

3ba2 Artificial Intelligence

Non-deterministic Turing machines in Prolog

Marks will be awarded for this exercise. Due by Th, Dec 9, 2004 (at lab).¹

A *non-deterministic Turing machine* (*nTm*) *M* is specified by four finite lists, `move-right`, `move-left`, `write-list`, `halt-list` where

- `move-right` is a list of triples `[Q0,X,Q]` saying:
from state `Q0`, reading symbol `X`, move one square right, and go to state `Q`
- `move-left` is a list of triples `[Q0,X,Q]` saying:
from state `Q0`, reading symbol `X`, move one square left, and go to state `Q`
- `write-list` is a list of quadruples `[Q0,X,Y,Q]` saying:
from state `Q0`, reading symbol `X`, write symbol `Y` and go to state `Q` (keeping the head still)

and

- `halt-list` is a list of pairs `[Q0,X]` saying:
from state `Q0`, reading symbol `X`, halt.

Let us assume that every *nTm* *M* has initial state `q0`, and let us write `b-k` for blank (a symbol indicating an empty tape cell). Let us agree that *M* falls into a loop from which it can never halt, if it should ever be at a state `Q0` reading symbol `X` such that none of its four lists specifies a next step.

Your task is to define a predicate

```
nTm(+move-right,+move-left,+write-list,+halt-list,+input,?output)
```

such that the *nTm* specified by `move-right`, `move-left`, `write-list` and `halt-list` may halt with tape content `output`, given tape content `input` (and initial state `q0` with the head at the leftmost symbol of `input`). Let us assume without loss of generality that `input` is a non-empty list, using the list `[b-k]`, if necessary, to represent the empty string. As for the output string, on the other hand, let us arrange that it never begins or ends with a blank (so that for example the list `[b-k]` is rewritten as `[]`, and `[b-k,a,b-k,b,b-k]` as `[a,b-k,b]`).

Hint

Take “snapshots” `[L,R,Q]` of a run of a *nTm*, where

- `L` lists the non-blank tape contents to the left of the *nTm* head (in reverse)
- `R` lists the non-blank tape contents to the right of the *nTm* head, including the currently scanned cell (the head of `R`)

¹You are strongly encouraged to have your solution marked before then. Email submissions to Tim Fernando will receive an F3.

- Q is the current nTm state.

Search through a graph with nodes [L,R,Q], the children of which arise from a single nTm step.

A query

nTm(MR,ML,WL,HL,Input,Output)

sets the **start node** (the root of the computation tree) to [[] ,Input,q0].

Sample runs

```
| ?- nTm([], [], [], [[q0,X]], [b-k,i,n,b-k,p,u,t,b-k,b-k], Out).  
X = b-k,  
Out = [i,n,b-k,p,u,t] ? ;  
no
```

```
| ?- nTm([[q1,1,q2],[q1,0,q2],[q1,b-k,q2]], [],  
        [[q0,0,1,q1], [q2,0,b-k,q1]],  
        [[q1,b-k]],  
        [0,0,0,0,0],  
        Out).
```

```
Out = [1,b-k,0,0,0] ? ;  
Out = [1,b-k,b-k,0,0] ? ;  
Out = [1,b-k,b-k,b-k,0] ? ;  
Out = [1] ? ;  
no
```

```
| ?- nTm([[mr1,h,we],[mr1,e,w1],[mr1,l,wp],[mr1,p,hbk],  
        [mr,l,wo],[mr,o,wo],[mp,o,wp]],  
        [[q0,0,lbk],[lbk,b-k,lbk]],  
        [[q0,0,h,mr1],[we,1,e,mr1],[w1,0,1,mr1],[wp,1,p,mr1],  
        [q0,0,1,mr],[wo,1,o,mr],[wo,0,o,mp]],  
        [[hbk,b-k]],  
        [0,1,0,1],  
        Output).
```

```
Output = [h,e,l,p] ? ;  
Output = [l,o,o,p] ? ;
```

<loops>