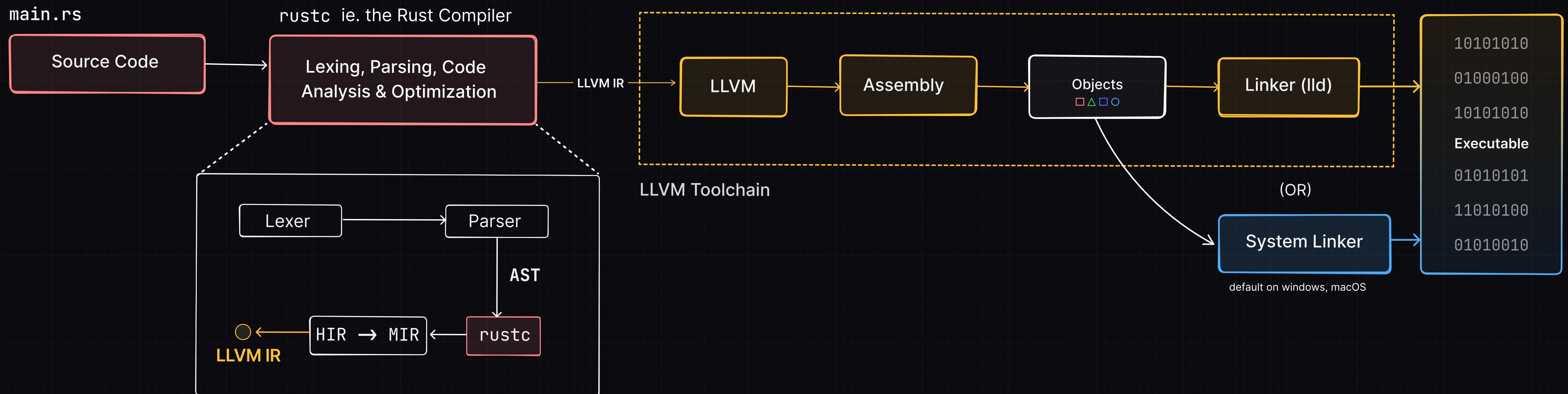


Rust 🦀 Unlinked

Compiler, Symbols, Linkers & Static Libraries



ABOUT ME

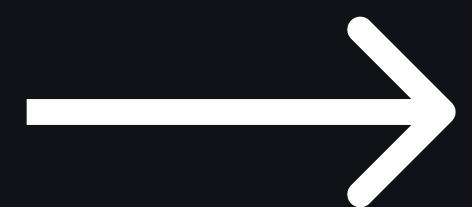
- Working on **M365 Core** at Microsoft
- Tinkering with Rust since 2020
- Lately, I've been into reading about databases, systems programming languages, and distributed systems
- **@shrirambalaji** everywhere   

AGENDA

- Understanding Linking
- Rust Compilation - A High Level Overview
- What's in an Object File? Can we link them?
- ELF - The Executable and Linkable Format
- Symbols, Symbol Tables and how to visualize them?
- **staticlib** to the rescue
- Cargo Build Script for linking object files

Understanding Linking

Linking involves combining object files into an executable or shared library. It's like putting together puzzle pieces to create a working program.



.exe

Linking involves combining object files into an executable or shared library. It's like putting together puzzle pieces to create a working program.



`./program`

Linking does the magic of **Symbol Resolution**, where the linker matches variable and function names (ie. symbols) to their specific memory addresses, making sure everything fits together.



`./program`

Why is understanding Linking necessary?

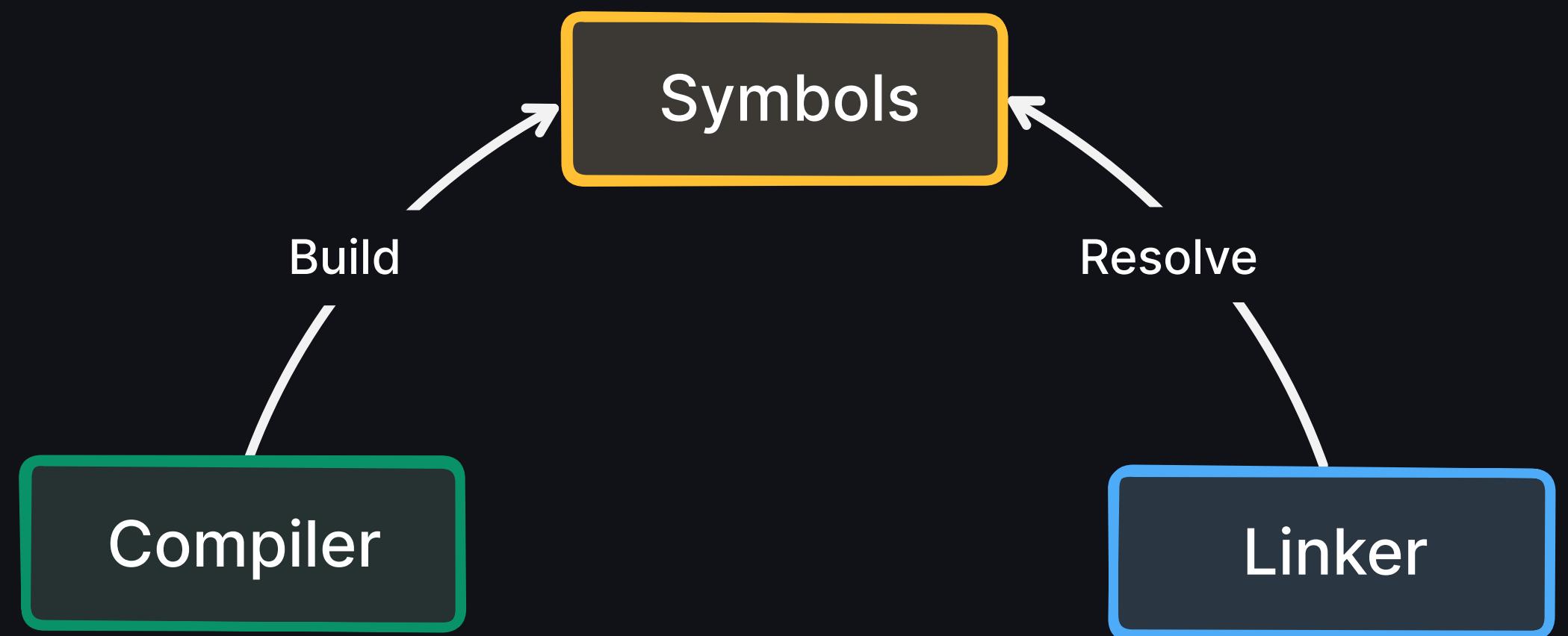
**Linking time is often a big part of
compilation time.**

In large Rust projects, roughly half of the
time could be spent in the linker.

COMPILATION

Phases of Compilation

- a compiler compiles source files into object files (.o files)
- then, a linker takes all object files and combines them into a single executable or shared library file.



Rust  Static Linking

STATIC LINKING

All the necessary dependencies are compiled and linked in the final executable binary statically. This enables easier distribution, but the tradeoff being bigger executables.

DYNAMIC LINKING

Dynamic linking allows a program to load external libraries / shared libraries into memory and use their functionalities at runtime, rather than at compile time.

It is **crucial** to understand a little about the stages
of rust compilation, *before* we get to linking.

Disclaimer: I'm not a `rustc` compiler dev, rather
just someone curious about it 😊

Rust Compilation - High Level Overview

Simplified

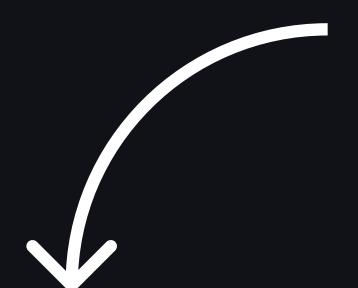
Rust Compilation - High Level Overview

**presented linearly for clarity*



Rust Compilation - High Level Overview

**actual implementation is query based*



Rust Compilation - High Level Overview

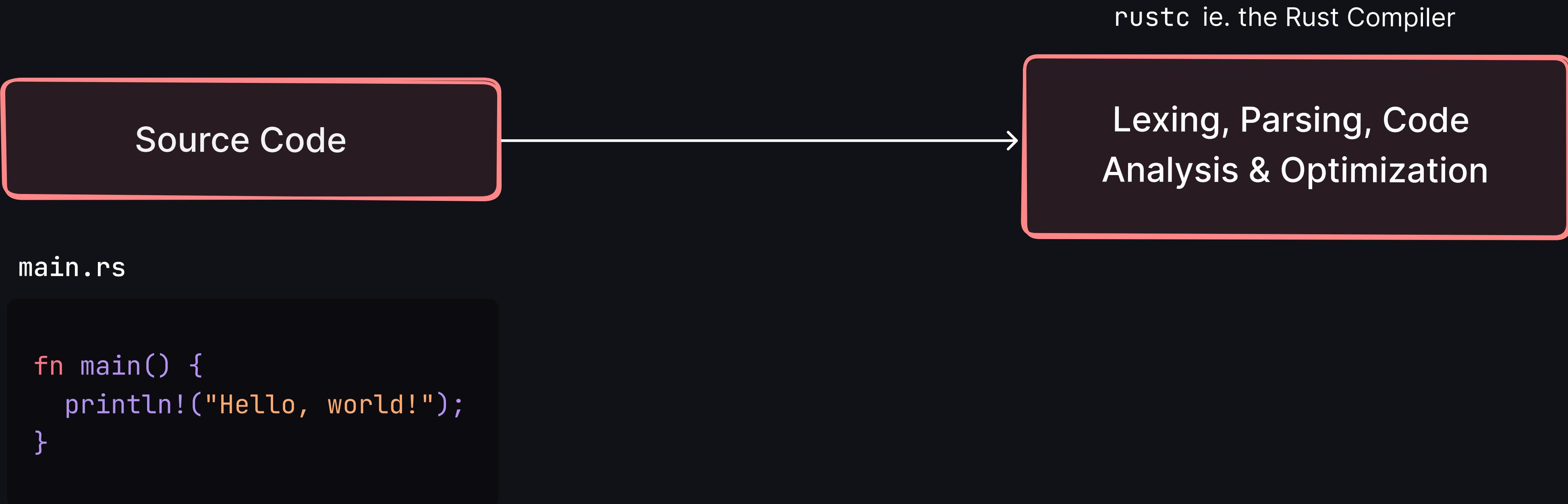
Lexing and Parsing

Source Code

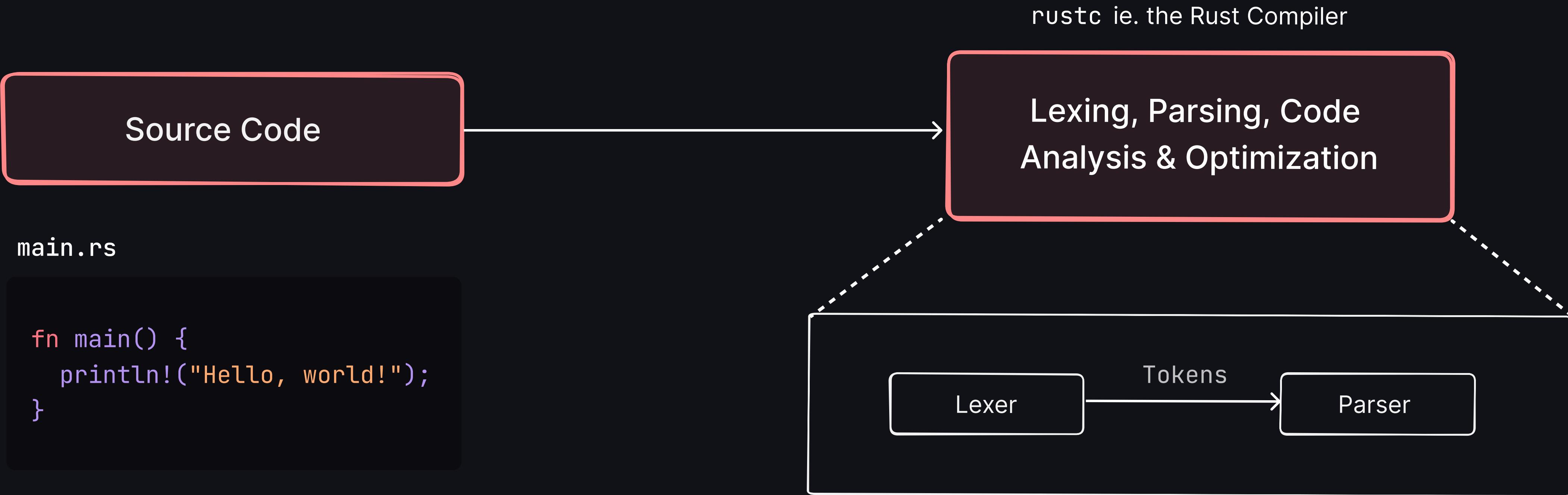
main.rs

```
fn main() {  
    println!("Hello, world!");  
}
```

Lexing and Parsing

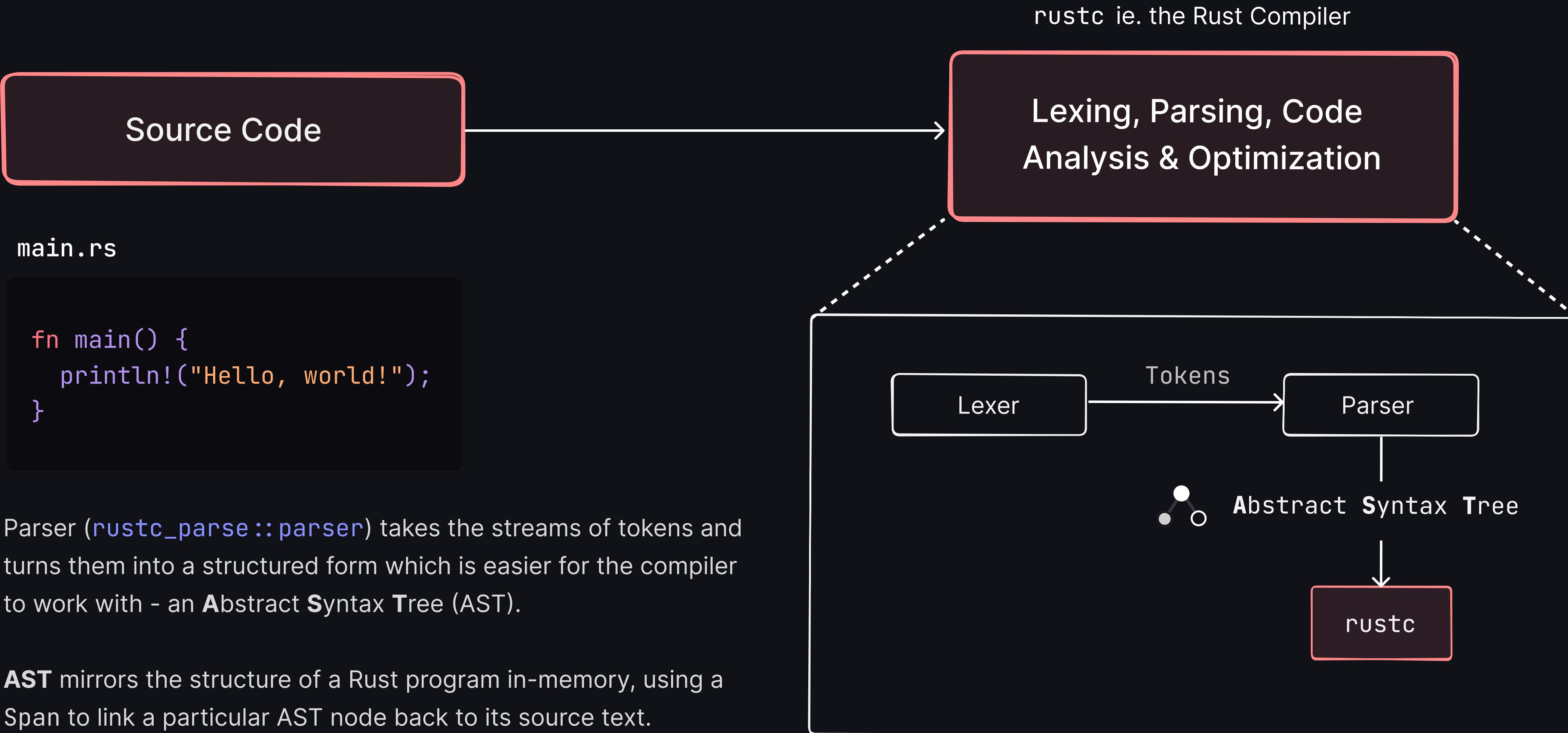


Lexing and Parsing

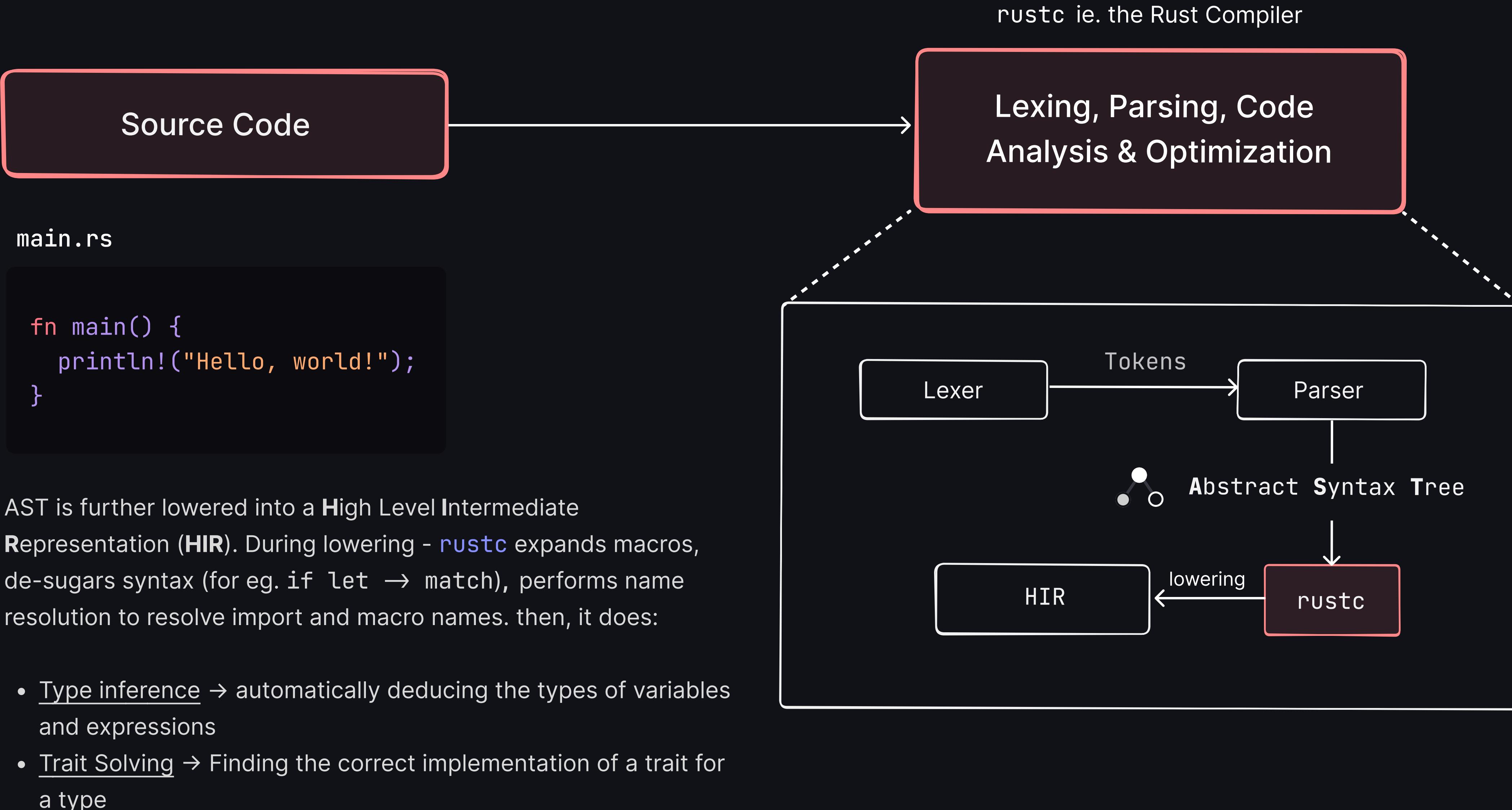


`rustc_lexer + rustc_parse::lexer` converts source code `&str` into parseable token types for the

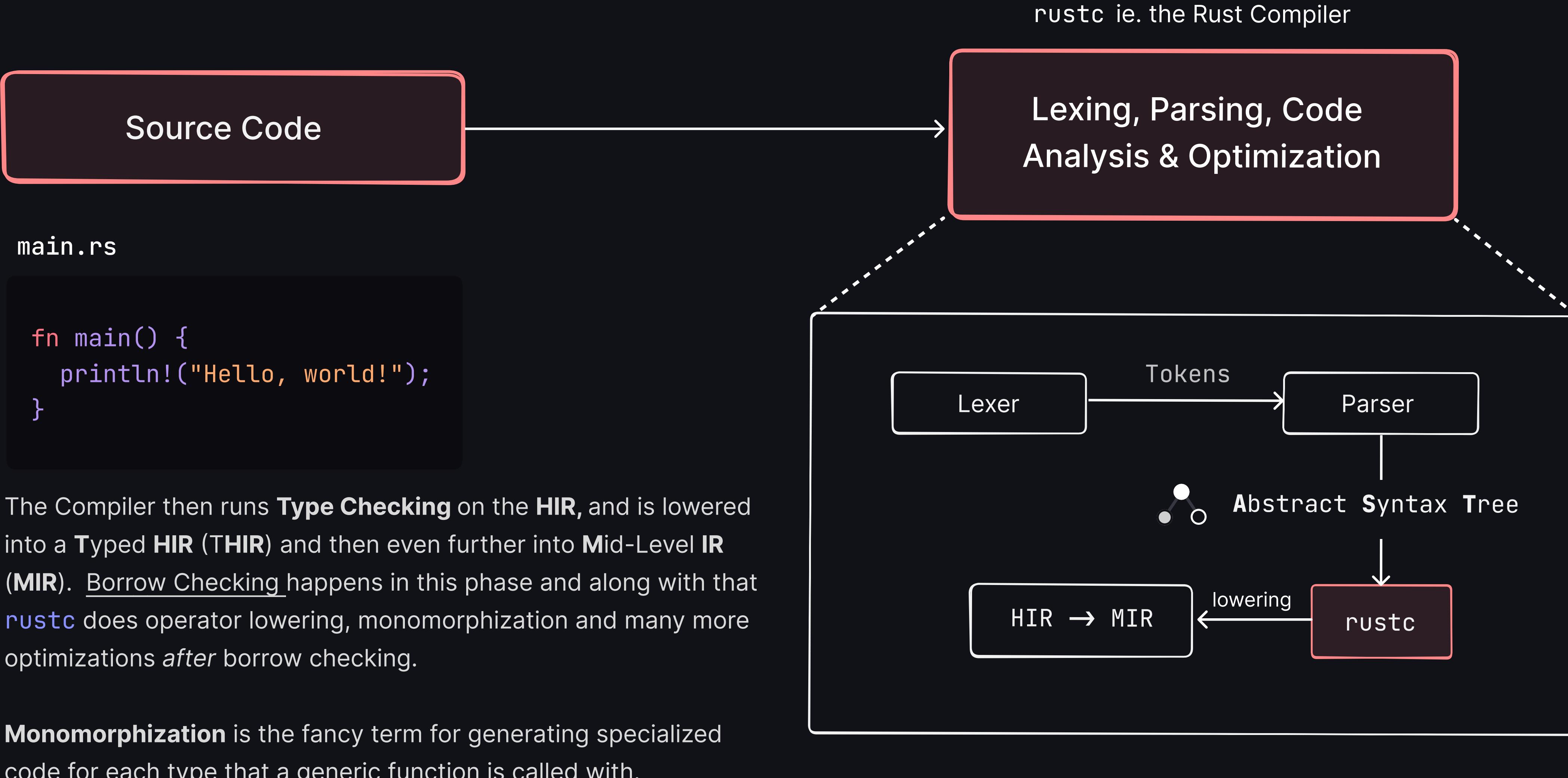
Lexing and Parsing



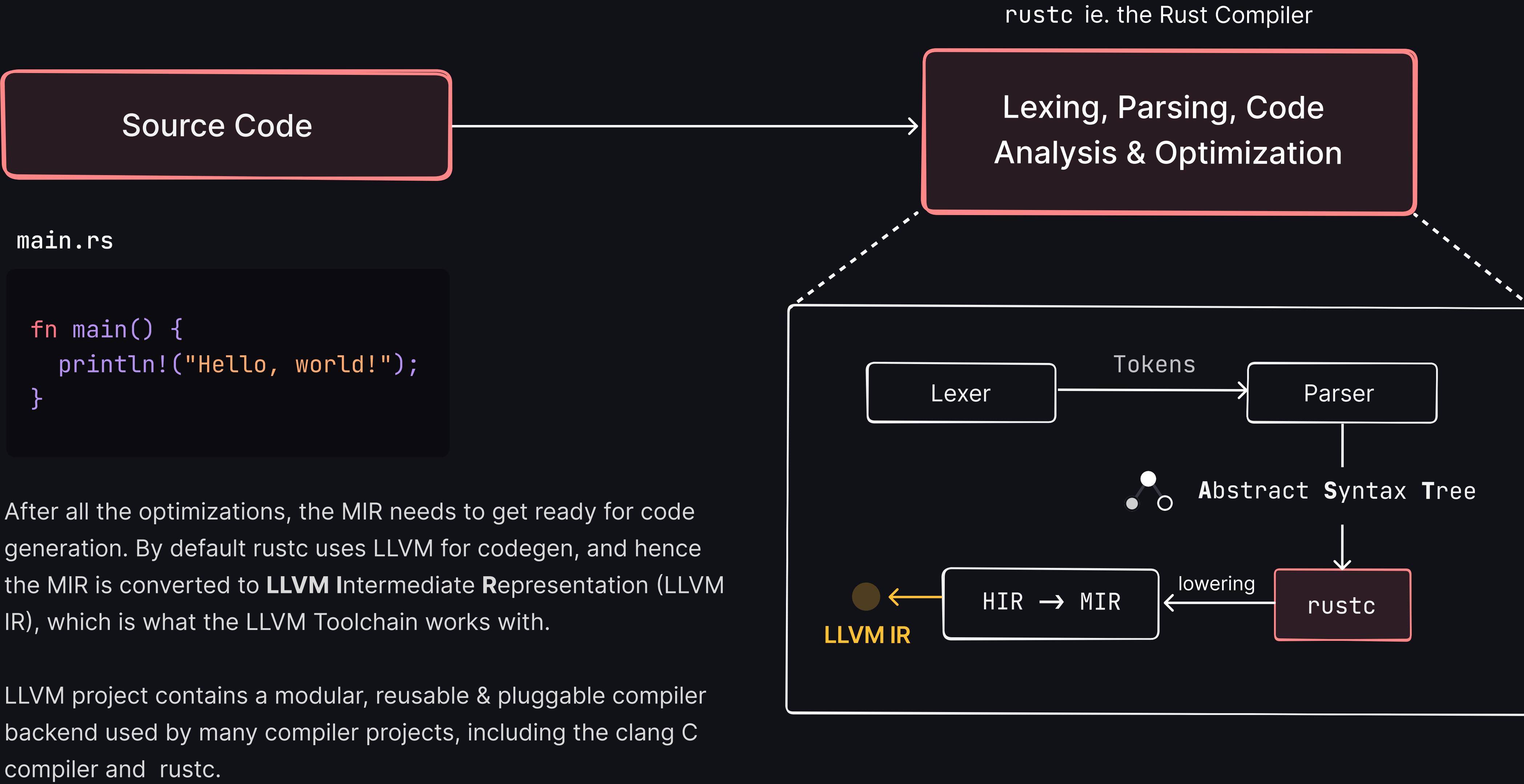
Code Analysis & Optimization



Code Analysis & Optimization



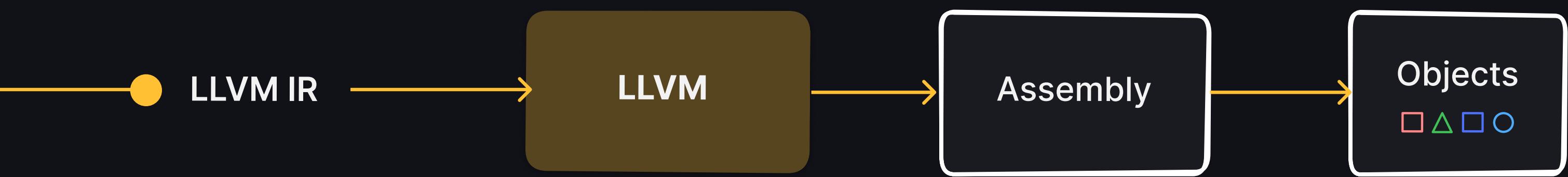
Preparing for Code Generation



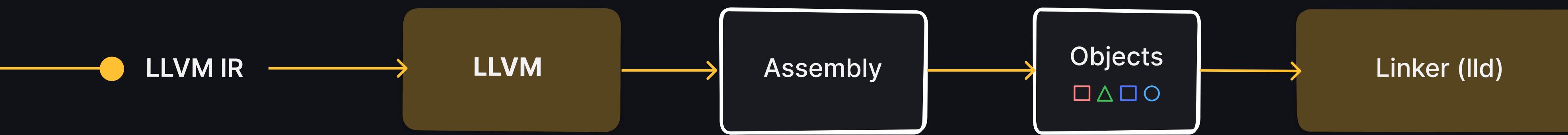
Code Generation & Building the executable



Code Generation & Building the executable



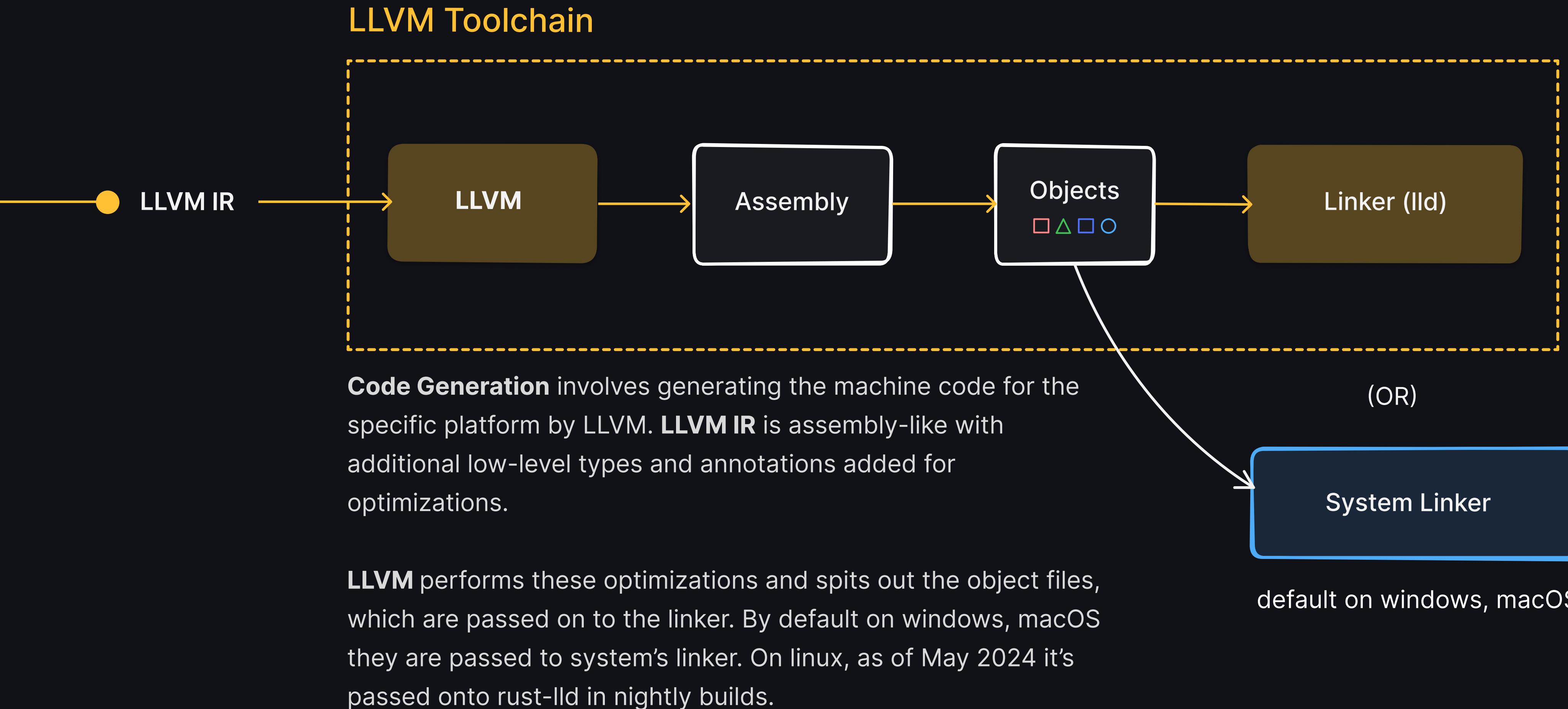
Code Generation & Building the executable



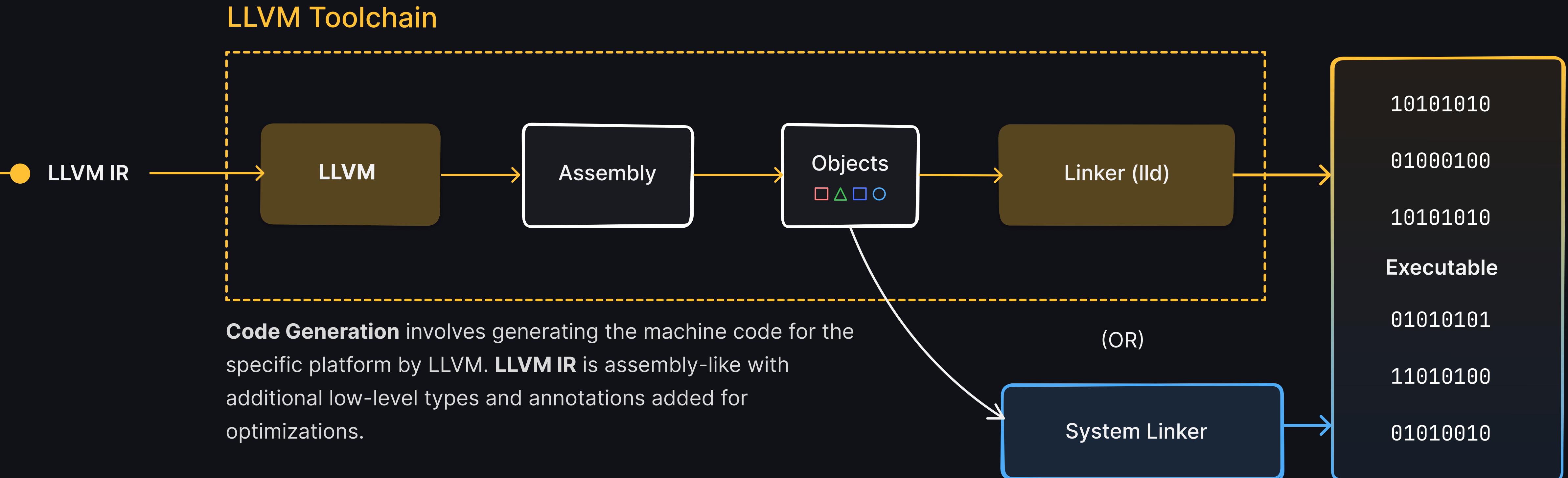
Code Generation involves generating the machine code for the specific platform by LLVM. **LLVM IR** is assembly-like with additional low-level types and annotations added for optimizations.

LLVM performs these optimizations and spits out the object files, which are passed on to the linker.

Code Generation & Building the executable



Code Generation & Building the executable



LLVM performs these optimizations and spits out object files, which are passed on to the linker. By default on windows, macOS they are passed to system's linker. On linux, as of **May 2024** it's passed onto rust-lld in nightly builds. The linker then links together the object files to return an executable.

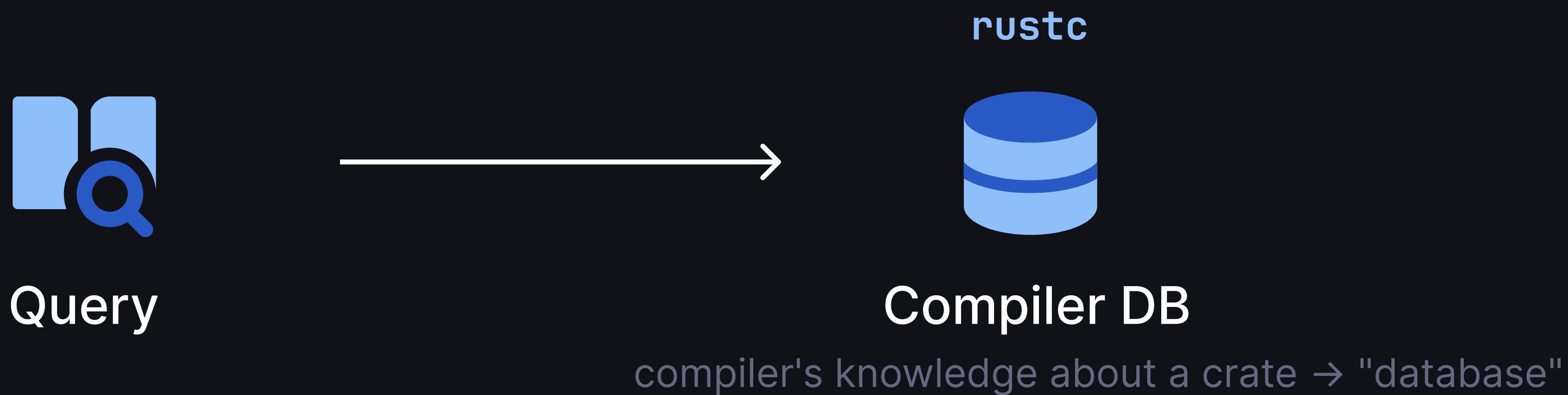
What does query based compilation look
like in `rustc`?

Demand Driven Compilation with Queries



Query

Demand Driven Compilation with Queries



Demand Driven Compilation with Queries



Every Step from earlier is modeled as a “Query”

Let's look at a query from the “Trait Solving” Step

Demand Driven Compilation with Queries

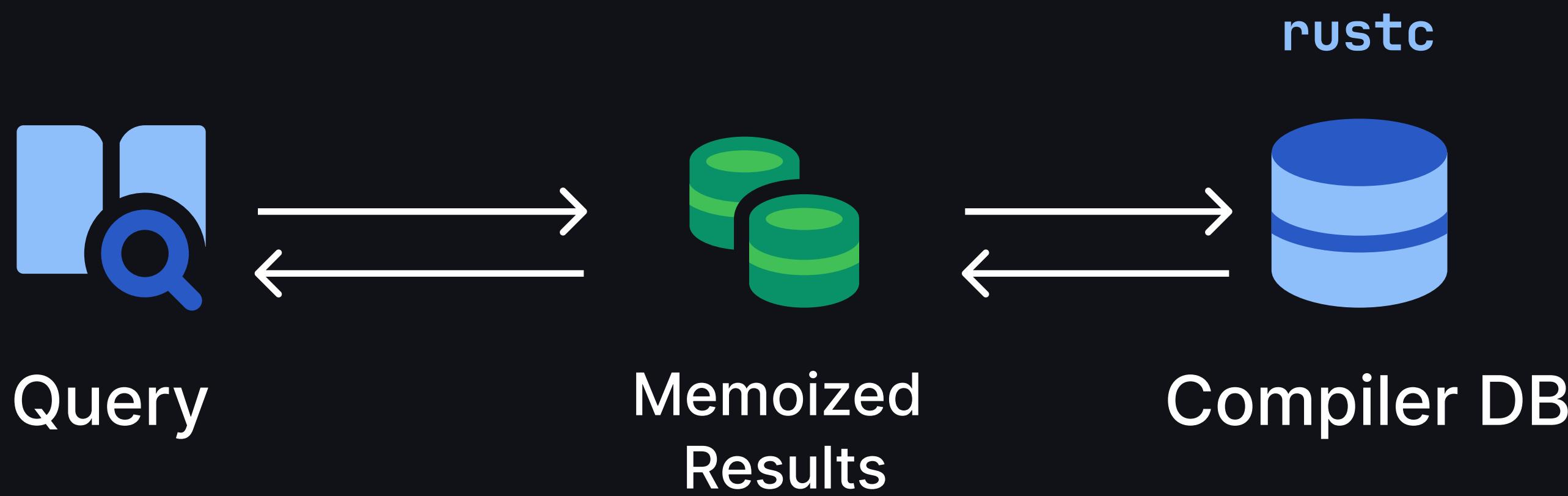
```
// Given a crate and a trait, look up all impls of that trait in the crate.  
// Return `(impl_id, self_ty)`.  
query implementations_of_trait(key: (CrateNum, DefId)) → &'tcx [(DefId, Option<SimplifiedType>)] {  
    desc { "looking up implementations of a trait in a crate" }  
    separate_provide_extern  
}
```

source: [compiler/rustc_middle/src/query/mod.rs](#)

Demand Driven Compilation with Queries

source: compiler/rustc_middle/src/query/mod.rs

Demand Driven Compilation with Queries

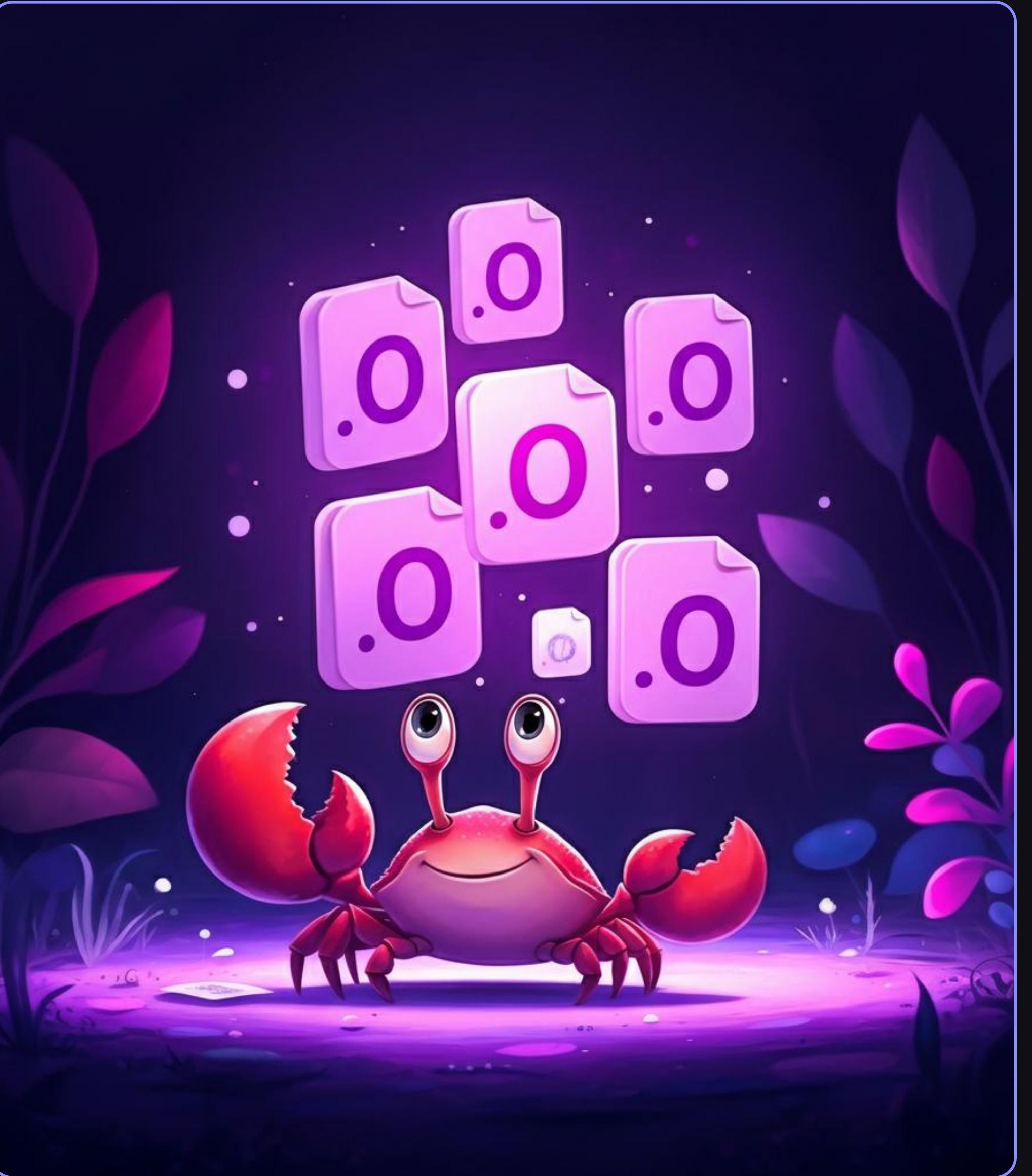


*Memoization enables incremental compilation, and faster builds

Enough about Compilation, Back to Linking 

You may have looked at .o files in the past and
wondered . . .

What's in these .o files?



“An **object file** contains machine code or bytecode, as well as other data and metadata, generated by a compiler or assembler from source code during the compilation or assembly process. The machine code that is generated is known as object code.”

source: Wikipedia

If it's just machine code,
can we link them
ourselves?



Let's understand with an example

FOO.RS

```
#![no_main]

#[no_mangle]
pub static mut Global: i32 = 5;

#[no_mangle]
pub fn foo() {
    unsafe {
        Global = 10;
    }
}
```

BAR.RS

```
#![no_main]

extern "C" {
    static mut Global: i32;
}

#[no_mangle]
pub extern "C" fn bar() {
    unsafe {
        Global = 20;
    }
}
```

importing a `Global` variable from `foo.rs` in `bar.rs` and update it's value to 20.

FOO.RS

```
#![no_main]
```

```
#[no_mangle]
pub static mut Global: i32 = 5;

#[no_mangle]
pub fn foo() {
    unsafe {
        Global = 10;
    }
}
```

BAR.RS

```
#![no_main]
```

```
extern "C" {
    static mut Global: i32;
}

#[no_mangle]
pub extern "C" fn bar() {
    unsafe {
        Global = 20;
    }
}
```

The `#![no_main]` attribute tells the compiler that there is no main function, and effectively not to throw a compiler error when it doesn't find one.

FOO.RS

```
#![no_main]
```

```
#[no_mangle]
```

```
pub static mut Global: i32 = 5;
```

```
#[no_mangle]
```

```
pub fn foo() {  
    unsafe {  
        Global = 10;  
    }  
}
```

The `#[no_mangle]` attribute disables mangling.

When Rust code is compiled, identifiers are
“mangled” ie. transformed into a different name.

BAR.RS

```
#![no_main]
```

```
extern "C" {
```

```
    static mut Global: i32;
```

```
}
```

```
#[no_mangle]
```

```
pub extern "C" fn bar() {
```

```
    unsafe {
```

```
        Global = 20;
```

```
}
```

```
}
```

FOO.RS

```
#![no_main]
```

```
#[no_mangle]
```

```
pub static mut Global: i32 = 5;
```

```
#[no_mangle]
```

```
pub fn foo() {  
    unsafe {  
        Global = 10;  
    }  
}
```

for eg. Global variable gets mangled

to `__ZN11foo6Global17ha2a12041c4e557c5E`.

This is done to avoid naming conflicts when
linking with other libraries.

BAR.RS

```
#![no_main]
```

```
extern "C" {
```

```
    static mut Global: i32;
```

```
}
```

```
#[no_mangle]
```

```
pub extern "C" fn bar() {
```

```
    unsafe {
```

```
        Global = 20;
```

```
}
```

```
}
```

FOO.RS

```
#![no_main]
```

```
#[no_mangle]
```

```
pub static mut Global: i32 = 5;
```

```
#[no_mangle]
```

```
pub fn foo() {  
    unsafe {  
        Global = 10;  
    }  
}
```

however, we disable it with `#[no_mangle]` so that
the symbol name is preserved, and can be easily
linked by name.

BAR.RS

```
#![no_main]
```

```
extern "C" {
```

```
    static mut Global: i32;
```

```
}
```

```
#[no_mangle]
```

```
pub extern "C" fn bar() {
```

```
    unsafe {
```

```
        Global = 20;
```

```
}
```

```
}
```

FOO.RS

```
#![no_main]

#[no_mangle]
pub static mut Global: i32 = 5;

#[no_mangle]
pub fn foo() {
    unsafe {
        Global = 10;
    }
}
```

BAR.RS

```
#![no_main]

extern "C" {
    static mut Global: i32;
}

#[no_mangle]
pub extern "C" fn bar() {
    unsafe {
        Global = 20;
    }
}
```

FOO.RS

```
#![no_main]

#[no_mangle]
pub static mut Global: i32 = 5;

#[no_mangle]
pub fn foo() {
    unsafe {
        Global = 10;
    }
}
```

BAR.RS

```
#![no_main]

extern "C" {
    static mut Global: i32;
}

#[no_mangle]
pub extern "C" fn bar() {
    unsafe {
        Global = 20;
    }
}
```

FOO.RS

```
#![no_main]

#[no_mangle]
pub static mut Global: i32 = 5;

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    unsafe {
        Global = 10;
    }
}
```

BAR.RS

```
#![no_main]

extern "C" {
    static mut Global: i32;
}

#[no_mangle]
pub extern "C" fn bar() {
    unsafe {
        Global = 20;
    }
}
```

The `extern "C"` block tells the compiler that `Global` is defined elsewhere in a foreign library.

FOO.RS

```
#![no_main]

#[no_mangle]
pub static mut Global: i32 = 5;

#[no_mangle]
pub fn foo() {
    unsafe {
        Global = 10;
    }
}
```

BAR.RS

```
#![no_main]

extern "C" {
    static mut Global: i32;
}

#[no_mangle]
pub extern "C" fn bar() {
    unsafe {
        Global = 20;
    }
}
```

extern "C" doesn't mean we are inter-operating with C, but rather using the platform's C ABI (**Application Binary Interface**).

FOO.RS

```
#![no_main]

#[no_mangle]
pub static mut Global: i32 = 5;

#[no_mangle]
pub fn foo() {
    unsafe {
        Global = 10;
    }
}
```

BAR.RS

```
#![no_main]

extern "C" {
    static mut Global: i32;
}

#[no_mangle]
pub extern "C" fn bar() {
    unsafe {
        Global = 20;
    }
}
```

bar.rs assumes that a variable declaration for **Global**, is present in a foreign library.

FOO.RS

```
#![no_main]

#[no_mangle]
pub static mut Global: i32 = 5;

#[no_mangle]
pub fn foo() {
    unsafe {
        Global = 10;
    }
}
```

This block is `unsafe` because we are updating a global static mutable.

BAR.RS

```
#![no_main]

extern "C" {
    static mut Global: i32;
}

#[no_mangle]
pub extern "C" fn bar() {
    unsafe {
        Global = 20;
    }
}
```

FOO.RS

```
#![no_main]

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pub static mut Global: i32 = 5;

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    }
}
```

BAR.RS

```
#![no_main]

extern "C" {
    static mut Global: i32;
}

#[no_mangle]
pub extern "C" fn bar() {
    unsafe {
        Global = 20;
    }
}
```

This block is `unsafe` because Rust cannot guarantee safety in FFI calls. We are trying to mutate a global static variable imported from a library, which cannot be memory-safe.

Let's compile and get those object files!

But, wait since we want to try manually
linking - let's **not** use cargo for now

Compiling & Emitting Object Files

```
...
```

```
$ rustc --emit=obj src/foo.rs && rustc --emit=obj src/bar.rs
```

A **symbol** in a symbol table refers to an identifier, such as a variable name or function name, that is stored in a data structure called a **symbol table**.

Symbols are stored in sections of the object file in a specific format - **ELF (Executable and Linkable Format)** on Unix-like systems. On macOS, it's Mach-O (Mach Object) but similar to ELF. On Windows, it's the **COFF (Common Object File Format)**

Visualizing Symbols - nm

```
$ nm foo.o
0000000000000010 D _Global
0000000000000000 T _foo
0000000000000000 t ltmp0
0000000000000000 d ltmp1
0000000000000000 s ltmp2
```

The output of `nm` is in the following format:

- `D` - Global Data section symbol
- `T` - Global Text symbol
- `d` - Local symbol in the data section
- `s` - Uninitialized Local symbol for small objects

If you haven't noticed, lowercase denotes local symbols, and uppercase denotes global symbols.

The `ltmp` symbols are temporary symbols generated by the compiler during compilation.

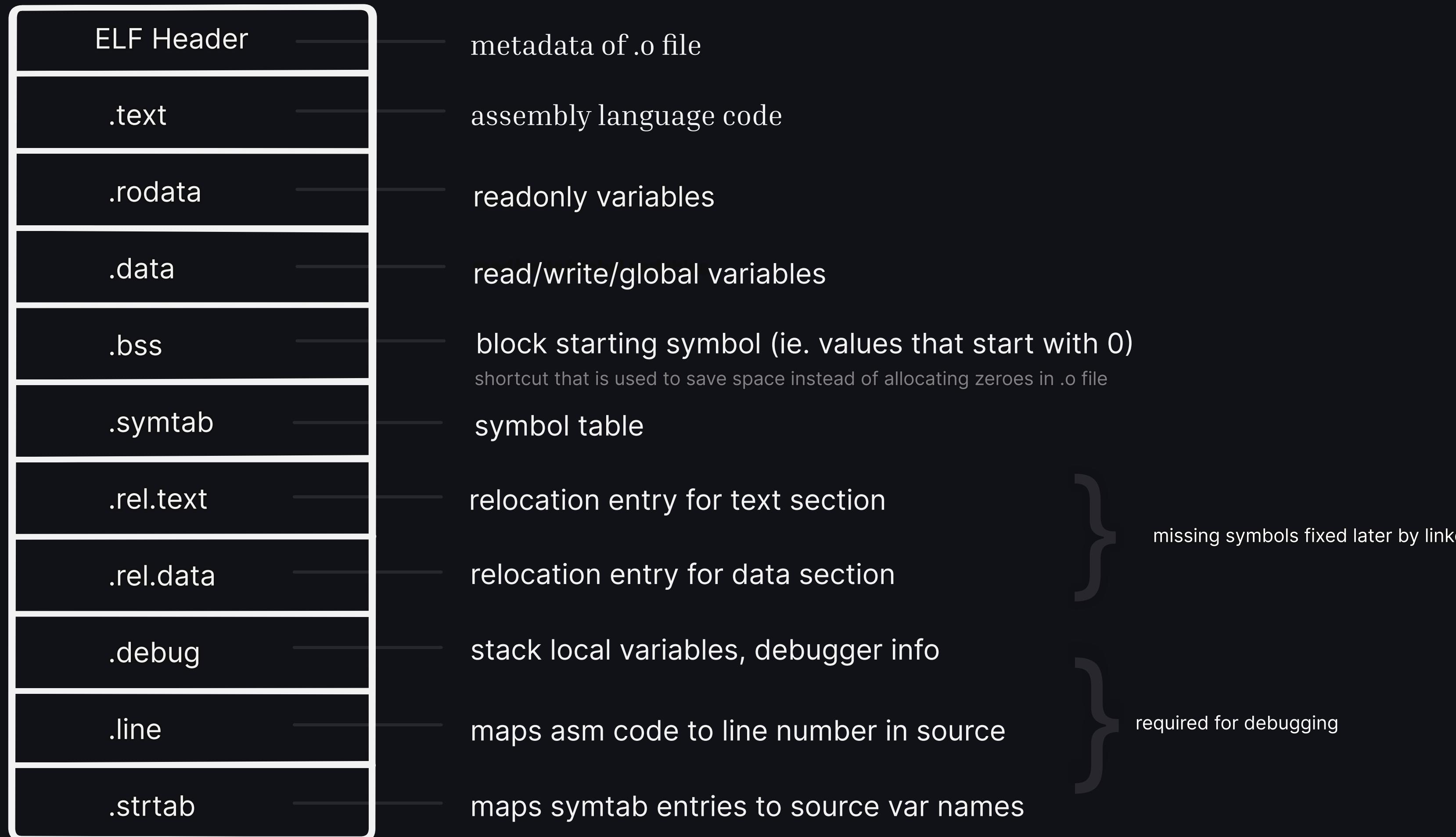
Visualizing Symbols - nm

Let's take a look at the symbol table for `bar.o` as well:

```
$ nm bar.o
          U _Global
0000000000000000 T _bar
0000000000000000 t ltmp0
0000000000000018 N ltmp1
```

wherein `U` denotes an Undefined symbol. Remember, the Undefined pseudo section I was mentioning, that's where the `Global` symbol exists. This is because there's an *undefined* symbol reference to the `Global` variable, which will be resolved only during the linking phase.

Inside ELF - Executable & Linkable Format



Let's try manually linking!

Lets make a `main.rs` that calls the `foo` and `bar` functions.

main.rs

```
extern "C" {
    fn foo();
    fn bar();
    static mut Global: i32;
}

fn main() {
    unsafe {
        foo();
        bar();
        println!("Global: {}", Global);
    }
}
```

Let's compile the `main.rs` file and emit an object file like before:

```
$ rustc --emit=obj -o main.o main.rs
```

Manually Linking using `ld`

```
$ ld -o main main.o foo.o bar.o
```

Manually Linking using `ld`



```
$ ld -o main main.o foo.o bar.o
Undefined symbols for architecture arm64:
    "__Unwind_Resume", referenced from:
        __ZN4core3ops8function6FnOnce9call_once17hf02687347fd78dc0E in main.o
    "__ZN3std2io5stdio6_print17h27e3b43a8b5f8b6aE", referenced from:
        __ZN4main4main17h49930d4df5c05f23E in main.o
    "__ZN3std2rt19lang_start_internal17h47d7f1f6477d860bE", referenced from:
        __ZN3std2rt10lang_start17h43f0cdc6e9029b25E in main.o

    "__ZN4core3fmt3num3imp52$_LT$impl$u20$core..fmt..Display$u20$for$u20$i32$GT$3fmt17h810eb3
12f616c580E", referenced from:
        __ZN4main4main17h49930d4df5c05f23E in main.o
    "_rust_eh_personality", referenced from:
        /Users/shrirambalaji/Repositories/learning-linkers/main.o
    "dyld_stub_binder", referenced from:
        <initial-undefined>
ld: symbol(s) not found for architecture arm64
```

staticlib to the rescue

Instead of us trying to link the core crate and bring in std dependencies ourselves, we can create a static library from the `foo.rs` and `bar.rs` files, and then link them manually:

```
$ mkdir -p target/out  
$ rustc --crate-type=staticlib -o target/out/libfoo.a foo.rs  
$ rustc --crate-type=staticlib -o target/out/libbar.a bar.rs
```

The output is a `.a` file, which is a static library / archive in *nix systems.
and it contains the `.o` files we saw previously.

staticlib to the rescue

We can use the `ar` command to list the contents of the archive.

```
$ ar -t target/out/libfoo.a | grep foo
foo.foo.730f9a7e513a85b2-cgu.0.rcgu.o
foo.10ftosr6tvdwscdu.rcgu.o
```

Interestingly the `.a` file contains the `.o` files we saw earlier, but with a different name, specifically with `*.rcgu.o` suffix. The `rcgu` stands for “Rust Codegen Unit” and is a unit of code that the compiler generates during [Code Generation](#) phase.

staticlib to the rescue

If we extract the `.o` file and look, we can see the same symbols we saw earlier.

```
$ ar -x target/out/libfoo.a foo.foo.730f9a7e513a85b2-cgu.0.rcgu.o
$ nm foo.foo.730f9a7e513a85b2-cgu.0.rcgu.o
0000000000000010 D _Global
0000000000000000 T _foo
0000000000000000 t ltmp0
0000000000000010 d ltmp1
0000000000000018 s ltmp2
```

Doing things the rust way - cargo's back!

Until now, we ignored poor cargo and were relying on rustc. Ideally, we should leverage cargo as its meant to be

Cargo build script

We can add a build script in a `build.rs` that goes in the project's root. This will link the static libraries from the previous step together.

build.rs

```
fn main() {
    println!("cargo:rustc-link-search=native=target/out");
    println!("cargo:rustc-link-lib=static=foo");
    println!("cargo:rustc-link-lib=static=bar");
}
```

- `cargo:rustc-link-search=native=target/out` instruction tells the compiler to search for the static libraries in the `target/out` directory
- `cargo:rustc-link-lib=static=foo` and `cargo:rustc-link-lib=static=bar` tells the compiler to link the `foo` and `bar` static libraries. As an alternative to the linking these in the build script, we can also use the `#[link](https://doc.rust-lang.org/reference/items/external-blocks.html#the-link-attribute)` attribute directly in `main.rs`

Bonus: What does the LLVM IR look like?

LINKS

- [Blog](#)
- [Slides](#)
- [Code Snippets on Github](#)
- [CS 361 Systems Programming by Chris Kanich](#)
- [High Level Compiler Architecture - Rustc Guide](#)
- [Rust Borrow Checker - Nell Shamrell-Harrington](#)
- [Linkage - Rust Reference](#)
- [Visualizing Rust Compilation](#)
- [Freestanding Rust Binary - Philipp Oppermann](#)
- [Matt Godbolt - The Bits between the Bits](#)

References



Thank You

@shrirambalaji   