

Dynamic causal modelling for fMRI

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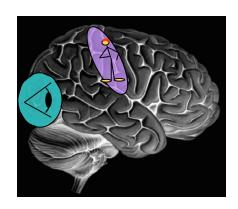
CPC 2018, Zürich, Switzerland

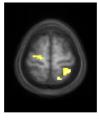




Specialisation vs. Integration

Functional Specialisation



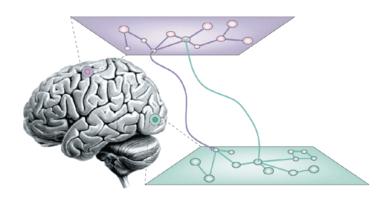


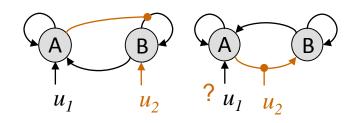
 u_1



«Where, in the brain, did my experimental manipulation have an effect?»

Functional Integration





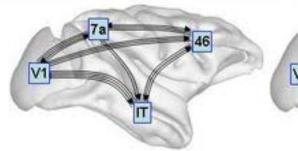
«How did my experimental manipulation propagate through the network?»

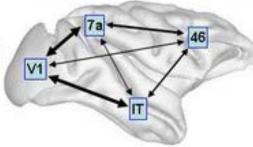


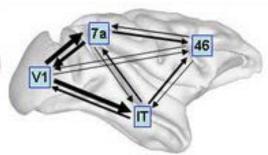




Structural, functional & effective connectivity







Sporns 2007, Scholarpedia

anatomical/structural

presence of physical connections

→ DWI, tractography, tracer studies (animals)

functional

statistical
 dependency between
 regional time series

→ correlations, ICA

effective

direct influences
 between neuronal
 populations

 $\rightarrow DCM$

Context-independent

Mechanism - free

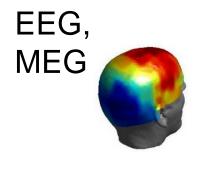
Mechanistic





fMRI

Dynamic causal modelling



Model inversion:

Estimating neuronal mechanisms

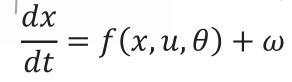
Forward model:

Predicting measured activity

$$y = g(x, \theta) + \varepsilon$$

DCM for EEG

- → Next lecture
- → Dario Schöbi



State equation:

Describing neuronal dynamics (and hemodynamics)







Dynamic causal modelling



Available online at www.sciencedirect.com



NeuroImage

NeuroImage 19 (2003) 1273-1302

www.elsevier.com/locate/ynimg

Dynamic causal modelling

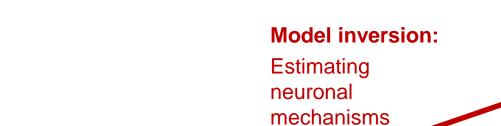
K.J. Friston,* L. Harrison, and W. Penny

The Wellcome Department of Imaging Neuroscience, Institute of Neurology, Queen Square, London WC1N 3BG, UK

Received 18 October 2002; revised 7 March 2003; accepted 2 April 2003



DCM for fMRI - Overview





fMRI

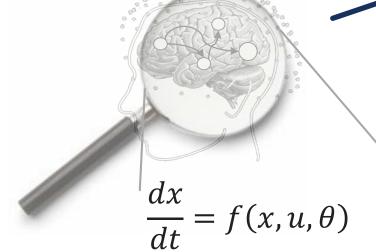
Forward model:

Predicting measured activity

$$y = g(x, \theta) + \varepsilon$$

Neural state equation:

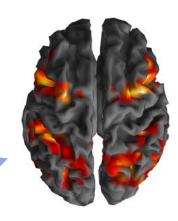
Describing neuronal dynamics



DCM for fMRI - Overview



Estimating neuronal mechanisms



fMRI

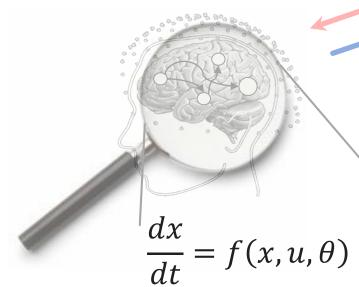


Predicting measured activity

$$y = g(x, \theta) + \varepsilon$$

Neural state equation:

Describing neuronal dynamics







$$\frac{dx}{dt} = f(x, u)$$

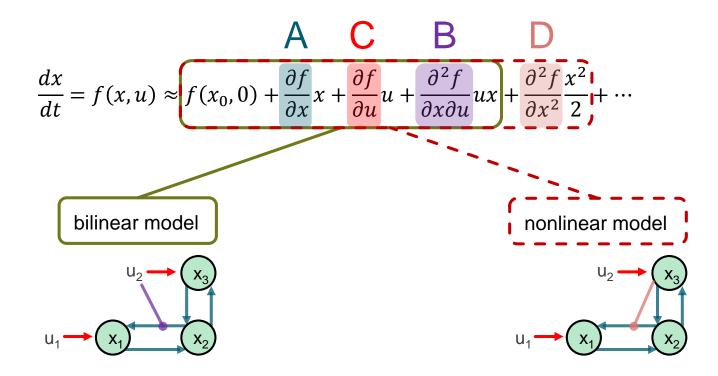


$$\frac{dx}{dt} = f(x, u) \approx \left[f(x_0, 0) + \frac{\partial f}{\partial x} x + \frac{\partial f}{\partial u} u + \frac{\partial^2 f}{\partial x \partial u} u x \right] + \frac{\partial^2 f}{\partial x^2} \frac{x^2}{2} + \cdots$$

bilinear model



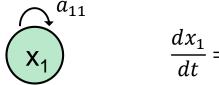




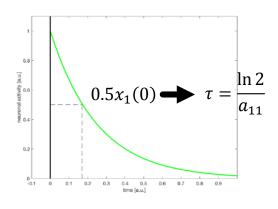
FIH zürich

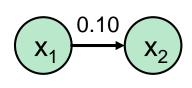
Neuronal state equations

DCM effective connectivity parameters are rate constants



$$\frac{dx_1}{dt} = a_{11}x_1 \qquad \longrightarrow \qquad x_1(t) = x_1(0) \cdot exp(a_{11}t)$$



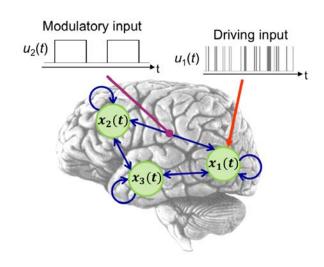


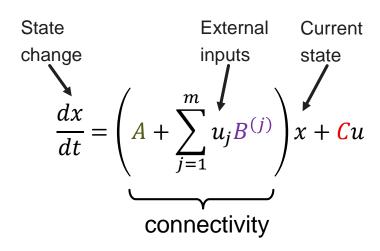
If $region_1 \rightarrow region_2$ is 0.10s⁻¹, this means that, per unit time, the increase in activity in $region_2$ corresponds to 10% of the current activity in $region_1$





Interim summary: bilinear neuronal state equation





$$\theta = \{A, B^{(1)}, \dots, B^{(m)}, C\}$$
 Endogenous Modulatory Driving connectivity connectivity inputs

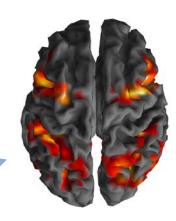




DCM for fMRI - Overview



Estimating neuronal mechanisms



fMRI



Predicting measured activity

$$y = g(x, \theta) + \varepsilon$$

$\frac{dx_h}{dt} = f_h(x_h, x, \theta)$

Hemodynamic state equation:

Describing hemodynamics





The hemodynamic response

Neuronal dynamics only indirectly observable via hemodynamic response

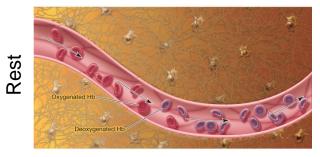
neuronal activity

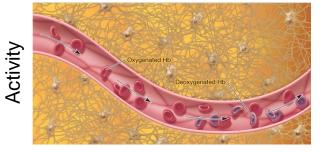
blood flow

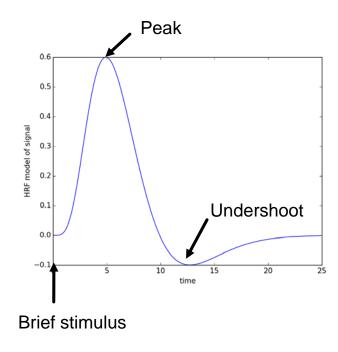
oxygenated Hb

↑ _{T2*}

fMRI signal











The hemodynamic model

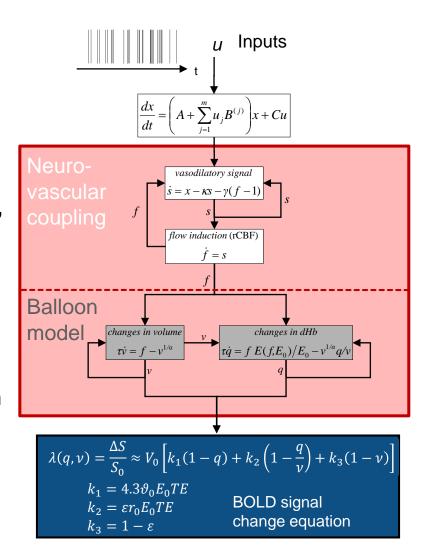
6 parameters:

$$\theta^h = \{\kappa, \gamma, \tau, \alpha, \rho, \varepsilon\}$$

Important for model fitting, but typically of no interest for statistical inference.

Region specific HRF

→ Parameters computed separately for each region



State equation

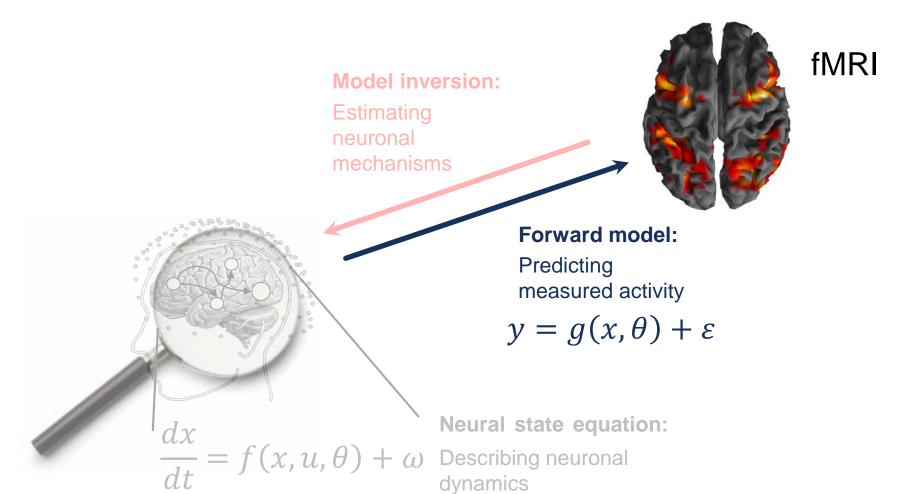
neural

hemodynamic





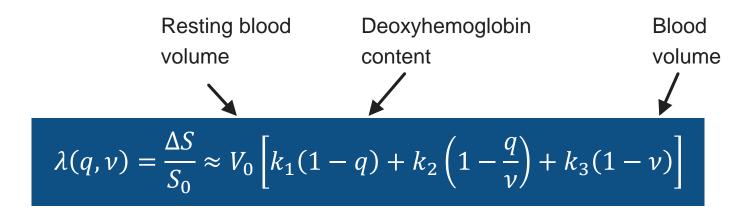
DCM for fMRI - Overview







The BOLD signal equation



BOLD-Signal Parameters:

$$k_1 = 4.3\vartheta_0 E_0 T E$$

$$k_2 = \varepsilon r_0 E_0 T E$$

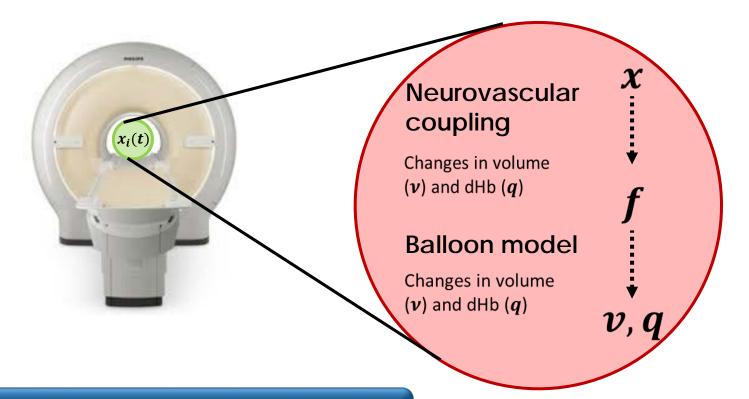
$$k_3 = 1 - \varepsilon$$

$$V_0 = 0.04$$
 $E_0 = 0.32 - 0.4$ At 1.5 Tesla At 3 Tesla At 7 Tesla $\vartheta_0 \approx 40.3 \, \mathrm{s}^{-1}$ $\vartheta_0 \approx 80.6 \, \mathrm{s}^{-1}$ $\vartheta_0 \approx 188 \, \mathrm{s}^{-1}$ $r_0 \approx 25 \, \mathrm{s}^{-1}$ $r_0 \approx 110 \, \mathrm{s}^{-1}$ $r_0 \approx 340 \, \mathrm{s}^{-1}$ $TE \approx 0.04 \, \mathrm{s}$ $TE \approx 0.035 \, \mathrm{s}$ $TE \approx 0.025 \, \mathrm{s}$ $\varepsilon \approx 1.28$ $\varepsilon \approx 0.47$ $\varepsilon \approx 0.026$





From neural activity to the BOLD signal: Summary



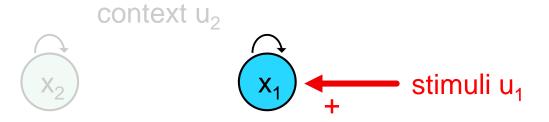
BOLD signal is a **direct function** of ν and q

$$y = \frac{\Delta S}{S_0} = g(v, q) + \varepsilon$$



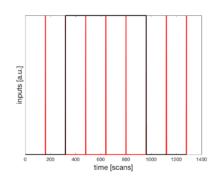


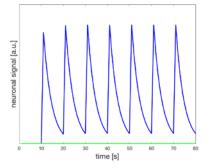
Example: single node

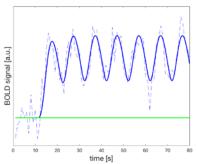


$$\frac{dx}{dt} = Ax + u_2 B^{(2)} x + C u_1$$

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} a_{11} & 0 \\ 0 & a_{22} \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + u_2 \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} c_{11} & 0 \\ 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$$



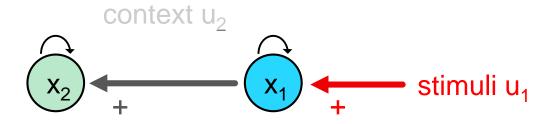






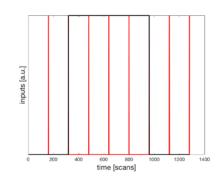


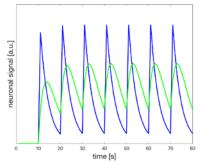
Example: two connected node

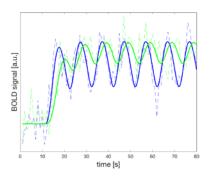


$$\frac{dx}{dt} = Ax + u_2 B^{(2)} x + C u_1$$

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} a_{11} & 0 \\ a_{21} & a_{22} \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + u_2 \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} c_{11} & 0 \\ 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$$



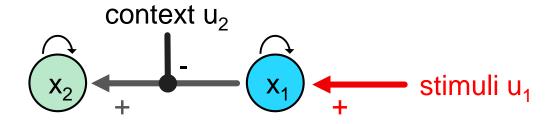






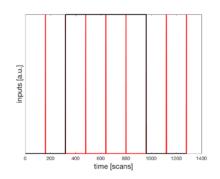


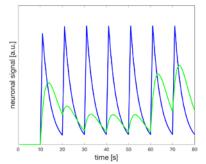
Example: modulation of connection

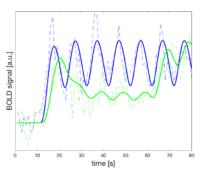


$$\frac{dx}{dt} = Ax + u_2 B^{(2)} x + C u_1$$

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} a_{11} & 0 \\ a_{21} & a_{22} \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + u_2 \begin{bmatrix} 0 & 0 \\ b_{21}^{(2)} & 0 \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} c_{11} & 0 \\ 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$$



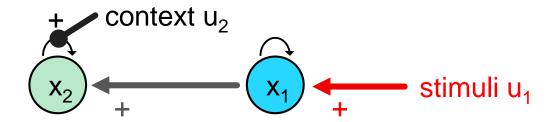






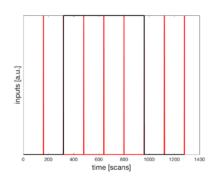


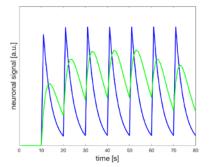
Example: modulation of inhibitory self-connection

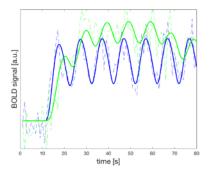


$$\frac{dx}{dt} = Ax + u_2 B^{(2)} x + C u_1$$

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} a_{11} & 0 \\ a_{21} & a_{22} \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + u_2 \begin{bmatrix} 0 & 0 \\ 0 & b_{22}^{(2)} \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} c_{11} & 0 \\ 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$$







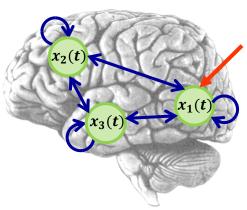




DCM for fMRI

A simple model of a neural network

. . .





Neural node



Input



Connections

... described as a dynamical system

. . .

 $\dot{x} = f(x, u, \theta)$

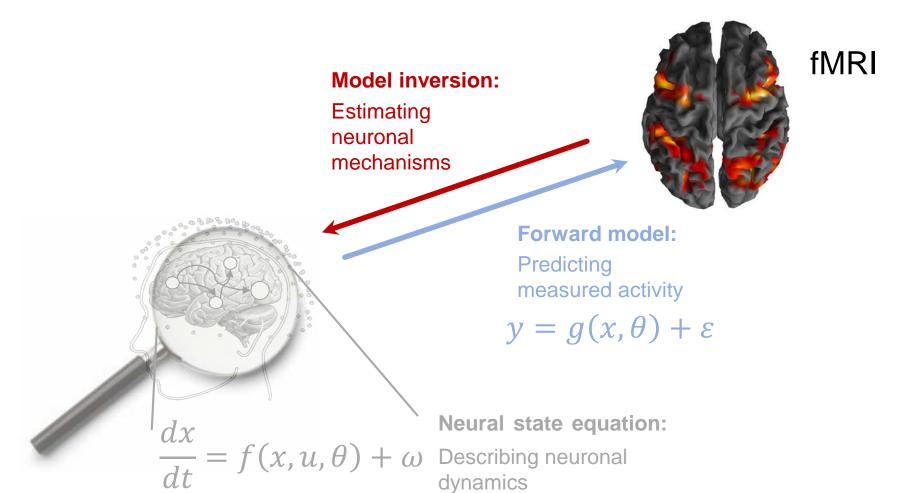
$$y = g(x, \theta) + \varepsilon$$

Let the system run with input (u) and parameters (θ) , and you will get a BOLD signal time course y that you can compare to the measured data.





DCM for fMRI - Overview





Bayes' theorem



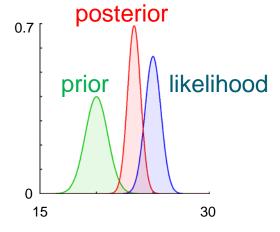
Reverend Thomas Bayes (1702-1761)

$$p(\theta|y,m) = \frac{p(y|\theta,m)p(\theta|m)}{p(y|m)}$$

$$p(y|m)$$

$$p(y|m)$$

$$p(y|m)$$





The likelihood function for DCM

$$p(y(t)|\theta,m) = \mathcal{N}(y(t); g(\theta^n, \theta^h, u), \theta^\sigma)$$
likelihood

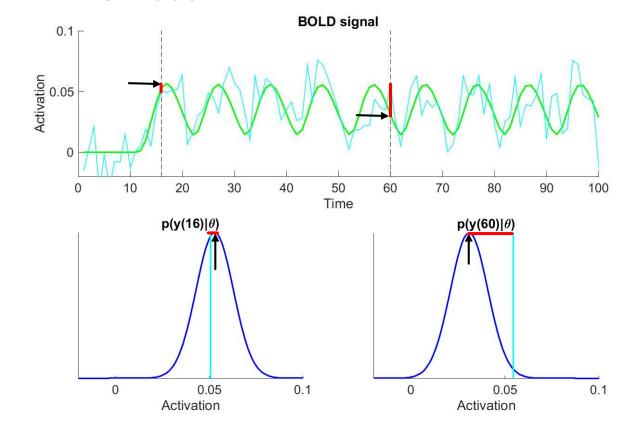
Assume data is normally distributed around the prediction from the dynamical model (Gaussian noise)





The likelihood function for DCM

$$p(y(t)|\theta,m) = \mathcal{N}(y(t); g(\theta^n, \theta^h, u), \theta^\sigma)$$
 likelihood





Priors

$$p(\theta|y,m) = \frac{p(y|\theta,m)p(\theta|m)}{p(y|m)}$$

Neuronal parameters:

- self-connections: principled (to ensure that the system is stable)
- other parameters (between—region connections, modulation, inputs): shrinkage priors

Hemodynamic parameters:

empirical

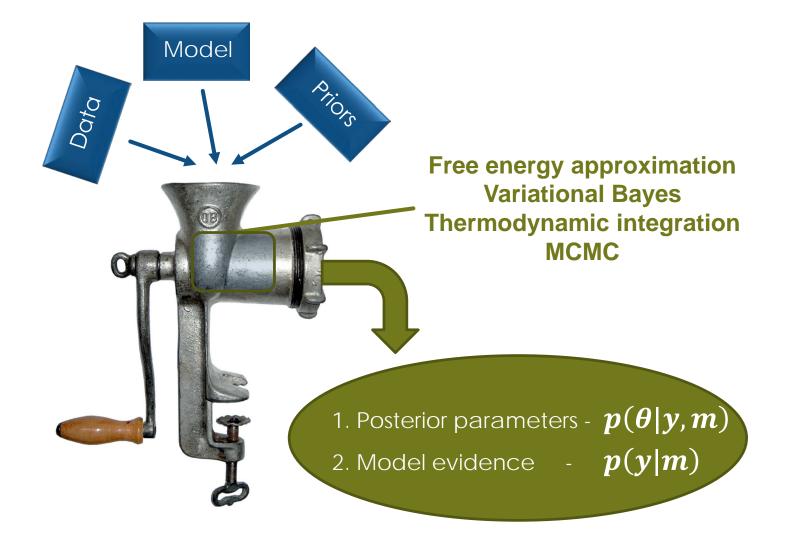
Noise prior:

assume relatively noisy data





Model estimation: running the machinery







Inversion – variational Free Energy approximation to model evidence

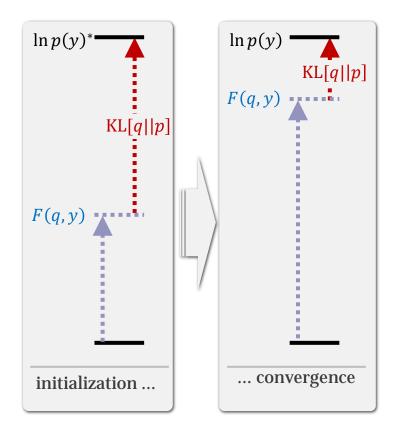
model evidence

$$\ln p(y) = \text{KL}[q||p] + F(q,y)$$

divergence neg. free energy

 ≥ 0 (easy to evaluate for a given q)

When F(q, y) is maximized, $q(\theta)$ is our best estimate of the true posterior.

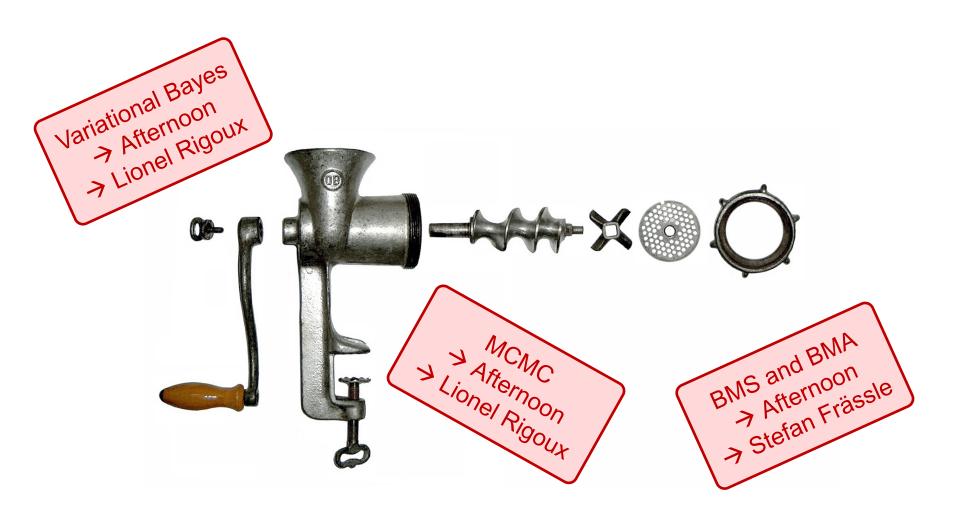








Model estimation: running the machinery

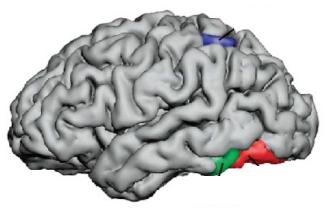






Example: Model Selection

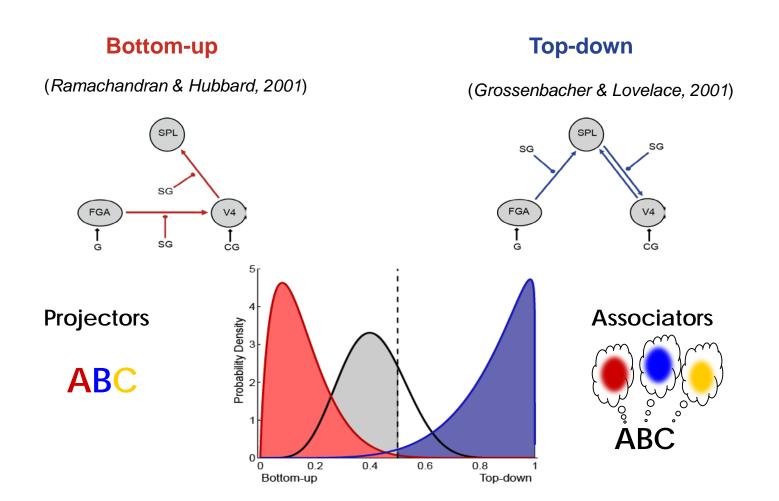
- Specific sensory stimuli lead to unusual, additional experiences
- Grapheme-color synesthesia: color
- Involuntary, automatic; stable over time, prevalence ~4%
- Potential cause: aberrant cross-activation/coupling between brain areas
 - grapheme encoding area (FGA)
 - color area V4
 - superior parietal lobule (SPL)







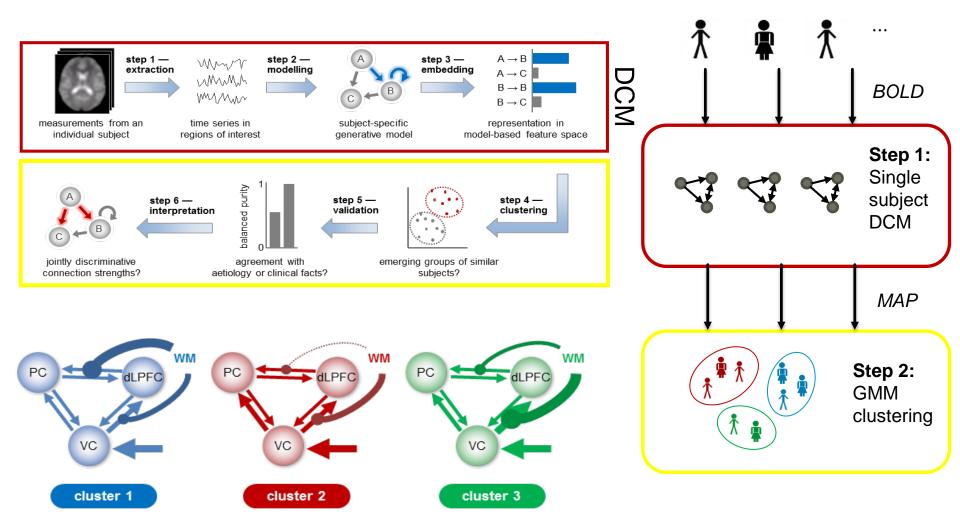
Bottom-up or Top-down "cross-activation"?







Example: DCM for physiologically plausible feature extraction







What questions can we answer using DCM?

Model comparison

What is the functional architecture of a network of brain regions?

→ Synesthesia

Are optimal models different between groups?

→ Synesthesia

Which connections are modulated by experimental manipulations?

Parameter inference

Are parameters different between individuals/groups?

Use parameters as physiologically informed summary statistics

→ Generative embedding

... and of course many more!





DCM software note

Basic functionality for DCM for fMRI is provided within

SPM

https://www.fil.ion.ucl.ac.uk/spm/





Limitations

- Local minima:
 - Variational approximation can get stuck in local minima of free energy
- Size of networks:
 - Standard inversion gets prohibitively slow for large networks (more than 10 nodes).
- Regularization through fixed priors:
 - Current regularization depends on priors only. Regularization based on group (all subjects) would be better → empirical Bayes.



Recent additions to DCM for fMRI

- Massively parallel dynamic causal modelling
 - mpdcm

Eduardo Aponte



- Regression dynamic causal modelling
 - rDCM

Stefan Frässle



- Hierarchical unsupervised generative embedding
 - HUGE

Yu Yao

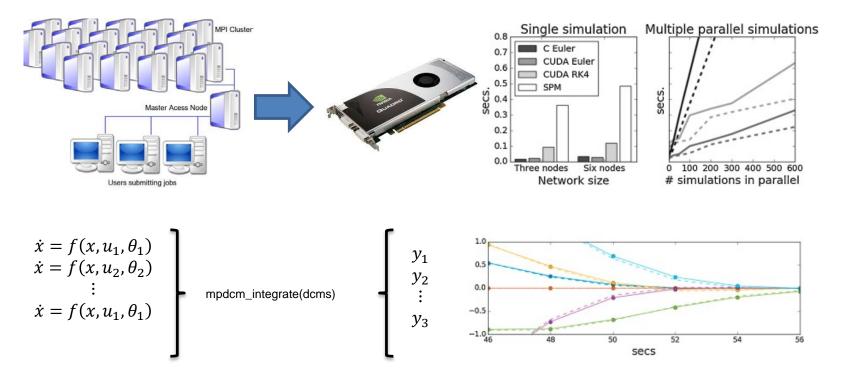


Available in TAPAS: www.translationalneuromodeling.org/tapas





Massively parallel DCM - mpdcm



- Fast inversion of DCMs
- MCMC based inversion possible
- → Thermodynamic Integration (alternative to Free Energy)





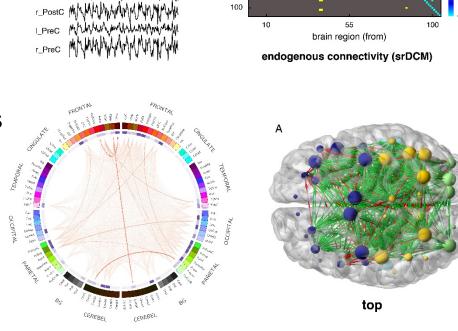
AAL parcellation

BOLD signal time series



Regression DCM - rDCM

- Extremely efficient model inversion
- Graceful scaling to large networks
- Network pruning as part of model inversion (sparsity constraints)
- Inference of whole-brain connectogram (~100 nodes and 10000 connections)



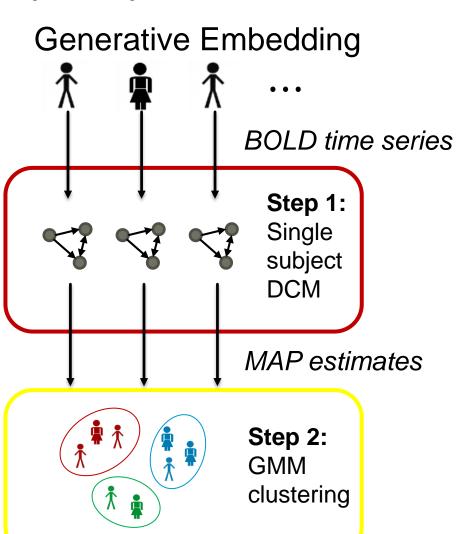
orain region (to)

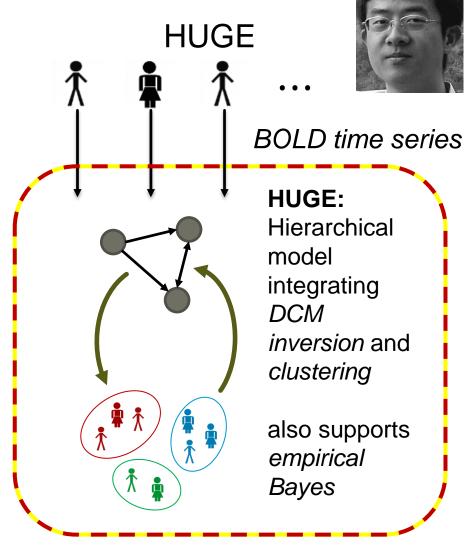






Hierarchical Unsupervised Generative Embedding (HUGE)

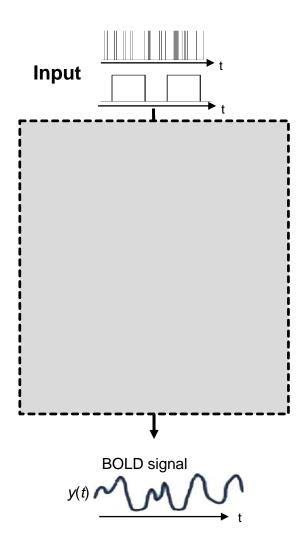








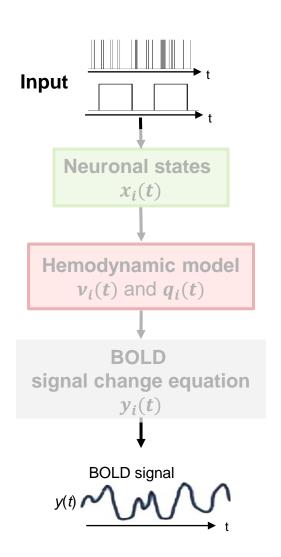
Summary – Generative model

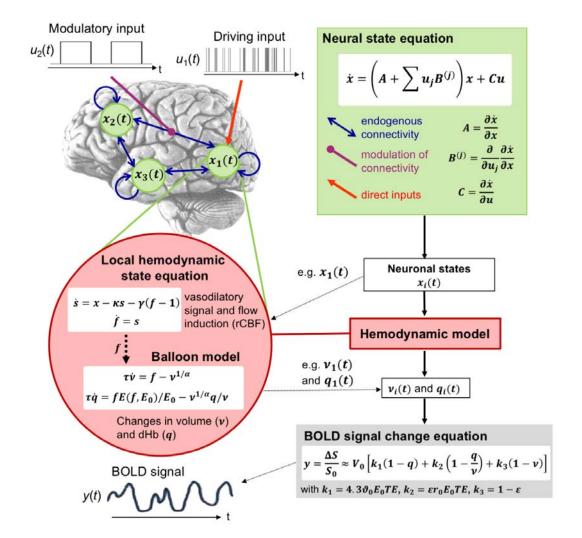






Summary – Generative Model





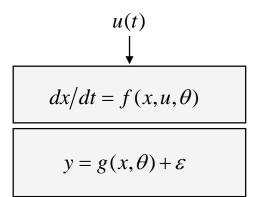




Summary - Bayesian System Identification

Neural (and hemo-) dynamics

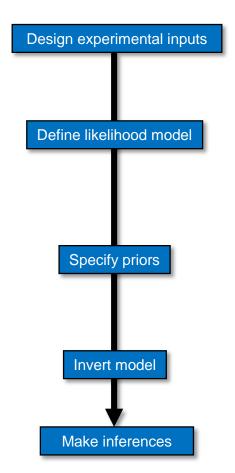
Observer function



$$p(y \mid \theta, m) = N(g(\theta), \Sigma(\theta))$$
$$p(\theta, m) = N(\mu_{\theta}, \Sigma_{\theta})$$

Inference on model structure
Inference on parameters

$$p(y \mid m) = \int p(y \mid \theta, m) p(\theta) d\theta$$
$$p(\theta \mid y, m) = \frac{p(y \mid \theta, m) p(\theta, m)}{p(y \mid m)}$$







Thank you!

Many thanks to Stefan Frässle, Klaas Enno Stephan, Hanneke den Ouden and Jean Daunizeau for many of the slides!

List with suggested DCM literature in Appendix of this presentation!

DCM literature (1)

- Aponte EA, Raman S, Sengupta B, Penny WD, Stephan KE, Heinzle J (2016). mpdcm: A Toolbox for Massively Parallel Dynamic Causal Modeling. Journal of Neuroscience Methods 257: 7-16.
- Brodersen KH, Schofield TM, Leff AP, Ong CS, Lomakina EI, Buhmann JM, Stephan KE (2011) Generative embedding for model-based classification of fMRI data. PLoS Computational Biology 7: e1002079.
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