

Robust video fingerprinting system

Daniel Pereira, Luis Loyola
Research and Development Department
SkillUpJapan Corporation
Tokyo, Japan
{d.pereira,loyola}@skillupjapan.co.jp

Abstract— Video fingerprinting is one of the most promising technologies to uniquely identify video content in the Internet in a totally format-independent way. The logic behind the creation of the video fingerprints or perceptual hashes is a key factor for the performance of the system, especially in terms of storage and search efficiency. Although several video fingerprinting methods have been proposed, most of them largely focus on the robustness of the perceptual hashes to distortions, giving much less importance to the required storage as well as the efficiency of the database structure for fast and reliable searches of video content. In this paper we propose a video fingerprinting system with an excellent robustness to distortions but also offering lower storage requirements and a more efficient database structure than prior schemes.

Keywords- video processing; pattern recognition; perceptual hash; information storage; video fingerprinting;

I. INTRODUCTION

The growth of video-related services in the Internet is increasingly creating needs for uniquely identifying video data in the Internet using video fingerprints. Applications that may profit from such technology include automatic tracking of copyrighted titles in user generated content sites, tagging movies for reducing the cost of its distributed storage and improving video search engines in a totally video-codec or video-format independent way.

Video fingerprints are perceptual hashes that allow us to discriminate one video from all the rest in a totally binary-independent way, i.e. irrespective of the codec or format in which they have been compressed. The main requirements for such a system are given below:

- Uniqueness: a piece of video content must be associated to a unique hash value.
- Storage: the amount of bits generated per unit of time from the hashing system should be as low as possible.
- Database: the necessary time to find a specific piece of content inside a huge pool of contents should be as low as possible. To do that the logic behind the creation of the hash is quite important since it defines the efficiency of the database structure.

- Robustness: the perceptual hash should be robust to malicious or intentional distortions including chromatic alterations, addition of watermark and subtitles and rotations.

Several video fingerprinting methods have been proposed. Most of them relate to pixel-level statistical analysis due to their low computational complexity. Lee and Yoo [1] propose an approach based on centroid of gradient orientation (CGO), while Lee and Suh [2] proposal focus on the orientation of luminance centroid and Lowe [3] focus on the histogram of gradient orientation. Other approaches propose histogram similarity calculations[4], ordinal measures of block means [5] and differential block means [6], however the dimensionality of these solutions is problematic.

In this work we propose a video fingerprints generation system as well as its associated database structure. Furthermore, the structure of the perceptual hash allows to significantly reducing the amount of storage required for the hash values as well as to decreasing the search time in the database.

The paper is organized as follows: some background is given in section II. The related work is covered in section III. Section IV describes in detail our proposed fingerprinting system. Experimental results and comparisons with previous art are shown in Section V. Finally, Section VI concludes the paper and point out some directions for future work.

II. BACKGROUND

Movies, or motion pictures, pose some interesting obstacles that need to be properly addressed in the digital domain. The amount of information present in full high-definition movies is so large that easily becomes a problem in areas such as information extraction and processing, data storage and the subsequent search inside the stored information.

While information extraction can be as straightforward as decoding a movie, the subsequent processing cannot only be a simple, instantaneous, analysis of characteristics of each frame. Data needs to be processed as a whole so that more meaningful information can be obtained from a specific movie, or part of it. In particular, the perceptual analysis of the data must produce results that are independent of the format on which the data has been encoded or compressed. That is, rather than a binary analysis of the data, a perceptual analysis of it is necessary. For

instance, five different files corresponding to a 30-second scene from a movie encoded with mpeg2, mpeg4, vp-6 and vc-1 using different values of width, height and frame rate must originate exactly the same unique fingerprint. Thus, that fingerprint is intrinsically associated to the perceptual content of the scene of interest and not to the binary format in which it is presented or stored. The development of data storage has been enormous, however the improvement of quality of motion pictures have expanded even further. Storing, for analysis, many copies of a movie in its original raw format may involve an extremely high cost and negatively impact the whole system.

Moreover, searching for information in a continuous, time based, structure is very inefficient. Efficient algorithms need to get rid of irrelevant information and know where to start searching for similar content. The increasing number of content creators and holders need a solution to efficiently search and analyze and identify audiovisual contents stored in several formats that are distributed across several third-party networks. This is another field where the utilization of perceptual fingerprints has a great potential.

It is therefore essential to provide tools that allow a fast and efficient binary-independent perceptual search of information that cannot be organized as a simple liaison of facts, keywords or occurrences. New search engines and data storage systems can take a lot of advantage from perceptual fingerprinting.

III. RELATED WORK

Several video fingerprinting algorithms that work at the pixel level have been proposed. Working directly with pixels is, nowadays, computationally feasible and accurate. However, those solutions do not address the magnitude of the resources needed for such a system and little analysis is provided in order to use a video fingerprinting solution in practical cases.

Many solutions proposed in previous papers use no real databases and temporarily store the content in memory. Others provide no effective way to index the video contents in an effective and scalable manner, which can lead to significant gains in system resources. Additionally, recent approaches [1][2] rely on a heavy fingerprint extraction process, which generally consists of video frame partitioning, frame-rate conversion and image resizing.

Out of the analyzed solutions, the proposals based on CGO [1] are deemed the most interesting, incorporating some unaddressed practical points, while providing a challenging algorithm. For instance, the previous recent approaches give little or no insight on database indexing schemas or resources, as well as no information on the expected timings for a fingerprint analysis. This is why we have selected this technique as our comparative benchmark.

IV. PROPOSED METHOD

Several characteristics can be analyzed in movies. While a plethora of information is readily available, our goal has been to use the least possible information in a way that guarantees an excellent performance. Out of the large set of characteristics and statistics that can be extracted from a movie, we have selected the luminance (also known as Luma) in each frame as a base for our algorithm. The luminance

actually gives us enough information to uniquely identify a video and is very robust to distortions, especially chromatic alterations.

A. Data extraction

The Luma associated to a time period corresponds to the average Luma per frame calculated during such period T as shown in Eq. 1:

$$M_T = \frac{1}{w \times h \times N} \sum_{f=0}^{N-1} \sum_{x=0}^w \sum_{y=0}^h L[x, y, f] \quad (1)$$

For the movie M , the Luma L of each pixel (x, y) inside each frame f is averaged in time – over N frames within period T – and space – over $w \times h$ pixels.

Other works [1,2] segment or partition a frame in order to have better results, by assigning different fingerprints to each partition. This will increase the dimensionality of the fingerprints, as well as the storage needed in the database. Our proposal uses the whole frame, with no segmentation.

B. Database indexing

The database indexing relies on an inherent aspect of the measured Luma. After an exhaustive analysis of large sets of movies, we found that Luma values are similar for a contiguous, and variable, amount of time. Thus, in order to reduce storage footprint we aggregate information from frames whose Luma falls into a range of values defined by $[A + t, A - t]$ where A is the average Luma of a time period (as shown in Eq. 1) and t corresponds to an adjustable threshold. This is what we define as *database threshold*. When the Luma value goes beyond the maximum or minimum range value a new Luma index, that is, a new reference in time for the start of the current period of information, is created until all the information is processed for that movie. This allows the system to save a significant storage space with respect to the per-frame characteristics of the movie. This process is what we define as *information clustering*, i.e. storing clusters of similar values, with respect to the selected threshold.

Figure 1 depicts a typical Luma value along the time in which two different indexing periods can be easily identified. Both periods are automatically detected by the proposed system. The left side of Figure 1 shows the original measurements of the Luma values of a video file. On the right side, the black vertical bars depict where the indexes are detected.

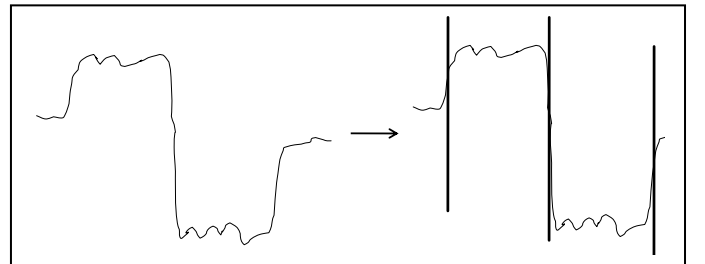


Figure 1. Detection of indexes

As the threshold value depends on the expected usage of the information and the storage infrastructure it needs to be carefully chosen. A smaller threshold aggregates fewer Luma values and generates more indexes that in turn may compromise the system accuracy. The amount of storage needed also increases. Likewise, a large threshold aggregates more Luma values and thus it saves a large amount of space in the database at the expense of turning the stored information less valuable for video fingerprinting purposes due to an insufficient number of significant Luma changes detected. Hence, the selected threshold becomes extremely important for the performance of the whole system.

Figure 2 shows how that information - taken from the index detection algorithm previously described - can be used to build the Luma vs. time graph on the right-hand side. When having the information stored in a database, depicted in the left-hand side, it is easy to reconstruct the information, while saving a large amount of space in the database. Instead of storing Luma information about every second or frame, only the indexes are stored.

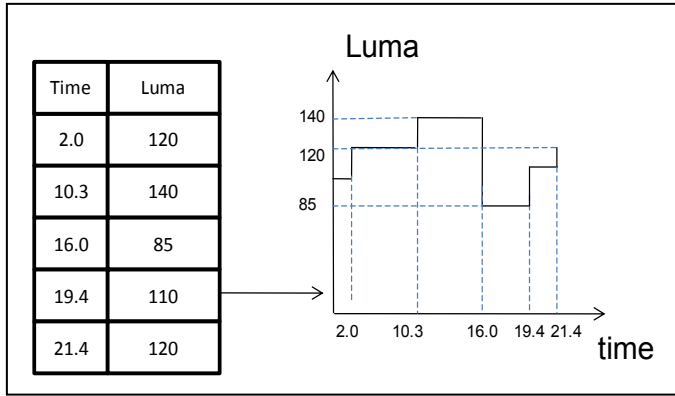


Figure 2. Information clustering algorithm

Additional to the information from each movie, a look-up table for the values of Luma is used. This table allows to quickly search for movies that have a specific Luma value in any of the movie indexes. The need for this table stems from a performance increase in the initial screening of the movies to analyze, in the search algorithm explained on next section.

C. Search algorithm

The search algorithm consists of several levels or layers of filtering. By providing a hierarchical identification structure, we can achieve faster searches and, therefore, use fewer resources. Using such an approach it is possible to discard movies that are clearly not related to our source video, or clip, and focus the effort of the search on videos that have a higher probability of being a match to the searched sequence.

The initial filtering consists of calculating the clustered Luma information of a given video clip or scene, to be found, calculate its time indexes and associated Luma values. Then the algorithm will proceed to perform two analyses. Firstly, search the look-up tables for movies with indexes of similar values of Luma. Secondly, analyze the time indexes of the

selected movies and consider for further analysis only the movies that have a similar number and time distribution of indexes. That information is extremely effective in an initial phase, since the time indexes and their values of Luma provide a simple, computationally effective, way to discard unrelated movies, while retaining a high level of uniqueness. It is, therefore, possible to spend less time, in the following steps, searching movies that are easily identified as not being a match.

Next step consists on analyzing all the videos that were previously found to be possible matches of our source video clip. In this step, different correlation approaches are used. After trying out several of them, we have finally selected the Tanimoto correlation factor [7], defined in Eq. 2, due to its great efficiency in a large number of trial movie sets.

$$T(A, B) = \frac{A \cdot B}{\|A\|^2 + \|B\|^2 - A \cdot B} \quad (2)$$

The Tanimoto correlation compares vectors of values and calculates the probability of those vectors to be similar. In more detail, the vectors that are used in this similarity algorithm are the vectors containing the time indexes and associated Luma values from both the fingerprinting database contents and the input video clip. Initially, the time index correlation calculation is performed in periods of n seconds, being n the total number of seconds from the ingested clip, or the sequence to search.

However, not every index from the source video will be compared to every index of the video in the database. Instead, if a threshold is not met from that comparison, the algorithm will jump to the next index of that movie that is calculated as a possible match and a new comparison will be initiated. Allowing the algorithm to jump to the next relevant section makes the algorithm faster, depending on the threshold used. High gains are achievable at the expense of an increased number of False Negatives; that is, videos in the database that appear as a matching result but not correspond to the input video clip. Subsequently, if the correlation of Luma vectors from both the input video clip and the database movie is high, a thorough examination is done, further comparing every second within the current index and the next one. The subsequent and final step is an analysis of the Euclidean distance of the vectors, defined by Eq. 3.

$$D = \sqrt{\sum_{i=0}^n (A_i - B_i)^2} \quad (3)$$

Those vectors are the same that were previously used in the Tanimoto correlation algorithm. However, this time, the distance between those vectors is calculated and the lower the distance, the higher the probability that those vectors are the same and, therefore, that the videos are a match. The purpose of this final analysis is to aid the previous Tanimoto correlation to get rid of possible False Negative or False Positive cases.

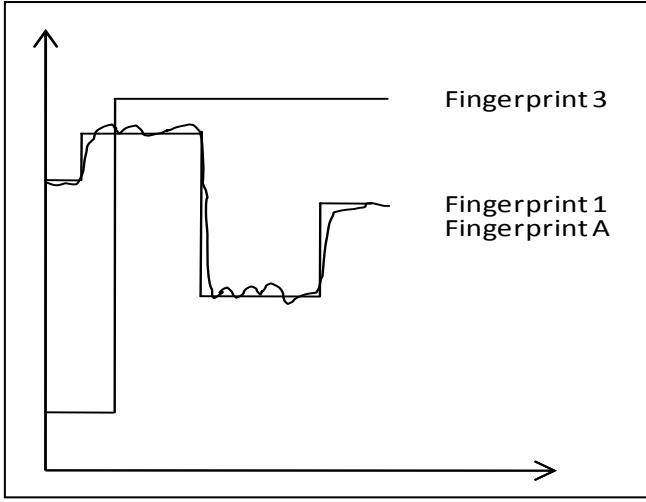


Figure 3. Example of fingerprint comparison

Figure 3 illustrates how the initial stages of the fingerprint matching process work. Fingerprints A, 1 and 3 are compared. Fingerprint A would be the original movie before clustering its information and fingerprint 1 would be the fingerprint of movie A after clustering its information. Clearly, fingerprints 1 and A are a match. However, fingerprint 3 is related to another movie and should be discarded from further comparison in a hypothetical search process.

V. RESULTS

To test our proposed algorithm, we compare it with the CGO [1] algorithm. The 210 targeted movies were downloaded from popular UGC websites, amounting to over 700 minutes of video. The movies have varying resolutions (from VGA (640x480) to FullHD (1920x1080)), lengths (from 1 minute to 60 minutes) and frame-rates (15fps to 30fps). The variety of the videos allows us to make the tests in a large diversity of genres like documentaries, music clips, movie trailers, animations and static image clips generated by users.

The parameters used for the CGO are the same defined by the authors: each frame was partitioned into 8 parts (4 columns and 2 rows), a threshold of 0.4 was chosen and the search sequence is made of 100 consecutive frames (10 seconds). The parameters for our algorithm are set to provide a clearer comparison with CGO. Therefore, the searched sequence length is also 10 seconds. In order to provide a better insight of the influence the Luma value clustering can have, a varying database threshold, between 1 and 30, is analyzed.

Our proposed algorithm, named SUJ, was tested by searching a fragment of each movie against itself and the remaining 209 videos in the database. Each test will, in the end, have 44100 comparisons.

Finally, the hardware spec of the PC used for the experiments was an AMD dual-core running at 2.6 Ghz with 3GB memory. However, all tests were ran using a single core, although the amount of tasks can easily be divided in order to distribute the processing power more evenly. This will be analyzed in further steps of this paper.

A. Analysis of database results

Table I presents the comparison between our proposed solution and the CGO-based solution. In the proposed solution the needed storage for the fingerprints of all 210 movies never exceeds 5Mbytes, while the CGO solution needs over 100Mbytes.

TABLE I. DATABASE RESULTS

SUJ		CGO
<i>DB threshold</i>	<i>Size (Kbytes)</i>	<i>Size (Kbytes)</i>
1	4944	107900
2	3390	
3	2611	
5	1783	
10	1020	
15	678	
20	512	
25	412	
30	348	

Moreover, in Table I we also present several thresholds used in our proposal for the database. Those thresholds are used in the information clustering algorithm, when deciding what degree of Luma variance can be allowed until a new index is created. Lower values of this threshold mean that lower variances of Luma will create a richer set of indexes for a movie, causing the size of the database to grow. On the other hand, high thresholds allow to reducing the size of the database. The implications of such thresholds will be further analyzed in the following sub-sections.

B. Analysis of timing results

This sub-section will present the results obtained when the time performance of the presented solutions is analyzed.

TABLE II. INITIAL IMPORT MEASUREMENTS

	SUJ	CGO
Time (minutes)	181	4538

As explained in Section III, the two compared solutions have large differences in the initial extraction of fingerprints of movies to the databases. More specifically, the CGO-based solution needs to have several calculations done, such as frame partitioning, conversion and the CGO calculations. Those calculations, as presented in Table II are very expensive, and completely shatter any possibilities of using CGO in a real-time environment, with an initial fingerprint extraction time of over 75 hours for the 773 minutes of content. On the other hand, our SUJ scheme took 3 hours to extract the fingerprint of 773 minutes of video, faster than real-time. That allows our

scheme to work inline a video transmission system in a totally real-time way.

Table III presents the time spent in the search of videos for both mechanisms. Here, a section of each one of the 210 videos was looked up in the database. The results were then averaged for all the 210 results obtained.

TABLE III. LOOK UP TIME RESULTS

SUJ		CGO
DB threshold	Avg. Time (s)	Avg. Time (s)
1	74.16	92.41
2	28.38	
3	20.48	
5	13.27	
10	8.84	
15	8.66	
20	10.1	
25	12.42	
30	15.11	

The timing results from our SUJ scheme are lower than CGO, with a minimum average of 8.66 seconds for the time of one lookup averaged over the search within 210 movies. It is also relevant to look into the DB threshold column. A low threshold will make the number of indexes grow and the lookup time increase. As the threshold grows the lookups become faster. However, a too large threshold will make the lookup time grow. This is due to the fact that valuable information is discarded when using large thresholds, making the algorithm analyze sections of videos that are not a real match in later stages. An example of this is depicted in Figure 4.

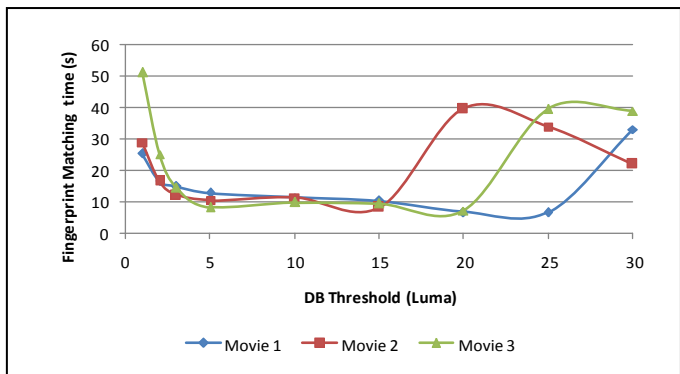


Figure 4. Example of fingerprint timings for 3 movies

In figure 4 the search times are initially high, as expected, due to the high number of indexes created for low threshold values. With an increase of the threshold value, the average search times converge to lower values up to a database threshold of 15. However, after that threshold the values

become higher and unreliable. This is generally seen in every movie, with minor variations of the threshold or timing measurements. This trend show how important is the threshold value for achieving a good performance of the system.

C. Analysis of robustness results

A video fingerprinting platform needs to give accurate results. That accuracy can be expressed by the amount of videos reported as found, but being mismatches (false positives) or by the number of times a video is known to be in a database but the algorithm is not able to find it (false negatives)[8]. Out of the two, it is needless to say that false negatives are certainly more undesirable than false positives.

Our presented solution considers more relevant to properly find every video, even if the result will increase the reported number of false positives.

TABLE IV. SUJ ROBUSTNESS RESULTS

DB threshold	False Positives	False Negatives
1	8	0
2	12	0
3	9	0
5	11	0
10	11	3
15	8	8
20	9	6
25	11	14
30	9	18

Table IV shows the average number of false positives and negatives for the search of every 10-second scene in our test dataset with 210 movies. From the results it can be seen that our solution can effectively find all the matches of every searched 10-second scene within the whole set comprising 776 minutes - or 46,380 seconds- of content in four of the analyzed database thresholds (thresholds 1 to 5). The total number of comparisons performed has been 21,506,406, as a result of all possible 4638 x 4637 comparisons of 10-second scenes across the whole test dataset of 210 movies. Hence, it can be seen that the number of false positives obtained out of the whole dataset is proportionally very low.

As the database threshold increases, the number of false negatives also increases due to loss of information. The clustering algorithm will have less indexes and group larger clusters of Luma, leading to zones with no unique variations of Luma that can identify only small segments of videos.

TABLE V. CGO ROBUSTNESS RESULTS

False Positives	False Negatives
211	1

In contrast, depicted in Table V, CGO presents a larger amount of false positives. While having some false positives would be expected, the amount of false positives attained by CGO is quite large in comparison to our scheme even though there is much more processing involved in obtaining the fingerprints. The number of similar movies obtained that were, in fact, not related to the movie ingested for search would provide a high number of false reports.

VI. SUMMARY AND FUTURE WORK

In this paper, we propose a novel video fingerprinting method based on Tanimoto correlation. We also propose a method to greatly reduce the amount of database information needed to effectively store and search fingerprints of videos.

The results show that our solution can achieve a large improvement over the CGO scheme. Moreover, our method can reduce the amount of False Positives and False Negatives, reduce the time spend on fingerprint matching and reduce the amount of initial processing so that it can effectively be incorporated in a real-time, practical, situation.

The future work will comprise further improvements and comparisons, testing the algorithm against resizing, different compression algorithms, brightness and gamma alterations, subtitling, frame cropping and rotation modifications.

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