Introduction to Matrix Product State: Detecting Symmetry Protected Topological Phase

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Ref: Lecture of F. Pollmann at TNQMP2016

You can find contents (slides and movies) of the lectures at http://www.issp.u-tokyo.ac.jp/public/tnqmp2016/

Outline

- Symmetry of MPS
 - Effect of "local" symmetry to iMPS
 - Possibility of non-trivial phase
 - Important symmetry of S=1 spin chain
 - Expected behavior in Haldane phase and Large-D phase
 - Detection of SPT phase from iMPS
- Exercise 5: Observe degeneracy in entanglement spectrum
- Exercise 6: Observe non-trivial phases

Symmetry

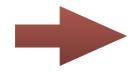
Symmetry operation:

$$\hat{O}_g$$
 :symmetry operator

$$|\tilde{\Psi}\rangle = \hat{O}_g |\Psi\rangle$$

$$g \in G$$

When a quantum state is invariant under a symmetry



The state after symmetry operation is invariant up to a phase.

$$|\tilde{\Psi}\rangle = e^{i\theta_g}|\Psi\rangle$$

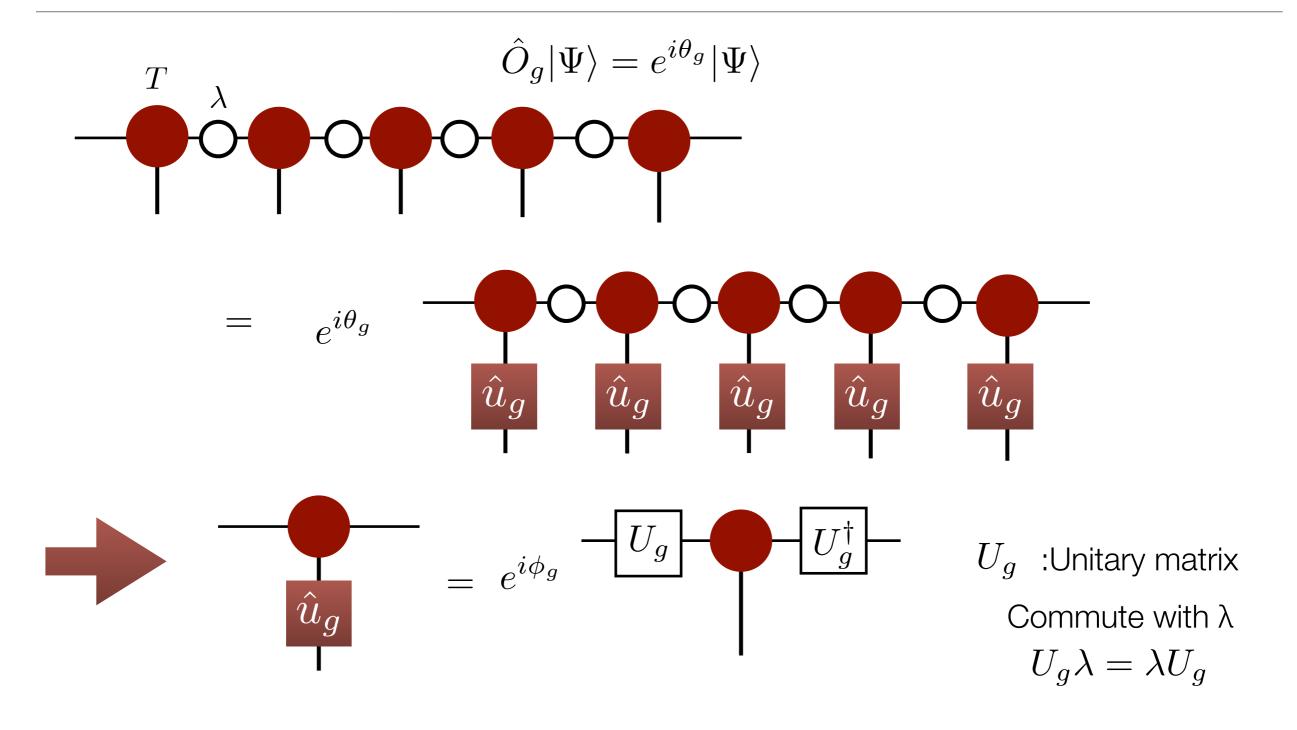
"Local" symmetry:

The symmetry operator can be represented as a product of local operators:

$$\hat{O}_g = \cdots \hat{u}(g)_1 \otimes \hat{u}(g)_2 \otimes \cdots \hat{u}(g)_i \otimes \cdots$$

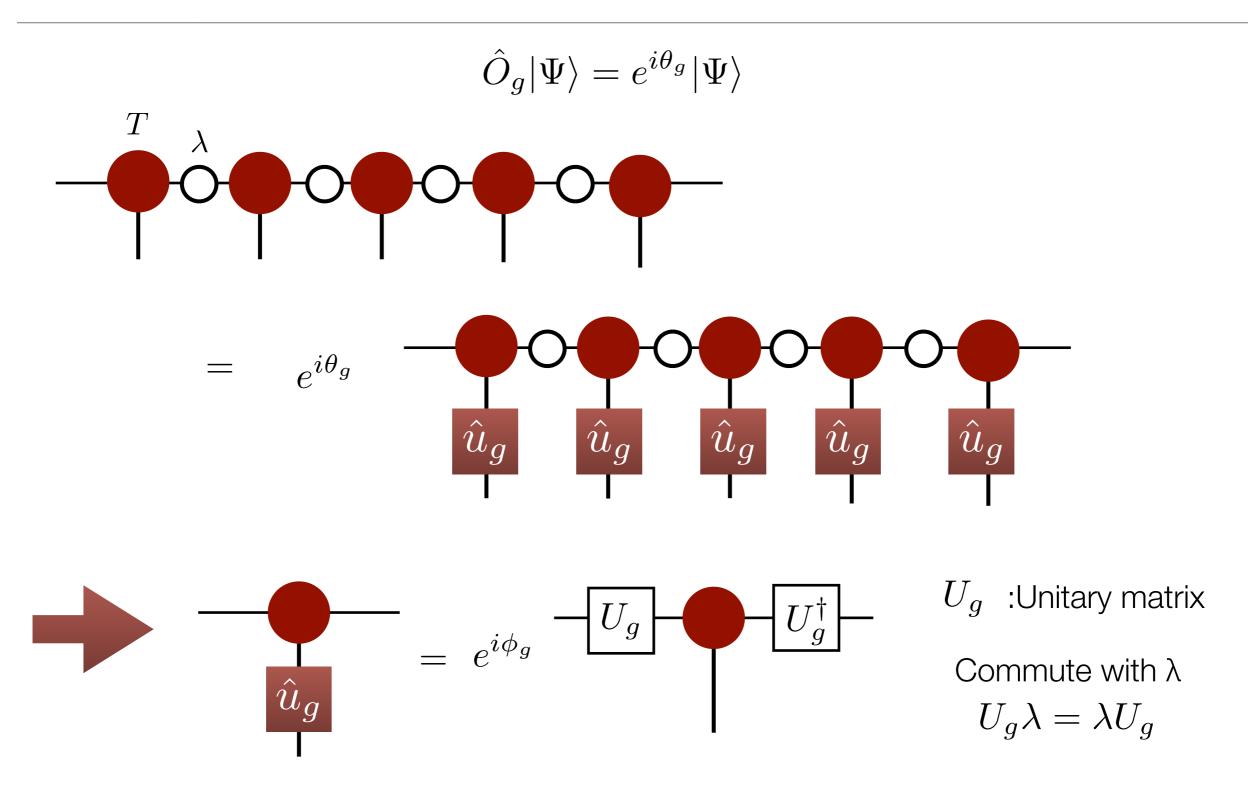
$$= \hat{u}_g \hat{u}_g$$

Effect of local symmetry to iMPS



*Note: $U_q' = e^{ix}U_g$ also satisfies the same relation.

Effect of local symmetry to iMPS



(D. Pérez-García, et al, Phys. Rev. Lett. 100, 167202 (2008))

Representation and projective representation

$$g, g' \in G$$

Symmetry operator is a representation of the symmetry group G:

$$\hat{u}_g \hat{u}_{g'} = \hat{u}_{gg'}$$



Matrix U_g satisfies a similar relation with a phase:

$$U_g U_{g'} = e^{i\psi_{gg'}} U_{gg'}$$

"Projective representation"

If the phase ψ cannot be absorbed by a rescaling, the state is distinguished from a trivial state.

Important symmetry of the S=1 spin chain

$$\mathcal{H} = \sum_{i} \vec{S}_i \cdot \vec{S}_{i+1} + D \sum_{i} S_{z,i}^2$$

Spin rotation:

eg. π rotation

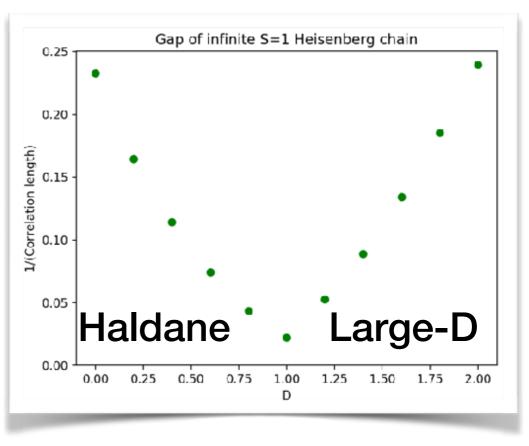
$$R_x = e^{i\pi S_x}, R_y = e^{i\pi S_y}, R_z = e^{i\pi S_z}$$

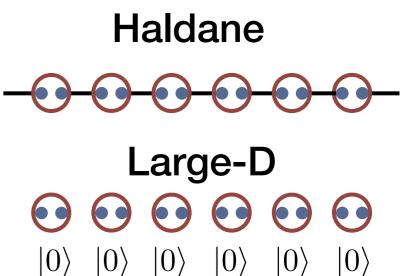
Time reversal:

$$\mathcal{T}|\Psi\rangle = R_y|\Psi^*\rangle$$

Space Inversion:







Both of Haldane and Large-D phases keep these symmetries.

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Space inversion in iMPS

6

4



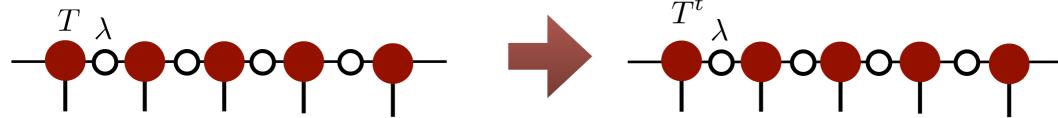
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Space inversion:

(F. Pollmann, et al, Phys. Rev. B 81, 064439 (2010))

(F. Pollmann, et al, Phys. Rev. B 86, 125441 (2012))



Take transpose of the matrix T

Apply this relation twice,

$$= e^{2i\phi_{\mathcal{I}}} - U_{\mathcal{I}}^* - U_{\mathcal{I}}^* - U_{\mathcal{I}}^t - U_{\mathcal{I}}^t$$

From the condition of the canonical form,

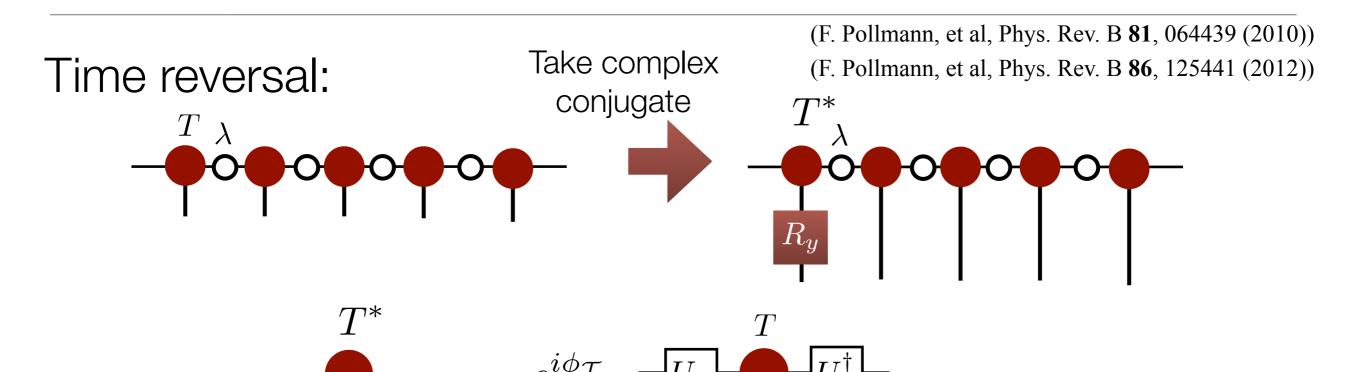
$$e^{2i\phi_{\mathcal{I}}} = 1, U_{\mathcal{I}}U_{\mathcal{I}}^* = e^{i\psi_{\mathcal{I}}}$$



$$\psi_{\mathcal{I}} = 0, \pi$$

Time reversal in iMPS

$$\mathcal{T}|\Psi\rangle = R_y|\Psi^*\rangle$$



From the same logic with the inversion,

$$U_{\mathcal{T}}U_{\mathcal{T}}^* = e^{i\psi_{\mathcal{T}}}$$
$$\psi_{\mathcal{T}} = 0, \pi$$

Set of rotations $R_x R_y |\Phi\rangle$

$$R_x R_y |\Phi\rangle$$

Single rotation always gives a trivial phase. However, set of rotations can be non-trivial.

(F. Pollmann, et al, Phys. Rev. B **86**, 125441 (2012))

$$R_x = e^{i\pi S_x}, R_y = e^{i\pi S_y}, R_z = e^{i\pi S_z}$$

$$T$$

$$= e^{i\phi_x} - U_x - U_x$$

(Similar relations for R_y and R_z)

From the relation $R_x R_z = R_z R_x = R_y$



$$U_x U_z = e^{i\psi_{\mathcal{D}_2}} U_z U_x$$

$$U_x U_z = e^{i\psi_{\mathcal{D}_2}} U_z U_x$$

$$U_x U_z U_x^{\dagger} U_z^{\dagger} = e^{i\psi_{\mathcal{D}_2}}$$

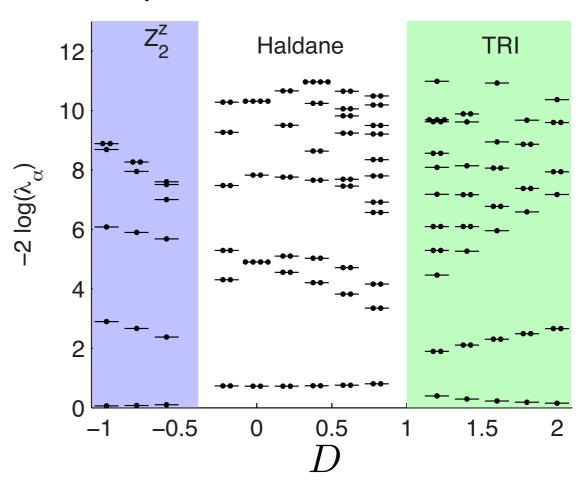
$$\phi_{\mathcal{D}_2} = 0, \pi$$

Expected behavior in Haldane and large-D phases

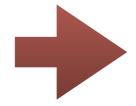
(F. Pollmann, et al, Phys. Rev. B 81, 064439 (2010))

Spectrum of Schmidt coefficient

Phase	Time reversal	Inversion	RxRz
Haldane	π	π	π
Large-D	0	0	0



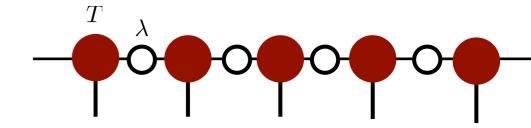
If the phase is π , all Schmidt coefficients are degenerated in even number.



By observing Schmidt coefficients, we can distinguish Haldane and large-D phases.

Detection of SPT from iMPS

- (F. Pollmann, et al, Phys. Rev. B **81**, 064439 (2010))
- (F. Pollmann, et al, Phys. Rev. B **86**, 125441 (2012))
- 1. Just observe λ and check the degeneracy

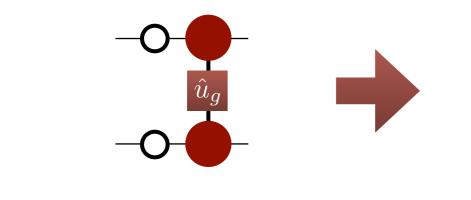


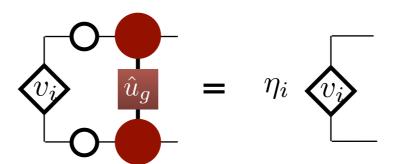
2. Directly calculate a non-trivial phase

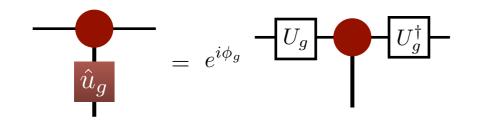
We can calculate the matrix Ug from a transfer matrix

Transfer matrix

eigen value problem









Dominant eigen vector is U_g $\eta = e^{-i\phi_g}, v_i = U_g^\dagger$

$$\eta = e^{-i\phi_g}, v_i = U_g^{\dagger}$$

Note: if the state does not have symmetry,

$$|\eta| < 1$$

Exercise 5: Observe entanglement spectrum

Simulate infinite system and output singular value λ .

Sample code: Ex5.py

python Ex5.py

- Compare degeneracies varying parameter "D"
 - In Haldane phase, all λs are expected to degenerated in even number
- By using TEBD (or ED) instead of iTEBD, check the degeneracy in a finite system

Exercise 6: Calculate non-trivial phases

Simulate infinite system and output $e^{i\psi}$ for

- Time reversal
- Inversion
- R_xR_y

 Sample code: Ex6.py
 python Ex6.py
- Compare phases varying parameter "D"
 - In Haldane phase, all phases are expected to be π, while it is 0 in large D phase.
 - Plot $e^{i\psi}$ as a function of D. (By combining Ex4.py and Ex6.py, you might make a code for this purpose.)
- For large negative D, the GS is an ordered state which breaks symmetries.
 - Check that the dominant eigenvalue of the transfer matrix is less than 1

Ex6.py

```
## time reversal
\mathbb{E}_{V} = \text{linalg.expm}(0.5*np.pi * (Sp -Sm))
eig, UTR = iTEBD.Transfer Matrix SPT TR(Tn, lam, Ry)
UTR= UTR.reshape(chi,chi).T
UTR /= np.sqrt(np.trace(np.dot(UTR,UTR.T.conj()))/chi)
print "##Time reversal",eig, np.trace(np.dot(UTR,UTR.conj()))/chi
## Inversion
eig_I, UI = iTEBD.Transfer_Matrix_Inv_bond(Tn,lam)
UI = UI.reshape(chi,chi).T
UI /= np.sqrt(np.trace(np.dot(UI,UI.T.conj()))/chi)
print "##Inversion",eig_I, np.trace(np.dot(UI,UI.conj()))/chi
## set of rotation (D2)
Rx = linalg.expm(0.5j * np.pi * (Sp+Sm))
Rz = linalg.expm(1.0j * np.pi * Sz)
eigx, Ux = iTEBD.Transfer_Matrix_SPT(Tn,lam,Rx)
eigz, Uz = iTEBD.Transfer_Matrix_SPT(Tn,lam,Rz)
Ux = Ux.reshape(chi,chi).T
Ux /= np.sqrt(np.trace(np.dot(Ux,Ux.T.conj()))/chi)
Uz = Uz.reshape(chi,chi).T
Uz /= np.sgrt(np.trace(np.dot(Uz,Uz.T.conj()))/chi)
print "##D2",eigx,eigz, np.trace(np.dot(np.dot(np.dot(Ux,Uz),Ux.T.conj()),Uz.T.conj()))/chi
```

Exponential of a matrix is easily calculated by

scipy.linalg.expm(Mat)

iTEBD.Transfer_Matrix_SPT(Tn,lam,op)
returns dominant eigenvalue
and eigenvectors for a symmetry

operator "op".

For time reversal and space inversion, we need special routines:

iTEBD.Transfer_Matrix_SPT_TR, iTEBD.Transfer_Matrix_Inv_bond,

to treat a "complex conjugate" and "transpose" operations.

$$U_{\mathcal{T}}U_{\mathcal{T}}^* = e^{i\psi_{\mathcal{T}}} \qquad \qquad \text{Tr } U_{\mathcal{T}}U_{\mathcal{T}}^* = \chi e^{i\phi_{\mathcal{T}}}$$

$$U_{\mathcal{I}}U_{\mathcal{I}}^* = e^{i\psi_{\mathcal{I}}} \qquad \qquad \text{Tr } U_{\mathcal{I}}U_{\mathcal{I}}^* = \chi e^{i\phi_{\mathcal{I}}}$$

$$U_xU_zU_x^{\dagger}U_z^{\dagger} = e^{i\psi_{\mathcal{D}_2}} \qquad \qquad \text{Tr } U_xU_zU_x^{\dagger}U_z^{\dagger} = \chi e^{i\phi_{\mathcal{D}_2}}$$