

Modeling connectivity: Dynamic Causal Modeling for fMRI

Jakob Heinzle
Translational Neuromodeling Unit (TNU),
Institute for Biomedical Engineering
University and ETH Zürich

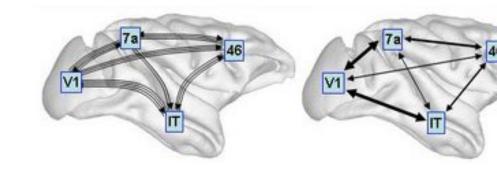
CP Course 2022, Zürich, Switzerland

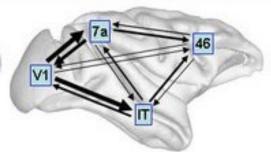






Structural, functional & effective connectivity





Sporns 2007, Scholarpedia

anatomical/structural

presence of physical connections

→ DWI, tractography, tracer studies (animals)

functional

statistical
 dependency between
 regional time series

→ correlations, ICA

effective

direct influences
 between neuronal
 populations

 $\rightarrow DCM$

Context-independent

Mechanism - free

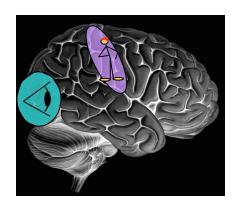
Mechanistic

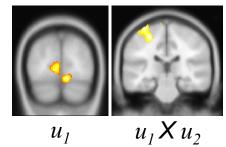




Specialisation vs. Integration

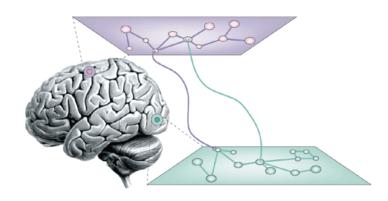
Functional Specialisation

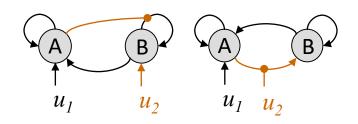




«Where, in the brain, did my experimental manipulation have an effect?»

Functional Integration

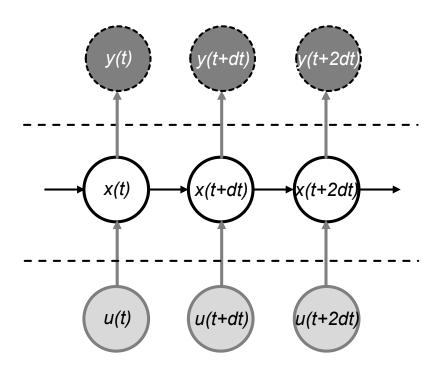




«How did my experimental manipulation propagate through the network?»



A reminder – generative models



Observed data (fMRI)

$$y = g(x, \theta) + \varepsilon$$

Hidden states (Brain activity)

$$\frac{dx}{dt} = f(x, u, \theta) + \omega$$

Inputs (Exp. manipulations) u(t)

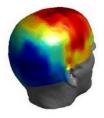




fMRI

Dynamic causal modelling





Model inversion:

Estimating neuronal mechanisms

Forward model:

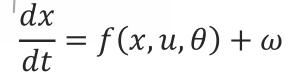
Predicting measured activity

$$y = g(x, \theta) + \varepsilon$$

DCM for EEG

→ later today

→ Rosalyn Moran



State equation:

Describing neuronal dynamics (and hemodynamics)







Dynamic causal modelling



Available online at www.sciencedirect.com



NeuroImage

NeuroImage 19 (2003) 1273-1302

www.elsevier.com/locate/ynimg

Dynamic causal modelling

K.J. Friston,* L. Harrison, and W. Penny

The Wellcome Department of Imaging Neuroscience, Institute of Neurology, Queen Square, London WC1N 3BG, UK

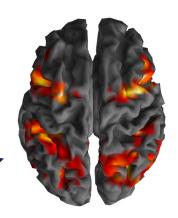
Received 18 October 2002; revised 7 March 2003; accepted 2 April 2003



DCM for fMRI - overview



Estimating neuronal mechanisms



fMRI

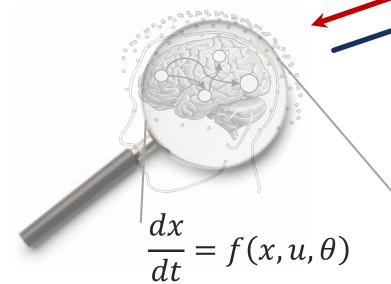


Predicting measured activity

$$y = g(x, \theta) + \varepsilon$$

Neural state equation:

Describing neuronal dynamics

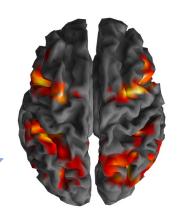




DCM for fMRI - overview



Estimating neuronal mechanisms



fMRI

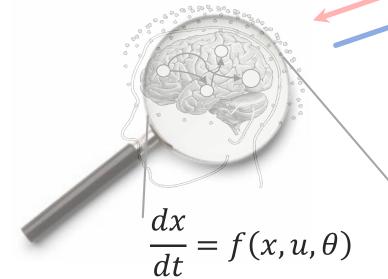


Predicting measured activity

$$y = g(x, \theta) + \varepsilon$$

Neural state equation:

Describing neuronal dynamics







$$\frac{dx}{dt} = f(x, u)$$

ETH zürich



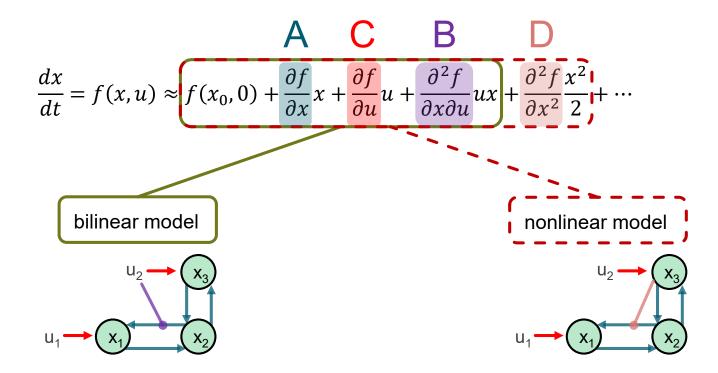
Neuronal state equations

$$\frac{dx}{dt} = f(x, u) \approx \left[f(x_0, 0) + \frac{\partial f}{\partial x} x + \frac{\partial f}{\partial u} u + \frac{\partial^2 f}{\partial x \partial u} u x \right] + \frac{\partial^2 f}{\partial x^2} \frac{x^2}{2} + \cdots$$

bilinear model









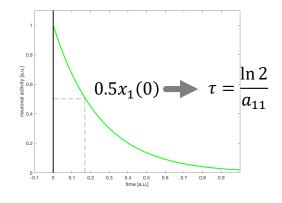


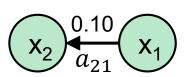
DCM effective connectivity parameters are rate constants



$$\frac{dx_1}{dt} = a_{11}x_1 \qquad \qquad x_1(t) = x_1(0) \cdot exp(a_{11}t)$$

$$x_1(t) = x_1(0) \cdot exp(a_{11}t)$$



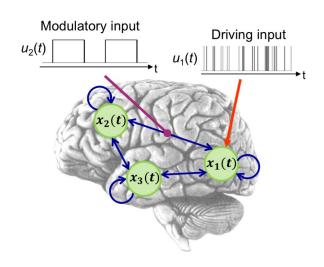


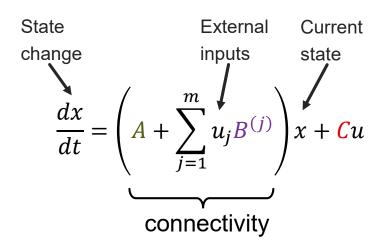
If a_{21} is 0.10s⁻¹, this means that, per unit time, the increase in activity in x₂ corresponds to 10% of the current activity in x₁





Interim summary: bilinear neuronal state equation





$$\theta = \{A, B^{(1)}, \dots, B^{(m)}, C\}$$
 Endogenous Modulatory Driving input connectivity connectivity weights

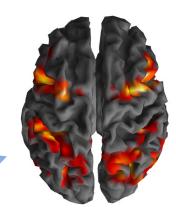




DCM for fMRI - overview



Estimating neuronal mechanisms

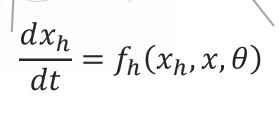


fMRI



Predicting measured activity

$$y = g(x, \theta) + \varepsilon$$



Hemodynamic state equation:

Describing hemodynamics





The hemodynamic response

Neuronal dynamics only indirectly observable via hemodynamic response

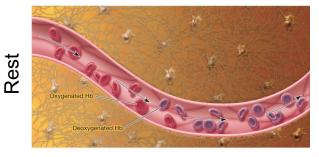
neuronal activity

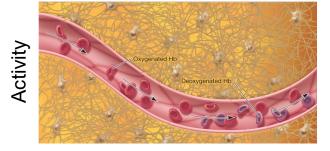
blood flow

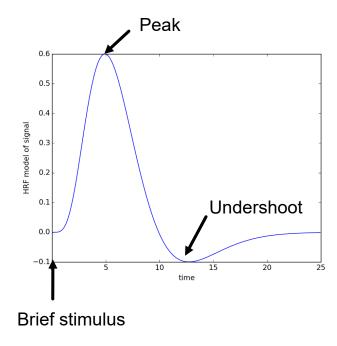
oxygenated Hb

↑ _{T2}*

fMRI signal











The hemodynamic model

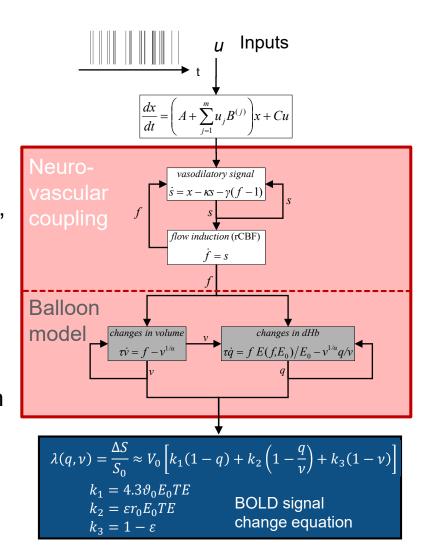
6 parameters:

$$\theta^h = \{\kappa, \gamma, \tau, \alpha, \rho, \varepsilon\}$$

Important for model fitting, but typically of no interest for statistical inference.

Region specific HRF

→ Parameters computed separately for each region



State equation

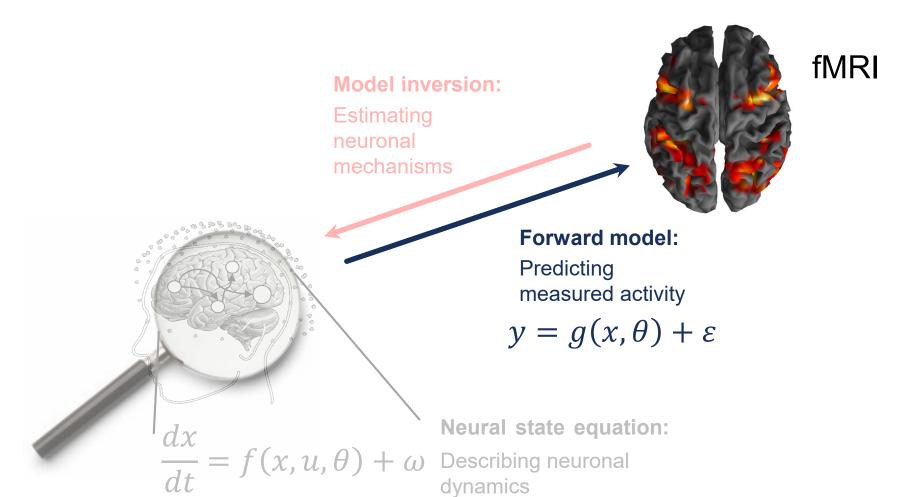
neural

hemodynamic





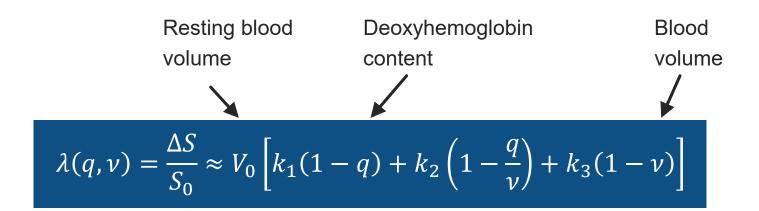
DCM for fMRI - overview







The BOLD signal equation



BOLD-Signal Parameters:

$$k_1 = 4.3\vartheta_0 E_0 T E$$

$$k_2 = \varepsilon r_0 E_0 T E$$

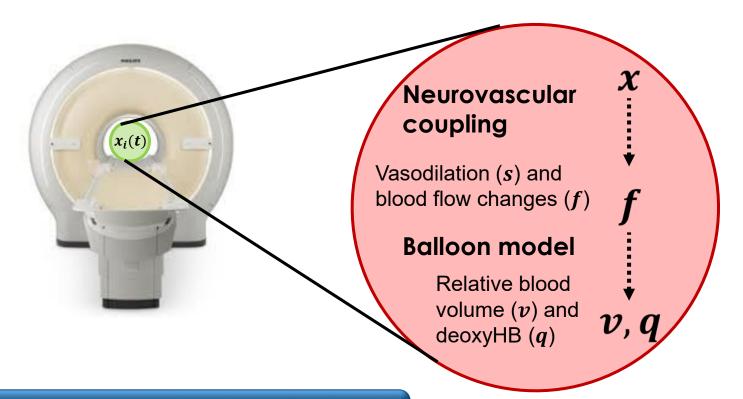
$$k_3 = 1 - \varepsilon$$

$$V_0 = 0.04$$
 $E_0 = 0.32 - 0.4$ At 1.5 Tesla At 3 Tesla At 7 Tesla $\theta_0 \approx 40.3 \, \mathrm{s}^{-1}$ $\theta_0 \approx 80.6 \, \mathrm{s}^{-1}$ $\theta_0 \approx 188 \, \mathrm{s}^{-1}$ $r_0 \approx 25 \, \mathrm{s}^{-1}$ $r_0 \approx 110 \, \mathrm{s}^{-1}$ $r_0 \approx 340 \, \mathrm{s}^{-1}$ $r_0 \approx 1.28$ $\epsilon \approx 0.47$ $\epsilon \approx 0.025 \, \mathrm{s}$





From neural activity to the BOLD signal: summary



BOLD signal is a **direct function** of ν and q

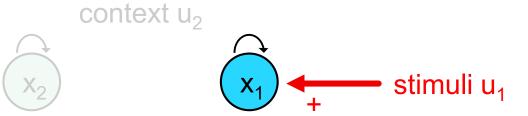
$$y = \frac{\Delta S}{S_0} = g(v, q) + \varepsilon$$





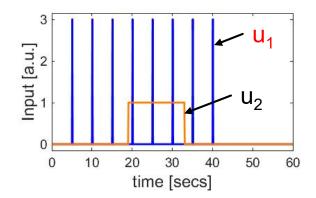
Simulation example: What can DCM explain?

Example: single node



$$\frac{dx}{dt} = (A + u_2 B^{(2)})x + Cu_1$$

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{pmatrix} \begin{bmatrix} a_{11} & 0 \\ 0 & a_{22} \end{bmatrix} + u_2 \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \end{pmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} c_{11} & 0 \\ 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$$

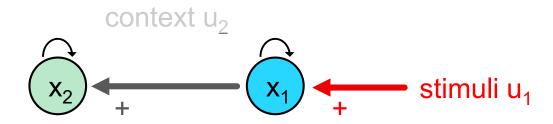






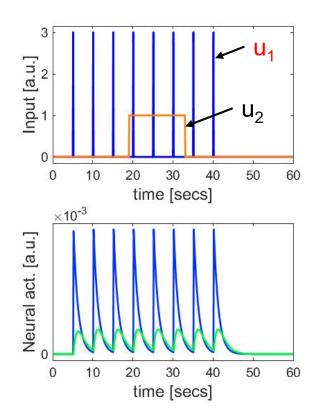
Simulation example: What can DCM explain?

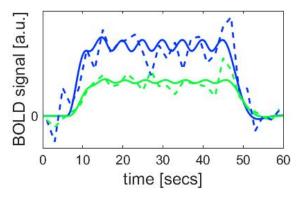
Example: two connected node



$$\frac{dx}{dt} = (A + u_2 B^{(2)})x + Cu_1$$

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{pmatrix} \begin{bmatrix} a_{11} & 0 \\ a_{21} & a_{22} \end{bmatrix} + u_2 \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \end{pmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} c_{11} & 0 \\ 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$$



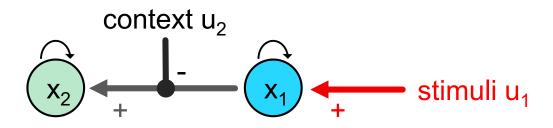






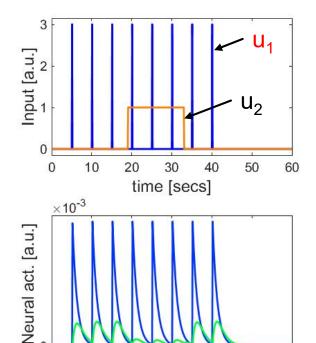
Simulation example: What can DCM explain?

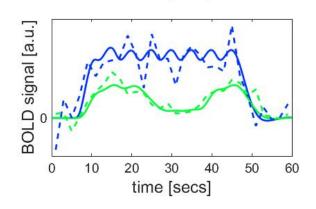
Example: modulation of connection



$$\frac{dx}{dt} = (A + u_2 B^{(2)})x + Cu_1$$

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{pmatrix} \begin{bmatrix} a_{11} & 0 \\ a_{21} & a_{22} \end{bmatrix} + u_2 \begin{bmatrix} 0 & 0 \\ b_{21}^{(2)} & 0 \end{bmatrix} \end{pmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} c_{11} & 0 \\ 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$$





30

time [secs]

50

60

20

10



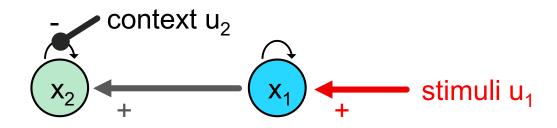


50

60

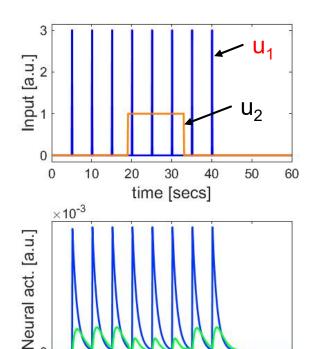
Simulation example: What can DCM explain?

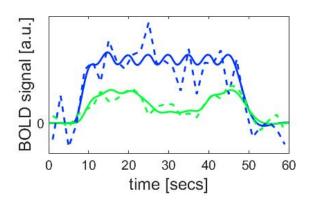
Example: modulation of inhibitory self-connection



$$\frac{dx}{dt} = (A + u_2 B^{(2)})x + Cu_1$$

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{pmatrix} \begin{bmatrix} a_{11} & 0 \\ a_{21} & a_{22} \end{bmatrix} + u_2 \begin{bmatrix} 0 & 0 \\ \mathbf{0} & b_{22}^{(2)} \end{bmatrix} \end{pmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} c_{11} & 0 \\ 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$$





time [secs]

10

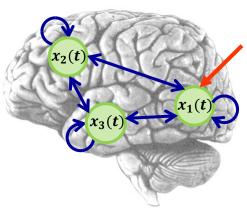




DCM for fMRI

A simple model of a neural network

. . .





Neural node



Input



Connections

... described as a dynamical system

- - -

... causes the data (BOLD signal).

$$\dot{x} = f(x, u, \theta)$$

$$y = g(x, \theta) + \varepsilon$$

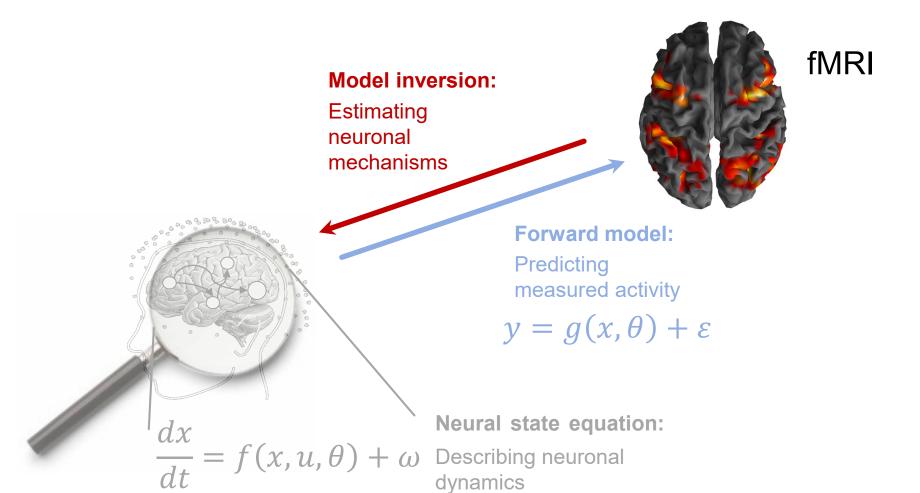
Simulate the system with input u and parameters θ \rightarrow BOLD signal time course y that can be

→ BOLD signal time course y that can be compared to measured data.



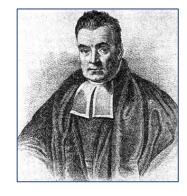


DCM for fMRI - overview





Bayes' theorem



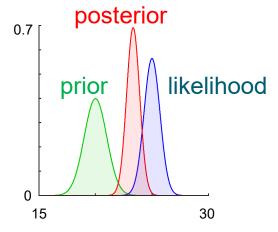
Reverend Thomas Bayes (1702-1761)

$$p(\theta|y,m) = \frac{p(y|\theta,m)p(\theta|m)}{p(y|m)}$$

$$p(y|m)$$

$$p(y|m)$$

$$p(y|m)$$





$$p(y(t)|\theta,m) = \mathcal{N}(y(t); g(\theta^n, \theta^h, u(t)), \theta^\sigma)$$
likelihood

Assume data is normally distributed around the prediction from the dynamical model (Gaussian noise)

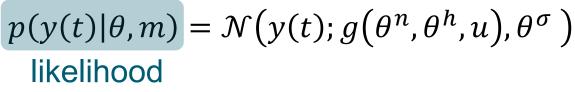
$$y(t) = g(x(t), \theta) + \varepsilon$$
$$\varepsilon \sim \mathcal{N}(0, \sigma^2 I)$$

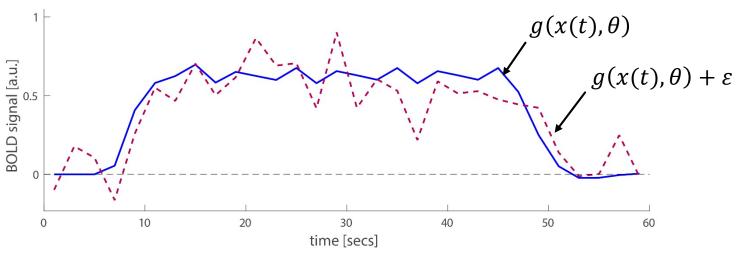
Data is prediction plus Gaussian noise





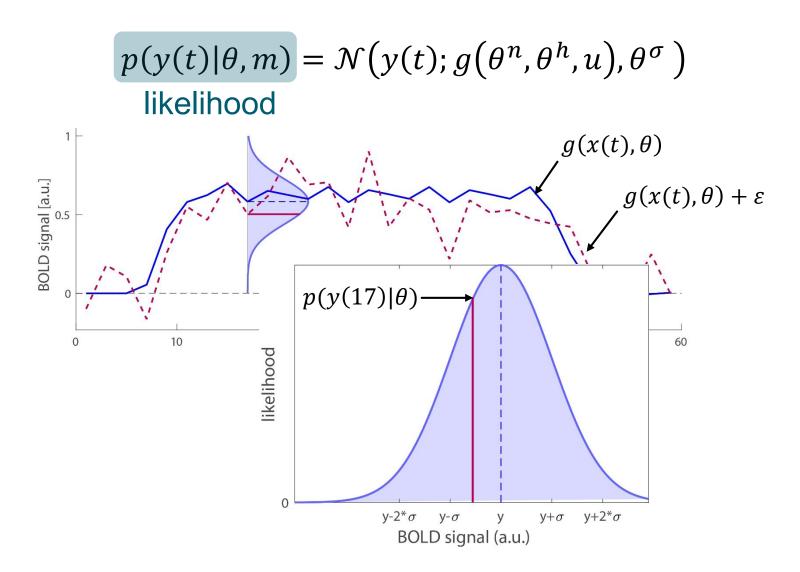






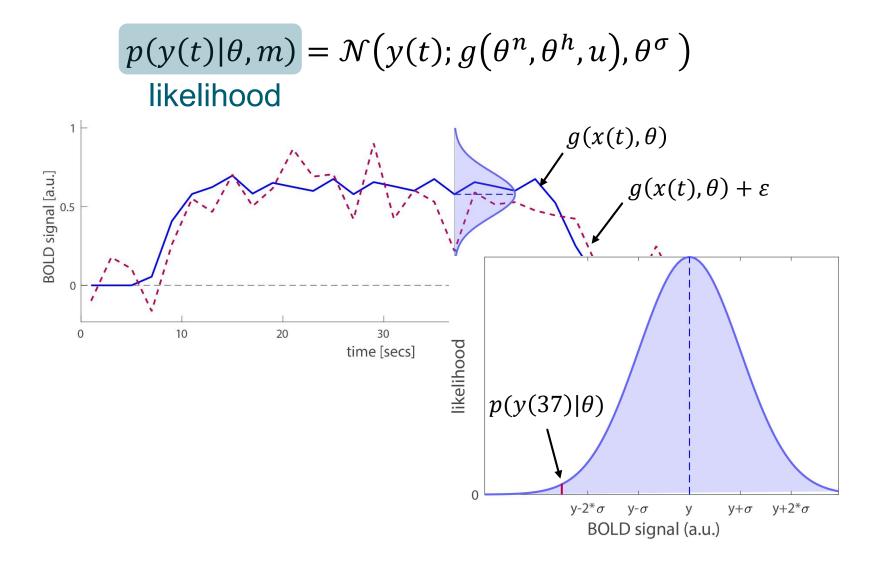
















Priors

$$p(\theta|y,m) = \frac{p(y|\theta,m)p(\theta|m)}{p(y|m)}$$

Neuronal parameters:

- self-connections: principled (to "ensure" that the system is stable)
- other parameters (between—region connections, modulation, inputs): shrinkage priors

Hemodynamic parameters:

empirical

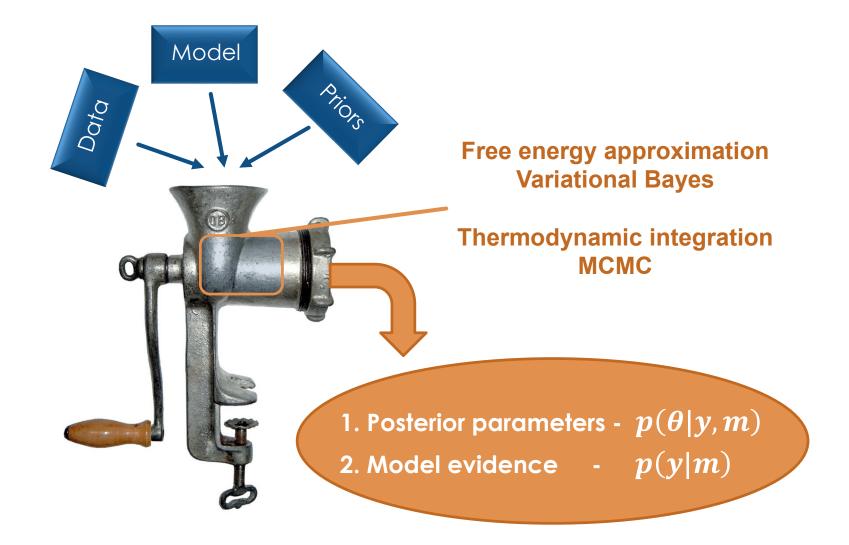
Noise prior:

assume relatively noisy data
 (not default in SPM12 → set DCM.options.hE = 0; DCM.options.hC = 1)





Model estimation: running the machinery







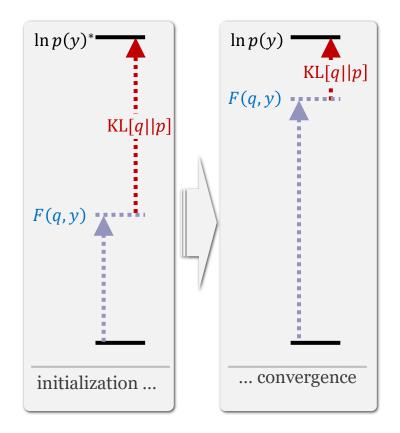
Inversion – variational Free Energy approximation to model evidence

model evidence

$$\ln p(y) = \text{KL}[q||p] + F(q,y)$$

divergence neg. free energy
 ≥ 0 (easy to evaluate for a given q)

When F(q, y) is maximized, $q(\theta)$ is our best estimate of the true posterior.

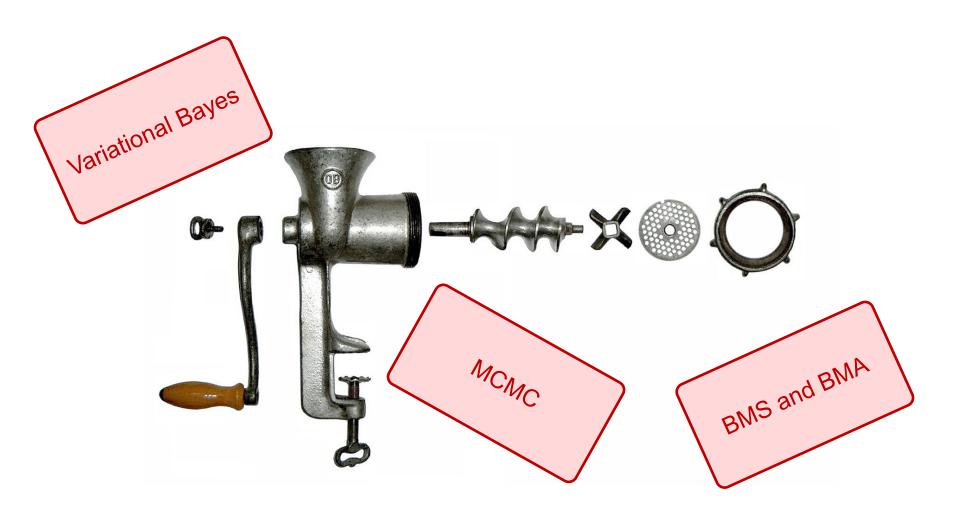








Model estimation: running the machinery

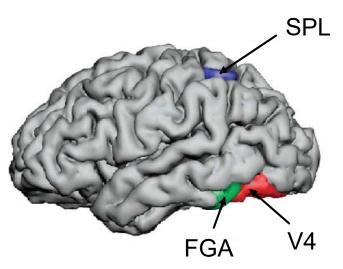






Model selection example: Synesthesia

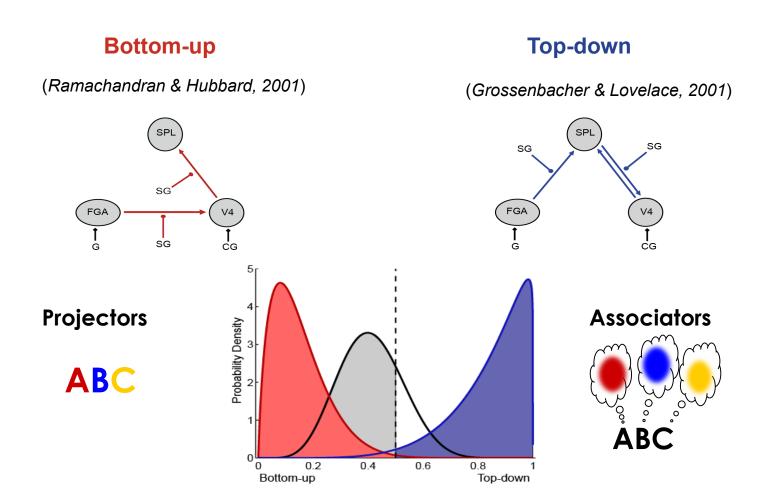
- Specific sensory stimuli lead to unusual, additional experiences
- Grapheme-color synesthesia: color
- Involuntary, automatic; stable over time, prevalence ~4%
- Potential cause: aberrant cross-activation/coupling between brain areas
 - grapheme encoding area (FGA)
 - color area (V4)
 - superior parietal lobule (SPL)







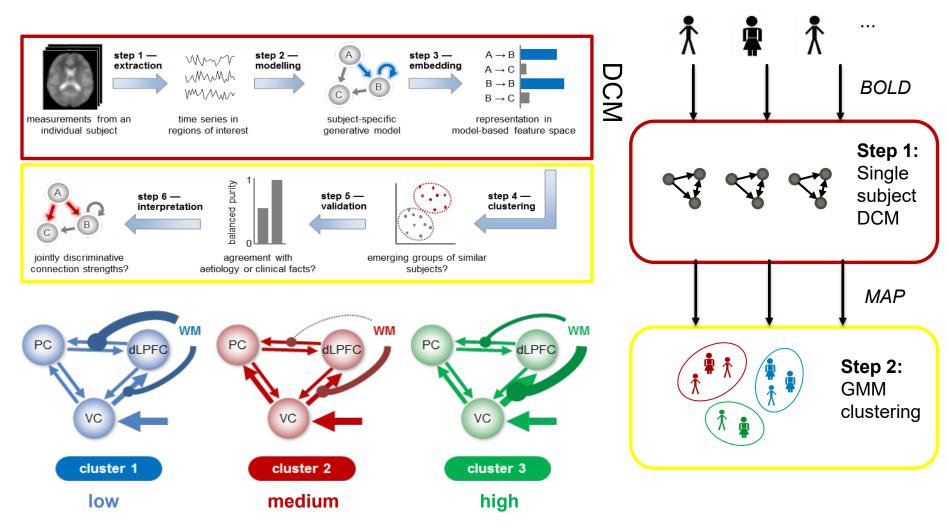
Bottom-up or Top-down "cross-activation"?







Example: DCM for physiologically plausible feature extraction (generative embedding)







What questions can we answer using DCM?

Model comparison

What is the functional architecture of a network of brain regions?

→ Synesthesia

Are optimal models different between groups?

→ Synesthesia

Which connections are modulated by experimental manipulations?

Parameter inference

Are parameters different between individuals/groups?

Use parameters as physiologically informed summary statistics

→ Generative embedding

... and of course many more!



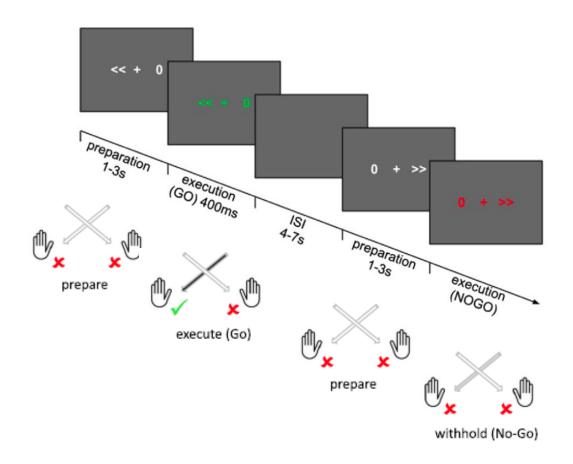
Limitations

- DCMs only have inputs, no outputs
 - Limits the study of behavioral paradigms
- Local minima
 - Variational approximation can get stuck in local minima of free energy
- Size of networks
 - Standard inversion too slow for large networks (>10 nodes).
- Regularization through fixed priors:
 - Regularization based on other data → empirical Bayes.





Behavioral DCM – a step towards a neurocomputational model

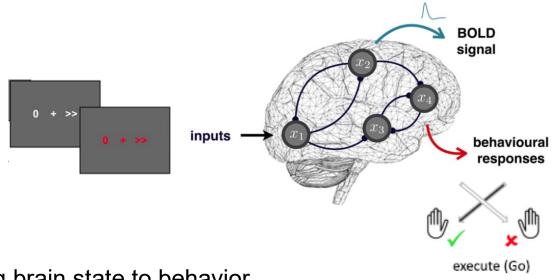




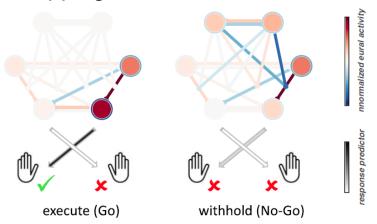


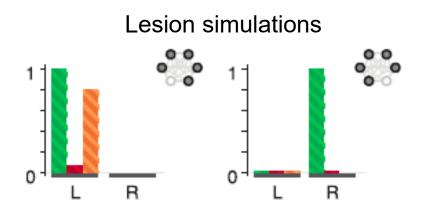


Behavioral DCM – a step towards a neurocomputational model



Mapping brain state to behavior

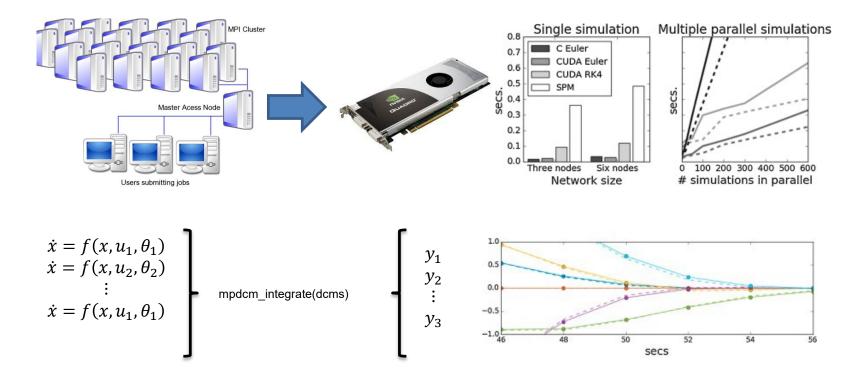








MCMC inversion of DCMs: Massively Parallel DCM - mpdcm



- Fast inversion of DCMs
- MCMC based inversion possible
- → Thermodynamic Integration (alternative to negative Free Energy)





Recent additions to DCM for fMRI

- Massively parallel dynamic causal modelling
 - > mpdcm Aponte et al., J Neuroscience Methods, 2016
- Regression dynamic causal modelling
 - > rDCM Frässle et al., Neuroimage, 2017

Modeling Connectivity:
Advanced DCM for
fMRI

→ Stefan Frässle

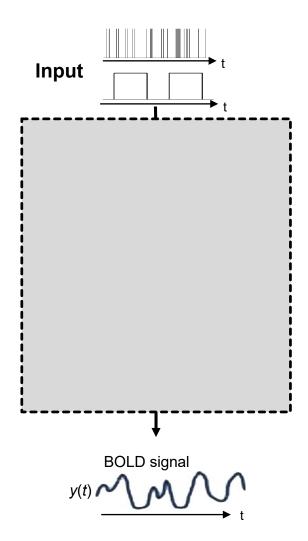
- Hierarchical unsupervised generative embedding
 - > HUGE Yu et al., Neuroimage, 2019

Available in TAPAS: www.translationalneuromodeling.org/tapas





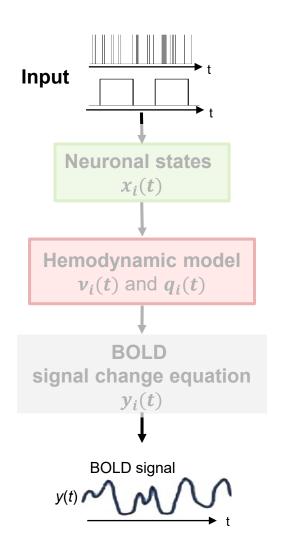
Summary – generative model

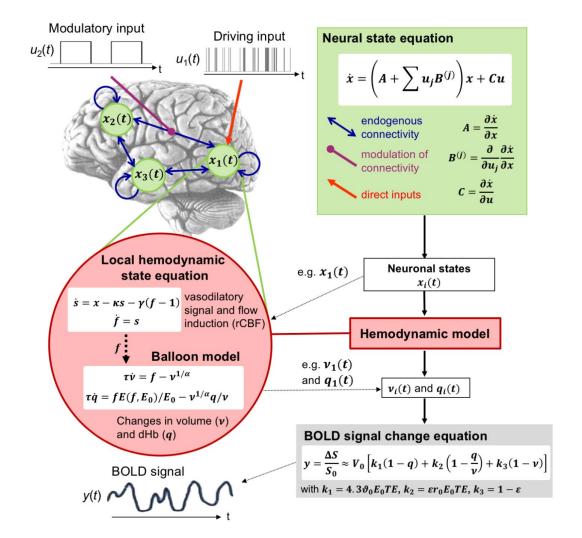






Summary – generative model





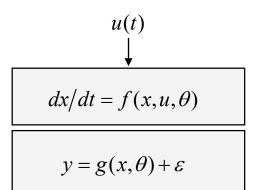




Summary - Bayesian system identification

Neural (and hemo-) dynamics

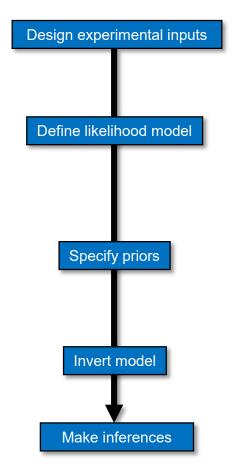
Observer function



$$p(y \mid \theta, m) = N(g(\theta), \Sigma(\theta))$$
$$p(\theta, m) = N(\mu_{\theta}, \Sigma_{\theta})$$

Inference on model structure
Inference on parameters

$$p(y \mid m) = \int p(y \mid \theta, m) p(\theta) d\theta$$
$$p(\theta \mid y, m) = \frac{p(y \mid \theta, m) p(\theta, m)}{p(y \mid m)}$$







DCM software note

Basic functionality for DCM for fMRI is provided within

SPM

https://www.fil.ion.ucl.ac.uk/spm/





Thank you!

Many thanks to Stefan Frässle, Klaas Enno Stephan, Hanneke den Ouden and Jean Daunizeau for many of the slides!

List with suggested DCM literature in Appendix of this presentation!



DCM literature (1)

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