

# Course Summary: Ordinary differential equations

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I took this differential equations course in my third semester.

## 1 First Order Equations

Some description of what a first order differential equation is comes here.

### 1.1 Homogeneous first order linear differential equations

These equations are of the form

$$\frac{dy}{dt} + a(t)y = 0.$$

Here  $y$  is a function of  $t$ . To solve these equations use the method below:

$$\begin{aligned}\frac{\frac{dy}{dt}}{y} = -a(t) &\implies \frac{d \ln |y|}{dt} = -a(t) \implies \ln |y| = -\int a(t)dt + c_1 \\ &\implies |y| = \exp\left(-\int a(t)dt + c_1\right) = c \exp\left(-\int a(t)dt\right) \\ &\implies |y \exp\left(\int a(t)dt\right)| = c.\end{aligned}$$

Since  $c$  is a constant and  $|y \exp(\int a(t)dt)|$  is a continuous function of  $t$ , by the intermediate value theorem it can be deduced that

$$y(t) = c \exp\left(-\int a(t)dt\right). \quad (1)$$

This equation is regarded as the general solution of the homogeneous linear differential equation. Given the initial value  $y(t_0) = y_0$ , to find the specific solution of the equation, do the integration from  $t_0$  to  $t$ . The solution will be

$$y(t) = y_0 \exp\left(-\int_{t_0}^t a(s)ds\right).$$

### 1.2 Non-homogeneous first order linear differential equations

These equations are of the form

$$\frac{dy}{dt} + a(t)y = b(t).$$

In order to solve these more general equations we try to write them as  $\frac{dy}{dt} = b(t)$ . To do so, we multiply the equation by  $\mu$ , the integrating factor. So now,

$$\mu(t)y' + \mu(t)a(t)y = \mu(t)b(t).$$

If we choose a function  $\mu$  such that  $\mu' = \mu(t)a(t)$ , then

$$\frac{d}{dt}\mu(t)y(t) = \mu(t)b(t) \implies \mu(t)y(t) = \int \mu(t)b(t)dt + c \implies y = \frac{1}{\mu(t)}\left(\int b(t)\mu(t)dt + c\right).$$

Now to actually find such  $\mu$ , we have to solve  $\mu'(t) = a(t)\mu(t)$  which is a first order linear homogeneous equation. From (1), we know that  $\mu(t) = c_1 \exp(\int a(t)dt)$ . Let  $c_1 = 1$ . So Now

$$y = \frac{1}{\mu(t)}\left(\int \mu(t)b(t)dt + c\right) = \exp\left(-\int a(t)dt\right)\left(\int \mu(t)b(t)dt + c\right). \quad (2)$$

Equation (2) is the general solution of these types of differential equations. If the initial condition  $y(t_0 = y_0)$  is given, integrate from  $t_0$  to  $t$ , just as we did for the homogeneous types.

### 1.3 Separable equations

A separable equation here, is a first order differential equation that can be written in the form

$$\frac{dy}{dt} = \frac{g(t)}{f(y)}.$$

( $f, g$  are continuous functions)

Solving these equations also involves a similar technique.

$$y'f(y) = g(t) \implies \frac{d}{dt}F(y(t)) = g(t) \implies F(y(t)) = \int g(t)dt + c. \quad (3)$$

Where  $F(y) = \int f(y)dy$ .

Another way to see these equations is that, a differential equation is called separable if we can 'separate' all  $y$ s and  $x$ s in the equation and write it as

$$f(y)dy = g(t)dt.$$

Once we do this, we can integrate both sides with respect to their own variable. Thus,  $\int f(y)dy = \int g(t)dt$  which yields the same result.

### 1.4 Bernoulli Equations

These equations are of the form

$$y' + p(x)y = q(x)y^n.$$

And using a change of variables, they can be turned into a linear equation.  
To solve Bernoulli equations, we first divide both sides by  $y^n$ .

$$\frac{y'}{y^n} + p(x)\frac{1}{y^{n-1}} = q(x)$$

Let  $u = \frac{1}{y^{n-1}}$ . Therefore,  $\frac{du}{dt} = u' = \frac{(1-n)y'}{y^n}$ . Replacing  $\frac{y'}{y^n}$  by  $\frac{u'}{1-n}$  in the original equation will result in

$$\frac{u'}{1-n} + p(x)u = q(x).$$

This is now a first order linear differential equation we know how to solve for  $u$ . Using the results from (2),

$$u = \frac{1}{(1-n)\mu} \left( \int \mu(x)q(x)dx + c \right)$$

where  $\mu = e^{\int p(x)dx}$ . Finally the solution can be computed

$$y = \sqrt[n-1]{\frac{1}{u}}. \quad (4)$$

## 1.5 Homogeneous Equations

A First order differential equation is said to be homogeneous, iff it can be written in the form

$$y' = F\left(\frac{y}{x}\right).$$

A quick way to find out whether an equation is homogeneous or not is to multiply both  $x$  and  $y$  by a constant factor  $n$ . If the resulting equation is the same as the original one, then that equation is homogeneous.

To solve equations of this type, we use a change of variable  $u = \frac{y}{x}$ . Thus,  $y' = u'x + u$ . Now,

$$x \frac{du}{dx} = F(u) - u \implies \frac{dx}{x} = \frac{du}{F(u) - u} \implies \ln x = \int \frac{du}{F(u) - u}.$$

The former is a separable equation we know how to solve from (3). By solving it, we obtain  $u$  and then from  $y = ux$ ,  $y$  can be found.

## 1.6 Exact Equations

We can solve all differential equations which can be put in the form

$$\frac{d}{dt}\phi(t, y) = 0$$

for some function  $\phi(t, y)$ . To wit, we can integrate both sides with respect to  $t$  to obtain

$$\phi(t, y) = C$$

for some constant  $C$ . Now we can solve it for  $y$  to get the desired function  $y(t)$ . Consider a first order differential equation. It has the form

$$M(t, y) + N(t, y)y' = 0. \quad (5)$$

We want to find a function  $\phi(t, y)$  such that  $\frac{d}{dt}\phi(t, y) = M(t, y) + N(t, y)y'$ . From the chain rule, we know that  $\frac{d\phi}{dt} = \frac{\partial\phi}{\partial t} + \frac{\partial\phi}{\partial y} \frac{dy}{dt}$ . Comparing this with the previous equality, we can see that  $M(t, y) = \frac{\partial\phi}{\partial t}$ ,  $N(t, y) = \frac{\partial\phi}{\partial y}$ .

For an arbitrary first order differential equation to be an exact equation (i.e a desired  $\phi$  exists), it is necessary that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial t}.$$

If this equality holds, and also the domain of  $M, N$  is a simply connected subset of  $\mathbb{R}^2$  (i.e is without a hole), then a function  $\phi$  with the aforementioned property exists.

In order to find this  $\phi(t, y)$ , integrate  $M(t, y)$  with respect to  $t$  and treat  $y$  like a constant. So,

$$\phi(t, y) = \int M(t, y)dt + h(y).$$

Now, partial differentiation with respect to  $y$  would result in

$$\frac{\partial\phi}{\partial y} = N(t, y) = \frac{\partial \int Mdt}{\partial y} + h'(y) \implies h'(y) = N(t, y) - \frac{\partial \int Mdt}{\partial y}.$$

From this,  $h(y)$  and consequently  $\phi(t, y)$  can be obtained.

In some cases where equation (5) is not exact, it might be possible to make it exact by multiplying it in an integrating factor  $\mu$ . If such a function exists, then the following equations should be exact.

$$\mu M(t, y) + \mu N(t, y)y' = 0$$

Therefore,

$$\frac{\partial\mu}{\partial y}M(t, y) + \mu\frac{\partial M}{\partial y} = \frac{\partial\mu}{\partial t}N(t, y) + \mu\frac{\partial N}{\partial t}.$$

We can check for existence of  $\mu$  in two special cases. When  $\mu$  is solely a function of  $t$  or of  $y$ . For example, if such  $\mu(t)$  exists, then the above equality will turn to

$$\mu\frac{\partial M(t, y)}{\partial y} = \frac{d\mu}{dt}N(t, y) + \mu\frac{\partial N(t, y)}{\partial t}.$$

Hence,

$$\frac{d\mu}{dt} = \frac{\frac{\partial M}{\partial y} - \frac{\partial N}{\partial t}}{N}\mu = \mu R(t).$$

If  $\frac{\frac{\partial M}{\partial y} - \frac{\partial N}{\partial t}}{N}$  is a function of  $t$  alone, then this equality is meaningful and we can find an integrating factor  $\mu(t) = \exp(\int R(t)dt)$ .