

Processes

- Reading: OS Concepts pp.95-107
- A process is a program in execution and is represented by

- _____
- _____
- _____
- _____

PCB

- Process Control Block contains

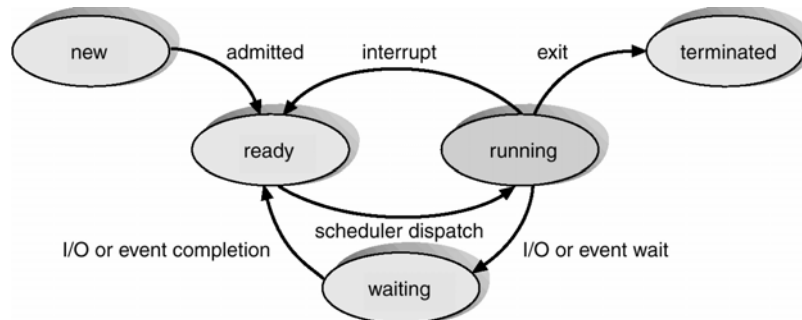
- _____
- _____
- _____
- _____
- _____
- _____

pointer	process state
process number	
program counter	
registers	
memory limits	
list of open files	
⋮	

Process State

Processes
Scheduling
Operations

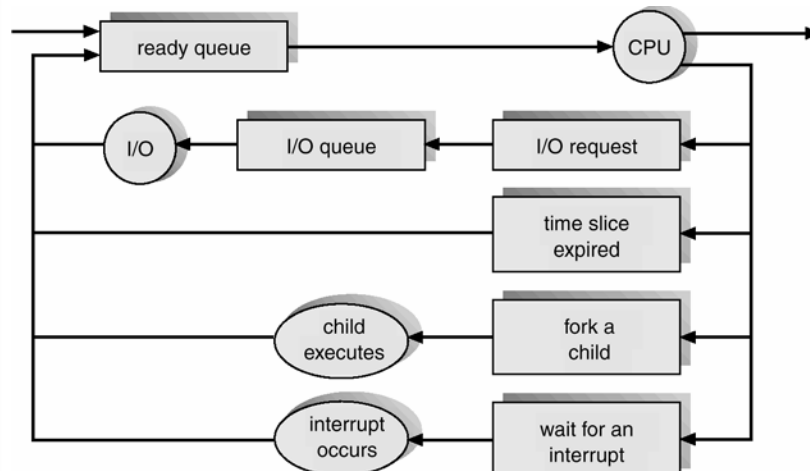
- New: _____
- Ready: _____
- Running: _____
- Waiting: _____
- Terminated: _____



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Process Scheduling

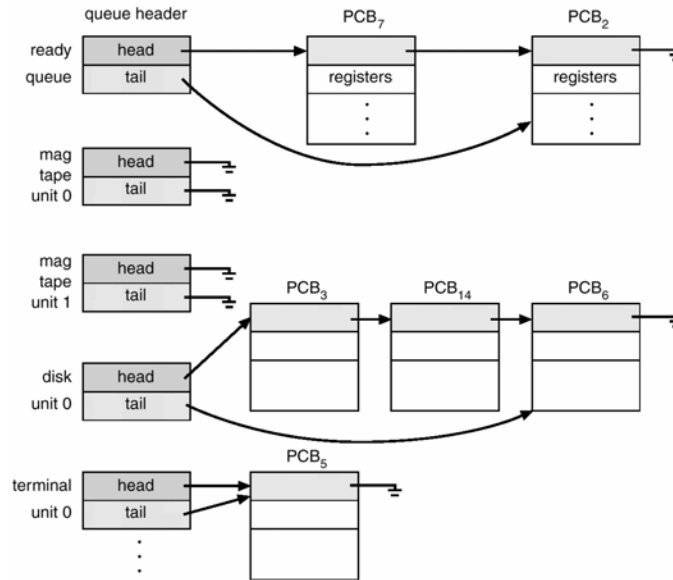
Processes
Scheduling
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Scheduling Queues

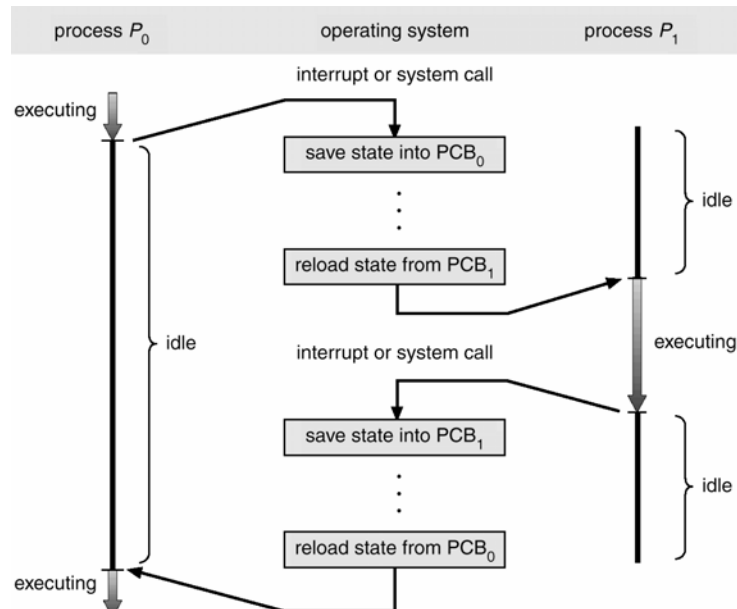
Processes
Scheduling
Operations



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Context Switch Illustrated

Processes
Scheduling
Operations



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Context Switch

Processes
Scheduling
Operations

■ When the CPU switches between processes

- _____
- _____
- _____
- _____
- _____

■ Types of processes

- I/O bound: _____
- CPU bound: _____
- _____

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Operations – Creation

Processes
Scheduling
Operations

■ Generally any process may create another process

- _____
- _____
- _____



Typical UNIX process tree

■ After creation the parent can either

- _____
- or _____

■ And the child can either

- _____
- or _____

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Process Creation in UNIX

Processes
Scheduling
Operations

```
main()
{
    int new_pid = fork();
    if (new_pid < 0) {
        exit(-1);
    }
    else if (new_pid == 0) {
        execlp("/bin/ls", "ls", "-l", NULL);
    }
    else {
        int statusp, process;
        do {
            process = wait(&statusp);
        } while ((process != -1) &&
                (process != new_pid));
    }
}
```

[Resources/Code/Processes.C](#)

[Resources/Output/Processes.SampleOutput](#)

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Operations – Termination

Processes
Scheduling
Operations

■ Processes are terminated (by their parents) if

- _____
- _____
- _____

■ In UNIX:

- The kill() system call is used

- _____

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Process Termination in UNIX

```
void handle_signal(int signal_no)
{
    switch (signal_no) {
        case SIGALRM: // Do nothing
            break;
    }
}

main()
{
    ... < Create child and execute program >
    else
    {
        if (signal(SIGALRM, handle_signal) != SIG_ERR)
            alarm(5);
        ... < Wait for child >
        if ((process == -1) && (errno == EINTR))
            int success = kill( new_pid, SIGKILL );
    }
}
```

[Resources/Code/Killer.C](#)[Resources/Output/Killer.SampleOutput](#)