Dynamic Causal Modelling for M/EEG: introduction

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Overview

- 1 DCM: introduction
- 2 Dynamical systems theory
- 3 Neural states dynamics
- 4 Bayesian inference
- 5 Conclusion

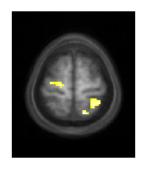
Overview

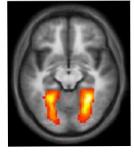
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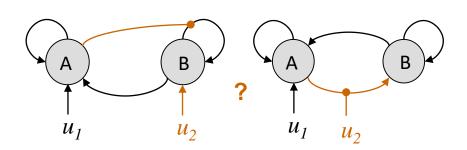
from functional segregation to functional integration

localizing brain activity: functional segregation

effective connectivity analysis: functional integration







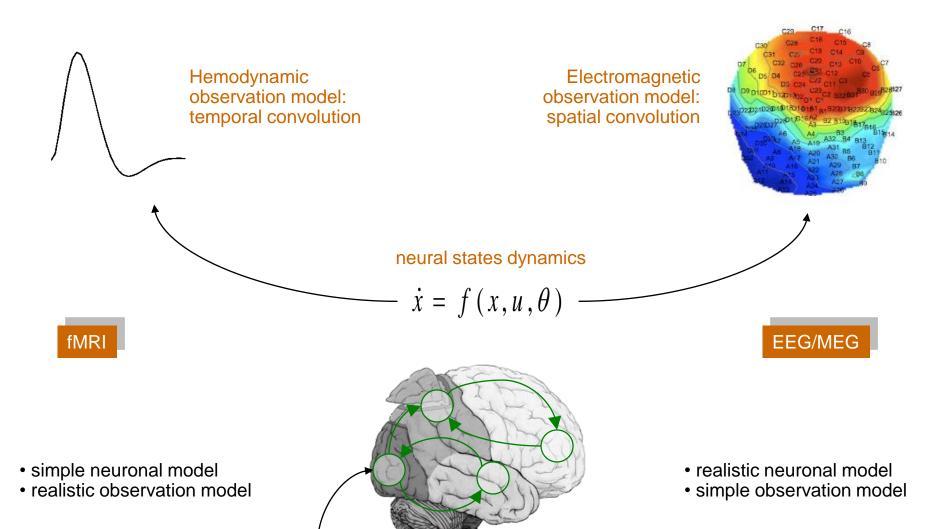
 u_1

 $u_1 X u_2$

« Where, in the brain, did my experimental manipulation have an effect? »

« How did my experimental manipulation propagate through the network? »

DCM: evolution and observation mappings



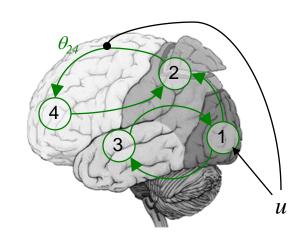
inputs

DCM: a parametric statistical approach

DCM: model structure

$$\begin{cases} y = g(x, \varphi) + \varepsilon \\ \dot{x} = f(x, u, \theta) \end{cases}$$

likelihood
$$\Rightarrow p(y|\theta,\varphi,m)$$



• DCM: Bayesian inference

parameter estimate:

$$\hat{\theta} = E[\theta | y, m]$$

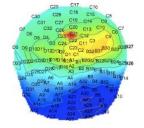
$$p(y|m) = \int p(y|\theta,\varphi,m) p(\theta|m) p(\varphi|m) d\varphi d\theta$$

DCM for EEG-MEG: auditory mismatch negativity

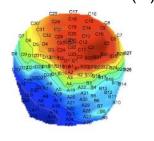
sequence of auditory stimuli



standard condition (S)

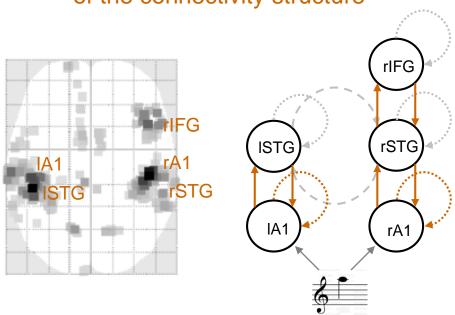


deviant condition (D)



t ~ 200 ms

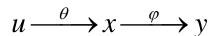
S-D: **reorganisation** of the connectivity structure

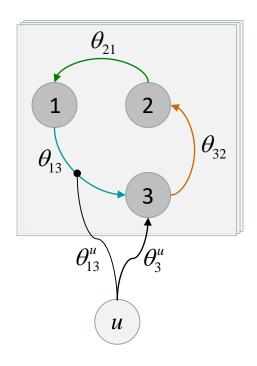


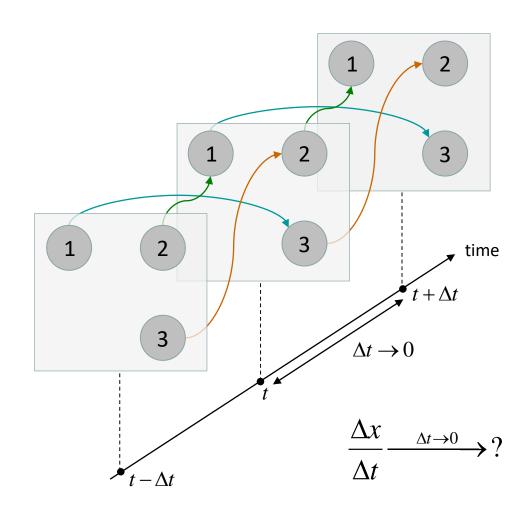
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dealing with feedback loops

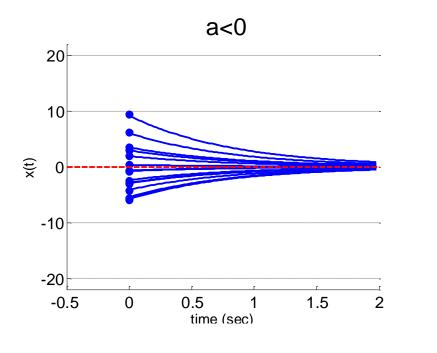


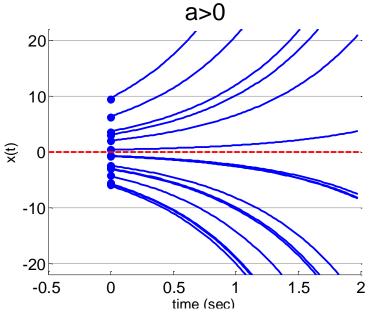




1D linear dynamical system

Ordinary Differential Equation (ODE): $\dot{x} = a \times x$





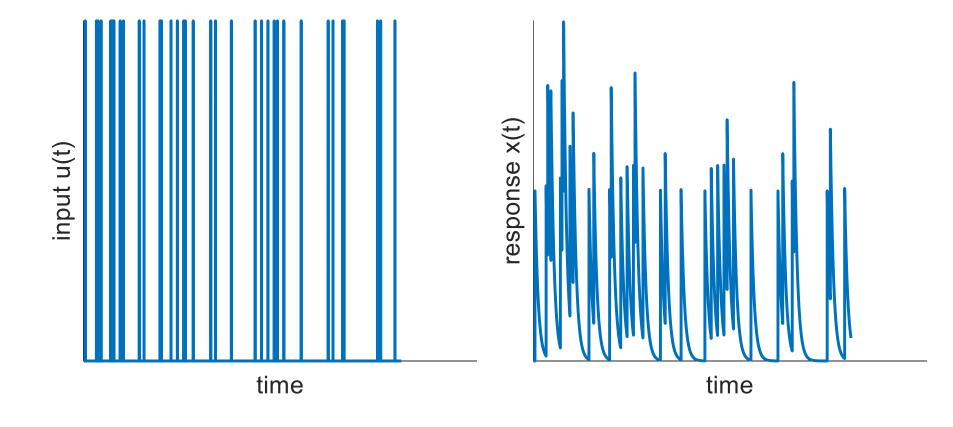
fixed point = stable

fixed point = unstable

1D linear dynamical system: input history effects

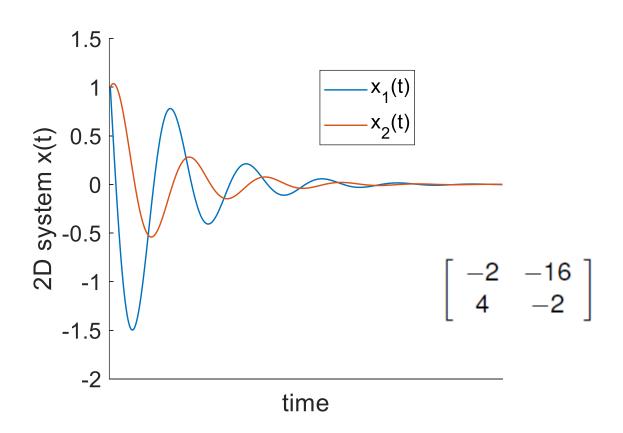
Impact of inputs on the system:

$$\dot{x} = u - a \times x$$



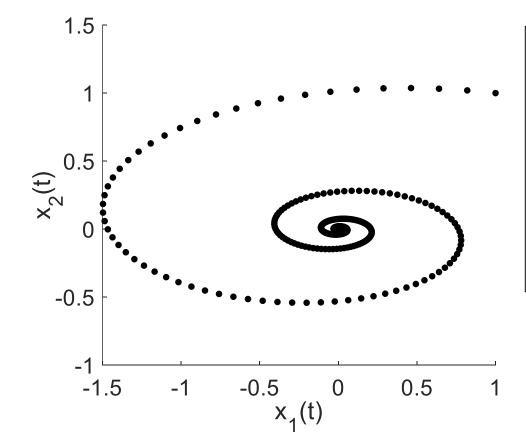
2D linear dynamical system

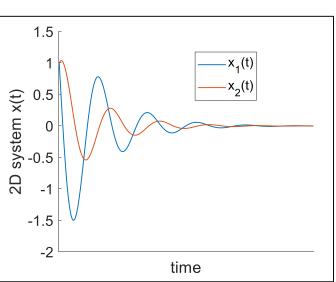
$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$



2D linear dynamical system: states' correlation structure

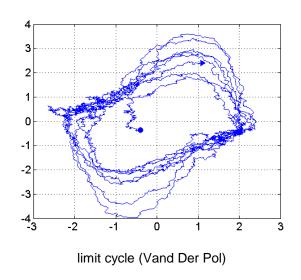
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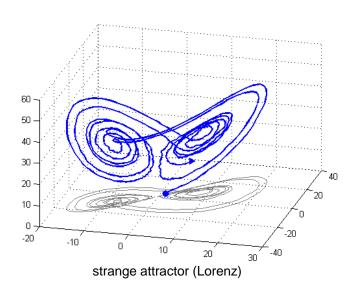




Dynamical systems theory summary

- Motivation: modelling reciprocal influences (feedback loops)
- Linear dynamical systems can be described in terms of their impulse response
- Dynamical repertoire depend on the system's dimension (and nonlinearities):
 - D>0: fixed points
 - D>1: spirals
 - D>1: limit cycles (e.g., action potentials)
 - D>2: metastability (e.g., winnerless competition)

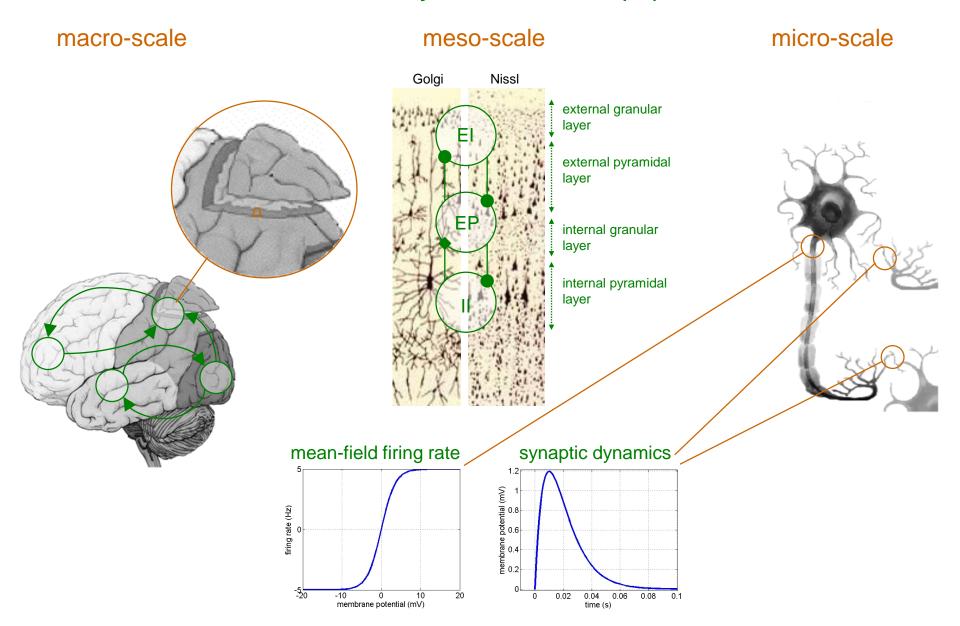




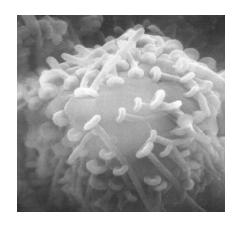
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DCM for M/EEG: systems of neural populations



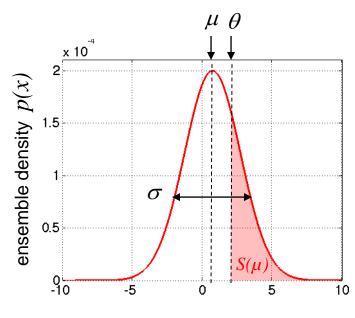
DCM for M/EEG: from micro- to meso-scale



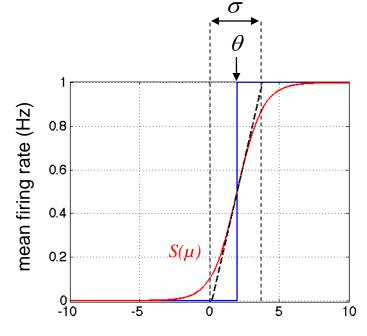
 $x_{i}(t)$: post-synaptic potential of j^{th} neuron within its ensemble

$$\frac{1}{N-1} \sum_{j' \neq j} H\left(x_{j'}(t) - \theta\right) \xrightarrow{N \to \infty} \int H\left(x(t) - \theta\right) p\left(x(t)\right) dx$$

$$\approx S\left(\mu\right) \text{ mean-field firing rate}$$

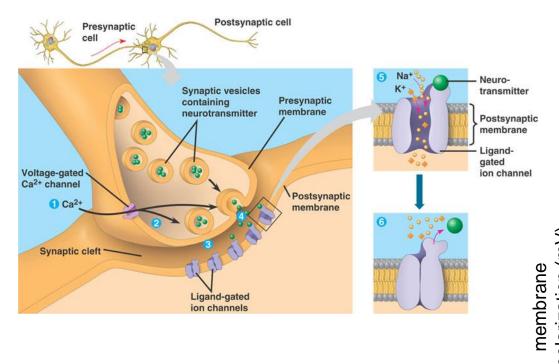






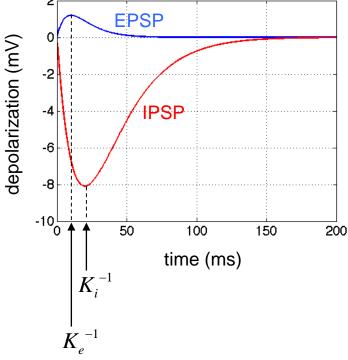
mean membrane depolarization μ (mV)

DCM for M/EEG: synaptic dynamics

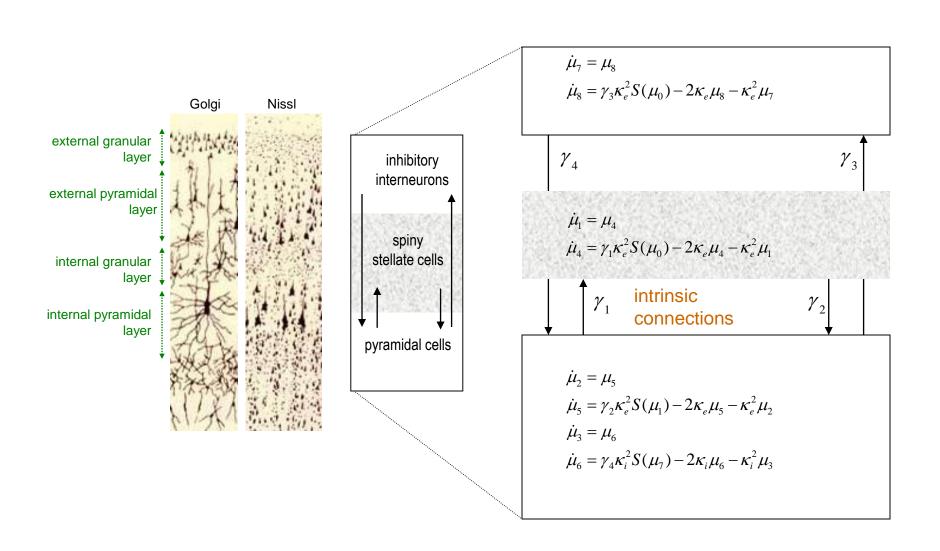


$\begin{cases} \dot{\mu}_1 = \mu_2 \\ \dot{\mu}_2 = \kappa_{i/e}^2 S(\bullet) - 2\kappa_{i/e} \mu_2 - \kappa_{i/e}^2 \mu_1 \end{cases}$

post-synaptic potential



DCM for M/EEG: intrinsic connections within the cortical column



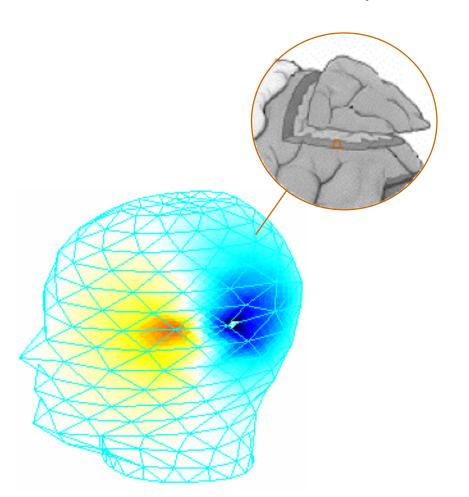
Overview

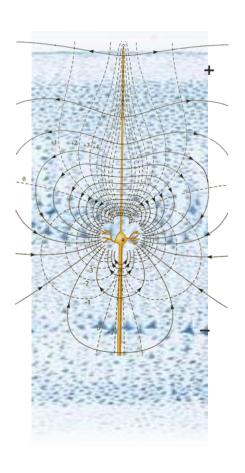
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Observation mappings

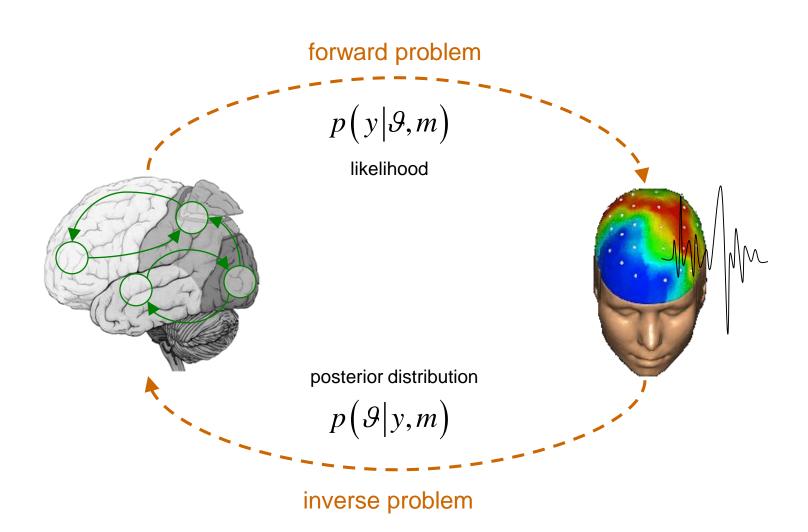
DCM for M/EEG: the electromagnetic forward problem

$$\mathbf{y}(t) = \sum_{i} \mathbf{L}^{(i)} \sum_{j} \beta_{j} \mu^{(ij)}(t)$$



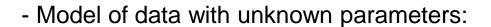


forward and inverse problems



Bayesian paradigm

deriving the likelihood function



$$y = f(\theta)$$

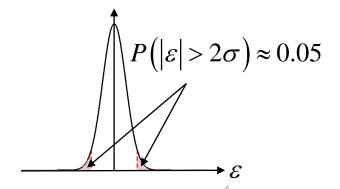
$$y = f(\theta)$$
 e.g., GLM: $f(\theta) = X\theta$

- But data is noisy: $y = f(\theta) + \varepsilon$

$$y = f(\theta) + \varepsilon$$

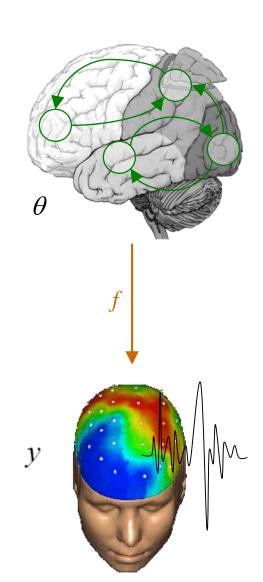
- Assume noise/residuals is 'small':

$$p(\varepsilon) \propto \exp\left(-\frac{1}{2\sigma^2}\varepsilon^2\right)$$



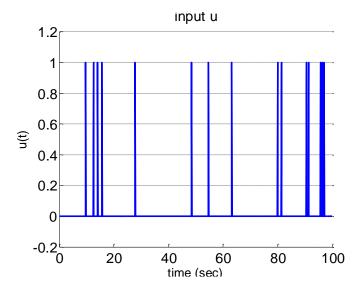
→ Distribution of data, *given fixed parameters*:

$$p(y|\theta) \propto \exp\left(-\frac{1}{2\sigma^2}(y-f(\theta))^2\right)$$



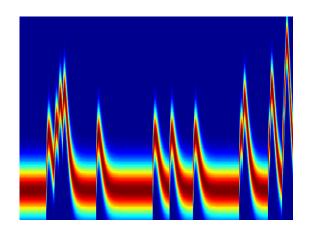
Bayesian paradigm

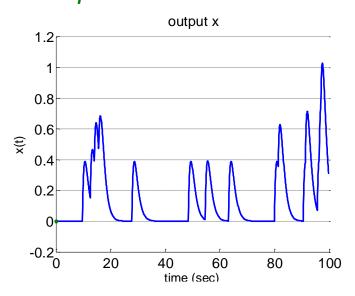
the likelihood function of an alpha kernel



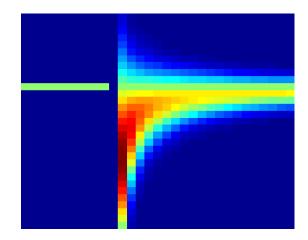
$$p(y|\theta,m)$$

holding the parameters fixed



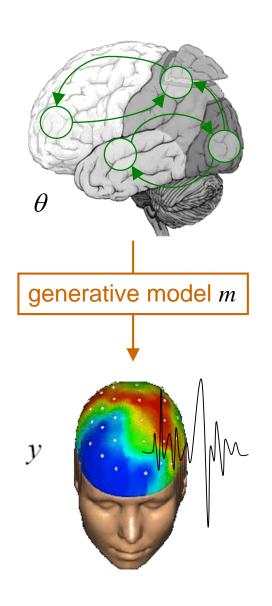


$$p(y|\theta,m)$$
 holding the data fixed



Bayesian paradigm

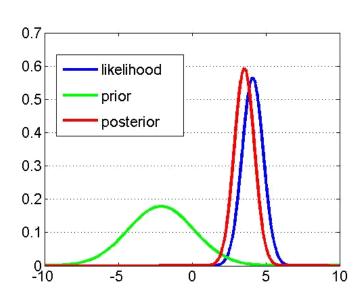
likelihood, priors and the model evidence



Likelihood: $p(y|\theta,m)$

Prior: $p(\theta|m)$

Bayes rule: $p(\theta|y,m) = \frac{p(y|\theta,m) p(\theta|m)}{p(y|m)}$



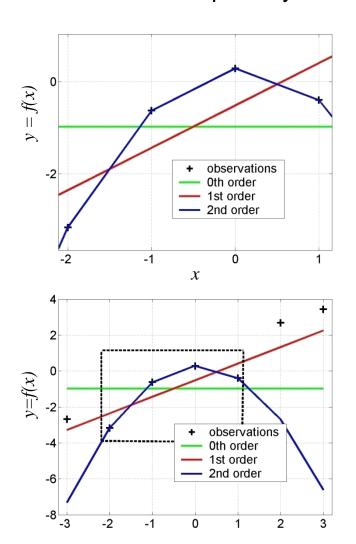
type, role and impact of priors

- Types of priors:
 - ✓ Explicit priors on model parameters (e.g., connection strengths)
 - ✓ Implicit priors on model functional form (e.g., system dynamics)
 - ✓ Choice of "interesting" data features (e.g., ERP vs phase data)
- Role of priors (on model parameters):
 - ✓ Resolving the *ill-posedness* of the inverse problem
 - ✓ Avoiding overfitting (cf. generalization error)
- Impact of priors:
 - ✓ On parameter posterior distributions (cf. "shrinkage to the mean" effect)
 - ✓ On model evidence (cf. "Occam's razor")
 - ✓ On free-energy landscape (cf. Laplace approximation)

model comparison

Principle of parsimony:

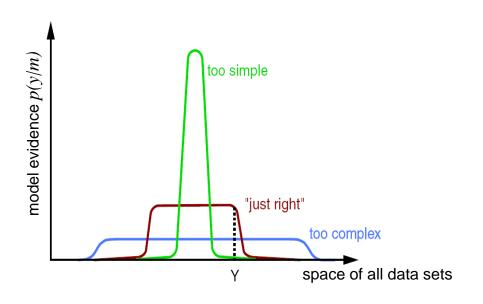
« plurality should not be assumed without necessity »



Model evidence:

$$p(y|m) = \int p(y|\theta,m)p(\theta|m)d\theta$$

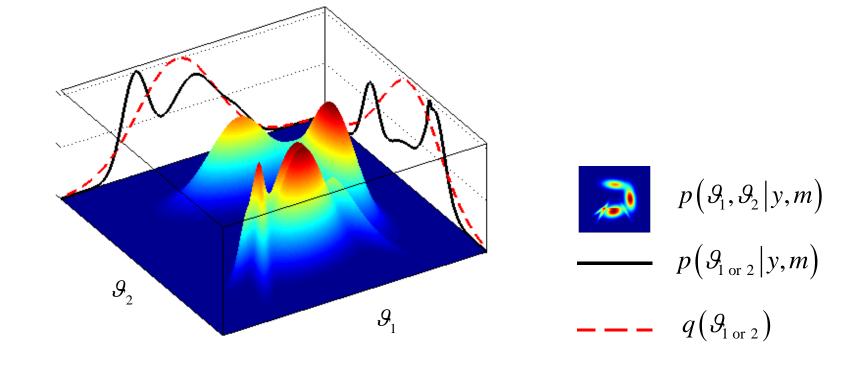
"Occam's razor":



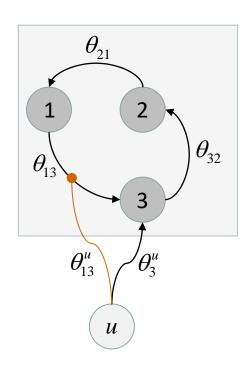
the variational Bayesian approach

$$\ln p(y|m) = \left\langle \ln p(\vartheta, y|m) \right\rangle_{q} + S(q) + D_{KL}(q(\vartheta); p(\vartheta|y, m))$$
free energy: functional of q

mean-field: approximate marginal posterior distributions: $\left\{q\left(artheta_{\!\scriptscriptstyle 1}
ight),q\left(artheta_{\!\scriptscriptstyle 2}
ight)
ight\}$



DCM: key model parameters

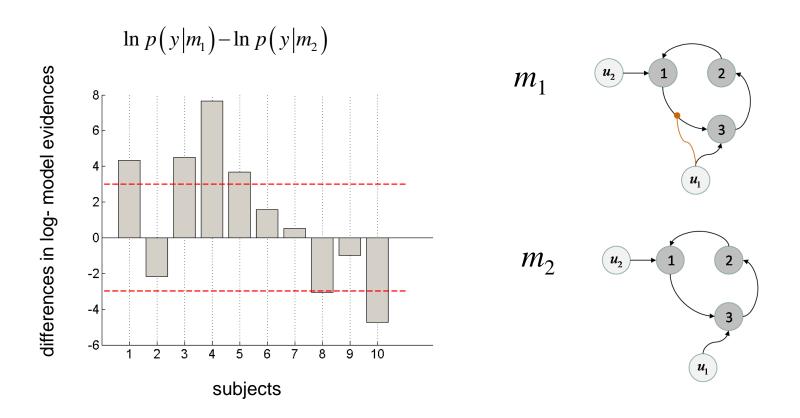


 $(\theta_{21}, \theta_{32}, \theta_{13})$ state-state coupling

 θ_3^u input-state coupling

 θ_{13}^u input-dependent modulatory effect

model comparison for group studies



fixed effect

assume all subjects correspond to the same model

random effect

assume different subjects might correspond to different models

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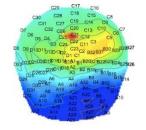
Conclusion

back to the auditory mismatch negativity

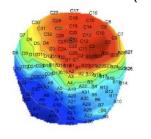
sequence of auditory stimuli



standard condition (S)

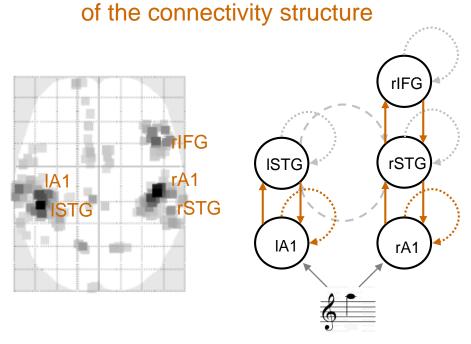


deviant condition (D)



t ~ 200 ms

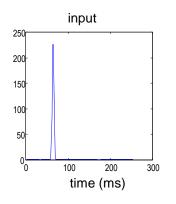
S-D: reorganisation

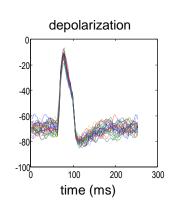


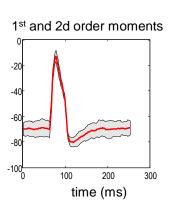
Conclusion

DCM for M/EEG: variants

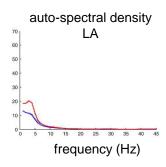
second-order mean-field DCM

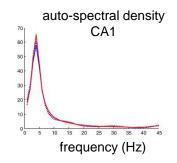


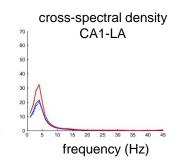




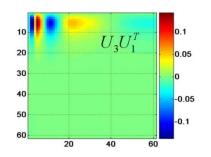
DCM for steady-state responses

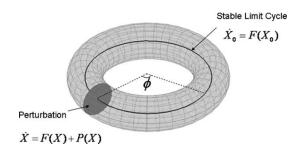






- DCM for induced responses
- DCM for phase coupling





Conclusions

- Objectives of a DCM study
 - Compare candidate interpretations of an effect of interest
 - Assess micro- and/or meso-scopic mechanisms ("mathematical microscope")
 - **–** ...

Assumptions

- Biophysical/neurophysiological (e.g., neural ensemble dynamics...)
- Statistical (e.g., Gaussian residuals...)
- Algorithmic (e.g., ODE integration scheme, VB,...)

Limitations

- Robustness to violations of assumptions
 - → Family inference, validity analysis,...
- Reliability of statistical inference
 - → Parameter recovery and/or confusion analysis
- Interpretation

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