thrust vector control

from
reciver data

pwr   +

            -

ghd   vin   pin D5

arduino
nano

channel 2

data

+

−

y harness

data

+

−

pin 4

arduino
pin 8

−

+ data

to elev
servo

to
elev Vec
servo
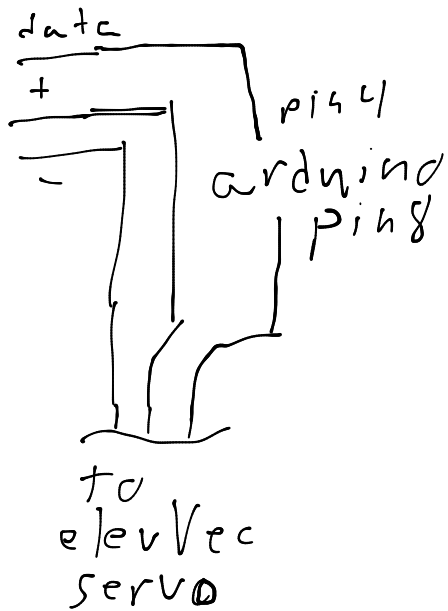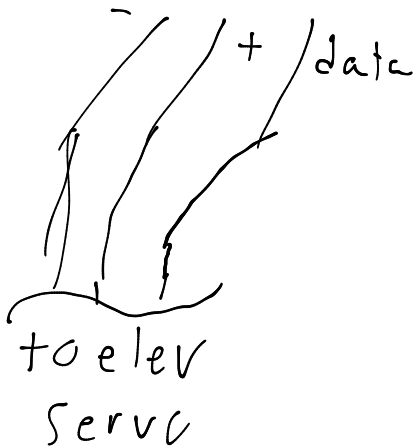
arduino already has power
from vector thruston/off line

chan 4

after
y harness
data

pin 11
arduino
pin 7

to
rudder
servo

+