

$$C = \{ \text{red, orange, yellow, green, blue} \}$$

$$n = 100 \text{ balls}$$

$$n_{\text{red}}, n_{\text{orange}}, n_{\text{yellow}}, n_{\text{green}}, n_{\text{blue}}$$

$$p(\text{red}) = \frac{n_{\text{red}}}{n}$$

$$\begin{array}{cccc} HH & HT & TH & TT \end{array}$$

$$p(T, T) = \frac{1}{2} \cdot \frac{1}{2} = p(T)p(T)$$

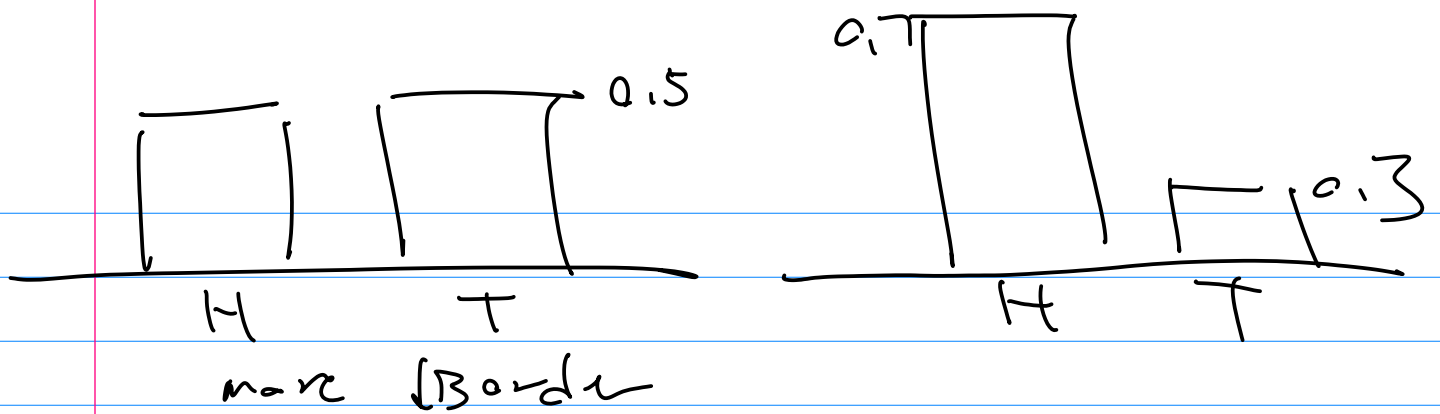
$$p(\text{red, red}) = \frac{n_{\text{red}}}{n} \cdot \frac{n_{\text{red}}}{n}$$

$$p(\text{different col}) = 1 - p(\text{same color})$$

$$= 1 - \left[p(\text{red, red}) + p(\text{blue, blue}) + \dots \right]$$

$c \in C$

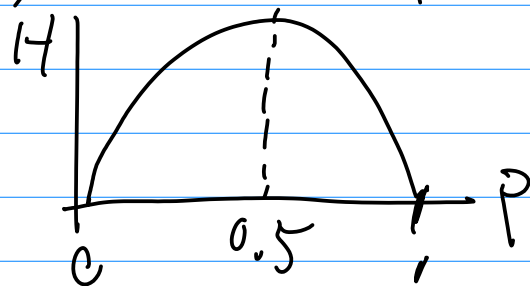
$$= 1 - \sum_{c \in C} \left(\frac{n_c}{n} \right)^2 = 1 - \sum_c p_c^2$$



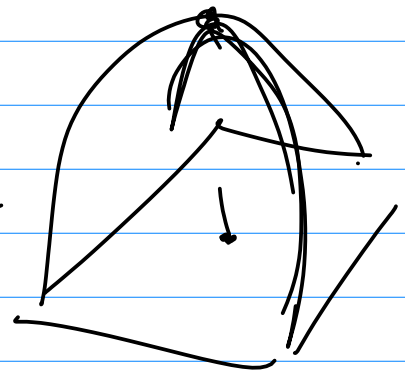
→ LOOK AT YOUR DT NOTES

$$\text{entropy } H = -\{p \log p + (1-p) \log(1-p)\}$$

max H wrt $p \rightarrow p = 0.5$



$$H = -\sum_k p_k \log p_k$$



Gini Index

$$G = 1 - \sum_k p_k^2$$

Print each wr 10 + mes

$$\sigma(w_0 + w_1 x_1 + w_2 x_2 + \dots) \rightarrow [0, 1]$$

$$\frac{x - f}{x} \frac{e}{a} c$$

$$P(Y=1 | X)$$

↑ class ↑ data

posterior

$$P(Y=1 | x) = \frac{P(x, Y=1)}{P(x)}$$

$$= \frac{P(x | Y=1) P(Y)}{P(x)}$$

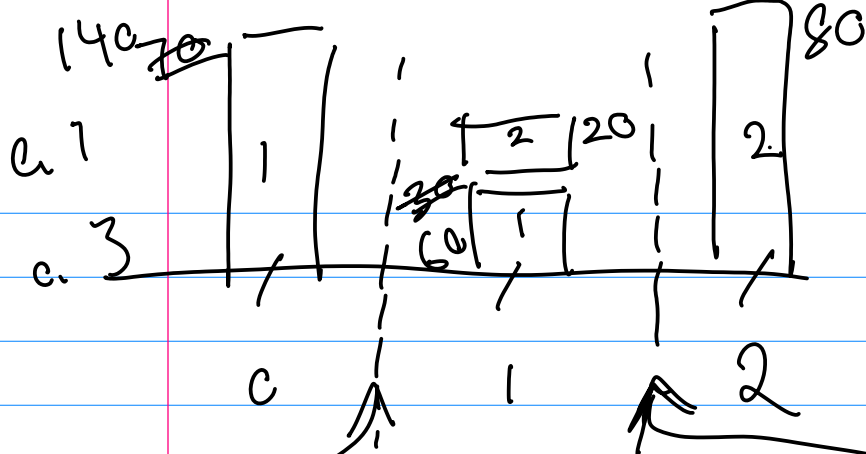
$$\propto \underbrace{P(x | Y=1)}_{\text{likelihood}} \underbrace{P(Y)}_{\text{prior}}$$

$$P(Y=1) = 0.001$$

$$P(Y=0) = 0.999$$

$$\pi_1 = 0.001$$

$$\pi_0 = 0.999$$



c. 2 2. coms

c. 2 $C_1 \rightarrow C_2$

$C_2 \rightarrow 1, 2$

$\$1$

$$\pi_1 = 0.5 = \frac{100}{200}$$

$$\pi_2 = 0.5 = \frac{100}{200}$$

cost 20

$\$3$

cost 30

$$\pi_1 = \frac{200}{300} = \frac{2}{3}$$

$$\pi_2 = \frac{100}{300} = \frac{1}{3}$$

FP

cost 60
\$60

cost 20
\$60

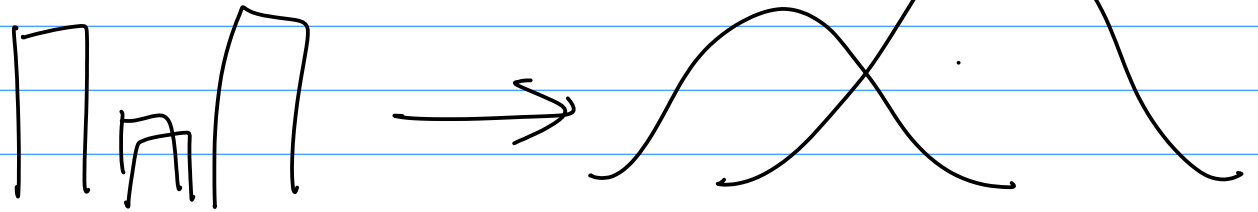
not $\rightarrow P(x | c_1)$ vs, $P(x | c_2)$

$\checkmark \rightarrow P(c_1 | x)$ vs, $P(c_2 | x)$

$P(x | c_1) \pi_1$ vs, $P(x | c_2) \pi_2$
 $\times \frac{2}{3}$ $\times \frac{1}{3}$

$$P(x|c_1)\pi_1 = P(x|c_2)\pi_2$$

find x



$$\pi_0 = 2/3 \quad \pi_1 = 1/3$$

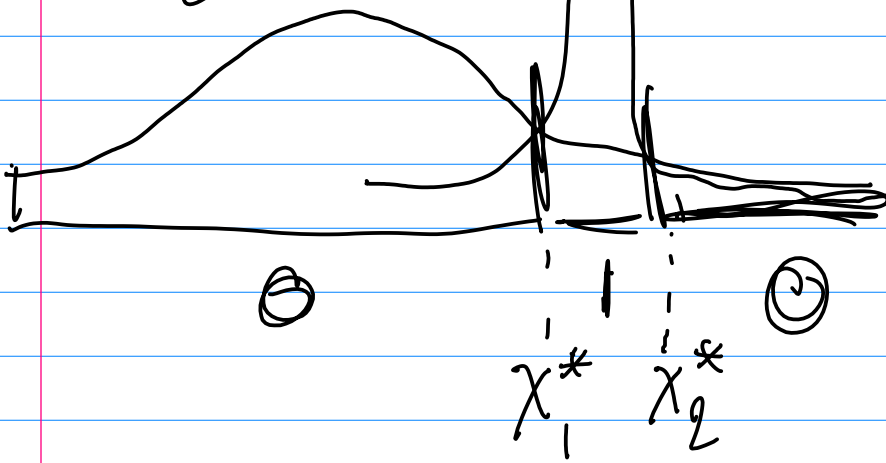
$$P(x|Y=0) = N(0, 1) = \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2}x^2}$$

$$P(x|Y=1) = N(1, 1/4) = \frac{1}{\sqrt{2\pi(1/4)}} e^{-\frac{1}{2}\left(\frac{x-1}{\sqrt{1/4}}\right)^2}$$

$$P(x|Y=0)\pi_0 = P(x|Y=1)\pi_1$$

→ find x boundary

→ quadratic → 2 answers



$$ax^2 + bx + c = 0$$

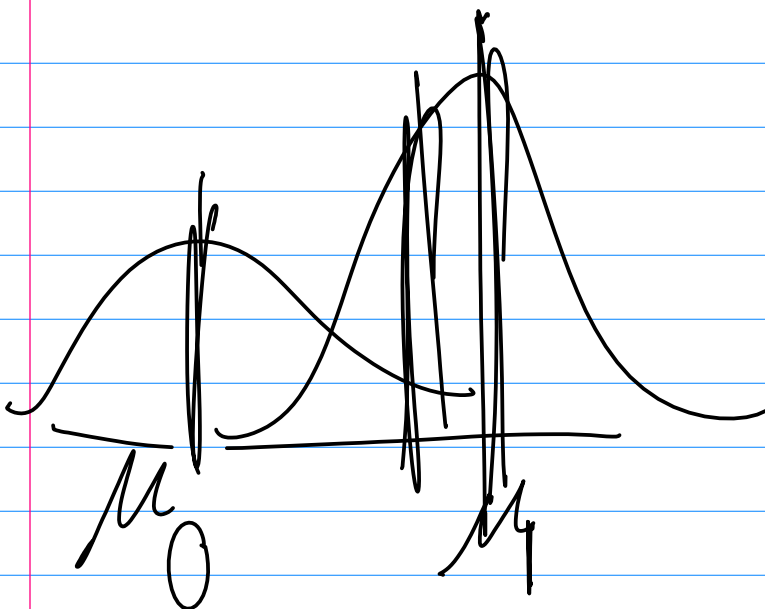
quadratic formula

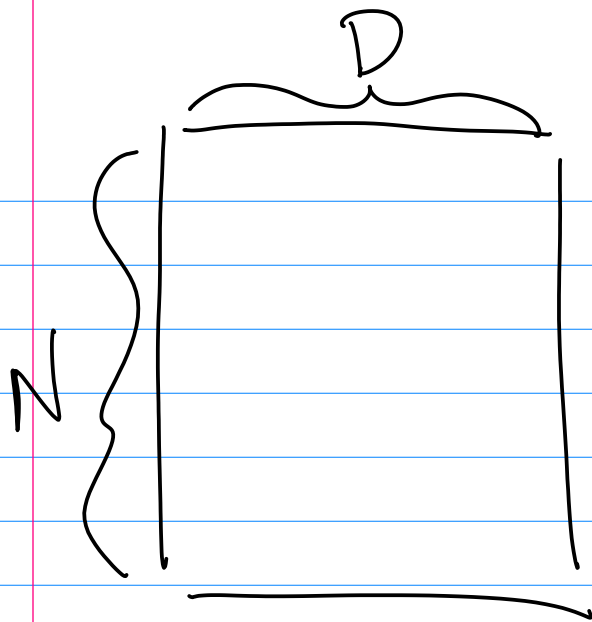
$$x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$



b_1
 b_2

$$f^*(x) = \begin{cases} 0 & x < b_1 \\ 1 & b_1 < x < b_2 \\ 0 & x > b_2 \end{cases}$$

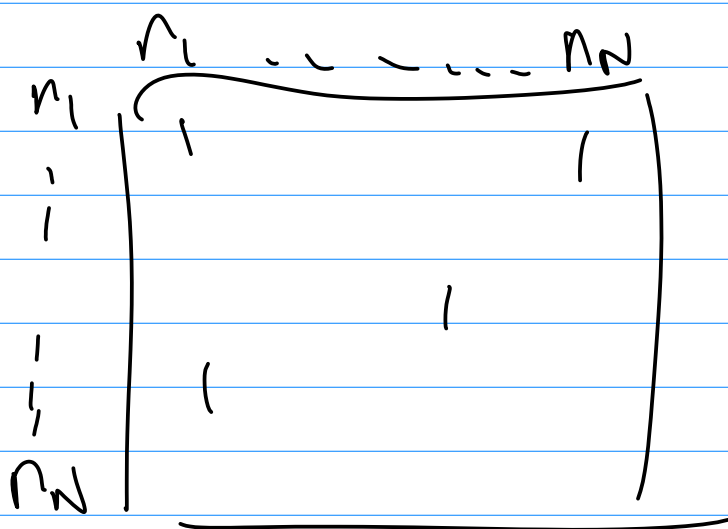




	"dog"	"cat"	"mouse"
0	1	1	0
1	0	1	0
2	0	0	1

Vocab:
 dog
 cat
 mouse

$A[c, o]$



$d = \{$

$(c, 0) : 1,$

$(c, 5) : 1,$

$\}$

$$P(x | \text{class}) = \prod_{j=1}^d \mu_j^{x_j} (1 - \mu_j)^{1-x_j}$$

$$L = \log(\dots) \rightarrow \frac{\partial L}{\partial \mu_j} = 0$$

$$P(\text{motorcycle})P(\text{gas}) \dots P(\text{mouse})$$



$$\frac{0}{N} \rightarrow \frac{1+0}{2+N}$$

$$= (M_{LE} | L_{tr})$$

~~star~~ $P(Y | X)$

$$\text{Prediction} = \underset{\text{forum}}{\text{argmax}} P(Y = \text{forum} | X)$$

$$\propto P(X | \text{forum}) P(\text{forum})$$

$$\prod_{j=1}^d \mu_j^{x_j} (1 - \mu_j)^{1-x_j} \cdot \frac{\# \text{forum}}{\text{total}}$$

$$P(\text{data} | \mu) \rightsquigarrow$$

$$P(\text{data} | \mu_{\text{forum}_1}) -$$

$$P(\text{data} | \mu_{\text{forum 2}})$$

$$\text{likelihood} = \prod P(\text{word appears})$$

$$\arg \max_y \left(\prod_{j=1}^d \mu_{y,j}^{x_j} (1 - \mu_{y,j})^{1-x_j} \right) \pi_y$$

Linear classifier: $y = w_0 + w_1x_1 + w_2x_2 + \dots$

$$y = mx + b = w_0 + \sum_{j=1}^d w_j x_j$$

$$\log \left[\prod_{j=1}^d \mu_{y,j}^{x_j} (1 - \mu_{y,j})^{1-x_j} \right] \prod_{j=1}^d \pi_{y,j}$$

$$= \log \pi_y + \sum_{j=1}^d x_j \log \mu_{y,j} + (1-x_j) \log (1-\mu_{y,j})$$

$$= \underbrace{\log \pi_y + \sum_j \log(1 - \mu_{y,j})}_b + \sum_j \underbrace{[\log \mu_{y,j} - \log(1 - \mu_{y,j})]}_{w_j} x_j$$

$$= b_y + \underbrace{w_{y,j}}_{\substack{\text{forum} \\ \text{or} \\ \text{class}}} \underbrace{x_j}_{\substack{\text{dimension} \\ \text{or} \\ \text{word index}}}$$

$$\prod_{j=1}^n \mu_{y,j} \dots (1 - \mu_{y,j}) \pi_y$$

$$\underbrace{b}_y + \underbrace{w^T x}_{\text{dot product}}$$

$$\text{params} = \left\{ \begin{array}{l} \text{label}_y : \{ \text{"bias"} : b_y, \\ \text{"weights"} : \vec{w}_y \} \end{array} \right.$$