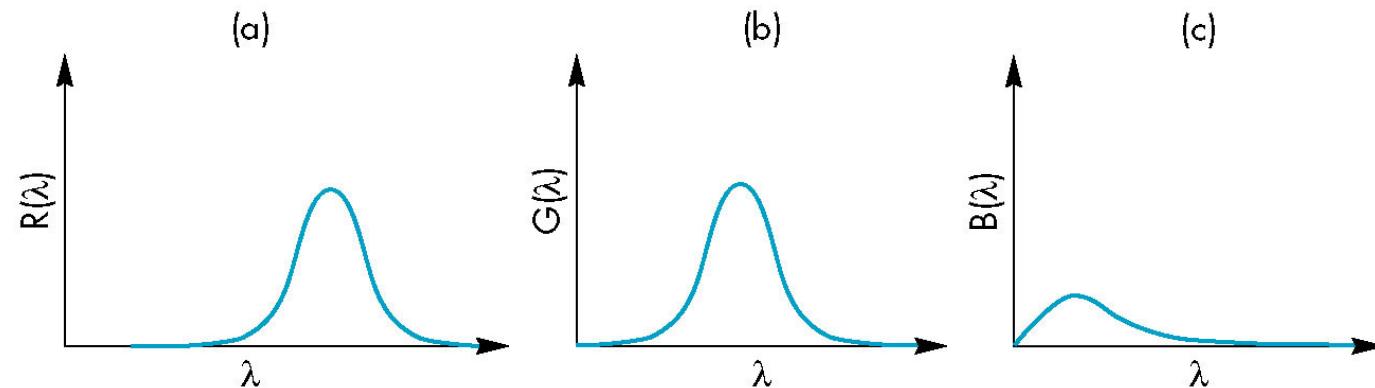
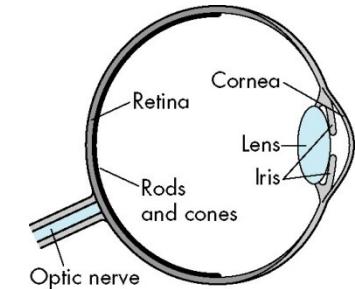
- Understanding visual perception helps designing image processing algorithms.
- Image data represents physical quantities, e.g. chromaticity and luminance.
- Chromaticity: color quality of light defined by its wavelength.
- Luminance: amount of light



# ***Visual Perception***

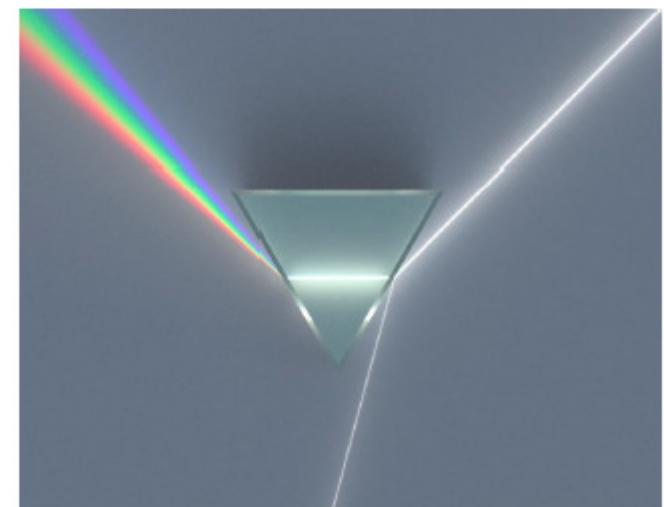
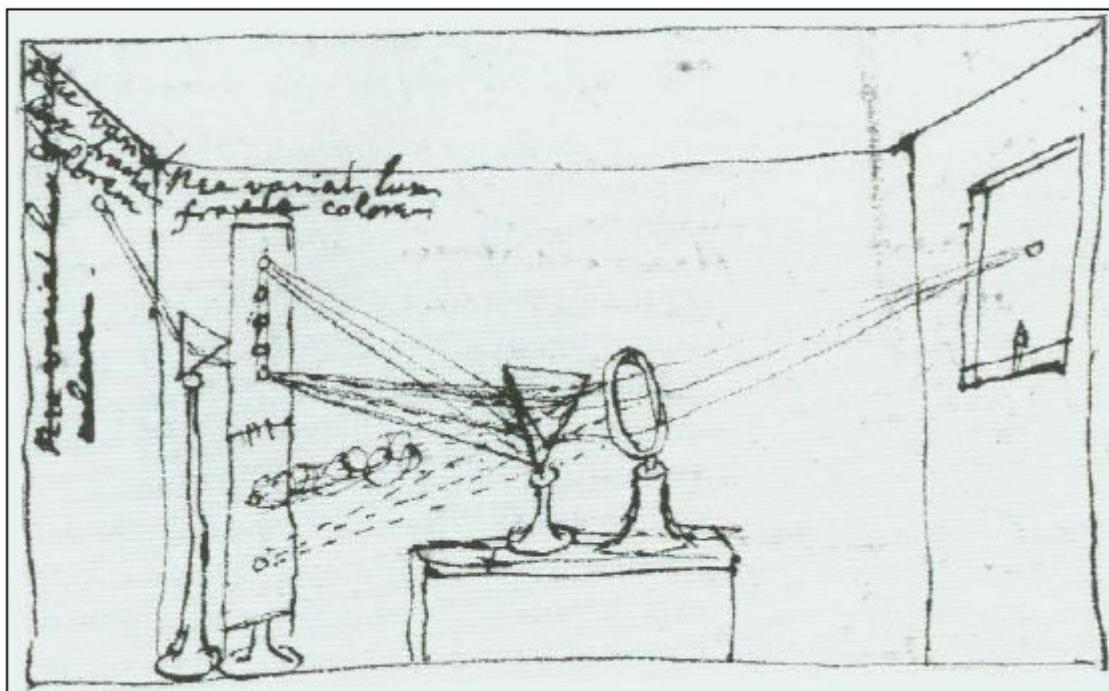
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- Rods
  - Intensity only
  - Essentially night vision and peripheral vision only
- Cones
  - Concentrated in the center of the retina in an area called the fovea.
  - Detect color and fine detail
  - Three types perceive different portions of the visible light spectrum

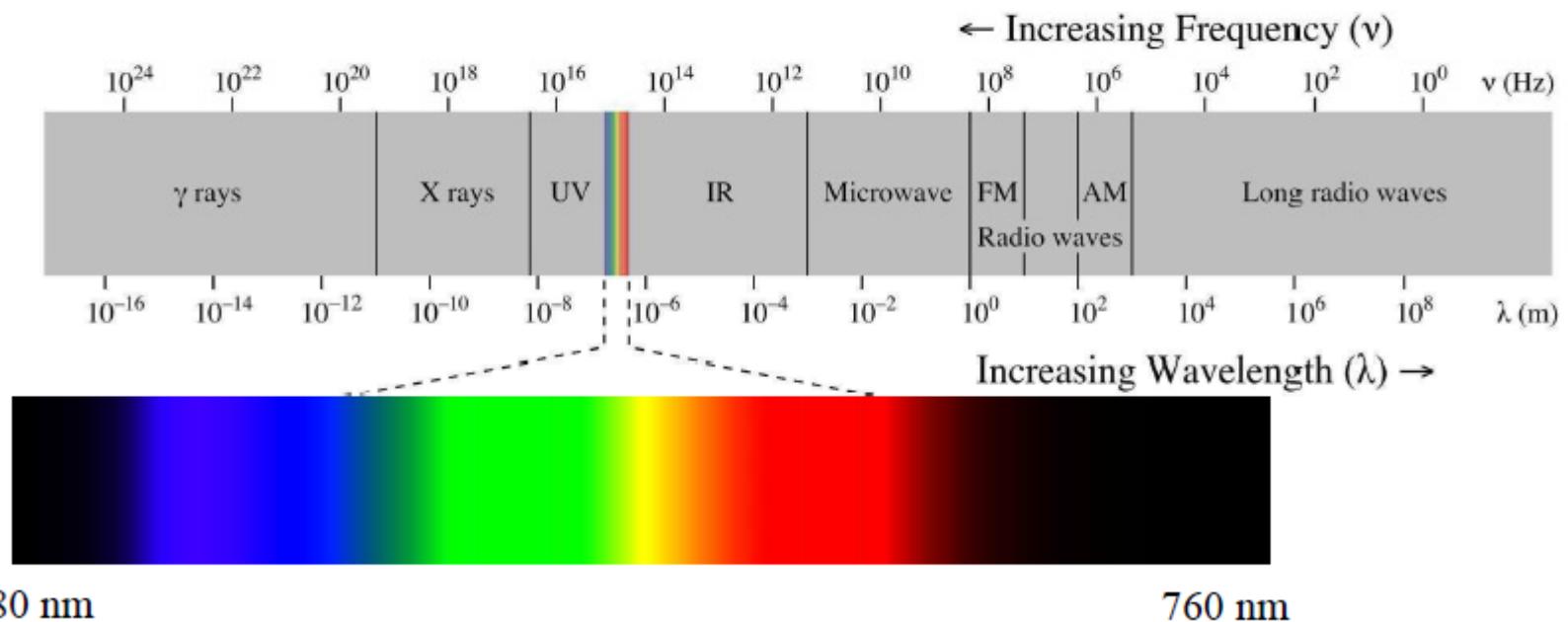


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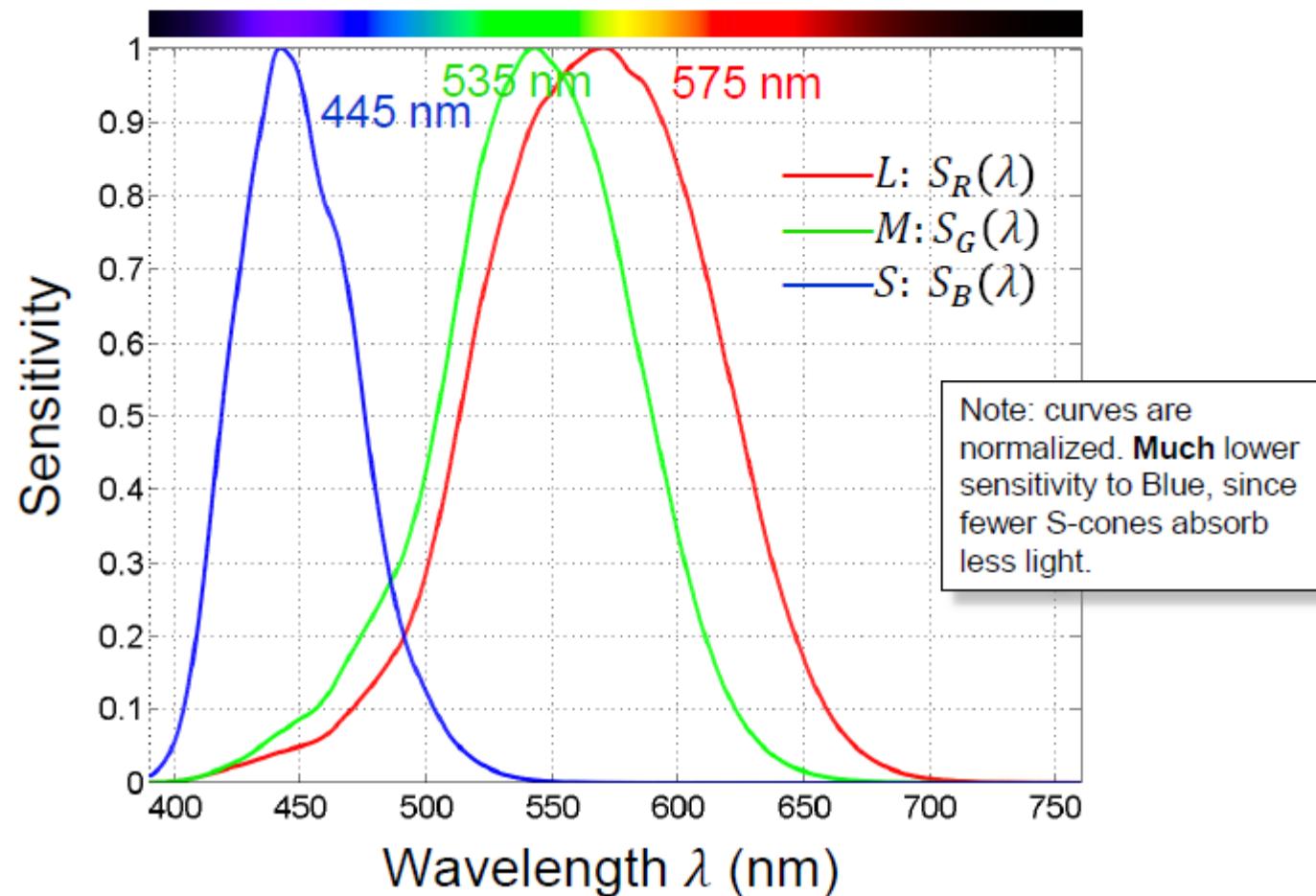
## Newton's Prism Experiment - 1666



# Color: visible range of the electromagnetic spectrum



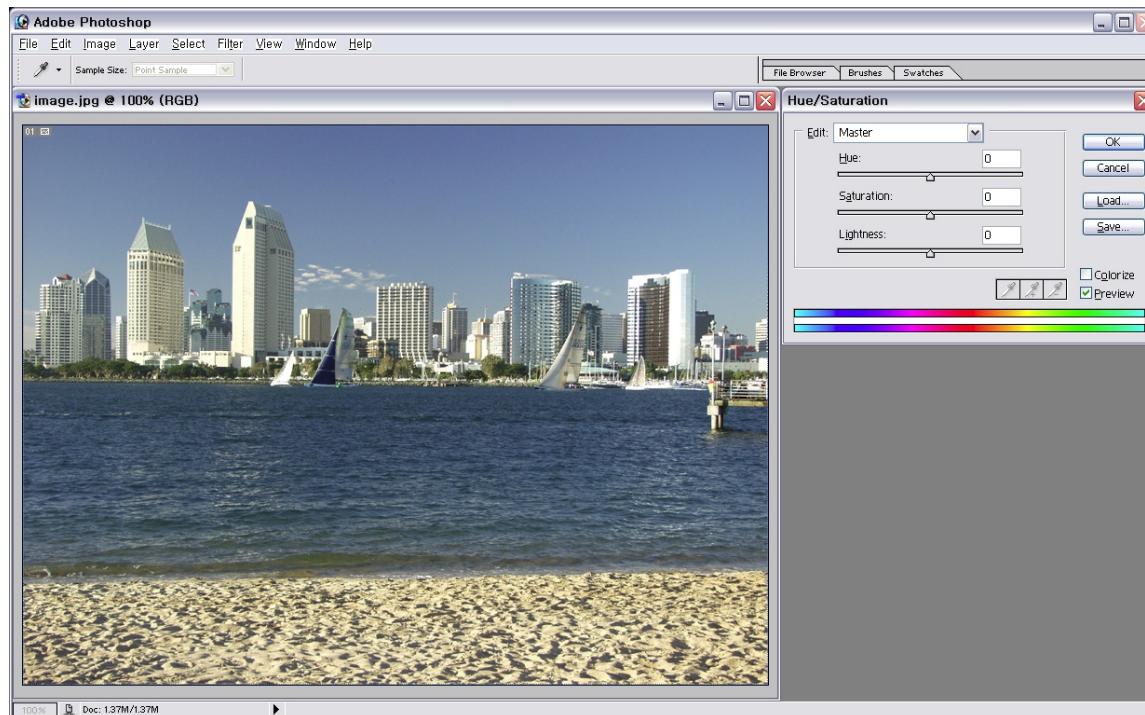
# Absorption of light in the cones of the human retina



# ***Visual Perception***

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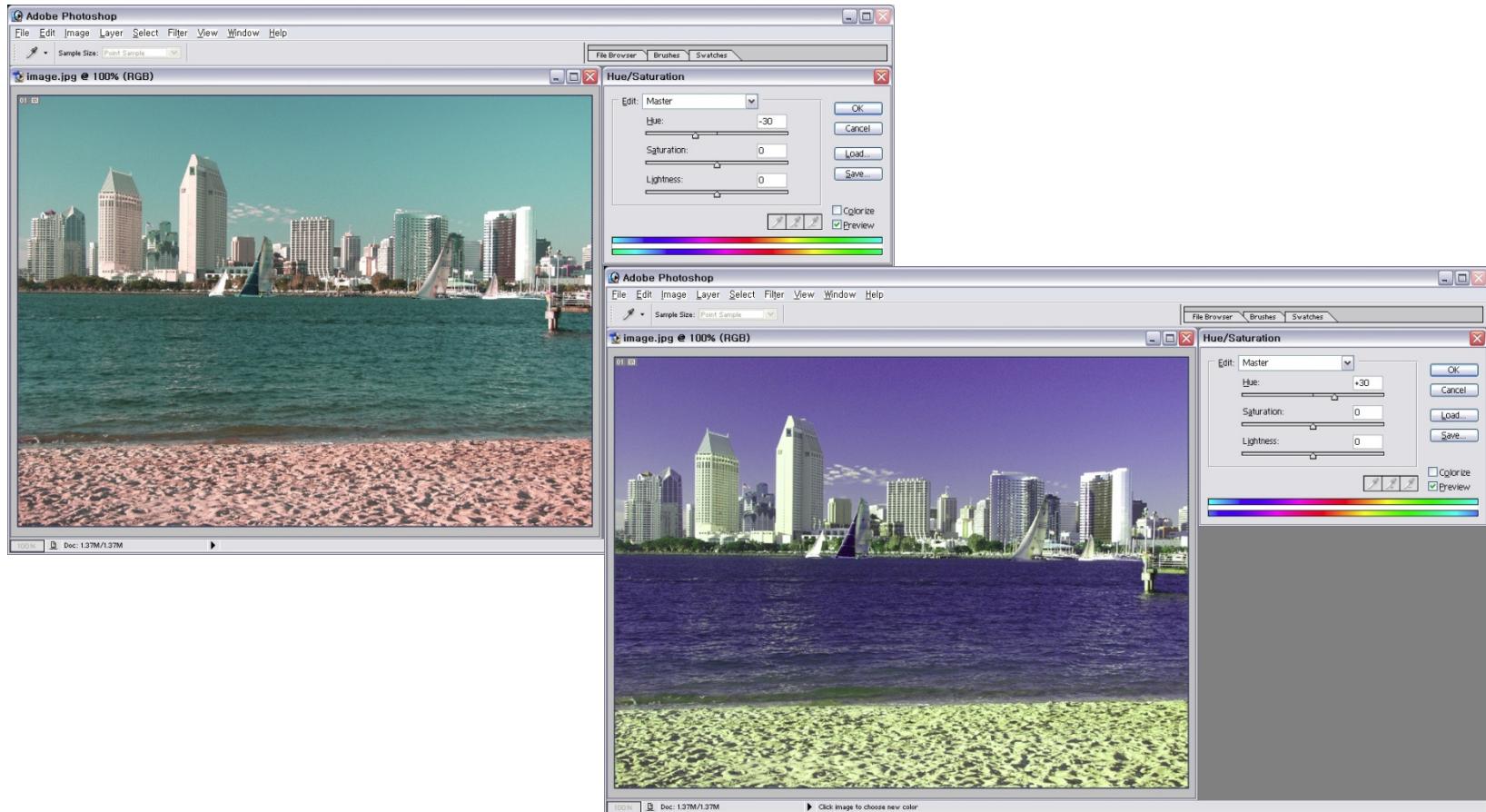
- Three variables for color image perception:
  - Hue
  - Saturation
  - Lightness



# ***Visual Perception***

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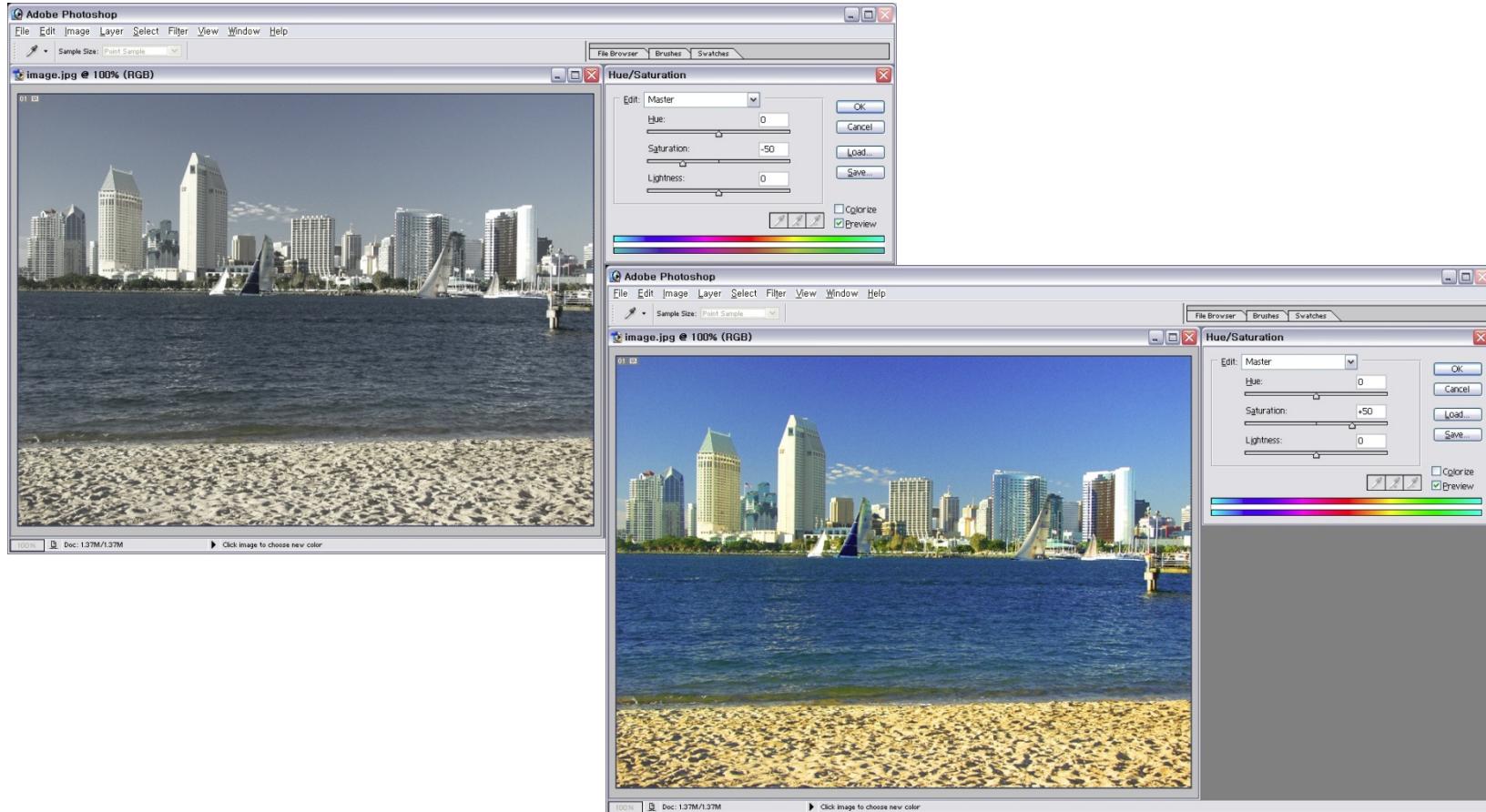
- Hue



# ***Visual Perception***

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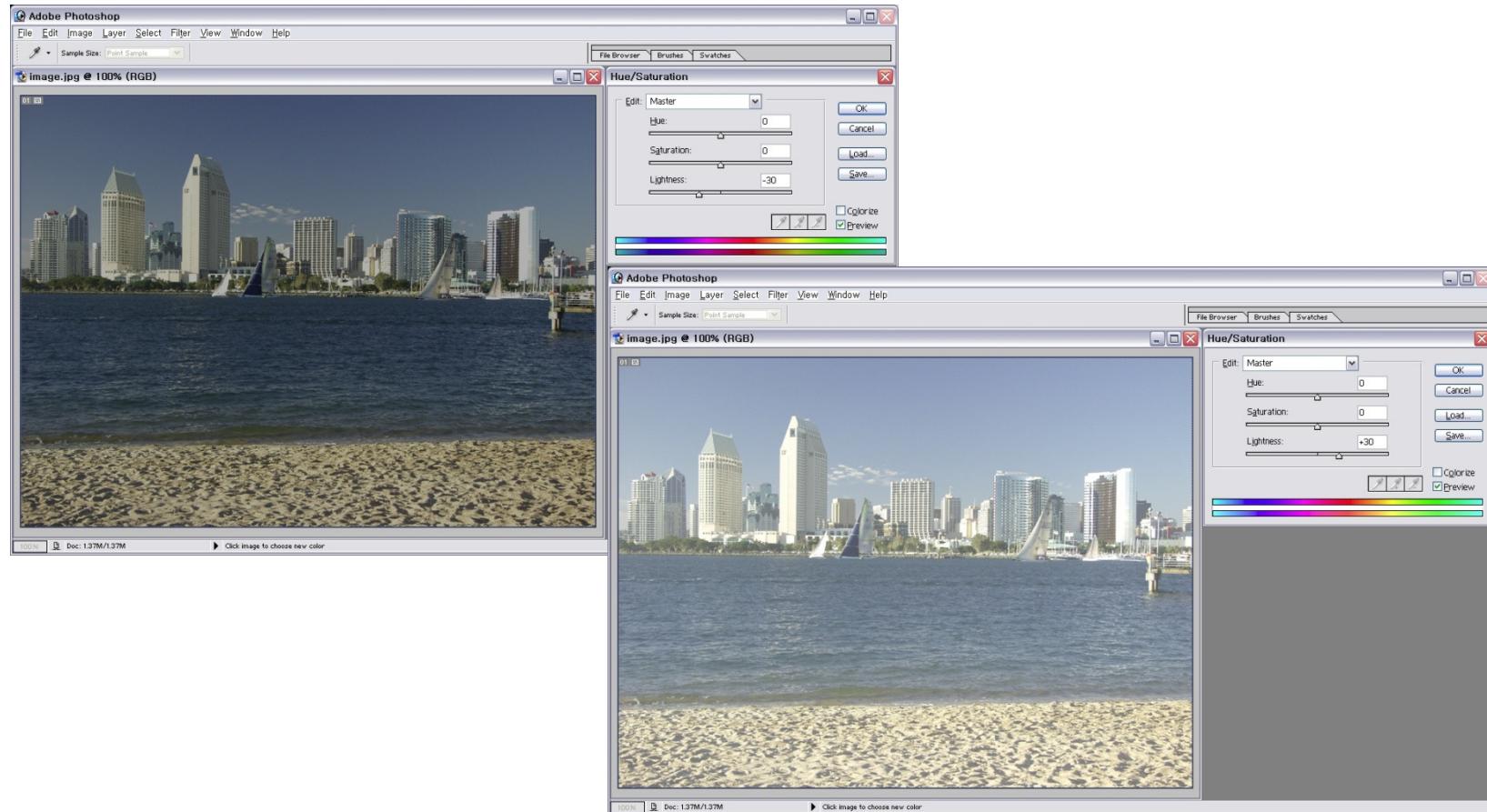
- **Saturation**



# ***Visual Perception***

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- Lightness



# ***Visual Perception***

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- **Contrast**

The range from the darkest regions of the image to the light regions.

$$\text{contrast} = \frac{I_{\max} - I_{\min}}{I_{\max} + I_{\min}}$$

$I_{\max}$  ,  $I_{\min}$  : maximum, minimum intensities of a region or image

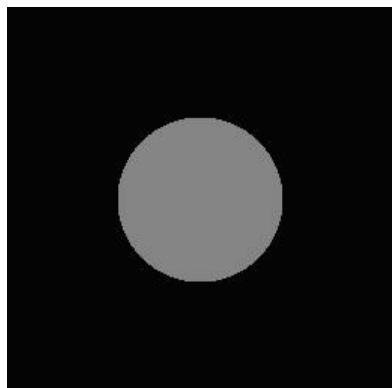


# ***Visual Perception***

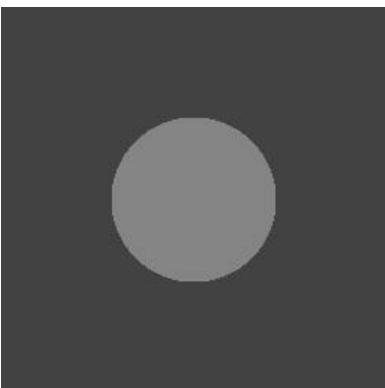
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- **Simultaneous Contrast**

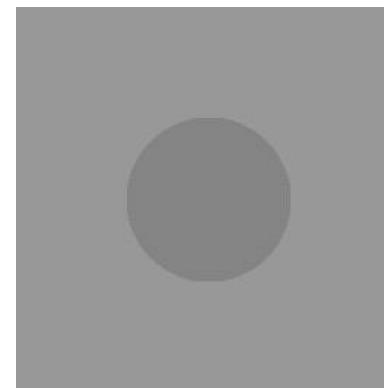
A phenomenon of the human visual system that causes perceived brightness to be dependent not only on the brightness levels, but also on brightness levels of the adjacent areas



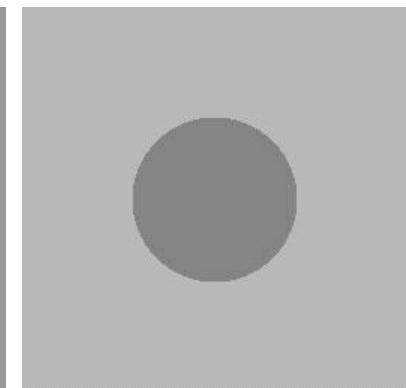
Circle = 127, background =0



Circle = 127, background =64



Circle = 127, background =150



Circle = 127, background =180

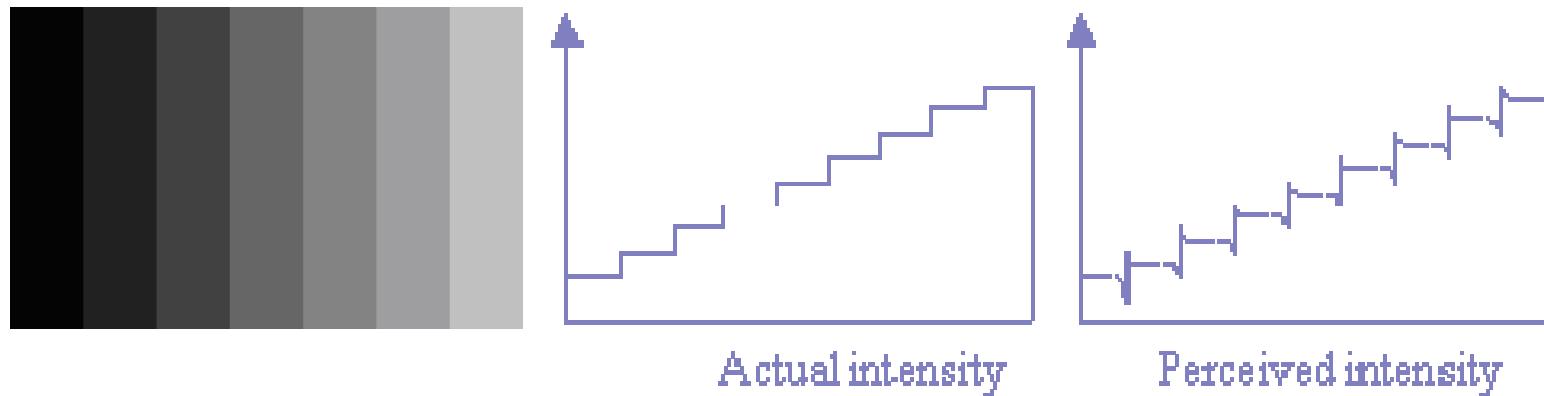
All the inner circles have the same intensity, but they appear progressively darker as the background becomes lighter.

# ***Visual Perception***

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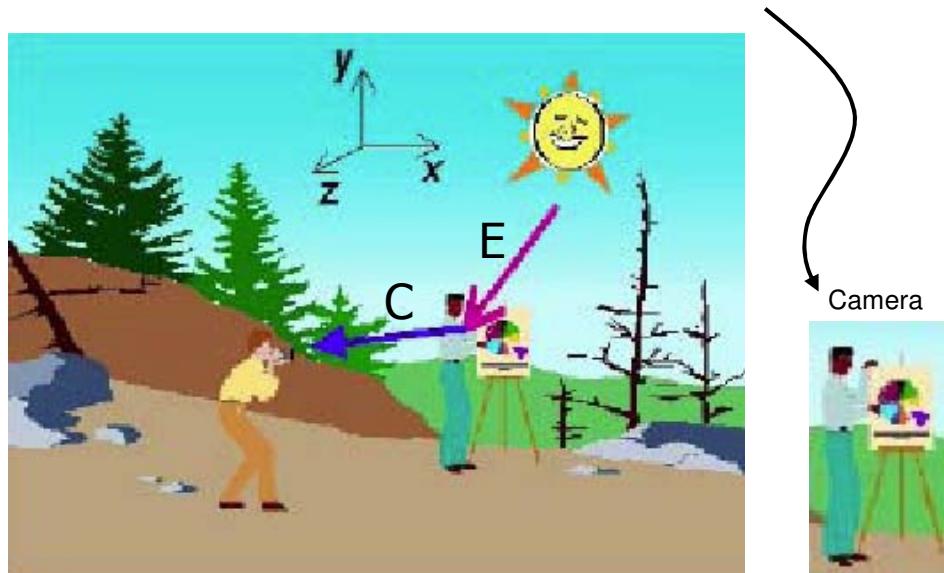
- **The Mach Band Effect**

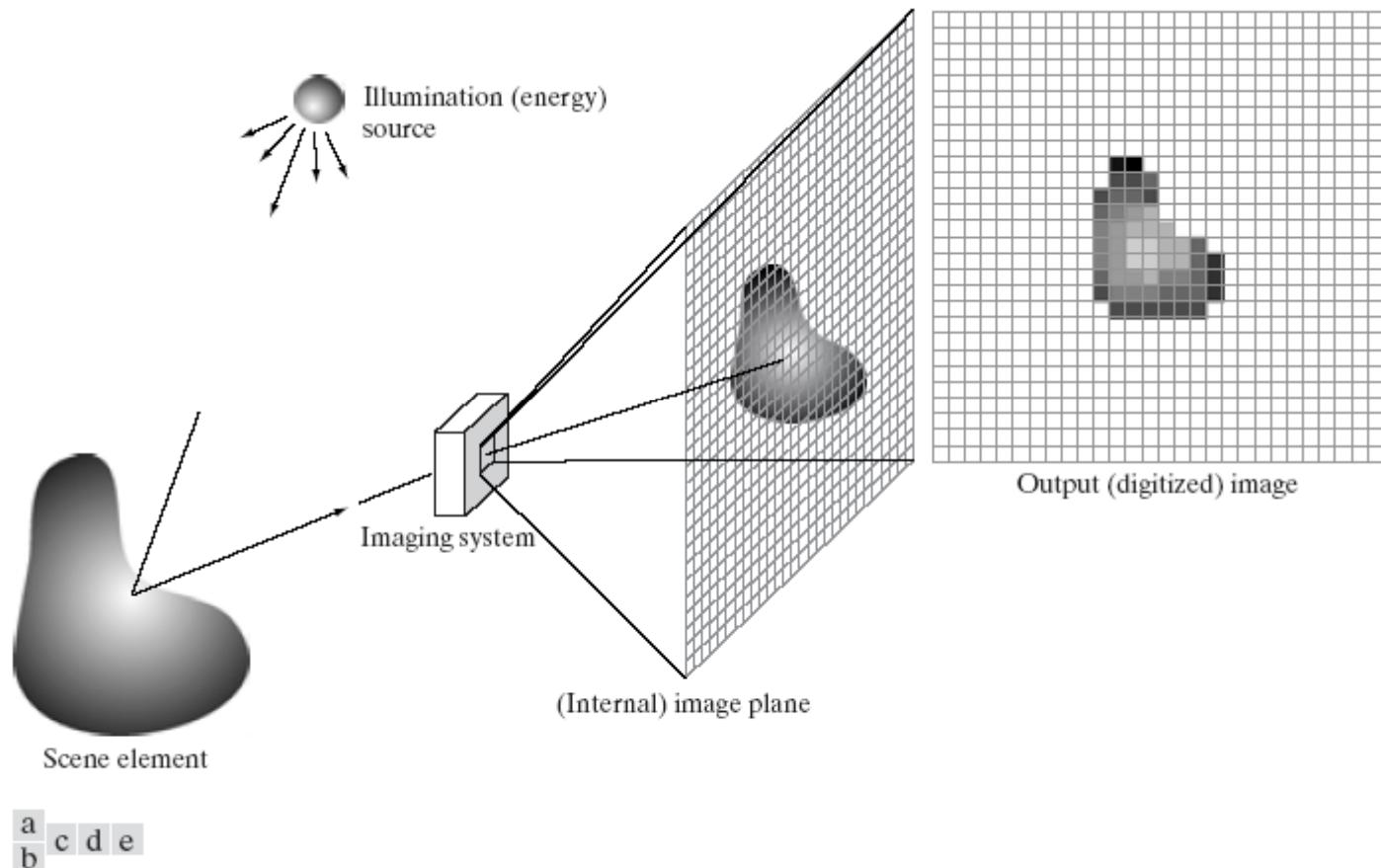
The response of our visual system to an abrupt change in luminance tends to emphasize the edge.



# **Image Formation**

- Light source ( $\lambda$ : wavelength of the source)
  - $E(x,y,z,\lambda)$ : incident light on a point  $(x,y,z)$
- Each point of the scene has a reflectivity function
  - $r(x,y,z,\lambda)$ : reflectivity function
- Light reflects from a point and the reflected light is captured by an imaging device
  - $C(x,y,z,\lambda) = E(x,y,z,\lambda) * r(x,y,z,\lambda)$ : reflected light

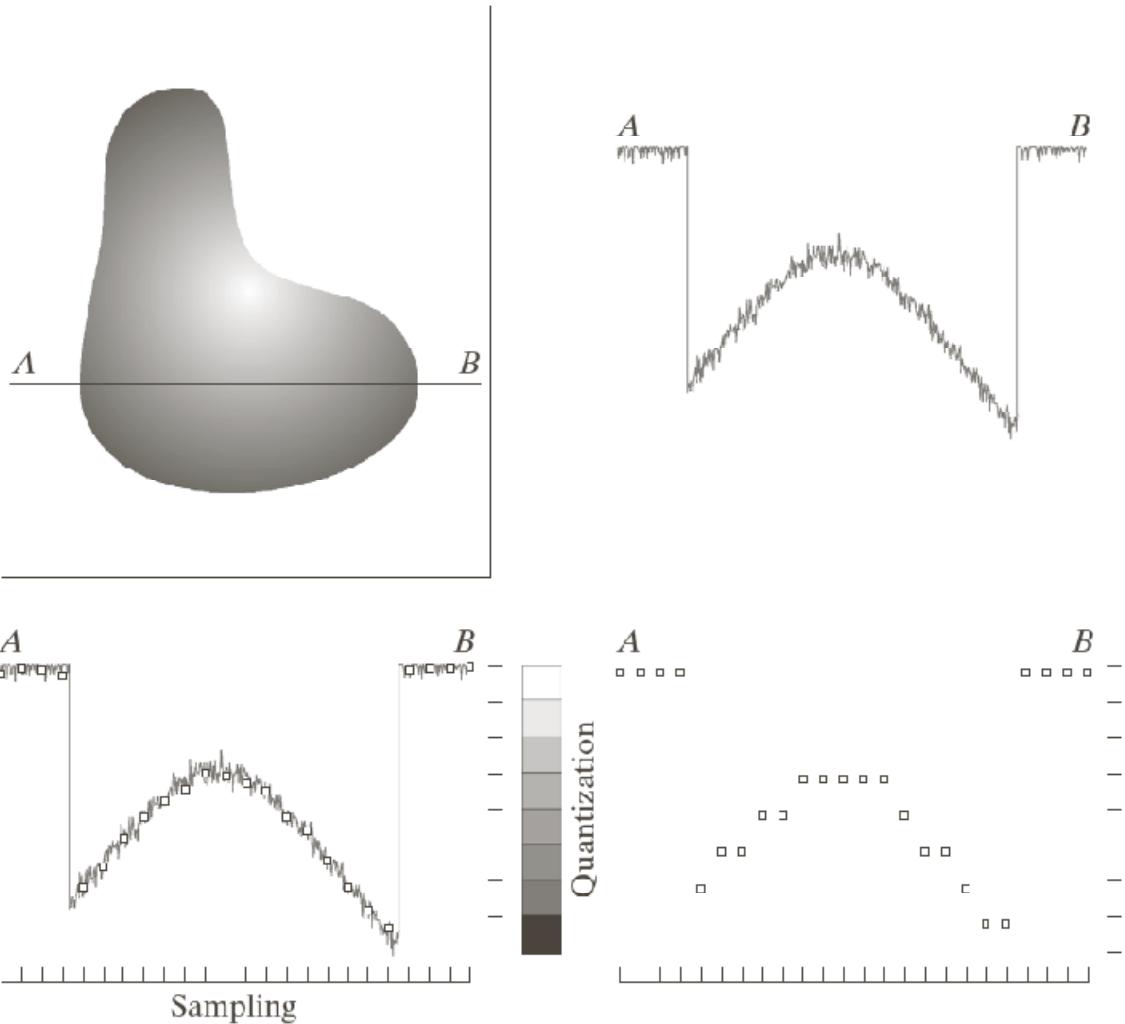


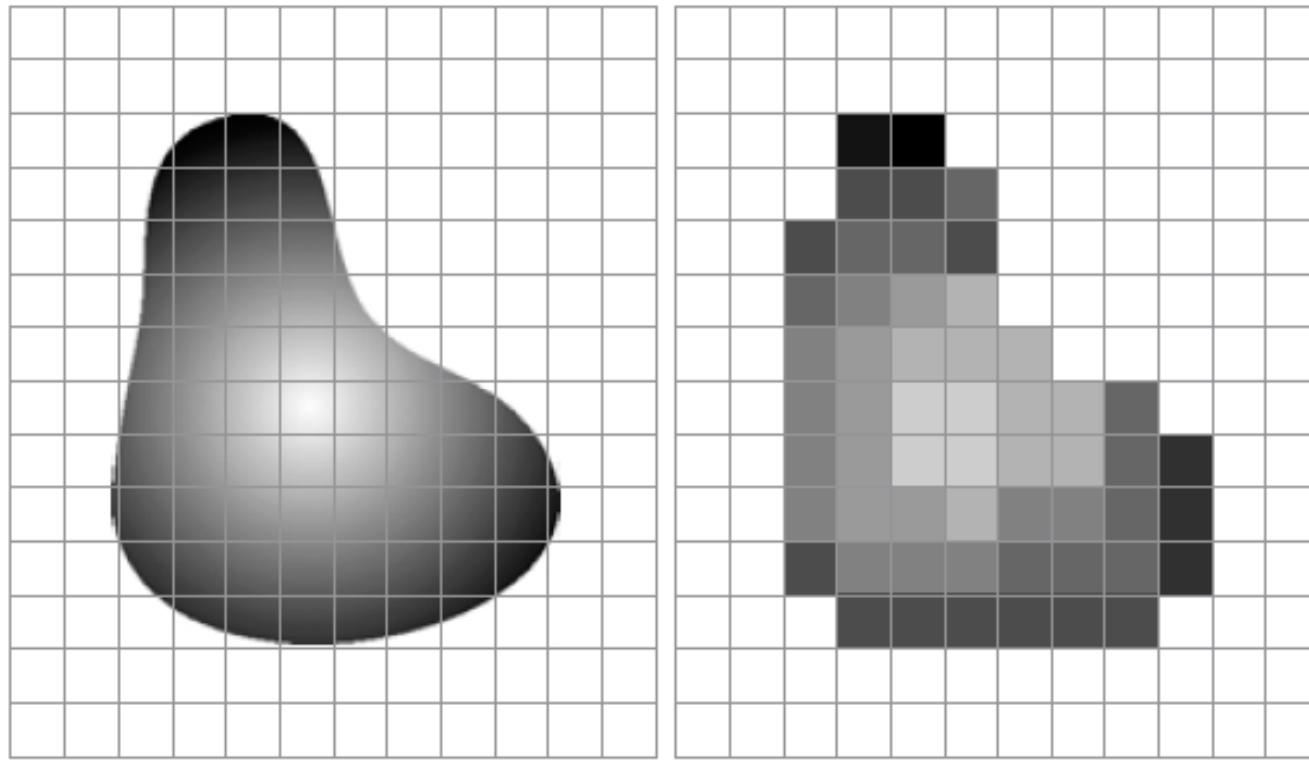


**FIGURE 2.15** An example of the digital image acquisition process. (a) Energy (“illumination”) source. (b) An element of a scene. (c) Imaging system. (d) Projection of the scene onto the image plane. (e) Digitized image.

a	b
c	d

**FIGURE 2.16**  
Generating a digital image.  
(a) Continuous image.  
(b) A scan line from A to B  
in the continuous image, used to  
illustrate the  
concepts of  
sampling and  
quantization.  
(c) Sampling and  
quantization.  
(d) Digital  
scan line.





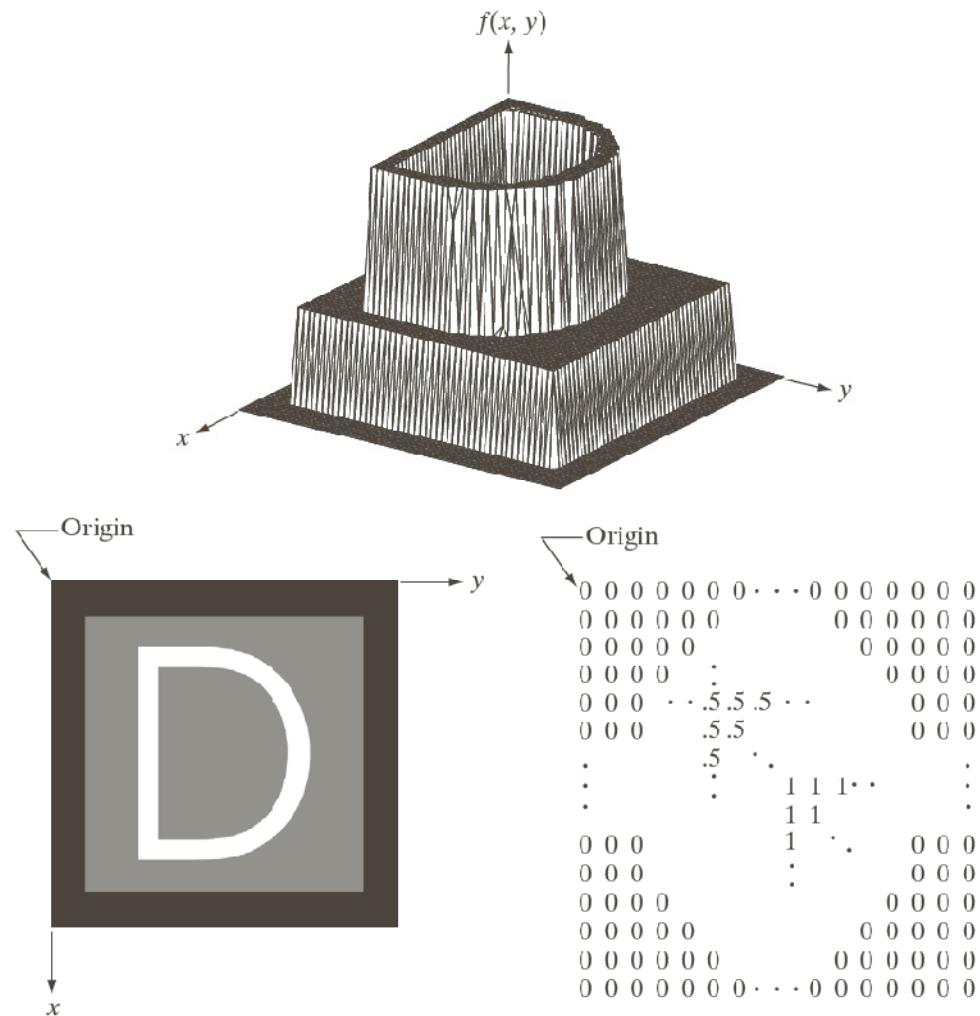
a b

**FIGURE 2.17** (a) Continuous image projected onto a sensor array. (b) Result of image sampling and quantization.

a  
b c

**FIGURE 2.18**

- (a) Image plotted as a surface.  
(b) Image displayed as a visual intensity array.  
(c) Image shown as a 2-D numerical array (0, .5, and 1 represent black, gray, and white, respectively).



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## Spatial and Gray-Level Resolution

- Spatial resolution
  - A measure of the smallest discernible detail in an image
  - Stated with *line pairs per unit distance, dots (pixels) per unit distance, dots per inch (dpi)*
- Intensity resolution
  - The smallest discernible change in intensity level
  - Stated with *8 bits, 12 bits, 16 bits, etc.*



1024



512



256

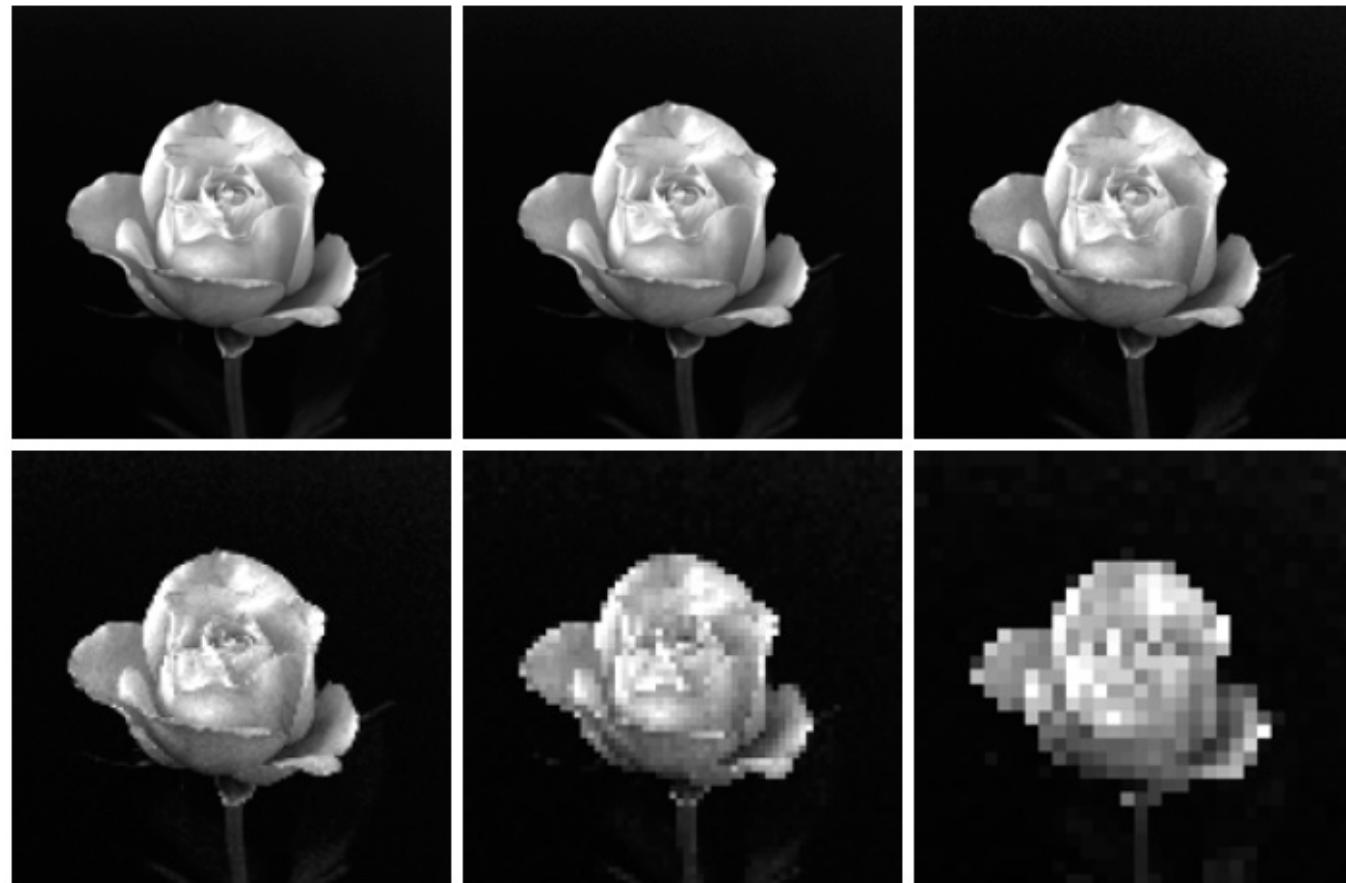
128



64

32

**FIGURE 2.19** A  $1024 \times 1024$ , 8-bit image subsampled down to size  $32 \times 32$  pixels. The number of allowable gray levels was kept at 256.



a	b	c
d	e	f

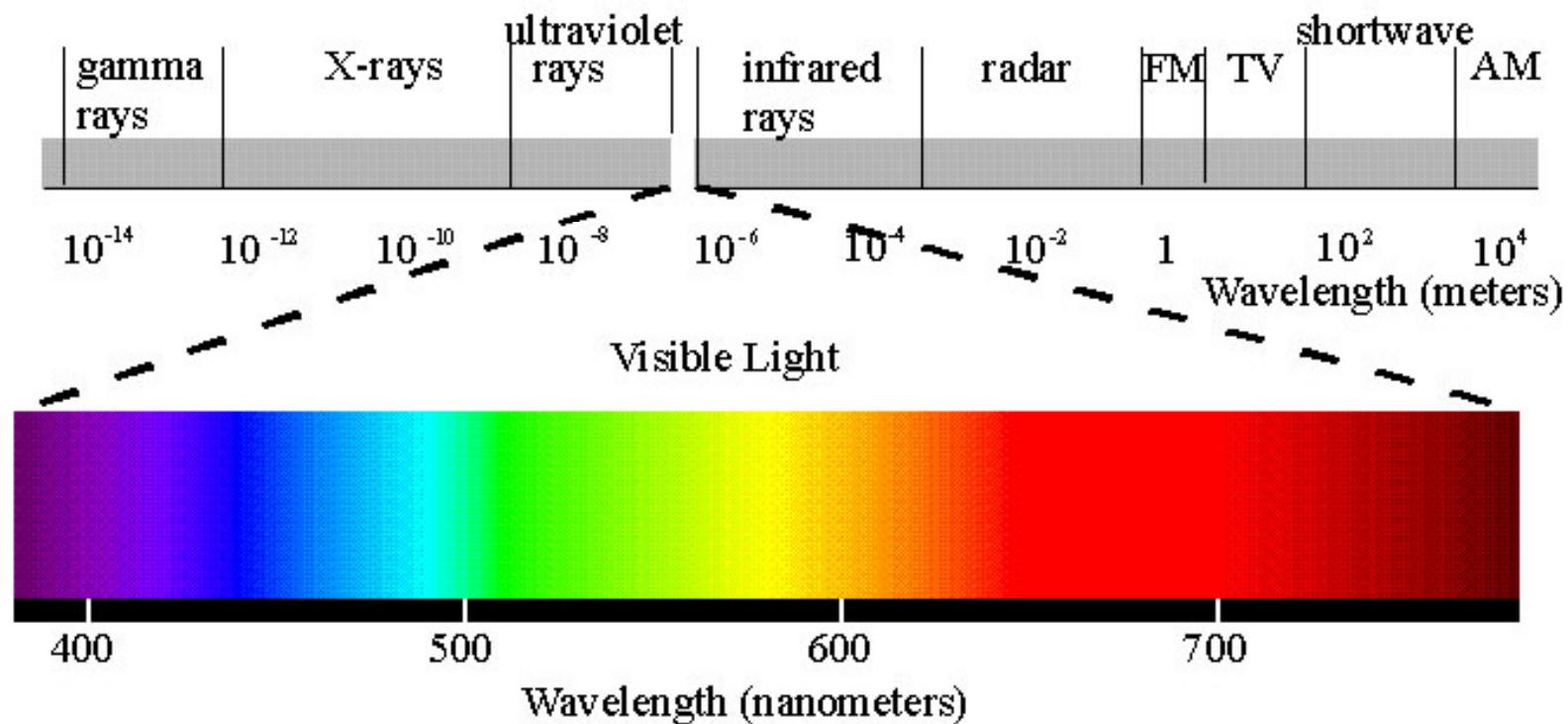
**FIGURE 2.20** (a)  $1024 \times 1024$ , 8-bit image. (b)  $512 \times 512$  image resampled into  $1024 \times 1024$  pixels by row and column duplication. (c) through (f)  $256 \times 256$ ,  $128 \times 128$ ,  $64 \times 64$ , and  $32 \times 32$  images resampled into  $1024 \times 1024$  pixels.

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## ***Image Formation***

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- Visible light is a form of ElectroMagnetic (EM) radiation, with  $\lambda$  at 350nm to 750nm.

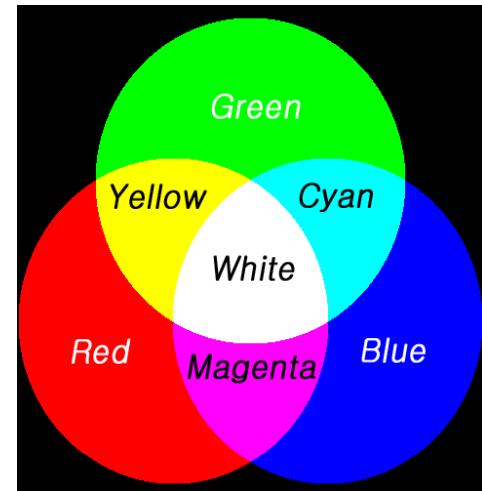


## ***Two Types of Light Source***

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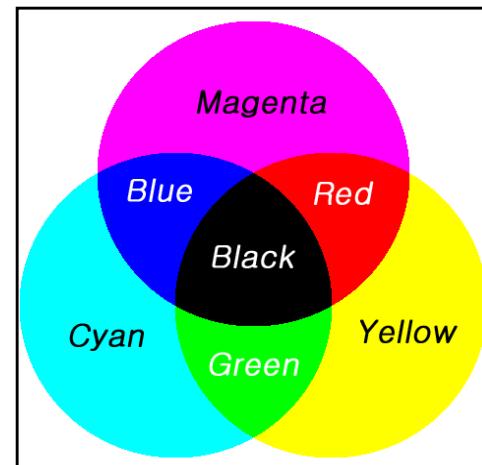
- Primary Light

- Emits the EM wave (sun, light bulb, etc.)
- Follows the additive law
- Primary colors: Red/Green/Blue



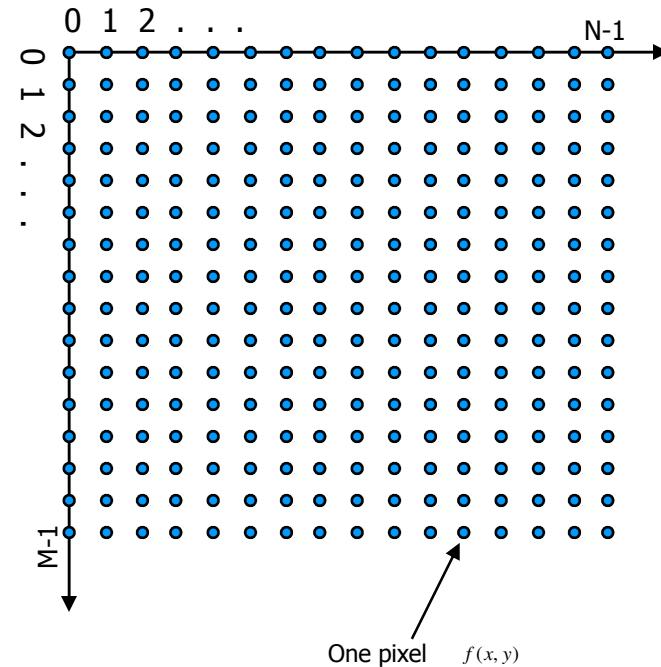
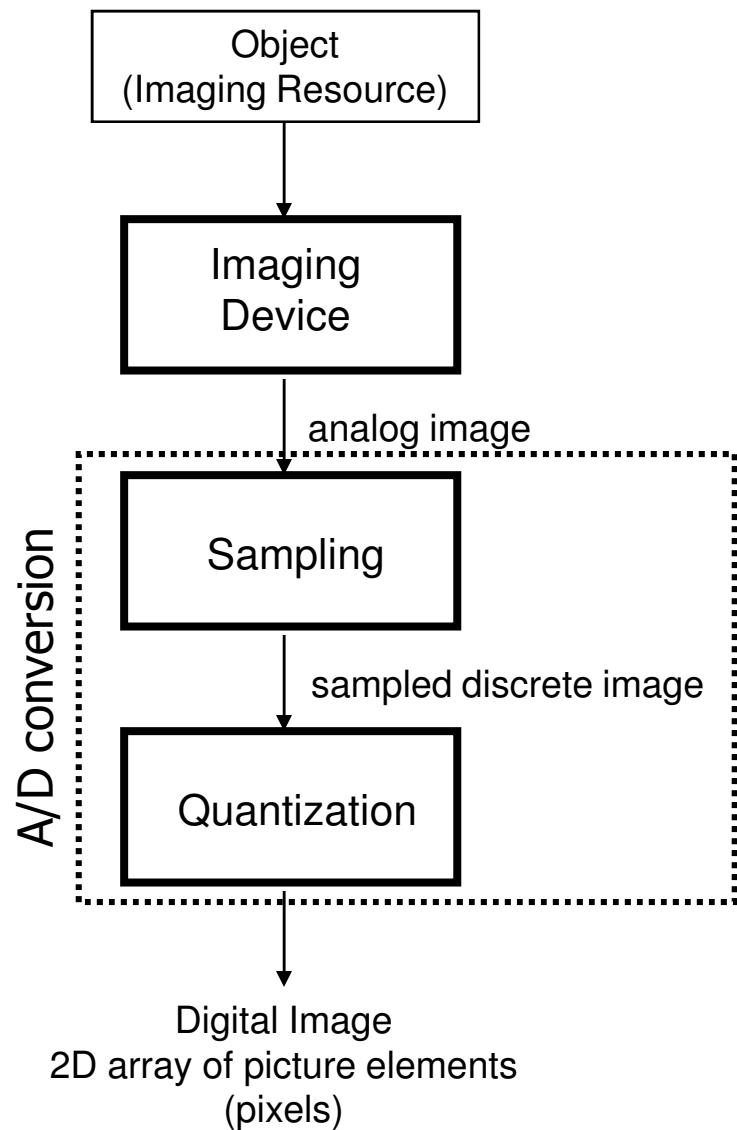
- Secondary Light

- Reflects an incident light (dye, object, etc.)
- Follows the subtractive law
- Primary colors: Cyan/Magenta/Yellow



# ***Image Representation***

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## Grayscale Images

- The intensity value of each pixel is  $0 \sim 255$ .
- Matrix representation of 2-D image:



The Lena Picture

$$F = \begin{bmatrix} 142 & 139 & \dots & 192 & 213 \\ 146 & 137 & \dots & 187 & 205 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 94 & 93 & \dots & 84 & 89 \\ 87 & 89 & \dots & 79 & 82 \end{bmatrix}$$

## ***Binary vs. Grayscale Images***

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- Binary images use only 2 levels (0 or 1)
- Grayscale images use 256 ( $=2^8$ ) gray levels (0 to 255)



Binary Image



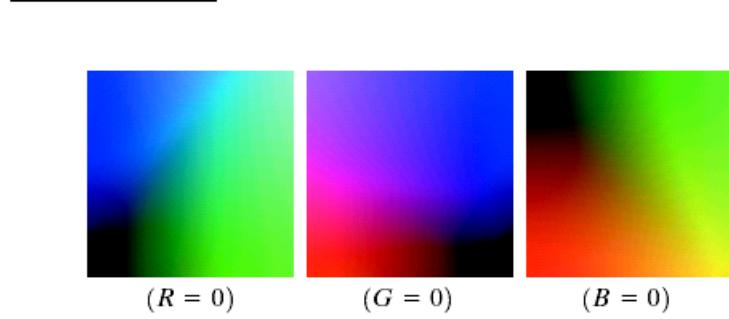
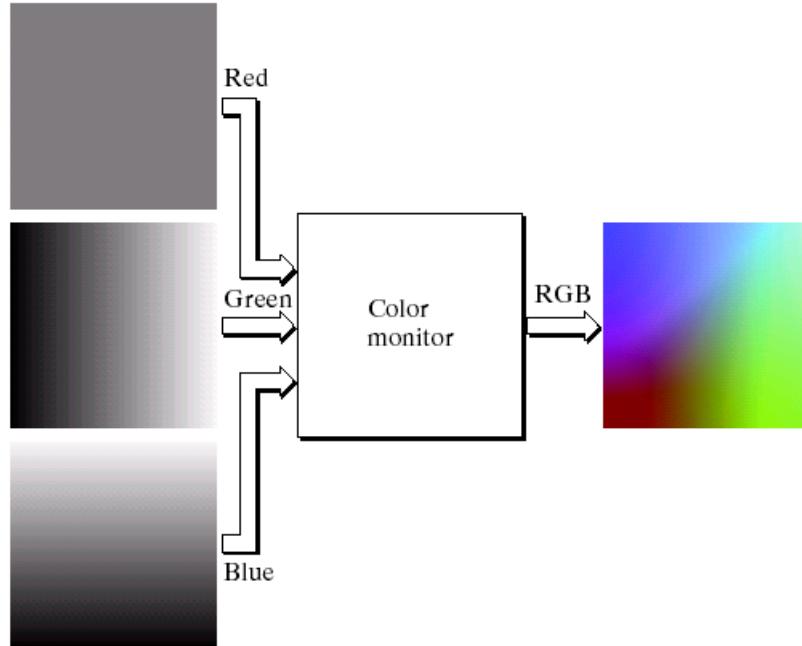
Grayscale Image

# Color Images

- Generating RGB Images

a

(a) Generating  
the RGB image of  
the cross-sectional  
color plane  
 $(127, G, B)$ .  
(b) The three  
hidden surface  
planes in the color  
cube of Fig. 6.8.



# Color Images



a	b
c	d

- (a) RGB image.
- (b) Red component image.
- (c) Green component.
- (d) Blue component.

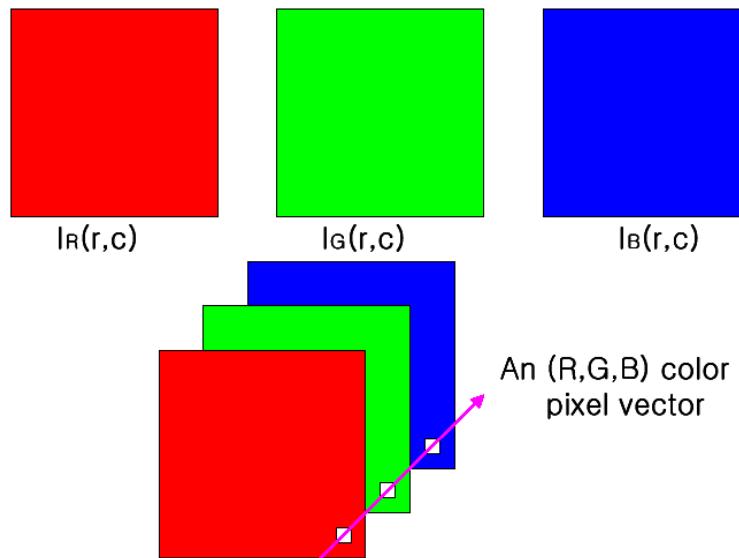
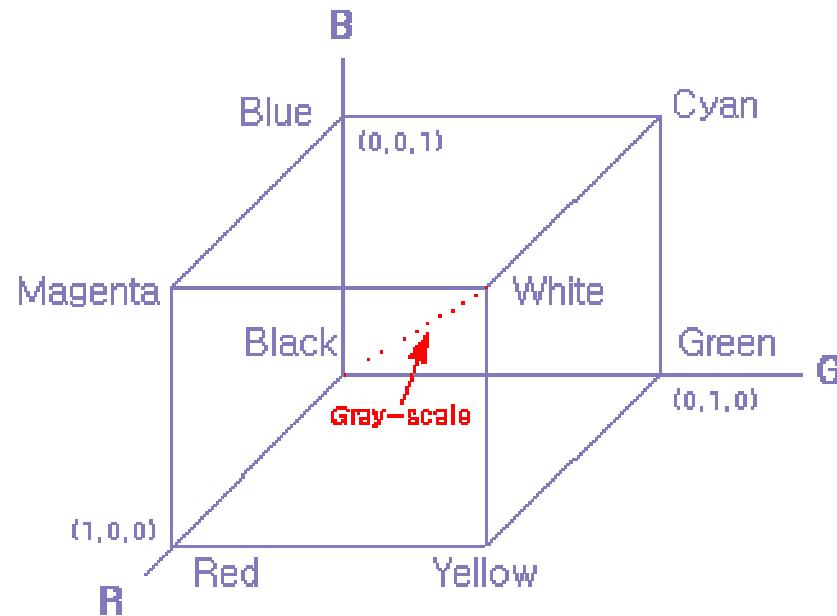
# ***Color Representation***

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- Different image processing systems use different color models for different reasons.
- Human perception of color is a function of the response of three types of cones.
- Color systems are based on three numbers (tristimulus values).
- Color Models
  - RGB: CRT monitors and most computer graphics systems
  - CMY: color picture publishing industry
  - HSI: systems requiring manipulations of Hue/Saturation/Intensity separately
  - YC<sub>b</sub>C<sub>r</sub>: systems needed to separate the luminance from the color information

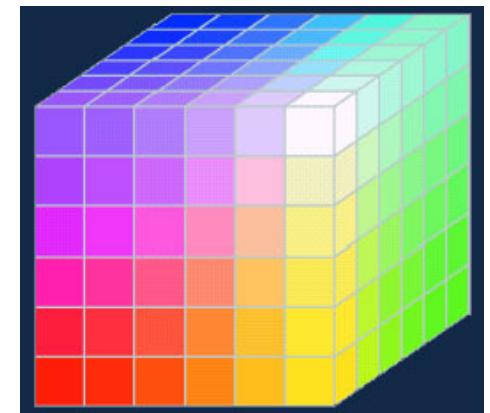
# Color Representation

- RGB Model



- RGB to Grayscale Conversion

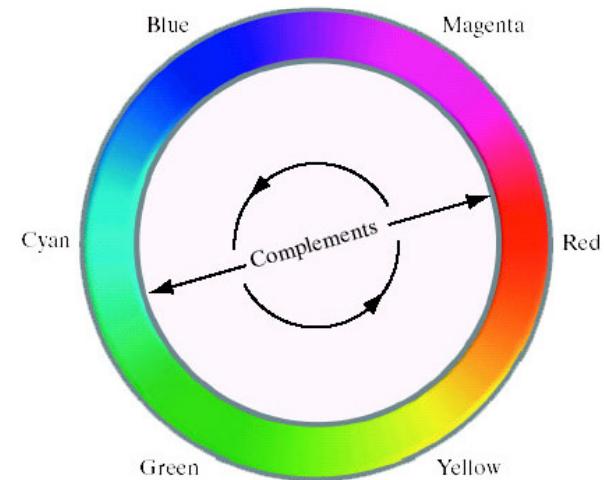
- NTSC standard:  $0.299R + 0.587G + 0.114B$
- Simple average:  $0.333R + 0.333G + 0.333B$



# ***Color Representation***

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- CMY Model
  - Consists of cyan, magenta, and yellow.
  - Cyan, magenta, and yellow are the complements of red, green, and blue, respectively.
  - To go from RGB to CMY, subtract the complement from white:
    - $C=1.0-R$  ( $R=1.0-C$ ) (in a 24-bit color system,  $C=255-R$ )
    - $M=1.0-G$  ( $G=1.0-M$ )
    - $Y=1.0-B$  ( $B=1.0-Y$ )
- CMYK Model
  - Black (K) is added in the printing process :  $CMYK=CMY+K$
  - Pure black provides greater contrast.
  - CMY to CMYK conversion:
    - $K=\min(C,M,Y)$
    - $C=C-K$
    - $M=M-K$
    - $Y=Y-K$



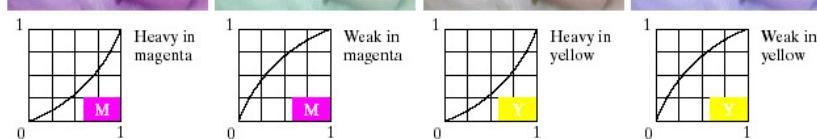
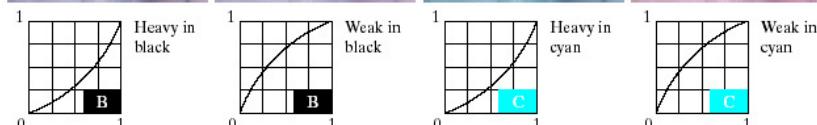
# ***Color Representation***

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**FIGURE 6.36** Color balancing corrections for CMYK color images.

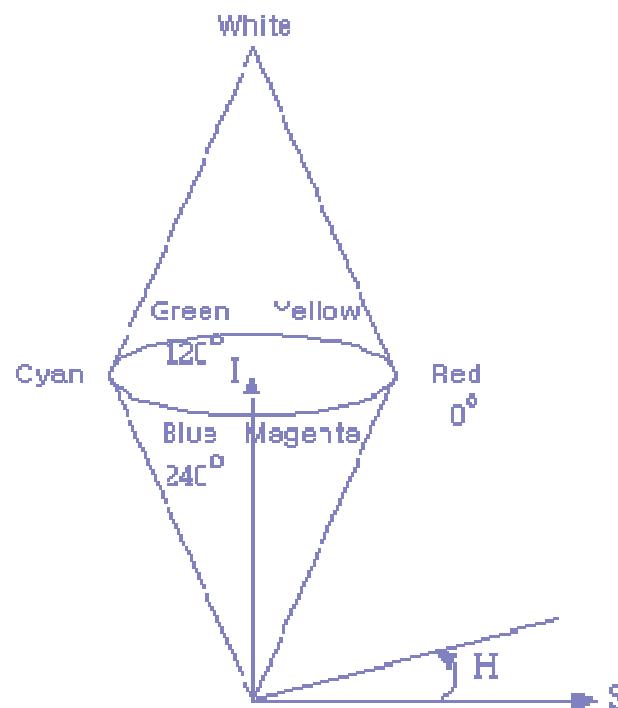
Original/Corrected



# ***Color Representation***

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- HSI Mode
- (Hue), (Saturation), (Intensity)

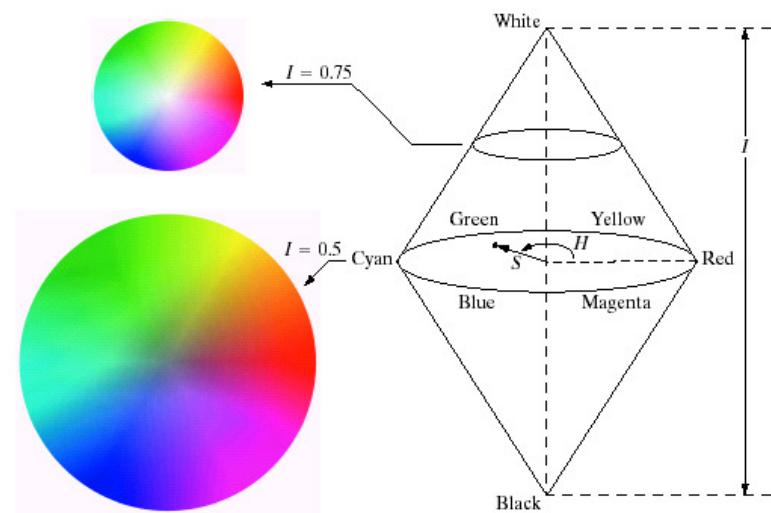
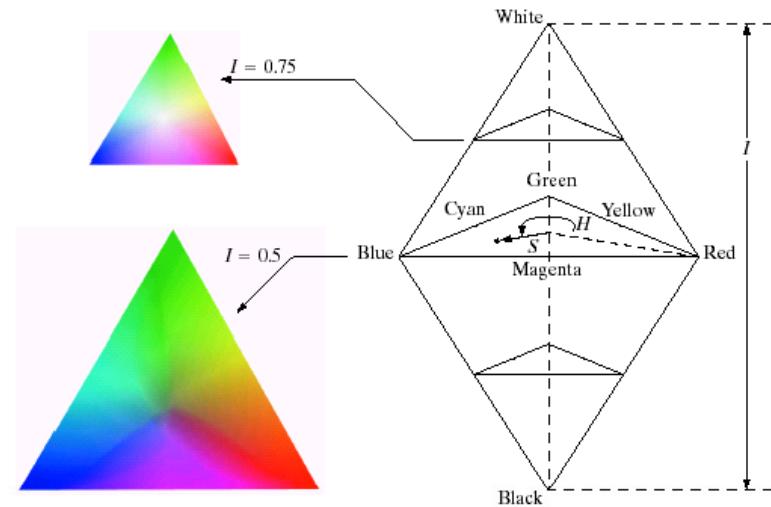


# ***Color Representation***

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- HSI Model  
(continued)

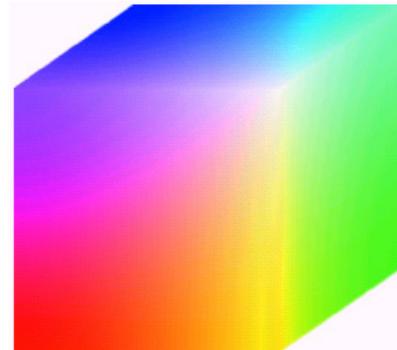
- To produce a color, simply adjust the hue. (angle  $H$ )
- To make it deeper or shallower, adjust the saturation. (radius  $S$ )
- To make it darker or lighter, adjust the intensity. (vertical axis  $I$ )



# ***Color Representation***

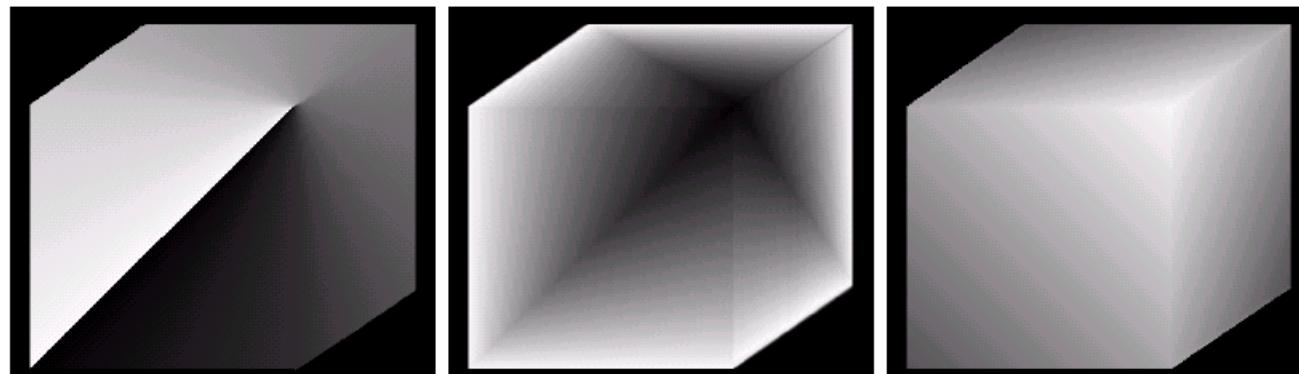
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- RGB vs. HSI



RGB 24-bit color cube.

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a b c

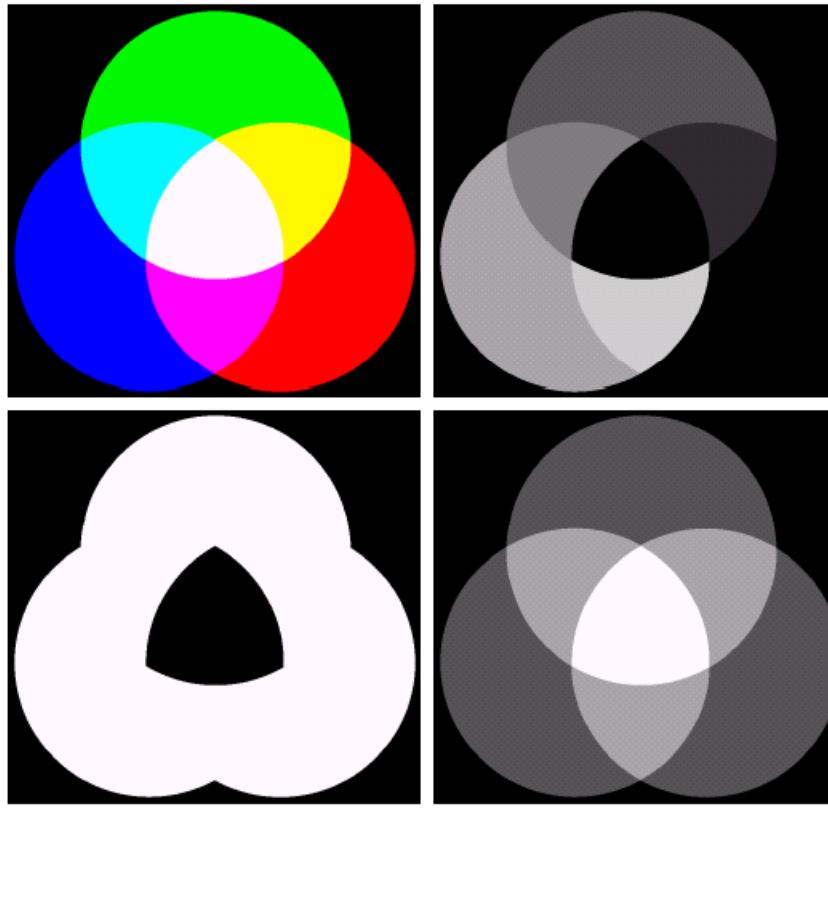
HSI components of the image in Fig. 6.8. (a) Hue, (b) saturation, and (c) intensity images.

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# ***Color Representation***

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- RGB vs. HSI



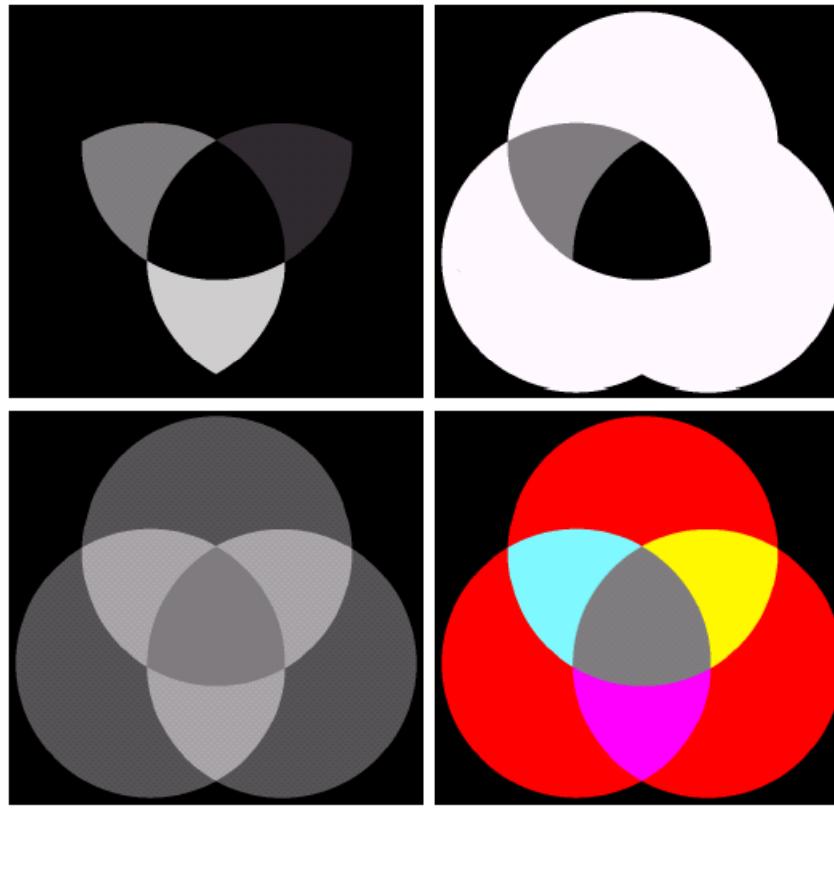
a b  
c d

(a) RGB image and the components of its corresponding HSI image:  
(b) hue, (c) saturation, and (d) intensity.

## ***Color Representation***

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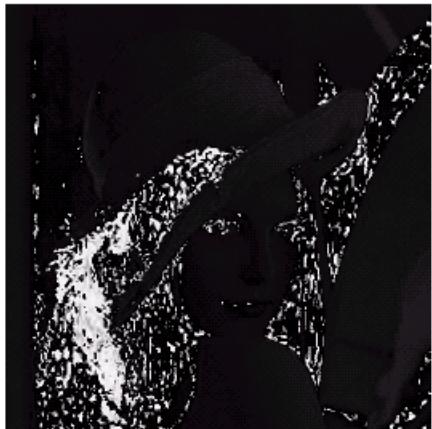
- RGB vs. HSI



(a)–(c) Modified HSI component images. (d) Resulting RGB image.  
(See Fig. 6.16 for the original HSI images.)

## ***Color Representation***

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a b c

HSI components of the RGB color image in Fig. 6.38(a). (a) Hue. (b) Saturation. (c) Intensity.

# ***Color Representation***

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- YC<sub>b</sub>C<sub>r</sub> Mode
  - Another color space that separates the luminance from the color information.
  - The luminance is encoded in Y and the blueness and redness encoded in C<sub>b</sub>C<sub>r</sub>.
  - Conversion from RGB to YCbCr:
$$Y = 0.29900R + 0.58700G + 0.11400B$$
$$Cb = -0.16874R - 0.33126G + 0.50000B$$
$$Cr = 0.50000R - 0.41869G - 0.08131B$$
  - Conversion from YCbCr to RGB:
$$R = 1.00000Y + 1.40200Cr$$
$$G = 1.00000Y - 0.34414Cb - 0.71414Cr$$
$$B = 1.00000Y + 1.77200Cb$$

# ***Color Representation***

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Full color



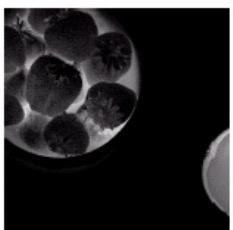
Cyan



Magenta



Yellow



Black



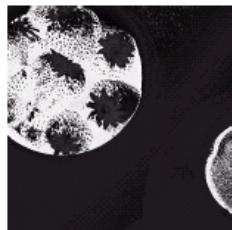
Red



Green



Blue



Hue



Saturation



Intensity

A full-color image and its various color-space components.