

18.5 L1 Trot technology - Lecture Notes

Typeset by Esko de Vries

October 3, 2001

.4.4	Technique of integration	18
.4.5	General tip on performing integration	19
.4.6	Differential equation	19
.4.7	Terminology	20
.4.8	Solving differential equation	21
.4.9	Application of differential equation	2
4	Physics Review	25
4.1	Part A - Mechanic	25

8.11.2	Average Power	74
8.11	Root Mean Square Current and Voltage	74
8.11.4	Complex Power	75
8.11.5	Power Factor	76
8.11.6	Power factor correction	76
8.12	Phasor Diagram	77
8.12.1	The Power Triangle	77
8.1	The maximum power transfer theorem	80
8.14	Resonant circuit	81
8.14.1	Background	81
8.14.2	The series resonant circuit	82
8.14	The Quality Factor Q	82
8.14.4	Impedance vs. Frequency	83
8.14.5	Variation of V_R , V_L and V_C with frequency in a series RL circuit	84

9 Transient Analysis of RC and RL

Chapter 1

About this document

This document contains all the lecture notes of the 1BA5 of Computer Science, BA., Trinity College, Dublin, as lectured by Dr. O'Nuallain. The notes are a literal representation of the notes given in class, including diagrams, graphs and circuits.

Note that the course overview in the first chapter is not actually correct. This is because the course structure was changed halfway through the course. But since this document is a direct copy of the notes, this inconsistency is still visible in this document. Never mind ;)

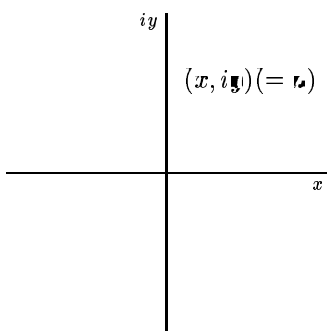
This document has been created using LaTeX for the typesetting, GNUPlot for the graphs and M4

2.5 Section V - Electric Circuit Components

1. Resistor
2. Capacitor
3. Inductor
4. Transformer
5. Semiconductor diode and transistor

2.6 Section VI - Electric Circuits

1. DC circuit



3.1.1 The coordinates

Let $x = r \cos \Theta$, $y = r \sin \Theta$; $r = |z|$, then

$$\begin{aligned} z &= x + iy = r \cos \Theta + ir \sin \Theta \\ &= r(\cos \Theta + i \sin \Theta) \end{aligned}$$

3.3. Multipli ation of a matrix by a s alar

$$A + A + A + A + A = 5A.$$

Given a real number $k \in \mathbb{R}$ and a matrix (a_{ij}) we define kA to be the $m \times n$ matrix where the entries are (ka_{ij}) .

3.3.7 Properties of s alar multipli ation

$k \in \mathbb{R}$, A, B are $m \times n$ matrices

1. Closure: kA is an $m \times n$ matrix
2. Distributive: $k(A + B) = kA + kB$ (Also: $(k_1 + k_2)A = k_1A + k_2A$)
3. Associative: $k_1(k_2A) = (k_1k_2)A$
4. $1 \cdot A = A$

3.3.8 Matrix multipli ation

If A is $m \times n$ and B is $n \times k$, multiplication of A and B goes as follows :

Example $A: 2 \times 3$, $B: 3 \times 3$

$$A = \begin{pmatrix} 1 & 2 & 4 \\ 0 & 1 & -5 \end{pmatrix}, B = \begin{pmatrix} 6 & -1 & 4 \\ 0 & 2 & 4 \\ 1 & 1 & - \end{pmatrix}, \text{ then:}$$

$$AB =$$

$$\frac{d}{d}$$

This equation describes the oscillation of a body on a spring where m is the mass of the body, C the damping constant, k the spring modulus at rest.
 $F(t)$

Note If $f(x, y)$ is homogeneous, then $f = \left(\frac{x}{x}, \frac{y}{x}\right) = f\left(1, \frac{y}{x}\right) = f(1, u)$

The equation then becomes $x \frac{dv}{dx} + v = f(1, u)$, which can be written in separable form:

$$\frac{dv}{dx} = \frac{1}{x} \left\{ f(1, u) - v \right\}$$

which can be solved using previous method.

Example 2

Application II - the RC circuit

Setup:

|

Chapter 4

Systems in Equilibrium

For a discussion on the physics section, see:

Senior Physics
by George Porter

4.1 Part A - Mechanics

Example It takes 10 times the force to move object A from rest as it does to move object B (in the same environment). Hence the mass of object A is 10 times that of object B.

Example

Law II

When a resultant external force acts on a body, the rate of change of the body's momentum is proportional to the force and takes place in the direction of the force.

Law III

In any interaction between two bodies A and B, the force exerted by A on B is equal in magnitude

Why with a constant acceleration and not with constant velocity?

Note Read

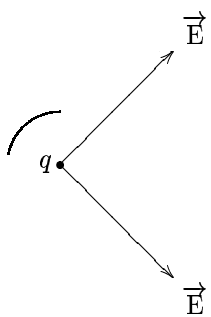
Chapter 5

El tr

■.1.3 Definitions

W

When charge move they exert a force on one another. Another way of looking at this phenomenon



Diagram

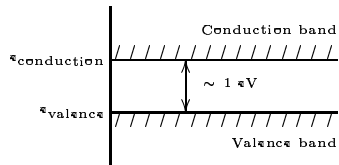
$$(0) \qquad B_a \ B_{\mathfrak{y}} \ (x)$$

$$\leftarrow \qquad x \qquad \rightarrow$$

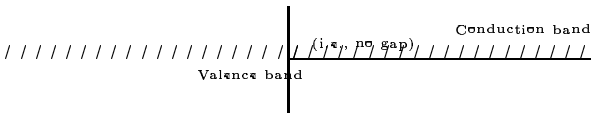
N

Chapter 6

Semi-conductors



Conductors



3.2 Semi- conductor doping

Process known as dopin

Chapter 7

Electrical Circuit Components

7.1 Introduction

7.1.1 Current

Definition The current $i(t)$

2 The Resistor

A resistor is a two-terminal element which impedes the flow of electric current through it by converting some of the electrical energy into heat. The degree to which it impedes the current flow is characterized by its resistance. Every material possesses this property to some extent. The relationship between the terminal voltage of a resistor and the current flowing through it is given by Ohm's Law:

$$v(t) = Ri(t)$$

This implies

(1468 0 4

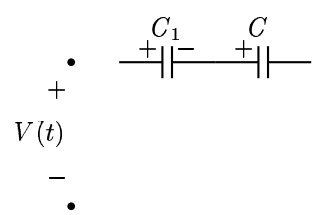
$$p_{\text{wire}} = \frac{V(t)}{R_{\text{wire}}}$$

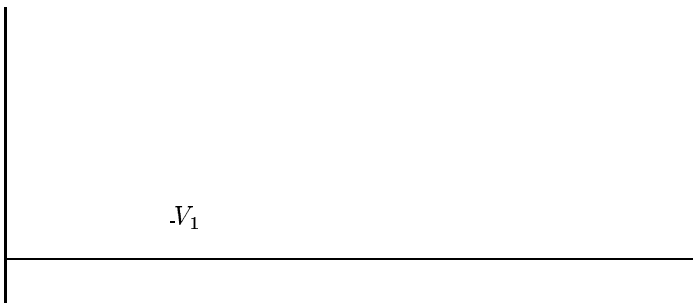
which seem to contradict the second suggestion above. However, it doesn't. $V(t)$ is the potential difference between the positive and negative terminal, i.e. across the wire

7.2.2 The Potential Divider

An important application of resistors is the potential divider. It is used to obtain a

$$C = \epsilon^{\overline{A}}$$





$$\begin{aligned}
 \text{Let } V(t) &= V_m \cos(\omega t + \varphi) \\
 i(t) &= C \frac{dv}{dt} \\
 \text{or } i(t) &= -C\omega V_m \sin(\omega t + \varphi) \\
 &= C\omega V_m \cos(\omega t + \varphi + \frac{\pi}{2}) \\
 &= I_m \cos(\omega t + \varphi + \frac{\pi}{2})
 \end{aligned}$$

Diagrammatically:

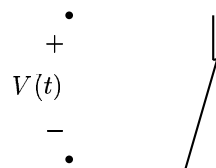
V_m

throughout.

Then: $L_T = \frac{di(t)}{dt} = L_1 \frac{di(t)}{dt} + L_2 \frac{di(t)}{dt} + \cdots L_n \frac{di(t)}{dt} \therefore L_T = L_1 + L_2 + \cdots + L_n$

Inductors in parallel

Consider the following setup:



The forward characteri

.6 Transformers

One of the main ad

In practice sources are not id

Convention

You will have noticed the alignment of the positive and negative terminal to the resistor in the above circuit. We note that electrical current is deemed to flow from the positive terminal of the source to the negative terminal.

to a

$$V_{NW} = V_s - I_{sv}$$

$$V_{NW} = (I_s - I)_{sI}$$

For the two equa

$$\begin{aligned}
 V(t) &= V_m \cos(\omega t + \varphi); V_m \in \mathbb{R} \\
 &= \operatorname{Re} \{ V_m e^{j(\omega t + \varphi)} \} \quad (\text{from Euler's formula } (j = \sqrt{-1})) \\
 &= \operatorname{Re} \{ V_m e^{j\varphi} e^{j\omega t} \} \\
 &= \operatorname{Re} \{ \hat{V} e^{j\omega t} \}
 \end{aligned}$$

$\hat{V} = V_m e^{j\varphi}$ is referred to as a *phasor*.

For simplicity, we can ignore the $\operatorname{Re}\{\}$ notation and simply describe the supply voltage in the above circuit as $V(t) = \hat{V} e^{j\omega t}$.

Note The unit assigned to all impedance is the Ohm (Ω).

8. Impedance Series and Parallel

It is easily shown from the formulae for a parallel combination of impedances that

3.3.1 Procedure to get Thévenin's Equivalent Circuit

1. Remove the load impedance and mark the terminal a and b
2. Calculate R_{TH} or V_{TH} by setting all

Answer (the Thévenin e

$$\begin{aligned}
Z_{TH} &= 500\Omega || -j1500\Omega \\
&= \frac{(500\angle 0^\circ)(1500\angle -90^\circ)}{500 - j1500} \\
&= \frac{7.5 \cdot 10^5 \angle -90^\circ}{1581\angle -71.57^\circ} \\
&= 474.8\angle -18.4^\circ \Omega \\
&= 450 - j150\Omega \quad (\text{in polar representation of complex num})
\end{aligned}$$

Example (D. .) Find the current through the 2Ω res

5.11.2 Nodal Analysis

Procedure

1. Define all node using independent variable taking one as reference (0)
2. A

5.11.1 Power Factor

The power factor p.f

From K. .L.:

$$\hat{i} = \hat{i}_c + \hat{i}_L$$

Also:

$$\hat{i}_c = j\omega C\hat{V}$$

$$\hat{i}_L = \frac{\hat{V}}{R + j\omega L}$$

(Multiply by complex conjugate of the denominator)

8.1 The maximum power transfer theorem

o

$$R_L = R_T \therefore V_L = \frac{V_T}{2}$$

$$P_{L,matched} = \frac{V_T^2}{4R_L} = 0.0125V_T^2$$

Hence the power increase with impedance matching would be $\frac{0.0125 - 0.0278}{0.0125} =$

From the plot of i v. f we note there is a range of frequencies about f_s where the current is near its maximum. These frequencies are (f_1, f_2)

Chapter 9

Transient Analysis of RC and RL Circuits

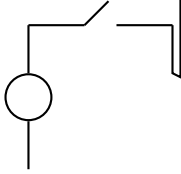
Tran

9.1.1 Charging phase of an RC circuit

Apply K



Sparking at the switch can be prevented by having the circuit set up a :



In x

A.

- Zener, 54
- Di placement, 22
- Doping, 40
- Dynamic resistance
 - Of diode , 54
- Electric Di placement Vector, 29
- Electron , 25
 - Max. number of in a cell, 26
- Energy, 25
 - Form of 25
 - Kinetic, 25
 - Potential, 25
- eV, 9
- Farad (F), 47
- Field
 - Electric, 28
 - Strength

Momentum, 2