

## Some mathematics

### A first order differential equation

Many of the differential equations we come across in neuroscience are inhomogeneous first order differential equations

$$\tau \frac{df}{dt} = g(t) - f(t) \quad (1)$$

where  $f(t)$  is some function of  $t$  we are interested,  $g(t)$  is some outside *driving function* and  $\tau$  is a constant. One example we will examine is the integrate and fire equation:

$$\tau_m \frac{dV}{dt} = E_l - V(t) + g_l I(t) \quad (2)$$

where  $V(t)$  is the voltage inside a neuron, and the driving function is made up of two parts  $E_l$ , the so called reversal potential and  $g_l I(t)$  which represents current coming into the cell, for example, through an electrode if the cell being modelled is being experimented on, or because of signals from other neurons. Another example is the gating equation which represents the opening and closing of ion-channels, little gates in the membrane of the cells and a third example is the equation for synaptic conductance. In each of these examples the underlying equation is the same, or nearly the same, and so we will look at it now in the abstract without considering the application.

These are called first order linear differential equations, first order because the highest derivative is  $df/dt$ , there is no  $d^2f/dt^2$  term for example, and linear because there are no non-linear  $f$  terms, no  $f^2$  or anything like that. First order linear differential equations can be solved, or, at least the solution can be written as an integral. The solution uses an *integrating factor*: the trick of simplifying the equation by multiplying across by

$$\lambda = e^{t/\tau} \quad (3)$$

This gives

$$\tau e^{t/\tau} \frac{df}{dt} + e^{t/\tau} f = e^{t/\tau} g(t) \quad (4)$$

The clever bit, now, is that the two terms on the left hand side can be rewritten in product form

$$\tau \frac{d}{dt} \left( e^{t/\tau} f \right) = e^{t/\tau} g(t) \quad (5)$$

We integrate both sides

$$\tau e^{t/\tau} f(t) = \int_0^t e^{t'/\tau} g(t') dt' + A \quad (6)$$

where  $A$  is some integration constant. Setting  $t = 0$  shows that  $A = \tau f(0)$  and, hence, dividing across by the stuff in front of  $f(t)$

$$f(t) = e^{-t/\tau} \left[ \frac{1}{\tau} \int_0^t e^{t'/\tau} g(t') dt' + f(0) \right] \quad (7)$$

Figure 1: Two examples of  $f(t)$  decaying towards  $\bar{g}$ . Here  $\bar{g} = 1$  and  $\tau = 10$ ; in the top curve  $f(0) = 2.5$  whereas in the other  $f(0) = 0.5$ .

Hence,  $f(t)$  is written as an integral, if we can do the integral we have solved the equation.

The easiest case is obviously  $g(t) = \bar{g}$  a constant:

$$f(t) = \bar{g} \left[ \frac{1}{\tau} e^{-t/\tau} \int_0^t e^{t'/\tau} dt' \right] + f(0)e^{-t/\tau} = \bar{g} (1 - e^{-t/\tau}) + f(0)e^{-t/\tau} \quad (8)$$

or

$$f(t) = \bar{g} + [f(0) - \bar{g}]e^{-t/\tau} \quad (9)$$

It is easy to understand this solution:

$$\tau \frac{df}{dt} = \bar{g} - f(t) \quad (10)$$

has  $df/dt = 0$  only if  $f(t) = \bar{g}$  furthermore if  $f(t) > \bar{g}$  then  $df/dt < 0$  and  $f(t)$  decreases towards  $\bar{g}$ ; if  $f(t) < \bar{g}$  so  $df/dt > 0$  then  $f(t)$  increases. Since  $df/dt$  is zero for  $f(t) = \bar{g}$  we say this is the equilibrium; since the sign of  $df/dt$  means that  $f(t)$  always approaches  $\bar{g}$  we say this solution is stable.

We can see in the solution that  $f(t)$  decays exponentially towards  $\bar{g}$  and it does so with a time scale that depends on  $\tau$ . An example is shown in Fig. 1.

What happens if  $g(t)$  isn't constant; well some of the same logic applies, the sign of  $df/dt$  means that the solution is trying to get to  $g(t)$  but the difference is now that  $g(t)$  might change before it gets there. Actually looking at

$$f(t) = e^{-t/\tau} \left[ \frac{1}{\tau} \int_0^t e^{t'/\tau} g(t') dt' + f(0) \right] \quad (11)$$

lets consider the function

$$T(t) = \frac{1}{\tau} e^{-t/\tau} \int_0^t e^{t'/\tau} g(t') dt' \quad (12)$$

and do a change of variable  $t' = t - s$  so

$$T(t) = \frac{1}{\tau} \int_0^t e^{-s/\tau} g(t-s) ds \quad (13)$$

then the role of the integral is to filter or smooth out  $g(t)$  by averaging it over its past with a exponential window. This is illustrated in Fig. 2.

Imagine that  $g(t)$  varies slowly compared to the time scale  $\tau$ , so by the time  $g(t-s)$  changes much compared to  $g(t)$  then  $\exp(-s/\tau)$  is more-or-less zero, then

$$T(t) \approx \frac{1}{\tau} g(t) \int_0^t e^{-s/\tau} ds = g(t) (1 - e^{-t/\tau}) \quad (14)$$

Figure 2: This shows how the response  $f(t)$  filters the input  $g(t)$ ; the differential equation has  $\tau = 3$  and an input  $g(t)$  which varies as shown above; the code used to calculate  $f(t)$  is `filtered_input.py`.

and substituting back in we get

$$f(t) \approx g(t) + [f(0) - g(t)]e^{-t/\tau} \quad (15)$$