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Supplementary Information: Improving Monocular Depth Estimation with Global Depth Histogram Matching	
Anonymous CVPR submission	
Paper ID ****	

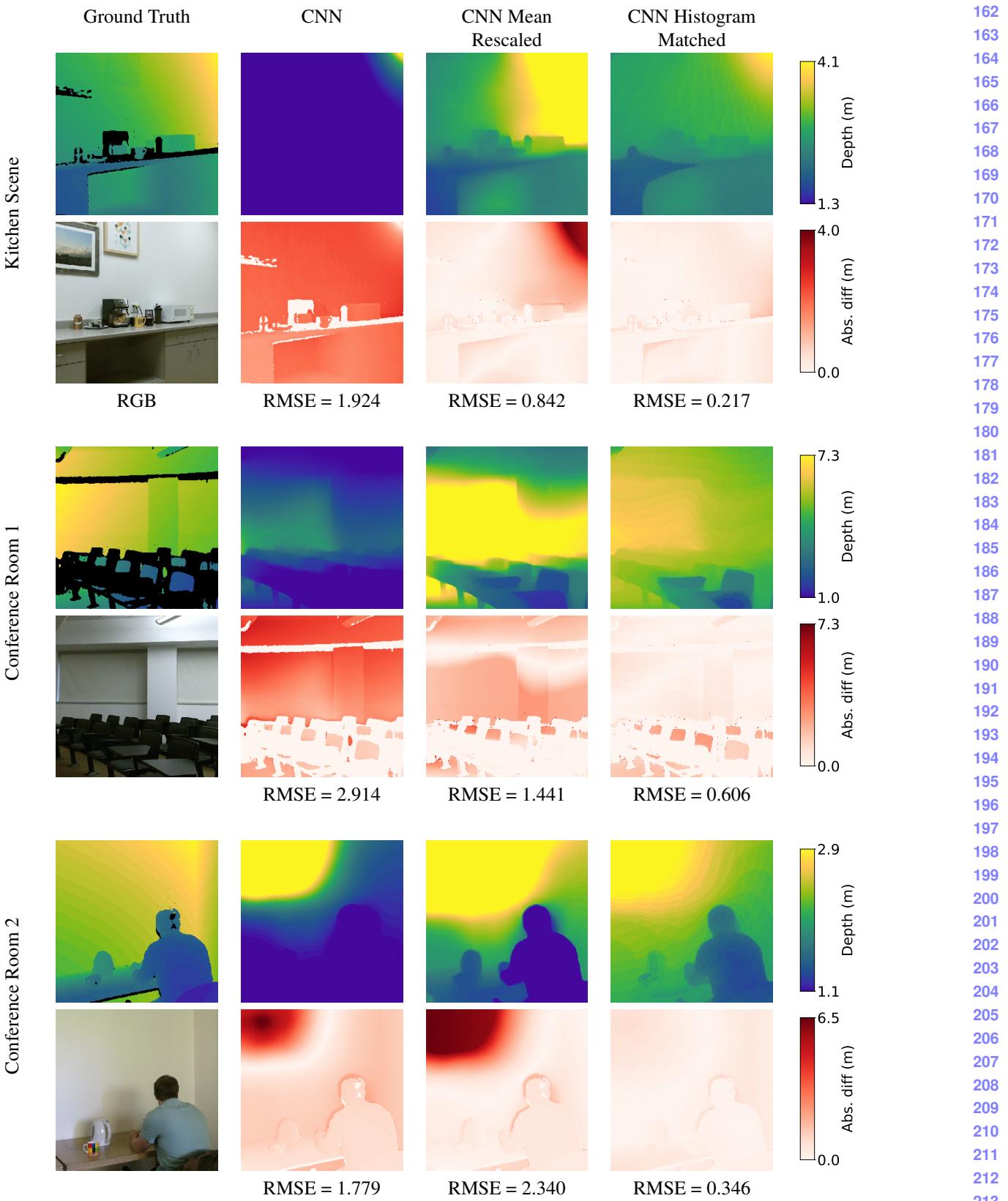


Figure 1: Captured results initialized using the MiDaS CNN. Second row shows absolute difference between above estimates and ground truth.

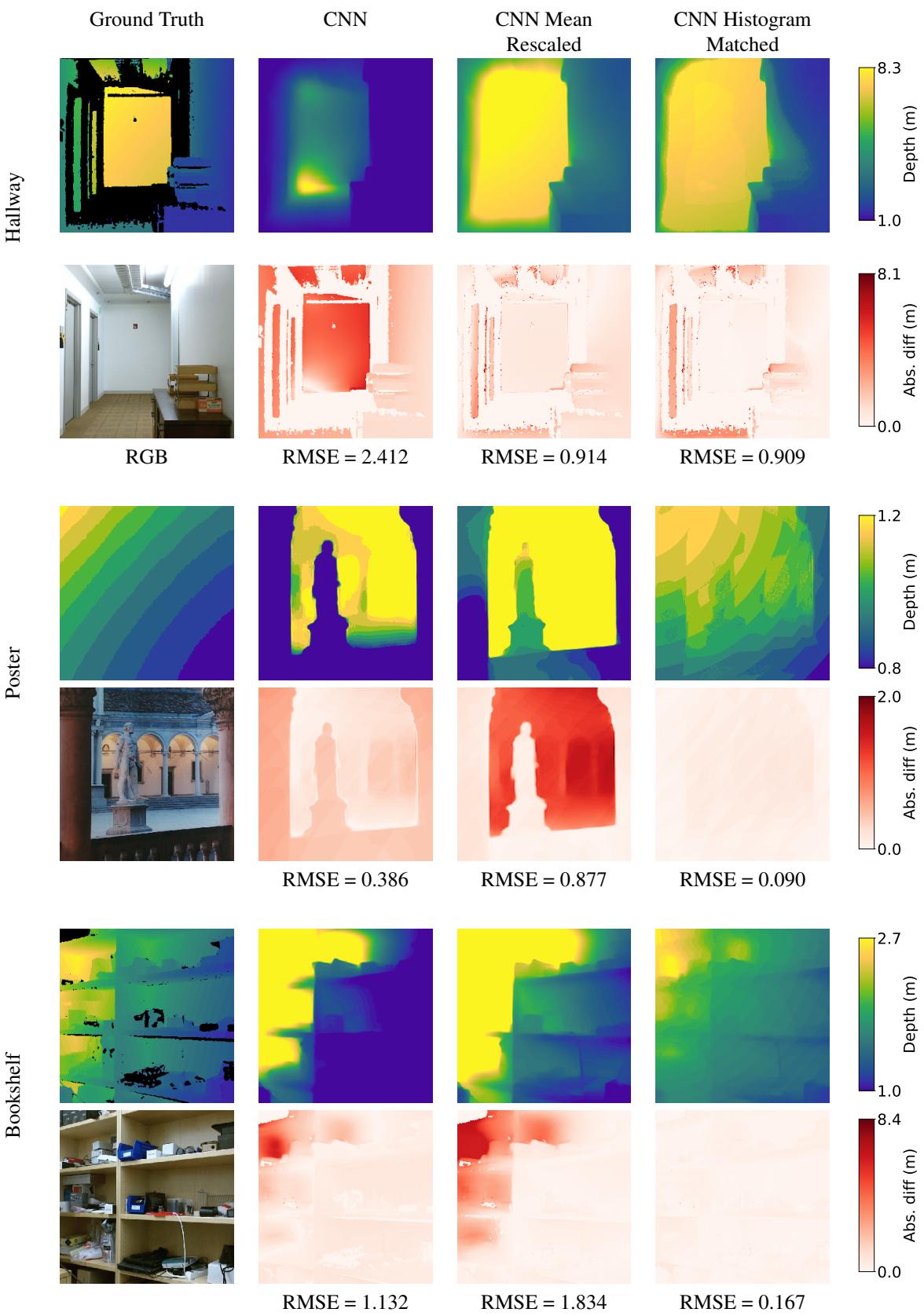


Figure 2: Captured results initialized using the MiDaS CNN. Second row shows absolute difference between above estimates and ground truth.

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Figure 3: Captured results initialized using the MiDaS CNN on an outdoor scene. Second row shows absolute difference between above estimates and ground truth.

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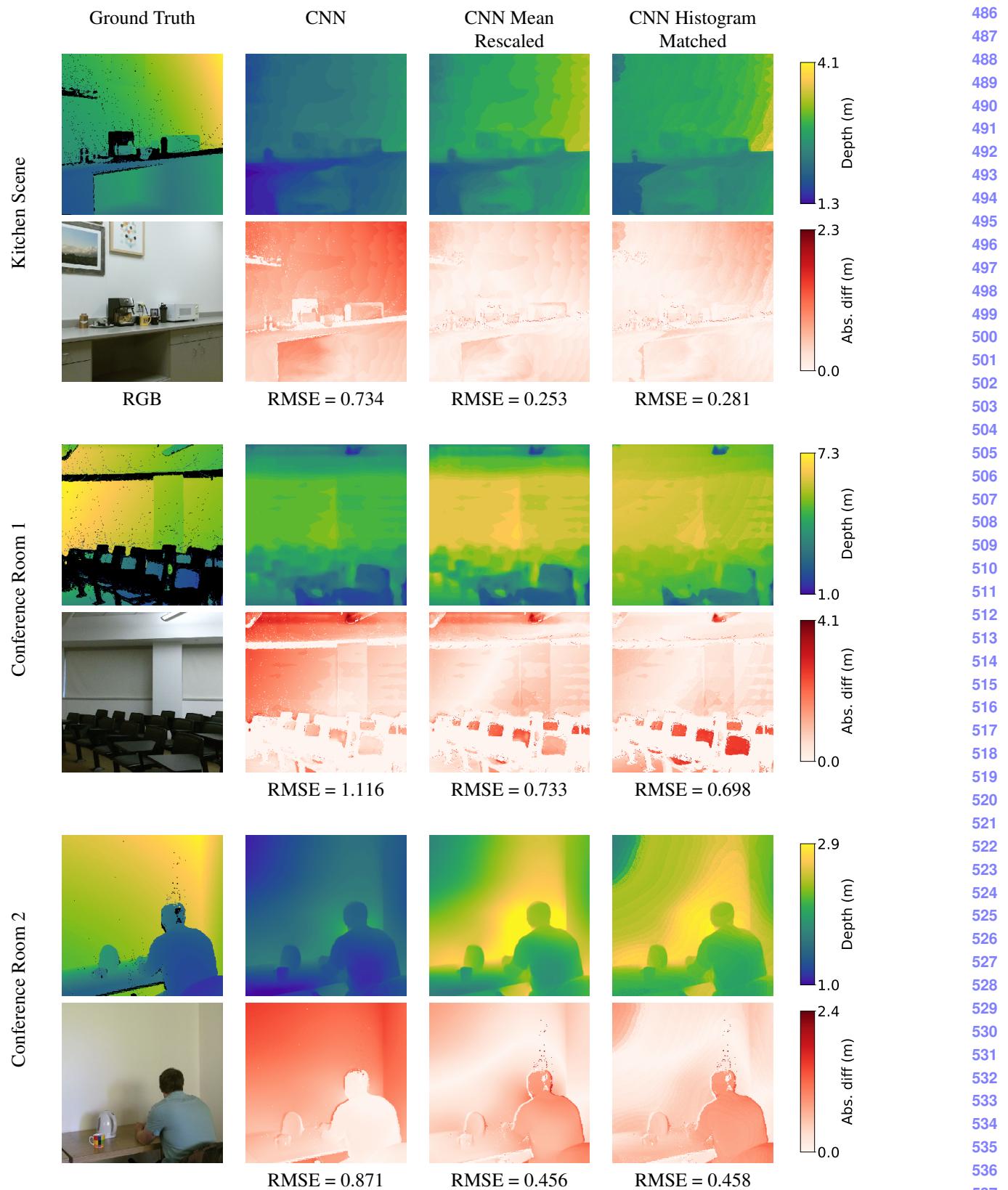


Figure 4: Captured results initialized using the DenseDepth CNN. Second row shows absolute difference between above estimates and ground truth.

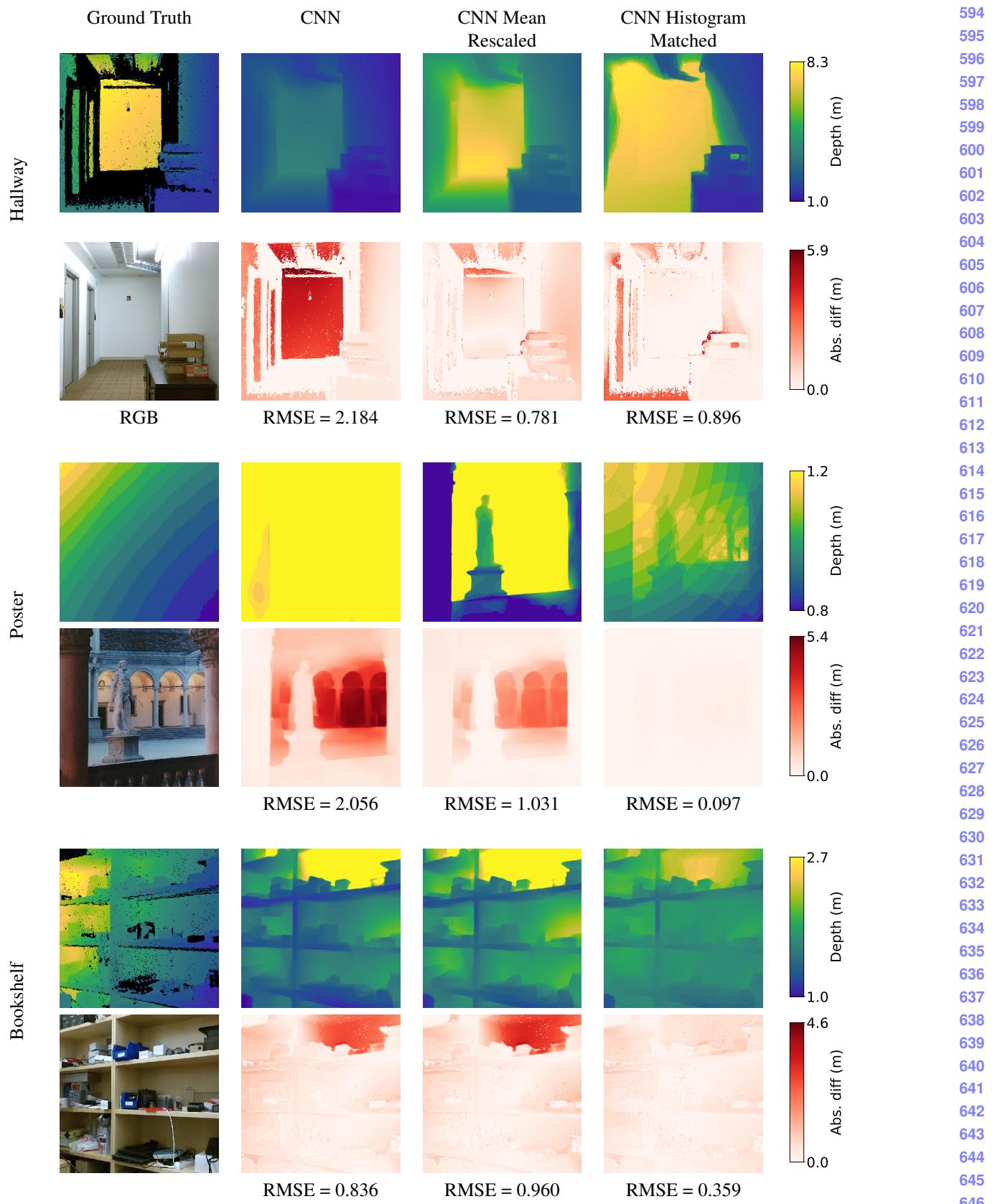


Figure 5: Captured results initialized using the DenseDepth CNN. Second row shows absolute difference between above estimates and ground truth.

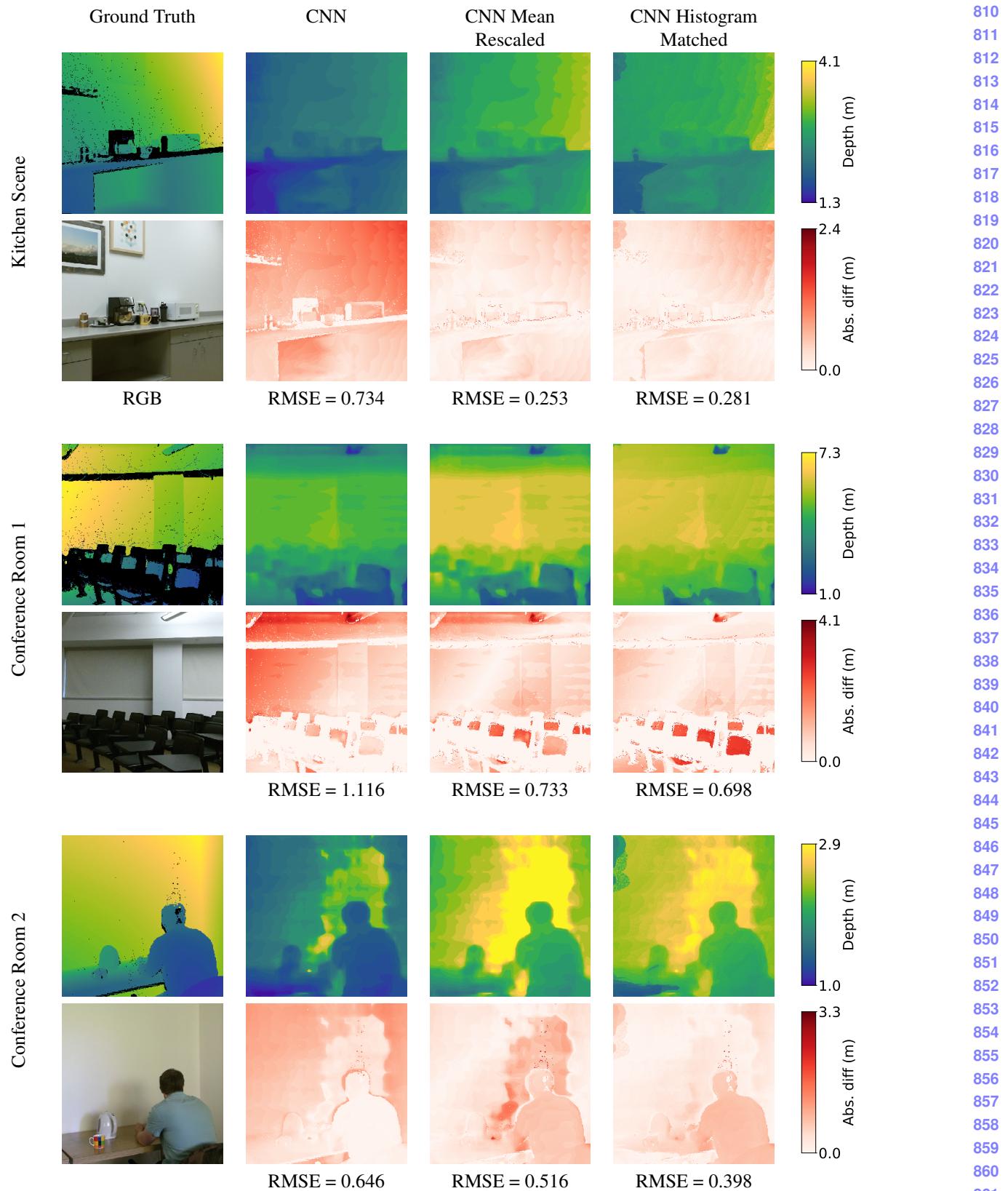


Figure 7: Captured results initialized using the DORN CNN. Second row shows absolute difference between above estimates and ground truth.

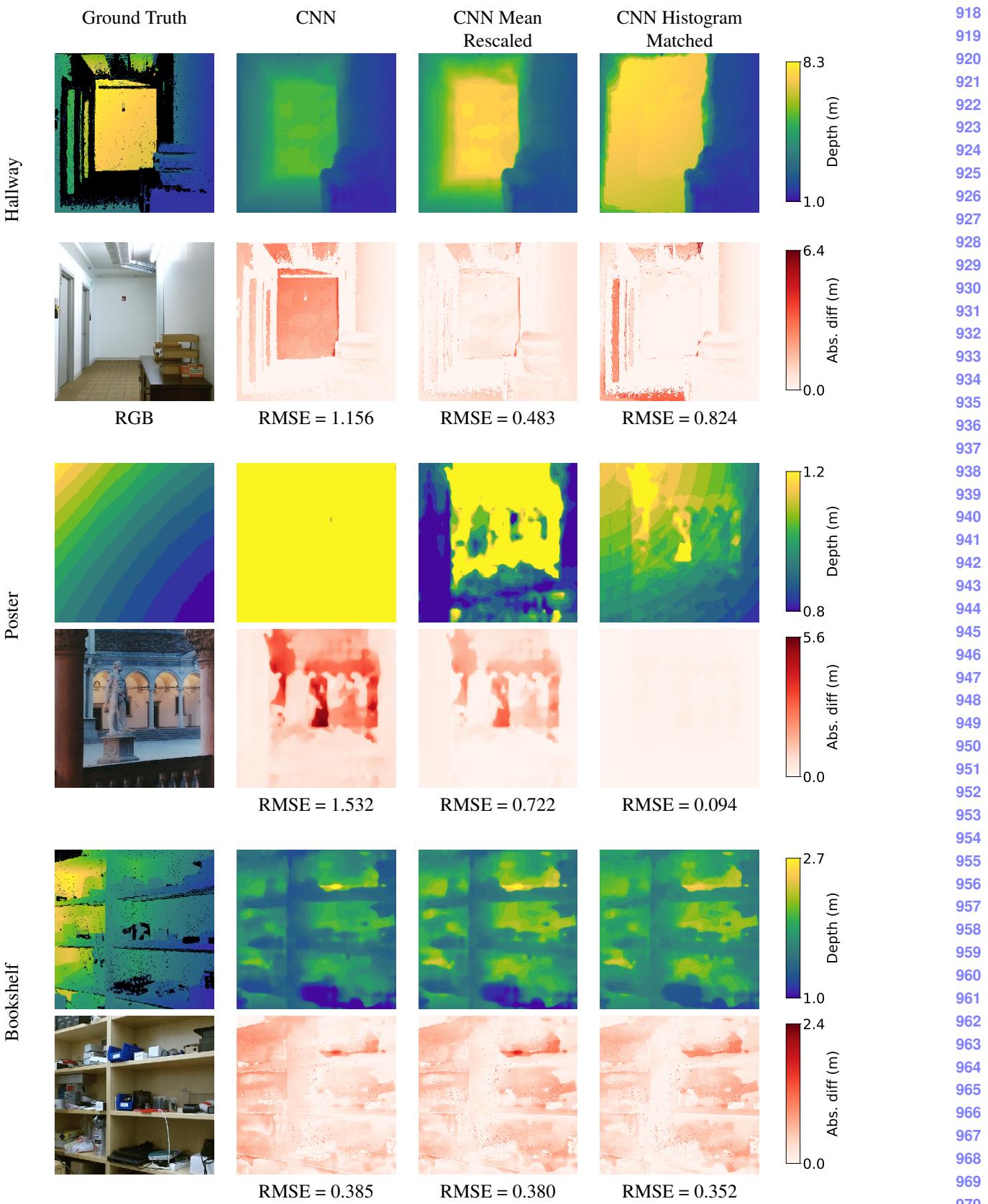


Figure 8: Captured results initialized using the DORN CNN. Second row shows absolute difference between above estimates and ground truth.

