

# Model inversion: Variational Bayes and Markov Chain Monte Carlo

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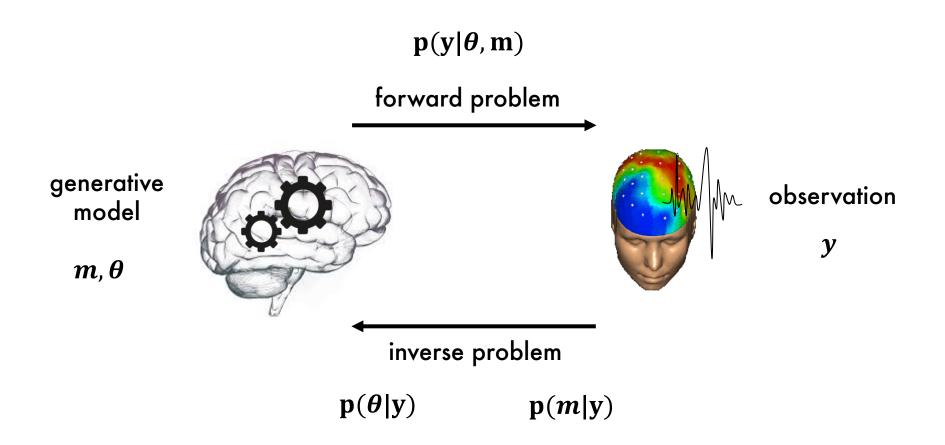
## Overview

Bayesian inference

Sampling methods

Variational methods

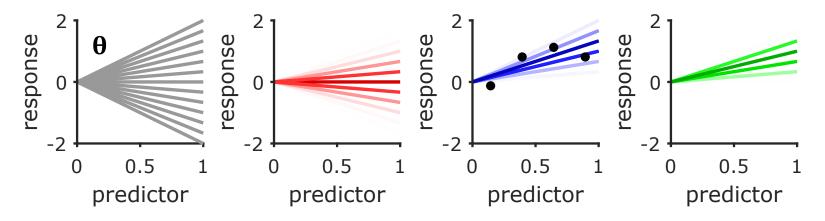
# Model inversion



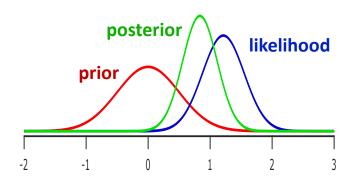
# Bayes rule

#### Linear regression

$$\begin{array}{ll} \text{model} & \text{prior} & \text{likelihood} & \text{posterior} \\ y = \theta \ x + \epsilon & \\ \epsilon = \mathcal{N} \big( 0, \sigma_v^2 \big) & \mathbf{p} \big( \mathbf{0}, \sigma_p^2 \, \big) & \mathbf{p} \big( \mathbf{y} | \theta \big) = \mathcal{N} \big( \theta \ x, \sigma_y^2 \big) & \mathbf{p} \big( \theta | \mathbf{y} \big) \end{array}$$



$$p(\theta|y,m) = \frac{p(\theta|m) p(y|\theta,m)}{p(y|m)}$$



# Inference in practice

How to compute the posterior?

- Write  $p(\theta|m) p(y|\theta,m)$ 
  - 1. recognize it looks like a know distribution (conjugacy)

$$\begin{array}{ll} p(\theta|m) &= \boldsymbol{\mathcal{N}}(\mu_0, \sigma_0^2) \\ p(y|\theta, m) &= \boldsymbol{\mathcal{N}}(\theta, \sigma_y^2) \end{array} \quad \Rightarrow \quad \begin{array}{ll} p(\theta|y, m) &= \boldsymbol{\mathcal{N}}(\mu', \sigma^2{}') \\ p(y|m) &= [analytical \ solution] \end{array}$$

$$\sigma^{2'} = \left(\frac{1}{\sigma_0^2} + \frac{n}{\sigma_v^2}\right)^{-1} \qquad \mu' = \left(\sigma^{2'}\right)^{-1} \left(\frac{\mu_0}{\sigma_0^2} + \frac{\sum_n y_n}{\sigma_y^2}\right)$$

2. use variational Bayes or Monte Carlo methods

## Monte-Carlo methods



If you can not calculate it, simulate many random trials and see what happens...

## Law of large numbers

- simulate many independent draws of a random variable
- the average of the results will converge to the true expected value (probability mean)

$$E[\theta] = \int p(\theta|y,m)\theta \approx \frac{1}{n} \sum_{n} \theta_{n}$$

# A little game

## The un-normalized posterior:

$$p(\theta|y,m) \propto p(\theta|m) p(y|\theta,m) = \widetilde{p}(\theta|y,m)$$

- is not a probability
- gives the relative plausibility of parameter values



# Markov Chain sampling

Markov Chain: stochastic process that evolve in time

- initial state  $\theta_0$
- state evolve following a transition function  $T(\theta_{t+1}|\theta_t)$
- > In the long run the probability of visiting  $\theta$  is called the ergodic density

# Metropolis Hastings algorithm

## The Metropolis-Hastings algorithm

- start form  $\theta_0$
- propose a new value according to  $T'(\theta'|\theta_t)$
- look for guidance





$$\mathbf{r} = \frac{\widetilde{\mathbf{p}}(\boldsymbol{\theta}'|\mathbf{y}, \mathbf{m})}{\widetilde{\mathbf{p}}(\boldsymbol{\theta}_t|\mathbf{y}, \mathbf{m})}$$



$$\theta_{t+1} = \theta'$$

jump to proposed value

$$\begin{aligned} \text{if } r > X \sim U(0,1) \\ \theta_{t+1} = \theta' \end{aligned}$$

else

$$\theta_{t+1} = \theta_t$$

ergodic density =  $p(\theta|y, m)$ 

# Metropolis Hastings algorithm: example

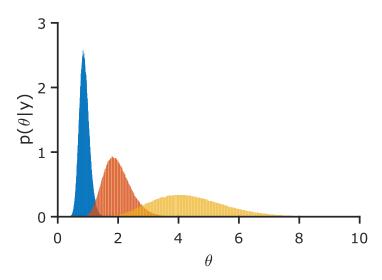
## Logistic regression

$$\mathbf{p}(\mathbf{y} = \mathbf{1}|\mathbf{\theta}) = \mathbf{s}(\mathbf{\theta}\mathbf{x})$$

$$\mathbf{p}(\mathbf{\theta}) = \mathcal{N}(\mathbf{0}, \mathbf{\sigma}_0^2)$$

$$\mathbf{s} = \frac{\mathbf{1}}{\mathbf{1} + \mathbf{e}^{-\mathbf{x}}}$$

$$\widetilde{\mathbf{p}}(\boldsymbol{\theta}|\mathbf{y}) = \exp\left(-\frac{\boldsymbol{\theta}^2}{2\sigma_0^2}\right) \times \prod_{\mathbf{y}} \mathbf{s}(\boldsymbol{\theta}\mathbf{x})^{\mathbf{y}} \left(\mathbf{1} - \mathbf{s}(\boldsymbol{\theta}\mathbf{x})\right)^{1-\mathbf{y}}$$



# Inference using sampling

#### Multivariate case:

- write conditional posteriors  $\mathbf{p}(\mathbf{\theta}^1|\mathbf{y},\mathbf{\theta}^2,\mathbf{\theta}^3,...,\mathbf{\theta}^n)$
- sample in turn  $\theta^1$ ,  $\theta^2$ , etc.

#### Further tricks

- Gibbs sampling (conditional has a known form)
- Collapsing (marginalization)
- Blocking (multivariate sampling)
- Adaptive step, Langevin, ...

## Monte-Carlo inference

Sample in turn from all the conditional (Gibbs) or the un-normalized conditional (Markov chain/Metropolis-Hastings) posterior.

> Sufficient statistics converge to the true value.

#### **Problems:**

- computationally expensive
- does not scale well
- no direct measure of model evidence (Chib & Jeliazkov estimator)
- hard to tune and diagnose (jump size, burn in, sample autocorrelation, convergence, ...)

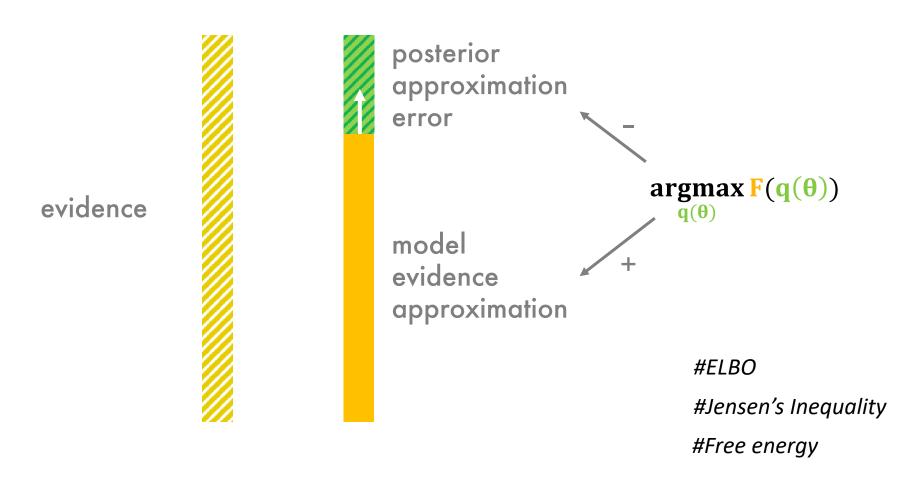
# Variational inference

"variational inference is the thing you implement while you wait for your sampler to converge"

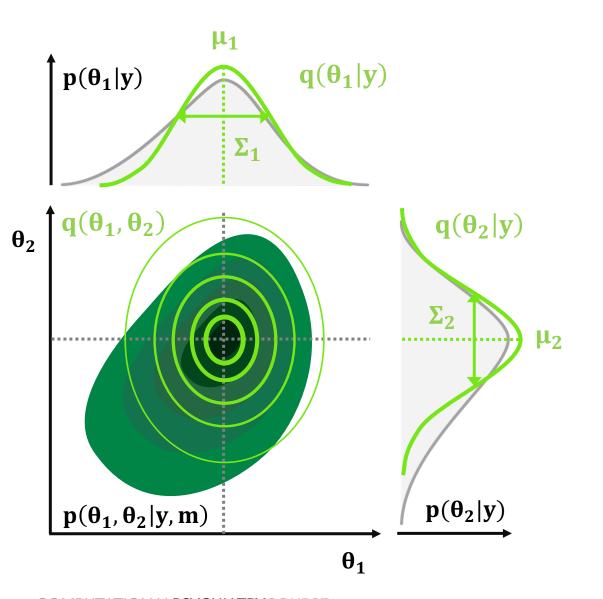
David Blei

#### Free Energy approximation

$$\log p(y|m) = F(q(\theta), y) + KL[q(\theta)||p(\theta|y, m)]$$



## Posterior approximation

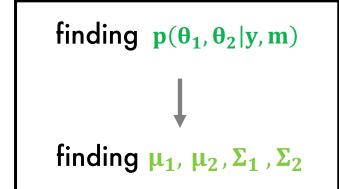


#### Mean field approximation

$$p(\theta_1,\theta_2|y)\approx p(\theta_1|y)p(\theta_2|y)$$

#### Laplace approximation

$$q(\theta_i|y) \approx \mathcal{N}(\mu_i, \Sigma_i)$$



#### Free Energy maximization

Approximating the model evidence = maximizing the ELBO wrt  $q(\theta)$ 

1) Maximize the free energy using variational calculus

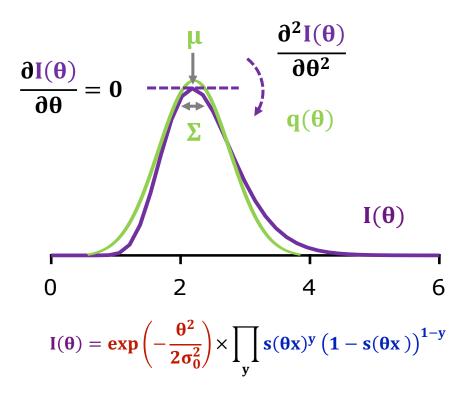
$$\mathbf{F} = \langle \log \mathbf{p}(\theta_1, \theta_2) + \log \mathbf{p}(\mathbf{y} | \theta_1, \theta_2, \mathbf{m}) \rangle_{\mathbf{q}} + \langle \log \mathbf{q}(\theta_1, \theta_2) \rangle_{\mathbf{q}}$$

$$\frac{\partial F}{\partial q(\theta_1)} = 0 \implies q(\theta_1) \propto exp\left(\langle log p(\theta_1, \theta_2) + log p(y|\theta_1, \theta_2, m)\rangle_{q(\theta_2)}\right)$$
variational free energy  $I(\theta_1)$ 

#### Posterior approximation

### Find $\mathcal{N}(\mu, \Sigma)$ that best approximates $I(\theta)$

#### logistic regression



#### multivariate case

# Until convergence:

for all i:

$$\triangleright \ \mu_i = \max_{\theta_i} (I(\theta_i))$$

end end

#### Variational inference

Summarize the posterior to its sufficient statistics (mean, variance) and optimize those values wrt the evidence lower bound.

This requires multiple approximations (free-energy, mean-field, Laplace) to be tractable.

#### **Problems:**

- does not converge to the true posterior
- can get stuck in local optimum



## Bayesian inference methods: summary

Model evidence (normalization factor of the posterior) is in general intractable.

Sampling methods give a computationally expensive estimation of the true posterior.

Variational methods are fast and scalable but potentially inaccurate.

#### Software

#### **Variational**

**VBA-toolbox** 

**TAPAS** 

**SPM** 

Sampling

**STAN** 

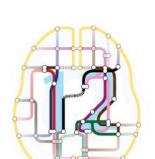
**BUGS** 

**JAGS** 

hBayesDM

hddm

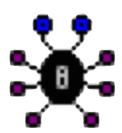










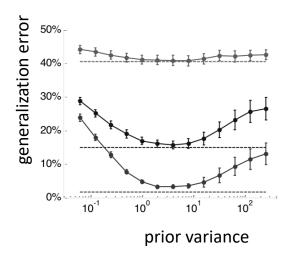


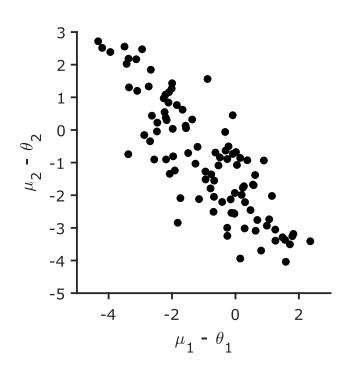
**JAGS** 

### Validating your model: parameters

# Checking if your parameters are identifiable:

- simulate data using your design with realistic θ
- invert your model (find  $\mu$ )
- compute estimation error  $(\mu \theta)$ 
  - check effect of prior mean
  - check effect of prior variance
  - check for posterior / error correlation

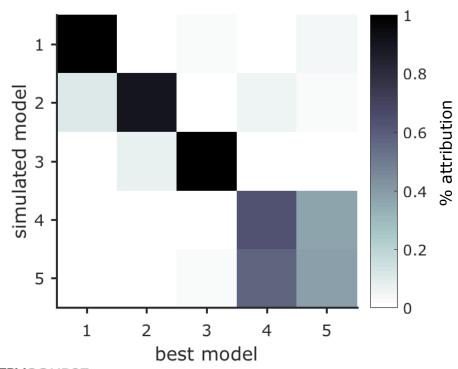




### Validating your model: hypothesis identifiability

## Checking if your models are identifiable:

- simulate all models
- compute evidence of each hypothesis for each dataset (BMS)
- count misattributions and build confusion matrix



# Thank you!