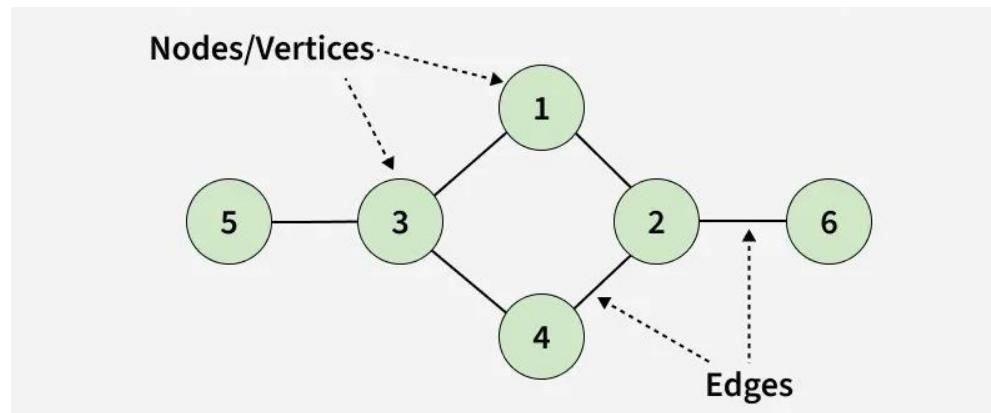


# Lecture 7

## Graphs II – BFS & DFS



# Announcements

- ❖ [Reflections on Homework 3](#) due Sunday night
  - ❖ **New question:** Did you use AI to assist with this assignment? If so, how?
- ❖ [Group Meetings](#) start this week
  - Self-scheduled meeting for an hour studying, working on HW, completing practice exercises
- ❖ [Individual Project 1](#) due Friday
  - [Project guide and instructions](#) posted
  - [Example](#) posted on Ed

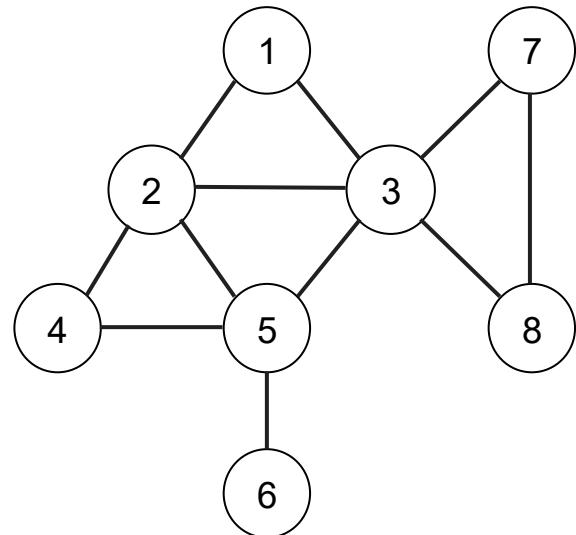
# Graph Traversal

An important question about graphs:

- ❖ Can we determine if there's a path between any two vertices?

How can we solve it?

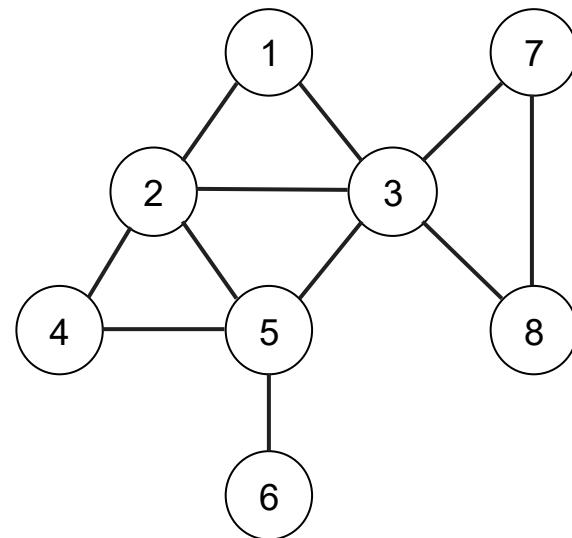
- ❖ Graph traversal
- ❖ Bread-first search (BFS): explore locally
- ❖ Depth-first search (DFS): deep dive and backtrack



# Breadth-First Search

Explore outward from starting node by distance

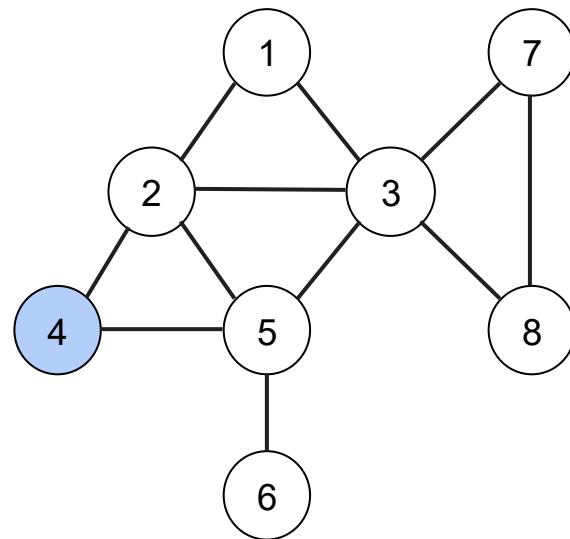
- ❖ "Expanding Wave"



# Breadth-First Search

Explore outward from starting node by distance

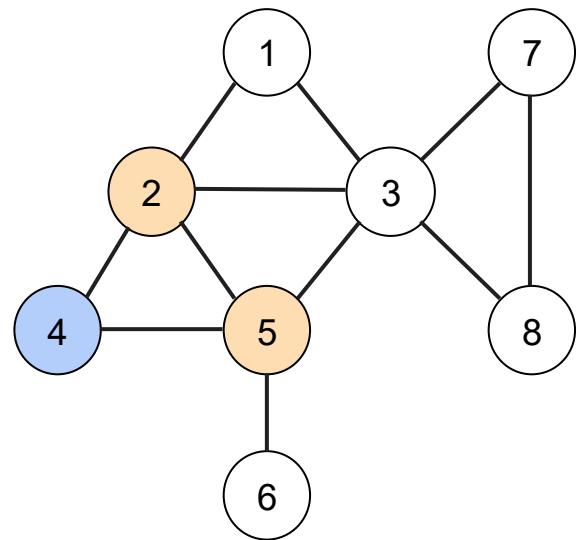
- ❖ "Expanding Wave"
- ❖ Let's start at vertex 4
  - ❖ Distance 0 from 4



# Breadth-First Search

Explore outward from starting node by distance

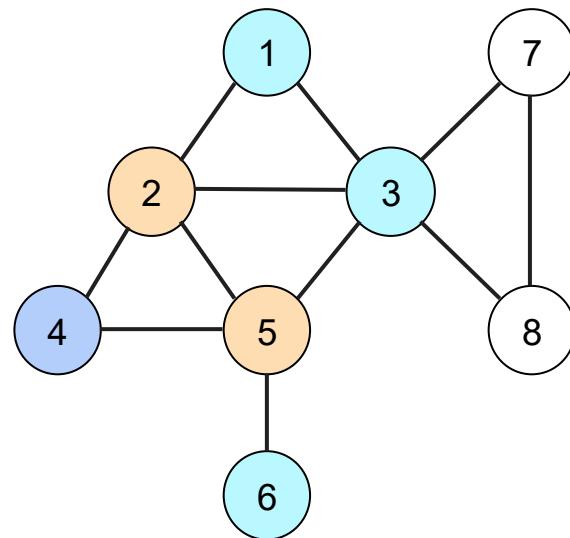
- ❖ "Expanding Wave"
- ❖ Let's start at vertex 4
  - ❖ Distance 0 from [4](#)
  - ❖ Distance 1 from [4](#)



# Breadth-First Search

Explore outward from starting node by distance

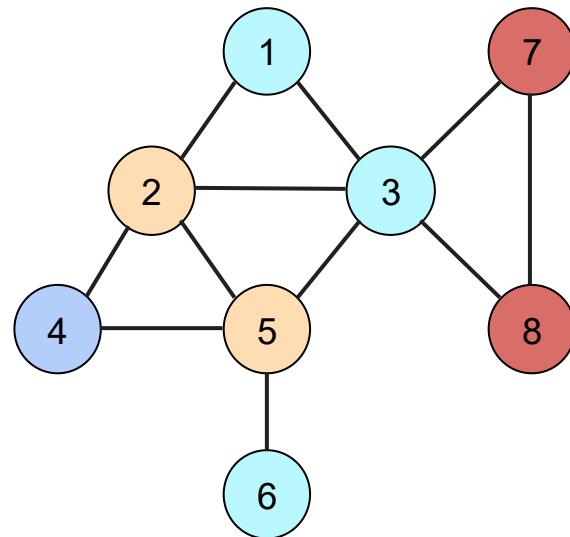
- ❖ "Expanding Wave"
- ❖ Let's start at vertex 4
  - ❖ Distance 0 from 4
  - ❖ Distance 1 from 4
  - ❖ Distance 2 from 4



# Breadth-First Search

Explore outward from starting node by distance

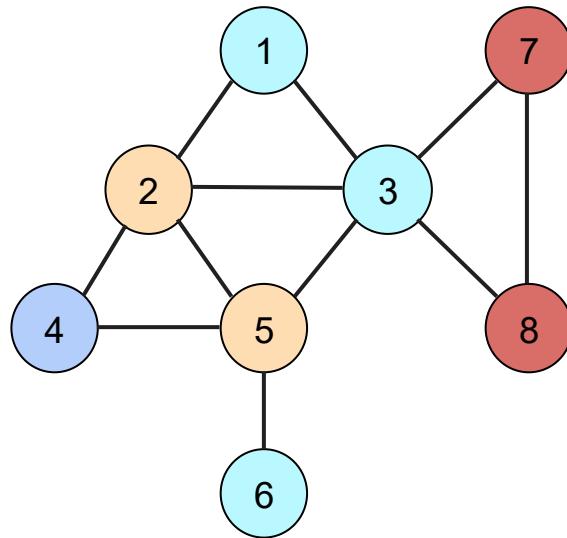
- ❖ "Expanding Wave"
- ❖ Let's start at vertex 4
  - ❖ Distance 0 from 4
  - ❖ Distance 1 from 4
  - ❖ Distance 2 from 4
  - ❖ Distance 3 from 4



# Breadth-First Search

Explore outward from starting node by distance

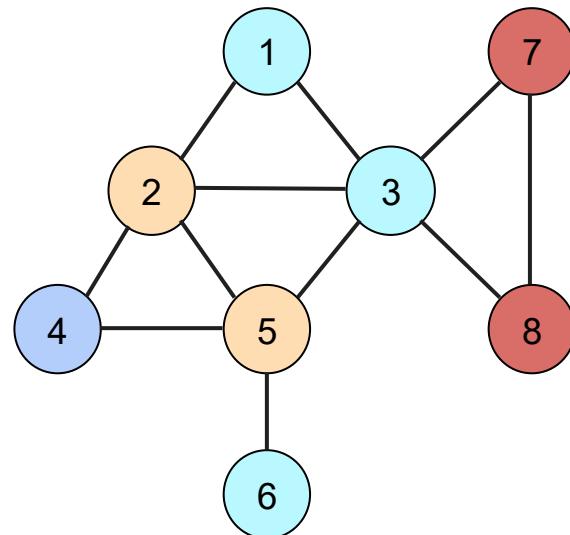
- ❖ "Expanding Wave"
- ❖ Let's start at vertex 4
  - ❖ Distance 0 from 4
  - ❖ Distance 1 from 4
  - ❖ Distance 2 from 4
  - ❖ Distance 3 from 4
- ❖ All vertices that are reachable from 4 will be explored eventually



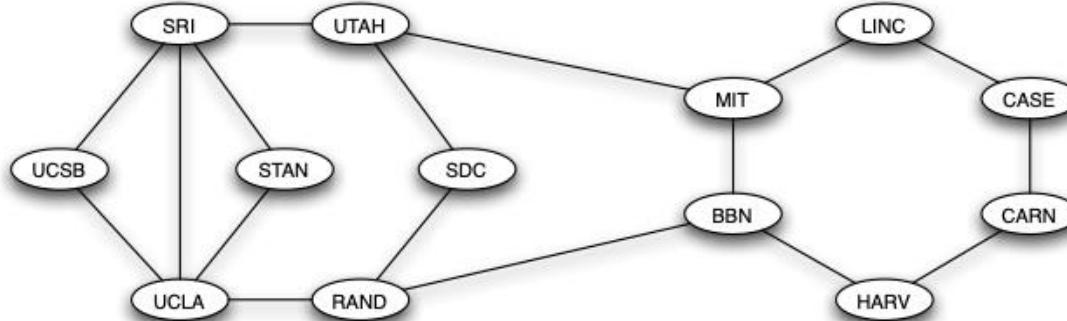
# Breadth-First Search

Explore outward from starting node  $s$  by distance

- ❖ Define **layer**  $L_i$  as all vertices at distance exactly  $i$  from  $s$
- ❖ Layers:
  - ❖  $L_0 = \{4\}$
  - ❖  $L_1 = \{2, 5\}$
  - ❖  $L_2 = \{1, 3, 6\}$
  - ❖ ...
  - ❖  $L_{i+1} = \text{all vertices with an edge to a vertex in } L_i \text{ that do not belong to any earlier layer}$
- ❖ Observation: there is a path from  $s$  to  $t$  if and only if  $t$  appears in some layer.



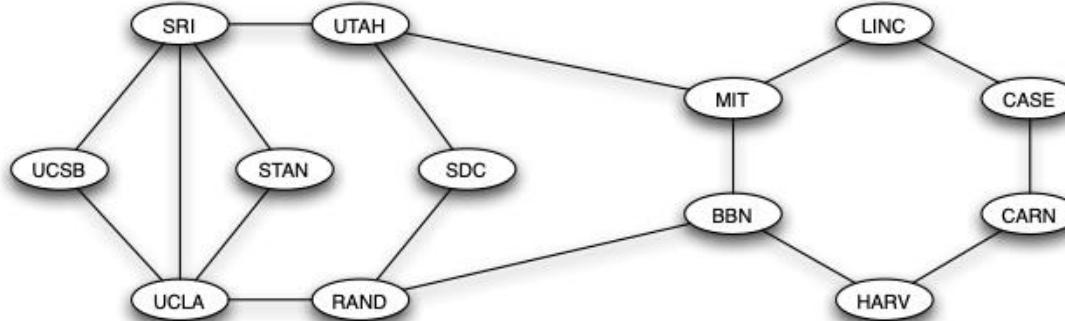
# Exercise I



**Q:** How many vertices are in layer 2, starting a BFS from MIT?

- a) 4
- b) 5
- c) 6
- d) 42

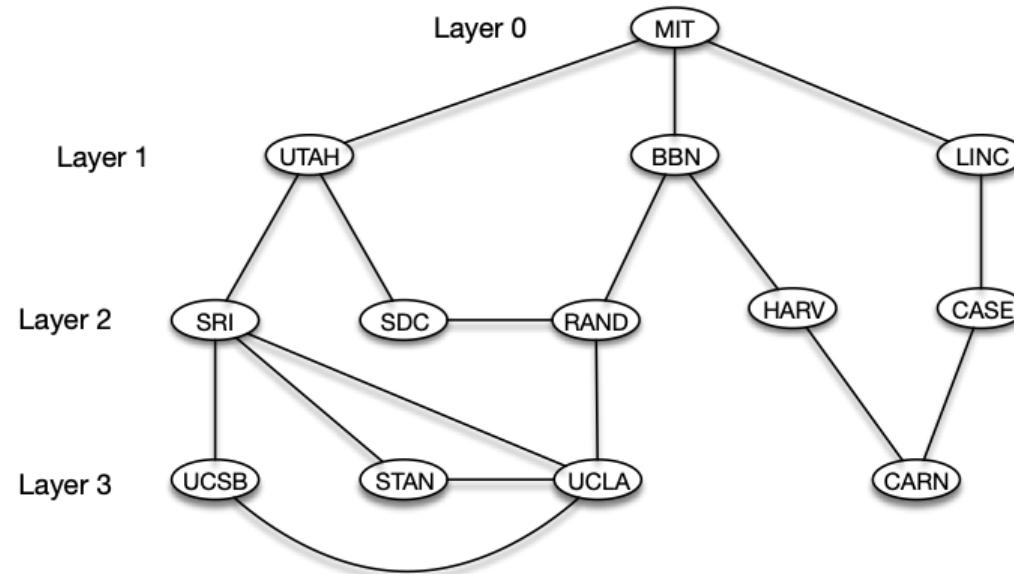
# Exercise I



**Q:** How many vertices are in layer 2, starting a BFS from MIT?

- a) 4
- b) 5
- c) 6
- d) 42

# Exercise I



# BFS Implementation

$\text{BFS}(s)$ :

    mark  $s$  as "discovered"

$L[0] \leftarrow \{s\}; i \leftarrow 0$

**while**  $L[i]$  is not empty **do**

$L[i + 1] \leftarrow$  empty list

**for all** vertices  $v$  in  $L[i]$  **do**

**for all** neighbors  $w$  of  $v$  **do**

**if**  $w$  is not marked "discovered" **then**

                    mark  $w$  as "discovered"

$L[i + 1].append(w)$

$i \leftarrow i + 1$

# BFS Implementation

BFS( $s$ ):

mark  $s$  as "discovered"

$L[0] \leftarrow \{s\}; i \leftarrow 0$

**while**  $L[i]$  is not empty **do**

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**for all** neighbors  $w$  of  $v$  **do**

**if**  $w$  is not marked "discovered" **then**

                mark  $w$  as "discovered"

$L[i + 1].append(w)$

$i \leftarrow i + 1$

start at layer 0

iterate until we hit an empty layer

loop over all vertices in a layer and  
all neighbors of those vertices

if neighbor is new, add to next layer

# BFS Implementation

*n* vertices  
*m* edges

BFS( $s$ ):

    mark  $s$  as "discovered"

$L[0] \leftarrow \{s\}; i \leftarrow 0$

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$L[i + 1].append(w)$

$i \leftarrow i + 1$

What is the running time? Can we use the structure of the graph to obtain our bound?

# BFS Implementation

*n* vertices  
*m* edges

BFS( $s$ ):

    mark  $s$  as "discovered"

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$L[i + 1].append(w)$

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} constant time operations

What is the running time? Can we use the structure of the graph to obtain our bound?

# BFS Implementation

*n* vertices  
*m* edges

BFS( $s$ ):

mark  $s$  as "discovered"

$L[0] \leftarrow \{s\}; i \leftarrow 0$

**while**  $L[i]$  is not empty **do**

$L[i + 1] \leftarrow$  empty list ← create at most  $n$  new lists

**for all** vertices  $v$  in  $L[i]$  **do**

**for all** neighbors  $w$  of  $v$  **do**

**if**  $w$  is not marked "discovered" **then**

                    mark  $w$  as "discovered"

$L[i + 1].append(w)$

$i \leftarrow i + 1$

    } looks like  $n * m$  loops, but we can do better

} constant time operations

What is the running time? Can we use the structure of the graph to obtain our bound?

# BFS Implementation

*n* vertices  
*m* edges

BFS( $s$ ):

mark  $s$  as "discovered"

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**for all** vertices  $v$  in  $L[i]$  **do**

**for all** neighbors  $w$  of  $v$  **do**

            } in total, this runs  $m$  times because there are  $m$  edges

**if**  $w$  is not marked "discovered" **then**

                mark  $w$  as "discovered"

$L[i + 1].append(w)$

} constant time operations

$i \leftarrow i + 1$

What is the running time? Can we use the structure of the graph to obtain our bound?

# BFS Implementation

$n$  vertices  
 $m$  edges

BFS( $s$ ):

mark  $s$  as "discovered"

$L[0] \leftarrow \{s\}; i \leftarrow 0$

**while**  $L[i]$  is not empty **do**

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**for all** neighbors  $w$  of  $v$  **do**

**if**  $w$  is not marked "discovered" **then**

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} constant time operations

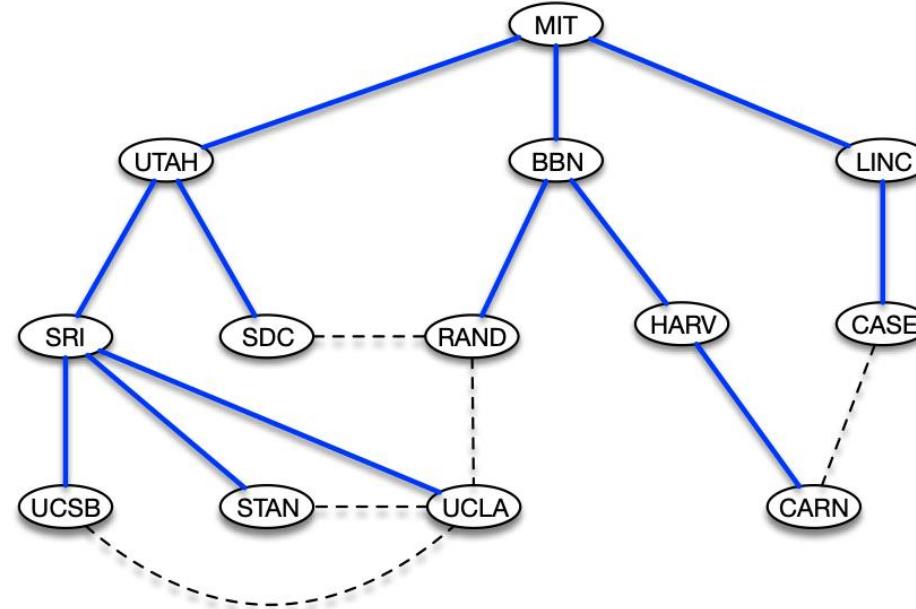
What is the running time?

$\Theta(n + m)$

# BFS Tree

We can use BFS to make a tree

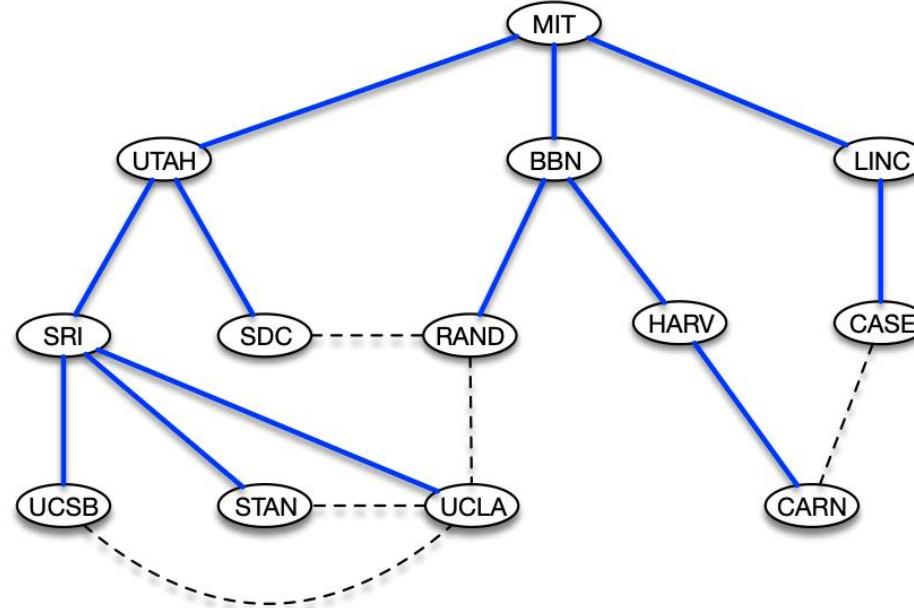
- ❖ Keep edge  $(v, w)$  if  $w$  was marked discovered as a neighbor of  $v$
- ❖ Why does BFS make a tree?
- ❖ e.g. starting from MIT



# BFS Tree

We can use BFS to make a tree

- ❖ Keep edge  $(v, w)$  if  $w$  was marked discovered as a neighbor of  $v$
- ❖ Why does BFS make a tree?
- ❖ e.g. starting from MIT
- ❖ **Claim:** Let  $T$  be the tree discovered by BFS on graph  $G = (V, E)$ , and let  $(x, y)$  be any edge of  $G$ . Then the layers of  $x$  and  $y$  in  $T$  differ by at most 1.



# BFS Tree

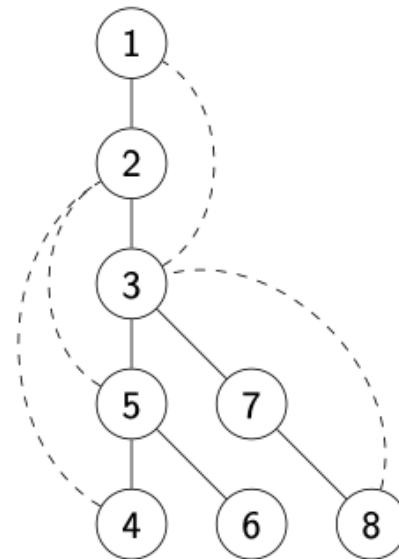
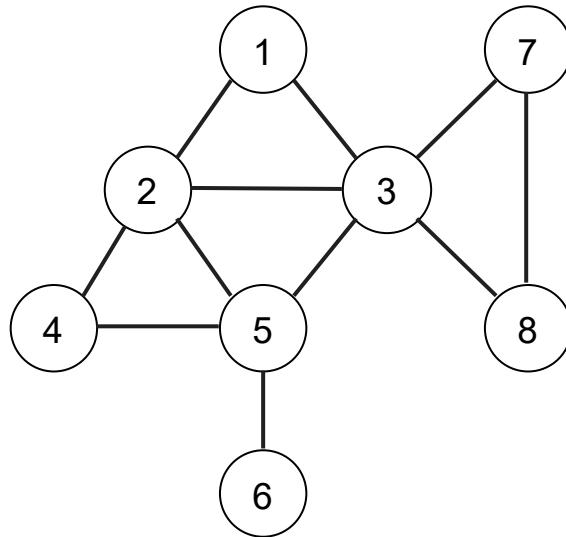
**Claim:** Let  $T$  be the tree discovered by BFS on graph  $G = (V, E)$ , and let  $(x, y)$  be any edge of  $G$ . Then the layers of  $x$  and  $y$  in  $T$  differ by at most 1.

**Proof:**

- ❖ Let  $(x, y)$  be an edge
- ❖ Assume  $x$  is discovered first and placed in  $L_i$
- ❖ Then  $y \in L_j$  for  $j \geq i$
- ❖ When neighbors of  $x$  are explored,  $y$  is either already in  $L_i$  or  $L_{i+1}$ , or is discovered and added to  $L_{i+1}$

# Depth-First Search

Keep exploring from the most recently added vertex until you reach a dead end, then backtrack



# Depth-First Search

DFS( $u$ ):

    mark  $u$  as "explored"

**for all** edges  $(u, v)$  **do**

**if**  $w$  is not "explored" **then**

            call DFS( $v$ ) recursively

# Depth-First Search

```
DFS( $u$ ):  
    mark  $u$  as "explored"  
    for all edges  $(u, v)$  do  
        if  $v$  is not "explored" then  
            call DFS( $v$ ) recursively
```

visit each vertex once

iterate over all edges

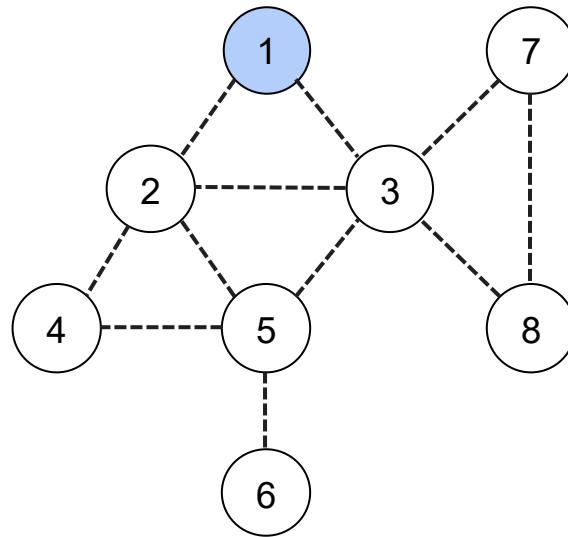
What is the running time?

$\Theta(n + m)$

# DFS Tree

We can use DFS to make a tree

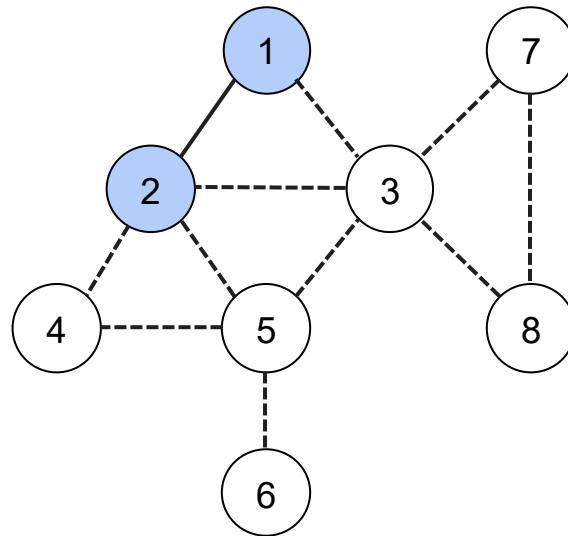
- ❖ Keep edge  $(v, w)$  if  $w$  was explored as a neighbor of  $v$
- ❖ Why does DFS make a tree?
- ❖ e.g. starting from 1



# DFS Tree

We can use DFS to make a tree

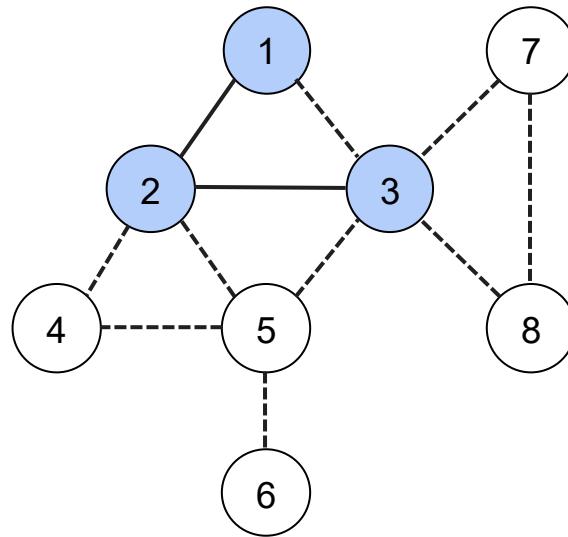
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# DFS Tree

We can use DFS to make a tree

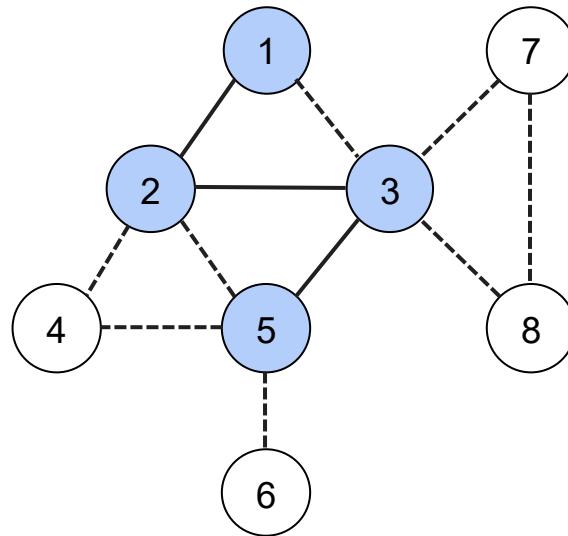
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# DFS Tree

We can use DFS to make a tree

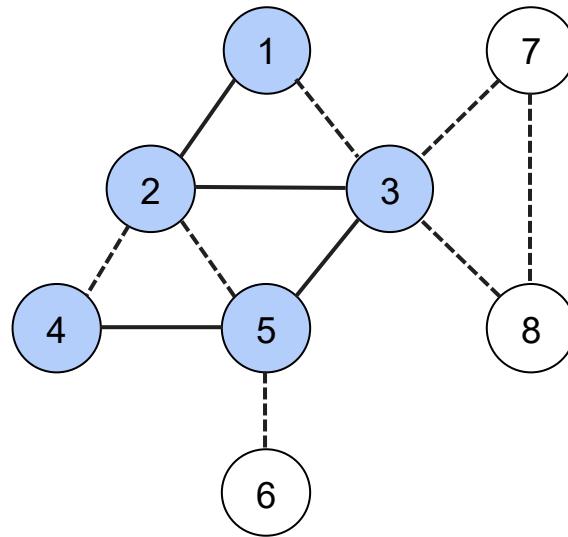
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# DFS Tree

We can use DFS to make a tree

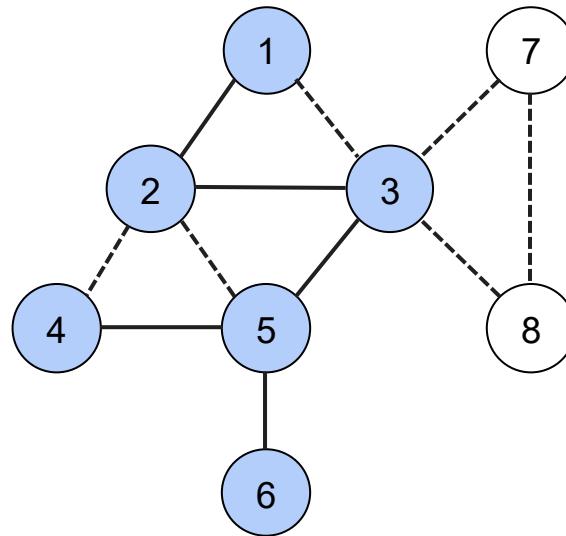
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# DFS Tree

We can use DFS to make a tree

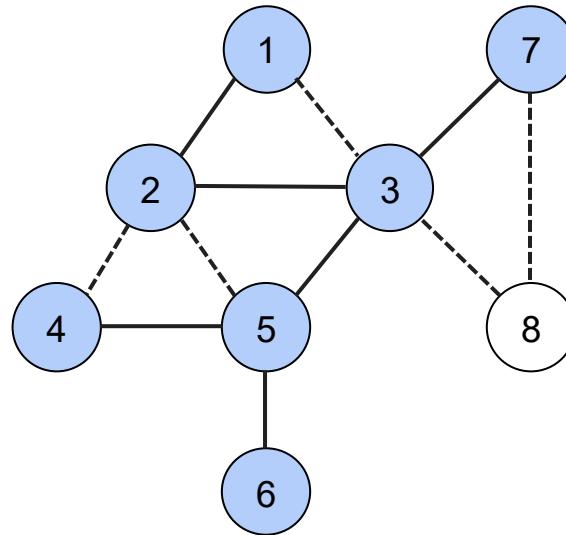
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# DFS Tree

We can use DFS to make a tree

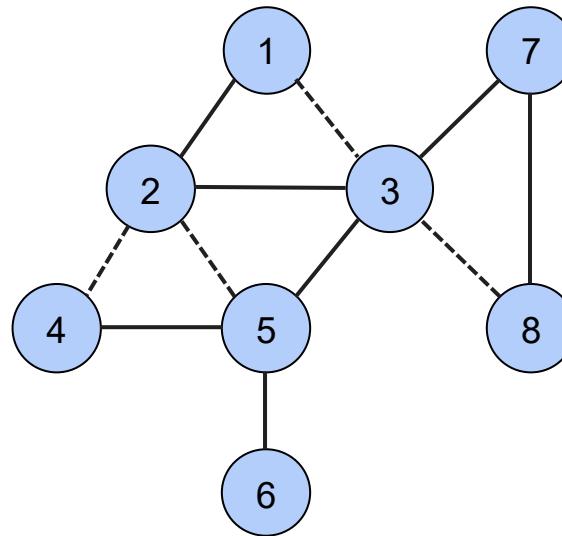
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# DFS Tree

We can use DFS to make a tree

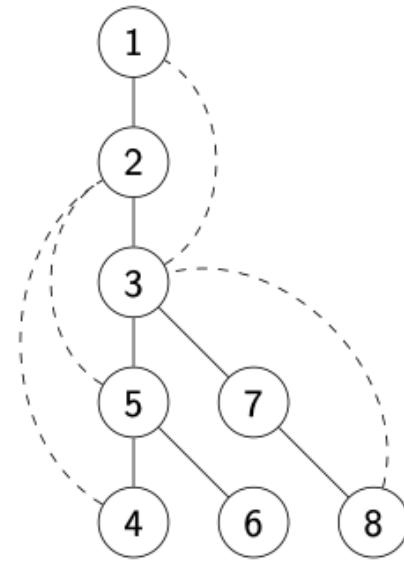
- ❖ Keep edge  $(v, w)$  if  $w$  was explored as a neighbor of  $v$
- ❖ Why does DFS make a tree?
- ❖ e.g. starting from 1



# DFS Tree

We can use DFS to make a tree

- ❖ Keep edge  $(v, w)$  if  $w$  was explored as a neighbor of  $v$
- ❖ Why does DFS make a tree?
- ❖ e.g. starting from 1
- ❖ Claim: Non-tree edges lead to ancestors.



# DFS Tree

**Claim:** Let  $T$  be the tree discovered by DFS on graph  $G = (V, E)$ , and let  $(x, y)$  be any edge of  $G$  that is not in  $T$ . Then one of  $x$  or  $y$  is an ancestor of the other.

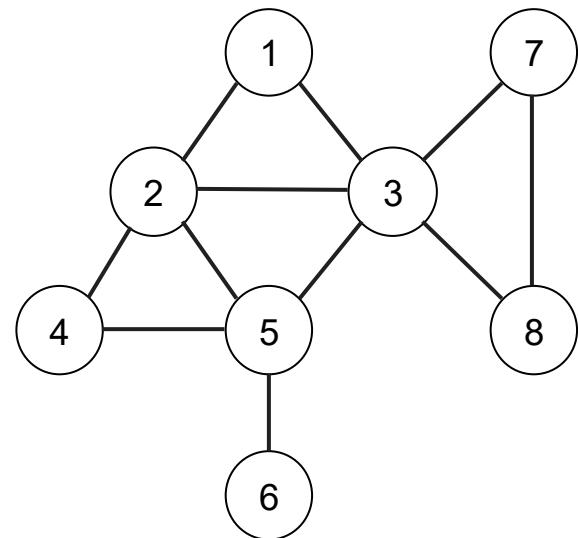
**Proof:**

- ❖ Let  $x$  be the first of the two vertices explored
- ❖ Is  $y$  explored at the beginning of  $\text{DFS}(x)$ ? No.
- ❖ At some point during  $\text{DFS}(x)$ , we examine the edge  $(x, y)$ . Is  $y$  explored then? Yes, otherwise, we would put  $(x, y)$  in  $T$
- ❖ Implies  $y$  was explored during  $\text{DFS}(x)$
- ❖ Therefore,  $y$  is a descendant of  $x$

# Generic Traversals

Maintain a set of explored vertices and discovered vertices

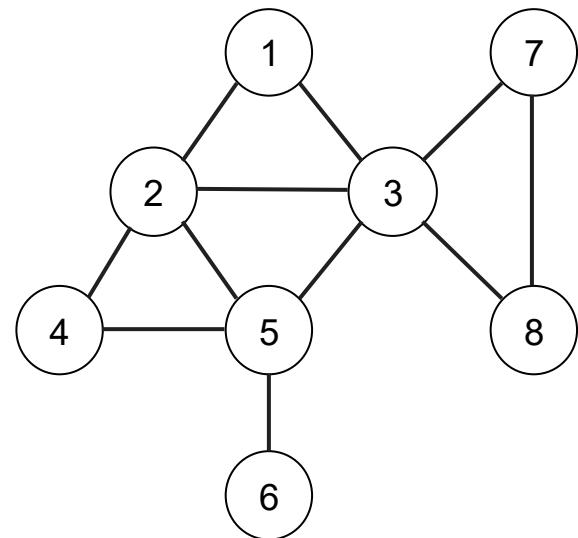
- ❖ Explored: we have seen this vertex before and explored its outgoing edges
- ❖ Discovered: the "frontier"; we have seen this vertex before, but not explored its outgoing edges
- ❖ A combination of exploring and discovering
  - ❖ See Homework 4



# Generic Traversals

Maintain a set of explored vertices and discovered vertices

- ❖ Explored: we have seen this vertex before and explored its outgoing edges
- ❖ Discovered: the "frontier"; we have seen this vertex before, but not explored its outgoing edges
- ❖ A combination of exploring and discovering
  - ❖ See Homework 4



# Exploring all Connected Components

How do you explore the entire graph even if its disconnected?

**while** there is an explored vertex  $s$  **do**

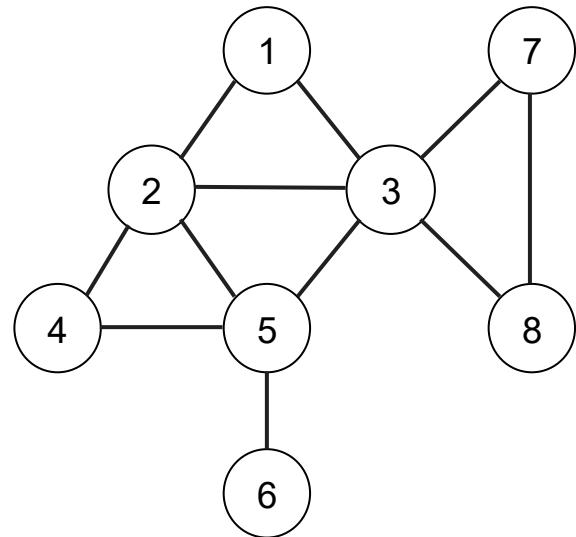
    Traverse( $s$ )

Running time?

- ❖ Still  $\Theta(n + m)$
- ❖ Traversal of each component takes time proportional to the number of vertices and edges in that components

Note:

- ❖ It's usually okay to assume a graph is connected. State if you are doing do and why it does not trivialize the problem.



# Next Time

- ❖ Dive into BSF and DSF
- ❖ Analyze implementations using stacks and queues