

Drift Diffusion Model

Computational Psychiatry Course Zurich
September 11, 2024
Matt Nassar

Perceptual Decisions

Perceptual Decisions



Perceptual Decisions



?

Perceptual Decisions

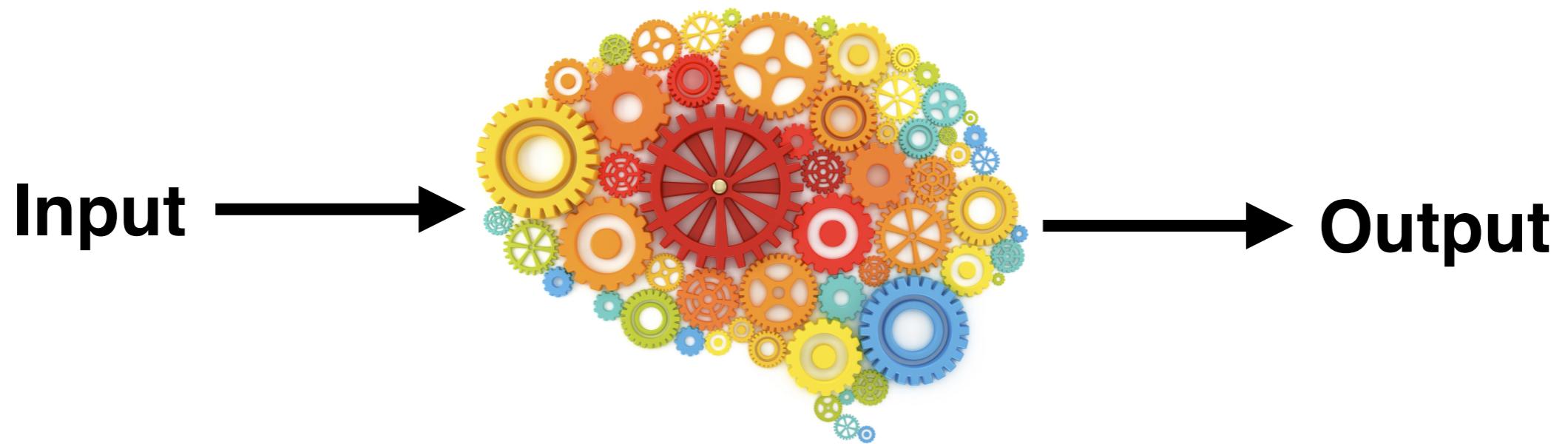


Perceptual Decisions

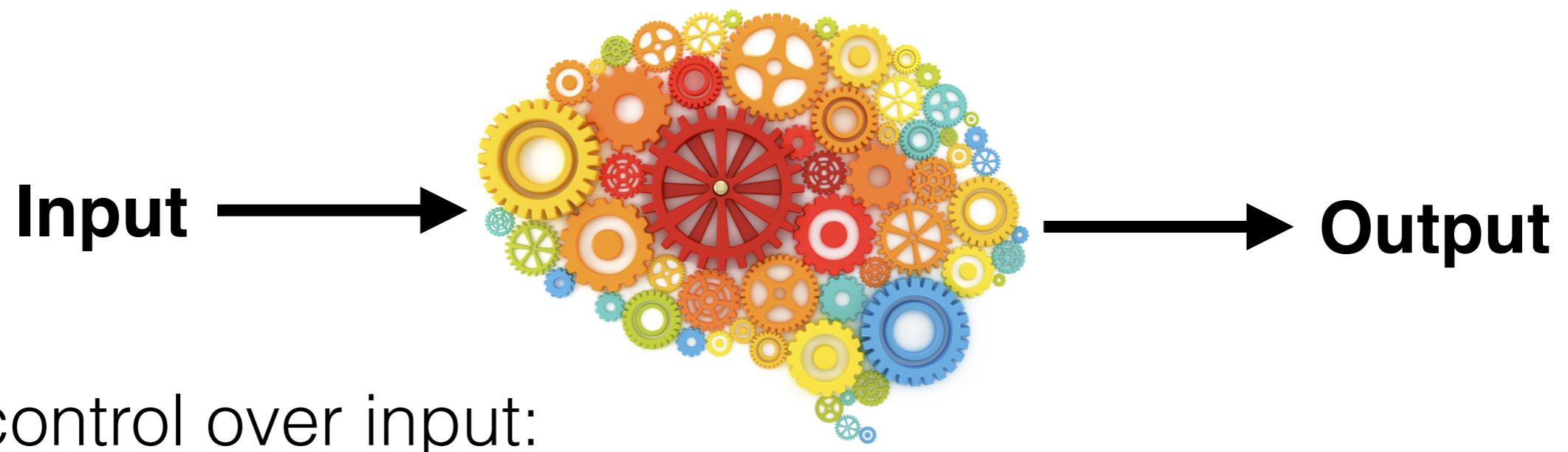


Important for survival!!!

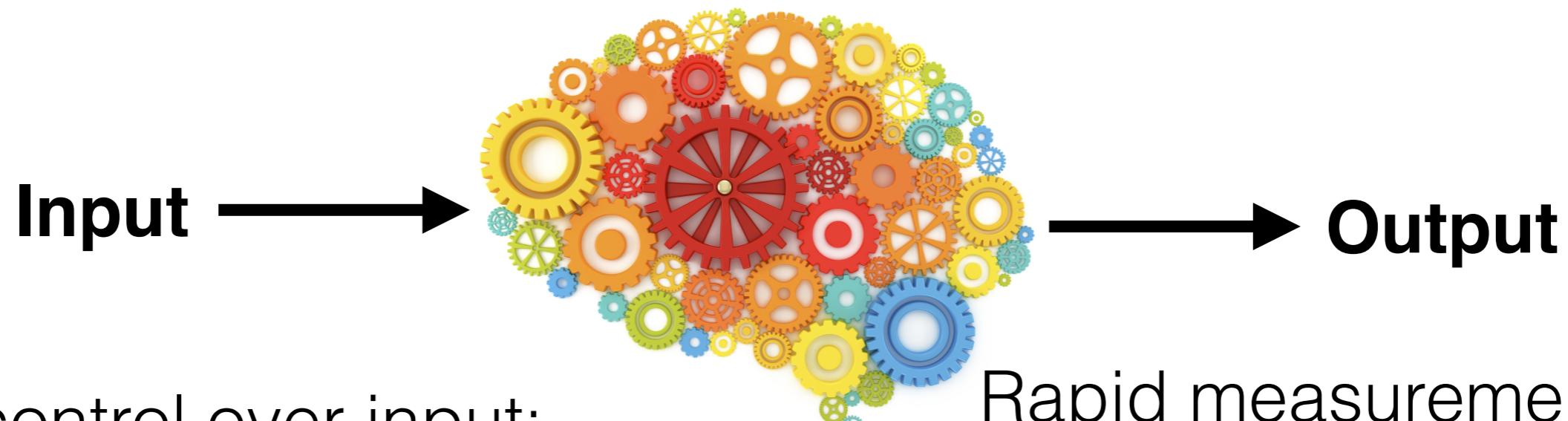
Perceptual Decisions



Perceptual Decisions



Perceptual Decisions



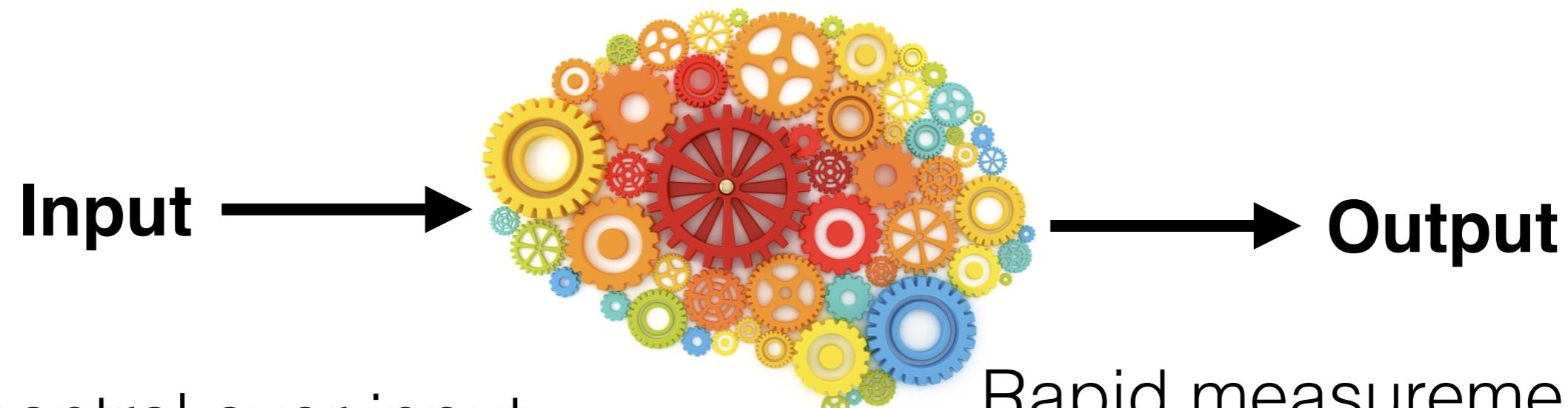
Total control over input:



Rapid measurement
of decision & timing



Perceptual Decisions

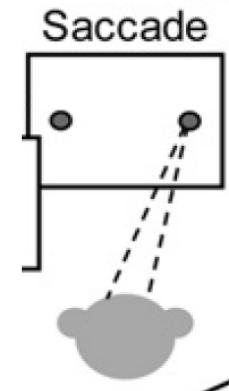


Total control over input:



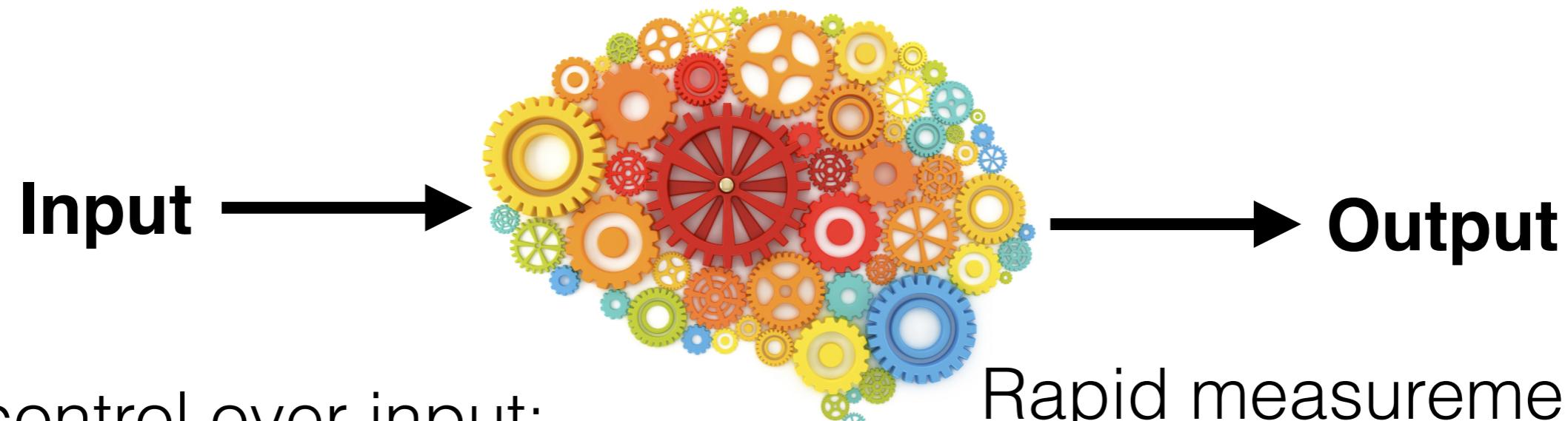
Rapid measurement
of decision & timing

a,s,d,f



Perceptual Decisions

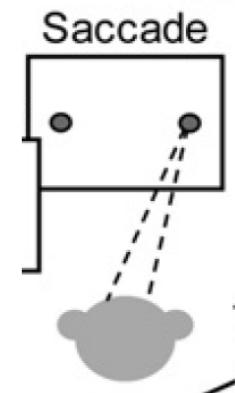
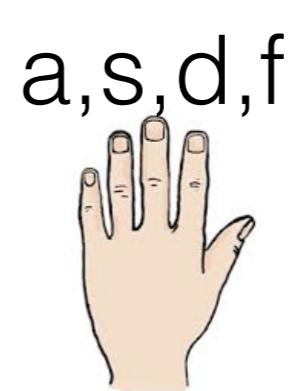
*Paradigms
conducive to animal
research*



Total control over input:



Rapid measurement
of decision & timing



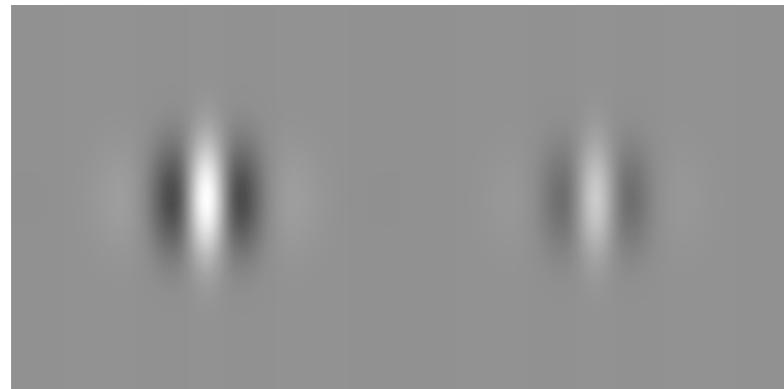
Perceptual Decisions

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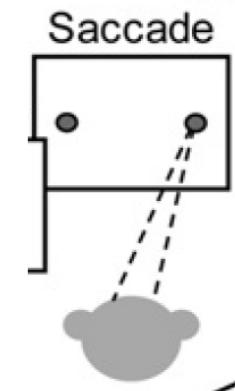
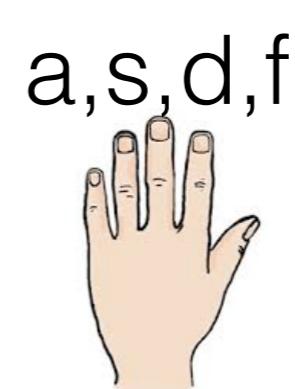
Record neurons!
Silence neurons!
Activate neurons!



Total control over input:



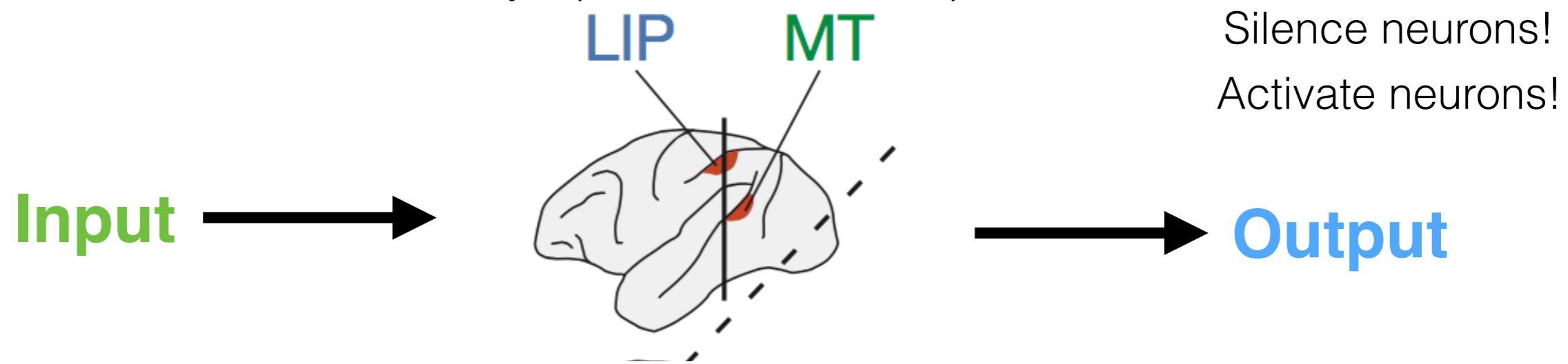
Rapid measurement
of decision & timing



Perceptual Decisions

*Paradigms
conducive to animal
research*

We have a good
idea where to look for
sensory inputs and motor outputs

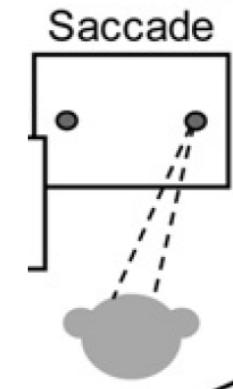


Total control over input:



Rapid measurement
of decision & timing

a,s,d,f



Perceptual Decisions

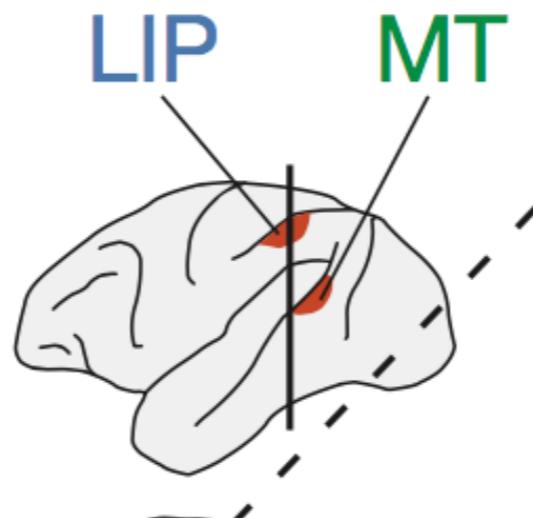
**Amenable to
good experiments!!!**

We have a good idea where to look for sensory inputs and motor outputs

*Paradigms
conducive to animal
research*

Record neurons!
Silence neurons!
Activate neurons!

Input →



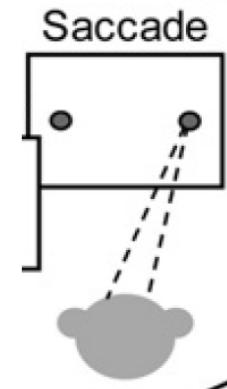
→ **Output**

Total control over input:

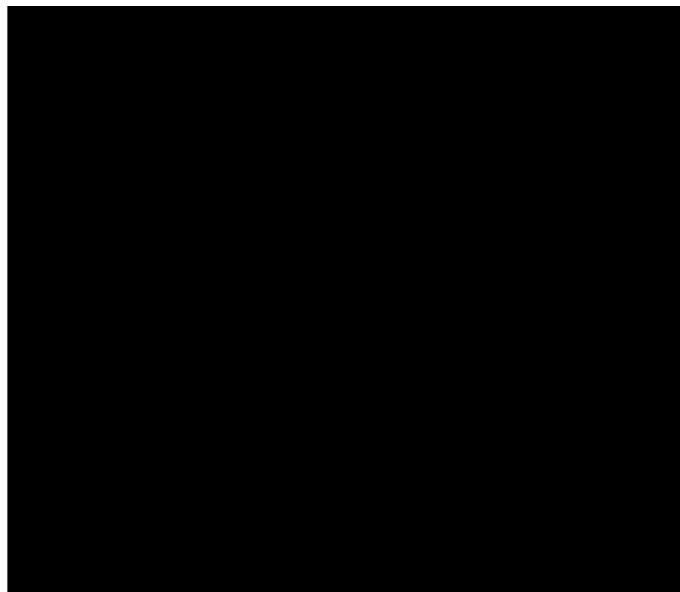


Rapid measurement
of decision & timing

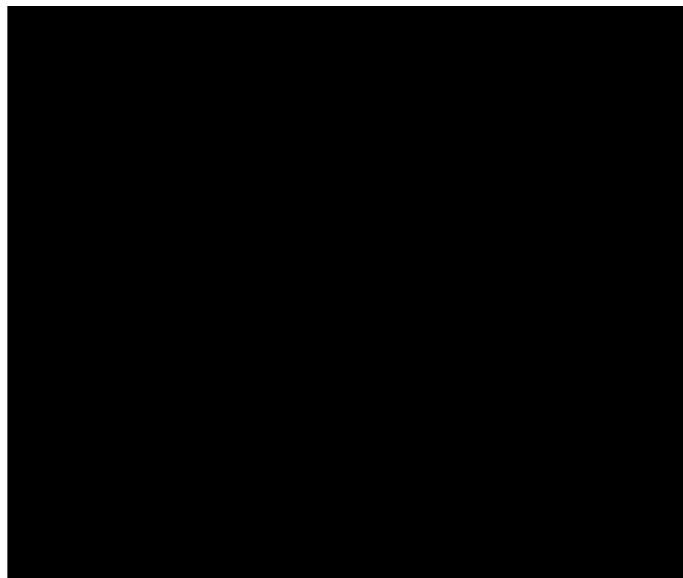
a,s,d,f



Which way are dots moving?



Which way are dots moving?



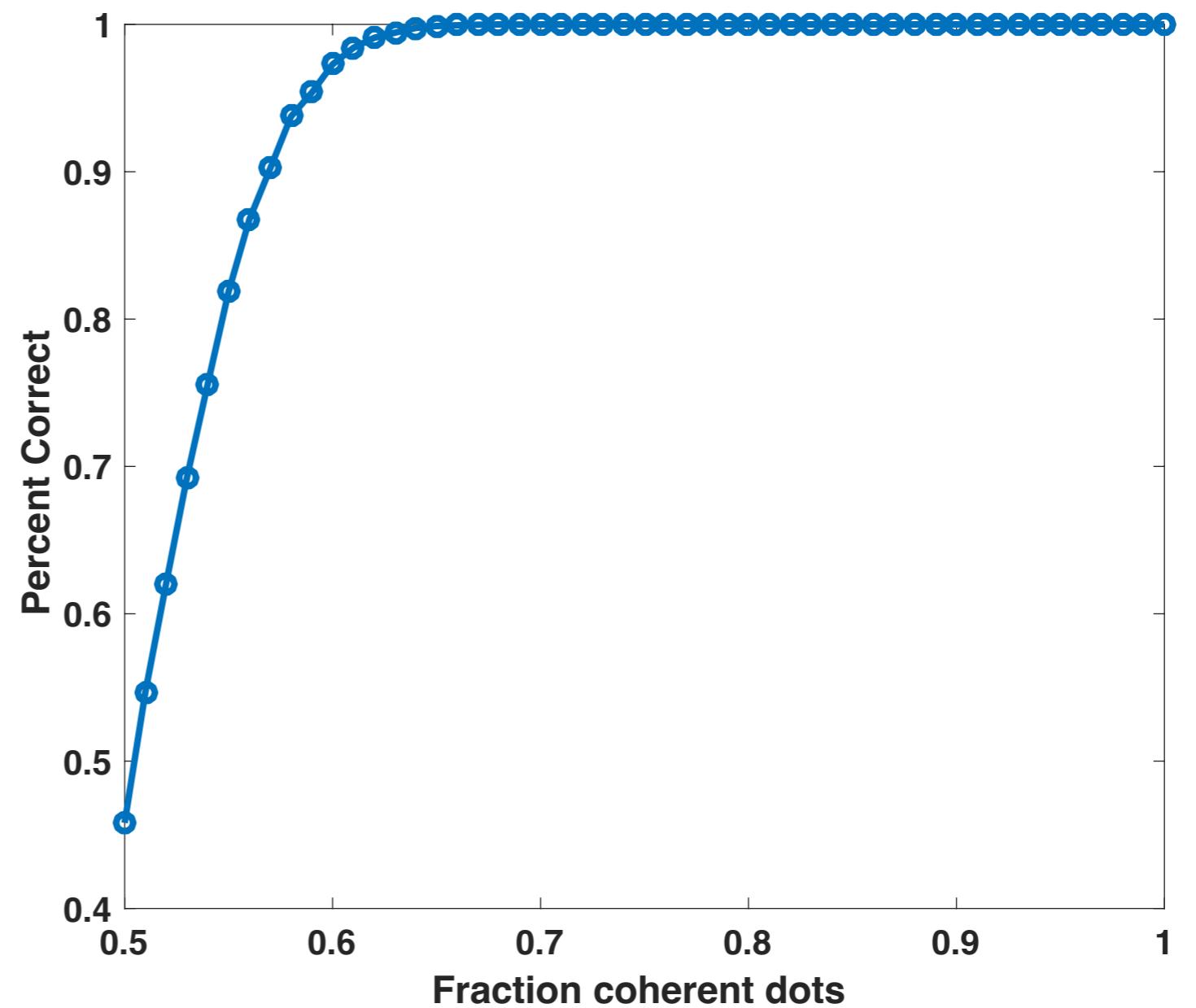
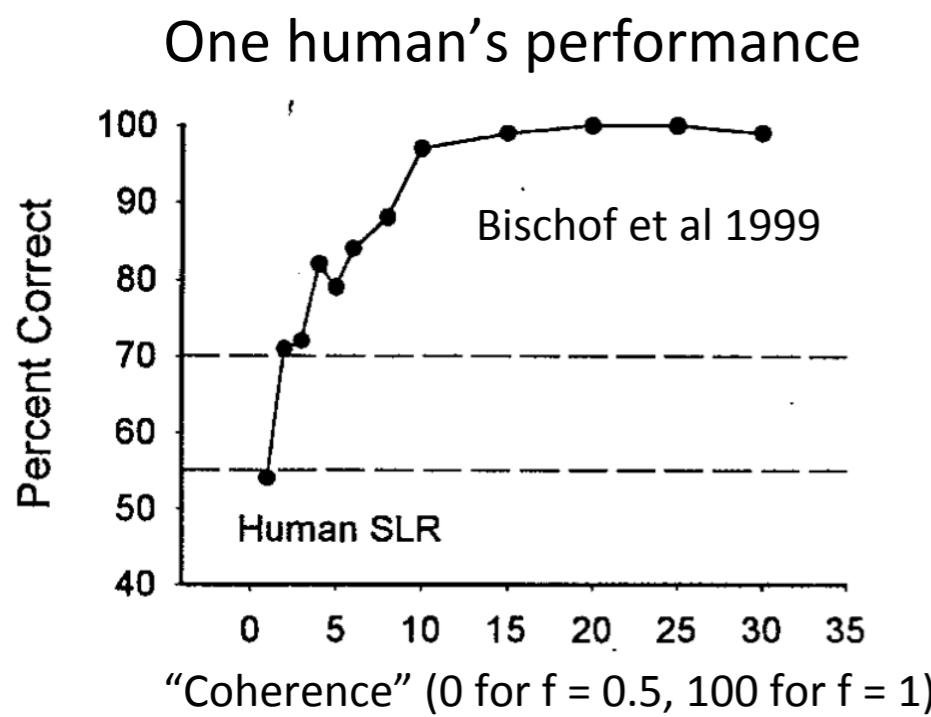
A simple model of perceptual decision making:

- Observe one frame (timestep) of dot motion

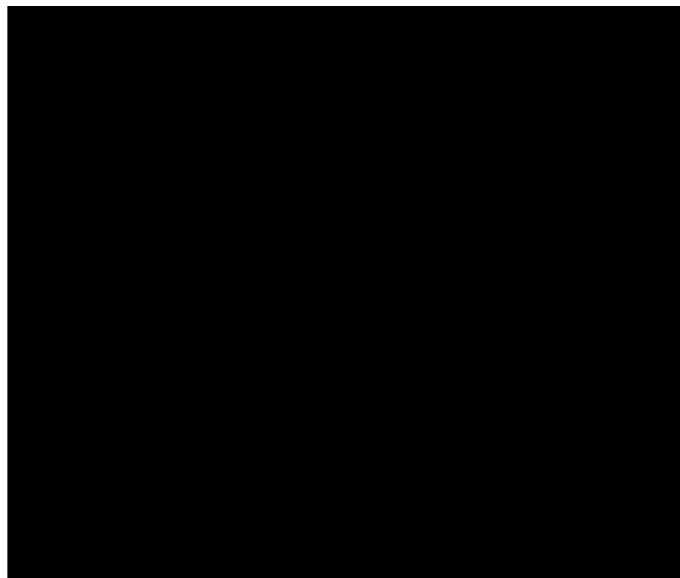
A simple model of perceptual decision making:

- Observe one frame (timestep) of dot motion
- Count ones that are moving rightward
- If that is greater than 1/2 the dots, say right
- Otherwise say left

Our simple model makes a prediction



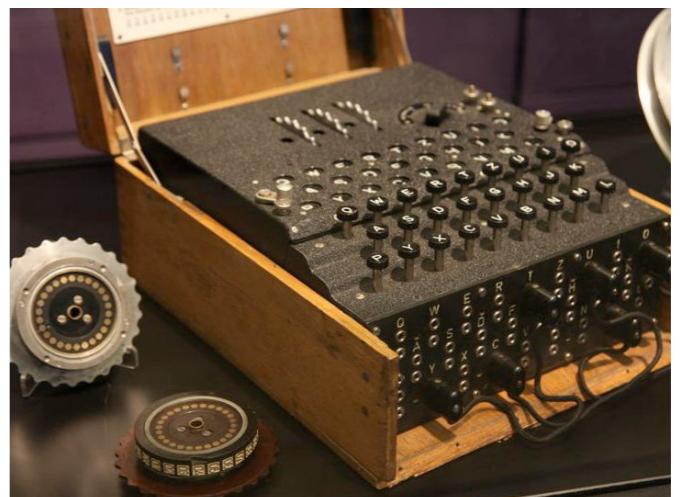
Which way are dots moving?



When *should* you stop to make a decision?

When *should* you stop to make a decision?

The “enigma”



Weight of evidence =

$$\log \left[\frac{\Pr(m|h_1)}{\Pr(m|h_0)} \right] + \log \left[\frac{\Pr(m|h_1)}{\Pr(m|h_0)} \right] + \dots$$

Accumulate to some log odds ratio
Stop at preferred level of certainty



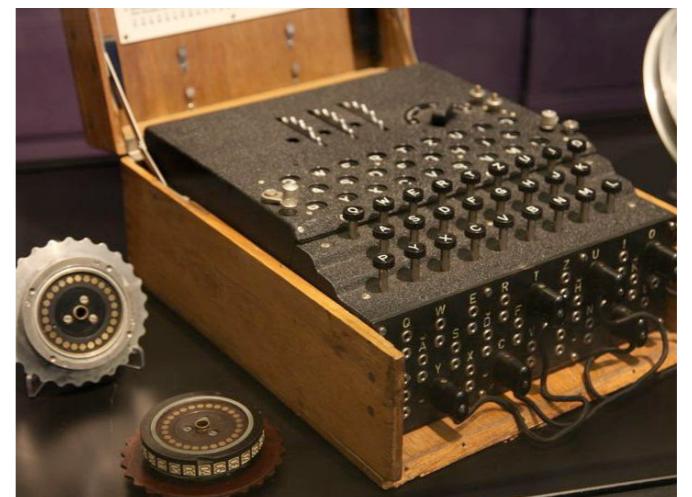
Alan Turing

When *should* you stop to make a decision?

The “enigma”

Key insights:

Evidence can be **accumulated** over time



A fixed **stopping criterion** on accumulated evidence ensures the shortest time to a given level of decision certainty

Wald 1947



Alan Turing

Dot motion evidence accumulation

“True” Motion
Direction

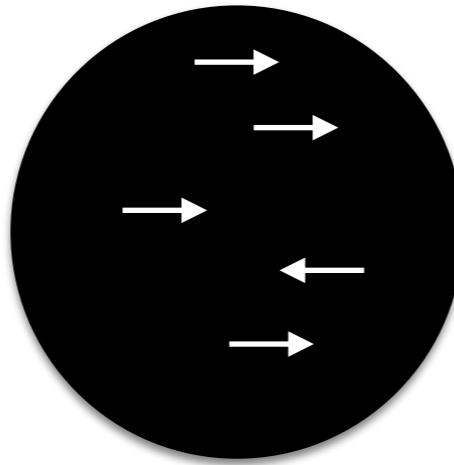


Dot motion evidence accumulation

“True” Motion
Direction



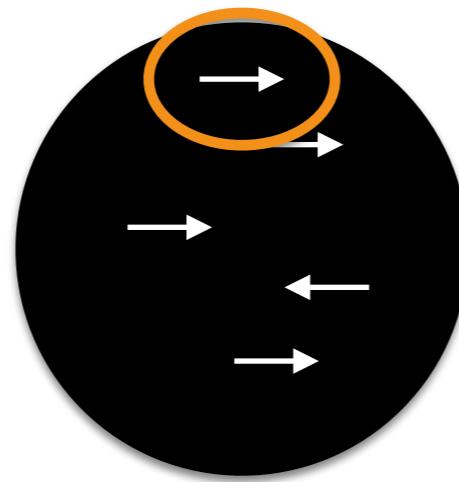
What we see:



Dot motion evidence accumulation

“True” Motion
Direction

What we see:

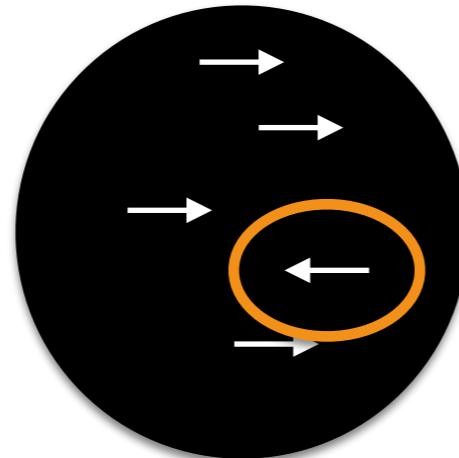


Motion in
Each frame
Comes from
Flip of a
weighted coin

Dot motion evidence accumulation

“True” Motion
Direction

What we see:



Motion in
Each frame
Comes from
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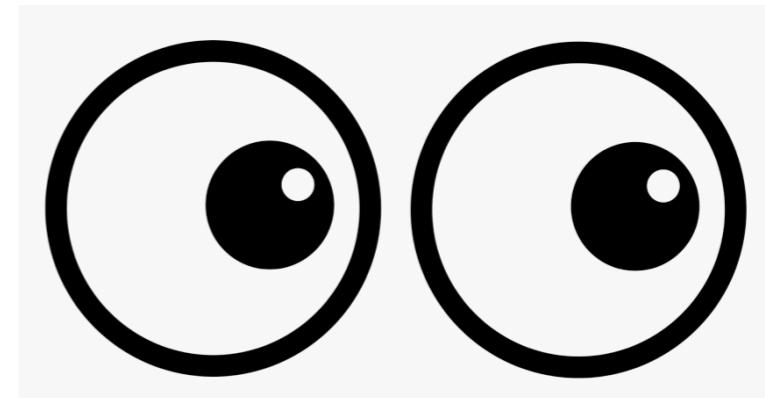
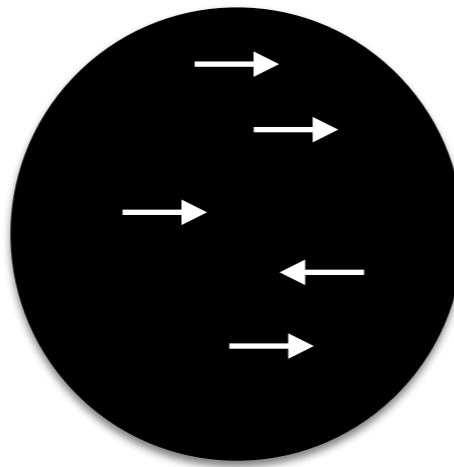
Dot motion evidence accumulation

“True” Motion
Direction



?

What we see:



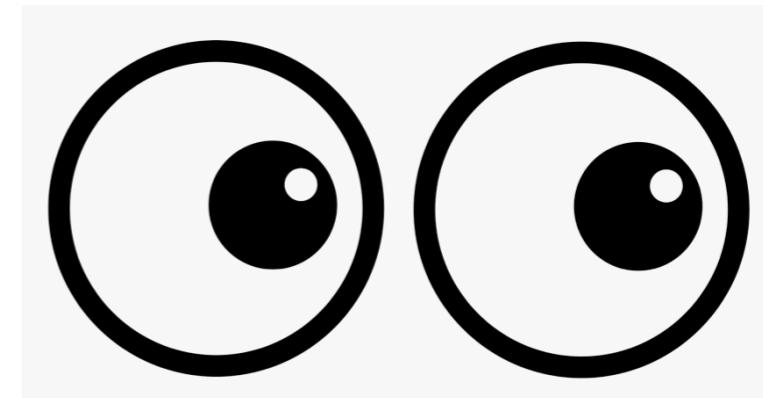
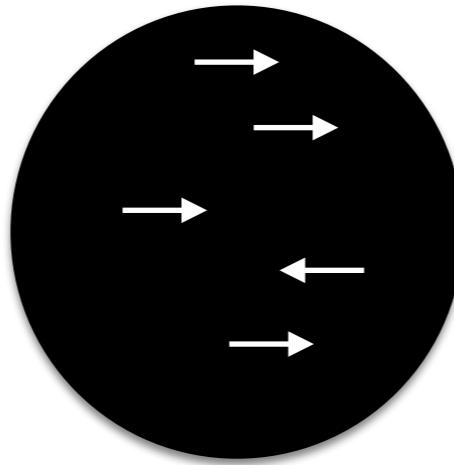
Dot motion evidence accumulation

“True” Motion
Direction



?

What we see:



$$p(\text{right} | \text{observations}) =$$

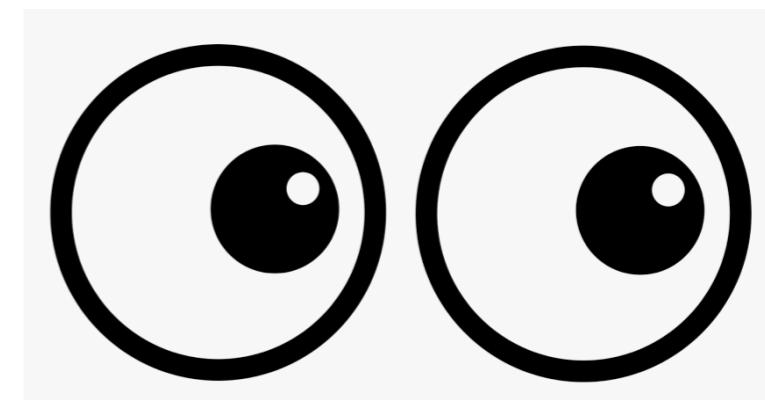
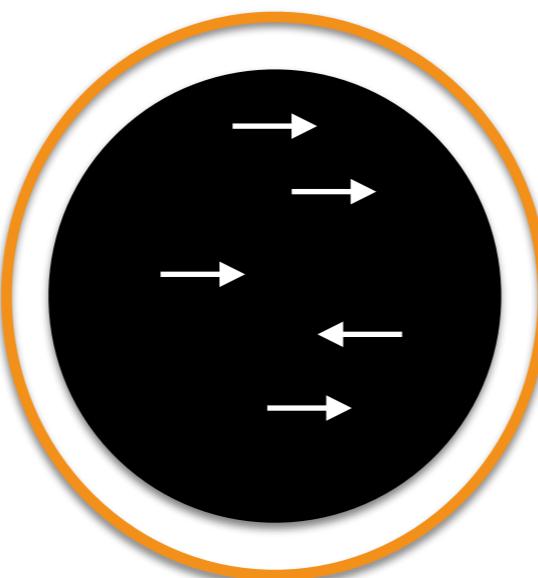
Dot motion evidence accumulation

“True” Motion
Direction



?

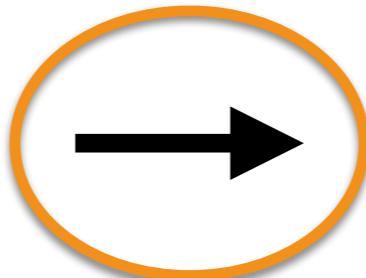
What we see:



$$p(\text{right} | \text{observations}) =$$

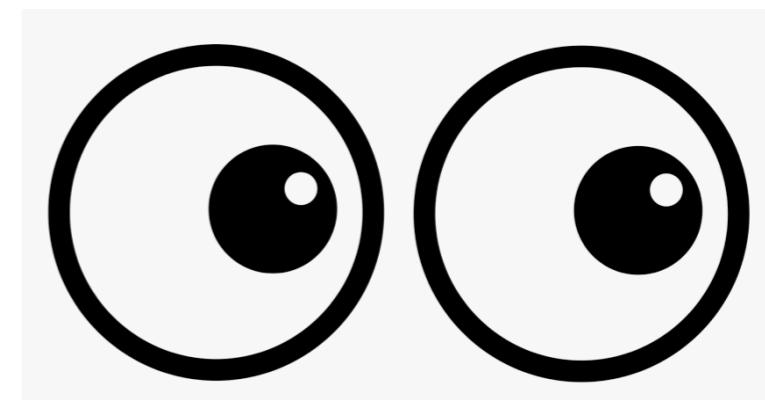
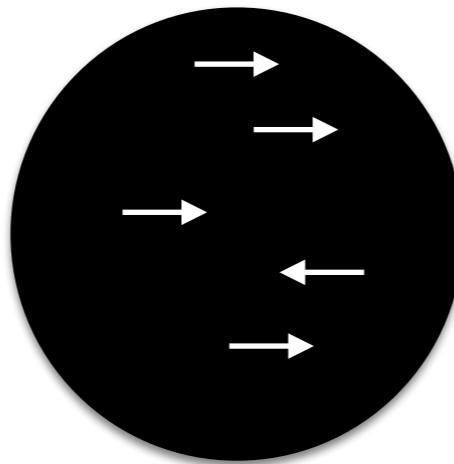
Dot motion evidence accumulation

“True” Motion Direction



?

What we see:



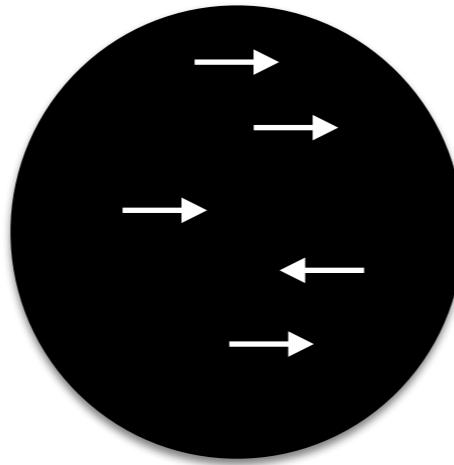
$$p(\text{right} | \text{observations}) =$$

Dot motion evidence accumulation

“True” Motion
Direction



What we see:



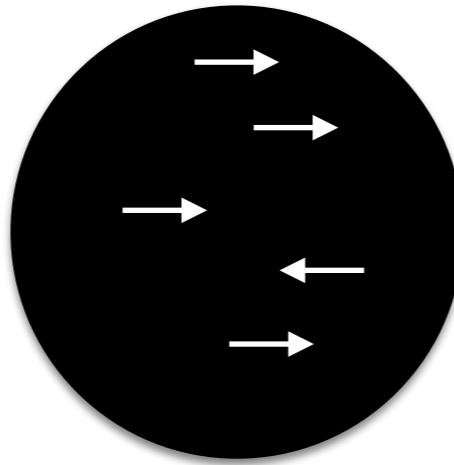
$$p(\text{right}|\text{observations}) = \frac{p(\text{observations}|\text{right})p(\text{right})}{p(\text{observations})}$$

Dot motion evidence accumulation

“True” Motion
Direction

?

What we see:

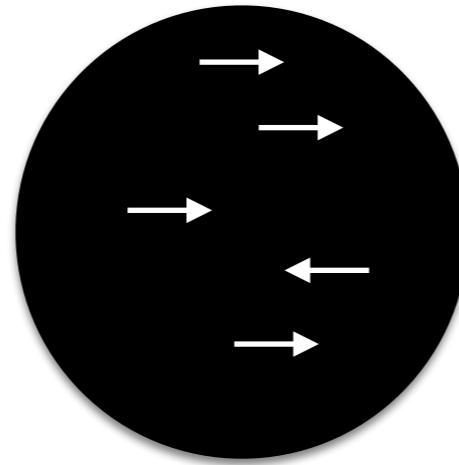


$$p(\text{right}|\text{observations}) = \frac{p(\text{observations}|\text{right})p(\text{right})}{p(\text{observations})}$$

Dot motion evidence accumulation

“True” Motion
Direction

?



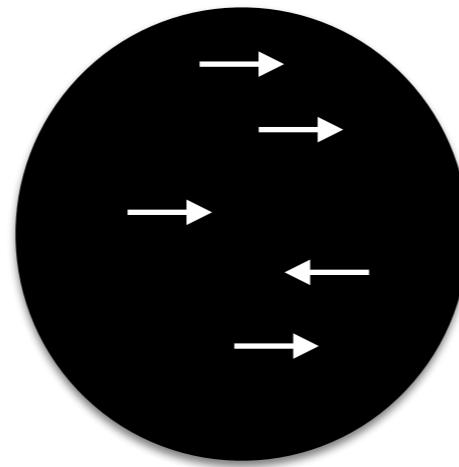
Bayes rule:

$$p(\text{right} | \text{observations}) = \frac{p(\text{observations} | \text{right}) p(\text{right})}{p(\text{observations})}$$

Dot motion evidence accumulation

“True” Motion
Direction

?



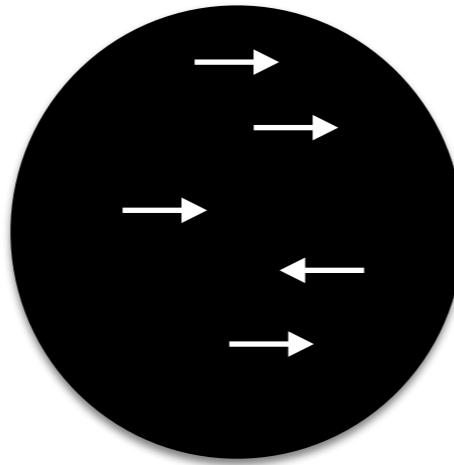
Bayes rule:

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Dot motion evidence accumulation

“True” Motion
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Bayes rule:

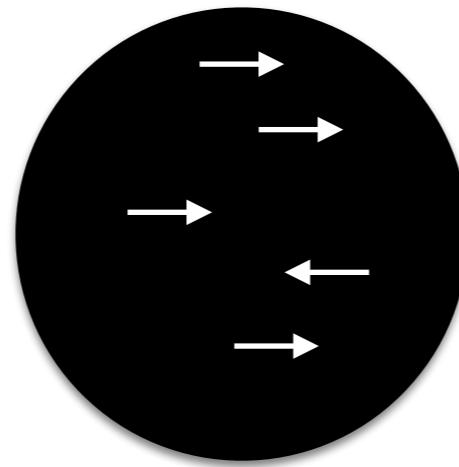
$$p(\text{right}|\text{observations}) = \frac{p(\text{observations}|\text{right})p(\text{right})}{p(\text{observations})}$$

$$p(\text{left}|\text{observations}) = \frac{p(\text{observations}|\text{left})p(\text{left})}{p(\text{observations})}$$

Dot motion evidence accumulation

“True” Motion
Direction

?



Bayes rule:

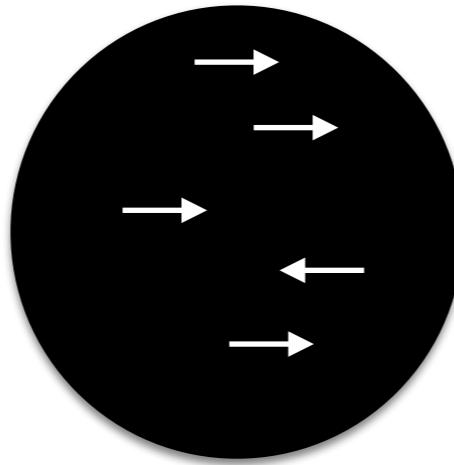
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Dot motion evidence accumulation

“True” Motion
Direction

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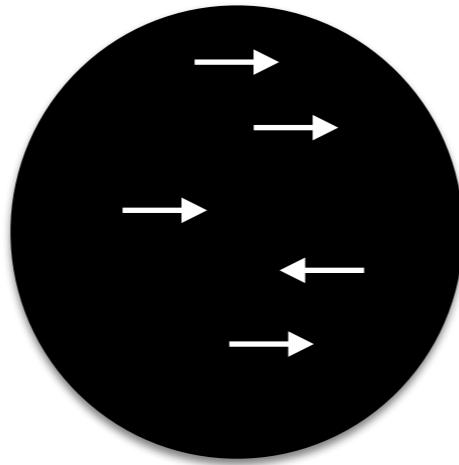


$$\frac{p(right|observations)}{p(left|observations)} = \frac{\frac{p(observations|right)p(right)}{\cancel{p(observations)}}}{\frac{p(observations|left)p(left)}{\cancel{p(observations)}}}$$

Dot motion evidence accumulation

“True” Motion
Direction

?



Ratio:

Posterior

$$\frac{p(\text{right}|\text{observations})}{p(\text{left}|\text{observations})}$$

Likelihood

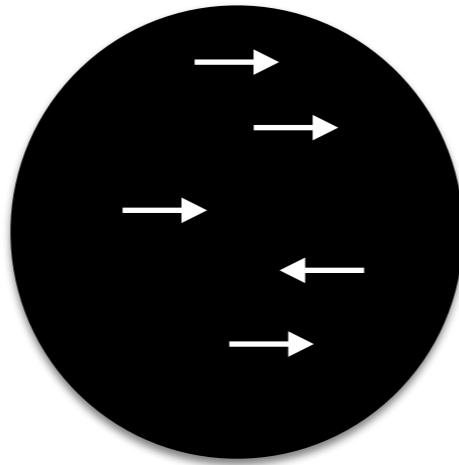
Prior

$$= \frac{p(\text{observations}|\text{right})p(\text{right})}{p(\text{observations}|\text{left})p(\text{left})}$$

Dot motion evidence accumulation

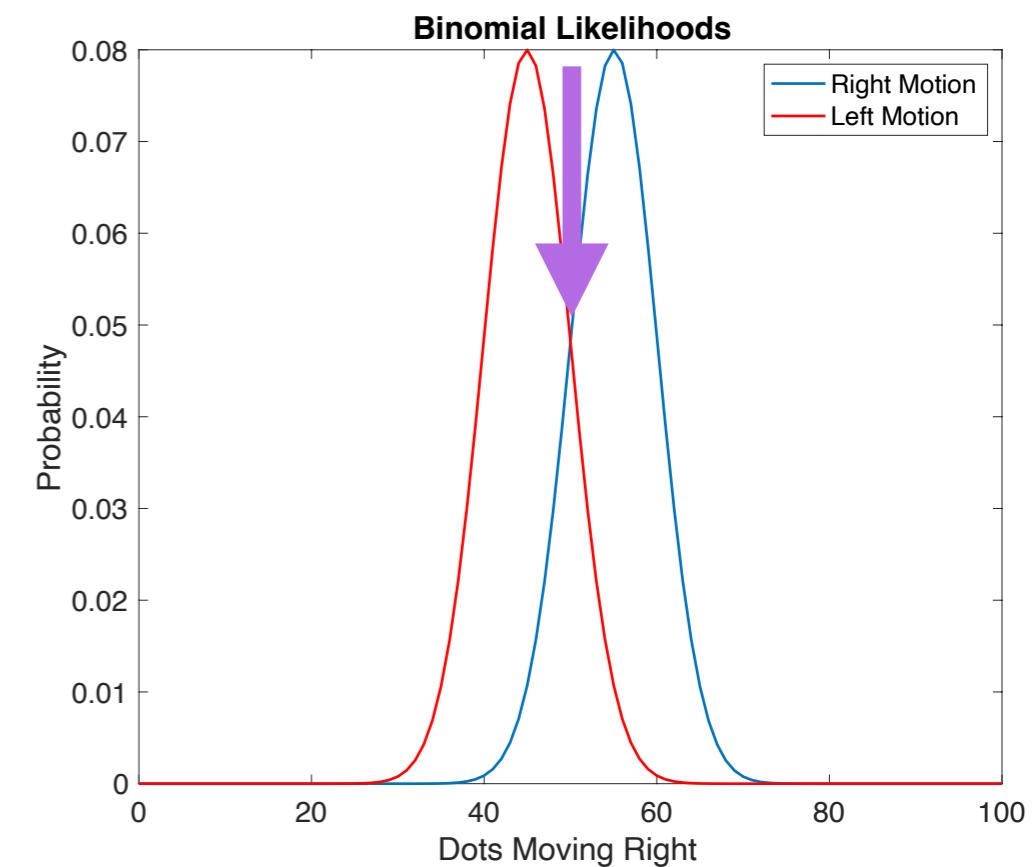
“True” Motion Direction

?



Ratio:

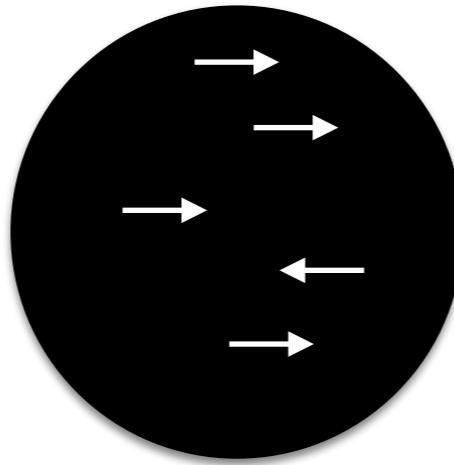
$$\frac{p(\text{right}|\text{observations})}{p(\text{left}|\text{observations})} = \frac{p(\text{observations}|\text{right})p(\text{right})}{p(\text{observations}|\text{left})p(\text{left})}$$



Dot motion evidence accumulation

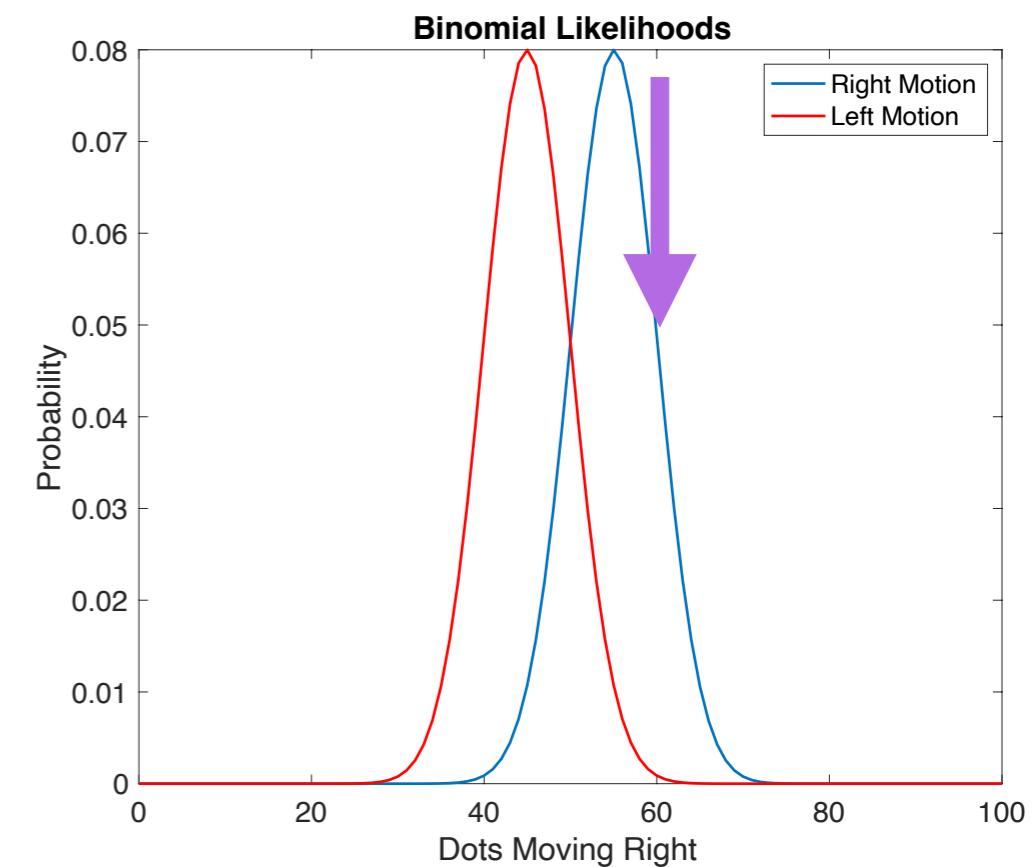
“True” Motion Direction

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Ratio:

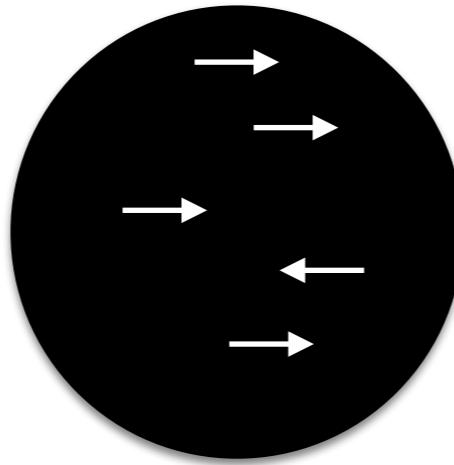
$$\frac{p(\text{right}|\text{observations})}{p(\text{left}|\text{observations})} = \frac{p(\text{observations}|\text{right})p(\text{right})}{p(\text{observations}|\text{left})p(\text{left})}$$



Dot motion evidence accumulation

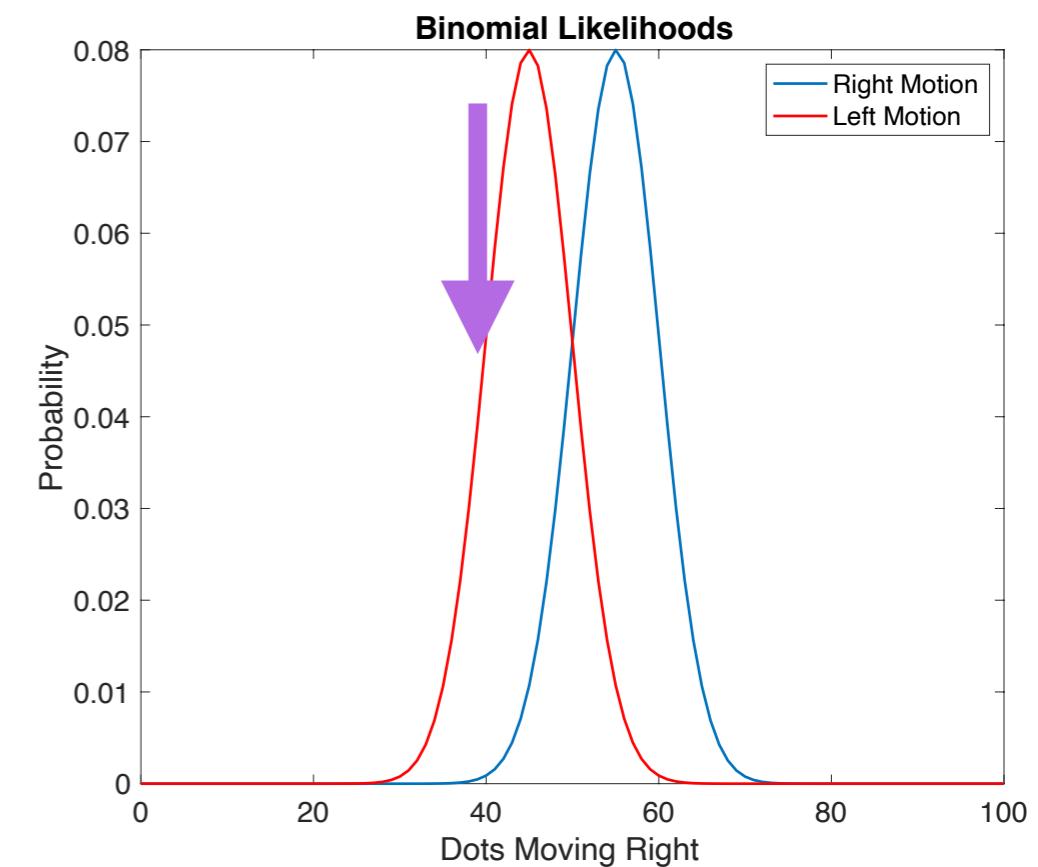
“True” Motion Direction

?



Ratio:

$$\frac{p(\text{right}|\text{observations})}{p(\text{left}|\text{observations})} = \frac{p(\text{observations}|\text{right})p(\text{right})}{p(\text{observations}|\text{left})p(\text{left})}$$



Dot motion evidence accumulation

Log Ratio:

Posterior

Likelihood

Prior

$$\log \left(\frac{p(\text{right}|\text{observations})}{p(\text{left}|\text{observations})} \right) = \log \left(\frac{p(\text{observations}|\text{right})}{p(\text{observations}|\text{left})} \right) + \log \left(\frac{p(\text{right})}{p(\text{left})} \right)$$

Dot motion evidence accumulation

Log Ratio:

Posterior

Likelihood

Prior

$$\log \left(\frac{p(right|observations)}{p(left|observations)} \right) = \log \left(\frac{p(observations|right)}{p(observations|left)} \right) + \boxed{\log \left(\frac{p(right)}{p(left)} \right)}$$

Dot motion evidence accumulation

Log Ratio:

Posterior

Likelihood

$$\log \left(\frac{p(right|observations)}{p(left|observations)} \right) = \log \left(\frac{p(observations|right)}{p(observations|left)} \right) + \log \left(\frac{p(observations|right)}{p(observations|left)} \right) + \dots$$

timestep 1

timestep 2

...

Dot motion evidence accumulation

Log Ratio:

Posterior

Likelihood

Prior

$$\log \left(\frac{p(right|observations)}{p(left|observations)} \right) = \log \left(\frac{p(observations|right)}{p(observations|left)} \right) + \log \left(\frac{p(right)}{p(left)} \right)$$



Dot motion evidence accumulation

Log Ratio:

Posterior

$$\log \left(\frac{p(right|observations)}{p(left|observations)} \right)$$

Likelihood

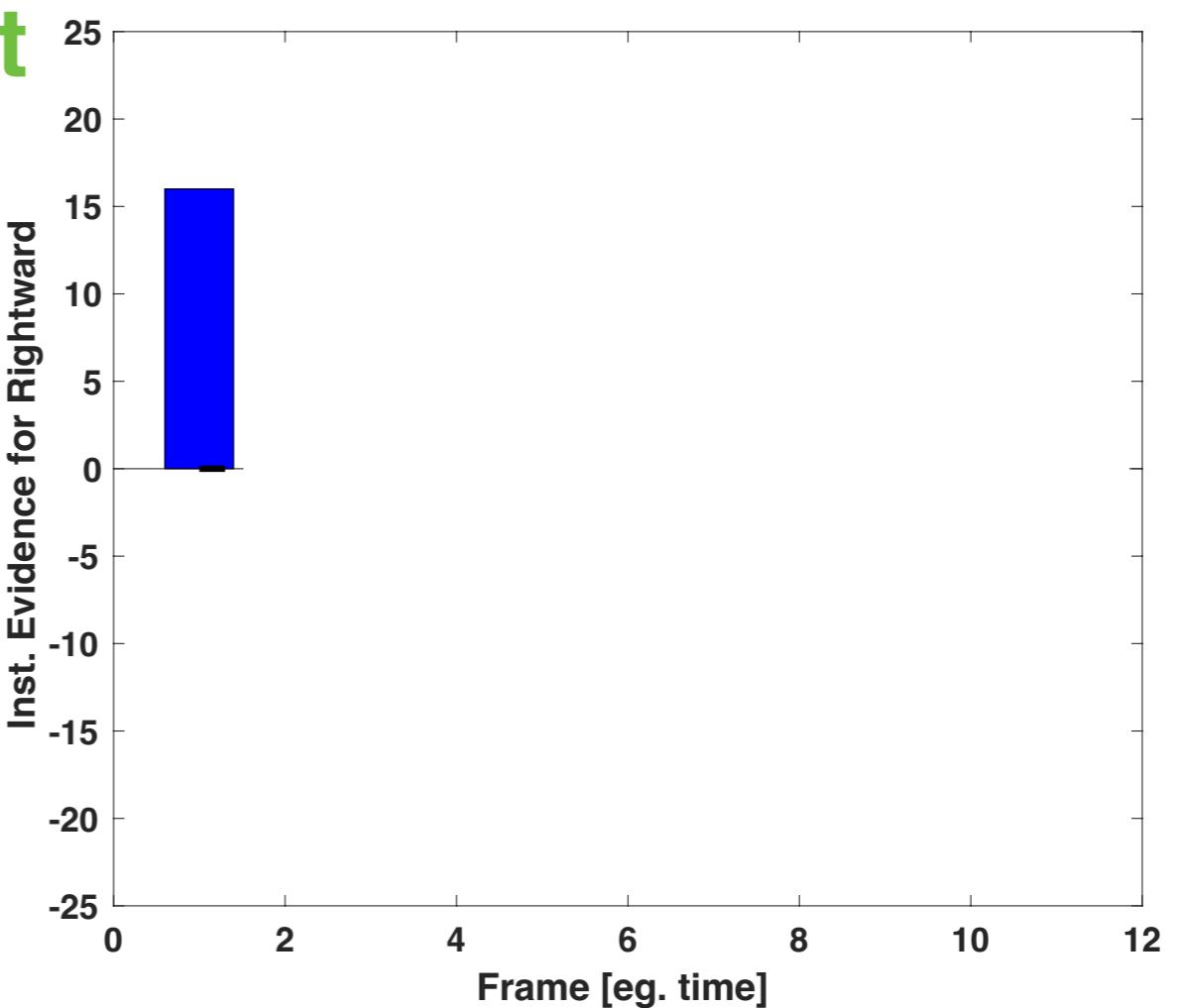
$$\log \left(\frac{p(observations|right)}{p(observations|left)} \right)$$

Prior

$$+ \log \left(\frac{p(right)}{p(left)} \right)$$

Instantaneous
evidence

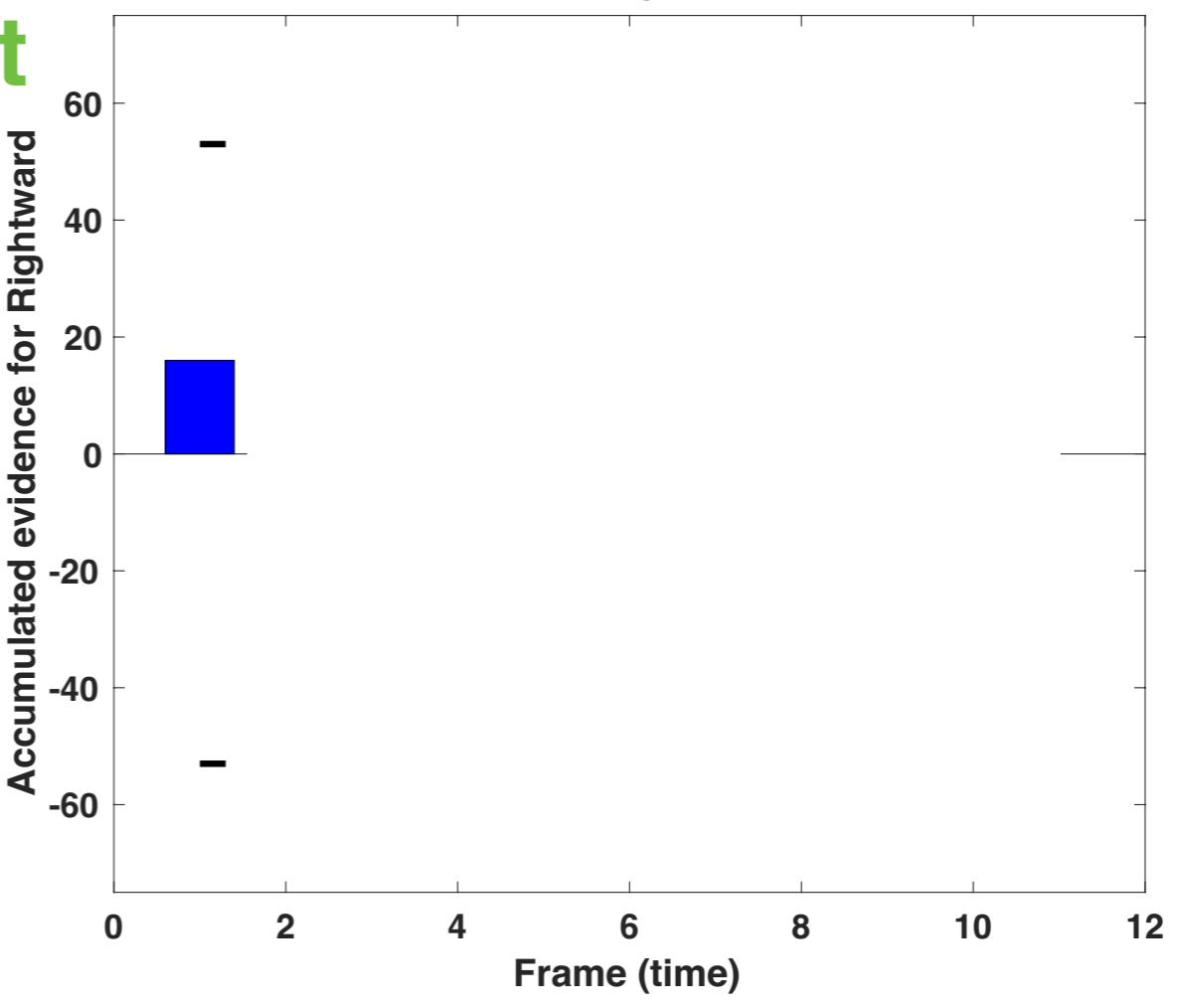
More right



Accumulated
evidence

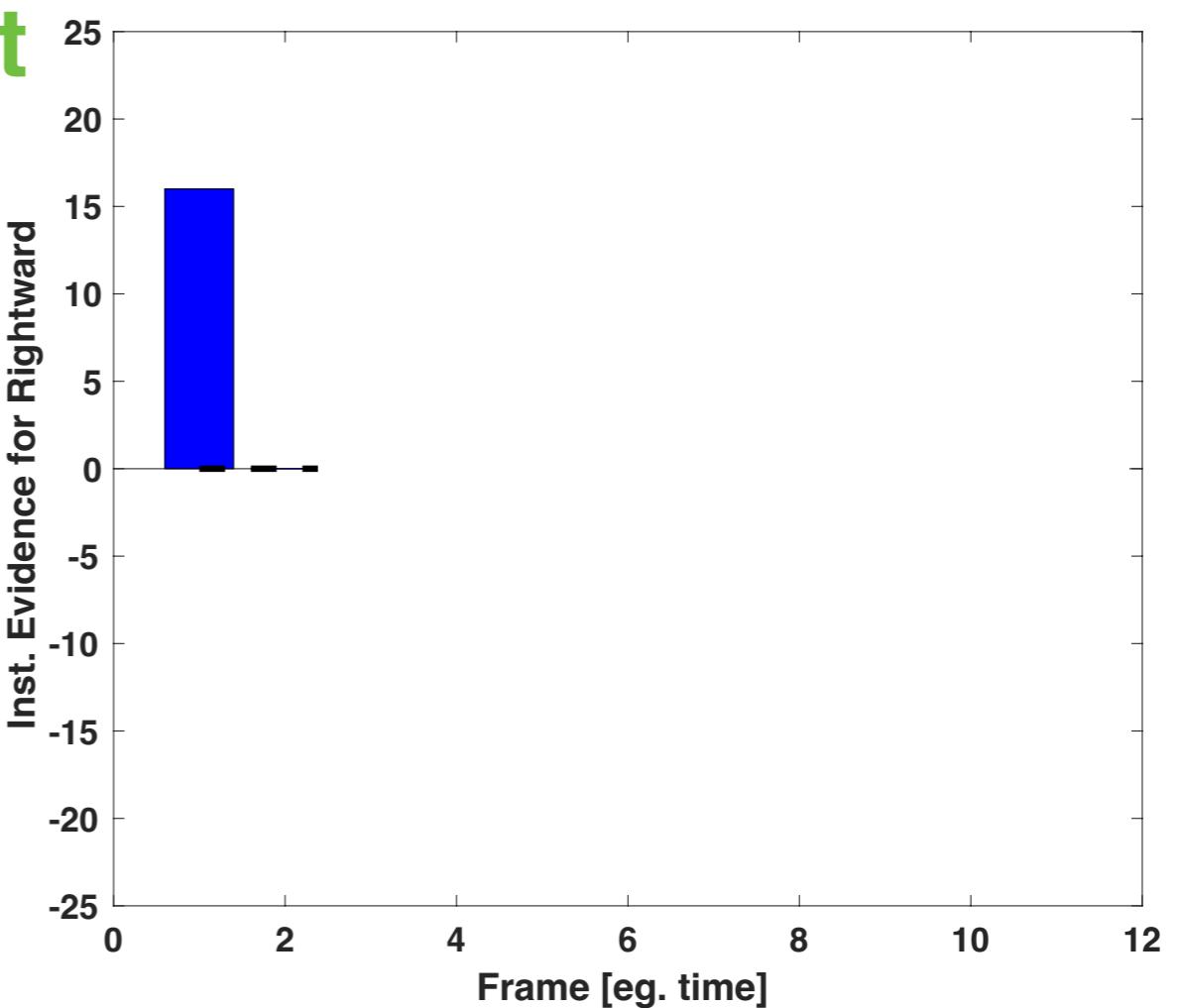
More right

More left



Instantaneous
evidence

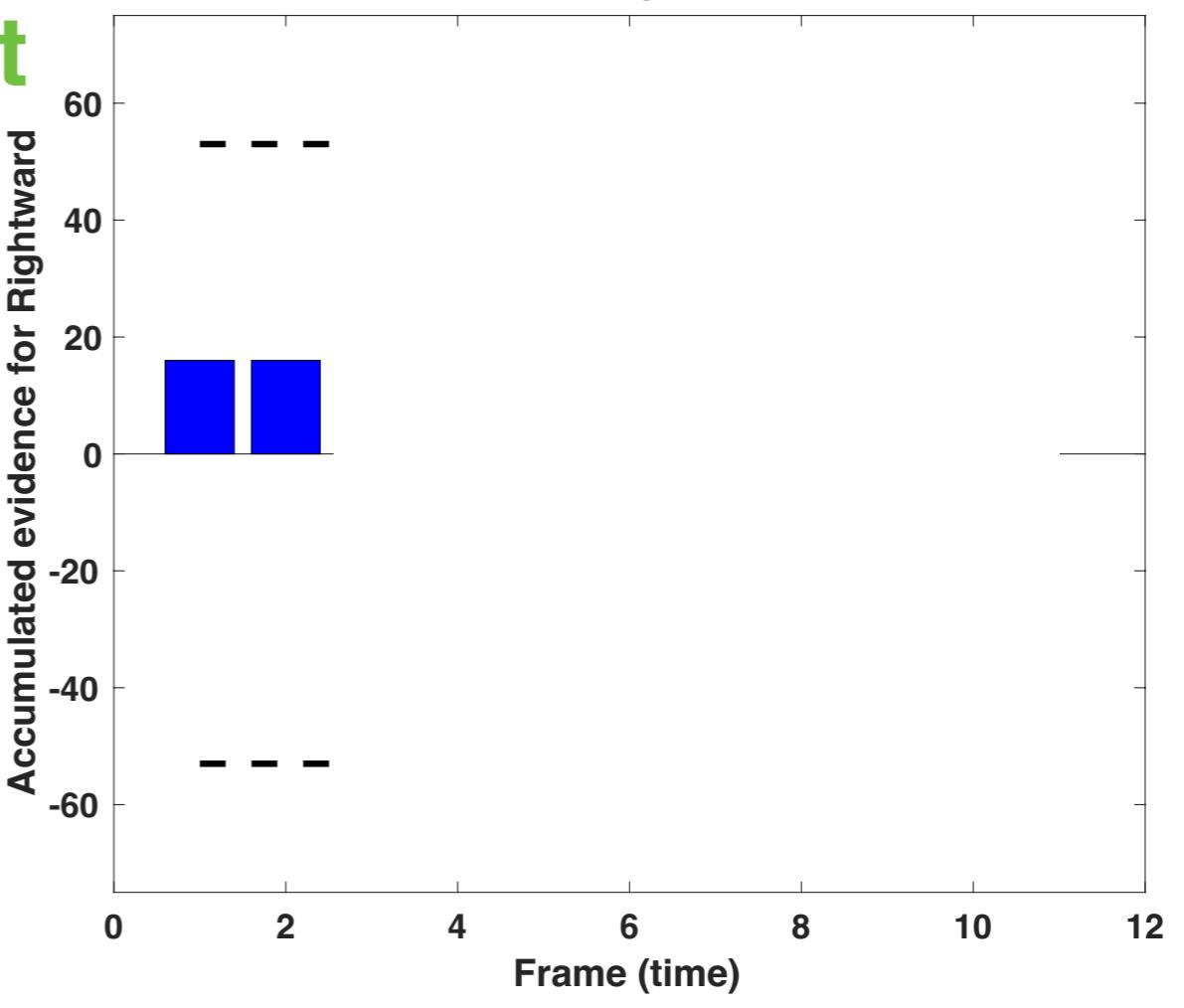
More right



Accumulated
evidence

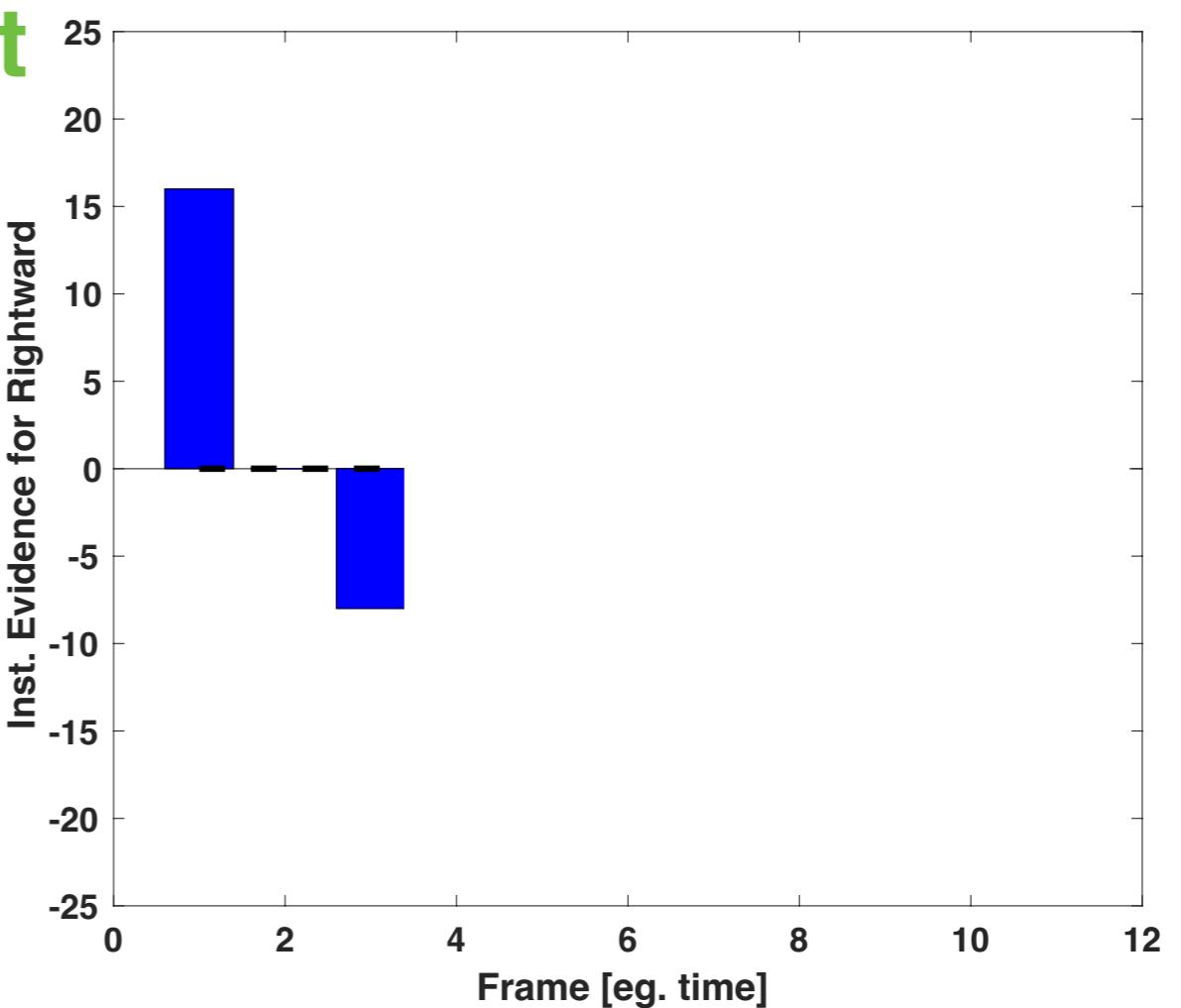
More right

More left



Instantaneous
evidence

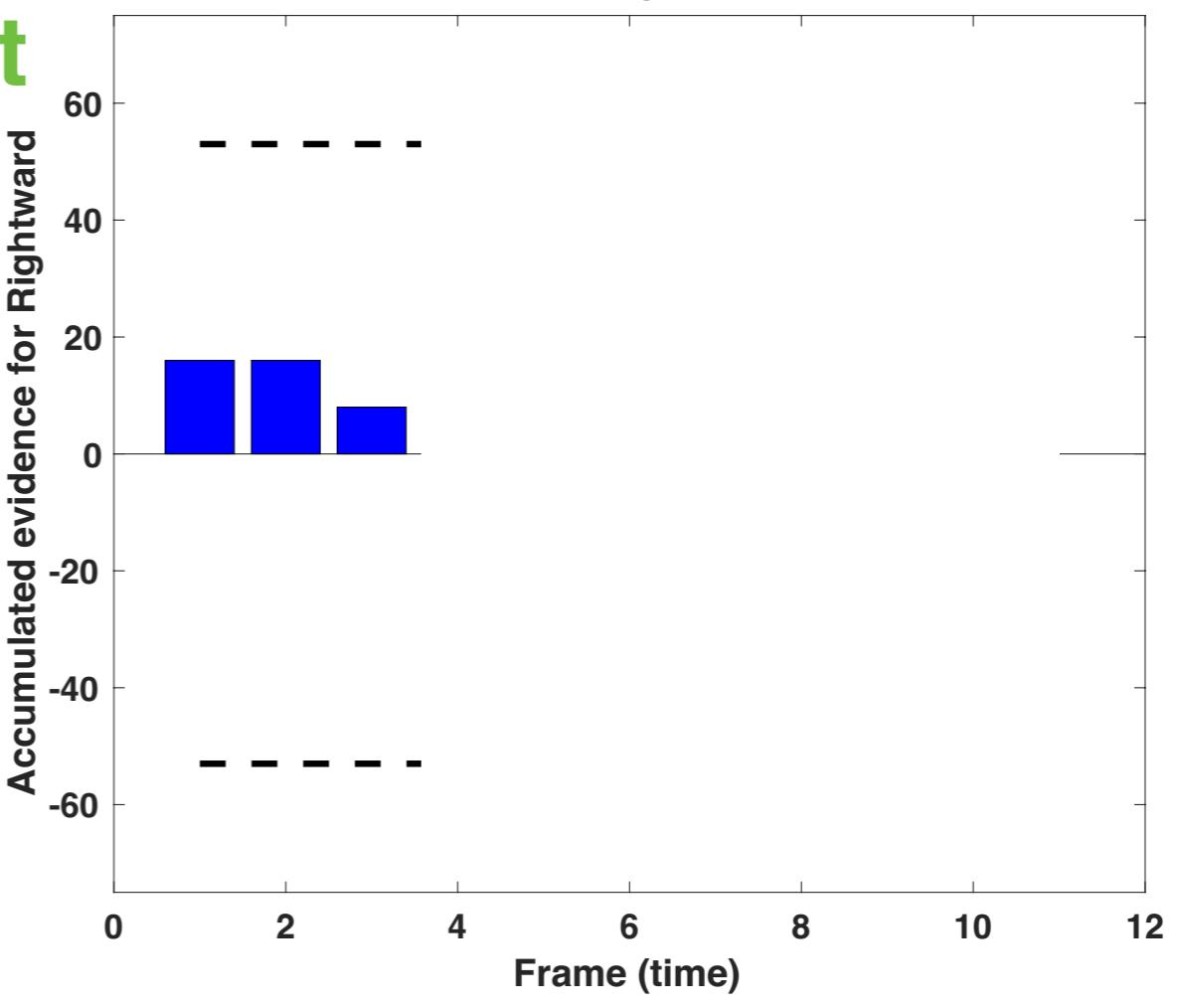
More right



Accumulated
evidence

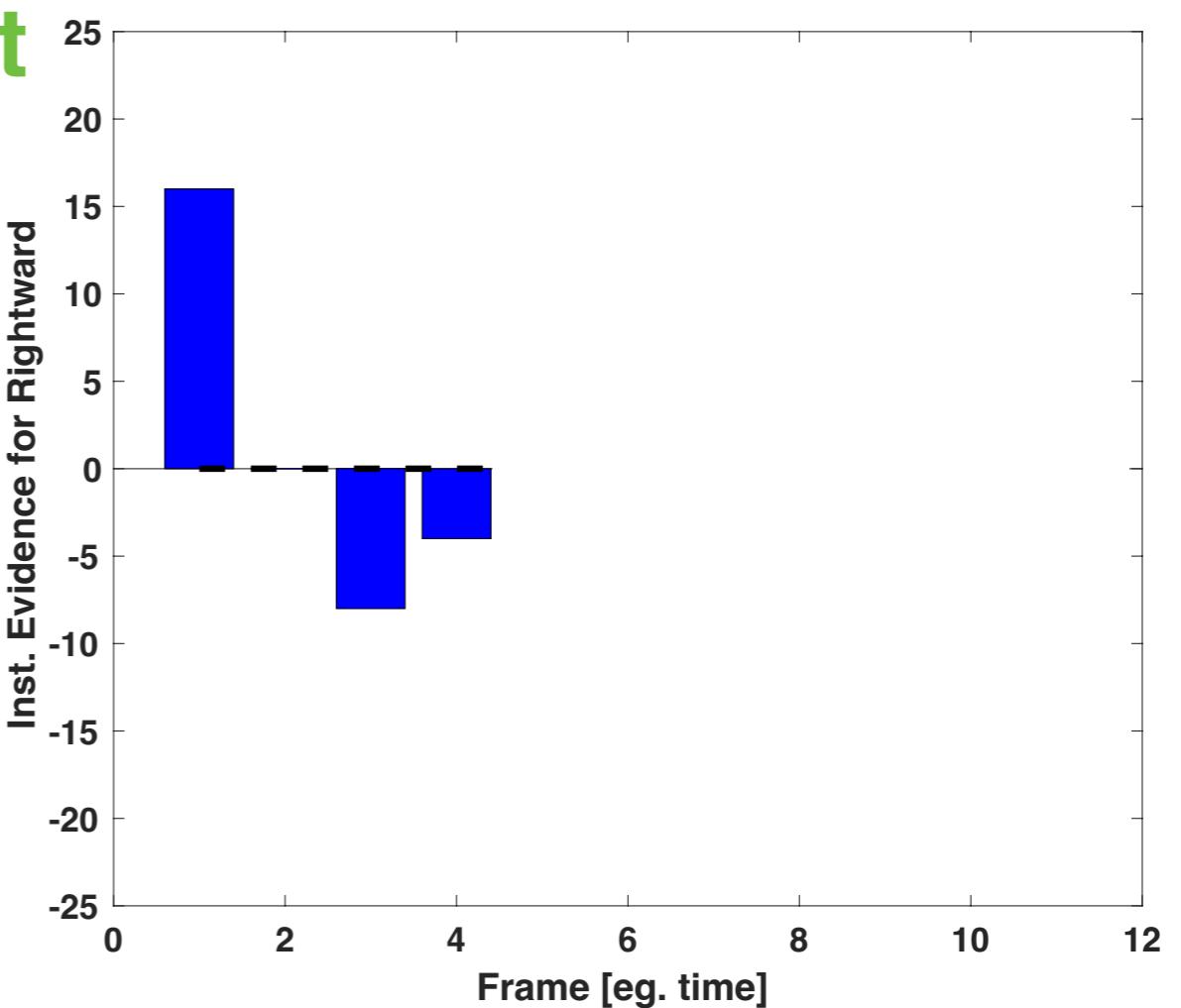
More right

More left



Instantaneous
evidence

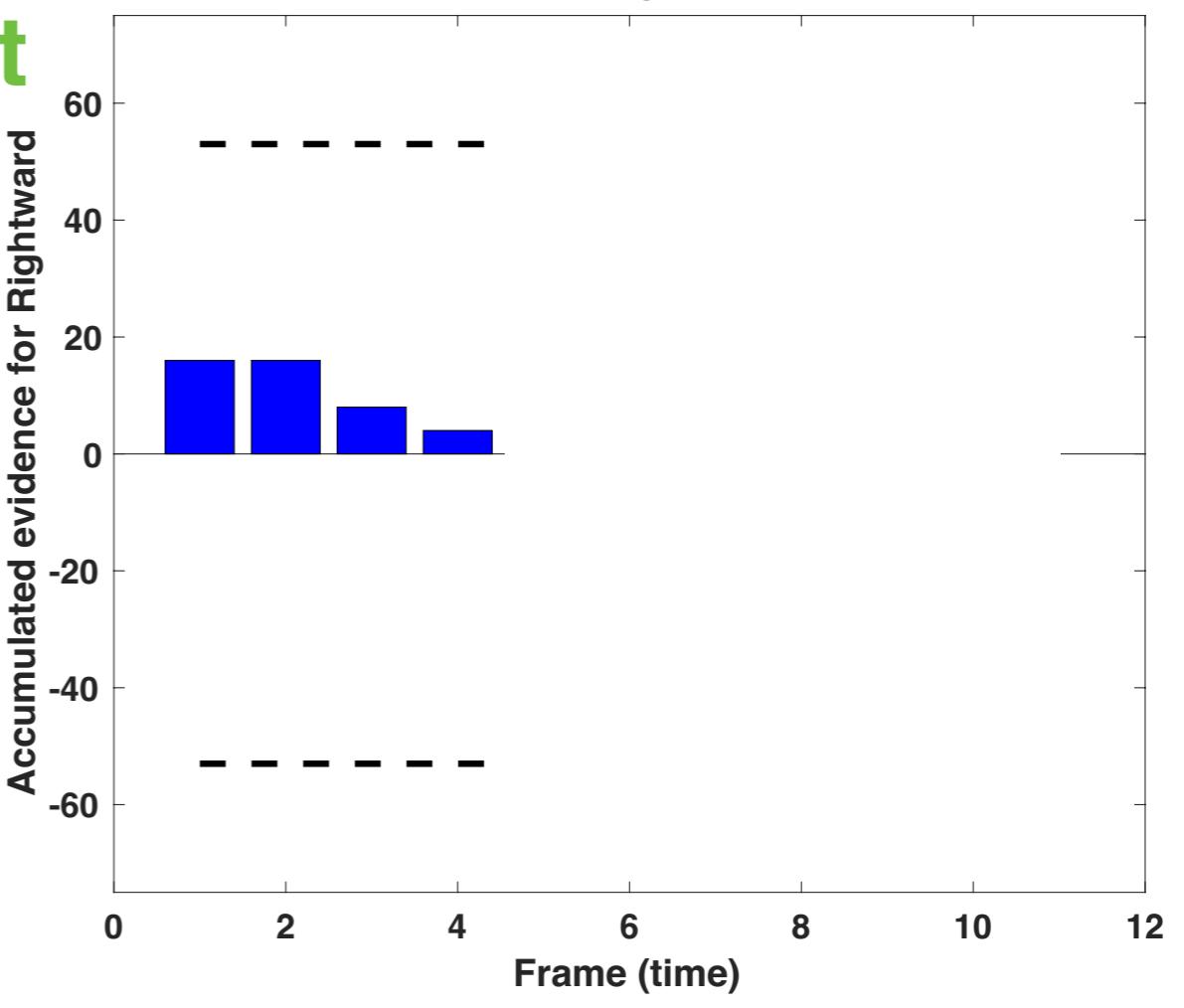
More right



Accumulated
evidence

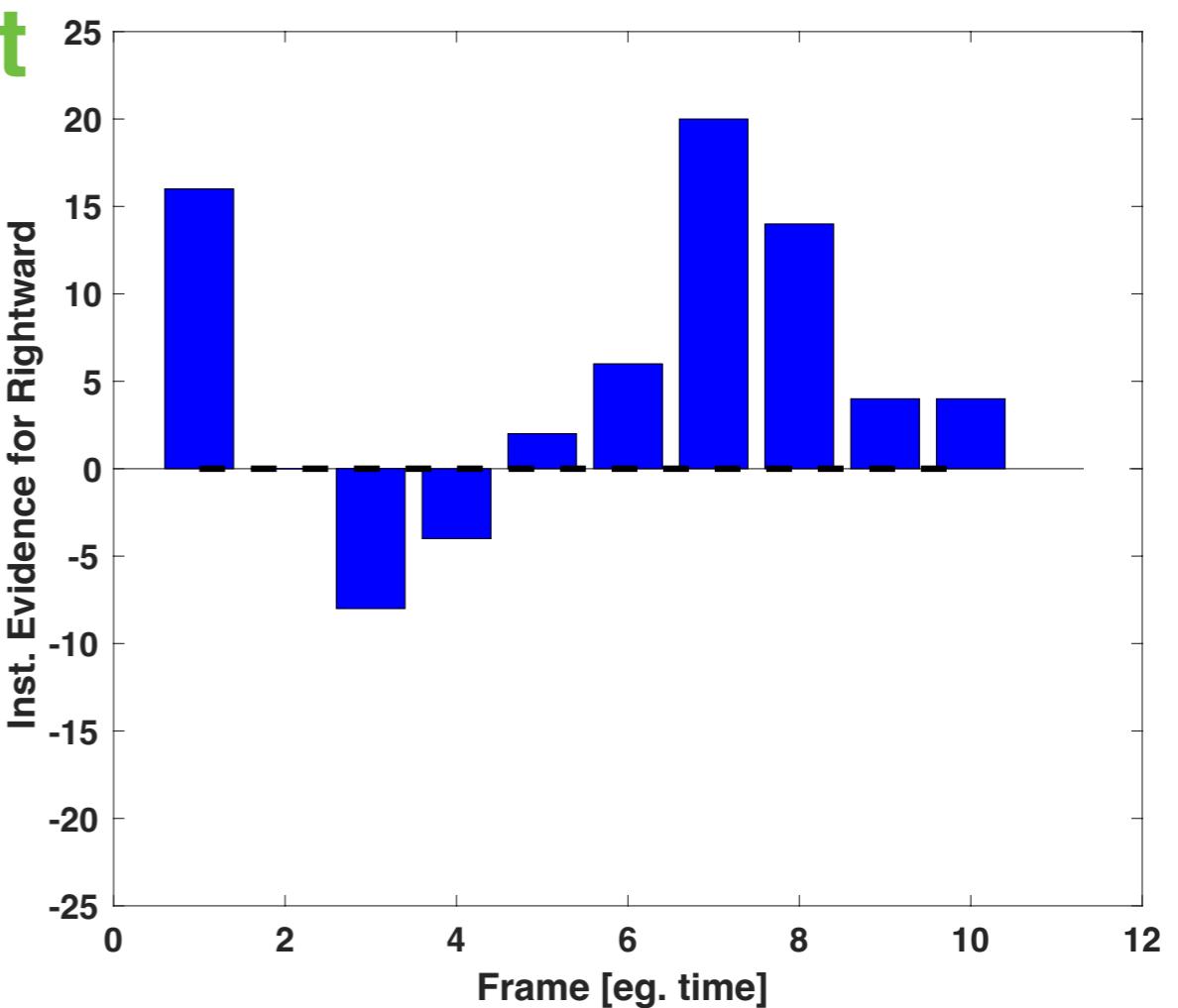
More right

More left



Instantaneous
evidence

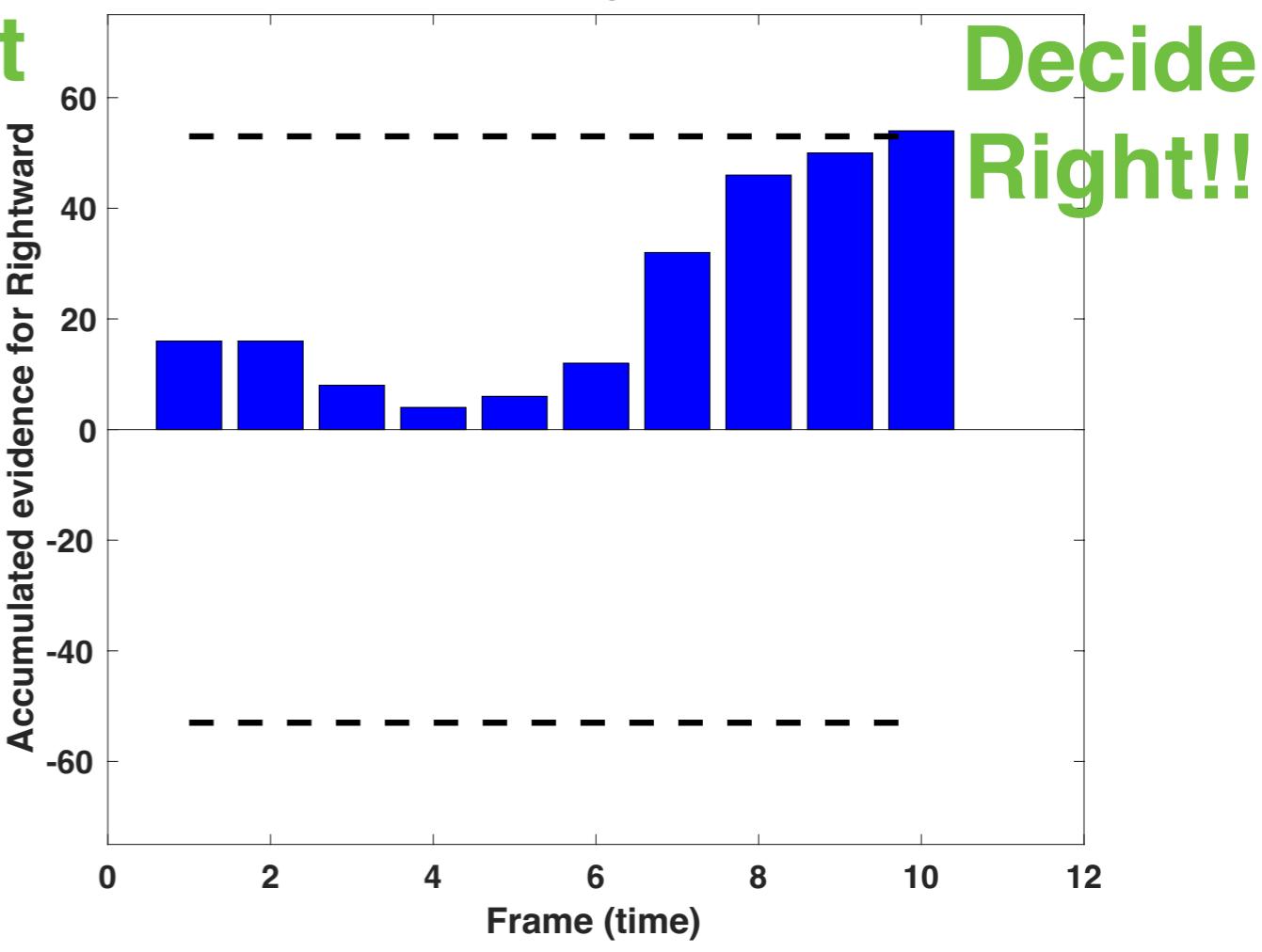
More right



Accumulated
evidence

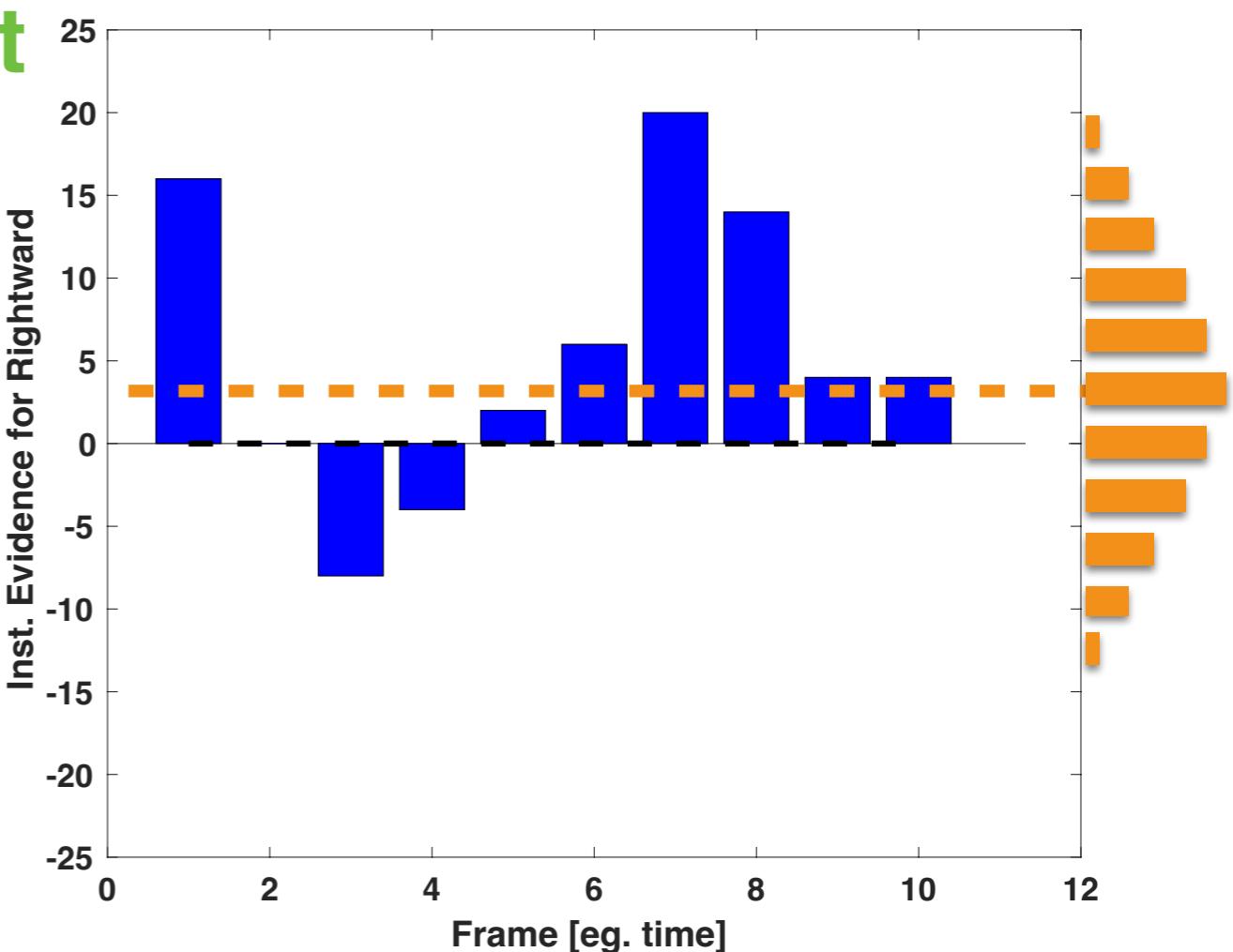
More right

More left



Instantaneous
evidence

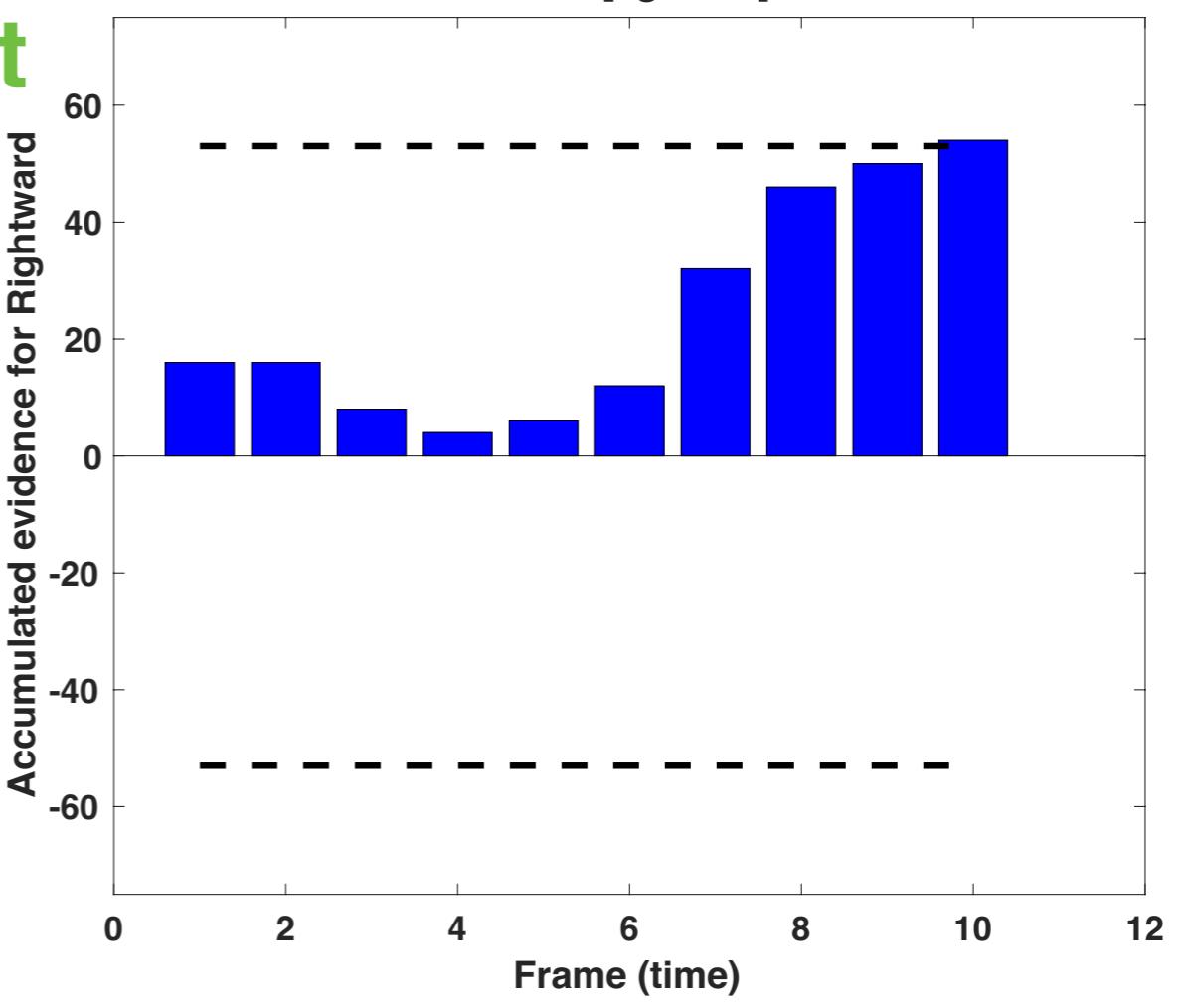
More right



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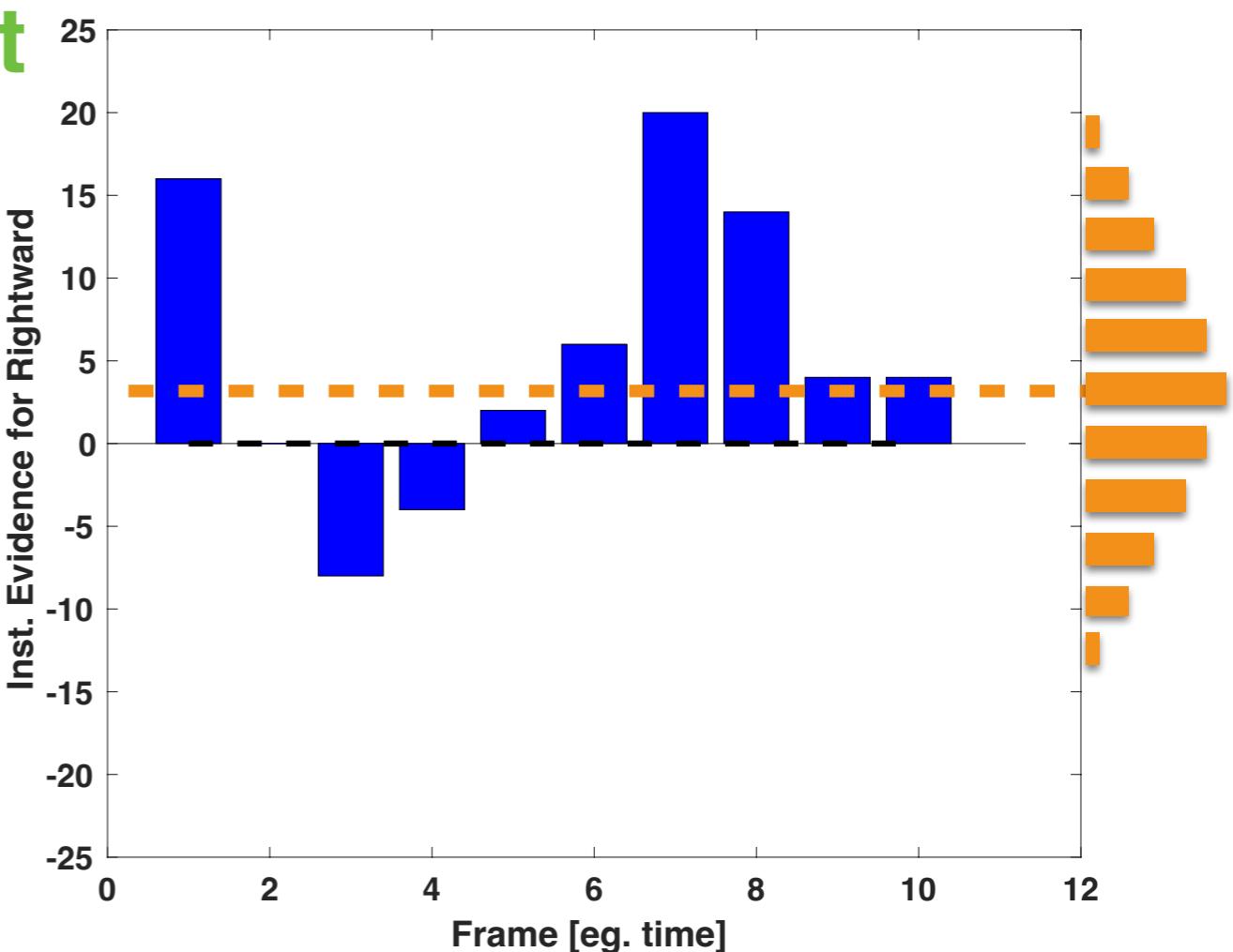
More right

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Instantaneous
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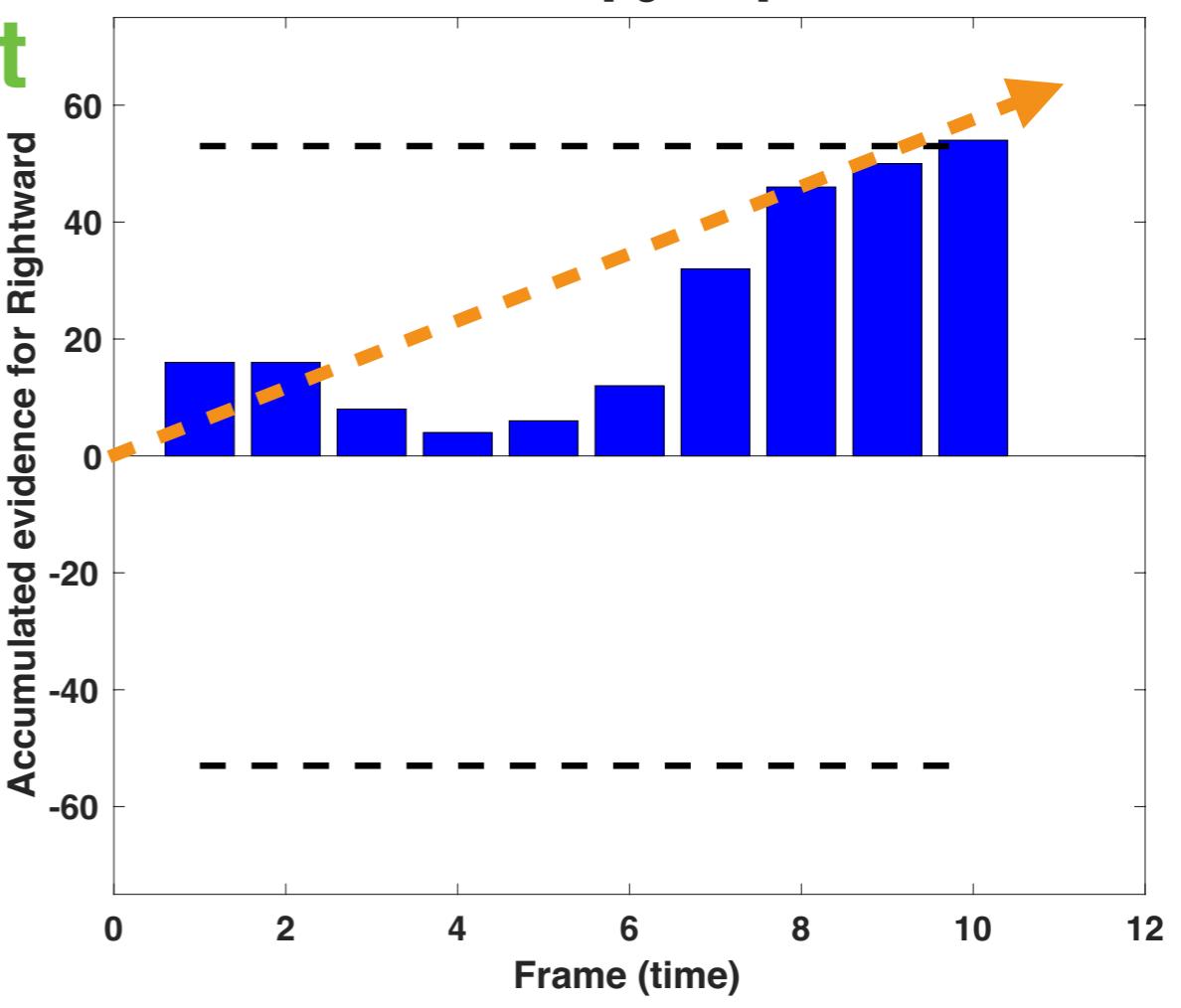
More right



Accumulated
evidence

More right

More left



Drift diffusion model:

Drift diffusion model:

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[TV Wiecki, I Sofer, MJ Frank - Frontiers in neuroinformatics, 2013 - frontiersin.org](#)
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Drift diffusion model:

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Since 2020 ... A basic goal of decision **neuroscience** and neuroeconomics is to characterize the computations carried out by the brain to make different ... Over the last decade, a sizable number of studies have found that standard **drift-diffusion**-models (DDM; Ratcliff, 1978, 2002; Busemeyer ...

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Create alert

The **drift diffusion** model can account for the accuracy and reaction time of value-based choices under high and low time pressure MM Mormann, J Malmaud, A Huth, C Koch... - ... and Decision Making, 2010 - papers.ssrn.com  caltech.edu Full View

... The **drift diffusion** model (DDM) is one of the corner- stones of modern psychology (Ratcliff ... & Smith, 2004; Smith & Ratcliff, 2004) and, increasingly, of behavioral **neuro-** science (Bogacz ... An important open problem in behavioral **neuroscience** is how the brain compares values to ...

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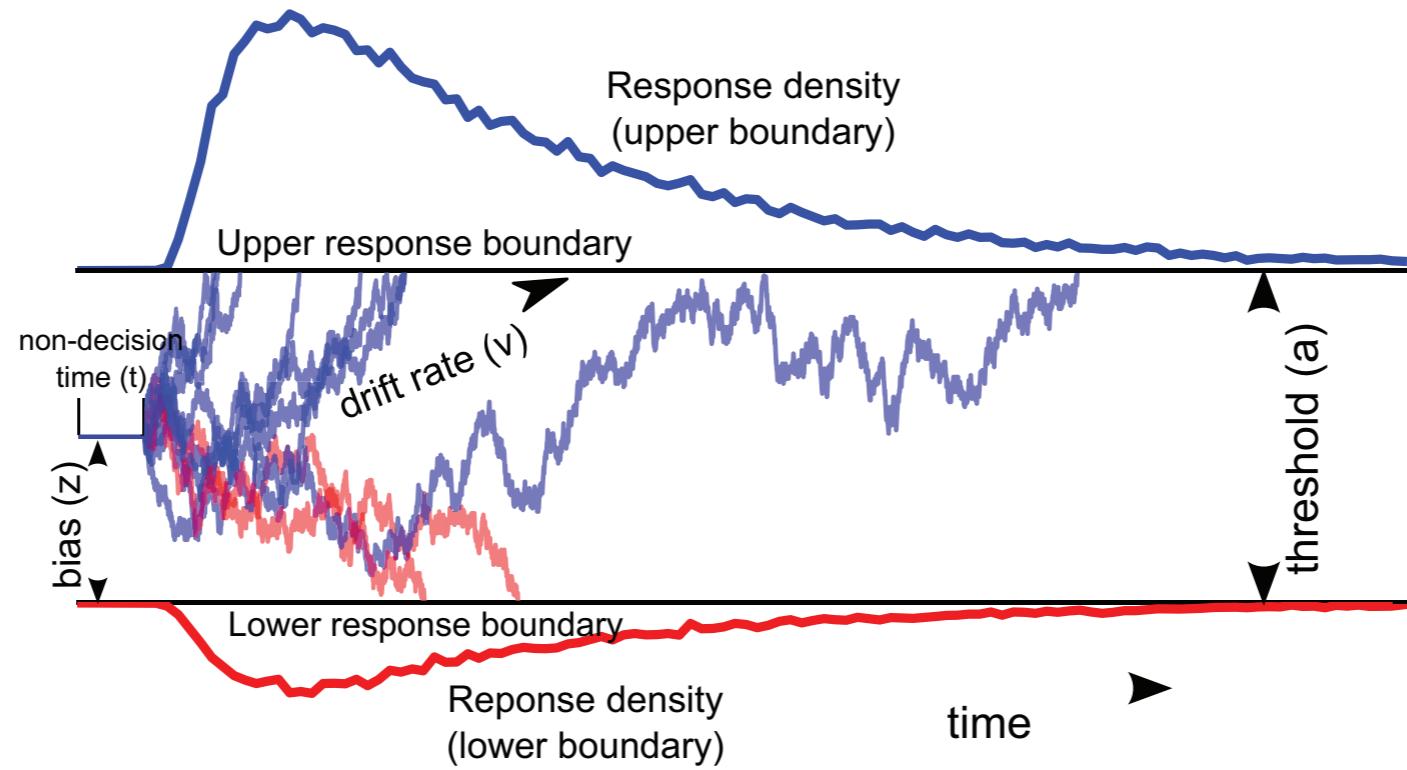
Key advance:

Model both choice AND reaction time!!!

Drift diffusion model:

Key advance:

Model both choice AND reaction time!!!



Drift diffusion model:

Our simple model with the following changes:

Drift diffusion model:

Our simple model with the following changes:

1)

accumulate evidence over time



Drift diffusion model:

Our simple model with the following changes:

- 1) accumulate evidence over time 
- 2) make a decision after reaching a criterion 

Drift diffusion model:

Our simple model with the following changes:

- 1) accumulate evidence over time 
- 2) make a decision after reaching a criterion 
- 3) normal distribution of evidence

Drift diffusion model formalism:

Parameters:

A = Drift rate

y0 = Starting point

c = Drift noise (std)

z = Decision threshold

Variables:

y = Accumulated evidence

t = timestep

Drift diffusion model formalism:

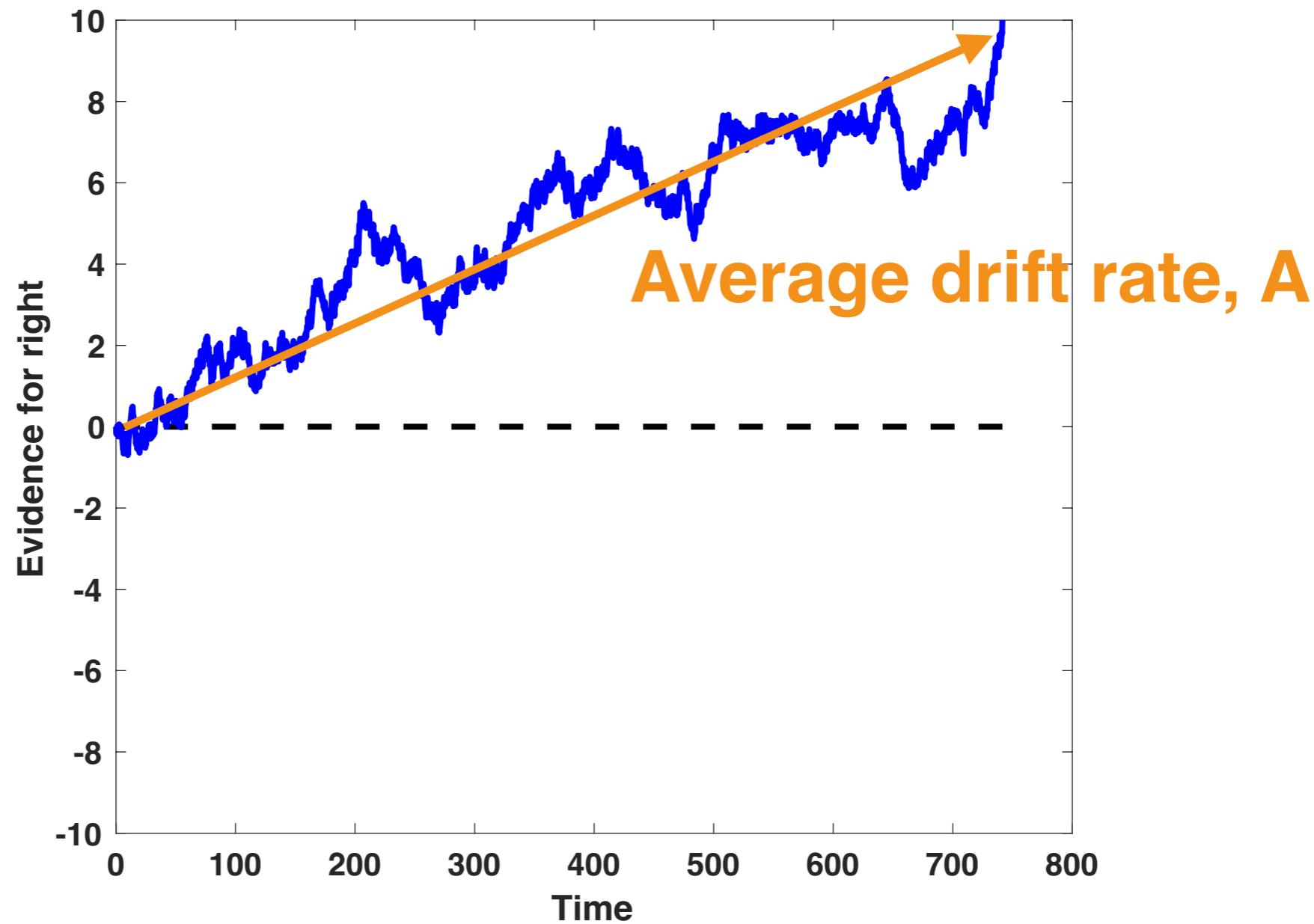
Parameters:

A = Drift rate
y0 = Starting point
c = Drift noise (std)
z = Decision threshold

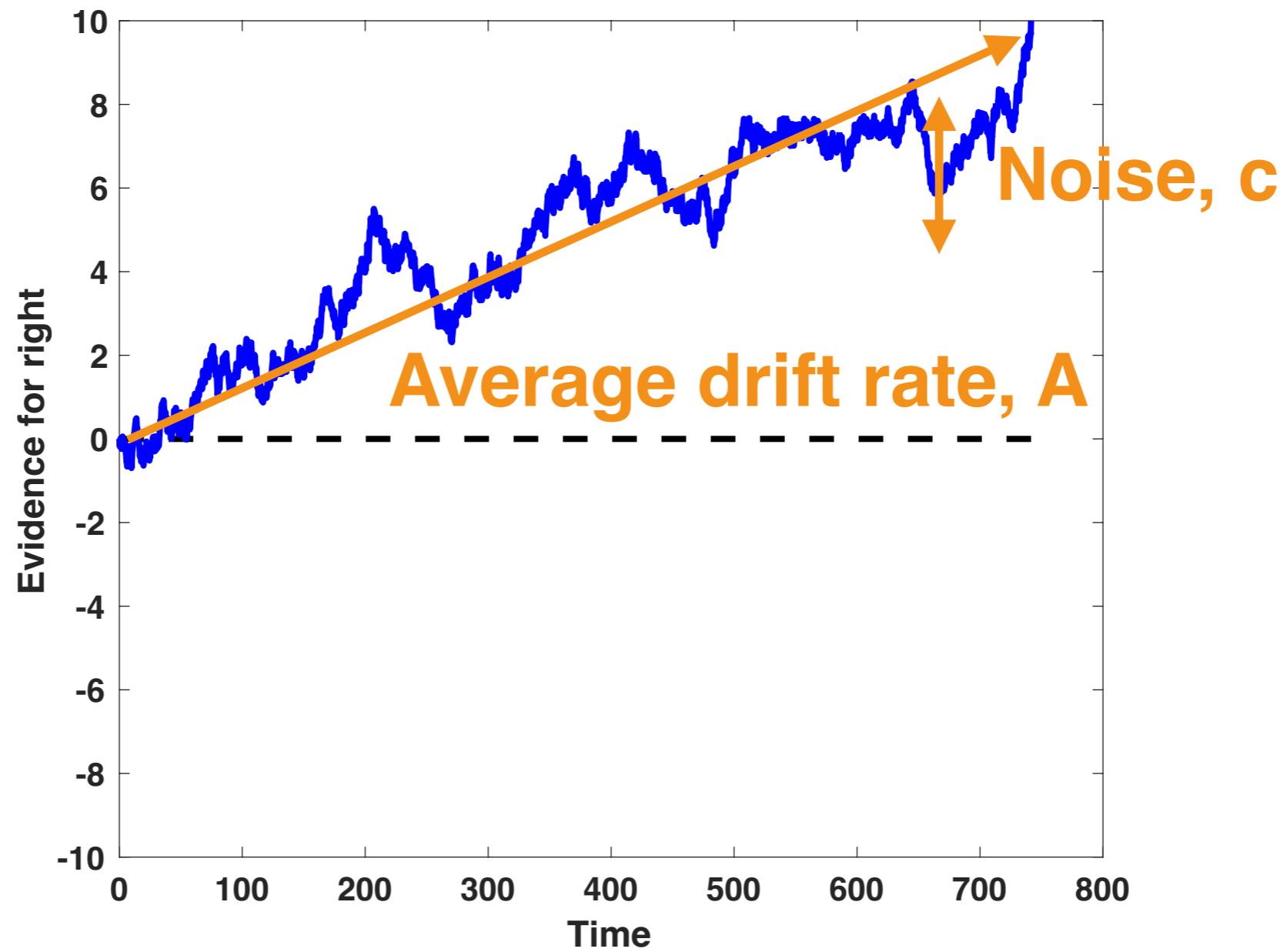
Variables:

y = Accumulated evidence
t = timestep

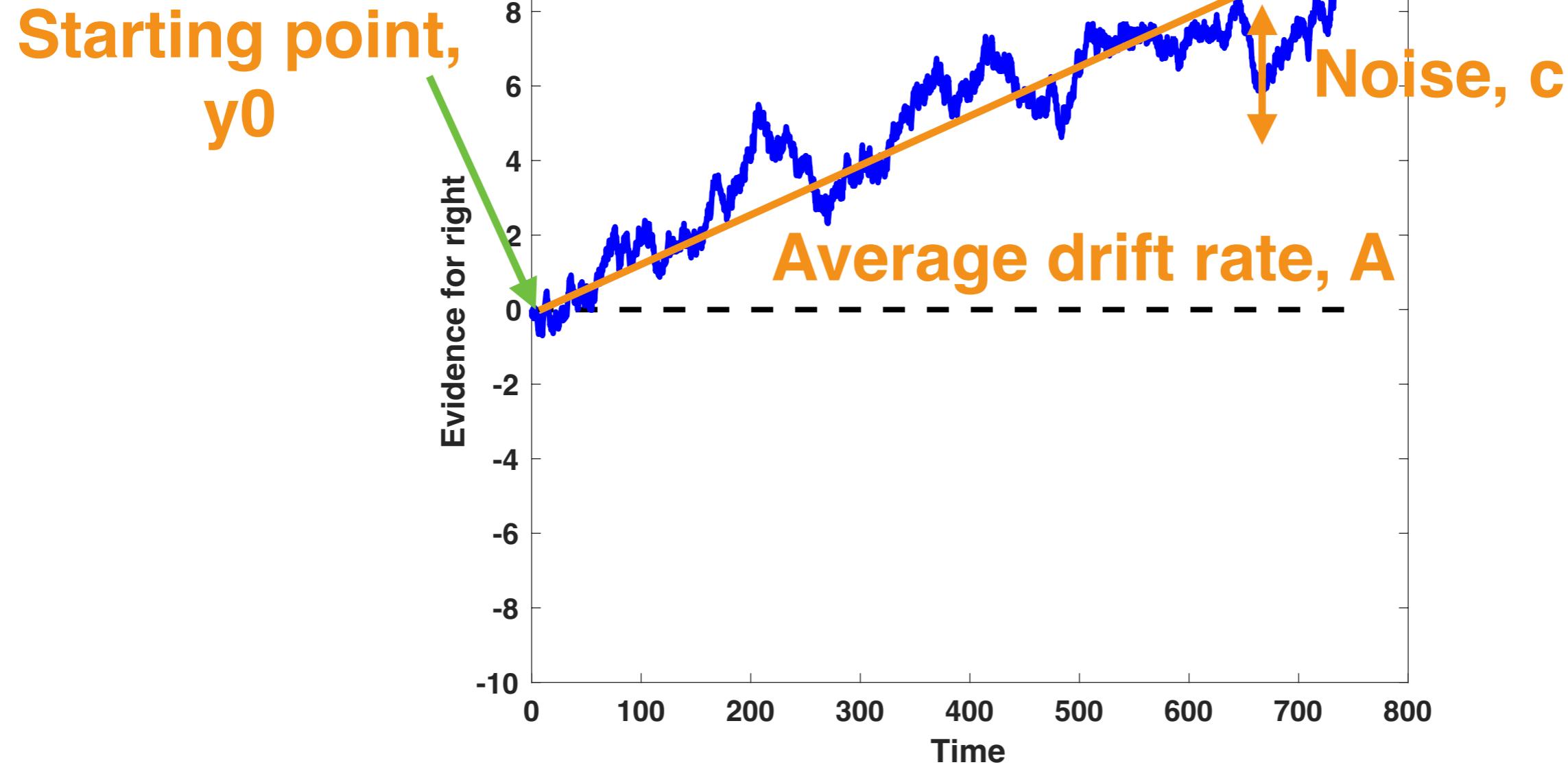
Drift diffusion model:



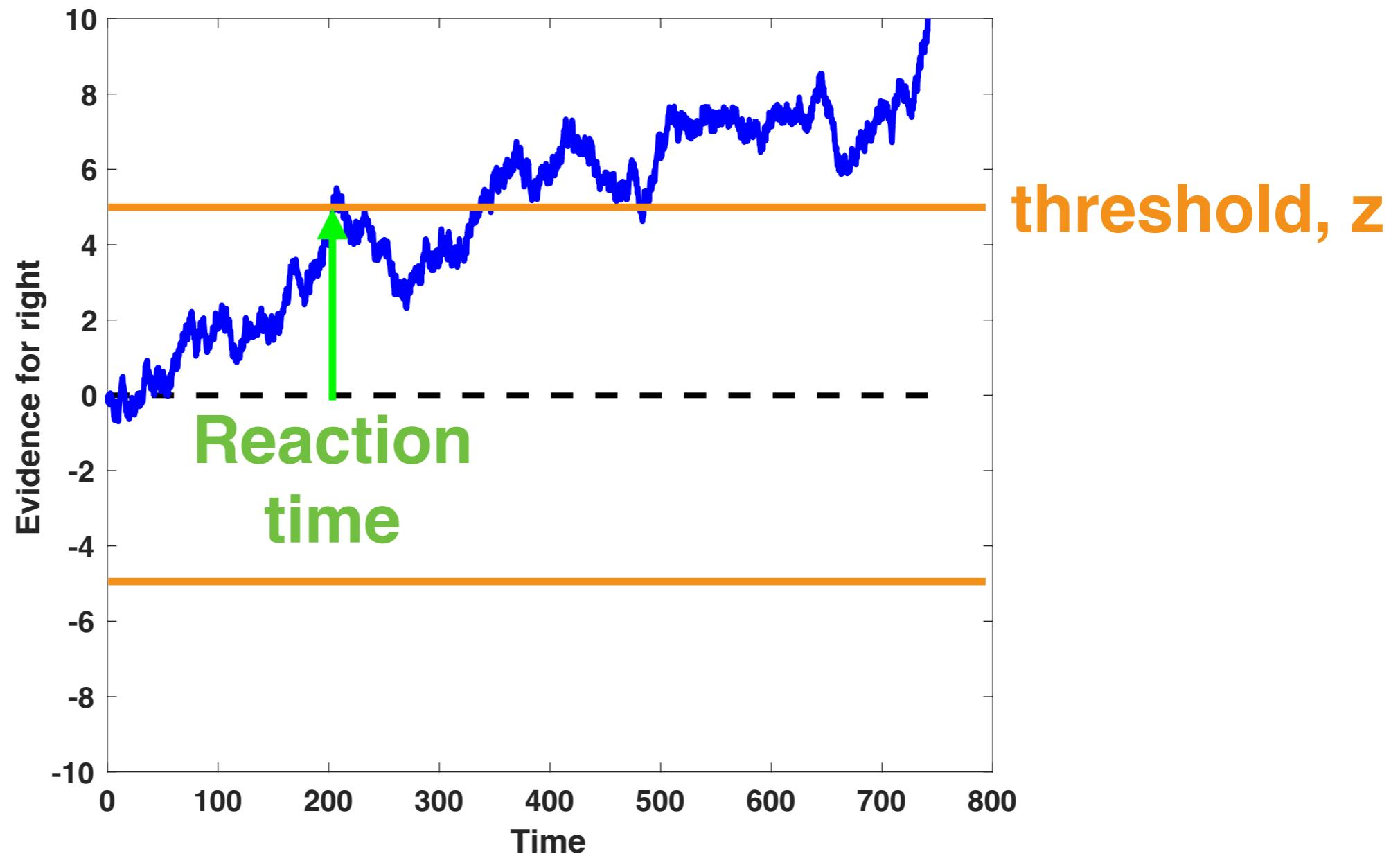
Drift diffusion model:



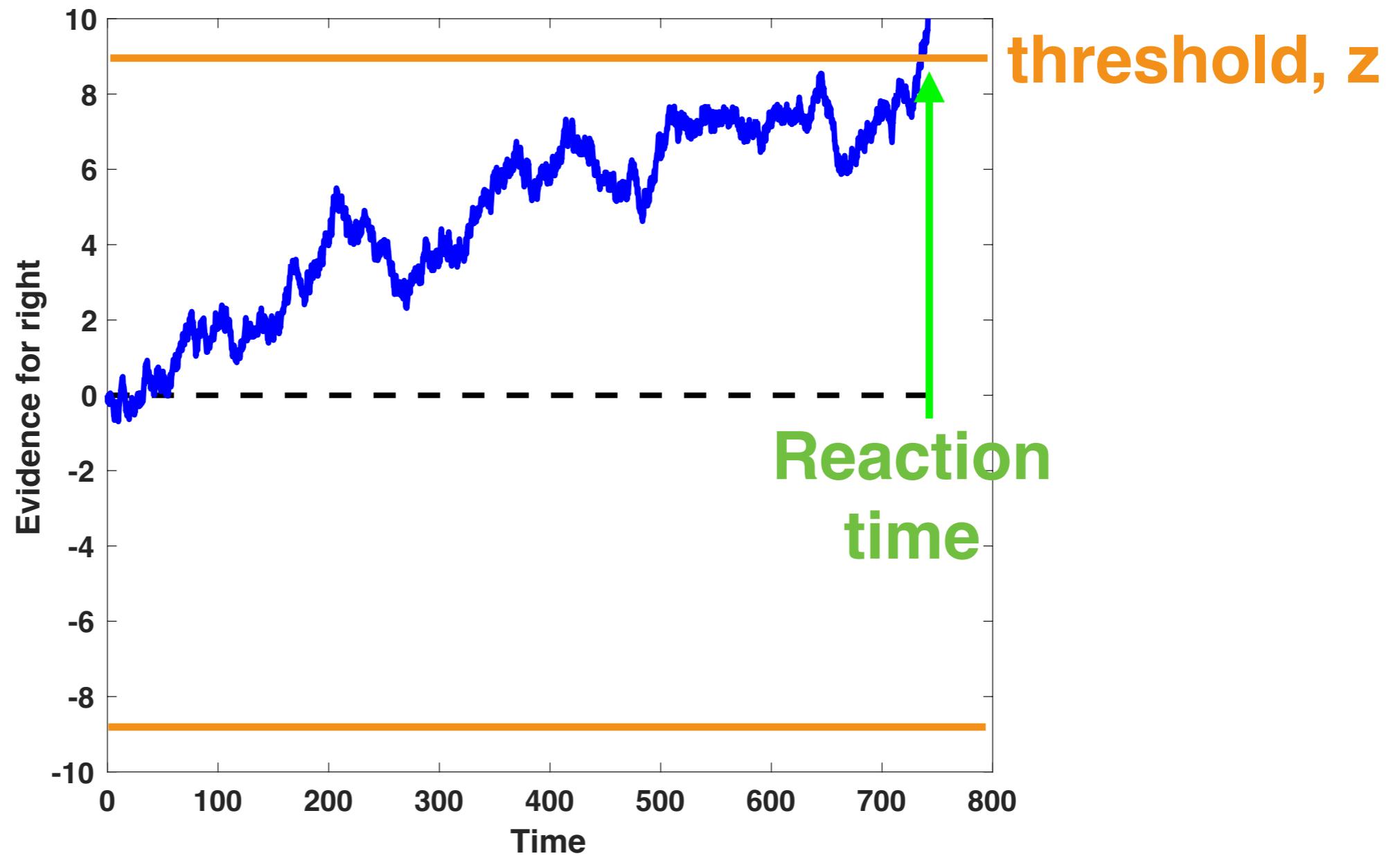
Drift diffusion model:



Drift diffusion model:



Drift diffusion model:



Drift diffusion model formalism:

Parameters:

A = Drift rate
y0 = Starting point
c = Drift noise (std)
z = Decision threshold

Variables:

y = Accumulated evidence
t = timestep

Drift diffusion model formalism:

Parameters:

A = Drift rate

y0 = Starting point

c = Drift noise (std)

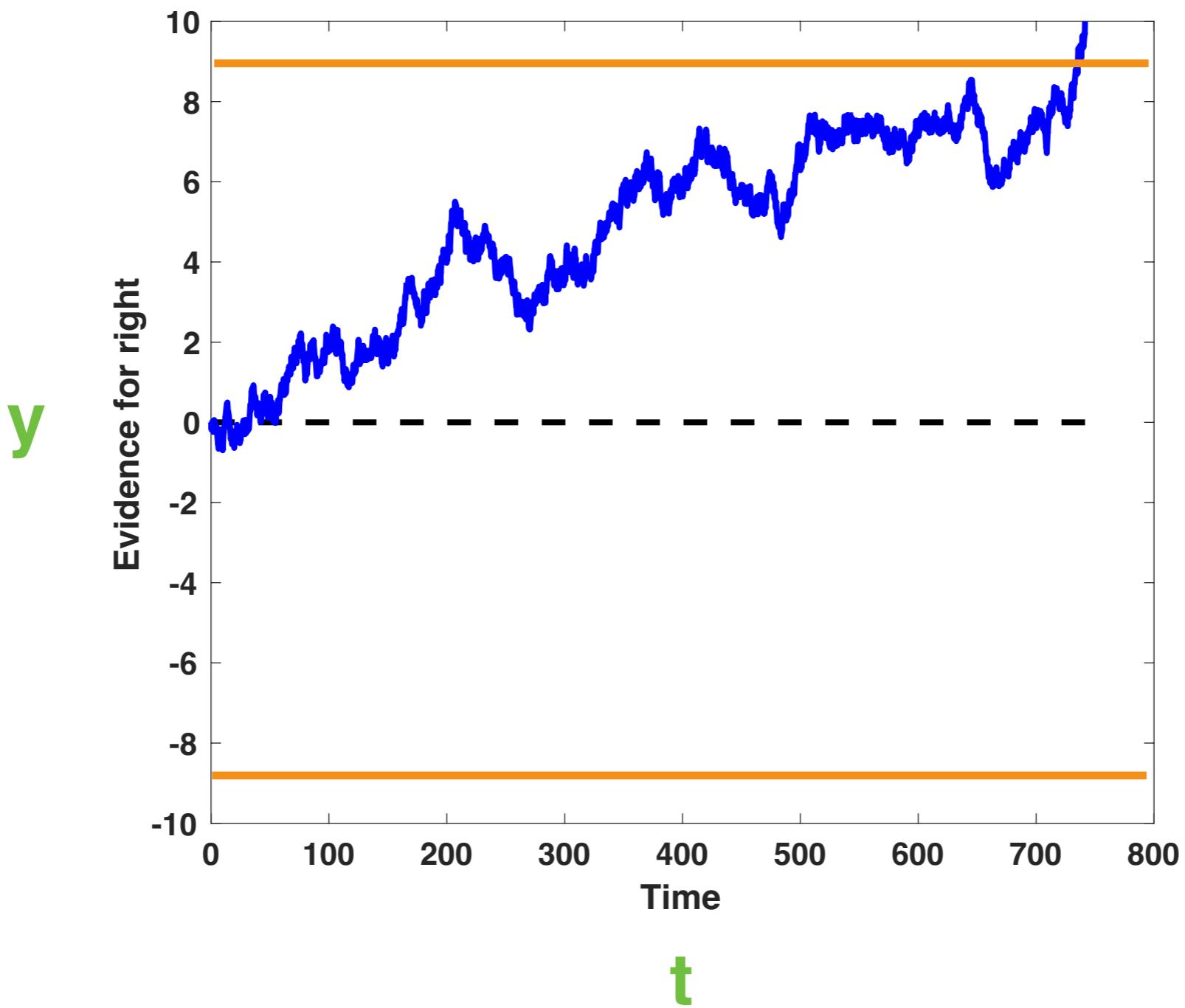
z = Decision threshold

Variables:

y = Accumulated evidence

t = timestep

Drift diffusion model:



Drift diffusion model formalism:

Parameters:

A = Drift rate

y0 = Starting point

c = Drift noise (std)

z = Decision threshold

Variables:

y = Accumulated evidence

t = timestep

Drift diffusion model formalism:

Parameters:

A = Drift rate

y0 = Starting point

c = Drift noise (std)

z = Decision threshold

Additional parameters:

Non-decision time

Start point variability

Drift rate variability

Variables:

y = Accumulated evidence

t = timestep

Simulation?

Drift diffusion for other sorts
of decisions

Which do you want?

'Which do you want?'



Which do you want?

'Which do you want?'



'Which do you want?'



Which do you want?

'Which do you want?'



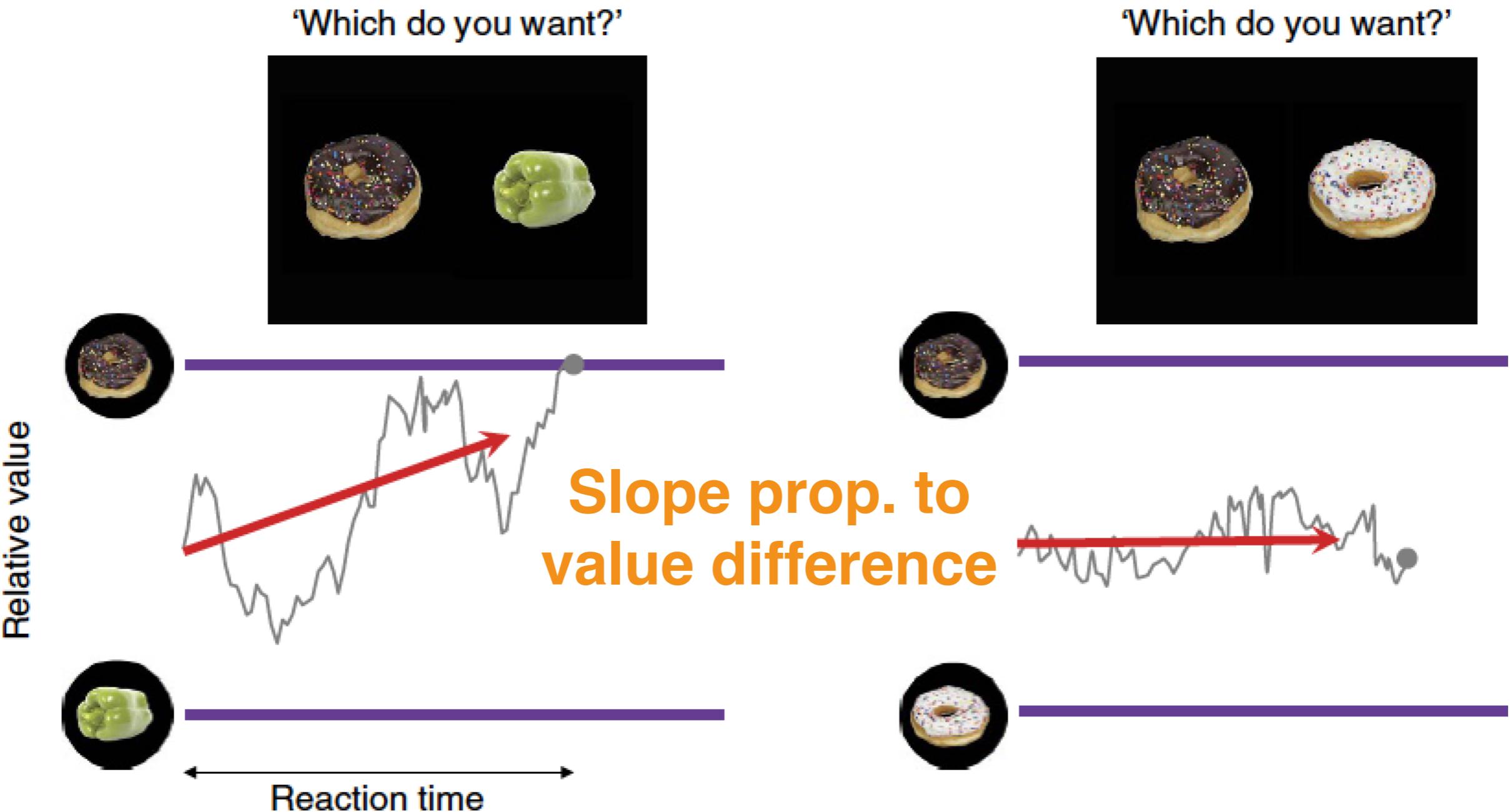
'Which do you want?'



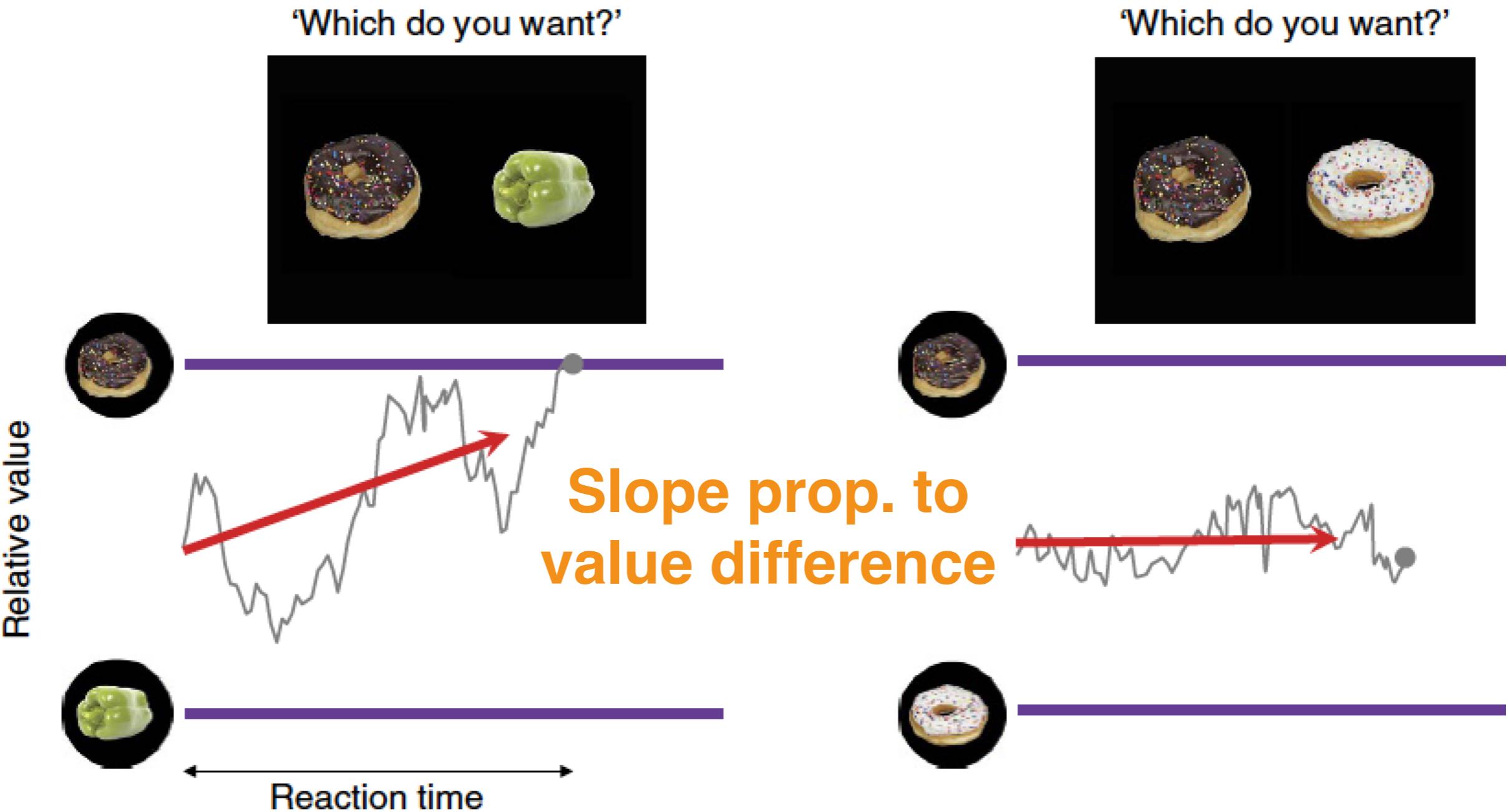
Large
value difference

Small
value difference

Which do you want?



Which do you want?



Fits choice & RT data!

Tajima 2019

Which do you want?

'Which do you want?'



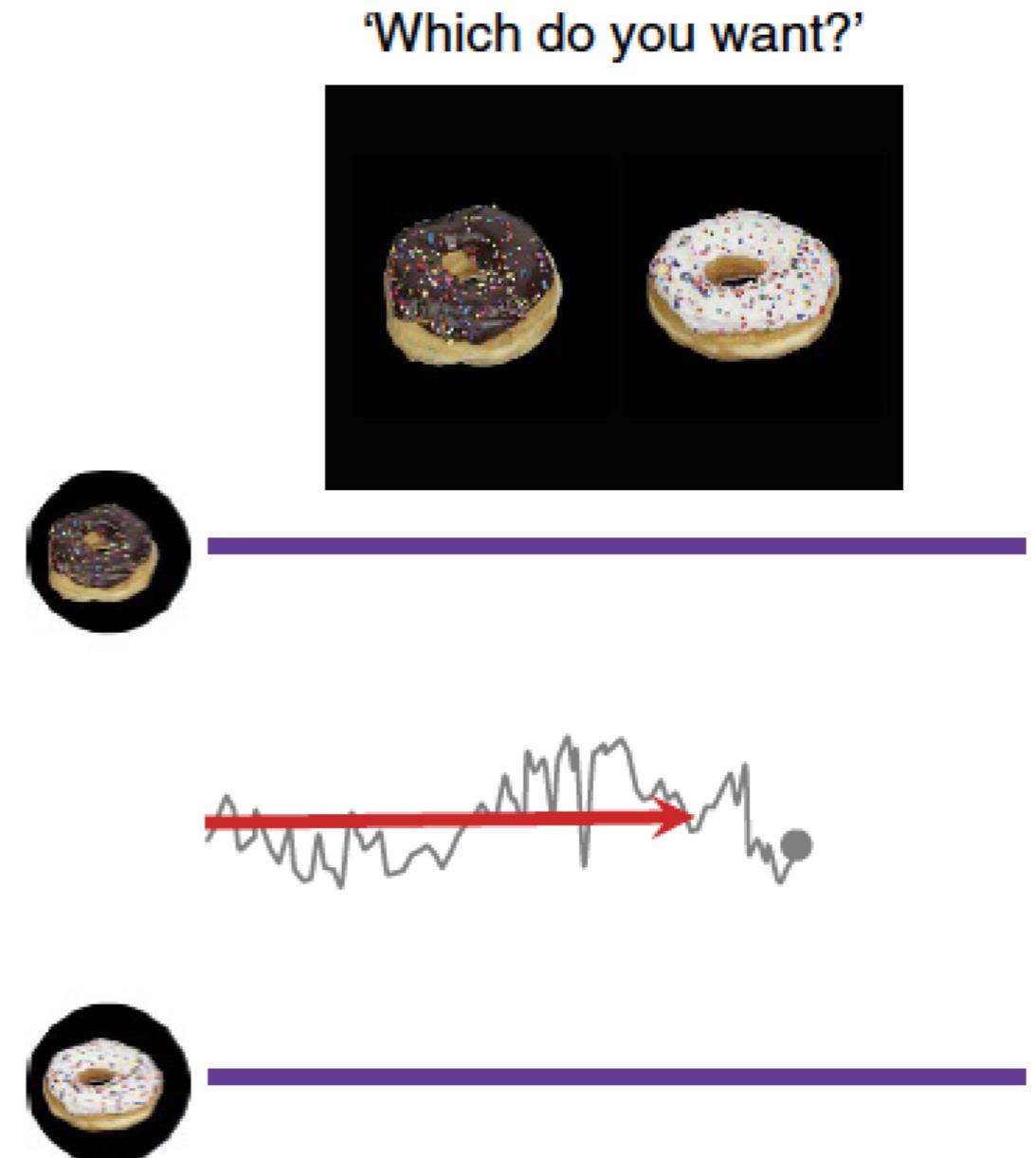
Decision paralysis?



Which do you want?



**Buridan's Ass
dies of hunger and thirst?**



Which do you want?

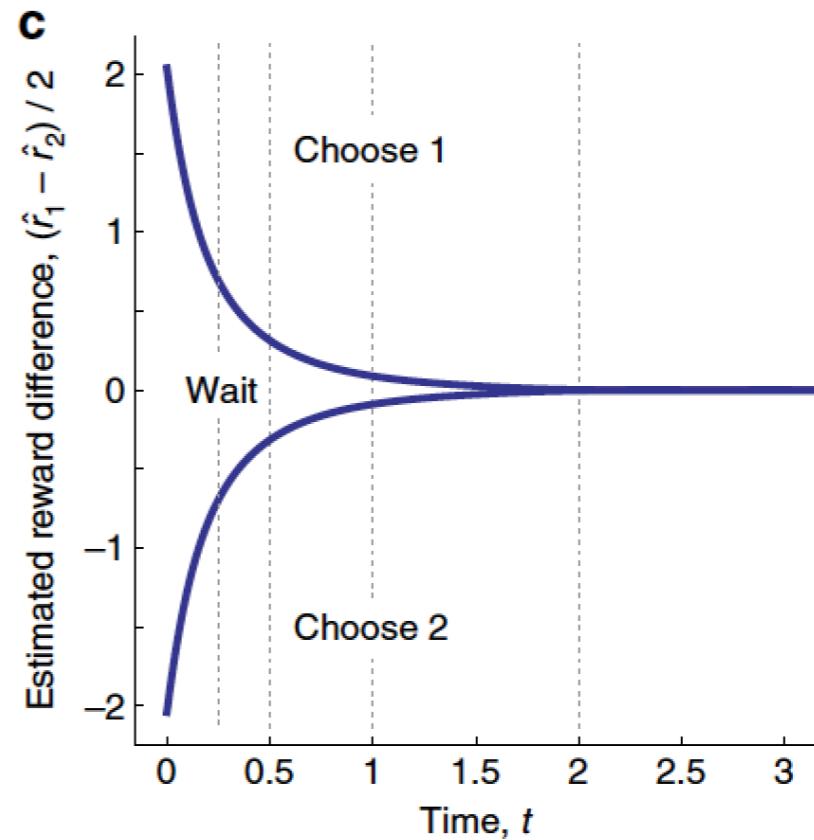


valdas.blog

**Buridan's Ass
dies of hunger and thirst?**

Probably not...

**Collapsing decision bound
to minimize time wasted
“accumulating” nothing**



But... why would the brain need
sequential samples in a value based
decision making task?????

But... why would the brain need
sequential samples in a value based
decision making task?????

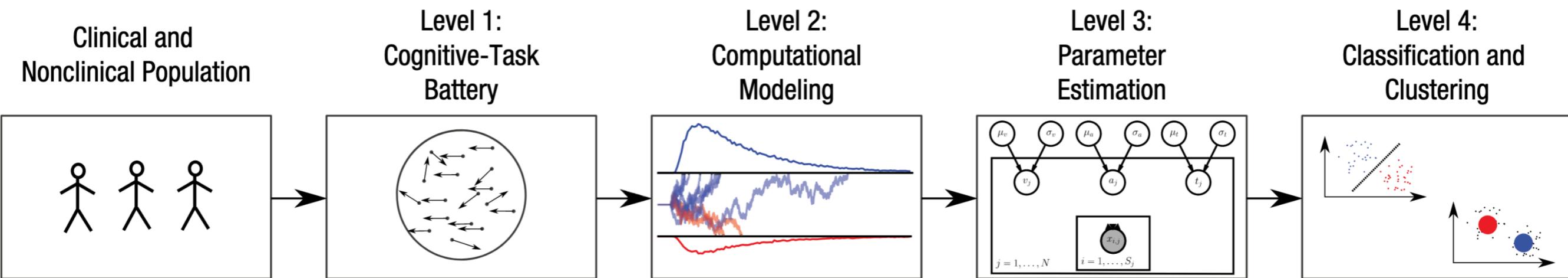
Sampling through attention (attentional DDM)?

Sampling from memory?

Open question...

DDM and computational psychiatry

DDM and computational psychiatry



How do we know whether decisions
are from a drift diffusion process?

How do we know whether decisions are from a drift diffusion process?

Unfalsifiability and mutual translatability of major modeling schemes for choice reaction time.

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[Jones, Matt](#) [Dzhafarov, Ehtibar N.](#)

Citation

Jones, M., & Dzhafarov, E. N. (2014). Unfalsifiability and mutual translatability of major modeling schemes for choice reaction time. *Psychological Review*, 121(1), 1–32. <https://doi.org/10.1037/a0034190>

Psychological Review

Journal TOC

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Abstract

[Correction Notice: An Erratum for this article was reported in Vol 121(1) of *Psychological Review* (see record [2014-03591-005](#)). The link to supplemental material was missing. All versions of this article have been corrected.] Much current research on speeded choice utilizes models in which the response is triggered by a stochastic process crossing a deterministic threshold. This article focuses on 2 such model classes, 1 based on continuous-time diffusion and the other on linear ballistic accumulation (LBA). Both models assume random variability in growth rates and in other model components across trials. We show that if the form of this variability is unconstrained, the models can exactly match any possible pattern of response probabilities and response time distributions. Thus, the explanatory or predictive content of these models is determined not by their structural assumptions but, rather, by distributional assumptions (e.g., Gaussian distributions) that are traditionally regarded as implementation details.

Related Content

"Unfalsifiability and mutual translatability of major modeling schemes for choice reaction time": Correction to Jones and Dzhafarov (2013). No authorship indicated, 2014

Can a two-state model account for

How do we know whether decisions
are from a drift diffusion process?

Behavior may not be sufficient...

How do we know whether decisions are from a drift diffusion process?

Behavior may not be sufficient...

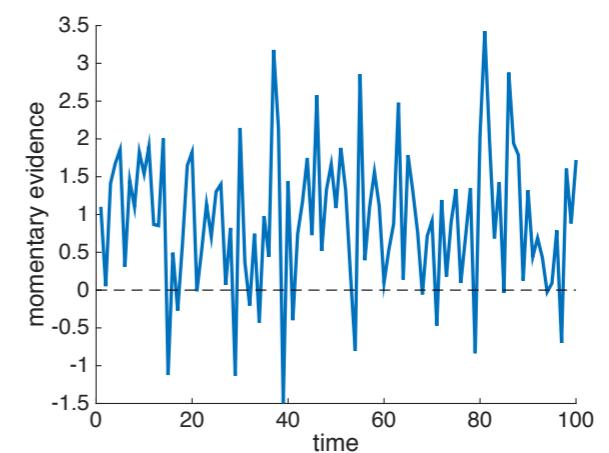


**“All models are wrong,
But some are useful”**

Looking for drift diffusion in
the brain

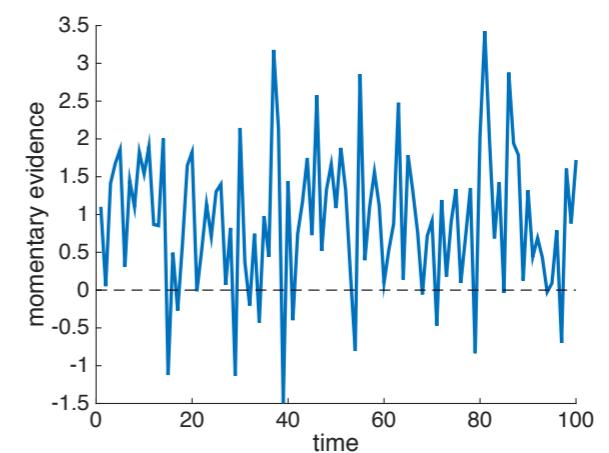
Drift diffusion in the brain

Step 1: compute momentary evidence

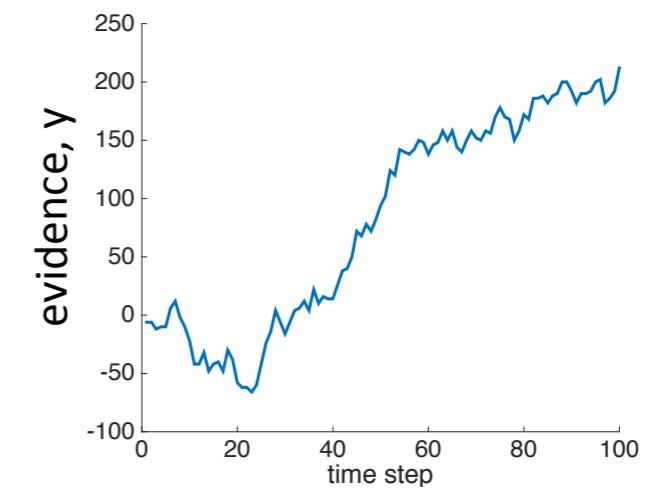


Drift diffusion in the brain

Step 1: compute momentary evidence

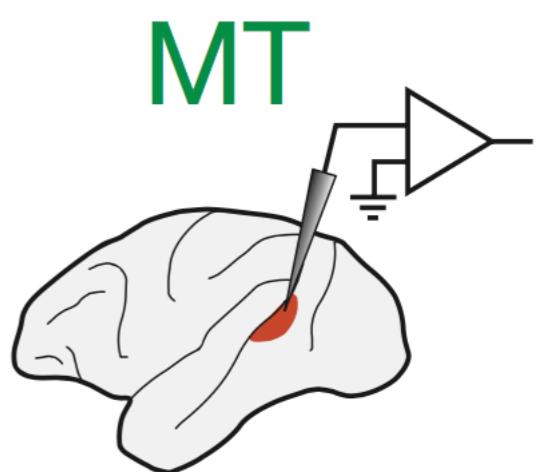


Step 2: integrate evidence over time
to make a decision

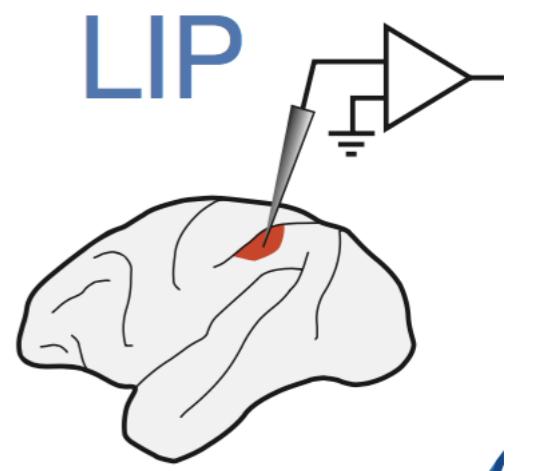


Drift diffusion in the brain

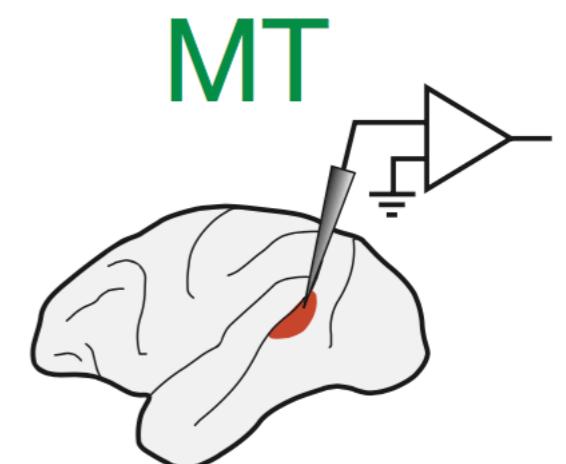
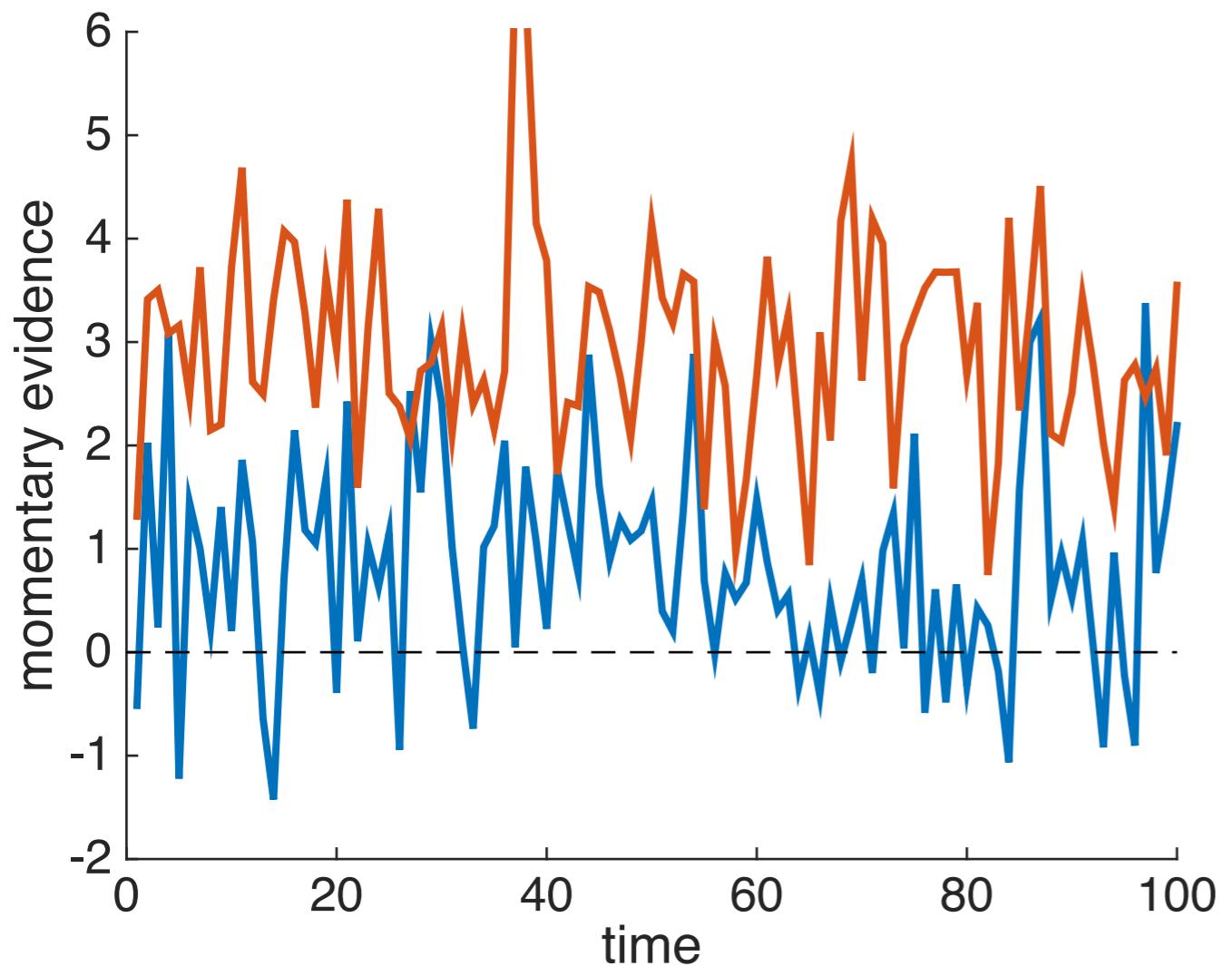
Step 1: compute momentary evidence



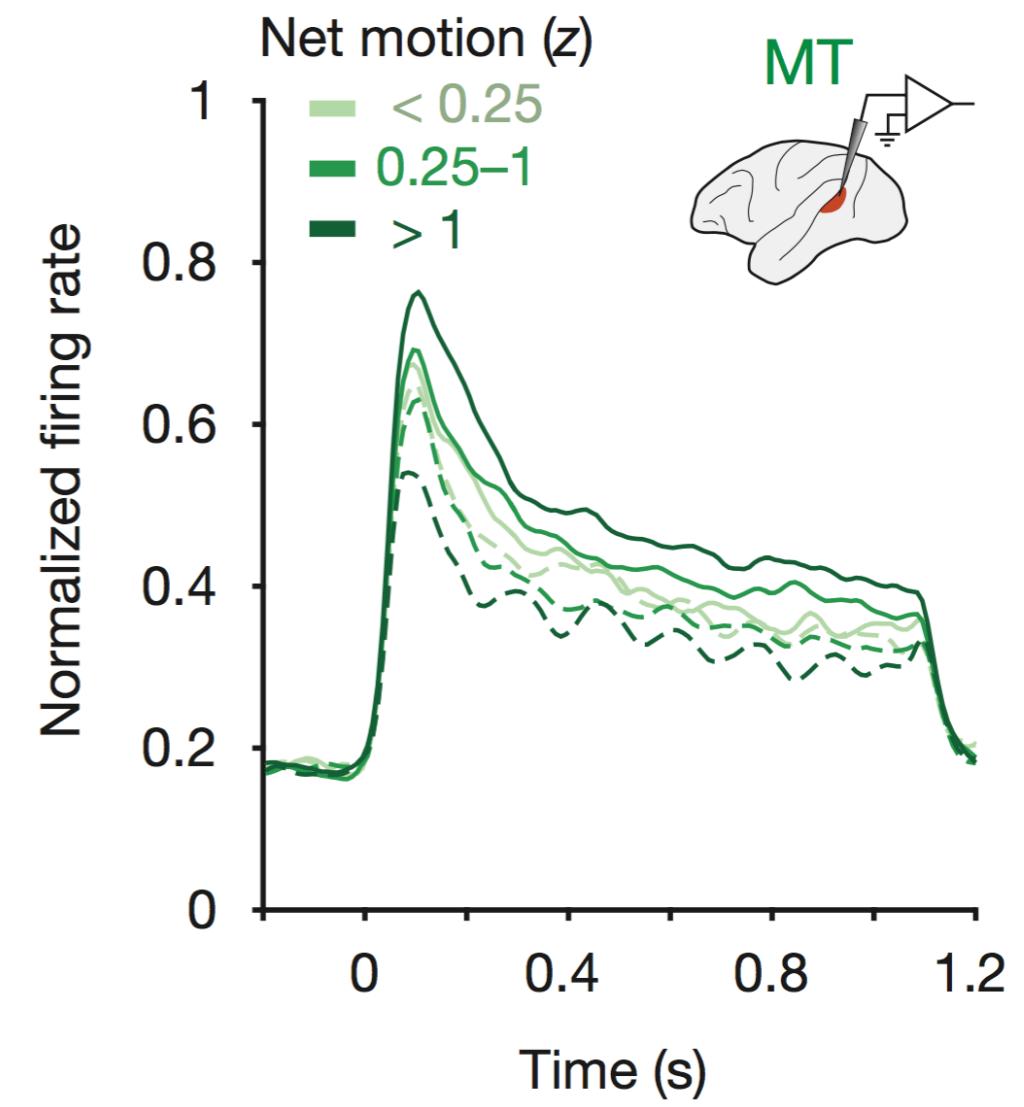
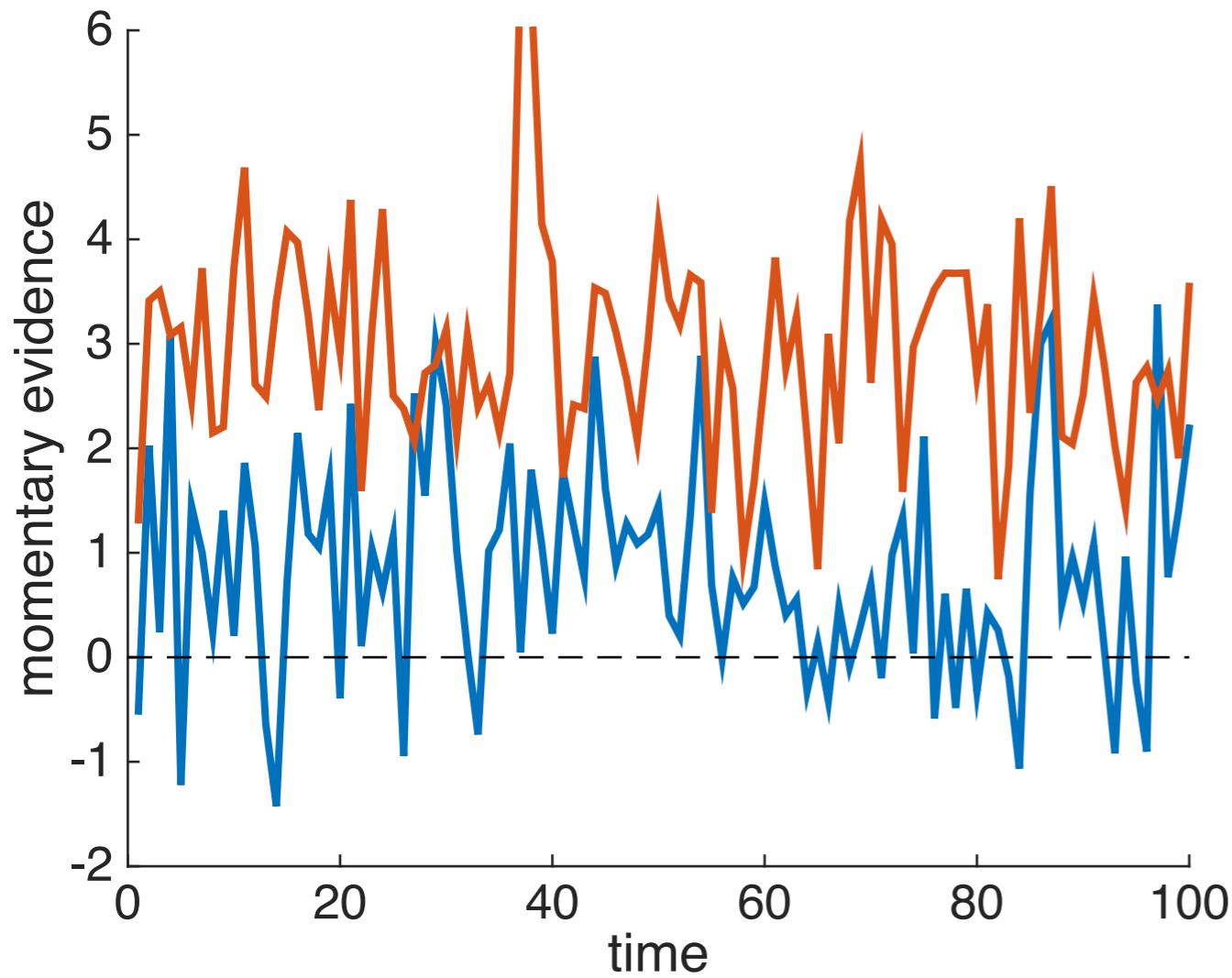
Step 2: integrate evidence over time
to make a decision



MT: momentary motion evidence



MT: momentary motion evidence



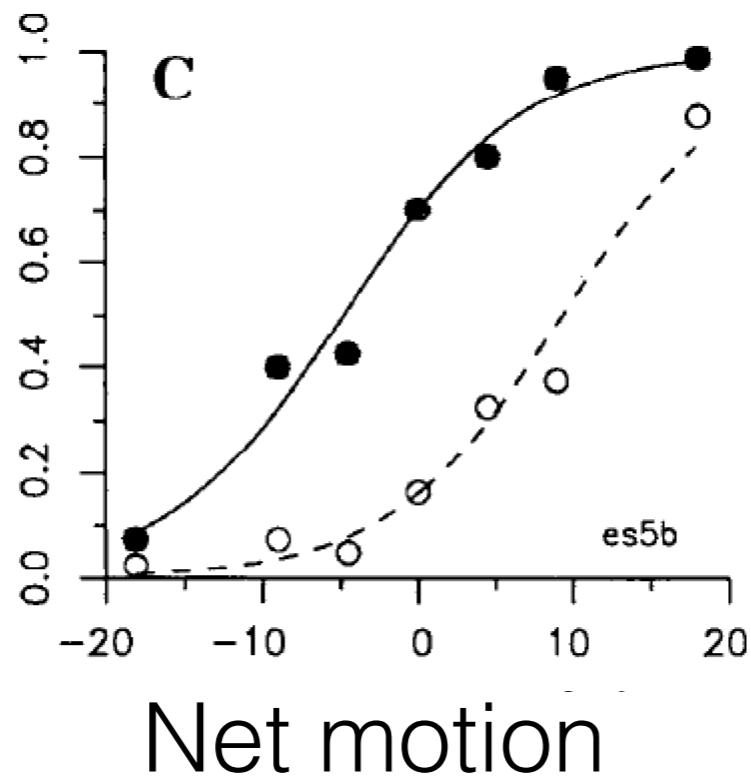
MT: momentary motion evidence

Is activity in MT *sufficient* to drive choice?

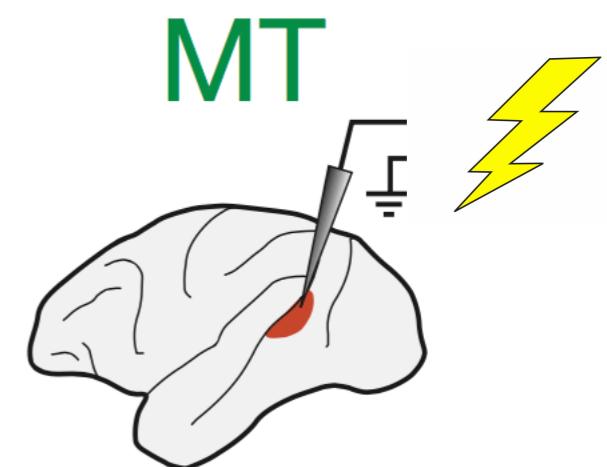
MT: momentary motion evidence

Is activity in MT *sufficient* to drive choice?

Proportion
choices
“preferred”
by MT
neuron



YES!!!

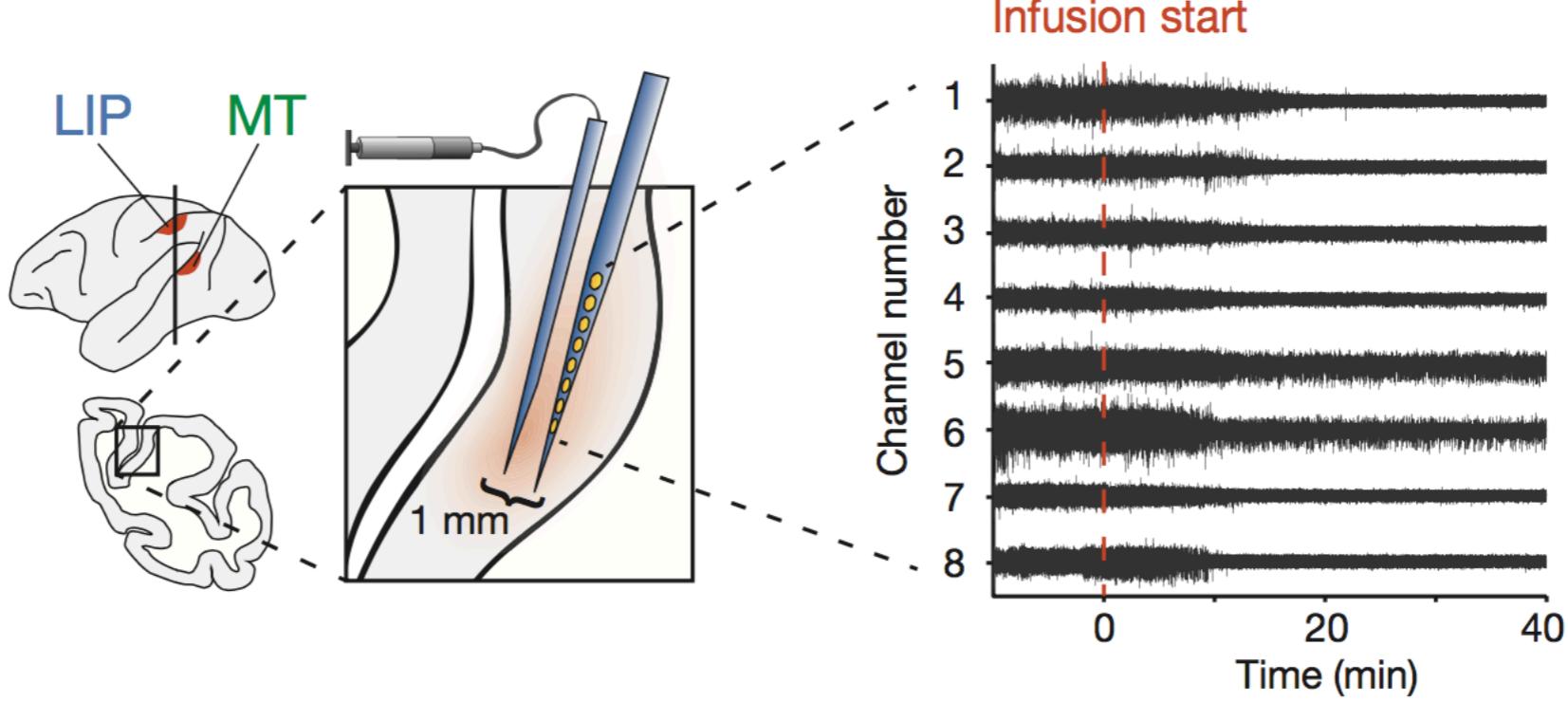


Salzman, 1992

MT: momentary motion evidence

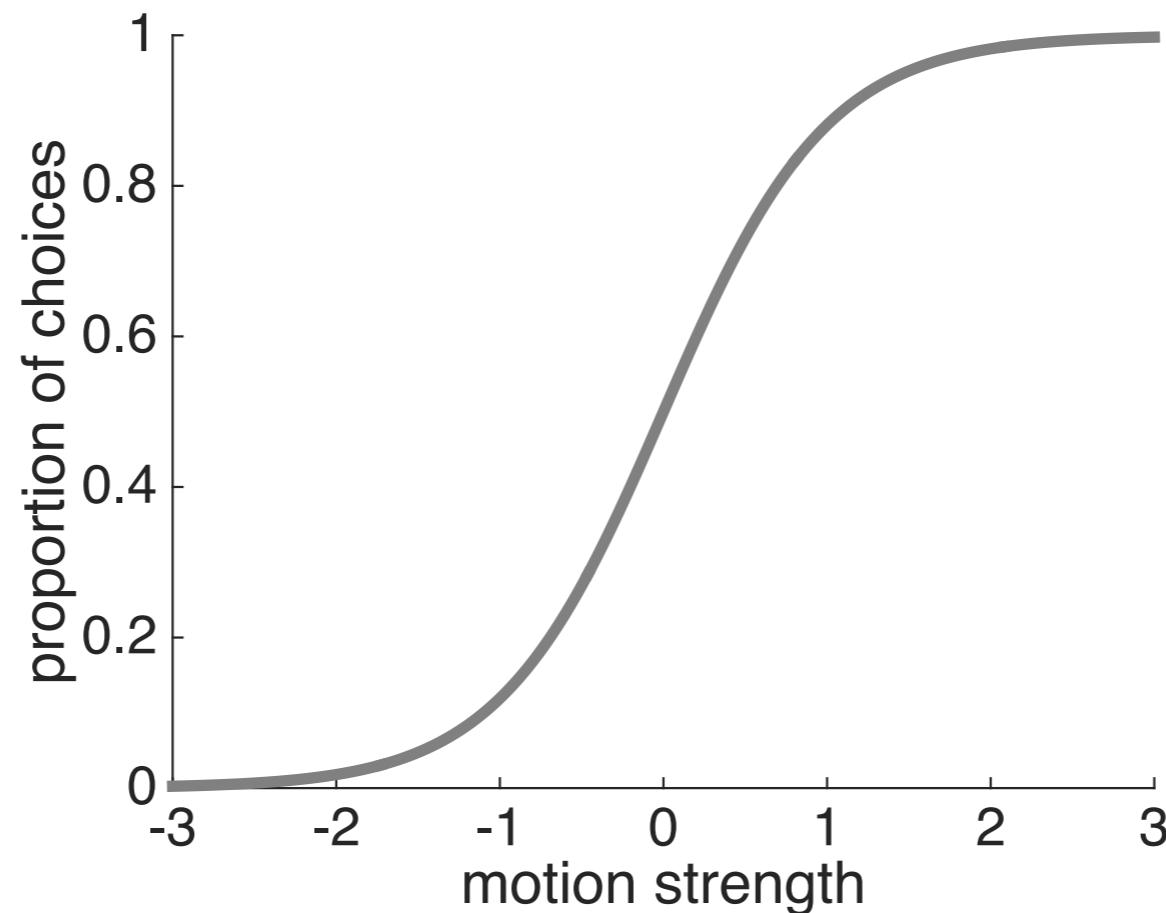
Is activity in MT *necessary* to drive choice?

b



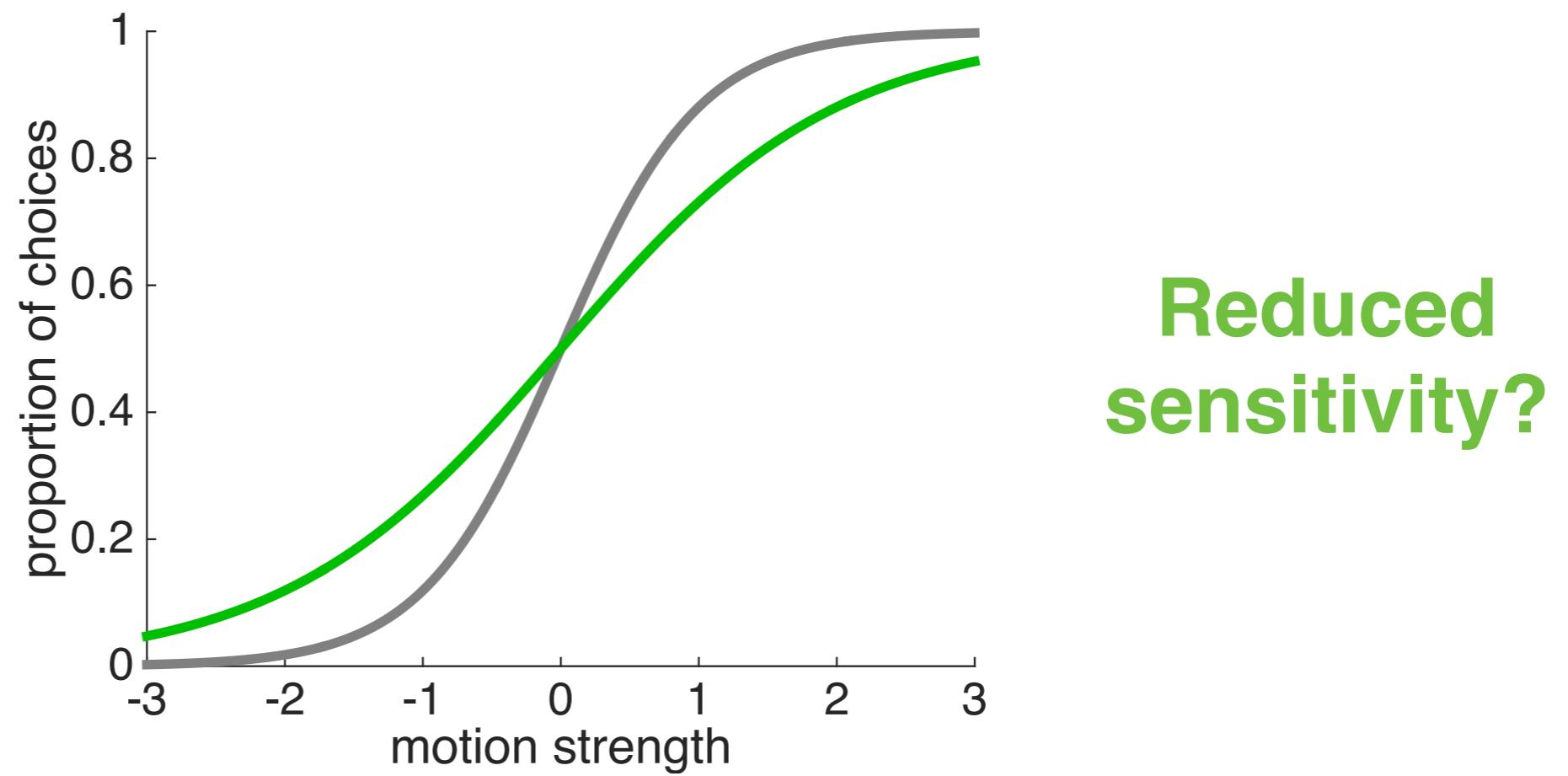
MT: momentary motion evidence

Is activity in MT *necessary* to drive choice?



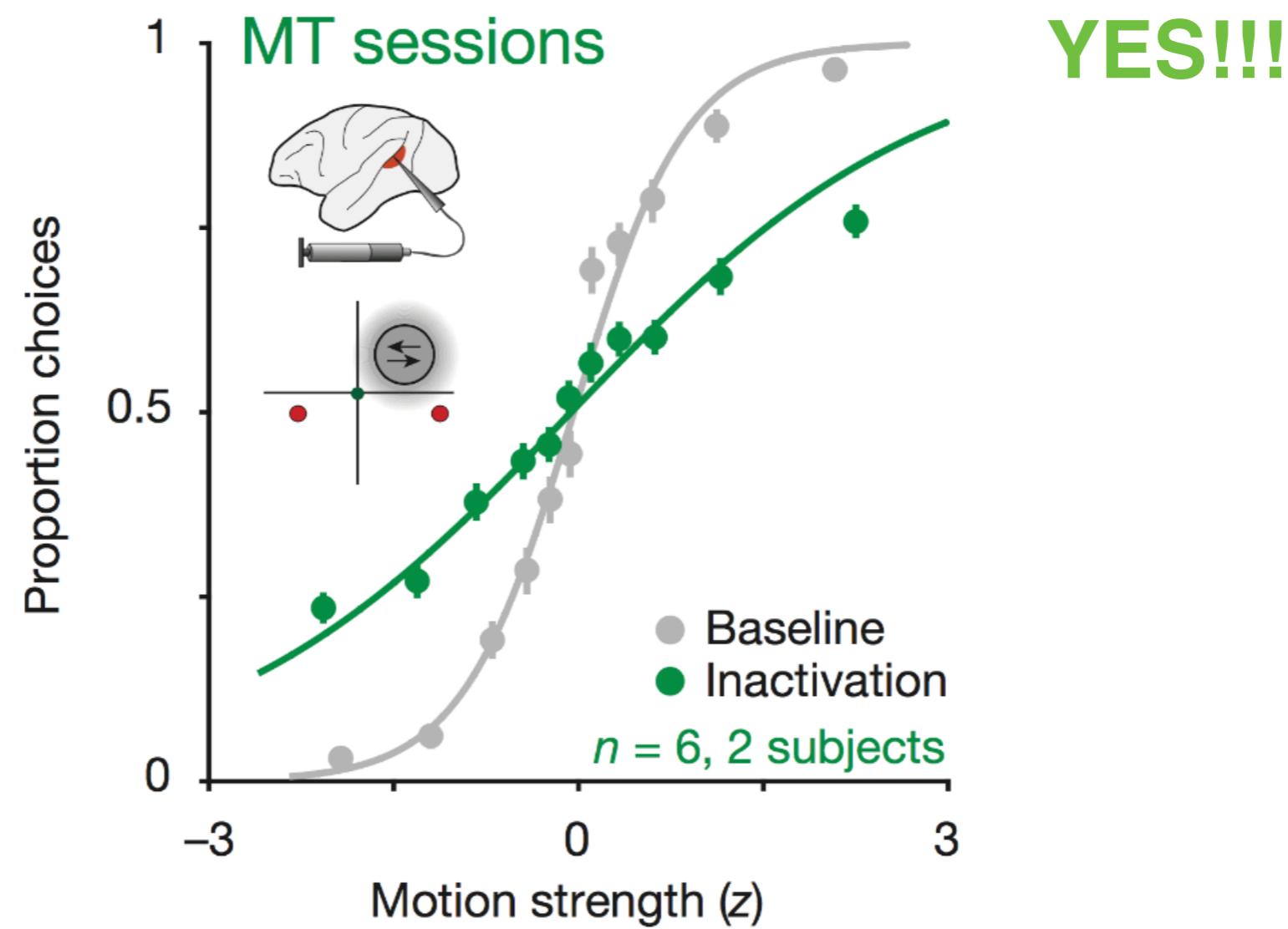
MT: momentary motion evidence

Is activity in MT *necessary* to drive choice?

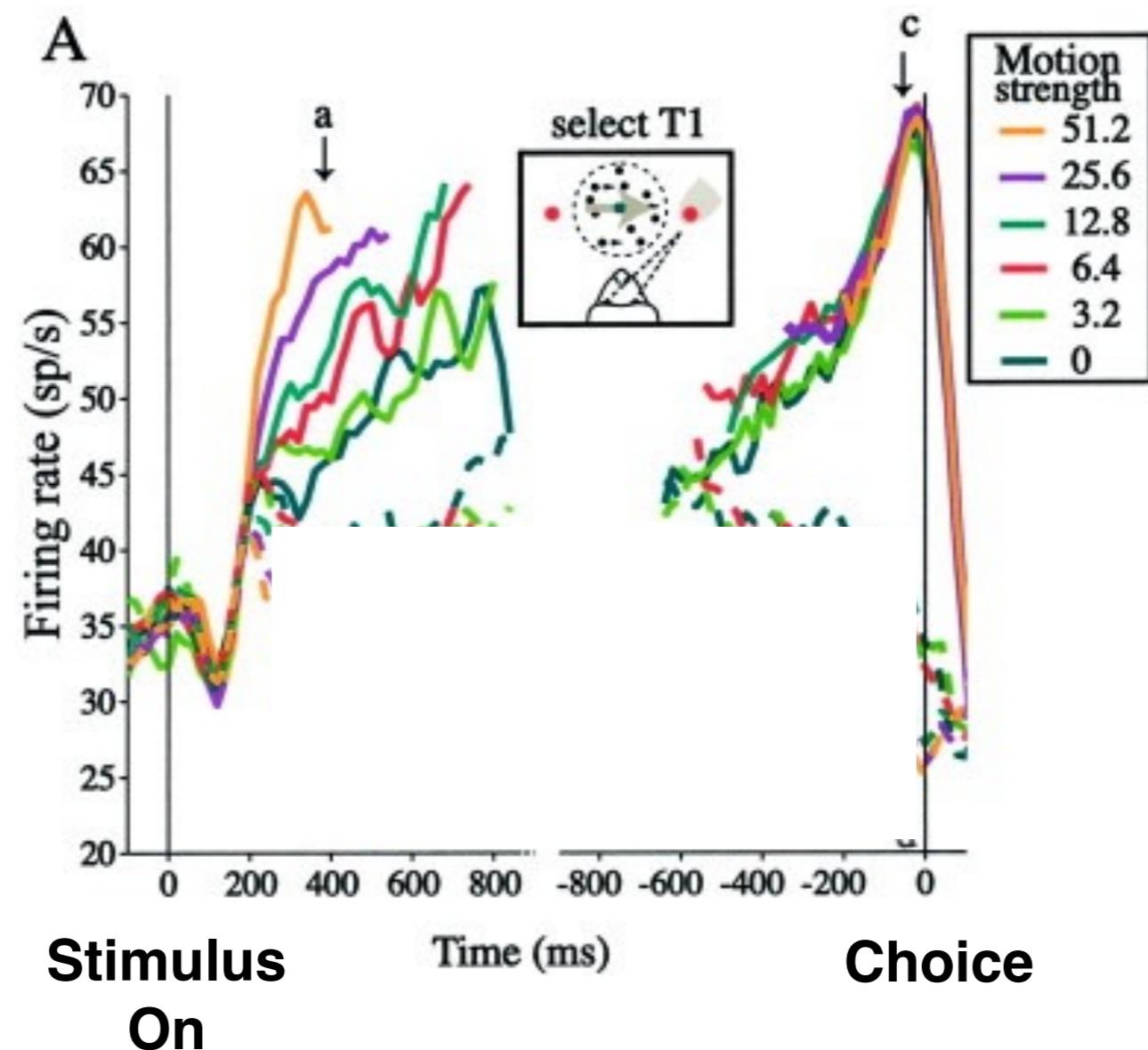


MT: momentary motion evidence

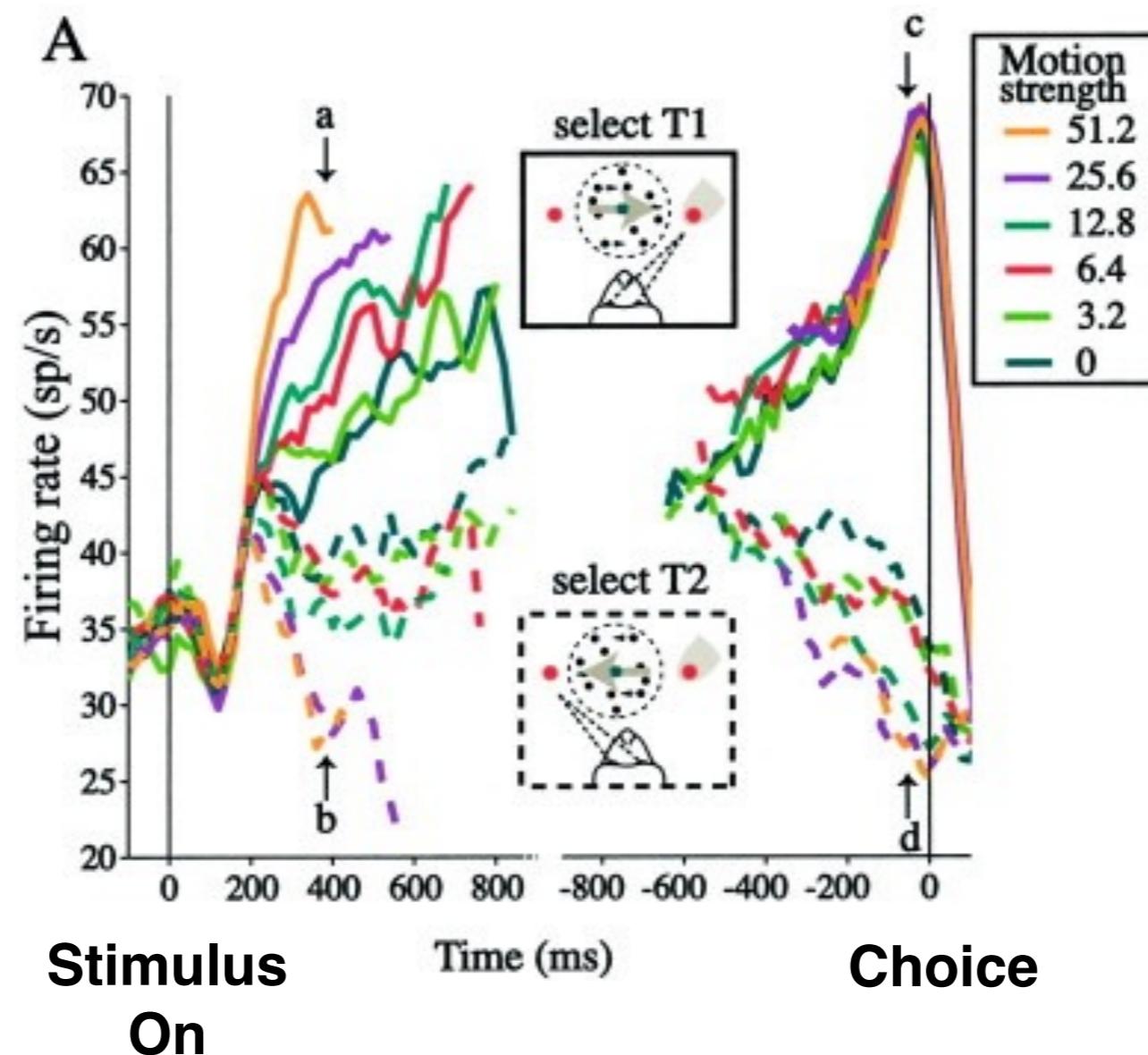
Is activity in MT *necessary* to drive choice?



LIP: Accumulated evidence



LIP: Accumulated evidence



LIP: Accumulated evidence

Computational

Algorithmic

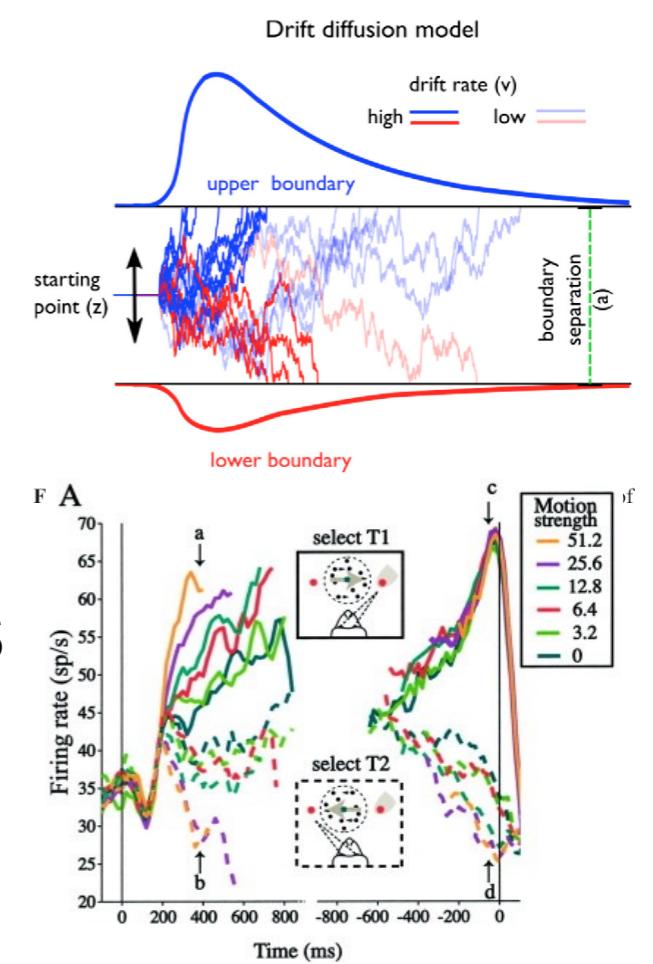
Implementation

Evidence accumulation

Drift diffusion to bound

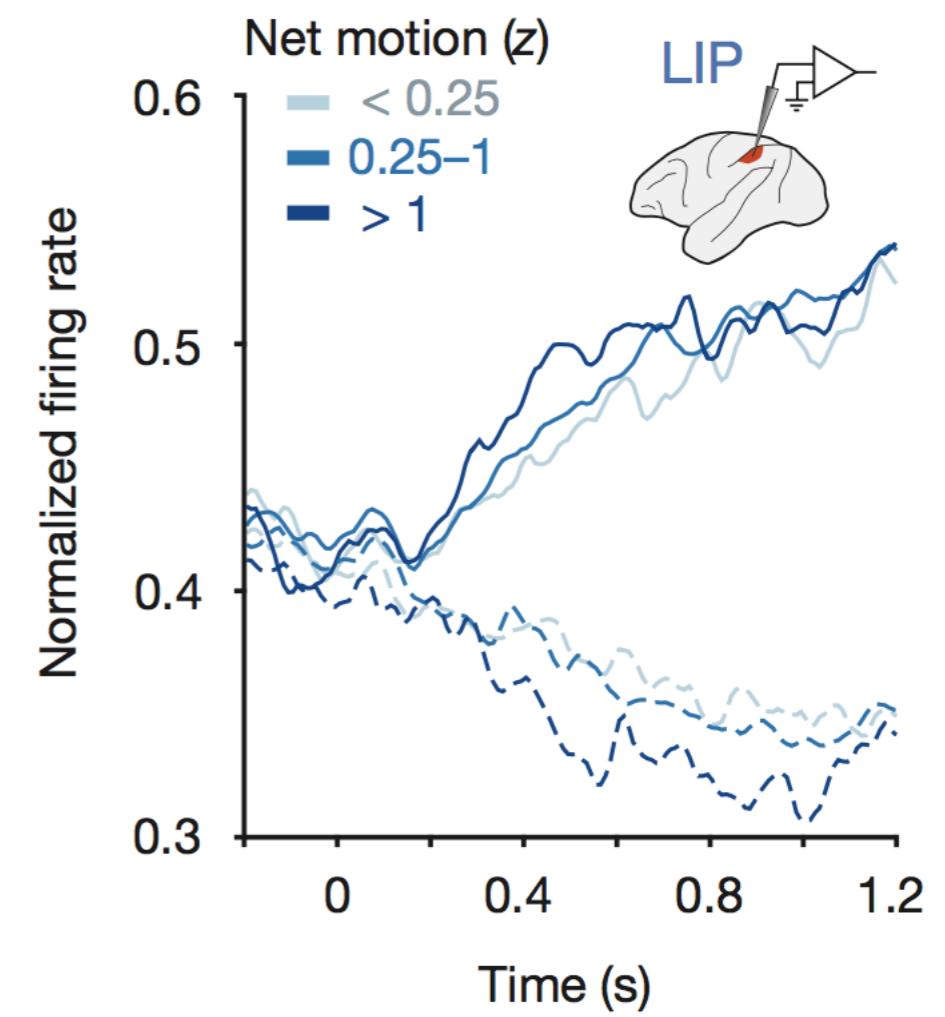
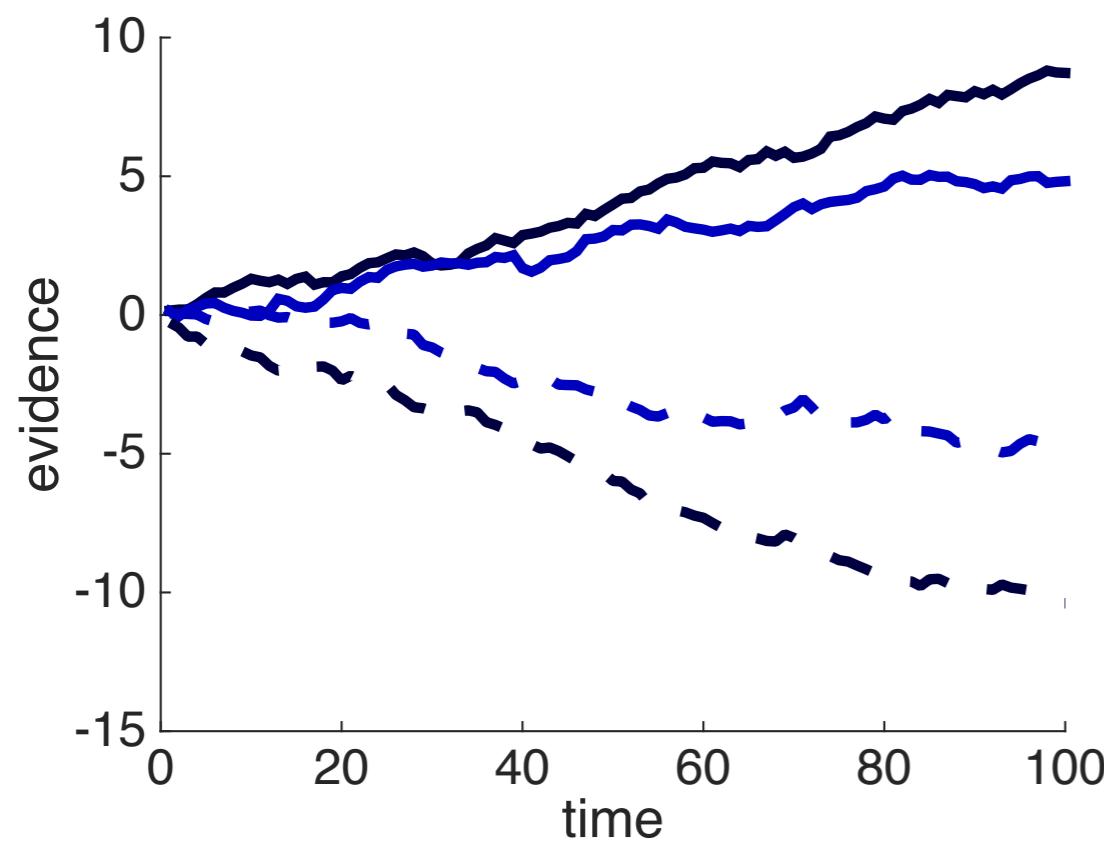
Neural responses in LIP/FEF

$$\log \left[\frac{\Pr(m|h_1)}{\Pr(m|h_0)} \right]$$



LIP: Accumulated evidence

LIP: Accumulated evidence

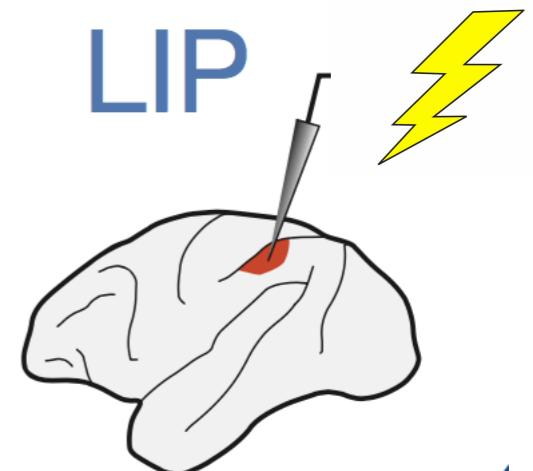
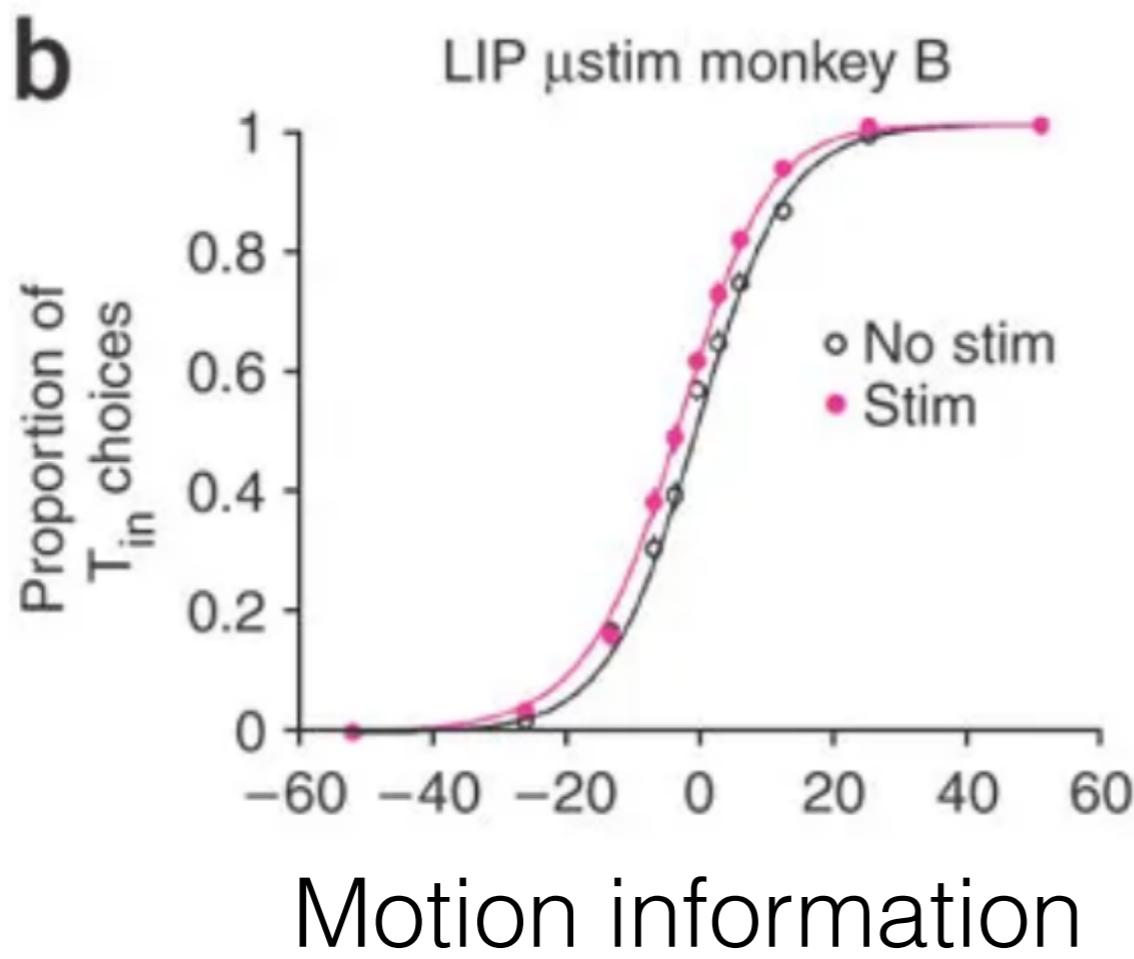


LIP: Accumulated evidence

Is LIP firing *sufficient* to influence evidence accumulation?

YES

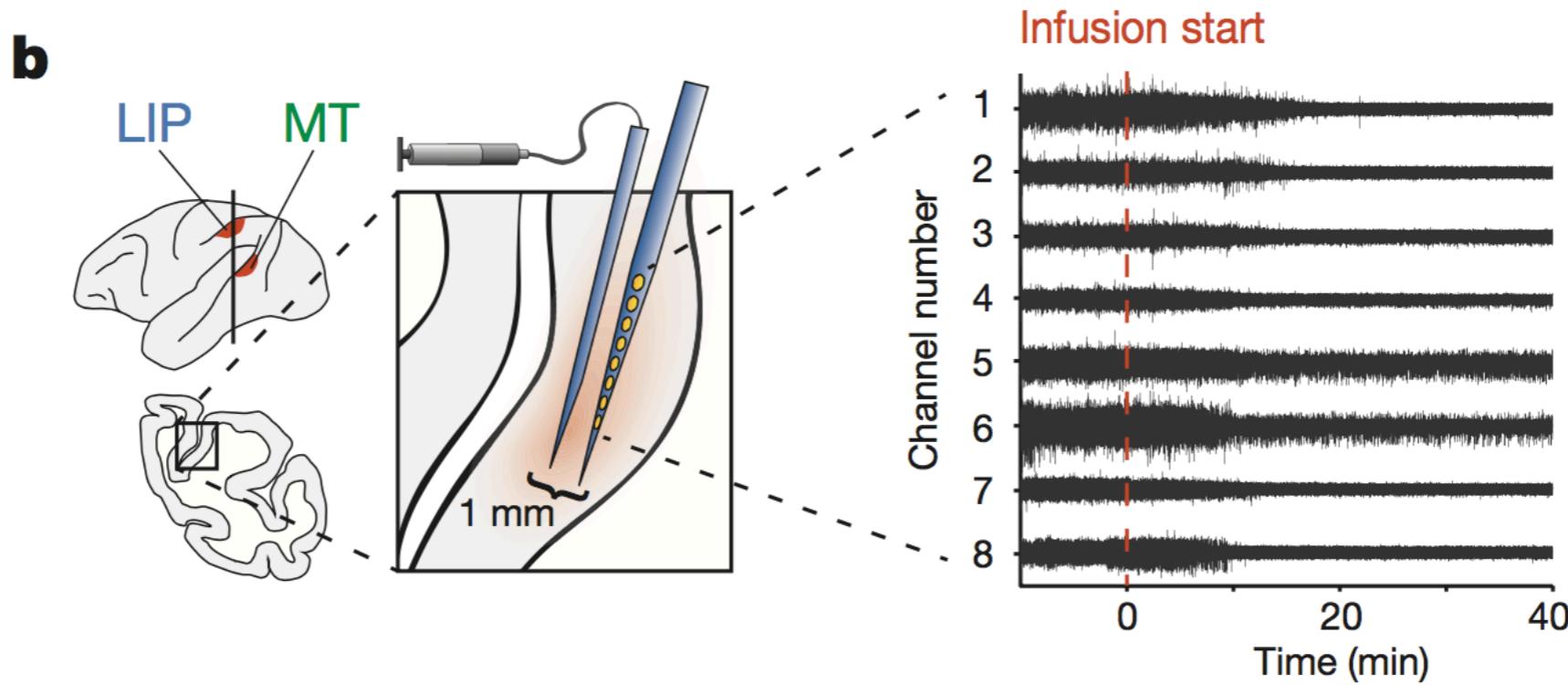
(but less impressively)



Hanks, 2006

LIP: Accumulated evidence

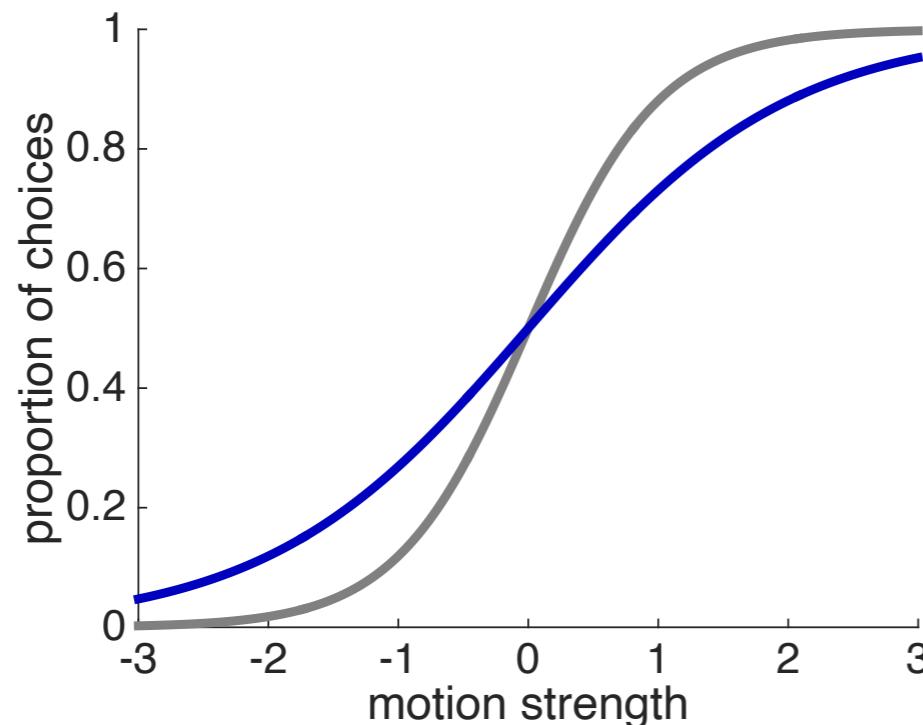
Is LIP firing *necessary* to influence evidence accumulation?



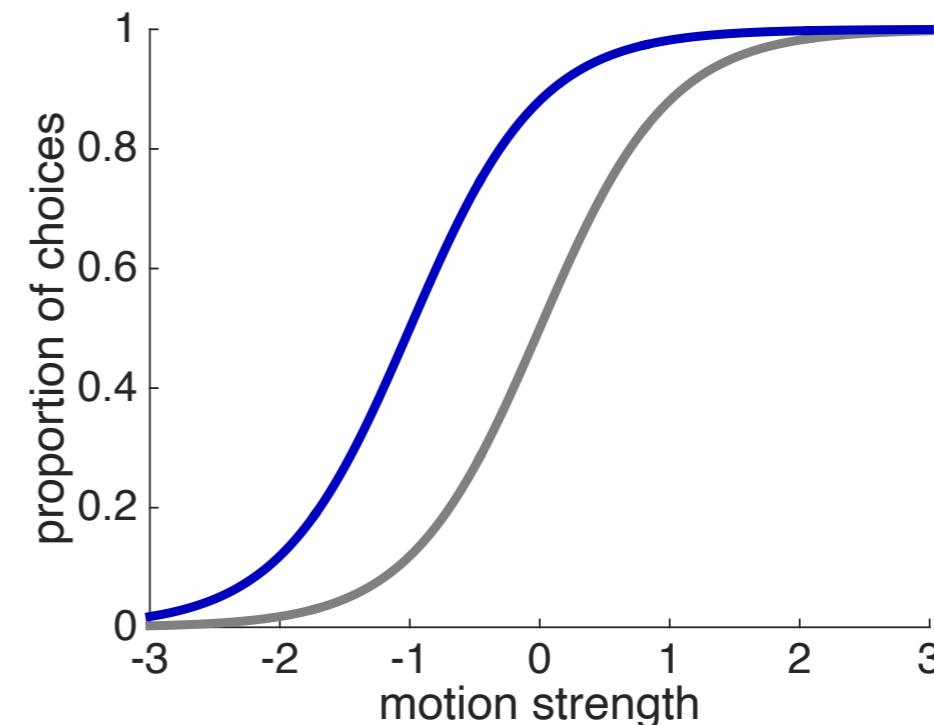
LIP: Accumulated evidence

Is LIP firing *necessary* to influence evidence accumulation?

Sensitivity?



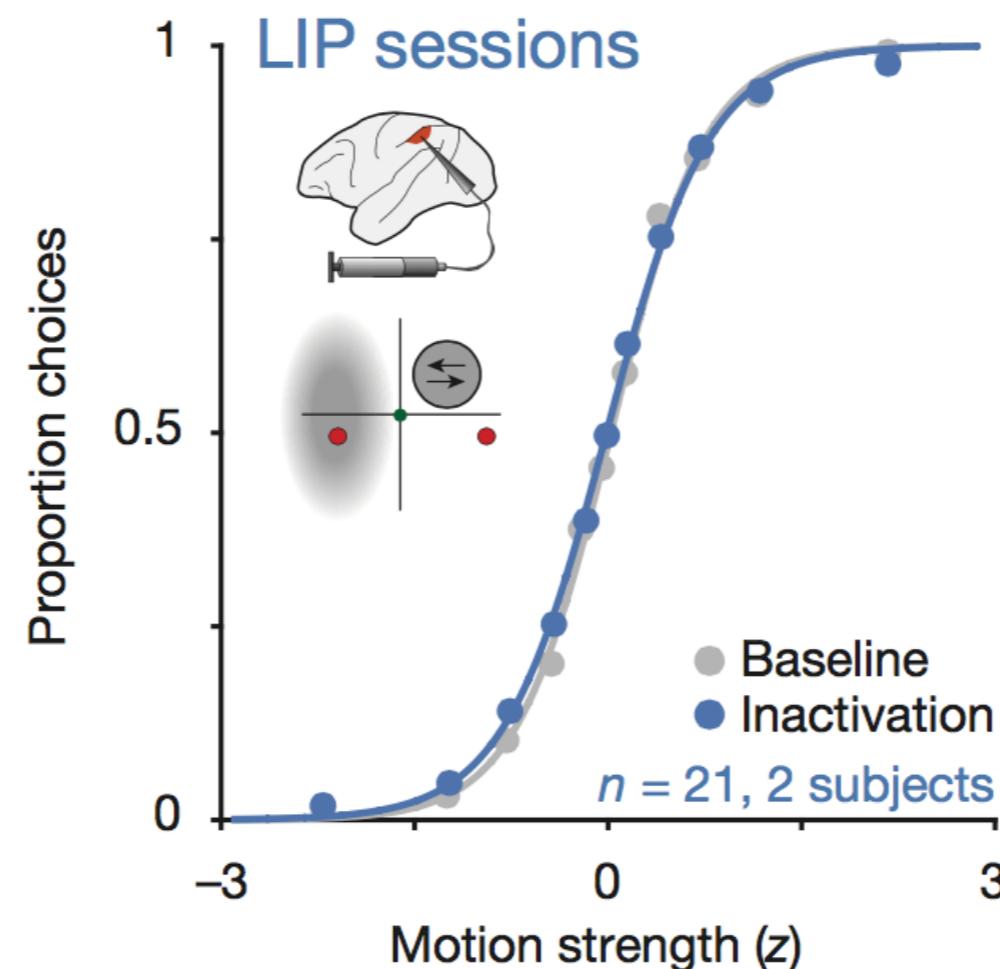
Bias?



LIP: Accumulated evidence

Is LIP firing *necessary* to influence evidence accumulation?

No???



What is going on?

- Compensation?
- Wrong model?
- Wrong brain area?

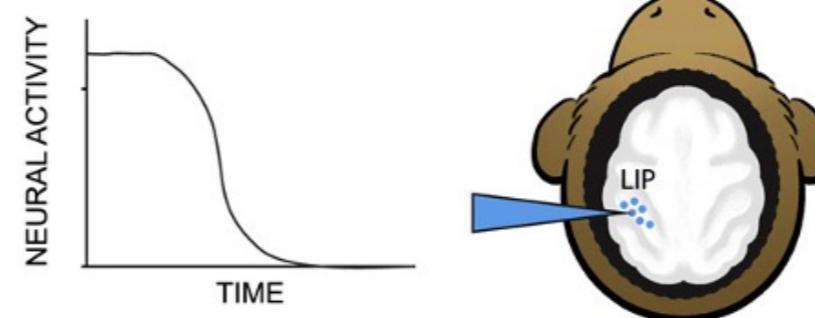
What is going on?

- **Compensation?**
- Wrong model?
- Wrong brain area?

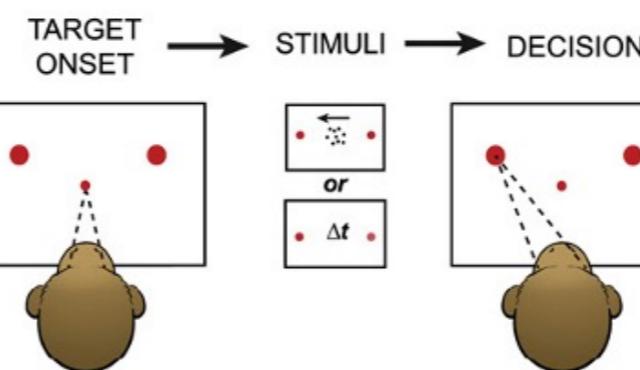
Compensation?

INACTIVATION

pharmacological&
chemogenetic

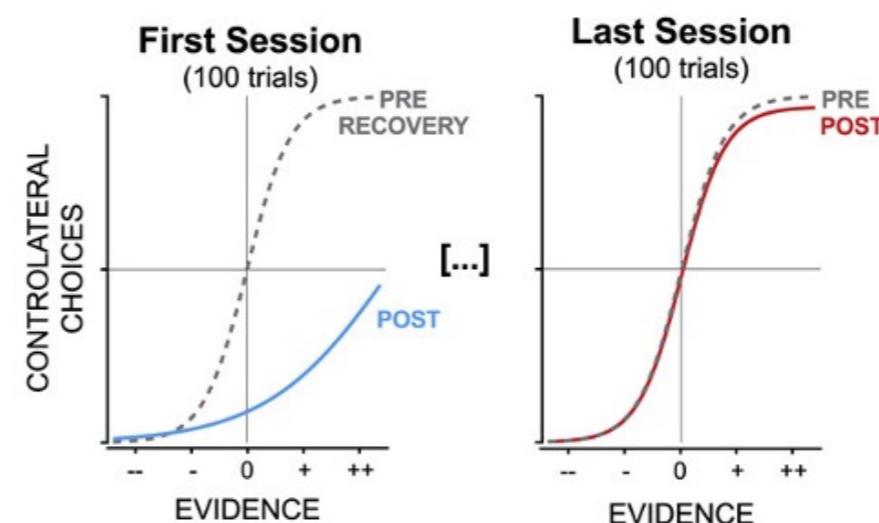


DECISION MAKING



BIAS FOLLOWED BY RECOVERY

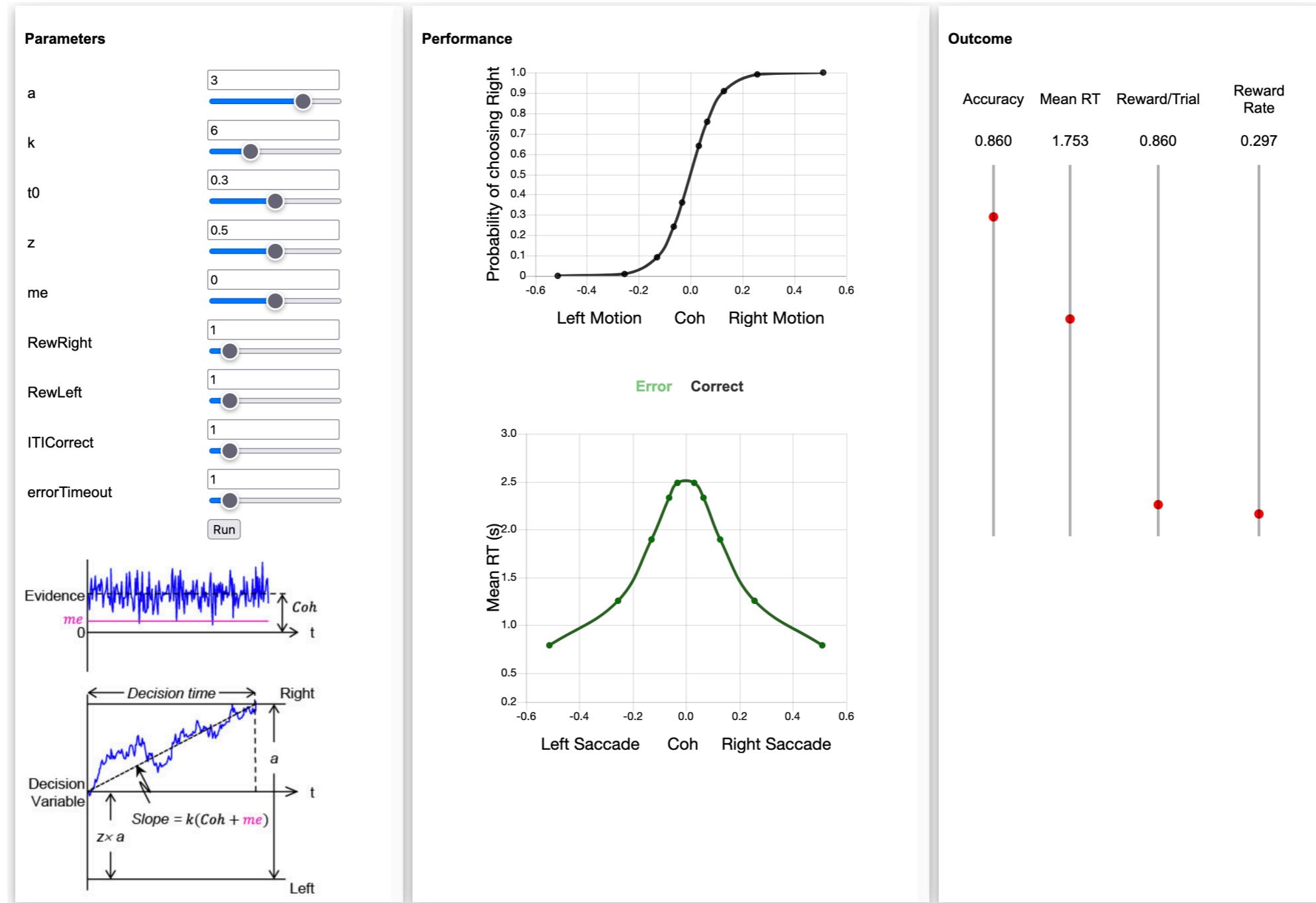
within sessions
and across sessions



Summary

- Accumulation of log-likelihood ratio to a bound is an efficient way to make decisions under uncertainty
- Drift diffusion framework can separate different parameters that affect performance — accumulation rate versus threshold
- It can also account for different “reasons” someone might make an error (too impulsive, or spacing out) through trial-to-trial variability terms
- There is strong evidence for something like a drift diffusion model playing out in the brain as monkeys and rodents do perceptual decision making tasks

Online simulation tools



HDDM

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Sequential Sampling Models

Drift Diffusion Model

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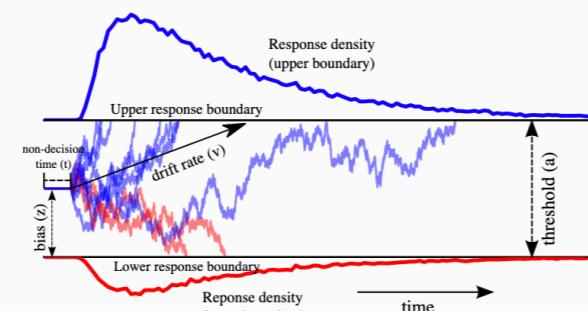
» Sequential Sampling Models Edit on GitHub

Sequential Sampling Models

Sequential Sampling Models generally fall into one of two classes: (i) diffusion models which assume that *relative* evidence is accumulated over time and (ii) race models which assume independent evidence accumulation and response commitment once the first accumulator crossed a boundary ([LaB62], [Vic70]). Currently, HDDM includes two of the most commonly used SSMs: the drift diffusion model (DDM) ([RR98], [RM08]) belonging to the class of diffusion models and the linear ballistic accumulator (LBA) ([BH08]) belonging to the class of race models.

Drift Diffusion Model

The DDM models decision making in two-choice tasks. Each choice is represented as an upper and lower boundary. A drift-process accumulates evidence over time until it crosses one of the two boundaries and initiates the corresponding response ([RR98], [SR04]). The speed with which the accumulation process approaches one of the two boundaries is called drift-rate v and represents the relative evidence for or against a particular response. Because there is noise in the drift process, the time of the boundary crossing and the selected response will vary between trials. The distance between the two boundaries (i.e. threshold a) influences how much evidence must be accumulated until a response is executed. A lower threshold makes responding faster in general but increases the influence of noise on decision making and can hence lead to errors or impulsive choice, whereas a higher threshold leads to more cautious responding (slower, more skewed RT distributions, but more accurate). Response time, however, is not solely comprised of the decision making process – perception, movement initiation and execution all take time and are lumped in the DDM by a single non-decision time parameter t . The model also allows for a prepotent bias z affecting the starting point of the drift process relative to the two boundaries. The termination times of this generative process give rise to the reaction time distributions of both choices.



<https://hddm.readthedocs.io/en/latest/methods.html>

Trajectories of multiple drift-process (blue and red lines, middle panel). Evidence is accumulated over time (x-axis) with drift-rate v until one of two boundaries (separated by threshold a) is crossed and a response

Frank, Wiecki, et al...

Questions?