Spectral methods: ℓ_2 perturbation theory



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Outline

- Preliminaries: basic matrix analysis
- Distance between two subspaces
- Eigenspace perturbation theory
- Perturbation bounds for singular subspaces
- Eigenvector perturbation bounds for probability transition matrices

Basic matrix analysis

Unitarily invariant norms

Definition 2.1

A matrix norm $\|\cdot\|$ on $\mathbb{R}^{m \times n}$ is said to be unitarily invariant if

$$\|A\| = \|U^{\top}AV\|$$

holds for any matrix $A \in \mathbb{R}^{m \times n}$ and any two square orthonormal matrices $U \in \mathcal{O}^{m \times m}$ and $V \in \mathcal{O}^{n \times n}$.

Examples:

- ullet $\|A\|$: spectral norm (largest singular value of A)
- $\|m{A}\|_{\mathrm{F}}$: Frobenius norm ($\|m{A}\|_{\mathrm{F}} = \sqrt{\mathrm{tr}(m{A}^{ op}m{A})} = \sqrt{\sum_{i,j}A_{i,j}^2}$)

Properties of unitarily invariant norms

Lemma 2.2

For any unitarily invariant norm $\|\cdot\|$, one has

$$\begin{split} \|\boldsymbol{A}\boldsymbol{B}\| &\leq \|\boldsymbol{A}\| \cdot \|\boldsymbol{B}\| \,, & \|\boldsymbol{A}\boldsymbol{B}\| &\leq \|\boldsymbol{B}\| \cdot \|\boldsymbol{A}\| \,, \\ \|\boldsymbol{A}\boldsymbol{B}\| &\geq \|\boldsymbol{A}\| \,\sigma_{\min}\left(\boldsymbol{B}\right), & \|\boldsymbol{A}\boldsymbol{B}\| &\geq \|\boldsymbol{B}\| \,\sigma_{\min}\left(\boldsymbol{A}\right). \end{split}$$

Exercise: prove the lemma for special cases $\|\cdot\|$, and $\|\cdot\|_{\rm F}$

Eigenvalue perturbation bounds

Lemma 2.3 (Weyl's inequality for eigenvalues)

Let $A, E \in \mathbb{R}^{n \times n}$ be two real symmetric matrices. For every $1 \leq i \leq n$, the i-th largest eigenvalues of A and A + E obey

$$\left|\lambda_{i}\left(\boldsymbol{A}\right)-\lambda_{i}\left(\boldsymbol{A}+\boldsymbol{E}\right)\right|\leq\left\Vert \boldsymbol{E}\right\Vert .$$

Eigenvalue perturbation bounds

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eigenvalues of real symmetric matrices are stable against perturbations

Eigenvalue perturbation bounds

Lemma 2.3 (Weyl's inequality for eigenvalues)

Let $A, E \in \mathbb{R}^{n \times n}$ be two real symmetric matrices. For every $1 \leq i \leq n$, the i-th largest eigenvalues of A and A + E obey

$$\left|\lambda_{i}\left(\boldsymbol{A}\right)-\lambda_{i}\left(\boldsymbol{A}+\boldsymbol{E}\right)\right|\leq\left\Vert \boldsymbol{E}\right\Vert .$$

proof left as exercise

eigenvalues of real symmetric matrices are stable against perturbations

Singular value perturbation bounds

Lemma 2.4 (Weyl's inequality for singular values)

Let $A, E \in \mathbb{R}^{m \times n}$ be two general matrices. Then for every $1 \leq i \leq \min\{m,n\}$, the i-th largest singular values of A and A + E obey

$$|\sigma_i(\mathbf{A} + \mathbf{E}) - \sigma_i(\mathbf{A})| \leq ||\mathbf{E}||.$$

Proof of Lemma 2.4

We begin with introducing a useful "dilation" trick:

Definition 2.5 (Symmetric dilation)

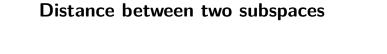
For $m{A} \in \mathbb{R}^{n_1 imes n_2}$, its symmetric dilation $\mathcal{S}(m{A})$ is defined to be

$$\mathcal{S}(oldsymbol{A}) = \left[egin{array}{cc} oldsymbol{0} & oldsymbol{A} \ oldsymbol{A}^ op & oldsymbol{0} \end{array}
ight].$$

Then one has the following eigendecomposition for $\mathcal{S}(A)$:

$$\mathcal{S}(m{A}) = rac{1}{\sqrt{2}} \left[egin{array}{ccc} m{U} & m{U} \\ m{V} & -m{V} \end{array}
ight] \cdot \left[egin{array}{ccc} m{\Sigma} & m{0} \\ m{0} & -m{\Sigma} \end{array}
ight] \cdot rac{1}{\sqrt{2}} \left[egin{array}{ccc} m{U} & m{U} \\ m{V} & -m{V} \end{array}
ight]^{ op}.$$

For $1 \le i \le \min\{m, n\}$, $\lambda_i(\mathcal{S}(\boldsymbol{A})) = \sigma_i(\boldsymbol{A})$. In addition, $\|\mathcal{S}(\boldsymbol{E})\| = \|\boldsymbol{E}\|$.



Setup and notation

- Two r-dimensional subspaces \mathcal{U}^{\star} and \mathcal{U} in \mathbb{R}^n
- ullet Two orthonormal matrices $oldsymbol{U}^{\star}$ and $oldsymbol{U}$ in $\mathbb{R}^{n imes r}$
- ullet Orthogonal complements: $[U^\star, U_\perp^\star]$, and $[U, U_\perp]$

Question: how to define distance?

ullet $\|m{U}-m{U}^\star\|_{ ext{F}}$ and $\|m{U}-m{U}^\star\|$ are not appropriate, since they fall short of accounting for global orthonormal transformation

 \forall orthonormal $R \in \mathbb{R}^{r \times r}, \ U$ and UR represent same subspace

Valid choices of distance

- Distance modulo optimal rotation
- Distance using projection matrices
- Geometric construction via principal angles

Distance modulo optimal rotation

Given global rotation ambiguity, it is natural to adjust for rotation before computing distance:

$$\mathsf{dist}_{\|\cdot\|}(U,U^\star) \coloneqq \min_{R \in \mathcal{O}^{r imes r}} \left\| UR - U^\star
ight\|$$

Distance using projection matrices

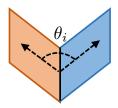
Key observation: projection matrix $UU^{ op}$ associated with subspace $\mathcal U$ is unique

$$\mathsf{dist}_{\mathsf{p},\|\cdot\|}(oldsymbol{U},oldsymbol{U}^\star)\coloneqq ig\|oldsymbol{U}oldsymbol{U}^ op - oldsymbol{U}^\staroldsymbol{U}^{\star op}ig\|$$

Principal angles between two eigen-spaces

In addition to "distance", one might also be interested in "angles"





We can quantify the similarity between two lines (represented resp. by unit vectors u and u^*) by an angle between them

$$\theta = \arccos\langle \boldsymbol{u}, \boldsymbol{u}^{\star} \rangle$$

Principal angles between two eigen-spaces

More generally, for r-dimensional subspaces, one needs r angles

Specifically, given $\|U^\top U^\star\| \le 1$, we write the singular value decomposition (SVD) of $U^\top U^\star \in \mathbb{R}^{r \times r}$ as

$$egin{aligned} oldsymbol{U}^{ op} oldsymbol{U}^{\star} &= oldsymbol{X} egin{bmatrix} \cos heta_1 & & & \\ & \ddots & & \\ & & \cos heta_r \end{bmatrix} oldsymbol{Y}^{ op} &\eqqcolon oldsymbol{X} \cos oldsymbol{\Theta} oldsymbol{Y}^{ op} \end{aligned}$$

where $\{\theta_1, \cdots, \theta_r\}$ are called the principal angles between U and U^{\star}

Distance using principal angles

With principal angles in place, we can define $\sin \Theta$ distance between subspaces as

$$\mathsf{dist}_{\mathsf{sin}, \|\cdot\|}(oldsymbol{U}, oldsymbol{U}^\star) \coloneqq \|\sin\Theta\|$$

Link between projections and principal angles

Lemma 2.6

We have

$$\begin{aligned} & \left\| \boldsymbol{U}\boldsymbol{U}^{\top} - \boldsymbol{U}^{\star}\boldsymbol{U}^{\star\top} \right\| = \|\sin\boldsymbol{\Theta}\| = \left\| \boldsymbol{U}_{\perp}^{\top}\boldsymbol{U}^{\star} \right\| = \left\| \boldsymbol{U}^{\top}\boldsymbol{U}_{\perp}^{\star} \right\|; \\ & \frac{1}{\sqrt{2}} \left\| \boldsymbol{U}\boldsymbol{U}^{\top} - \boldsymbol{U}^{\star}\boldsymbol{U}^{\star\top} \right\|_{\mathrm{F}} = \|\sin\boldsymbol{\Theta}\|_{\mathrm{F}} = \left\| \boldsymbol{U}_{\perp}^{\top}\boldsymbol{U}^{\star} \right\|_{\mathrm{F}} = \left\| \boldsymbol{U}^{\top}\boldsymbol{U}_{\perp}^{\star} \right\|_{\mathrm{F}}. \end{aligned}$$

ullet sanity check: if $oldsymbol{U} = oldsymbol{U}^{\star}$, then everything is 0

Proof of Lemma 2.6

We prove the claim for spectral norm; the claim for Frobenius norm follows similar argument

Note that

$$\|\boldsymbol{U}^{\top}\boldsymbol{U}_{\perp}^{\star}\| = \|\boldsymbol{U}^{\top}\underbrace{\boldsymbol{U}_{\perp}^{\star}\boldsymbol{U}_{\perp}^{\star\top}}_{=\boldsymbol{I}-\boldsymbol{U}^{\star}\boldsymbol{U}^{\star\top}}\boldsymbol{U}\|^{\frac{1}{2}}$$

$$= \|\boldsymbol{U}^{\top}\boldsymbol{U} - \boldsymbol{U}^{\top}\boldsymbol{U}^{\star}\boldsymbol{U}^{\star\top}\boldsymbol{U}\|^{\frac{1}{2}}$$

$$= \|\boldsymbol{I} - \boldsymbol{X}\cos^{2}\boldsymbol{\Theta}\boldsymbol{X}^{\top}\|^{\frac{1}{2}} \qquad (\text{since } \boldsymbol{U}^{\top}\boldsymbol{U}^{\star} = \boldsymbol{X}\cos\boldsymbol{\Theta}\boldsymbol{Y}^{\top})$$

$$= \|\boldsymbol{I} - \cos^{2}\boldsymbol{\Theta}\|^{\frac{1}{2}}$$

$$= \|\sin\boldsymbol{\Theta}^{2}\|^{\frac{1}{2}}$$

$$= \|\sin\boldsymbol{\Theta}\|$$

Proof of Lemma 2.6 (cont.)

Given that singular values are unitarily invariant, it suffices to look at the singular values of the following matrix

$$\left[egin{array}{c} oldsymbol{U}^{ op} \ oldsymbol{U}_{oldsymbol{\perp}}^{ op} \end{array}
ight] (oldsymbol{U}oldsymbol{U}^{ op} - oldsymbol{U}^{\star}oldsymbol{U}^{\star}^{ op}) ig[oldsymbol{U}_{oldsymbol{\perp}}^{\star}, oldsymbol{U}^{\star}ig] = \left[egin{array}{c} oldsymbol{U}^{ op}oldsymbol{U}_{oldsymbol{\perp}}^{\star} & oldsymbol{0} \ oldsymbol{0} & -oldsymbol{U}_{oldsymbol{\perp}}^{ op} oldsymbol{U}^{\star} \end{array}
ight]$$

which further implies

$$\begin{aligned} & \left\| \boldsymbol{U} \boldsymbol{U}^{\top} - \boldsymbol{U}^{\star} \boldsymbol{U}^{\star \top} \right\| = \max \left\{ \left\| \boldsymbol{U}^{\top} \boldsymbol{U}_{\perp}^{\star} \right\|, \left\| \boldsymbol{U}_{\perp}^{\top} \boldsymbol{U}^{\star} \right\| \right\}; \\ & \left\| \boldsymbol{U} \boldsymbol{U}^{\top} - \boldsymbol{U}^{\star} \boldsymbol{U}^{\star \top} \right\|_{F} = \left(\left\| \boldsymbol{U}^{\top} \boldsymbol{U}_{\perp}^{\star} \right\|_{F}^{2} + \left\| \boldsymbol{U}_{\perp}^{\top} \boldsymbol{U}^{\star} \right\|_{F}^{2} \right)^{1/2} \end{aligned}$$

Link between optimal rotations and projections

Lemma 2.7

One has

$$\|\boldsymbol{U}\boldsymbol{U}^{\top} - \boldsymbol{U}^{\star}\boldsymbol{U}^{\star\top}\| \leq \min_{\boldsymbol{R} \in \mathcal{O}^{r \times r}} \|\boldsymbol{U}\boldsymbol{R} - \boldsymbol{U}^{\star}\| \leq \sqrt{2}\|\boldsymbol{U}\boldsymbol{U}^{\top} - \boldsymbol{U}^{\star}\boldsymbol{U}^{\star\top}\|;$$

$$\frac{1}{\sqrt{2}}\|\boldsymbol{U}\boldsymbol{U}^{\top} - \boldsymbol{U}^{\star}\boldsymbol{U}^{\star\top}\|_{F} \leq \min_{\boldsymbol{R} \in \mathcal{O}^{r \times r}} \|\boldsymbol{U}\boldsymbol{R} - \boldsymbol{U}^{\star}\|_{F} \leq \|\boldsymbol{U}\boldsymbol{U}^{\top} - \boldsymbol{U}^{\star}\boldsymbol{U}^{\star\top}\|_{F}.$$

— proof left as exercise

Summary of distance metrics

So far we have discussed

- 1) $\|\boldsymbol{U}\boldsymbol{U}^{\top} \boldsymbol{U}^{\star}\boldsymbol{U}^{\star\top}\|$
- 2) $\|\sin \Theta\|$
- 3) $\|\boldsymbol{U}_{\perp}^{\mathsf{T}}\boldsymbol{U}^{\star}\| = \|\boldsymbol{U}^{\mathsf{T}}\boldsymbol{U}_{\perp}^{\star}\|$
- 4) $\min_{\boldsymbol{R} \in \mathcal{O}^{r \times r}} \| \boldsymbol{U} \boldsymbol{R} \boldsymbol{U}^{\star} \|$

Summary of distance metrics

So far we have discussed

- 1) $\|\boldsymbol{U}\boldsymbol{U}^{\top} \boldsymbol{U}^{\star}\boldsymbol{U}^{\star\top}\|$
- 2) $\|\sin \Theta\|$
- 3) $\|\boldsymbol{U}_{\perp}^{\mathsf{T}}\boldsymbol{U}^{\star}\| = \|\boldsymbol{U}^{\mathsf{T}}\boldsymbol{U}_{\perp}^{\star}\|$
- 4) $\min_{\boldsymbol{R} \in \mathcal{O}^{r \times r}} \| \boldsymbol{U} \boldsymbol{R} \boldsymbol{U}^{\star} \|$

Our choice of distance:

$$ext{dist}(\boldsymbol{U}, \boldsymbol{U}^{\star}) \coloneqq \min_{\boldsymbol{R} \in \mathcal{O}^{r imes r}} \left\| \boldsymbol{U} \boldsymbol{R} - \boldsymbol{U}^{\star} \right\|;$$
 $ext{dist}_{\mathrm{F}}(\boldsymbol{U}, \boldsymbol{U}^{\star}) \coloneqq \min_{\boldsymbol{R} \in \mathcal{O}^{r imes r}} \left\| \boldsymbol{U} \boldsymbol{R} - \boldsymbol{U}^{\star} \right\|_{\mathrm{F}}$

Eigen-space perturbation theory

Setup and notation

Consider 2 symmetric matrices $m{M}$, $\hat{m{M}} = m{M} + m{H} \in \mathbb{R}^{n imes n}$ with eigen-decompositions

$$m{M} = \sum_{i=1}^n \lambda_i m{u}_i m{u}_i^ op \qquad ext{and} \qquad \hat{m{M}} = \sum_{i=1}^n \hat{\lambda}_i \hat{m{u}}_i \hat{m{u}}_i^ op$$

where $\lambda_1 \geq \cdots \geq \lambda_n$; $\hat{\lambda}_1 \geq \cdots \geq \hat{\lambda}_n$. For simplicity, write

$$egin{aligned} m{M} &= [m{U}_0, m{U}_1] \left[egin{array}{ccc} m{\Lambda}_0 & & \ & m{\Lambda}_1 \end{array}
ight] \left[egin{array}{ccc} m{U}_0^ op \ m{U}_1^ op \end{array}
ight] \ \hat{m{M}} &= [\hat{m{U}}_0, \hat{m{U}}_1] \left[egin{array}{cccc} \hat{m{\Lambda}}_0 & & \ & \hat{m{\Lambda}}_1 \end{array}
ight] \left[egin{array}{cccc} \hat{m{U}}_0^ op \ \hat{m{U}}_1^ op \end{array}
ight] \end{aligned}$$

Here, $U_0 = [u_1, \cdots, u_r]$, $\Lambda_0 = \operatorname{diag}([\lambda_1, \cdots, \lambda_r])$, \cdots

Setup and notation

Davis-Kahan $\sin \Theta$ theorem: a simple case



Chandler Davis



William Kahan

Theorem 2.8

Suppose $M^{\star} \succeq \mathbf{0}$ and is rank-r. If $\|\mathbf{E}\| < (1 - 1/\sqrt{2})\lambda_r(M^{\star})$, then

$$\begin{aligned} \operatorname{dist}(\boldsymbol{U}, \boldsymbol{U}^{\star}) &\leq \sqrt{2} \| \sin \boldsymbol{\Theta} \| \leq \frac{2 \| \boldsymbol{E} \boldsymbol{U}^{\star} \|}{\lambda_r(\boldsymbol{M}^{\star})} \leq \frac{2 \| \boldsymbol{E} \|}{\lambda_r(\boldsymbol{M}^{\star})}; \\ \operatorname{dist}_{\mathrm{F}}(\boldsymbol{U}, \boldsymbol{U}^{\star}) &\leq \sqrt{2} \| \sin \boldsymbol{\Theta} \|_{\mathrm{F}} \leq \frac{2 \| \boldsymbol{E} \boldsymbol{U}^{\star} \|_{\mathrm{F}}}{\lambda_r(\boldsymbol{M}^{\star})} \leq \frac{2 \sqrt{r} \| \boldsymbol{E} \|}{\lambda_r(\boldsymbol{M}^{\star})}. \end{aligned}$$

Interpretations of Davis-Kahan's $\sin \Theta$ theorem

Suppose $M^\star \succeq \mathbf{0}$ and is rank-r. If $\| \pmb{E} \| < (1-1/\sqrt{2}) \lambda_r(\pmb{M}^\star)$, then

$$\mathsf{dist}\big(\boldsymbol{U},\boldsymbol{U}^{\star}\big) \leq \sqrt{2}\|\sin\boldsymbol{\Theta}\| \leq \frac{2\|\boldsymbol{E}\boldsymbol{U}^{\star}\|}{\lambda_{r}(\boldsymbol{M}^{\star})} \leq \frac{2\|\boldsymbol{E}\|}{\lambda_{r}(\boldsymbol{M}^{\star})}.$$

Remarks:

- ullet Eigen-gap $\lambda_r(M^\star) = \lambda_r(M^\star) \lambda_{r+1}(M^\star)$
- ullet Perturbation size $\|oldsymbol{E}\|$
- ullet Inverse signal-to-noise ratio $\dfrac{\|oldsymbol{E}\|}{\lambda_r(oldsymbol{M}^\star)}$
- Necessity of $\|E\| \lesssim \lambda_r(M^\star)$

What happens when SNR is small?

A toy example

$$\boldsymbol{M}^{\star} = \left[\begin{array}{cc} 1 + \epsilon & 0 \\ 0 & 1 - \epsilon \end{array} \right], \quad \boldsymbol{E} = \left[\begin{array}{cc} -\epsilon & \epsilon \\ \epsilon & \epsilon \end{array} \right], \quad \boldsymbol{M} = \left[\begin{array}{cc} 1 & \epsilon \\ \epsilon & 1 \end{array} \right],$$

where $0<\epsilon<1$ can be arbitrarily small. It is straightforward to check that the leading eigenvectors of ${\pmb M}^\star$ and ${\pmb M}$ are given respectively by

$$m{u}_1^\star = \left[egin{array}{c} 1 \\ 0 \end{array}
ight], \qquad ext{and} \qquad m{u}_1 = rac{1}{\sqrt{2}} \left[egin{array}{c} 1 \\ 1 \end{array}
ight].$$

Consequently, we have

$$\|oldsymbol{u}_1oldsymbol{u}_1^{ op}-oldsymbol{u}_1^{\star}oldsymbol{u}_1^{\star}^{ op}\|=rac{1}{\sqrt{2}}, \quad ext{and} \quad \|oldsymbol{u}_1oldsymbol{u}_1^{ op}-oldsymbol{u}_1^{\star}oldsymbol{u}_1^{\star}^{ op}\|_{ ext{F}}=1, \quad ext{(2.6)}$$

which are both quite large regardless of the size of ϵ or the size of the perturbation $\|E\|$.

Proof of Theorem 2.8

We intend to control $U_{\perp}^{\top}U^{\star}$ by studying their interactions through E:

$$\boldsymbol{U}_{\perp}^{\top}(\boldsymbol{M}-\boldsymbol{M}^{\star})\boldsymbol{U}^{\star}=\boldsymbol{\Lambda}_{\perp}\boldsymbol{U}_{\perp}^{\top}\boldsymbol{U}^{\star}-\boldsymbol{U}_{\perp}^{\top}\boldsymbol{U}^{\star}\boldsymbol{\Lambda}^{\star},\tag{2.7}$$

which together with triangle inequality implies

$$\| \boldsymbol{U}_{\perp}^{\top} \boldsymbol{E} \boldsymbol{U}^{\star} \| \geq \| \boldsymbol{U}_{\perp}^{\top} \boldsymbol{U}^{\star} \boldsymbol{\Lambda}^{\star} \| - \| \boldsymbol{\Lambda}_{\perp} \boldsymbol{U}_{\perp}^{\top} \boldsymbol{U}^{\star} \|$$

$$\geq \sigma_{\min}(\boldsymbol{\Lambda}^{\star}) \| \boldsymbol{U}_{\perp}^{\top} \boldsymbol{U}^{\star} \| - \| \boldsymbol{\Lambda}_{\perp} \| \cdot \| \boldsymbol{U}_{\perp}^{\top} \boldsymbol{U}^{\star} \|$$
(2.8)

In view of Weyl's lemma, one has $\|\hat{\Lambda}_{\perp}\| \leq \|E\|$. In addition, we have $\sigma_{\min}(\Lambda^{\star}) = \lambda_r(M^{\star})$. These combined with relation (2.8) give

$$|||\boldsymbol{U}_{\perp}^{\top}\boldsymbol{U}^{\star}||| \leq \frac{|||\boldsymbol{U}_{\perp}^{\top}\boldsymbol{E}\boldsymbol{U}^{\star}|||}{\lambda_{r}(\boldsymbol{M}^{\star}) - ||\boldsymbol{E}||} \leq \frac{\sqrt{2}||\boldsymbol{U}_{\perp}|| \cdot |||\boldsymbol{E}\boldsymbol{U}^{\star}|||}{\lambda_{r}(\boldsymbol{M}^{\star})} = \frac{\sqrt{2}|||\boldsymbol{E}\boldsymbol{U}^{\star}|||}{\lambda_{r}(\boldsymbol{M}^{\star})}$$

This together with Lemmas 2.6-2.7 completes the proof

Work until here

Davis-Kahan $\sin \Theta$ Theorem: general case

Theorem 2.9 (Davis-Kahan $\sin \Theta$ Theorem)

Suppose $\lambda_r(\mathbf{M}) \geq a$ and $\lambda_{r+1}(\hat{\mathbf{M}}) \leq a - \Delta$ for some $\Delta > 0$. Then

$$\mathsf{dist}(\hat{oldsymbol{U}}_0, oldsymbol{U}_0) \leq rac{\|oldsymbol{E} oldsymbol{U}_0\|}{\Delta} \leq rac{\|oldsymbol{E}\|}{\Delta}$$

ullet immediate consequence: if $\lambda_r(oldsymbol{M})>\lambda_{r+1}(oldsymbol{M})+\|oldsymbol{E}\|$, then

$$\operatorname{dist}(\hat{\boldsymbol{U}}_{0}, \boldsymbol{U}_{0}) \leq \underbrace{\frac{\|\boldsymbol{E}\|}{\lambda_{r}(\boldsymbol{M}) - \lambda_{r+1}(\boldsymbol{M})} - \|\boldsymbol{E}\|}_{\text{spectral gap}} \tag{2.9}$$

Perturbation theory for singular subspaces

Singular value decomposition

Consider two matrices $M, \hat{M} = M + E \in \mathbb{R}^{n_1 \times n_2}$ with SVD

$$egin{aligned} m{M} &= [m{U}_0, m{U}_1] \left[egin{array}{ccc} m{\Sigma}_0 & \mathbf{0} \ \mathbf{0} & m{\Sigma}_1 \ \mathbf{0} & \mathbf{0} \end{array}
ight] \left[m{V}_0^ op \ m{V}_1^ op \end{array}
ight] \ \hat{m{M}} &= \left[\hat{m{U}}_0, \hat{m{U}}_1
ight] \left[egin{array}{cccc} \hat{m{\Sigma}}_0 & \mathbf{0} \ \mathbf{0} & \hat{m{\Sigma}}_1 \ \mathbf{0} & \mathbf{0} \end{array}
ight] \left[m{\hat{V}}_0^ op \ \hat{m{V}}_1^ op \end{array}
ight] \end{aligned}$$

where U_0 (resp. \hat{U}_0) and V_0 (resp. \hat{V}_0) represent the top-r singular subspaces of M (resp. \hat{M})

Wedin's $\sin \Theta$ theorem

The Davis-Kahan Theorem generalizes to singular subspace perturbation:

Theorem 2.10 (Wedin's sin⊕ theorem)

$$\begin{split} & \text{If } \|\boldsymbol{E}\| < \sigma_r^{\star} - \sigma_{r+1}^{\star}, \text{ then one has} \\ & \max \left\{ \mathsf{dist}(\boldsymbol{U}, \boldsymbol{U}^{\star}), \mathsf{dist}(\boldsymbol{V}, \boldsymbol{V}^{\star}) \right\} \leq \frac{\sqrt{2} \max \left\{ \|\boldsymbol{E}^{\top} \boldsymbol{U}^{\star}\|, \|\boldsymbol{E} \boldsymbol{V}^{\star}\| \right\}}{\sigma_r^{\star} - \sigma_{r+1}^{\star} - \|\boldsymbol{E}\|}; \\ & \max \left\{ \mathsf{dist}_{\mathrm{F}}(\boldsymbol{U}, \boldsymbol{U}^{\star}), \mathsf{dist}_{\mathrm{F}}(\boldsymbol{V}, \boldsymbol{V}^{\star}) \right\} \leq \frac{\sqrt{2} \max \left\{ \|\boldsymbol{E}^{\top} \boldsymbol{U}^{\star}\|_{\mathrm{F}}, \|\boldsymbol{E} \boldsymbol{V}^{\star}\|_{\mathrm{F}} \right\}}{\sigma_r^{\star} - \sigma_{r+1}^{\star} - \|\boldsymbol{E}\|} \end{split}$$

Spectral methods:
$$\ell_2$$
 perturbation theory

Proof of Theorem 2.10

$$U_{\perp}^{\top} U^{*} = U_{\perp}^{\top} (U^{*} \Sigma^{*} V^{*\top}) V^{*} \Sigma^{*-1}$$

$$= U_{\perp}^{\top} \left(M - E - U_{\perp}^{*} \Sigma_{\perp}^{*} V_{\perp}^{*\top} \right) V^{*} \Sigma^{*-1}$$

$$= U_{\perp}^{\top} \left(U \Sigma V^{\top} + U_{\perp} \Sigma_{\perp} V_{\perp}^{\top} - E - U_{\perp}^{*} \Sigma_{\perp}^{*} V_{\perp}^{*\top} \right) V^{*} \Sigma^{*-1}$$

$$= \Sigma_{\perp} V_{\perp}^{\top} V^{*} \Sigma^{*-1} - U_{\perp}^{\top} E V^{*} \Sigma^{*-1}. \tag{2.10}$$

Applying the triangle inequality and Lemma 2.2 in Section $\ref{eq:2}$ to the identity (2.10) yields

$$\|\boldsymbol{U}_{\perp}^{\top}\boldsymbol{U}^{\star}\| \leq \|\boldsymbol{\Sigma}_{\perp}\| \cdot \|\boldsymbol{V}_{\perp}^{\top}\boldsymbol{V}^{\star}\| \cdot \|\boldsymbol{\Sigma}^{\star-1}\| + \|\boldsymbol{U}_{\perp}^{\top}\| \cdot \|\boldsymbol{E}\boldsymbol{V}^{\star}\| \cdot \|\boldsymbol{\Sigma}^{\star-1}\|$$

$$= \sigma_{r+1} \cdot \|\boldsymbol{V}_{\perp}^{\top}\boldsymbol{V}^{\star}\| \cdot \frac{1}{\sigma_{r}^{\star}} + \|\boldsymbol{E}\boldsymbol{V}^{\star}\| \cdot \frac{1}{\sigma_{r}^{\star}}$$

$$\leq \frac{\sigma_{r+1}^{\star} + \|\boldsymbol{E}\|}{\sigma_{r}^{\star}} \|\boldsymbol{V}_{\perp}^{\top}\boldsymbol{V}^{\star}\| + \frac{\|\boldsymbol{E}\boldsymbol{V}^{\star}\|}{\sigma_{r}^{\star}}.$$
(2.11)

Proof of Theorem 2.10 (cont.)

Repeating the same argument yields

$$\||\boldsymbol{V}_{\perp}^{\top}\boldsymbol{V}^{\star}\|| \leq \frac{\|\boldsymbol{E}^{\top}\boldsymbol{U}^{\star}\|\|}{\sigma_{r}^{\star}} + \frac{\sigma_{r+1}^{\star} + \|\boldsymbol{E}\|}{\sigma_{r}^{\star}} \||\boldsymbol{U}_{\perp}^{\top}\boldsymbol{U}^{\star}\|\|.$$
(2.12)

To finish up, combine the inequalities (2.11) and (2.12) to obtain

$$\max \left\{ \left\| \left\| \boldsymbol{U}_{\perp}^{\top} \boldsymbol{U}^{\star} \right\| , \left\| \boldsymbol{V}_{\perp}^{\top} \boldsymbol{V}^{\star} \right\| \right\} \leq \frac{\max \left\{ \left\| \boldsymbol{E}^{\top} \boldsymbol{U}^{\star} \right\| , \left\| \boldsymbol{E} \boldsymbol{V}^{\star} \right\| \right\}}{\sigma_{r}^{\star}} + \frac{\sigma_{r+1}^{\star} + \left\| \boldsymbol{E} \right\|}{\sigma_{r}^{\star}} \max \left\{ \left\| \boldsymbol{U}_{\perp}^{\top} \boldsymbol{U}^{\star} \right\| , \left\| \boldsymbol{V}_{\perp}^{\top} \boldsymbol{V}^{\star} \right\| \right\}.$$

When $\|E\| < \sigma_r^\star - \sigma_{r+1}^\star$, we can rearrange terms to arrive at

$$\max \left\{ \left\| \left\| \boldsymbol{U}_{\perp}^{\top} \boldsymbol{U}^{\star} \right\| , \left\| \boldsymbol{V}_{\perp}^{\top} \boldsymbol{V}^{\star} \right\| \right\} \leq \frac{\max \left\{ \left\| \boldsymbol{E}^{\top} \boldsymbol{U}^{\star} \right\| , \left\| \boldsymbol{E} \boldsymbol{V}^{\star} \right\| \right\}}{\sigma_{r}^{\star} - \sigma_{r+1}^{\star} - \left\| \boldsymbol{E} \right\|}.$$

The proof is then completed by invoking Lemmas ?? and 2.7.

Extensions of Wedin's theorem

- Single rotation matrix
- Separate bounds for left and right singular vectors

Eigenvector perturbation for probability transition matrices

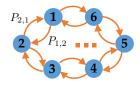
Eigen-decomposition for asymmetric matrices

Eigen-decomposition for asymmetric matrices is much more tricky:

- 1. both eigenvalues and eigenvectors might be complex-valued
- 2. eigenvectors might not be orthogonal to each other

This lecture focuses on a special case: **probability transition matrices**

Probability transition matrices



Consider a Markov chain $\{X_t\}_{t\geq 0}$

- n states
- transition probability $\mathbb{P}\{X_{t+1} = j \mid X_t = i\} = P_{i,j}$
- transition matrix ${m P} = [P_{i,j}]_{1 \le i,j \le n}$
- ullet stationary distribution $\underline{\pi=[\pi_1,\cdots,\pi_n]}_{\pi_1+\cdots+\pi_n=1}$ is 1st eigenvector of $m{P}$

$$\pi P = \pi$$

• $\{X_t\}_{t\geq 0}$ is said to be reversible if $\pi_i P_{i,j} = \pi_j P_{j,i}$ for all i, j

Eigenvector perturbation for transition matrices

Define
$$\|\boldsymbol{a}\|_{\boldsymbol{\pi}} := \sqrt{\pi_1 a_1^2 + \cdots + \pi_n a_n^2}$$

Theorem 2.11 (Chen, Fan, Ma, Wang '17)

Suppose P, \hat{P} are transition matrices with stationary distributions π , $\hat{\pi}$, respectively. Assume P induces a reversible Markov chain. If $1 > \max{\{\lambda_2(P), -\lambda_n(P)\}} + \|\hat{P} - P\|_{\pi}$, then

$$\|\hat{\boldsymbol{\pi}} - \boldsymbol{\pi}\|_{\boldsymbol{\pi}} \leq \underbrace{\frac{\left\|\boldsymbol{\pi}(\hat{\boldsymbol{P}} - \boldsymbol{P})\right\|_{\boldsymbol{\pi}}}{1 - \max\left\{\lambda_2(\boldsymbol{P}), -\lambda_n\left(\boldsymbol{P}\right)\right\}} - \underbrace{\left\|\hat{\boldsymbol{P}} - \boldsymbol{P}\right\|_{\boldsymbol{\pi}}}_{\text{perturbation}}}$$

ullet \hat{P} does not need to induce a reversible Markov chain

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