



$$\frac{dm(V_c)}{dt} = - \underbrace{\int_{A_c} \rho v \cdot n \, ds}$$

$$0 = \rho (\bar{V}_2 A_2 - \bar{V}_1 A_1)$$

$$\bar{V}_2 = \bar{V}_1 \frac{A_1}{A_2} = 3,36 \text{ m/s}$$

Cons momentum linear para V_c

$$\circ \quad \cancel{\frac{d}{dt} \int_{V_c} \rho v dV} = - \int_{\partial V_c} \rho v (v \cdot n) ds + \underbrace{\int_{\partial V_c} \tau \cdot n ds}_{\text{volume}} + \cancel{\int_{V_c} \rho b dV} \rightarrow 0$$

\swarrow

$$\therefore 0 = -\{\rho \bar{v}_1^2 A_1 - \rho \bar{v}_2^2 A_2\} + p_1 A_1 - F$$

$$F = \rho \{\bar{v}_1^2 A_1 - \bar{v}_2^2 A_2\} + p_1 A_1$$

$$= 5,42 \text{ N} \quad \Rightarrow$$

P2)

1)

$$[A] = \begin{bmatrix} r/a & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$[Q] = \begin{bmatrix} \cos \theta & \sin \theta & 0 \\ -\sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$$



$$[A] = [Q]^T [A'] [Q]$$

$$= \begin{bmatrix} \frac{r}{a} \cos^2 \theta & \frac{r}{a} \cos \theta \sin \theta & 0 \\ \frac{r}{a} \cos \theta \sin \theta & \frac{r}{a} \sin^2 \theta & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$ii) \quad \underline{P} = \underline{J} \underline{F} \underline{F}^{-T}$$

$$\begin{aligned} r(\underline{x}) &= \underline{R} \underline{U} \underline{x} \\ &= \begin{bmatrix} \left(\frac{l}{A} \cos \theta\right) X - \left(\frac{a}{A} \sin \theta\right) Y \\ \left(\frac{l}{A} \sin \theta\right) X + \left(\frac{a}{A} \cos \theta\right) Y \end{bmatrix} \begin{pmatrix} X \\ Y \end{pmatrix} \end{aligned}$$

$$\underline{F} = \nabla \varphi = \begin{bmatrix} \frac{l}{A} \cos \theta & -\frac{a}{A} \sin \theta & 0 \\ \frac{l}{A} \sin \theta & \frac{a}{A} \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\underline{F}^{-T} = \frac{LA}{a} \begin{bmatrix} \frac{a}{A} \cos \theta & -\frac{l}{A} \sin \theta & 0 \\ \frac{a}{A} \sin \theta & \frac{l}{A} \cos \theta & 0 \\ 0 & 0 & LA \end{bmatrix}$$

$$\underline{P} = \begin{bmatrix} \frac{1}{2} \cos \theta & \frac{1}{2} \sin \theta & 0 & 0 \\ \frac{1}{2} \sin \theta & \frac{1}{2} \cos \theta & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Interpretation of \underline{P} :

$$\underline{df} = \underline{I} dA, \quad \underline{I} = \underline{P} \underline{N}$$

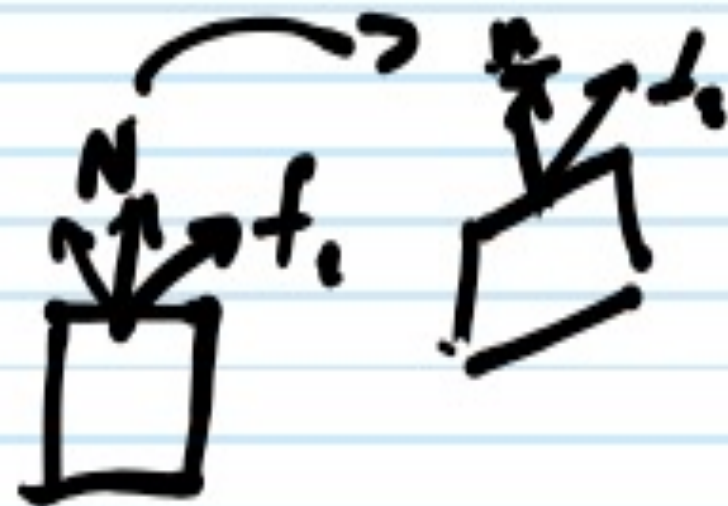
$$\Rightarrow f = \underline{P} \underline{N} A$$



$$\underline{N} = \underline{e}_1 = \{1, 0, 0\}$$

$$f = \underline{P} \underline{N} = \begin{bmatrix} f \cos \theta \\ f \sin \theta \\ 0 \end{bmatrix}$$

iii) $\underline{\zeta} = \underline{F}^{-1} \underline{p}$



$$\underline{f}_1 = \underline{f}_2 = \underline{p} \underline{N} = \underline{I} \underline{M}$$

$\underline{\zeta} \underline{N}$