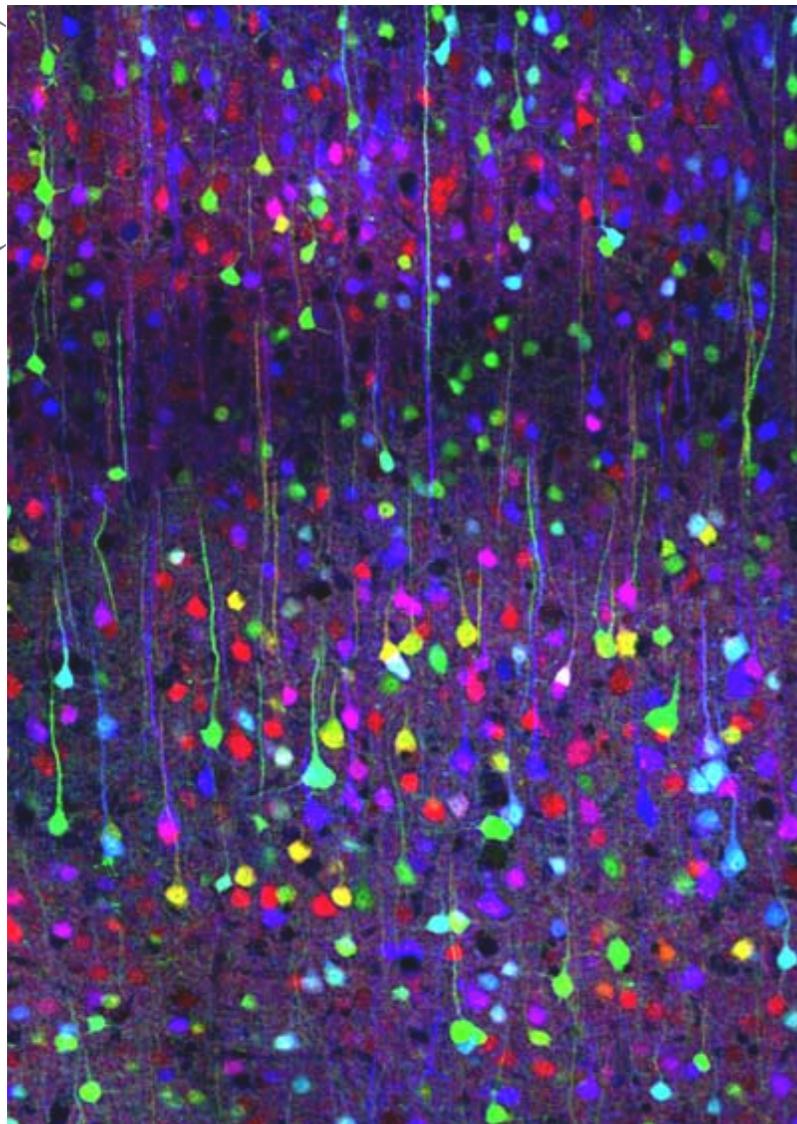


# Information Processing & the Brain 21/22



Brainbow (Litchman Lab)



## IPB: Part 2

### Lecture 1: Neural circuits and learning

Rui Ponte Costa

# What's going to happen?

- **Expectations**

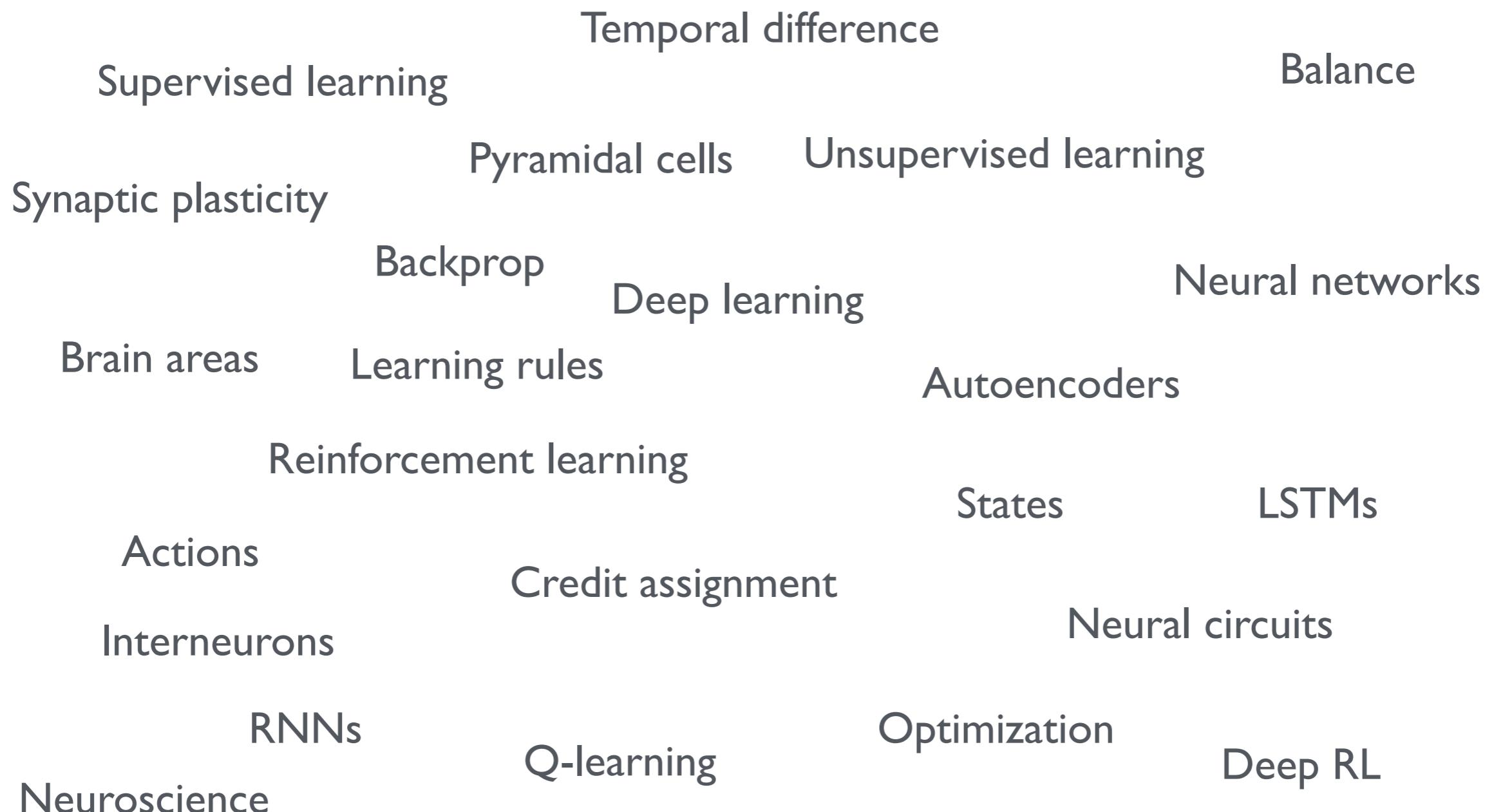
- Interactive lectures (BB quizzes, videos, simulations)
- Research oriented (papers)
- Neuroscience: a few theories, but mostly open
- Lecturer and TA support on Teams/in person

# What's going to happen?

- **Labs** [formative]
  - *Implement and discuss neural learning algorithms*
  - Lab 1 [w5,7]: on supervised learning
  - Lab 2 [w7,8]: on reinforcement learning
- **TAs:**
  - Joe Pemberton
  - Dabal Pedamonti
  - Kevin Nejad

# IPB: part 2

## Neural circuits and learning



# IPB: part 2

## Neural circuits and learning

- L1<sup>[4]</sup>: Neural circuits and learning: introduction
- L2<sup>[4]</sup>: Supervised learning & backprop
- L3<sup>[5]</sup>: Visual system: deep learning?
- L4<sup>[5]</sup>: Reinforcement learning
- L5<sup>[6]</sup>: Unsupervised learning
- L6<sup>[6]</sup>: Temporal processing
- L7<sup>[7]</sup>: Recurrent neural networks
- L8<sup>[7]</sup>: Guest lecture

# This lecture

A short overview on the credit assignment problem and the different forms of learning in the brain (and machine learning):

**Supervised learning**

**Unsupervised learning**

**Reinforcement learning**

# Given visual input how should you move?

Visual input → Prepare movement → Hit (or not) the ball



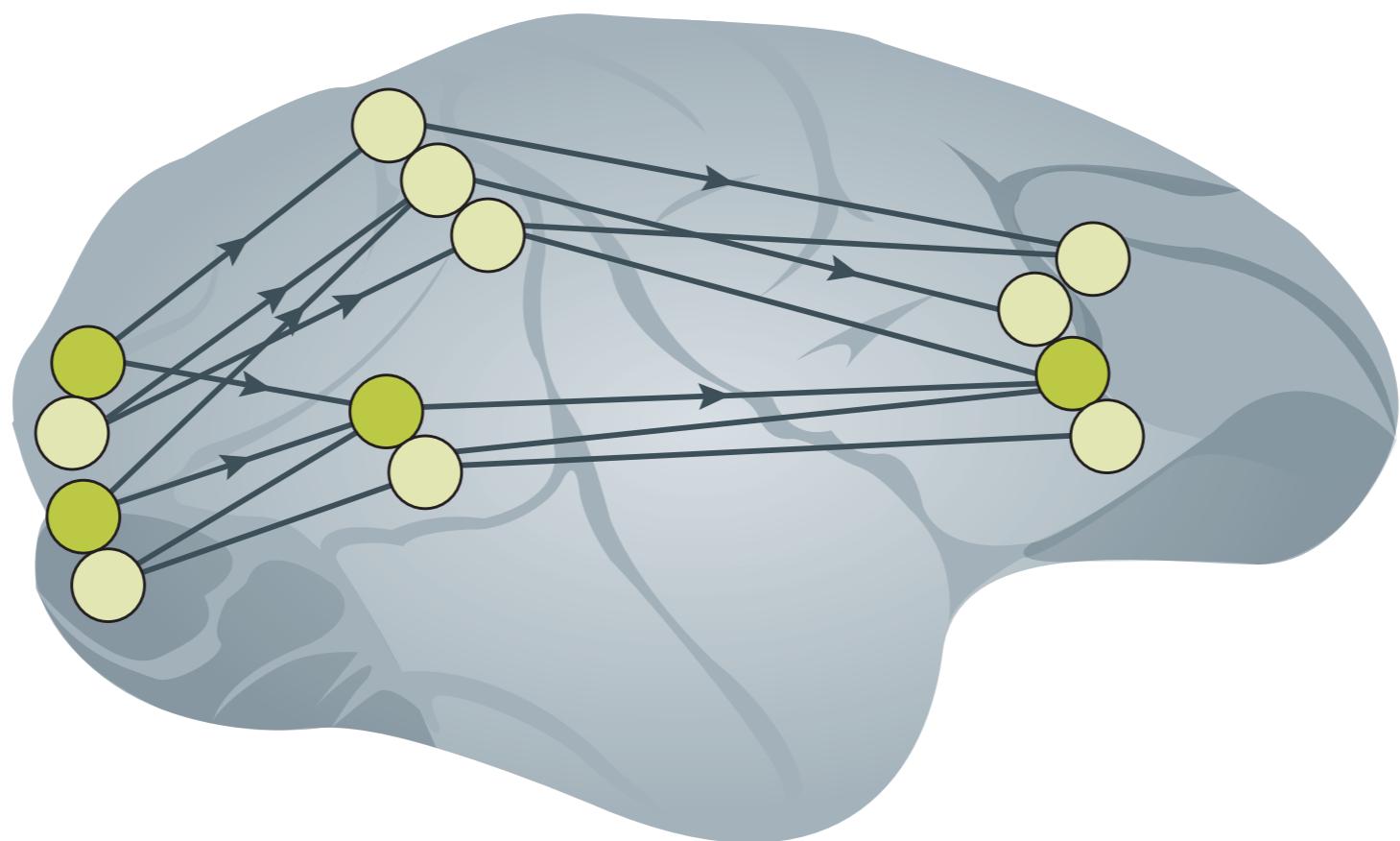
# How does the brain learn to associate visual input with motor output?

Visual input → Prepare movement → Hit (or not) the ball



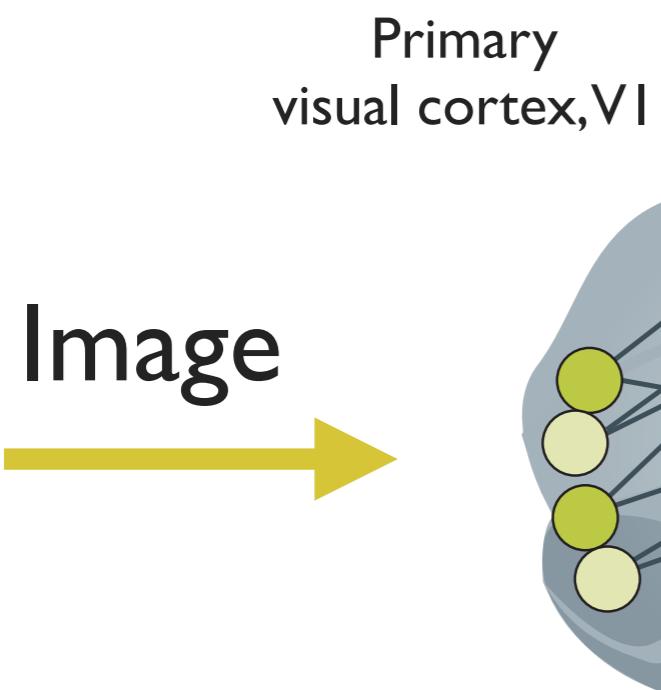
(typically **synapses**)

# How to assign credit to ‘parameters’ in the brain?



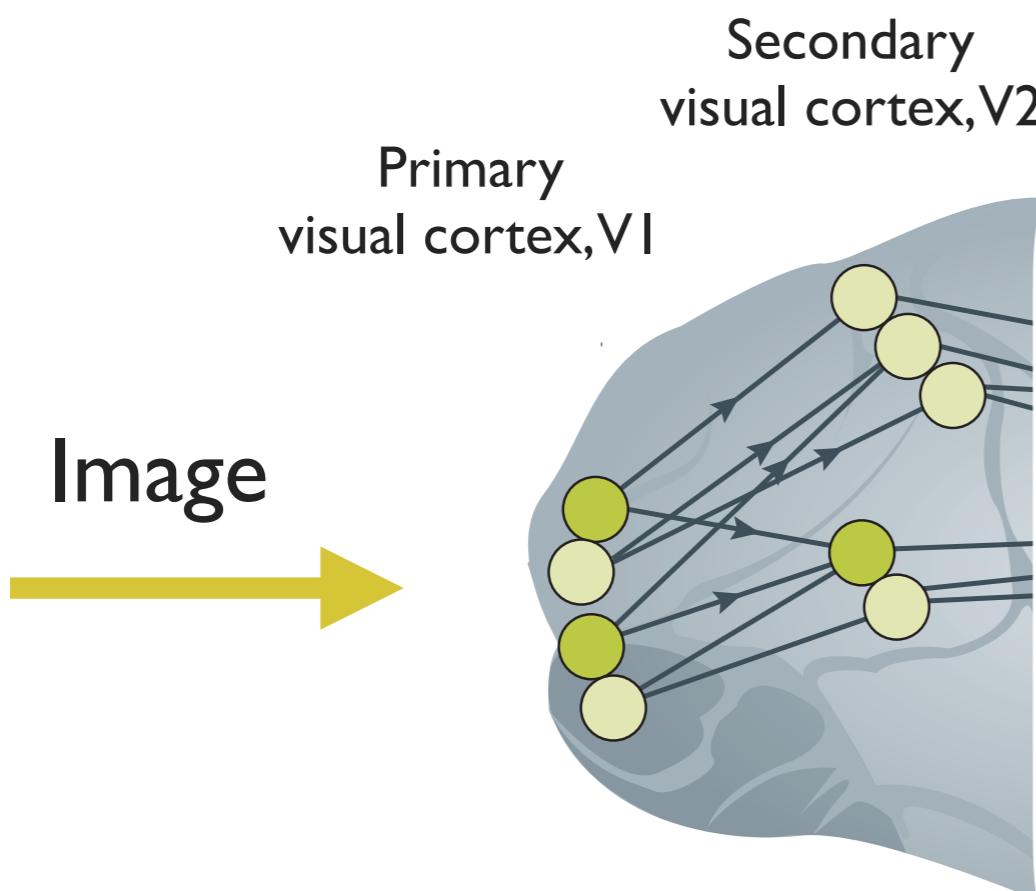
Roelfsema et al. Nature Neuroscience Rev 2018

# How to assign credit in the brain?



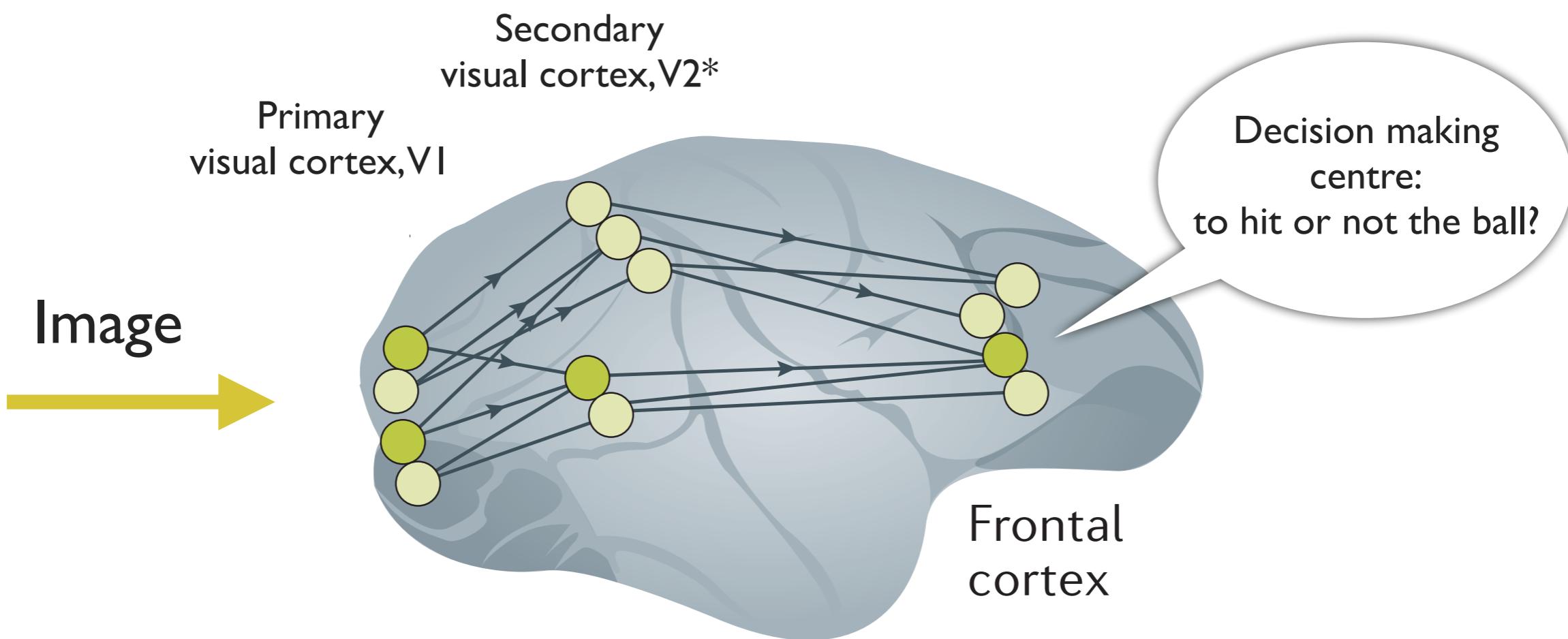
Roelfsema et al. Nature Neuroscience Rev 2018

# How to assign credit in the brain?



Roelfsema et al. Nature Neuroscience Rev 2018

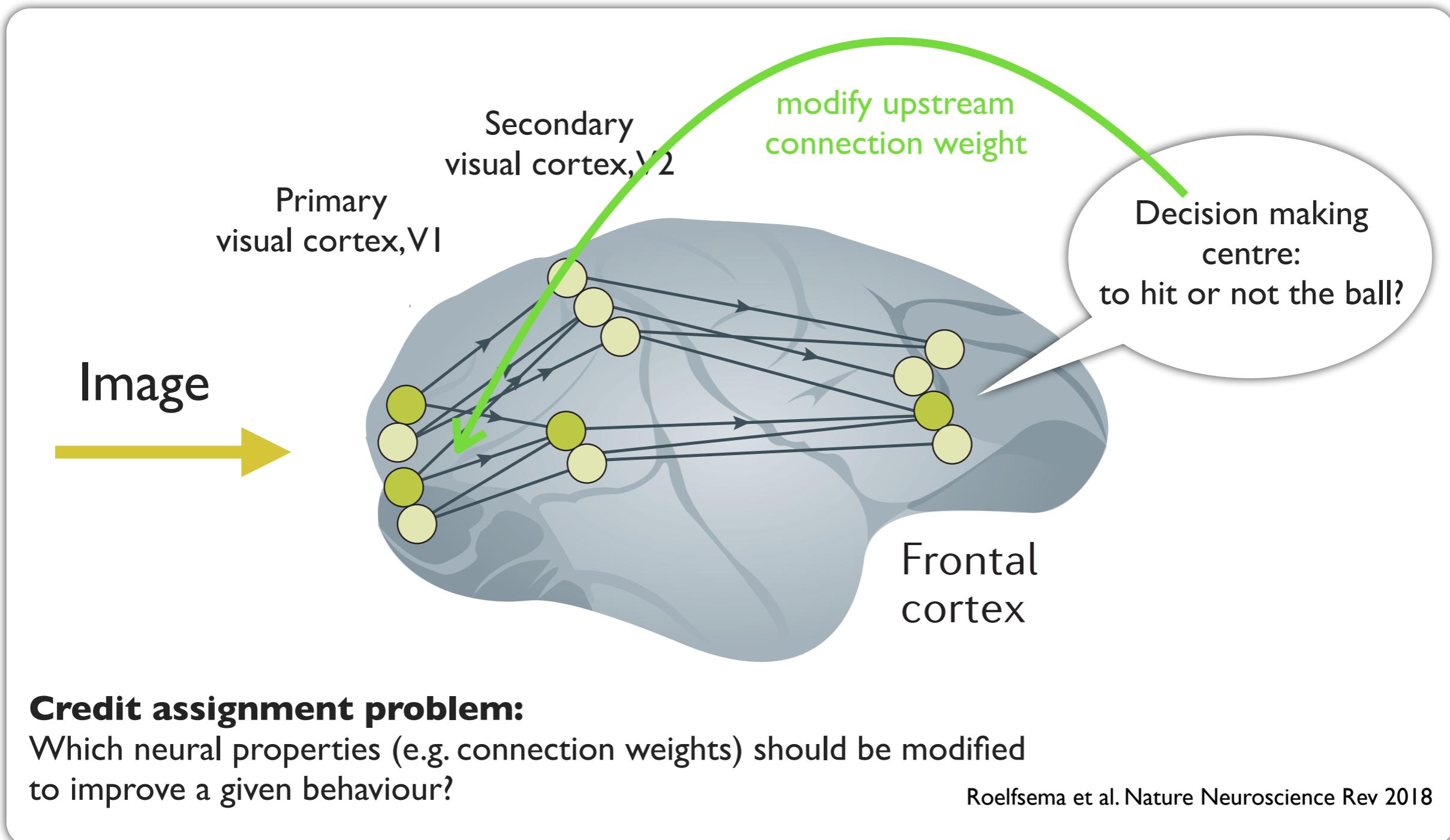
# How to assign credit in the brain?



\*: or associative cortices

Roelfsema et al. Nature Neuroscience Rev 2018

# How to assign credit in the brain?



Three forms of  
*credit assignment*

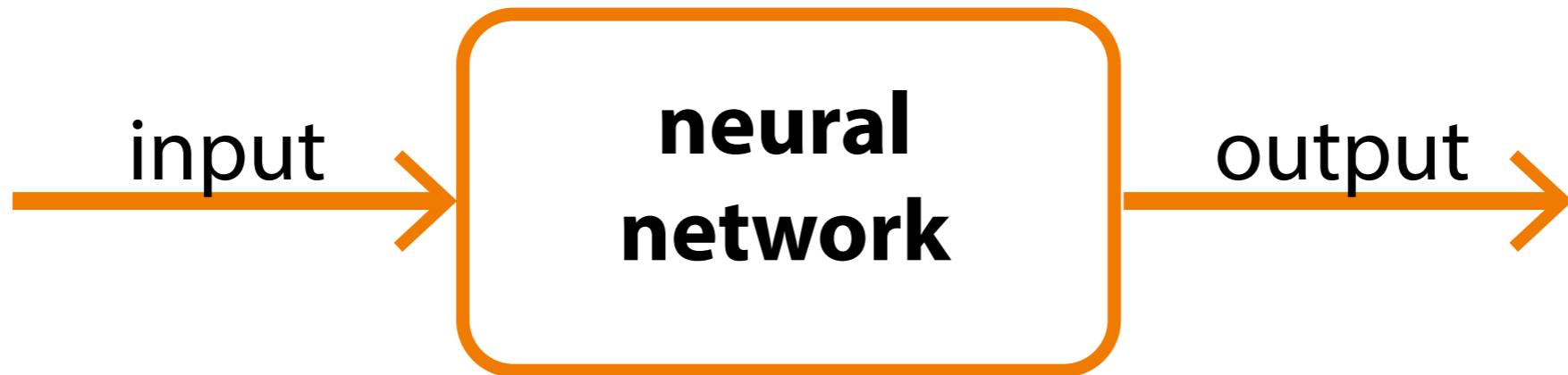
Supervised Learning

Unsupervised Learning

Reinforcement Learning

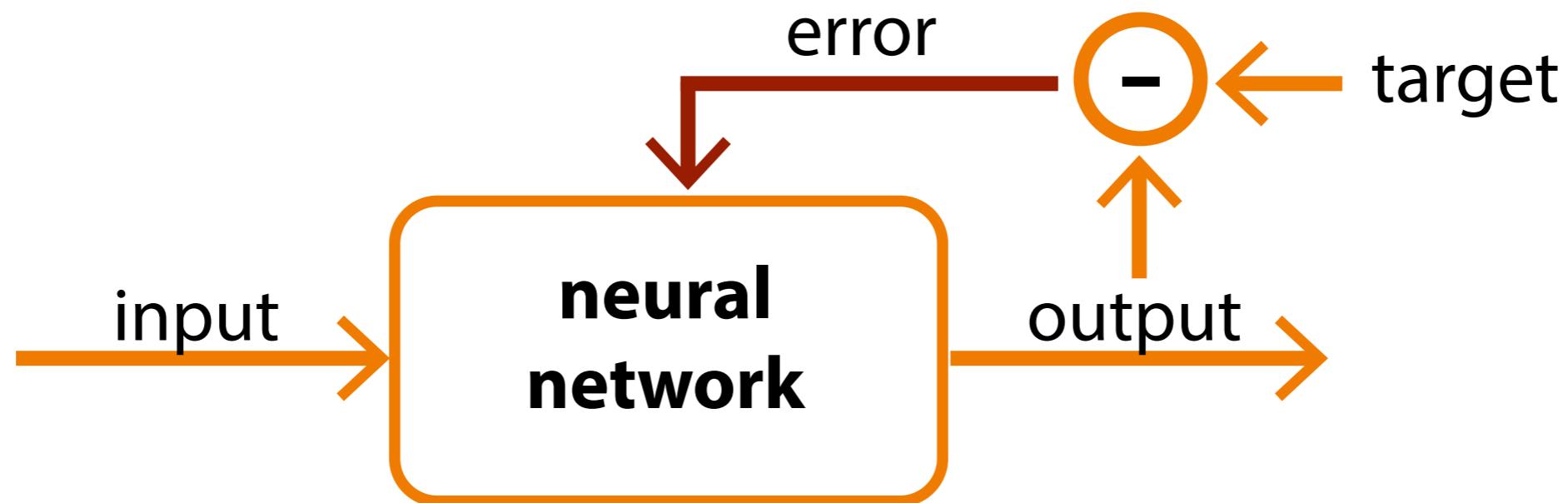
# Three forms of *credit assignment*

**Unsupervised Learning:**  
Extracts useful representations of input



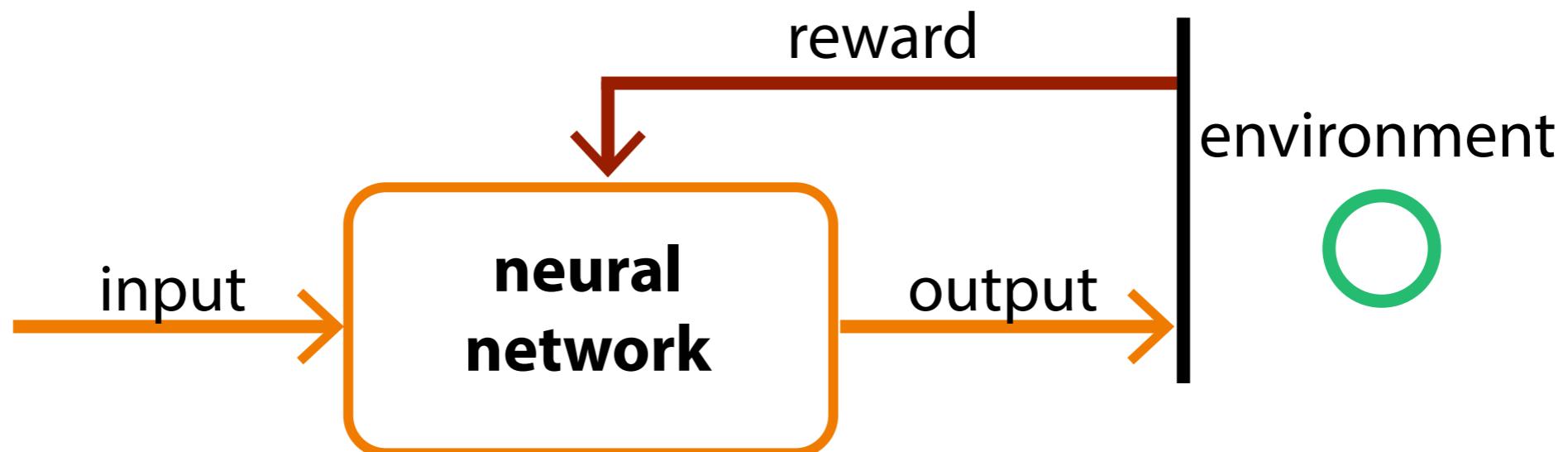
# Three forms of credit assignment

**Supervised Learning:**  
Relies on a teaching signal



# Three forms of credit assignment

**Reinforcement Learning:**  
Learn to navigate/survive an environment



# **Quiz time!**

**Please go to BB  
and solve quiz 1.1.**

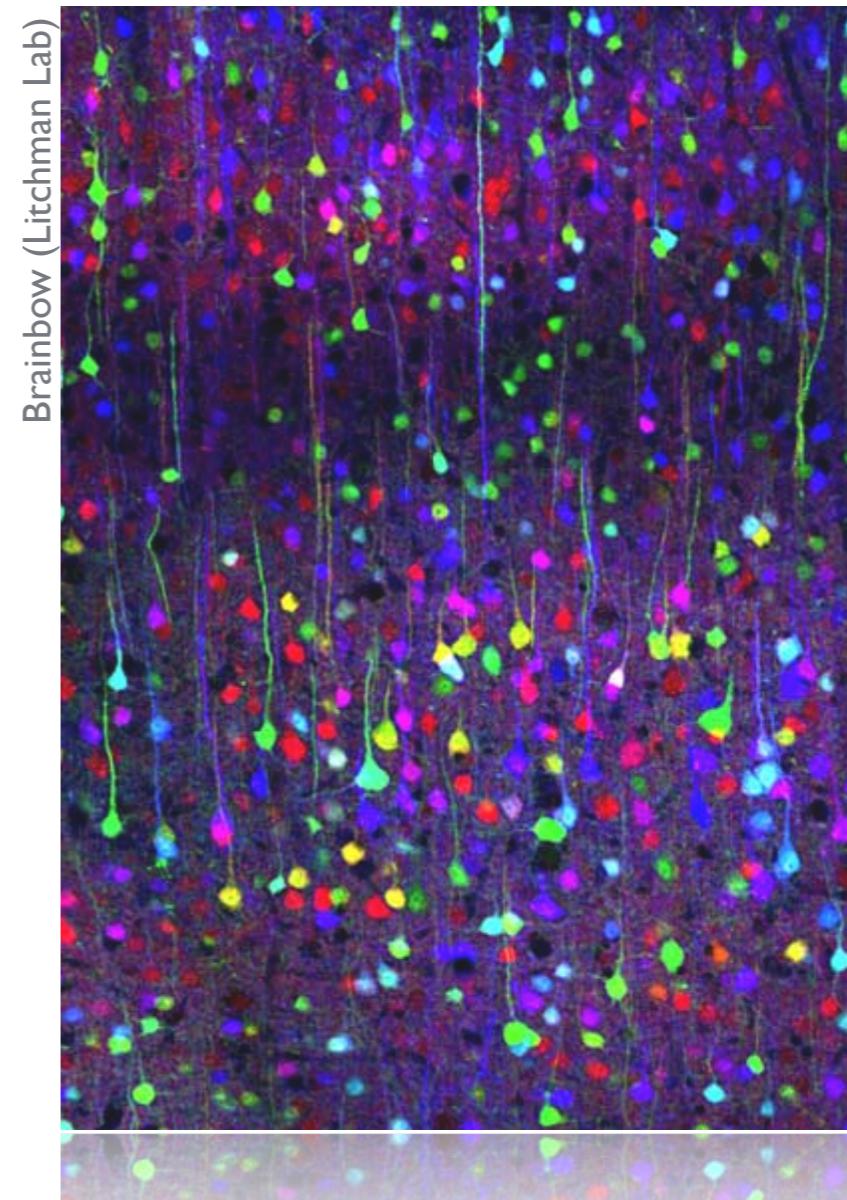
**It should take you just a couple of minutes.**

# A feedforward neural network

The brain is like a tropical forest!

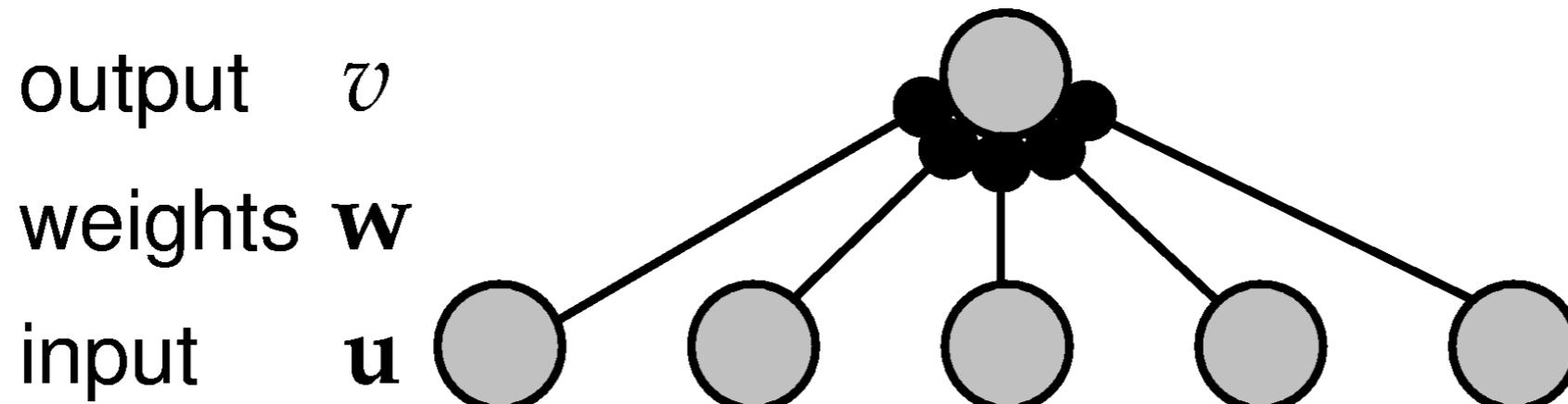
With many different neuron *types*  
and *architectures..*

DeFelipe et al. Nat. Neurosci. Reviews 2013



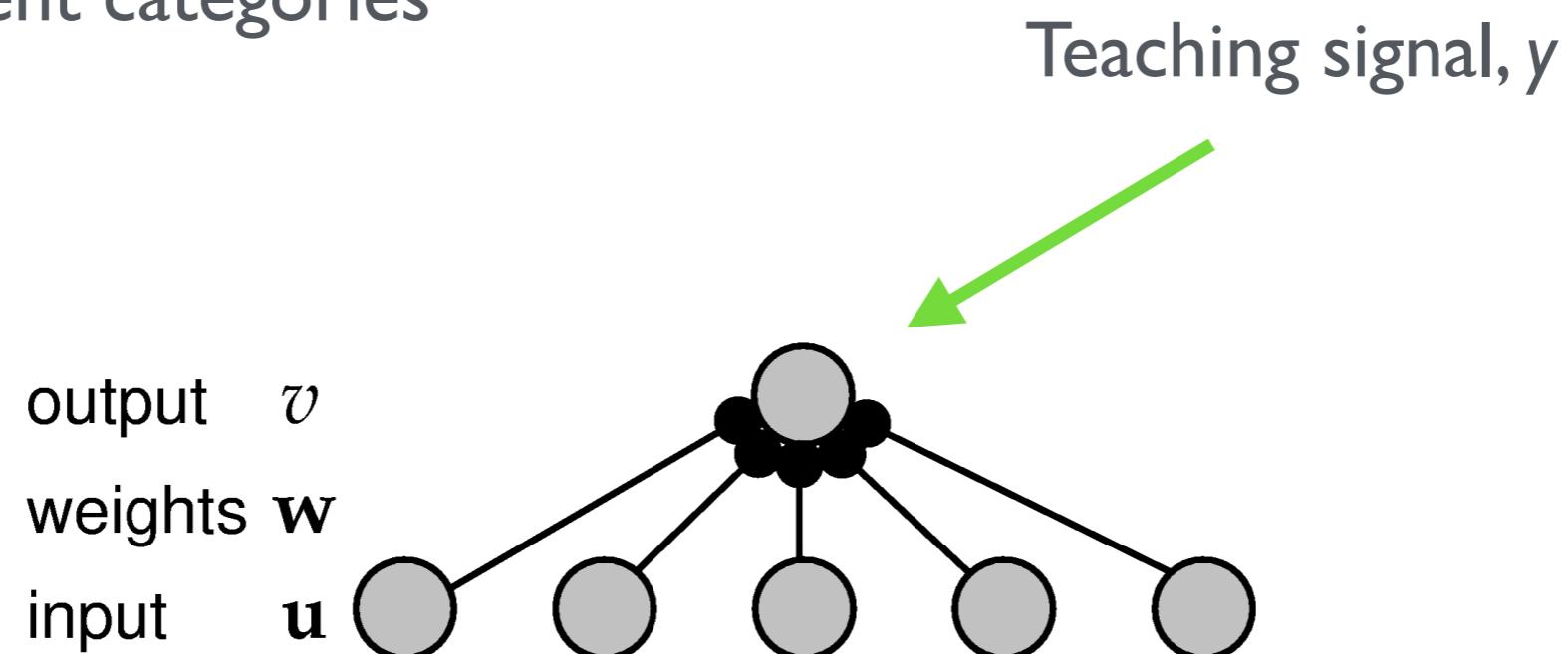
# A feedforward neural network

In theoretical neuroscience we need to abstract out some of this complexity to get at the principles of information processing in the brain!



# Supervised learning

**Goal:** Classify input into different categories



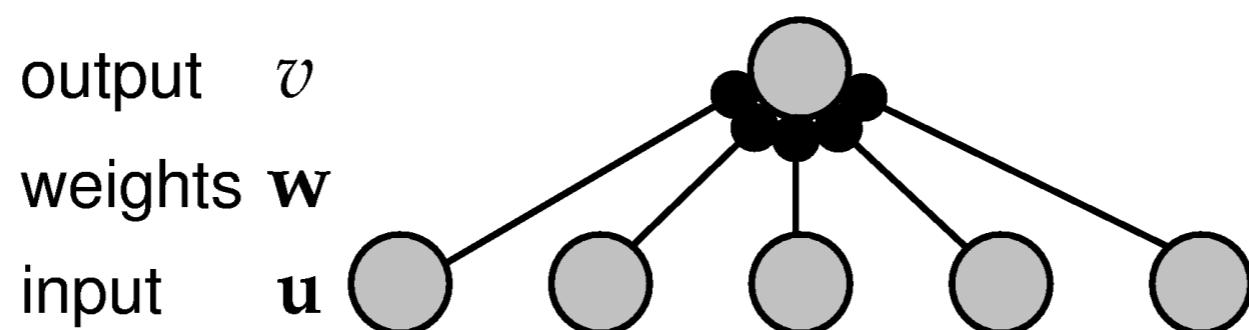
# Supervised learning

output,  $v = f(wu)$

where  $f$  is some (non)linear function

Predator, yes/no?  
 $y = \{1,0\}$

output  $v$   
weights  $w$   
input  $u$

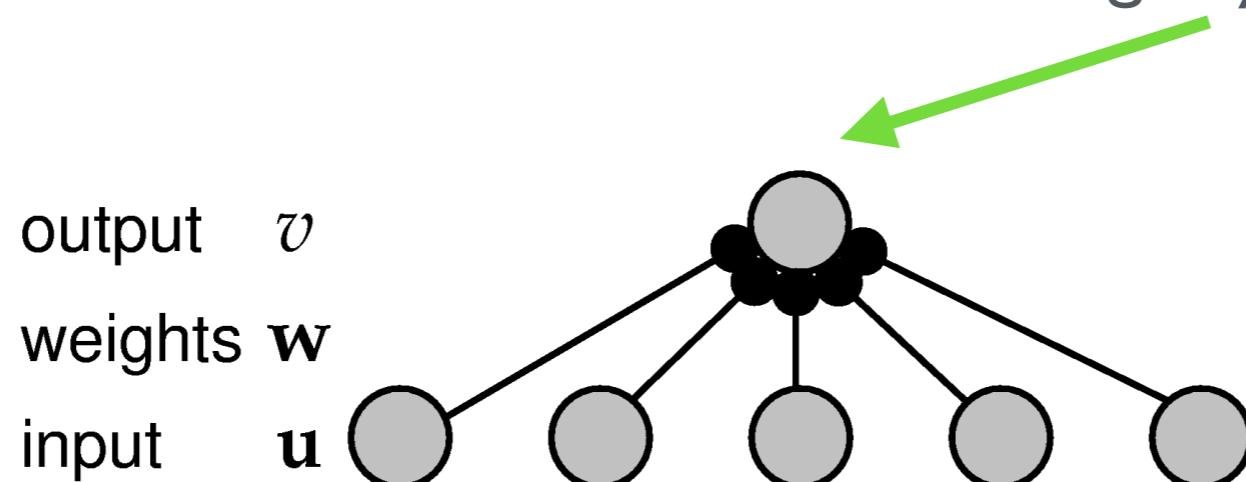


# Supervised learning

Minimise cost

$$\text{cost} = (v - y)^2$$

Predator, yes/no?  
target,  $y = \{1,0\}$



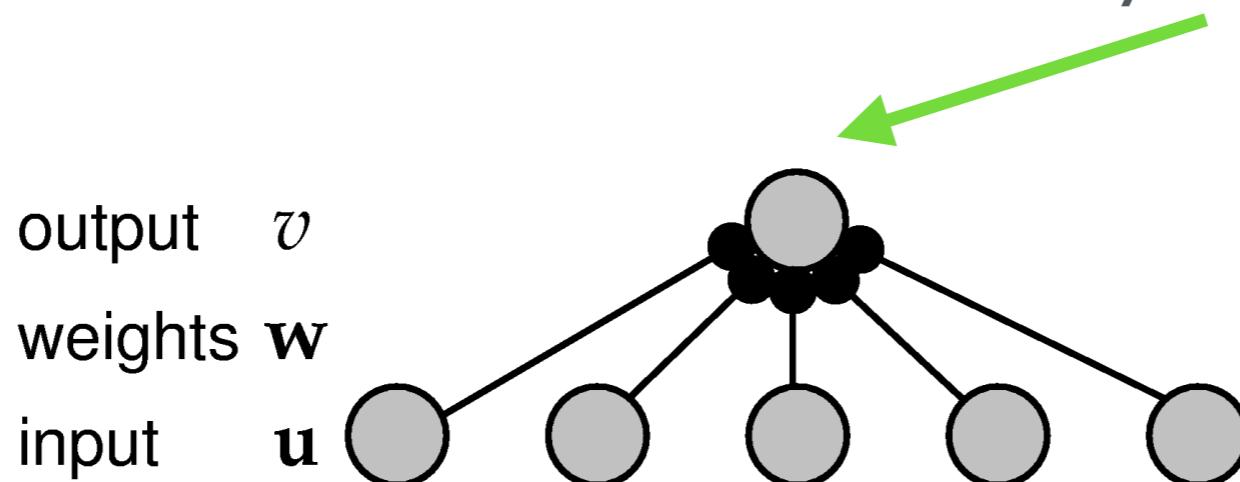
# Supervised learning

Minimise cost

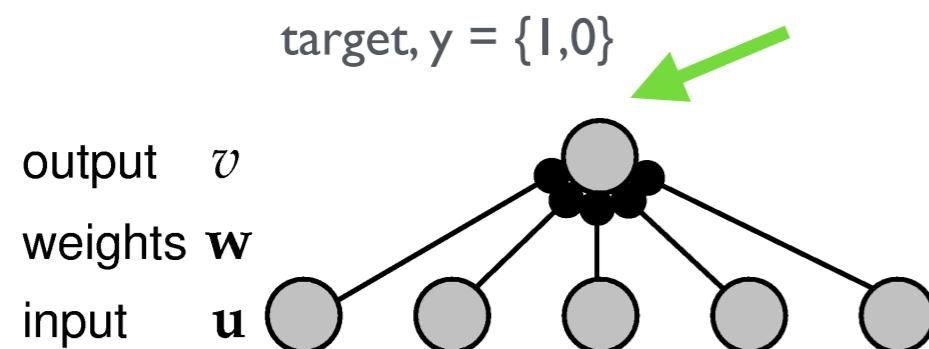
$$\text{cost} = (v - y)^2$$

Predator, yes/no?  
 $y = \{1, 0\}$

output  $v$   
weights  $w$   
input  $u$



# Supervised learning

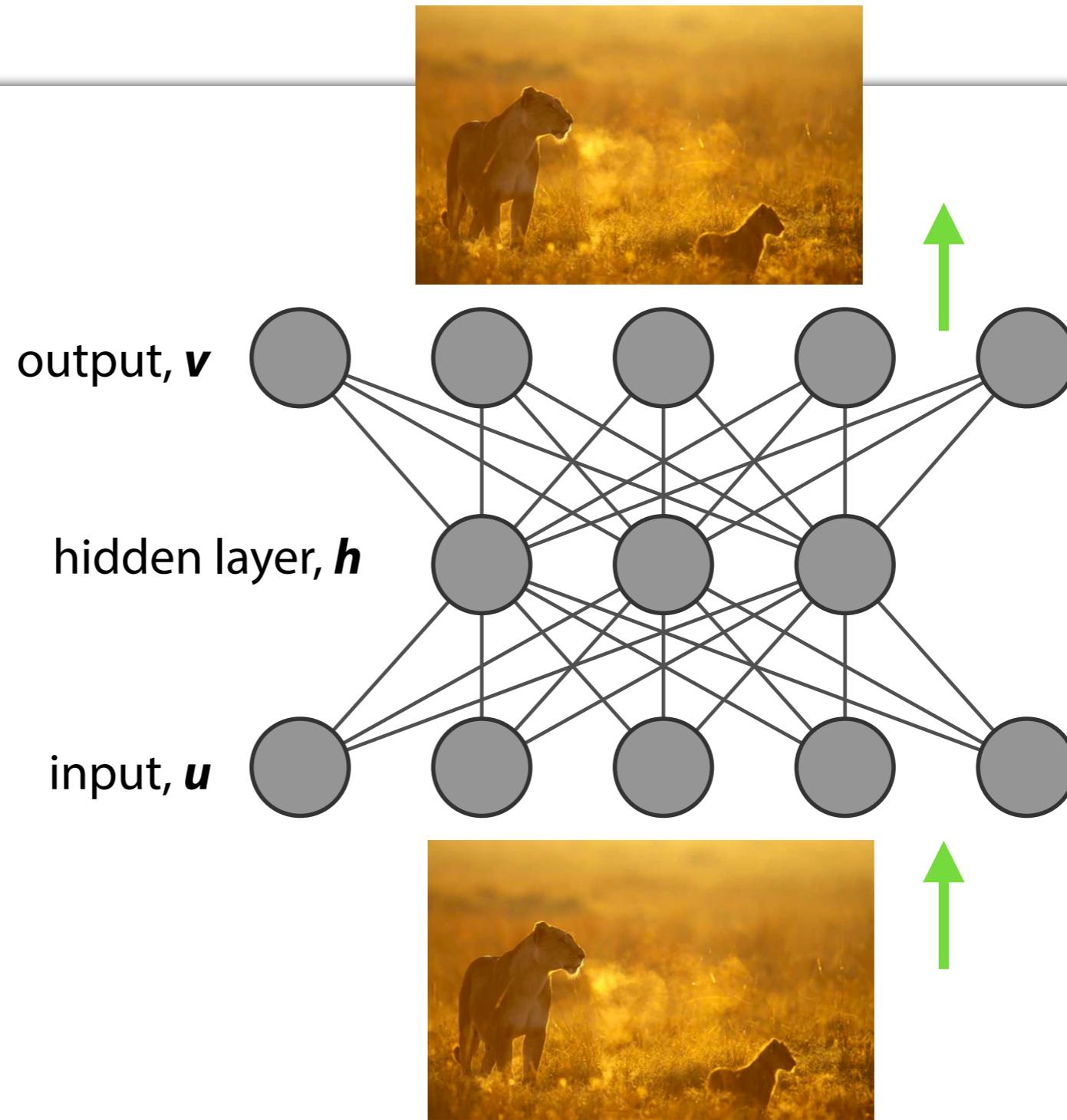


$$\text{cost} = (v - y)^2$$

- The learning rules for  $w$  can be derived from the cost (or error) function for a particular network: e.g. using the popular backpropagation algorithm
- Examples of methods that use supervised learning:
  - Convolutional neural networks
  - Recurrent neural networks
  - Linear regression
  - Animals experience some degree of supervised learning (e.g. with external teacher)

# Unsupervised learning

**Goal:** Extract a representation of the input (dimensionality reduction)

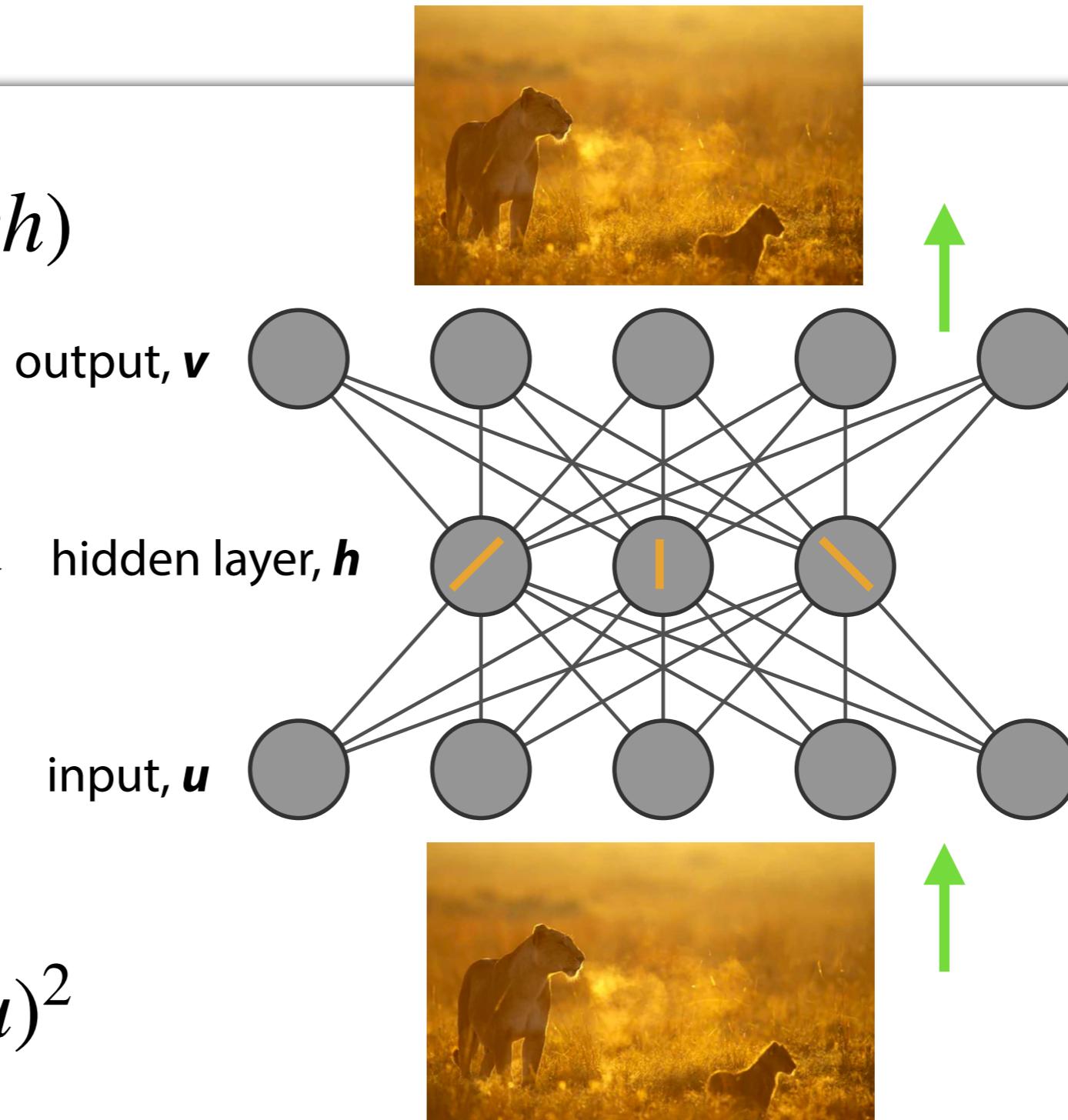


# Unsupervised learning

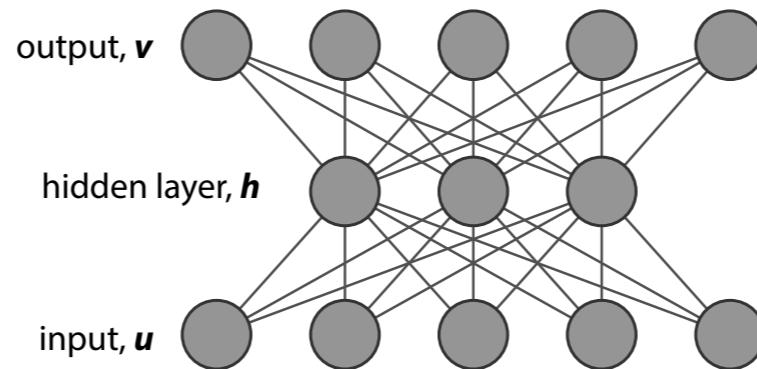
output,  $v = f(wh)$

**Learned  
representation** →  
(e.g. edges)

Minimise cost  
 $\text{cost} = (v - u)^2$



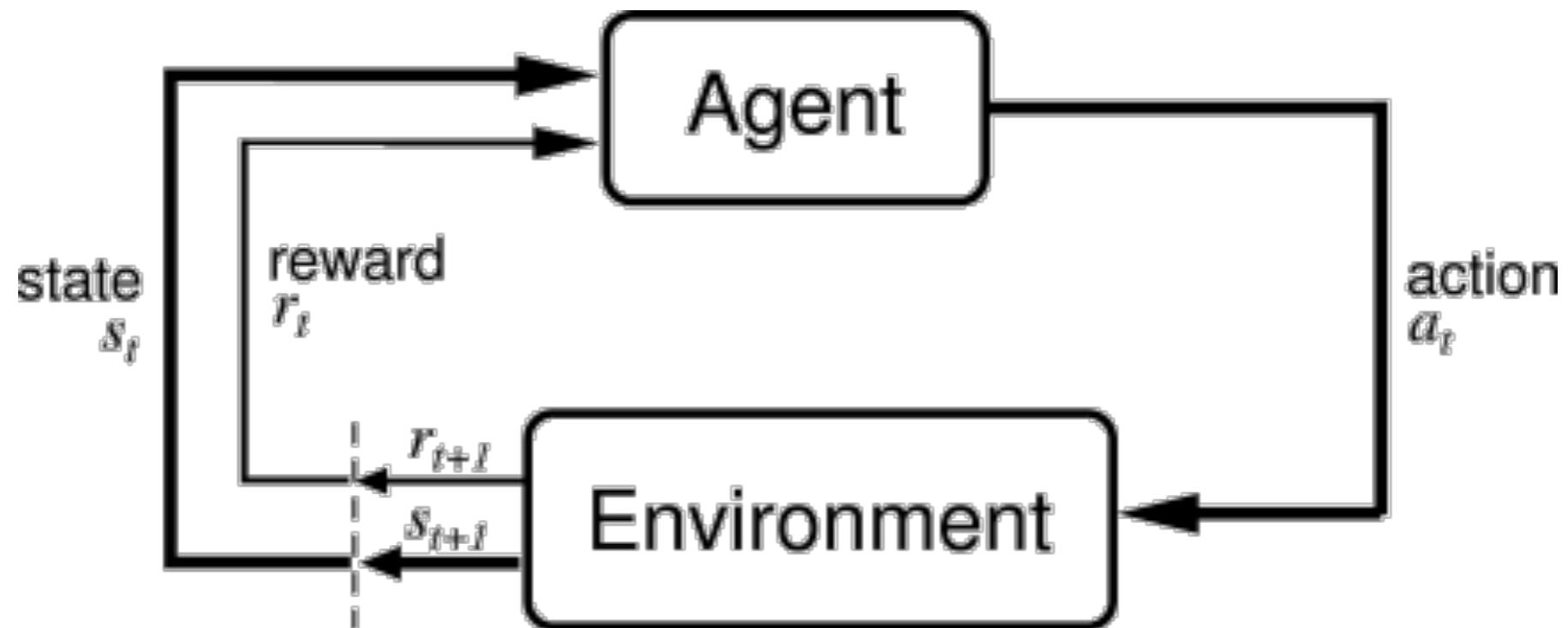
# Unsupervised learning



- The learning rules for  $w$  can be derived from the cost (or error) function for a particular network, e.g. sparse coding algorithm.
- Examples of unsupervised learning methods:
  - Sparse coding (akin to PCA)
  - Restricted Boltzmann Machines
  - Autoencoders
- Animals are bombarded with vast streams of sensory input with no supervisor

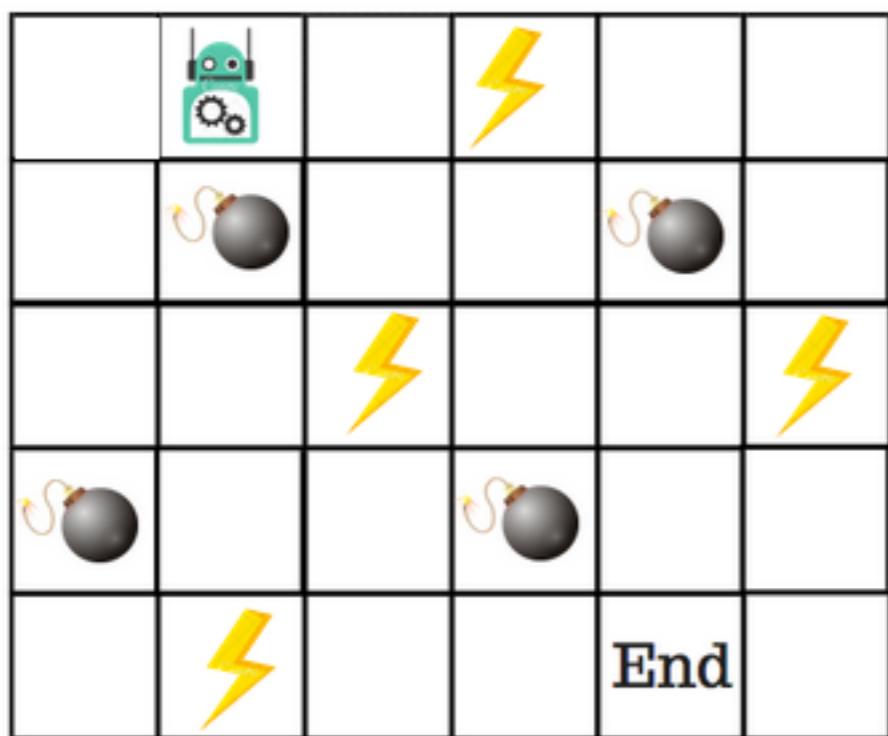
# Reinforcement learning

**Goal:** Find best policy (which actions to take) to maximise reward



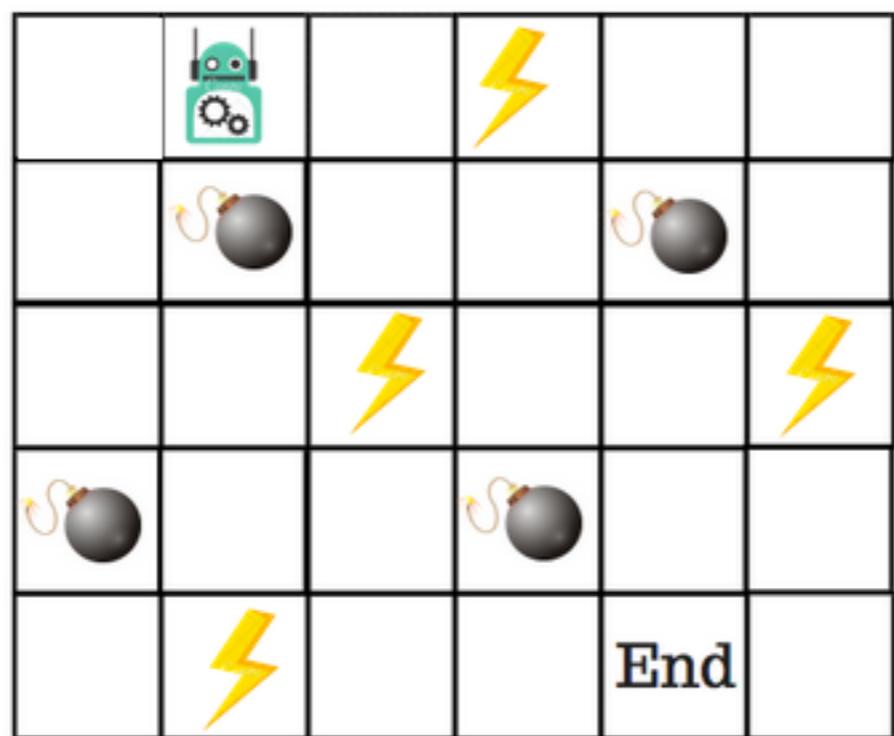
# Reinforcement learning

**Value table/policy**



0.2	0.1	0.1	<b>0.9</b>	0.7	0.5
0.1	<b>0</b>	0.1	0.5	<b>0</b>	0.8
0.5	0.5	<b>1</b>	0.8	0.9	<b>1</b>
<b>0</b>	0.8	0.7	<b>0</b>	0.9	0.9
0.6	<b>1</b>	0.8	0.9	1	0.9

# Reinforcement learning



**Value table/policy**

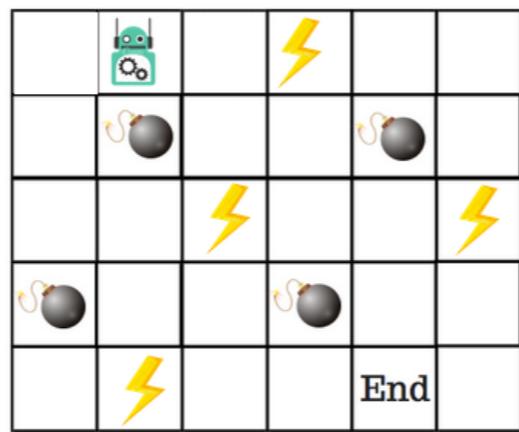
0.2	0.1	0.1	<b>0.9</b>	0.7	0.5
0.1	<b>0</b>	0.1	0.5	<b>0</b>	0.8
0.5	0.5	<b>1</b>	0.8	0.9	<b>1</b>
<b>0</b>	0.8	0.7	<b>0</b>	0.9	0.9
0.6	<b>1</b>	0.8	0.9	1	0.9

Update value table with temporal difference (TD) learning:

$$\underbrace{V(S_t)}_{\text{value}} = V(S_t) + \left( \underbrace{R_{t+1}}_{\text{reward}} + \lambda \underbrace{V(S_{t+1})}_{\text{future value}} \right) - V_t$$

$\lambda$ : discount factor

# Reinforcement learning



0.2	0.1	0.1	<b>0.9</b>	0.7	0.5
0.1	<b>0</b>	0.1	0.5	<b>0</b>	0.8
0.5	0.5	<b>1</b>	0.8	0.9	<b>1</b>
<b>0</b>	0.8	0.7	<b>0</b>	0.9	0.9
0.6	<b>1</b>	0.8	0.9	1	0.9

- The *TD learning equation* enables the agent to gradually learn to predict *future reward* ( $R$ ), based on *value estimates* ( $V_{t+1}$ ).
- Examples of reinforcement learning methods:
  - Temporal difference (TD) learning
  - Q-learning
  - Deep Q-learning
- Because of the role of rewards RL is a common framework in neuroscience

# Different objective/cost functions of learning

## Supervised Learning

$$\text{cost} = (v - y)^2$$

## Unsupervised Learning

$$\text{cost} = (v - u)^2$$

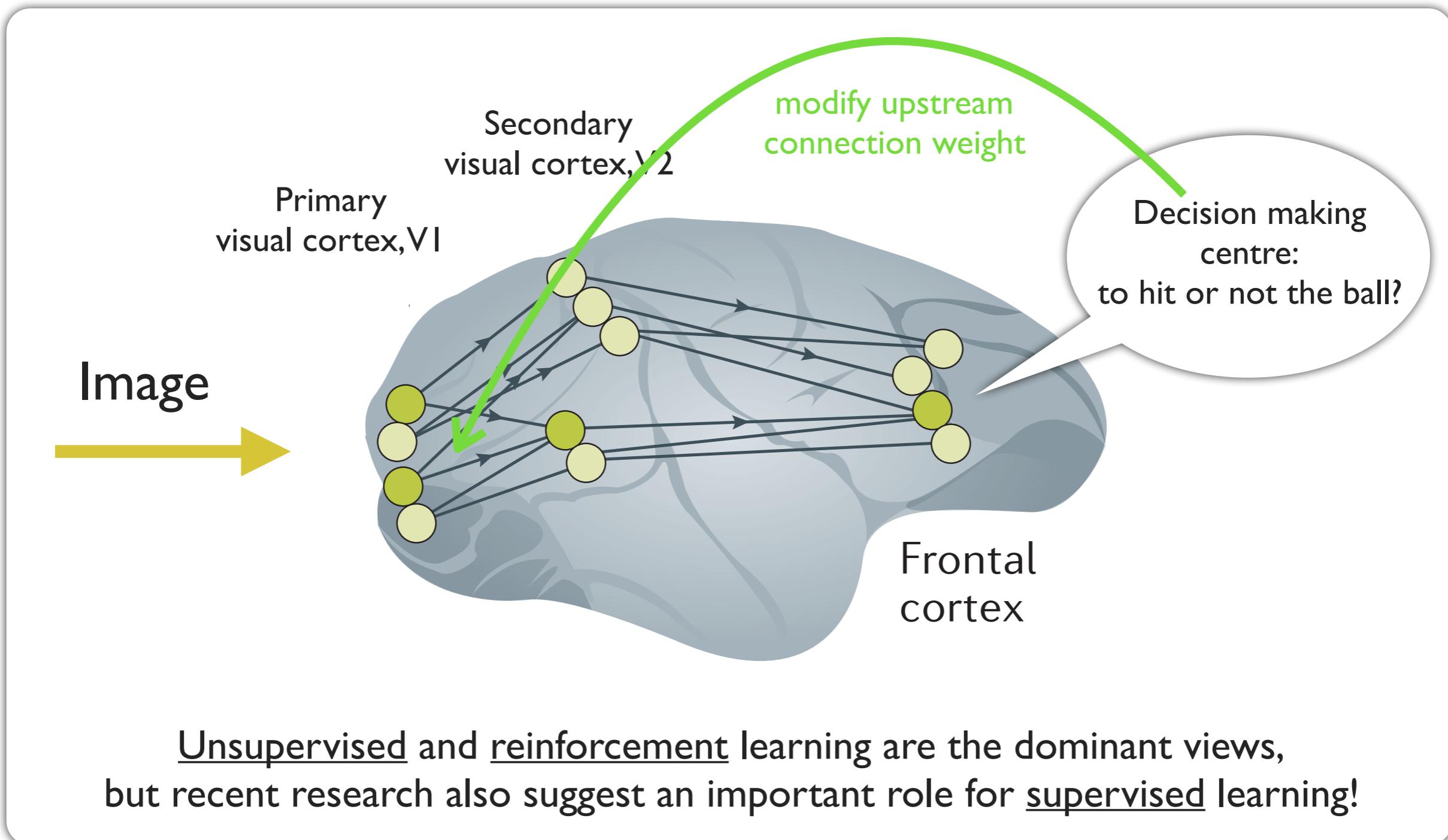
## Reinforcement Learning

$$\underbrace{V(S_t)}_{\text{value}} = V(S_t) + \left( \underbrace{R_{t+1}}_{\text{reward}} + \lambda \underbrace{V(S_{t+1})}_{\text{future value}} \right) - \underbrace{V_t}_{\text{learned value}}$$

# Summary

- Different forms of learning (or credit assignment) in the brain
- Supervised, unsupervised and reinforcement learning

# How to assign credit in the brain?



# Questions?

[reddit.com/r/comsm0075/](https://reddit.com/r/comsm0075/)

# References

## **Text books:**

General theoretical neuroscience: Dayan and Abbott, Principles of Neuroscience (Chapter III)

Deep Learning by Courville, Goodfellow and Bengio

Reinforcement Learning: Sutton & Barto, Reinforcement Learning: An Introduction (see online the newer 2018 edition)

Others: Mackay book on Information Theory, Inference and Learning; Rumelhart and McClelland, Parallel Distributed Processing books

## **Relevant papers:**

- Roelfsema and Holtmaat, Nature Neuroscience Reviews 2018 (recent review on the credit assignment problem)
- Olshausen and Field, Nature 1996 (seminal paper on sparse coding)
- Schultz et al. Science 1997 (seminal paper on neural substrates of reinforcement learning)

# Next lecture..

- L1<sup>[4]</sup>: Neural circuits and learning: introduction
- L2<sup>[4]</sup>: **Supervised learning & backprop**
- L3<sup>[5]</sup>: Visual system: deep learning?
- L4<sup>[5]</sup>: Reinforcement learning
- L5<sup>[6]</sup>: Unsupervised learning
- L6<sup>[6]</sup>: Temporal processing
- L7<sup>[7]</sup>: Recurrent neural networks
- L8<sup>[7]</sup>: Guest lecture