# **NetworkX Reference**

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# **CONTENTS**

1	1.1 Who uses NetworkX?  1.2 The Python programming language  1.3 Free software  1.4 Goals	1 1 1 1 2
2	2.1 NetworkX Basics	<b>3</b> 4
3	3.1 Which graph class should I use?	<b>9</b> 9
4	Operators         4.1 Graph Manipulation       12         4.2 Node Relabeling       13         4.3 Freezing       13	9
5	Algorithms       13         5.1 Boundary       13         5.2 Centrality       13         5.3 Clique       14         5.4 Clustering       14         5.5 Cores       14         5.6 Matching       14         5.7 Isomorphism       14         5.8 PageRank       16         5.9 HTTS       16         5.10 Traversal       16         5.11 Bipartite       18         5.12 Minimum Spanning Tree       18	7 8 2 5 7 8 8 1 3 4 0
6	Graph generators       18.         6.1 Atlas       18.         6.2 Classic       18.         6.3 Small       19.         6.4 Random Graphs       19.         6.5 Degree Sequence       20.	5 6 0 4

	6.6 Directed 6.7 Geometric 6.8 Hybrid 6.9 Bipartite	. 213 . 213
7	Linear algebra 7.1 Spectrum	<b>217</b> . 217
8	Converting to and from other formats 8.1 Convert	
9	Reading and writing graphs         9.1 Adjacency List          9.2 Edge List          9.3 GML          9.4 Pickle          9.5 GraphML          9.6 LEDA          9.7 YAML          9.8 SparseGraph6          9.9 Pajek	. 231 . 233 . 235 . 236 . 236 . 237
10	Drawing 10.1 Matplotlib 10.2 Graphviz AGraph (dot) 10.3 Graphviz with pydot 10.4 Graph Layout  10.5 Drawing 10.7 Drawing 10.8 Graphviz AGraph (dot) 10.9 Graphviz with pydot 10.9 Graph Layout	. 245 . 248
11	Exceptions	255
12	Utilities  12.1 Helper functions	. 258 . 258
13	License	261
14	Citing	263
15	Credits	265
16	Glossary	267
Bil	bliography	269
Mo	odule Index	271
Inc	dex	273

**CHAPTER** 

ONE

# INTRODUCTION

NetworkX is a Python-based package for the creation, manipulation, and study of the structure, dynamics, and function of complex networks.

The structure of a graph or network is encoded in the **edges** (connections, links, ties, arcs, bonds) between **nodes** (vertices, sites, actors). If unqualified, by graph we mean an undirected graph, i.e. no multiple edges are allowed. By a network we usually mean a graph with weights (fields, properties) on nodes and/or edges.

### 1.1 Who uses NetworkX?

The potential audience for NetworkX includes mathematicians, physicists, biologists, computer scientists, and social scientists. The current state of the art of the science of complex networks is presented in Albert and Barabási [BA02], Newman [Newman03], and Dorogovtsev and Mendes [DM03]. See also the classic texts [Bollobas01], [Diestel97] and [West01] for graph theoretic results and terminology. For basic graph algorithms, we recommend the texts of Sedgewick, e.g. [Sedgewick01] and [Sedgewick02] and the survey of Brandes and Erlebach [BE05].

# 1.2 The Python programming language

Why Python? Past experience showed this approach to maximize productivity, power, multi-disciplinary scope (applications include large communication, social, data and biological networks), and platform independence. This philosophy does not exclude using whatever other language is appropriate for a specific subtask, since Python is also an excellent "glue" language [Langtangen04]. Equally important, Python is free, well-supported and a joy to use. Among the many guides to Python, we recommend the documentation at <a href="http://www.python.org">http://www.python.org</a> and the text by Alex Martelli [Martelli03].

### 1.3 Free software

NetworkX is free software; you can redistribute it and/or modify it under the terms of the *NetworkX License*. We welcome contributions from the community. Information on NetworkX development is found at the NetworkX Developer Zone <a href="https://networkx.lanl.gov/trac">https://networkx.lanl.gov/trac</a>.

### 1.4 Goals

NetworkX is intended to:

- · Be a tool to study the structure and dynamics of social, biological, and infrastructure networks
- · Provide ease-of-use and rapid development in a collaborative, multidisciplinary environment
- Be an Open-source software package that can provide functionality to a diverse community of active and easily participating users and developers.
- Provide an easy interface to existing code bases written in C, C++, and FORTRAN
- Painlessly slurp in large nonstandard data sets
- Provide a standard API and/or graph implementation that is suitable for many applications.

# 1.5 History

- NetworkX was inspired by Guido van Rossum's 1998 Python graph representation essay [vanRossum98].
- First public release in April 2005. Version 1.0 released in 2009.

#### 1.5.1 What Next

- A Brief Tour
- Installing
- Reference
- Examples

**CHAPTER** 

**TWO** 

# **OVERVIEW**

The structure of NetworkX can be seen by the organization of its source code. The package provides classes for graph objects, generators to create standard graphs, IO routines for reading in existing datasets, algorithms to analyse the resulting networks and some basic drawing tools.

Most of the NetworkX API is provided by functions which take a graph object as an argument. Methods of the graph object are limited to basic manipulation and reporting. This provides modularity of code and documentation. It also makes it easier for newcomers to learn about the package in stages. The source code for each module is meant to be easy to read and reading this Python code is actually a good way to learn more about network algorithms, but we have put a lot of effort into making the documentation sufficient and friendly. If you have suggestions or questions please contact us by joining the NetworkX Google group.

Classes are named using CamelCase (capital letters at the start of each word). functions, methods and variable names are lower\_case\_underscore (lowercase with an underscore representing a space between words).

### 2.1 NetworkX Basics

After starting Python, import the networkx module with (the recommended way)

```
>>> import networkx as nx
```

To save repetition, in the documentation we assume that NetworkX has been imported this way.

If importing networkx fails, it means that Python cannot find the installed module. Check your installation and your PYTHONPATH.

The following basic graph types are provided as Python classes:

**Graph** This class implements an undirected graph. It ignores multiple edges between two nodes. It does allow self-loop edges between a node and itself.

**DiGraph** Directed graphs, that is, graphs with directed edges. Operations common to directed graphs, (a subclass of Graph).

**MultiGraph** A flexible graph class that allows multiple undirected edges between pairs of nodes. The additional flexibility leads to some degradation in performance, though usually not significant.

MultiDiGraph A directed version of a MultiGraph.

Empty graph-like objects are created with

```
>>> G=nx.Graph()
>>> G=nx.DiGraph()
```

```
>>> G=nx.MultiGraph()
>>> G=nx.MultiDiGraph()
```

All graph classes allow any *hashable* object as a node. Hashable objects include strings, tuples, integers, and more. Arbitrary edge attributes such as weights and labels can be associated with an edge.

The graph internal data structures are based on an adjacency list representation and implemented using Python *dictionary* datastructures. The graph adjaceny structure is implemented as a Python dictionary of dictionaries; the outer dictionary is keyed by nodes to values that are themselves dictionaries keyed by neighboring node to the edge attributes associated with that edge. This "dict-of-dicts" structure allows fast addition, deletion, and lookup of nodes and neighbors in large graphs. The underlying datastructure is accessed directly by methods (the programming interface "API") in the class definitions. All functions, on the other hand, manipulate graph-like objects solely via those API methods and not by acting directly on the datastructure. This design allows for possible replacement of the 'dicts-of-dicts'-based datastructure with an alternative datastructure that implements the same methods.

### **2.1.1 Graphs**

The first choice to be made when using NetworkX is what type of graph object to use. A graph (network) is a collection of nodes together with a collection of edges that are pairs of nodes. Attributes are often associated with nodes and/or edges. NetworkX graph objects come in different flavors depending on two main properties of the network:

- Directed: Are the edges **directed**? Does the order of the edge pairs (u,v) matter? A directed graph is specified by the "Di" prefix in the class name, e.g. DiGraph(). We make this distinction because many classical graph properties are defined differently for directed graphs.
- Multi-edges: Are multiple edges allowed between each pair of nodes? As you might imagine, multiple edges requires a different data structure, though tricky users could design edge data objects to support this functionality. We provide a standard data structure and interface for this type of graph using the prefix "Multi", e.g. MultiGraph().

The basic graph classes are named: Graph, DiGraph, MultiGraph, and MultiDiGraph

# 2.2 Nodes and Edges

The next choice you have to make when specifying a graph is what kinds of nodes and edges to use.

If the topology of the network is all you care about then using integers or strings as the nodes makes sense and you need not worry about edge data. If you have a data structure already in place to describe nodes you can simply use that structure as your nodes provided it is *hashable*. If it is not hashable you can use a unique identifier to represent the node and assign the data as a *node attribute*.

Edges often have data associated with them. Arbitrary data can associated with edges as an *edge attribute*. If the data is numeric and the intent is to represent a *weighted* graph then use the 'weight' keyword for the attribute. Some of the graph algorithms, such as Dijkstra's shortest path algorithm, use this attribute name to get the weight for each edge.

Other attributes can be assigned to an edge by using keyword/value pairs when adding edges. You can use any keyword except 'weight' to name your attribute and can then easily query the edge data by that attribute keyword.

Once you've decided how to encode the nodes and edges, and whether you have an undirected/directed graph with or without multiedges you are ready to build your network.

#### 2.2.1 Graph Creation

NetworkX graph objects can be created in one of three ways:

- Graph generators standard algorithms to create network topologies.
- Importing data from pre-existing (usually file) sources.
- · Adding edges and nodes explicitly.

Explicit addition and removal of nodes/edges is the easiest to describe. Each graph object supplies methods to manipulate the graph. For example,

```
>>> import networkx as nx
>>> G=nx.Graph()
>>> G.add_edge(1,2) # default edge data=1
>>> G.add_edge(2,3,weight=0.9) # specify edge data
```

Edge attributes can be anything:

```
>>> import math
>>> G.add_edge('y','x',function=math.cos)
>>> G.add_node(math.cos) # any hashable can be a node
```

You can add many edges at one time:

```
>>> elist=[('a','b',5.0),('b','c',3.0),('a','c',1.0),('c','d',7.3)]
>>> G.add_weighted_edges_from(elist)
```

See the /tutorial/index for more examples.

Some basic graph operations such as union and intersection are described in the *Operators module* documentation.

Graph generators such as binomial\_graph and powerlaw\_graph are provided in the *Graph generators* subpackage.

For importing network data from formats such as GML, GraphML, edge list text files see the *Reading and writing graphs* subpackage.

### 2.2.2 Graph Reporting

Class methods are used for the basic reporting functions neighbors, edges and degree. Reporting of lists is often needed only to iterate through that list so we supply iterator versions of many property reporting methods. For example edges() and nodes() have corresponding methods edges\_iter() and nodes\_iter(). Using these methods when you can will save memory and often time as well.

The basic graph relationship of an edge can be obtained in two basic ways. One can look for neighbors of a node or one can look for edges incident to a node. We jokingly refer to people who focus on nodes/neighbors as node-centric and people who focus on edges as edge-centric. The designers of NetworkX tend to be node-centric and view edges as a relationship between nodes. You can see this by our avoidance of notation like G[u,v] in favor of G[u][v]. Most data structures for sparse graphs are essentially adjacency lists and so fit this perspective. In the end, of course, it doesn't really matter which way you examine the graph. G.edges() removes duplicate representations of each edge while G.neighbors(n) or G[n] is slightly faster but doesn't remove duplicates.

Any properties that are more complicated than edges, neighbors and degree are provided by functions. For example nx.triangles(G,n) gives the number of triangles which include node n as a vertex. These functions are grouped in the code and documentation under the term *algorithms*.

### 2.2.3 Algorithms

A number of graph algorithms are provided with NetworkX. These include shortest path, and breadth first search (see *traversal*), clustering and isomorphism algorithms and others. There are many that we have not developed yet too. If you implement a graph algorithm that might be useful for others please let us know through the NetworkX Google group or the Developer Zone.

As an example here is code to use Dijkstra's algorithm to find the shortest weighted path:

```
>>> G=nx.Graph()
>>> e=[('a','b',0.3),('b','c',0.9),('a','c',0.5),('c','d',1.2)]
>>> G.add_weighted_edges_from(e)
>>> print nx.dijkstra_path(G,'a','d')
['a', 'c', 'd']
```

### 2.2.4 Drawing

While NetworkX is not designed as a network layout tool, we provide a simple interface to drawing packages and some simple layout algorithms. We interface to the excellent Graphviz layout tools like dot and neato with the (suggested) pygraphviz package or the pydot interface. Drawing can be done using external programs or the Matplotlib Python package. Interactive GUI interfaces are possible though not provided. The drawing tools are provided in the module *drawing*.

The basic drawing functions essentially place the nodes on a scatterplot using the positions in a dictionary or computed with a layout function. The edges are then lines between those dots.

```
>>> G=nx.cubical_graph()
>>> nx.draw(G) # default spring_layout
>>> nx.draw(G,pos=nx.spectral_layout(G), nodecolor='r',edge_color='b')
```

See the examples for more ideas.

#### 2.2.5 Data Structure

NetworkX uses a "dictionary of dictionaries of dictionaries" as the basic network data structure. This allows fast lookup with reasonable storage for large sparse networks. The keys are nodes so G[u] returns an adjacency dictionary keyed by neighbor to the edge attribute dictionary. The expression G[u][v] returns the edge attribute dictionary itself. A dictionary of lists would have also been possible, but not allowed fast edge detection nor convenient storage of edge data.

Advantages of dict-of-dicts-of-dicts data structure:

- Find edges and remove edges with two dictionary look-ups.
- Prefer to "lists" because of fast lookup with sparse storage.
- Prefer to "sets" since data can be attached to edge.
- G[u][v] returns the edge attribute dictionary.
- n in G tests if node n is in graph G.
- for n in G: iterates through the graph.
- for nbr in G[n]: iterates through neighbors.

As an example, here is a representation of an undirected graph with the edges ('A','B'), ('B','C')

```
>>> G=nx.Graph()
>>> G.add_edge('A','B')
>>> G.add_edge('B','C')
>>> print G.adj
{'A': {'B': {}}, 'C': {'B': {}}, 'B': {'A': {}}, 'C': {}}}
```

The data structure gets morphed slightly for each base graph class. For DiGraph two dict-of-dicts-of-dicts structures are provided, one for successors and one for predecessors. For MultiGraph/MultiDiGraph we use a dict-of-dicts-of-dicts-of-dicts of-dicts of-dicts

Graphs use a dictionary of attributes for each edge. We use a dict-of-dicts-of-dicts data structure with the inner dictionary storing "name-value" relationships for that edge.

```
>>> G=nx.Graph()
>>> G.add_edge(1,2,color='red',weight=0.84,size=300)
>>> print G[1][2]['size']
300
```

<sup>&</sup>lt;sup>1</sup> "It's dictionaries all the way down."

# **GRAPH TYPES**

NetworkX provides data structures and methods for storing graphs.

All NetworkX graph classes allow (hashable) Python objects as nodes. and any Python object can be assigned as an edge attribute.

The choice of graph class depends on the structure of the graph you want to represent.

## 3.1 Which graph class should I use?

Graph Type	NetworkX Class
Undirected Simple	Graph
Directed Simple	DiGraph
With Self-loops	Graph, DiGraph
With Parallel edges	MultiGraph, MultiDiGraph

# 3.2 Basic graph types

### 3.2.1 Graph – Undirected graphs with self loops

#### Overview

Graph (data=None, name=", \*\*attr)

Base class for undirected graphs.

A Graph stores nodes and edges with optional data, or attributes.

Graphs hold undirected edges. Self loops are allowed but multiple (parallel) edges are not.

Nodes can be arbitrary (hashable) Python objects with optional key/value attributes.

Edges are represented as links between nodes with optional key/value attributes.

Parameters data: input graph

Data to initialize graph. If data=None (default) an empty graph is created. The data can be an edge list, or any NetworkX graph object. If the corresponding optional Python packages are installed the data can also be a NumPy matrix or 2d ndarray, a SciPy sparse matrix, or a PyGraphviz graph.

name : string, optional (default='')

An optional name for the graph.

attr: keyword arguments, optional (default= no attributes)

Attributes to add to graph as key=value pairs.

#### See Also:

```
DiGraph, MultiGraph, MultiDiGraph
```

### **Examples**

Create an empty graph structure (a "null graph") with no nodes and no edges.

```
>>> G = nx.Graph()
```

G can be grown in several ways.

#### **Nodes:**

Add one node at a time:

```
>>> G.add_node(1)
```

Add the nodes from any container (a list, dict, set or even the lines from a file or the nodes from another graph).

```
>>> G.add_nodes_from([2,3])
>>> G.add_nodes_from(range(100,110))
>>> H=nx.path_graph(10)
>>> G.add_nodes_from(H)
```

In addition to strings and integers any hashable Python object (except None) can represent a node, e.g. a customized node object, or even another Graph.

```
>>> G.add_node(H)
```

#### **Edges:**

G can also be grown by adding edges.

Add one edge,

```
>>> G.add_edge(1, 2)
a list of edges,
>>> G.add_edges_from([(1,2),(1,3)])
or a collection of edges,
>>> G.add_edges_from(H.edges())
```

If some edges connect nodes not yet in the graph, the nodes are added automatically. There are no errors when adding nodes or edges that already exist.

#### **Attributes:**

Each graph, node, and edge can hold key/value attribute pairs in an associated attribute dictionary (the keys must be hashable). By default these are empty, but can be added or changed using add\_edge, add\_node or direct manipulation of the attribute dictionaries named graph, node and edge respectively.

```
>>> G = nx.Graph(day="Friday")
>>> G.graph
{'day': 'Friday'}
```

Add node attributes using add\_node(), add\_nodes\_from() or G.node

```
>>> G.add_node(1, time='5pm')
>>> G.add_nodes_from([3], time='2pm')
>>> G.node[1]
{'time': '5pm'}
>>> G.node[1]['room'] = 714
>>> G.nodes(data=True)
[(1, {'room': 714, 'time': '5pm'}), (3, {'time': '2pm'})]
```

Warning: adding a node to G.node does not add it to the graph.

Add edge attributes using add\_edge(), add\_edges\_from(), subscript notation, or G.edge.

```
>>> G.add_edge(1, 2, weight=4.7 )
>>> G.add_edges_from([(3,4),(4,5)], color='red')
>>> G.add_edges_from([(1,2,{'color':'blue'}), (2,3,{'weight':8})])
>>> G[1][2]['weight'] = 4.7
>>> G.edge[1][2]['weight'] = 4
```

#### **Shortcuts:**

Many common graph features allow python syntax to speed reporting.

```
>>> 1 in G  # check if node in graph
True
>>> print [n for n in G if n<3]  # iterate through nodes
[1, 2]
>>> print len(G)  # number of nodes in graph
5
>>> print G[1]  # adjacency dict keyed by neighbor to edge attributes
...  # Note: you should not change this dict manually!
{2: {'color': 'blue', 'weight': 4}}
```

The fastest way to traverse all edges of a graph is via adjacency\_iter(), but the edges() method is often more convenient.

#### **Reporting:**

Simple graph information is obtained using methods. Iterator versions of many reporting methods exist for efficiency. Methods exist for reporting nodes(), edges(), neighbors() and degree() as well as the number of nodes and edges.

For details on these and other miscellaneous methods, see below.

#### Adding and removing nodes and edges

```
Graph.___init___(**attr[, data, name])
                                                Initialize a graph with edges, name, graph attributes.
Graph.add node(n, **attr[, attr dict])
                                                Add a single node n and update node attributes.
Graph.add_nodes_from(nodes, **attr)
                                                Add multiple nodes.
Graph.remove_node(n)
                                                Remove node n.
                                                Remove multiple nodes.
Graph.remove_nodes_from(nodes)
Graph.add_edge(u, v, **attr[, attr_dict])
                                                Add an edge between u and v.
Graph.add_edges_from(ebunch, **attr[,
                                                Add all the edges in ebunch.
attr_dict])
Graph.add_weighted_edges_from(ebunch,
                                               Add all the edges in ebunch as weighted edges with
                                                specified weights.
Graph.remove edge(u, v)
                                                Remove the edge between u and v.
Graph.remove edges from(ebunch)
                                                Remove all edges specified in ebunch.
Graph.add_star(nlist, **attr)
                                                Add a star.
Graph.add_path(nlist, **attr)
                                                Add a path.
Graph.add_cycle(nlist, **attr)
                                                Add a cycle.
Graph.clear()
                                                Remove all nodes and edges from the graph.
```

### networkx.Graph. init

```
__init__(data=None, name=", **attr)
Initialize a graph with edges, name, graph attributes.
```

#### Parameters data: input graph

Data to initialize graph. If data=None (default) an empty graph is created. The data can be an edge list, or any NetworkX graph object. If the corresponding optional Python packages are installed the data can also be a NumPy matrix or 2d ndarray, a SciPy sparse matrix, or a PyGraphviz graph.

name : string, optional (default='')

An optional name for the graph.

**attr**: keyword arguments, optional (default= no attributes)

Attributes to add to graph as key=value pairs.

#### See Also:

convert

### **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G = nx.Graph(name='my graph')
>>> e = [(1,2),(2,3),(3,4)] # list of edges
>>> G = nx.Graph(e)
```

Arbitrary graph attribute pairs (key=value) may be assigned

```
>>> G=nx.Graph(e, day="Friday")
>>> G.graph
{'day': 'Friday'}
```

### networkx.Graph.add\_node

```
add_node (n, attr_dict=None, **attr)
```

Add a single node n and update node attributes.

Parameters n: node

A node can be any hashable Python object except None.

attr\_dict : dictionary, optional (default= no attributes)

Dictionary of node attributes. Key/value pairs will update existing data associated with the node.

attr: keyword arguments, optional

Set or change attributes using key=value.

#### See Also:

```
add_nodes_from
```

#### **Notes**

A hashable object is one that can be used as a key in a Python dictionary. This includes strings, numbers, tuples of strings and numbers, etc.

On many platforms hashable items also include mutables such as NetworkX Graphs, though one should be careful that the hash doesn't change on mutables.

### **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_node(1)
>>> G.add_node('Hello')
>>> K3 = nx.Graph([(0,1),(1,2),(2,0)])
>>> G.add_node(K3)
>>> G.number_of_nodes()
3
```

Use keywords set/change node attributes:

```
>>> G.add_node(1,size=10)
>>> G.add_node(3,weight=0.4,UTM=('138',382871,3972649))
```

### networkx.Graph.add\_nodes\_from

```
add_nodes_from (nodes, **attr)
    Add multiple nodes.
```

Parameters nodes: iterable container

A container of nodes (list, dict, set, etc.). The container will be iterated through once.

**attr**: keyword arguments, optional (default= no attributes)

Update attributes for all nodes in nodes.

#### See Also:

add\_node

### **Examples**

```
>>> G = nx.Graph()  # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_nodes_from('Hello')
>>> K3 = nx.Graph([(0,1),(1,2),(2,0)])
>>> G.add_nodes_from(K3)
>>> sorted(G.nodes())
[0, 1, 2, 'H', 'e', 'l', 'o']
```

Use keywords to update specific node attributes for every node.

```
>>> G.add_nodes_from([1,2], size=10)
>>> G.add_nodes_from([3,4], weight=0.4)
```

### networkx.Graph.remove\_node

```
remove\_node(n)
```

Remove node n.

Removes the node n and all adjacent edges. Attempting to remove a non-existent node will raise an exception.

Parameters n: node

A node in the graph

Raises NetworkXError:

If n is not in the graph.

#### See Also:

```
remove_nodes_from
```

### **Examples**

```
>>> G = nx.Graph()  # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2])
>>> G.edges()
[(0, 1), (1, 2)]
```

```
>>> G.remove_node(1)
>>> G.edges()
[]
```

### networkx.Graph.remove\_nodes\_from

```
remove_nodes_from(nodes)
```

Remove multiple nodes.

Parameters nodes: iterable container

A container of nodes (list, dict, set, etc.). If a node in the container is not in the graph it is silently ignored.

#### See Also:

remove\_node

### **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2])
>>> e = G.nodes()
>>> e
[0, 1, 2]
>>> G.remove_nodes_from(e)
>>> G.nodes()
[]
```

### networkx.Graph.add\_edge

```
add_edge (u, v, attr_dict=None, **attr)
```

Add an edge between u and v.

The nodes u and v will be automatically added if they are not already in the graph.

Edge attributes can be specified with keywords or by providing a dictionary with key/value pairs. See examples below.

#### Parameters u,v: nodes

Nodes can be, for example, strings or numbers. Nodes must be hashable (and not None) Python objects.

attr\_dict : dictionary, optional (default= no attributes)

Dictionary of edge attributes. Key/value pairs will update existing data associated with the edge.

attr: keyword arguments, optional

Edge data (or labels or objects) can be assigned using keyword arguments.

#### See Also:

add edges from add a collection of edges

#### **Notes**

Adding an edge that already exists updates the edge data.

NetworkX algorithms designed for weighted graphs use as the edge weight a numerical value assigned to the keyword 'weight'.

### **Examples**

The following all add the edge e=(1,2) to graph G:

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> e = (1,2)
>>> G.add_edge(1, 2) # explicit two-node form
>>> G.add_edge(*e) # single edge as tuple of two nodes
>>> G.add_edges_from([(1,2)]) # add edges from iterable container
```

Associate data to edges using keywords:

```
>>> G.add_edge(1, 2, weight=3)
>>> G.add_edge(1, 3, weight=7, capacity=15, length=342.7)
```

### networkx.Graph.add\_edges\_from

```
add_edges_from (ebunch, attr_dict=None, **attr)
Add all the edges in ebunch.
```

Parameters ebunch: container of edges

Each edge given in the container will be added to the graph. The edges must be given as as 2-tuples (u,v) or 3-tuples (u,v,d) where d is a dictionary containing edge data.

```
attr_dict : dictionary, optional (default= no attributes)
```

Dictionary of edge attributes. Key/value pairs will update existing data associated with each edge.

attr: keyword arguments, optional

Edge data (or labels or objects) can be assigned using keyword arguments.

#### See Also:

```
add_edge add a single edge
add_weighted_edges_from convenient way to add weighted edges
```

#### **Notes**

Adding the same edge twice has no effect but any edge data will be updated when each duplicate edge is added.

### **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_edges_from([(0,1),(1,2)]) # using a list of edge tuples
>>> e = zip(range(0,3),range(1,4))
>>> G.add_edges_from(e) # Add the path graph 0-1-2-3

Associate data to edges
>>> G.add_edges_from([(1,2),(2,3)], weight=3)
>>> G.add_edges_from([(3,4),(1,4)], label='WN2898')
```

### networkx.Graph.add\_weighted\_edges\_from

```
add_weighted_edges_from(ebunch, **attr)
```

Add all the edges in ebunch as weighted edges with specified weights.

Parameters ebunch: container of edges

Each edge given in the list or container will be added to the graph. The edges must be given as 3-tuples (u,v,w) where w is a number.

attr: keyword arguments, optional (default= no attributes)

Edge attributes to add/update for all edges.

#### See Also:

```
add_edge add a single edge
add_edges_from add multiple edges
```

#### **Notes**

Adding the same edge twice has no effect but any edge data will be updated when each duplicate edge is added.

### **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_weighted_edges_from([(0,1,3.0),(1,2,7.5)])
```

### networkx.Graph.remove\_edge

```
\verb"remove_edge"\,(u,\,v)
```

Remove the edge between u and v.

#### Parameters u,v: nodes:

Remove the edge between nodes u and v.

#### Raises NetworkXError:

If there is not an edge between u and v.

#### See Also:

remove\_edges\_from remove a collection of edges

### **Examples**

```
>>> G = nx.Graph() # or DiGraph, etc
>>> G.add_path([0,1,2,3])
>>> G.remove_edge(0,1)
>>> e = (1,2)
>>> G.remove_edge(*e) # unpacks e from an edge tuple
>>> e = (2,3,{'weight':7}) # an edge with attribute data
>>> G.remove_edge(*e[:2]) # select first part of edge tuple
```

### networkx.Graph.remove\_edges\_from

```
remove_edges_from(ebunch)
```

Remove all edges specified in ebunch.

#### Parameters ebunch: list or container of edge tuples :

Each edge given in the list or container will be removed from the graph. The edges can be:

- 2-tuples (u,v) edge between u and v.
- 3-tuples (u,v,k) where k is ignored.

#### See Also:

remove\_edge remove a single edge

### **Notes**

Will fail silently if an edge in ebunch is not in the graph.

### **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> ebunch=[(1,2),(2,3)]
>>> G.remove_edges_from(ebunch)
```

### networkx.Graph.add\_star

```
add_star (nlist, **attr)
    Add a star.
```

The first node in nlist is the middle of the star. It is connected to all other nodes in nlist.

Parameters nlist: list

A list of nodes.

attr: keyword arguments, optional (default= no attributes)

Attributes to add to every edge in star.

#### See Also:

```
add_path, add_cycle
```

### **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_star([0,1,2,3])
>>> G.add_star([10,11,12],weight=2)
```

### networkx.Graph.add\_path

```
add_path (nlist, **attr)
Add a path.
```

Parameters nlist: list

A list of nodes. A path will be constructed from the nodes (in order) and added to the graph.

attr : keyword arguments, optional (default= no attributes)

Attributes to add to every edge in path.

#### See Also:

```
add_star,add_cycle
```

### **Examples**

```
>>> G=nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> G.add_path([10,11,12], weight=7)
```

### networkx.Graph.add\_cycle

```
add_cycle (nlist, **attr)
Add a cycle.
```

Parameters nlist: list

A list of nodes. A cycle will be constructed from the nodes (in order) and added to the graph.

attr: keyword arguments, optional (default= no attributes)

Attributes to add to every edge in cycle.

#### See Also:

```
add_path, add_star
```

### **Examples**

```
>>> G=nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_cycle([0,1,2,3])
>>> G.add_cycle([10,11,12], weight=7)
```

### networkx.Graph.clear

```
clear()
```

Remove all nodes and edges from the graph.

This also removes the name, and all graph, node, and edge attributes.

### **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> G.clear()
>>> G.nodes()
[]
>>> G.edges()
[]
```

#### Iterating over nodes and edges

```
Graph.nodes([data])
                                          Return a list of the nodes in the graph.
Graph.nodes_iter([data])
                                          Return an iterator over the nodes.
Graph.__iter__()
                                          Iterate over the nodes.
Graph.edges([nbunch, data])
                                          Return a list of edges.
Graph.edges_iter([nbunch, data])
                                          Return an iterator over the edges.
                                          Return the attribute dictionary associated with edge (u,v).
Graph.get_edge_data(u, v[, default])
Graph.neighbors(n)
                                          Return a list of the nodes connected to the node n.
Graph.neighbors iter(n)
                                          Return an iterator over all neighbors of node n.
Graph.__getitem__(n)
                                          Return a dict of neighbors of node n.
Graph.adjacency_list()
                                          Return an adjacency list representation of the graph.
Graph.adjacency_iter()
                                          Return an iterator of (node, adjacency dict) tuples for all nodes.
Graph.nbunch_iter([nbunch])
                                          Return an iterator of nodes contained in nbunch that are also in the graph.
```

### networkx.Graph.nodes

```
nodes (data=False)
```

Return a list of the nodes in the graph.

**Parameters data**: boolean, optional (default=False)

If False return a list of nodes. If True return a two-tuple of node and node data dictionary

Returns nlist: list

A list of nodes. If data=True a list of two-tuples containing (node, node data dictionary).

### **Examples**

```
>>> G = nx.Graph()  # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2])
>>> print G.nodes()
[0, 1, 2]
>>> G.add_node(1, time='5pm')
>>> print G.nodes(data=True)
[(0, {}), (1, {'time': '5pm'}), (2, {})]
```

### networkx.Graph.nodes\_iter

```
nodes_iter(data=False)
```

Return an iterator over the nodes.

**Parameters data**: boolean, optional (default=False)

If False the iterator returns nodes. If True return a two-tuple of node and node data dictionary

Returns niter: iterator

An iterator over nodes. If data=True the iterator gives two-tuples containing (node, node data, dictionary)

#### **Notes**

If the node data is not required it is simpler and equivalent to use the expression 'for n in G'.

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2])
>>> for n in G:
... print n,
0 1 2
```

### **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2])
>>> for n in G.nodes_iter():
...    print n,
0 1 2
>>> for n,d in G.nodes_iter(data=True):
...    print d,
{} {} {}
```

### networkx.Graph.\_\_iter\_\_

```
___iter__()
```

Iterate over the nodes. Use the expression 'for n in G'.

Returns niter: iterator

An iterator over all nodes in the graph.

### **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> for n in G:
... print n,
0 1 2 3
```

### networkx.Graph.edges

edges (nbunch=None, data=False)

Return a list of edges.

Edges are returned as tuples with optional data in the order (node, neighbor, data).

**Parameters nbunch**: iterable container, optional (default= all nodes)

A container of nodes. The container will be iterated through once.

data: bool, optional (default=False)

Return two tuples (u,v) (False) or three-tuples (u,v,data) (True).

#### Returns edge\_list: list of edge tuples :

Edges that are adjacent to any node in nbunch, or a list of all edges if nbunch is not specified.

#### See Also:

edges\_iter return an iterator over the edges

### **Notes**

Nodes in nbunch that are not in the graph will be (quietly) ignored.

### **Examples**

```
>>> G = nx.Graph()  # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> G.edges()
[(0, 1), (1, 2), (2, 3)]
>>> G.edges(data=True) # default edge data is {} (empty dictionary)
[(0, 1, {}), (1, 2, {}), (2, 3, {})]
```

```
>>> G.edges([0,3])
[(0, 1), (3, 2)]
>>> G.edges(0)
[(0, 1)]
```

### networkx.Graph.edges\_iter

```
edges_iter (nbunch=None, data=False)
```

Return an iterator over the edges.

Edges are returned as tuples with optional data in the order (node, neighbor, data).

**Parameters nbunch**: iterable container, optional (default= all nodes)

A container of nodes. The container will be iterated through once.

data: bool, optional (default=False)

If True, return edge attribute dict in 3-tuple (u,v,data).

Returns edge iter: iterator

An iterator of (u,v) or (u,v,d) tuples of edges.

See Also:

edges return a list of edges

#### **Notes**

Nodes in nbunch that are not in the graph will be (quietly) ignored.

### **Examples**

```
>>> G = nx.Graph() # or MultiGraph, etc
>>> G.add_path([0,1,2,3])
>>> [e for e in G.edges_iter()]
[(0, 1), (1, 2), (2, 3)]
>>> list(G.edges_iter(data=True)) # default data is {} (empty dict)
[(0, 1, {}), (1, 2, {}), (2, 3, {})]
>>> list(G.edges_iter([0,3]))
[(0, 1), (3, 2)]
>>> list(G.edges_iter(0))
[(0, 1)]
```

### networkx.Graph.get edge data

```
get_edge_data(u, v, default=None)
```

Return the attribute dictionary associated with edge (u,v).

**Parameters u,v**: nodes

default: any Python object (default=None) :

Value to return if the edge (u,v) is not found.

```
Returns edge_dict: dictionary
```

The edge attribute dictionary.

#### **Notes**

It is faster to use G[u][v].

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> G[0][1]
{}
```

Warning: Assigning G[u][v] corrupts the graph data structure. But it is safe to assign attributes to that dictionary,

```
>>> G[0][1]['weight'] = 7
>>> G[0][1]['weight']
7
>>> G[1][0]['weight']
7
```

### **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> G.get_edge_data(0,1) # default edge data is {}
{}
>>> e = (0,1)
>>> G.get_edge_data(*e) # tuple form
{}
>>> G.get_edge_data('a','b',default=0) # edge not in graph, return 0
0
```

### networkx.Graph.neighbors

```
neighbors(n)
```

Return a list of the nodes connected to the node n.

Parameters n: node

A node in the graph

Returns nlist: list

A list of nodes that are adjacent to n.

Raises NetworkXError:

If the node n is not in the graph.

### **Notes**

It is usually more convenient (and faster) to access the adjacency dictionary as G[n]:

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_edge('a','b',weight=7)
>>> G['a']
{'b': {'weight': 7}}
```

### **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> G.neighbors(0)
[1]
```

### networkx.Graph.neighbors\_iter

```
neighbors\_iter(n)
```

Return an iterator over all neighbors of node n.

#### **Notes**

It is faster to use the idiom "in G[0]", e.g. >>> for n in G[0]: ... print n 1

### **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> print [n for n in G.neighbors_iter(0)]
[1]
```

## networkx.Graph.\_\_getitem\_\_

```
__getitem__(n)
```

Return a dict of neighbors of node n. Use the expression 'G[n]'.

Parameters n : node

A node in the graph.

Returns adj\_dict: dictionary

The adjacency dictionary for nodes connected to n.

#### **Notes**

G[n] is similar to G.neighbors(n) but the internal data dictionary is returned instead of a list.

Assigning G[n] will corrupt the internal graph data structure. Use G[n] for reading data only.

### **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> print G[0]
{1: {}}
```

### networkx.Graph.adjacency\_list

```
adjacency_list()
```

Return an adjacency list representation of the graph.

The output adjacency list is in the order of G.nodes(). For directed graphs, only outgoing adjacencies are included.

Returns adj\_list: lists of lists

The adjacency structure of the graph as a list of lists.

#### See Also:

```
adjacency_iter
```

### **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> G.adjacency_list() # in order given by G.nodes()
[[1], [0, 2], [1, 3], [2]]
```

### networkx.Graph.adjacency\_iter

```
adjacency_iter()
```

Return an iterator of (node, adjacency dict) tuples for all nodes.

This is the fastest way to look at every edge. For directed graphs, only outgoing adjacencies are included.

```
Returns adj_iter: iterator
```

An iterator of (node, adjacency dictionary) for all nodes in the graph.

#### See Also:

```
adjacency_list
```

### **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> [(n,nbrdict) for n,nbrdict in G.adjacency_iter()]
[(0, {1: {}}), (1, {0: {}, 2: {}}), (2, {1: {}, 3: {}}), (3, {2: {}})]
```

### networkx.Graph.nbunch iter

```
nbunch_iter(nbunch=None)
```

Return an iterator of nodes contained in nbunch that are also in the graph.

The nodes in nbunch are checked for membership in the graph and if not are silently ignored.

Parameters nbunch: iterable container, optional (default=all nodes)

A container of nodes. The container will be iterated through once.

Returns niter: iterator

An iterator over nodes in nbunch that are also in the graph. If nbunch is None, iterate over all nodes in the graph.

#### Raises NetworkXError:

If nbunch is not a node or or sequence of nodes. If a node in nbunch is not hashable.

#### See Also:

```
Graph.__iter__
```

#### **Notes**

When nbunch is an iterator, the returned iterator yields values directly from nbunch, becoming exhausted when nbunch is exhausted.

To test whether nbunch is a single node, one can use "if nbunch in self:", even after processing with this routine.

If nbunch is not a node or a (possibly empty) sequence/iterator or None, a NetworkXError is raised. Also, if any object in nbunch is not hashable, a NetworkXError is raised.

#### Information about graph structure

Graph.has_node(n)	Return True if the graph contains the node n.
Graphcontains(n)	Return True if n is a node, False otherwise. Use the expression
$Graph.has\_edge(u, v)$	Return True if the edge (u,v) is in the graph.
<pre>Graph.nodes_with_selfloops()</pre>	Return a list of nodes with self loops.
<pre>Graph.selfloop_edges([data])</pre>	Return a list of selfloop edges.
Graph.order()	Return the number of nodes in the graph.
<pre>Graph.number_of_nodes()</pre>	Return the number of nodes in the graph.
Graphlen()	Return the number of nodes.
<pre>Graph.size([weighted])</pre>	Return the number of edges.
${ t Graph.number\_of\_edges([u,v])}$	Return the number of edges between two nodes.
<pre>Graph.number_of_selfloops()</pre>	Return the number of selfloop edges.
<pre>Graph.degree([nbunch, with_labels, weighted])</pre>	Return the degree of a node or nodes.
<pre>Graph.degree_iter([nbunch, weighted])</pre>	Return an iterator for (node, degree).

### networkx.Graph.has\_node

```
has\_node(n)
```

Return True if the graph contains the node n.

Parameters n: node

### **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2])
>>> print G.has_node(0)
True
```

It is more readable and simpler to use

```
>>> 0 in G
True
```

### networkx.Graph. contains

```
__contains__(n)
```

Return True if n is a node, False otherwise. Use the expression 'n in G'.

### **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> print 1 in G
True
```

### networkx.Graph.has edge

```
has\_edge(u, v)
```

Return True if the edge (u,v) is in the graph.

Parameters u,v: nodes

Nodes can be, for example, strings or numbers. Nodes must be hashable (and not None) Python objects.

Returns edge\_ind: bool

True if edge is in the graph, False otherwise.

### **Examples**

Can be called either using two nodes u,v or edge tuple (u,v)

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> G.has_edge(0,1) # using two nodes
True
>>> e = (0,1)
>>> G.has_edge(*e) # e is a 2-tuple (u,v)
True
>>> e = (0,1,{'weight':7})
>>> G.has_edge(*e[:2]) # e is a 3-tuple (u,v,data_dictionary)
True
The following syntax are all equivalent:
>>> G.has_edge(0,1)
True
>>> 1 in G[0] # though this gives KeyError if 0 not in G
```

### networkx.Graph.nodes\_with\_selfloops

```
nodes_with_selfloops()
```

Return a list of nodes with self loops.

A node with a self loop has an edge with both ends adjacent to that node.

Returns nodelist: list

A list of nodes with self loops.

#### See Also:

True

```
selfloop_edges, number_of_selfloops
```

#### **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_edge(1,1)
>>> G.add_edge(1,2)
>>> G.nodes_with_selfloops()
[1]
```

### networkx.Graph.selfloop\_edges

```
selfloop_edges (data=False)
```

Return a list of selfloop edges.

A selfloop edge has the same node at both ends.

```
Parameters data: bool, optional (default=False)
```

Return selfloop edges as two tuples (u,v) (data=False) or three-tuples (u,v,data) (data=True)

Returns edgelist: list of edge tuples

A list of all selfloop edges.

#### See Also:

```
selfloop_nodes, number_of_selfloops
```

### **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_edge(1,1)
>>> G.add_edge(1,2)
>>> G.selfloop_edges()
[(1, 1)]
>>> G.selfloop_edges(data=True)
[(1, 1, {})]
```

### networkx.Graph.order

```
order()
```

Return the number of nodes in the graph.

Returns nnodes: int

The number of nodes in the graph.

#### See Also:

```
number_of_nodes, __len__
```

### networkx.Graph.number\_of\_nodes

```
number_of_nodes()
```

Return the number of nodes in the graph.

Returns nnodes: int

The number of nodes in the graph.

#### See Also:

```
order, __len__
```

### **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2])
>>> print len(G)
3
```

### networkx.Graph.\_\_len\_\_

```
__len__()
```

Return the number of nodes. Use the expression 'len(G)'.

Returns nnodes: int

The number of nodes in the graph.

### **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> print len(G)
4
```

### networkx.Graph.size

```
size (weighted=False)
```

Return the number of edges.

**Parameters weighted**: boolean, optional (default=False)

If True return the sum of the edge weights.

Returns nedges: int

The number of edges in the graph.

#### See Also:

```
number_of_edges
```

### **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> G.size()
3
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_edge('a','b',weight=2)
>>> G.add_edge('b','c',weight=4)
>>> G.size()
2
>>> G.size(weighted=True)
6
```

### networkx.Graph.number\_of\_edges

```
number_of_edges (u=None, v=None)
```

Return the number of edges between two nodes.

**Parameters u,v**: nodes, optional (default=all edges)

If u and v are specified, return the number of edges between u and v. Otherwise return the total number of all edges.

Returns nedges: int

The number of edges in the graph. If nodes u and v are specified return the number of edges between those nodes.

#### See Also:

size

### **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> G.number_of_edges()
3
>>> G.number_of_edges(0,1)
1
>>> e = (0,1)
>>> G.number_of_edges(*e)
```

### networkx.Graph.number\_of\_selfloops

```
number_of_selfloops()
```

Return the number of selfloop edges.

A selfloop edge has the same node at both ends.

Returns nloops: int

The number of selfloops.

#### See Also:

```
selfloop_nodes, selfloop_edges
```

### **Examples**

```
>>> G=nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_edge(1,1)
>>> G.add_edge(1,2)
>>> G.number_of_selfloops()
1
```

### networkx.Graph.degree

```
degree (nbunch=None, with_labels=False, weighted=False) Return the degree of a node or nodes.
```

The node degree is the number of edges adjacent to that node.

Parameters nbunch: iterable container, optional (default=all nodes)

A container of nodes. The container will be iterated through once.

with\_labels : bool, optional (default=False)

If True return a dictionary of degrees keyed by node.

weighted: bool, optional (default=False)

If True return the sum of edge weights adjacent to the node.

Returns nd: list, or dictionary

A list of node degrees or a dictionary with nodes as keys and degree as values if with\_labels=True).

# **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> G.degree(0)
1
>>> G.degree([0,1])
[1, 2]
>>> G.degree([0,1], with_labels=True)
{0: 1, 1: 2}
```

# networkx.Graph.degree\_iter

```
degree_iter (nbunch=None, weighted=False)
```

Return an iterator for (node, degree).

The node degree is the number of edges adjacent to the node.

**Parameters nbunch**: iterable container, optional (default=all nodes)

A container of nodes. The container will be iterated through once.

weighted : bool, optional (default=False)

If True return the sum of edge weights adjacent to the node.

Returns nd iter: an iterator

The iterator returns two-tuples of (node, degree).

### See Also:

degree

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> list(G.degree_iter(0)) # node 0 with degree 1
```

```
[(0, 1)]
>>> list(G.degree_iter([0,1]))
[(0, 1), (1, 2)]
```

## Making copies and subgraphs

```
Graph.copy()
Graph.to_directed()
Graph.subgraph(nbunch[, copy])
Return a copy of the graph.
Return a directed representation of the graph.
Return the subgraph induced on nodes in nbunch.
```

## networkx.Graph.copy

#### copy()

Return a copy of the graph.

Returns G: Graph

A copy of the graph.

#### See Also:

to\_directed return a directed copy of the graph.

### **Notes**

This makes a complete copy of the graph including all of the node or edge attributes.

## **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> H = G.copy()
```

## networkx.Graph.to\_directed

```
to directed()
```

Return a directed representation of the graph.

## Returns G: DiGraph

A directed graph with the same name, same nodes, and with each edge (u,v,data) replaced by two directed edges (u,v,data) and (v,u,data).

## **Notes**

This is similar to DiGraph(self) which returns a shallow copy. self.to\_undirected() returns a deepcopy of edge, node and graph attributes.

## **Examples**

```
>>> G = nx.Graph() # or MultiGraph, etc
>>> G.add_path([0,1])
>>> H = G.to_directed()
>>> H.edges()
[(0, 1), (1, 0)]

If already directed, return a (deep) copy

>>> G = nx.DiGraph() # or MultiDiGraph, etc
>>> G.add_path([0,1])
>>> H = G.to_directed()
>>> H.edges()
```

## networkx.Graph.subgraph

[(0, 1)]

```
subgraph (nbunch, copy=True)
```

Return the subgraph induced on nodes in nbunch.

The induced subgraph of the graph has the nodes in nbunch as its node set and the edges adjacent to those nodes as its edge set.

Parameters nbunch: list, iterable

A container of nodes. The container will be iterated through once.

```
copy: bool, optional (default=True)
```

If True return a new graph holding the subgraph including copies of all edge and node properties. If False the subgraph is created using the original graph by deleting all nodes not in nbunch (this changes the original graph).

## Returns G: Graph

A subgraph of the graph. If copy=True a new graph is returned with copies of graph, node, and edge data. If copy=False the subgraph is created in place by modifying the original graph.

### **Notes**

If copy=True, nodes and edges are copied using copy.deepcopy.

```
>>> G = nx.Graph()  # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> H = G.subgraph([0,1,2])
>>> print H.edges()
[(0, 1), (1, 2)]
```

## 3.2.2 DiGraph - Directed graphs with self loops

#### Overview

```
DiGraph (data=None, name=", **attr)
Base class for directed graphs.
```

A DiGraph stores nodes and edges with optional data, or attributes.

DiGraphs hold directed edges. Self loops are allowed but multiple (parallel) edges are not.

Nodes can be arbitrary (hashable) Python objects with optional key/value attributes.

Edges are represented as links between nodes with optional key/value attributes.

### Parameters data: input graph

Data to initialize graph. If data=None (default) an empty graph is created. The data can be an edge list, or any NetworkX graph object. If the corresponding optional Python packages are installed the data can also be a NumPy matrix or 2d ndarray, a SciPy sparse matrix, or a PyGraphviz graph.

```
name : string, optional (default='')
```

An optional name for the graph.

**attr**: keyword arguments, optional (default= no attributes)

Attributes to add to graph as key=value pairs.

### See Also:

```
Graph, MultiGraph, MultiDiGraph
```

## **Examples**

Create an empty graph structure (a "null graph") with no nodes and no edges.

```
>>> G = nx.DiGraph()
```

G can be grown in several ways.

### **Nodes:**

Add one node at a time:

```
>>> G.add_node(1)
```

Add the nodes from any container (a list, dict, set or even the lines from a file or the nodes from another graph).

```
>>> G.add_nodes_from([2,3])
>>> G.add_nodes_from(range(100,110))
>>> H=nx.path_graph(10)
>>> G.add_nodes_from(H)
```

In addition to strings and integers any hashable Python object (except None) can represent a node, e.g. a customized node object, or even another Graph.

```
>>> G.add_node(H)
```

### **Edges:**

G can also be grown by adding edges.

Add one edge,

```
>>> G.add_edge(1, 2)
a list of edges,
>>> G.add_edges_from([(1,2),(1,3)])
or a collection of edges,
>>> G.add_edges_from(H.edges())
```

If some edges connect nodes not yet in the graph, the nodes are added automatically. There are no errors when adding nodes or edges that already exist.

#### **Attributes:**

Each graph, node, and edge can hold key/value attribute pairs in an associated attribute dictionary (the keys must be hashable). By default these are empty, but can be added or changed using add\_edge, add\_node or direct manipulation of the attribute dictionaries named graph, node and edge respectively.

```
>>> G = nx.DiGraph(day="Friday")
>>> G.graph
{'day': 'Friday'}
```

Add node attributes using add\_node(), add\_nodes\_from() or G.node

```
>>> G.add_node(1, time='5pm')
>>> G.add_nodes_from([3], time='2pm')
>>> G.node[1]
{'time': '5pm'}
>>> G.node[1]['room'] = 714
>>> G.nodes(data=True)
[(1, {'room': 714, 'time': '5pm'}), (3, {'time': '2pm'})]
```

Warning: adding a node to G.node does not add it to the graph.

Add edge attributes using add\_edge(), add\_edges\_from(), subscript notation, or G.edge.

```
>>> G.add_edge(1, 2, weight=4.7 )
>>> G.add_edges_from([(3,4),(4,5)], color='red')
>>> G.add_edges_from([(1,2,{'color':'blue'}), (2,3,{'weight':8})])
>>> G[1][2]['weight'] = 4.7
>>> G.edge[1][2]['weight'] = 4
```

### **Shortcuts:**

Many common graph features allow python syntax to speed reporting.

```
>>> 1 in G  # check if node in graph
True
>>> print [n for n in G if n<3]  # iterate through nodes
[1, 2]
>>> print len(G)  # number of nodes in graph
```

```
5
>>> print G[1] # adjacency dict keyed by neighbor to edge attributes
... # Note: you should not change this dict manually!
{2: {'color': 'blue', 'weight': 4}}
```

The fastest way to traverse all edges of a graph is via adjacency\_iter(), but the edges() method is often more convenient.

### **Reporting:**

Simple graph information is obtained using methods. Iterator versions of many reporting methods exist for efficiency. Methods exist for reporting nodes(), edges(), neighbors() and degree() as well as the number of nodes and edges.

For details on these and other miscellaneous methods, see below.

### Adding and removing nodes and edges

```
DiGraph. init (**attr[, data, name])
                                                 Initialize a graph with edges, name, graph attributes.
DiGraph.add node(n, **attr[, attr dict])
                                                 Add a single node n and update node attributes.
DiGraph.add_nodes_from(nodes, **attr)
                                                 Add multiple nodes.
                                                 Remove node n.
DiGraph.remove node(n)
                                                Remove multiple nodes.
DiGraph.remove_nodes_from(nbunch)
DiGraph.add_edge(u, v, **attr[, attr_dict])
                                                 Add an edge between u and v.
DiGraph.add_edges_from(ebunch, **attr[,
                                                 Add all the edges in ebunch.
...])
DiGraph.add_weighted_edges_from(ebunch, Add all the edges in ebunch as weighted edges with
**attr)
                                                 specified weights.
                                                 Remove the edge between u and v.
DiGraph.remove\_edge(u, v)
DiGraph.remove_edges_from(ebunch)
                                                 Remove all edges specified in ebunch.
DiGraph.add star(nlist, **attr)
                                                 Add a star.
DiGraph.add_path(nlist, **attr)
                                                Add a path.
DiGraph.add cycle(nlist, **attr)
                                                 Add a cycle.
DiGraph.clear()
                                                Remove all nodes and edges from the graph.
```

## networkx.DiGraph. init

```
__init__(data=None, name=", **attr)
Initialize a graph with edges, name, graph attributes.
```

### Parameters data: input graph

Data to initialize graph. If data=None (default) an empty graph is created. The data can be an edge list, or any NetworkX graph object. If the corresponding optional Python packages are installed the data can also be a NumPy matrix or 2d ndarray, a SciPy sparse matrix, or a PyGraphviz graph.

```
name : string, optional (default='')
```

An optional name for the graph.

attr: keyword arguments, optional (default= no attributes)

Attributes to add to graph as key=value pairs.

#### See Also:

convert

## **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G = nx.Graph(name='my graph')
>>> e = [(1,2),(2,3),(3,4)] # list of edges
>>> G = nx.Graph(e)
```

Arbitrary graph attribute pairs (key=value) may be assigned

```
>>> G=nx.Graph(e, day="Friday")
>>> G.graph
{'day': 'Friday'}
```

# networkx.DiGraph.add\_node

```
add_node (n, attr_dict=None, **attr)
```

Add a single node n and update node attributes.

### Parameters n: node

A node can be any hashable Python object except None.

```
attr_dict : dictionary, optional (default= no attributes)
```

Dictionary of node attributes. Key/value pairs will update existing data associated with the node.

attr: keyword arguments, optional

Set or change attributes using key=value.

## See Also:

```
add_nodes_from
```

#### **Notes**

A hashable object is one that can be used as a key in a Python dictionary. This includes strings, numbers, tuples of strings and numbers, etc.

On many platforms hashable items also include mutables such as NetworkX Graphs, though one should be careful that the hash doesn't change on mutables.

## **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_node(1)
>>> G.add_node('Hello')
>>> K3 = nx.Graph([(0,1),(1,2),(2,0)])
>>> G.add_node(K3)
>>> G.number_of_nodes()
3
```

Use keywords set/change node attributes:

```
>>> G.add_node(1,size=10)
>>> G.add_node(3,weight=0.4,UTM=('13S',382871,3972649))
```

## networkx.DiGraph.add nodes from

```
add_nodes_from (nodes, **attr)
```

Add multiple nodes.

Parameters nodes: iterable container

A container of nodes (list, dict, set, etc.). The container will be iterated through once.

attr : keyword arguments, optional (default= no attributes)

Update attributes for all nodes in nodes.

#### See Also:

add\_node

## **Examples**

```
>>> G = nx.Graph()  # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_nodes_from('Hello')
>>> K3 = nx.Graph([(0,1),(1,2),(2,0)])
>>> G.add_nodes_from(K3)
>>> sorted(G.nodes())
[0, 1, 2, 'H', 'e', 'l', 'o']
```

Use keywords to update specific node attributes for every node.

```
>>> G.add_nodes_from([1,2], size=10)
>>> G.add_nodes_from([3,4], weight=0.4)
```

# networkx.DiGraph.remove\_node

```
remove\_node(n)
```

Remove node n.

Removes the node n and all adjacent edges. Attempting to remove a non-existent node will raise an exception.

Parameters n: node

A node in the graph

#### Raises NetworkXError:

If n is not in the graph.

### See Also:

```
remove nodes from
```

## **Examples**

```
>>> G = nx.Graph()  # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2])
>>> G.edges()
[(0, 1), (1, 2)]
>>> G.remove_node(1)
>>> G.edges()
[]
```

# networkx.DiGraph.remove\_nodes\_from

```
remove_nodes_from(nbunch)
```

Remove multiple nodes.

Parameters nodes: iterable container

A container of nodes (list, dict, set, etc.). If a node in the container is not in the graph it is silently ignored.

#### See Also:

remove node

# **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2])
>>> e = G.nodes()
>>> e
[0, 1, 2]
>>> G.remove_nodes_from(e)
>>> G.nodes()
[]
```

## networkx.DiGraph.add\_edge

```
add_edge (u, v, attr_dict=None, **attr)
```

Add an edge between u and v.

The nodes u and v will be automatically added if they are not already in the graph.

Edge attributes can be specified with keywords or by providing a dictionary with key/value pairs. See examples below.

#### Parameters u,v: nodes

Nodes can be, for example, strings or numbers. Nodes must be hashable (and not None) Python objects.

attr\_dict : dictionary, optional (default= no attributes)

Dictionary of edge attributes. Key/value pairs will update existing data associated with the edge.

attr: keyword arguments, optional

Edge data (or labels or objects) can be assigned using keyword arguments.

### See Also:

```
add_edges_from add a collection of edges
```

### **Notes**

Adding an edge that already exists updates the edge data.

NetworkX algorithms designed for weighted graphs use as the edge weight a numerical value assigned to the keyword 'weight'.

## **Examples**

The following all add the edge e=(1,2) to graph G:

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> e = (1,2)
>>> G.add_edge(1, 2) # explicit two-node form
>>> G.add_edge(*e) # single edge as tuple of two nodes
>>> G.add_edges_from([(1,2)]) # add edges from iterable container
```

Associate data to edges using keywords:

```
>>> G.add_edge(1, 2, weight=3)
>>> G.add_edge(1, 3, weight=7, capacity=15, length=342.7)
```

# networkx.DiGraph.add\_edges\_from

```
add_edges_from (ebunch, attr_dict=None, **attr)
Add all the edges in ebunch.
```

Parameters ebunch: container of edges

Each edge given in the container will be added to the graph. The edges must be given as as 2-tuples (u,v) or 3-tuples (u,v,d) where d is a dictionary containing edge data.

attr dict: dictionary, optional (default= no attributes)

Dictionary of edge attributes. Key/value pairs will update existing data associated with each edge.

attr: keyword arguments, optional

Edge data (or labels or objects) can be assigned using keyword arguments.

### See Also:

```
add_edge add a single edge
add weighted edges from convenient way to add weighted edges
```

### **Notes**

Adding the same edge twice has no effect but any edge data will be updated when each duplicate edge is added.

## **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_edges_from([(0,1),(1,2)]) # using a list of edge tuples
>>> e = zip(range(0,3),range(1,4))
>>> G.add_edges_from(e) # Add the path graph 0-1-2-3
Associate data to edges
```

```
>>> G.add_edges_from([(1,2),(2,3)], weight=3)
>>> G.add_edges_from([(3,4),(1,4)], label='WN2898')
```

# networkx.DiGraph.add weighted edges from

```
add_weighted_edges_from(ebunch, **attr)
```

Add all the edges in ebunch as weighted edges with specified weights.

Parameters ebunch: container of edges

Each edge given in the list or container will be added to the graph. The edges must be given as 3-tuples (u,v,w) where w is a number.

attr : keyword arguments, optional (default= no attributes)

Edge attributes to add/update for all edges.

### See Also:

```
add_edge add a single edge
add_edges_from add multiple edges
```

### **Notes**

Adding the same edge twice has no effect but any edge data will be updated when each duplicate edge is added.

## **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_weighted_edges_from([(0,1,3.0),(1,2,7.5)])
```

## networkx.DiGraph.remove\_edge

```
remove\_edge(u, v)
```

Remove the edge between u and v.

### Parameters u,v: nodes:

Remove the edge between nodes u and v.

#### Raises NetworkXError:

If there is not an edge between u and v.

### See Also:

remove\_edges\_from remove a collection of edges

## **Examples**

```
>>> G = nx.Graph() # or DiGraph, etc
>>> G.add_path([0,1,2,3])
>>> G.remove_edge(0,1)
>>> e = (1,2)
>>> G.remove_edge(*e) # unpacks e from an edge tuple
>>> e = (2,3,{'weight':7}) # an edge with attribute data
>>> G.remove_edge(*e[:2]) # select first part of edge tuple
```

# networkx.DiGraph.remove edges from

```
remove_edges_from(ebunch)
```

Remove all edges specified in ebunch.

### Parameters ebunch: list or container of edge tuples :

Each edge given in the list or container will be removed from the graph. The edges can be:

- 2-tuples (u,v) edge between u and v.
- 3-tuples (u,v,k) where k is ignored.

#### See Also:

remove\_edge remove a single edge

## **Notes**

Will fail silently if an edge in ebunch is not in the graph.

# **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> ebunch=[(1,2),(2,3)]
>>> G.remove_edges_from(ebunch)
```

## networkx.DiGraph.add star

```
add_star (nlist, **attr)
Add a star.
```

The first node in nlist is the middle of the star. It is connected to all other nodes in nlist.

Parameters nlist: list

A list of nodes.

attr: keyword arguments, optional (default= no attributes)

Attributes to add to every edge in star.

### See Also:

```
add_path, add_cycle
```

# **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_star([0,1,2,3])
>>> G.add_star([10,11,12],weight=2)
```

# networkx.DiGraph.add\_path

```
add_path (nlist, **attr)
    Add a path.
```

Parameters nlist: list

A list of nodes. A path will be constructed from the nodes (in order) and added to the graph.

attr: keyword arguments, optional (default= no attributes)

Attributes to add to every edge in path.

### See Also:

```
add_star,add_cycle
```

```
>>> G=nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> G.add_path([10,11,12], weight=7)
```

# networkx.DiGraph.add\_cycle

```
add_cycle (nlist, **attr)
Add a cycle.
```

### Parameters nlist: list

A list of nodes. A cycle will be constructed from the nodes (in order) and added to the graph.

attr : keyword arguments, optional (default= no attributes)

Attributes to add to every edge in cycle.

### See Also:

```
add_path, add_star
```

# **Examples**

```
>>> G=nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_cycle([0,1,2,3])
>>> G.add_cycle([10,11,12], weight=7)
```

## networkx.DiGraph.clear

```
clear()
```

Remove all nodes and edges from the graph.

This also removes the name, and all graph, node, and edge attributes.

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> G.clear()
>>> G.nodes()
[]
>>> G.edges()
[]
```

### Iterating over nodes and edges

```
DiGraph.nodes([data])
                                           Return a list of the nodes in the graph.
DiGraph.nodes_iter([data])
                                           Return an iterator over the nodes.
DiGraph.__iter__()
                                           Iterate over the nodes.
DiGraph.edges([nbunch, data])
                                           Return a list of edges.
DiGraph.edges_iter([nbunch, data])
                                           Return an iterator over the edges.
DiGraph.out_edges([nbunch, data])
                                           Return a list of edges.
DiGraph.out_edges_iter([nbunch,
                                           Return an iterator over the edges.
data])
DiGraph.in edges([nbunch, data])
                                           Return a list of the incoming edges.
DiGraph.in_edges_iter([nbunch,
                                           Return an iterator over the incoming edges.
DiGraph.get_edge_data(u, v[,
                                           Return the attribute dictionary associated with edge (u,v).
default])
                                           Return a list of successor nodes of n.
DiGraph.neighbors(n)
DiGraph.neighbors iter(n)
                                           Return an iterator over successor nodes of n.
DiGraph. __getitem __(n)
                                           Return a dict of neighbors of node n.
DiGraph.successors(n)
                                           Return a list of successor nodes of n.
DiGraph.successors_iter(n)
                                           Return an iterator over successor nodes of n.
DiGraph.predecessors(n)
                                           Return a list of predecessor nodes of n.
                                           Return an iterator over predecessor nodes of n.
DiGraph.predecessors_iter(n)
                                           Return an adjacency list representation of the graph.
DiGraph.adjacency_list()
DiGraph.adjacency_iter()
                                           Return an iterator of (node, adjacency dict) tuples for all nodes.
DiGraph.nbunch_iter([nbunch])
                                           Return an iterator of nodes contained in nbunch that are also in the
                                           graph.
```

# networkx.DiGraph.nodes

nodes (data=False)

Return a list of the nodes in the graph.

Parameters data: boolean, optional (default=False)

If False return a list of nodes. If True return a two-tuple of node and node data dictionary

Returns nlist: list

A list of nodes. If data=True a list of two-tuples containing (node, node data dictionary).

```
>>> G = nx.Graph()  # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2])
>>> print G.nodes()
[0, 1, 2]
>>> G.add_node(1, time='5pm')
>>> print G.nodes(data=True)
[(0, {}), (1, {'time': '5pm'}), (2, {})]
```

# networkx.DiGraph.nodes\_iter

```
nodes_iter(data=False)
```

Return an iterator over the nodes.

Parameters data: boolean, optional (default=False)

If False the iterator returns nodes. If True return a two-tuple of node and node data dictionary

Returns niter: iterator

An iterator over nodes. If data=True the iterator gives two-tuples containing (node, node data, dictionary)

### **Notes**

If the node data is not required it is simpler and equivalent to use the expression 'for n in G'.

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2])
>>> for n in G:
... print n,
0 1 2
```

# **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2])
>>> for n in G.nodes_iter():
...    print n,
0 1 2
>>> for n,d in G.nodes_iter(data=True):
...    print d,
{} {} {}
```

# networkx.DiGraph. iter

```
___iter__()
```

Iterate over the nodes. Use the expression 'for n in G'.

Returns niter: iterator

An iterator over all nodes in the graph.

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> for n in G:
```

```
print n,
1 2 3
```

## networkx.DiGraph.edges

```
edges (nbunch=None, data=False)
```

Return a list of edges.

Edges are returned as tuples with optional data in the order (node, neighbor, data).

Parameters nbunch: iterable container, optional (default= all nodes)

A container of nodes. The container will be iterated through once.

**data**: bool, optional (default=False)

Return two tuples (u,v) (False) or three-tuples (u,v,data) (True).

### **Returns** edge\_list: list of edge tuples :

Edges that are adjacent to any node in nbunch, or a list of all edges if nbunch is not specified.

#### See Also:

edges\_iter return an iterator over the edges

### **Notes**

Nodes in nbunch that are not in the graph will be (quietly) ignored.

## **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> G.edges()
[(0, 1), (1, 2), (2, 3)]
>>> G.edges(data=True) # default edge data is {} (empty dictionary)
[(0, 1, {}), (1, 2, {}), (2, 3, {})]
>>> G.edges([0,3])
[(0, 1), (3, 2)]
>>> G.edges(0)
[(0, 1)]
```

## networkx.DiGraph.edges\_iter

```
edges_iter (nbunch=None, data=False)
```

Return an iterator over the edges.

Edges are returned as tuples with optional data in the order (node, neighbor, data).

**Parameters nbunch**: iterable container, optional (default= all nodes)

A container of nodes. The container will be iterated through once.

```
data: bool, optional (default=False)
```

If True, return edge attribute dict in 3-tuple (u,v,data).

### Returns edge\_iter: iterator

An iterator of (u,v) or (u,v,d) tuples of edges.

#### See Also:

edges return a list of edges

### **Notes**

Nodes in nbunch that are not in the graph will be (quietly) ignored.

# **Examples**

```
>>> G = nx.DiGraph() # or MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> [e for e in G.edges_iter()]
[(0, 1), (1, 2), (2, 3)]
>>> list(G.edges_iter(data=True)) # default data is {} (empty dict)
[(0, 1, {}), (1, 2, {}), (2, 3, {})]
>>> list(G.edges_iter([0,2]))
[(0, 1), (2, 3)]
>>> list(G.edges_iter(0))
[(0, 1)]
```

## networkx.DiGraph.out\_edges

```
out_edges (nbunch=None, data=False)
```

Return a list of edges.

Edges are returned as tuples with optional data in the order (node, neighbor, data).

**Parameters nbunch**: iterable container, optional (default= all nodes)

A container of nodes. The container will be iterated through once.

```
data: bool, optional (default=False)
```

Return two tuples (u,v) (False) or three-tuples (u,v,data) (True).

### Returns edge\_list: list of edge tuples :

Edges that are adjacent to any node in nbunch, or a list of all edges if nbunch is not specified.

## See Also:

edges\_iter return an iterator over the edges

## **Notes**

Nodes in nbunch that are not in the graph will be (quietly) ignored.

## **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> G.edges()
[(0, 1), (1, 2), (2, 3)]
>>> G.edges(data=True) # default edge data is {} (empty dictionary)
[(0, 1, {}), (1, 2, {}), (2, 3, {})]
>>> G.edges([0,3])
[(0, 1), (3, 2)]
>>> G.edges(0)
[(0, 1)]
```

## networkx.DiGraph.out edges iter

```
out_edges_iter (nbunch=None, data=False)
```

Return an iterator over the edges.

Edges are returned as tuples with optional data in the order (node, neighbor, data).

**Parameters nbunch**: iterable container, optional (default= all nodes)

A container of nodes. The container will be iterated through once.

data: bool, optional (default=False)

If True, return edge attribute dict in 3-tuple (u,v,data).

Returns edge\_iter: iterator

An iterator of (u,v) or (u,v,d) tuples of edges.

See Also:

edges return a list of edges

### **Notes**

Nodes in nbunch that are not in the graph will be (quietly) ignored.

```
>>> G = nx.DiGraph() # or MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> [e for e in G.edges_iter()]
[(0, 1), (1, 2), (2, 3)]
>>> list(G.edges_iter(data=True)) # default data is {} (empty dict)
[(0, 1, {}), (1, 2, {}), (2, 3, {})]
>>> list(G.edges_iter([0,2]))
```

```
[(0, 1), (2, 3)]
>>> list(G.edges_iter(0))
[(0, 1)]
```

# networkx.DiGraph.in\_edges

```
in_edges (nbunch=None, data=False)
Return a list of the incoming edges.
```

See Also:

edges return a list of edges

## networkx.DiGraph.in\_edges\_iter

```
\verb"in_edges_iter" (nbunch=None,\ data=False)
```

Return an iterator over the incoming edges.

**Parameters nbunch**: iterable container, optional (default= all nodes)

A container of nodes. The container will be iterated through once.

data: bool, optional (default=False)

If True, return edge attribute dict in 3-tuple (u,v,data).

Returns in\_edge\_iter : iterator

An iterator of (u,v) or (u,v,d) tuples of incoming edges.

See Also:

edges\_iter return an iterator of edges

## networkx.DiGraph.get\_edge\_data

```
get_edge_data(u, v, default=None)
```

Return the attribute dictionary associated with edge (u,v).

Parameters u,v: nodes

default: any Python object (default=None) :

Value to return if the edge (u,v) is not found.

Returns edge\_dict : dictionary

The edge attribute dictionary.

### **Notes**

It is faster to use G[u][v].

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> G[0][1]
{}
```

Warning: Assigning G[u][v] corrupts the graph data structure. But it is safe to assign attributes to that dictionary,

```
>>> G[0][1]['weight'] = 7
>>> G[0][1]['weight']
7
>>> G[1][0]['weight']
7
```

## **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> G.get_edge_data(0,1) # default edge data is {}
{}
>>> e = (0,1)
>>> G.get_edge_data(*e) # tuple form
{}
>>> G.get_edge_data('a','b',default=0) # edge not in graph, return 0
0
```

# networkx.DiGraph.neighbors

```
neighbors(n)
```

Return a list of successor nodes of n.

neighbors() and successors() are the same function.

## networkx.DiGraph.neighbors\_iter

```
neighbors_iter(n)
```

Return an iterator over successor nodes of n.

neighbors\_iter() and successors\_iter() are the same.

# networkx.DiGraph.\_\_getitem\_\_

```
\__getitem_{\__}(n)
```

Return a dict of neighbors of node n. Use the expression 'G[n]'.

Parameters n: node

A node in the graph.

Returns adj\_dict: dictionary

The adjacency dictionary for nodes connected to n.

## **Notes**

G[n] is similar to G.neighbors(n) but the internal data dictionary is returned instead of a list.

Assigning G[n] will corrupt the internal graph data structure. Use G[n] for reading data only.

## **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> print G[0]
{1: {}}
```

## networkx.DiGraph.successors

```
successors(n)
```

Return a list of successor nodes of n.

neighbors() and successors() are the same function.

## networkx.DiGraph.successors\_iter

```
successors\_iter(n)
```

Return an iterator over successor nodes of n.

neighbors\_iter() and successors\_iter() are the same.

### networkx.DiGraph.predecessors

```
predecessors(n)
```

Return a list of predecessor nodes of n.

## networkx.DiGraph.predecessors iter

```
predecessors_iter(n)
```

Return an iterator over predecessor nodes of n.

## networkx.DiGraph.adjacency\_list

```
adjacency_list()
```

Return an adjacency list representation of the graph.

The output adjacency list is in the order of G.nodes(). For directed graphs, only outgoing adjacencies are included.

Returns adj\_list: lists of lists

The adjacency structure of the graph as a list of lists.

### See Also:

```
adjacency_iter
```

## **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> G.adjacency_list() # in order given by G.nodes()
[[1], [0, 2], [1, 3], [2]]
```

## networkx.DiGraph.adjacency\_iter

```
adjacency_iter()
```

Return an iterator of (node, adjacency dict) tuples for all nodes.

This is the fastest way to look at every edge. For directed graphs, only outgoing adjacencies are included.

Returns adj\_iter: iterator

An iterator of (node, adjacency dictionary) for all nodes in the graph.

#### See Also:

```
adjacency list
```

# **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> [(n,nbrdict) for n,nbrdict in G.adjacency_iter()]
[(0, {1: {}}), (1, {0: {}, 2: {}}), (2, {1: {}, 3: {}}), (3, {2: {}})]
```

# networkx.DiGraph.nbunch\_iter

```
nbunch_iter(nbunch=None)
```

Return an iterator of nodes contained in nbunch that are also in the graph.

The nodes in nbunch are checked for membership in the graph and if not are silently ignored.

**Parameters nbunch**: iterable container, optional (default=all nodes)

A container of nodes. The container will be iterated through once.

Returns niter: iterator

An iterator over nodes in nbunch that are also in the graph. If nbunch is None, iterate over all nodes in the graph.

### Raises NetworkXError:

If nbunch is not a node or or sequence of nodes. If a node in nbunch is not hashable.

### See Also:

```
Graph.__iter__
```

### **Notes**

When nbunch is an iterator, the returned iterator yields values directly from nbunch, becoming exhausted when nbunch is exhausted.

To test whether nbunch is a single node, one can use "if nbunch in self:", even after processing with this routine.

If nbunch is not a node or a (possibly empty) sequence/iterator or None, a NetworkXError is raised. Also, if any object in nbunch is not hashable, a NetworkXError is raised.

### Information about graph structure

```
DiGraph.has node(n)
                                                 Return True if the graph contains the node n.
DiGraph.__contains__(n)
                                                 Return True if n is a node. False otherwise. Use the
                                                 expression
DiGraph.has\_edge(u, v)
                                                 Return True if the edge (u,v) is in the graph.
DiGraph.nodes with selfloops()
                                                 Return a list of nodes with self loops.
DiGraph.selfloop_edges([data])
                                                 Return a list of selfloop edges.
DiGraph.order()
                                                 Return the number of nodes in the graph.
DiGraph.number_of_nodes()
                                                 Return the number of nodes in the graph.
DiGraph.__len__()
                                                 Return the number of nodes.
DiGraph.size([weighted])
                                                 Return the number of edges.
                                                 Return the number of edges between two nodes.
DiGraph.number_of_edges([u, v])
DiGraph.number_of_selfloops()
                                                 Return the number of selfloop edges.
DiGraph.degree([nbunch, with_labels,
                                                 Return the degree of a node or nodes.
weighted])
DiGraph.degree_iter([nbunch, weighted])
                                                 Return an iterator for (node, degree).
DiGraph.in degree([nbunch, with labels, ...])
                                                 Return the in-degree of a node or nodes.
DiGraph.in_degree_iter([nbunch,
                                                 Return an iterator for (node, in-degree).
weighted])
DiGraph.out_degree([nbunch, with_labels,
                                                 Return the out-degree of a node or nodes.
DiGraph.out degree iter([nbunch,
                                                 Return an iterator for (node, out-degree).
weighted])
```

# networkx.DiGraph.has node

```
has\_node(n)
```

Return True if the graph contains the node n.

Parameters n: node

# **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2])
>>> print G.has_node(0)
True
```

It is more readable and simpler to use

```
>>> 0 in G
True
```

## networkx.DiGraph. contains

```
__contains__(n)
```

Return True if n is a node, False otherwise. Use the expression 'n in G'.

## **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> print 1 in G
True
```

## networkx.DiGraph.has edge

```
has\_edge(u, v)
```

Return True if the edge (u,v) is in the graph.

Parameters u,v: nodes

Nodes can be, for example, strings or numbers. Nodes must be hashable (and not None) Python objects.

Returns edge\_ind: bool

True if edge is in the graph, False otherwise.

## **Examples**

Can be called either using two nodes u,v or edge tuple (u,v)

```
>>> G = nx.Graph()  # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> G.has_edge(0,1)  # using two nodes
True
>>> e = (0,1)
>>> G.has_edge(*e)  # e is a 2-tuple (u,v)
True
>>> e = (0,1,{'weight':7})
>>> G.has_edge(*e[:2])  # e is a 3-tuple (u,v,data_dictionary)
True
```

The following syntax are all equivalent:

```
>>> G.has_edge(0,1)
True
>>> 1 in G[0] # though this gives KeyError if 0 not in G
True
```

## networkx.DiGraph.nodes with selfloops

```
nodes_with_selfloops()
```

Return a list of nodes with self loops.

A node with a self loop has an edge with both ends adjacent to that node.

Returns nodelist: list

A list of nodes with self loops.

#### See Also:

```
selfloop_edges, number_of_selfloops
```

## **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_edge(1,1)
>>> G.add_edge(1,2)
>>> G.nodes_with_selfloops()
[1]
```

## networkx.DiGraph.selfloop\_edges

```
selfloop_edges (data=False)
```

Return a list of selfloop edges.

A selfloop edge has the same node at both ends.

**Parameters data**: bool, optional (default=False)

Return selfloop edges as two tuples (u,v) (data=False) or three-tuples (u,v,data) (data=True)

Returns edgelist: list of edge tuples

A list of all selfloop edges.

#### See Also:

```
selfloop_nodes, number_of_selfloops
```

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_edge(1,1)
>>> G.add_edge(1,2)
>>> G.selfloop_edges()
[(1, 1)]
>>> G.selfloop_edges(data=True)
[(1, 1, {})]
```

# networkx.DiGraph.order

```
order()
```

Return the number of nodes in the graph.

Returns nnodes: int

The number of nodes in the graph.

See Also:

```
number_of_nodes, __len__
```

# networkx.DiGraph.number of nodes

```
number_of_nodes()
```

Return the number of nodes in the graph.

Returns nnodes: int

The number of nodes in the graph.

See Also:

```
order, __len__
```

# **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2])
>>> print len(G)
3
```

# networkx.DiGraph.\_\_len\_\_

```
__len__()
```

Return the number of nodes. Use the expression 'len(G)'.

Returns nnodes: int

The number of nodes in the graph.

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> print len(G)
4
```

## networkx.DiGraph.size

```
size (weighted=False)
```

Return the number of edges.

**Parameters weighted**: boolean, optional (default=False)

If True return the sum of the edge weights.

Returns nedges: int

The number of edges in the graph.

### See Also:

```
number_of_edges
```

# **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> G.size()
3
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_edge('a','b',weight=2)
>>> G.add_edge('b','c',weight=4)
>>> G.size()
2
>>> G.size(weighted=True)
6
```

# networkx.DiGraph.number of edges

```
number_of_edges (u=None, v=None)
```

Return the number of edges between two nodes.

**Parameters u,v**: nodes, optional (default=all edges)

If u and v are specified, return the number of edges between u and v. Otherwise return the total number of all edges.

Returns nedges: int

The number of edges in the graph. If nodes u and v are specified return the number of edges between those nodes.

## See Also:

size

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> G.number_of_edges()
3
>>> G.number_of_edges(0,1)
1
>>> e = (0,1)
>>> G.number_of_edges(*e)
```

## networkx.DiGraph.number\_of\_selfloops

```
number_of_selfloops()
```

Return the number of selfloop edges.

A selfloop edge has the same node at both ends.

Returns nloops: int

The number of selfloops.

#### See Also:

```
selfloop_nodes, selfloop_edges
```

# **Examples**

```
>>> G=nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_edge(1,1)
>>> G.add_edge(1,2)
>>> G.number_of_selfloops()
```

# networkx.DiGraph.degree

degree (nbunch=None, with\_labels=False, weighted=False)

Return the degree of a node or nodes.

The node degree is the number of edges adjacent to that node.

**Parameters nbunch**: iterable container, optional (default=all nodes)

A container of nodes. The container will be iterated through once.

with\_labels : bool, optional (default=False)

If True return a dictionary of degrees keyed by node.

weighted: bool, optional (default=False)

If True return the sum of edge weights adjacent to the node.

Returns nd: list, or dictionary

A list of node degrees or a dictionary with nodes as keys and degree as values if with\_labels=True).

## **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> G.degree(0)
1
>>> G.degree([0,1])
[1, 2]
>>> G.degree([0,1], with_labels=True)
{0: 1, 1: 2}
```

# networkx.DiGraph.degree\_iter

```
degree_iter (nbunch=None, weighted=False)
```

Return an iterator for (node, degree).

The node degree is the number of edges adjacent to the node.

Parameters nbunch: iterable container, optional (default=all nodes)

A container of nodes. The container will be iterated through once.

weighted : bool, optional (default=False)

If True return the sum of edge weights adjacent to the node.

Returns nd iter: an iterator

The iterator returns two-tuples of (node, degree).

## See Also:

```
degree, in_degree, out_degree, in_degree_iter, out_degree_iter
```

# **Examples**

```
>>> G = nx.DiGraph() # or MultiDiGraph
>>> G.add_path([0,1,2,3])
>>> list(G.degree_iter(0)) # node 0 with degree 1
[(0, 1)]
>>> list(G.degree_iter([0,1]))
[(0, 1), (1, 2)]
```

# networkx.DiGraph.in\_degree

```
in_degree (nbunch=None, with_labels=False, weighted=False)
```

Return the in-degree of a node or nodes.

The node in-degree is the number of edges pointing in to the node.

Parameters nbunch: iterable container, optional (default=all nodes)

A container of nodes. The container will be iterated through once.

with\_labels : bool, optional (default=False)

If True return a dictionary of degrees keyed by node.

```
weighted : bool, optional (default=False)
```

If True return the sum of edge weights adjacent to the node.

**Returns nd**: list, or dictionary

A list of node in-degrees or a dictionary with nodes as keys and in-degree as values if with labels=True).

#### See Also:

```
degree, out_degree, in_degree_iter
```

## **Examples**

```
>>> G = nx.DiGraph() # or MultiDiGraph
>>> G.add_path([0,1,2,3])
>>> G.in_degree(0)
0
>>> G.in_degree([0,1])
[0, 1]
>>> G.in_degree([0,1],with_labels=True)
{0: 0, 1: 1}
```

# networkx.DiGraph.in\_degree\_iter

```
in_degree_iter (nbunch=None, weighted=False)
```

Return an iterator for (node, in-degree).

The node in-degree is the number of edges pointing in to the node.

Parameters nbunch: iterable container, optional (default=all nodes)

A container of nodes. The container will be iterated through once.

weighted : bool, optional (default=False)

If True return the sum of edge weights adjacent to the node.

Returns nd\_iter: an iterator

The iterator returns two-tuples of (node, in-degree).

#### See Also:

```
degree, in_degree, out_degree, out_degree_iter
```

```
>>> G = nx.DiGraph()
>>> G.add_path([0,1,2,3])
>>> list(G.in_degree_iter(0)) # node 0 with degree 0
[(0, 0)]
>>> list(G.in_degree_iter([0,1]))
[(0, 0), (1, 1)]
```

## networkx.DiGraph.out\_degree

```
out_degree (nbunch=None, with_labels=False, weighted=False)
Return the out-degree of a node or nodes.
```

The node out-degree is the number of edges pointing out of the node.

Parameters nbunch: iterable container, optional (default=all nodes)

A container of nodes. The container will be iterated through once.

```
with_labels : bool, optional (default=False)
```

If True return a dictionary of degrees keyed by node.

```
weighted : bool, optional (default=False)
```

If True return the sum of edge weights adjacent to the node.

Returns nd: list, or dictionary

A list of node out-degrees or a dictionary with nodes as keys and out-degree as values if with\_labels=True).

## **Examples**

```
>>> G = nx.DiGraph() # or MultiDiGraph
>>> G.add_path([0,1,2,3])
>>> G.out_degree(0)
1
>>> G.out_degree([0,1])
[1, 1]
>>> G.out_degree([0,1],with_labels=True)
{0: 1, 1: 1}
```

## networkx.DiGraph.out degree iter

```
out_degree_iter (nbunch=None, weighted=False)
Return an iterator for (node, out-degree).
```

The node out-degree is the number of edges pointing out of the node.

**Parameters nbunch**: iterable container, optional (default=all nodes)

A container of nodes. The container will be iterated through once.

```
weighted: bool, optional (default=False)
```

If True return the sum of edge weights adjacent to the node.

Returns nd\_iter: an iterator

The iterator returns two-tuples of (node, out-degree).

#### See Also:

```
degree, in_degree, out_degree, in_degree_iter
```

## **Examples**

```
>>> G = nx.DiGraph()
>>> G.add_path([0,1,2,3])
>>> list(G.out_degree_iter(0)) # node 0 with degree 1
[(0, 1)]
>>> list(G.out_degree_iter([0,1]))
[(0, 1), (1, 1)]
```

### Making copies and subgraphs

DiGraph.copy()	Return a copy of the graph.
DiGraph.to_undirected()	Return an undirected representation of the digraph.
<pre>DiGraph.subgraph(nbunch[, copy])</pre>	Return the subgraph induced on nodes in nbunch.
DiGraph.reverse([copy])	Return the reverse of the graph.

## networkx.DiGraph.copy

### copy()

Return a copy of the graph.

Returns G: Graph

A copy of the graph.

See Also:

to\_directed return a directed copy of the graph.

## **Notes**

This makes a complete copy of the graph including all of the node or edge attributes.

## **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> H = G.copy()
```

## networkx.DiGraph.to undirected

### to\_undirected()

Return an undirected representation of the digraph.

### Returns G: Graph

An undirected graph with the same name and nodes and with edge (u,v,data) if either (u,v,data) or (v,u,data) is in the digraph. If both edges exist in digraph and their edge data is different, only one edge is created with an arbitrary choice of which edge data to use. You must check and correct for this manually if desired.

## **Notes**

If edges in both directions (u,v) and (v,u) exist in the graph, attributes for the new undirected edge will be a combination of the attributes of the directed edges. The edge data is updated in the (arbitrary) order that the edges are encountered. For more customized control of the edge attributes use add\_edge().

This is similar to Graph(self) which returns a shallow copy. self.to\_undirected() returns a deepcopy of edge, node and graph attributes.

# networkx.DiGraph.subgraph

```
subgraph (nbunch, copy=True)
```

Return the subgraph induced on nodes in nbunch.

The induced subgraph of the graph has the nodes in nbunch as its node set and the edges adjacent to those nodes as its edge set.

Parameters nbunch: list, iterable

A container of nodes. The container will be iterated through once.

```
copy: bool, optional (default=True)
```

If True return a new graph holding the subgraph including copies of all edge and node properties. If False the subgraph is created using the original graph by deleting all nodes not in nbunch (this changes the original graph).

### Returns G: Graph

A subgraph of the graph. If copy=True a new graph is returned with copies of graph, node, and edge data. If copy=False the subgraph is created in place by modifying the original graph.

### **Notes**

If copy=True, nodes and edges are copied using copy.deepcopy.

# **Examples**

```
>>> G = nx.Graph()  # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> H = G.subgraph([0,1,2])
>>> print H.edges()
[(0, 1), (1, 2)]
```

# networkx.DiGraph.reverse

```
reverse (copy=True)
```

Return the reverse of the graph.

The reverse is a graph with the same nodes and edges but with the directions of the edges reversed.

Parameters copy: bool optional (default=True)

If True, return a new DiGraph holding the reversed edges. If False, reverse the reverse graph is created using the original graph (this changes the original graph).

# 3.2.3 MultiGraph - Undirected graphs with self loops and parallel edges

#### Overview

```
MultiGraph (data=None, name=", **attr)
```

An undirected graph class that can store multiedges.

Multiedges are multiple edges between two nodes. Each edge can hold optional data or attributes.

A MultiGraph holds undirected edges. Self loops are allowed.

Nodes can be arbitrary (hashable) Python objects with optional key/value attributes.

Edges are represented as links between nodes with optional key/value attributes.

Parameters data: input graph

Data to initialize graph. If data=None (default) an empty graph is created. The data can be an edge list, or any NetworkX graph object. If the corresponding optional Python packages are installed the data can also be a NumPy matrix or 2d ndarray, a SciPy sparse matrix, or a PyGraphviz graph.

```
name : string, optional (default='')
```

An optional name for the graph.

attr: keyword arguments, optional (default= no attributes)

Attributes to add to graph as key=value pairs.

### See Also:

```
Graph, DiGraph, MultiDiGraph
```

## **Examples**

Create an empty graph structure (a "null graph") with no nodes and no edges.

```
>>> G = nx.MultiGraph()
```

G can be grown in several ways.

#### **Nodes:**

Add one node at a time:

```
>>> G.add_node(1)
```

Add the nodes from any container (a list, dict, set or even the lines from a file or the nodes from another graph).

```
>>> G.add_nodes_from([2,3])
>>> G.add_nodes_from(range(100,110))
>>> H=nx.path_graph(10)
>>> G.add_nodes_from(H)
```

In addition to strings and integers any hashable Python object (except None) can represent a node, e.g. a customized node object, or even another Graph.

```
>>> G.add_node(H)
```

### **Edges:**

G can also be grown by adding edges.

Add one edge,

```
>>> G.add_edge(1, 2)
a list of edges,
>>> G.add_edges_from([(1,2),(1,3)])
or a collection of edges,
>>> G.add_edges_from(H.edges())
```

If some edges connect nodes not yet in the graph, the nodes are added automatically. If an edge already exists, an additional edge is created and stored using a key to identify the edge. By default the key is the lowest unused integer.

```
>>> G.add_edges_from([(4,5,dict(route=282)), (4,5,dict(route=37))])
>>> G[4]
{3: {0: {}}, 5: {0: {}, 1: {'route': 282}, 2: {'route': 37}}}
```

#### **Attributes:**

Each graph, node, and edge can hold key/value attribute pairs in an associated attribute dictionary (the keys must be hashable). By default these are empty, but can be added or changed using add\_edge, add\_node or direct manipulation of the attribute dictionaries named graph, node and edge respectively.

```
>>> G = nx.MultiGraph(day="Friday")
>>> G.graph
{'day': 'Friday'}
```

Add node attributes using add\_node(), add\_nodes\_from() or G.node

```
>>> G.add_node(1, time='5pm')
>>> G.add_nodes_from([3], time='2pm')
>>> G.node[1]
{'time': '5pm'}
>>> G.node[1]['room'] = 714
>>> G.nodes(data=True)
[(1, {'room': 714, 'time': '5pm'}), (3, {'time': '2pm'})]
```

Warning: adding a node to G.node does not add it to the graph.

Add edge attributes using add\_edge(), add\_edges\_from(), subscript notation, or G.edge.

```
>>> G.add_edge(1, 2, weight=4.7 )
>>> G.add_edges_from([(3,4),(4,5)], color='red')
>>> G.add_edges_from([(1,2,{'color':'blue'}), (2,3,{'weight':8})])
```

```
>>> G[1][2][0]['weight'] = 4.7
>>> G.edge[1][2][0]['weight'] = 4
```

#### **Shortcuts:**

Many common graph features allow python syntax to speed reporting.

```
>>> 1 in G  # check if node in graph
True
>>> print [n for n in G if n<3]  # iterate through nodes
[1, 2]
>>> print len(G)  # number of nodes in graph
5
>>> print G[1]  # adjacency dict keyed by neighbor to edge attributes
...  # Note: you should not change this dict manually!
{2: {0: {'weight': 4}, 1: {'color': 'blue'}}}
```

The fastest way to traverse all edges of a graph is via adjacency\_iter(), but the edges() method is often more convenient.

### Reporting:

Simple graph information is obtained using methods. Iterator versions of many reporting methods exist for efficiency. Methods exist for reporting nodes(), edges(), neighbors() and degree() as well as the number of nodes and edges.

For details on these and other miscellaneous methods, see below.

### Adding and removing nodes and edges

```
MultiGraph.__init__(**attr[, data, name])
                                                 Initialize a graph with edges, name, graph attributes.
MultiGraph.add_node(n, **attr[, attr_dict])
                                                 Add a single node n and update node attributes.
MultiGraph.add_nodes_from(nodes, **attr)
                                                 Add multiple nodes.
                                                 Remove node n.
MultiGraph.remove_node(n)
MultiGraph.remove_nodes_from(nodes)
                                                 Remove multiple nodes.
MultiGraph.add_edge(u, v, **attr[, key, ...])
                                                 Add an edge between u and v.
                                                 Add all the edges in ebunch.
MultiGraph.add_edges_from(ebunch,
**attr[, ...])
MultiGraph.add weighted edges from (ebuxAdd all the edges in ebunch as weighted edges with
...)
                                                 specified weights.
MultiGraph.remove edge(u, v[, key])
                                                 Remove an edge between u and v.
MultiGraph.remove_edges_from(ebunch)
                                                 Remove all edges specified in ebunch.
MultiGraph.add_star(nlist, **attr)
                                                 Add a star.
MultiGraph.add path(nlist, **attr)
                                                 Add a path.
MultiGraph.add cycle(nlist, **attr)
                                                 Add a cycle.
MultiGraph.clear()
                                                 Remove all nodes and edges from the graph.
```

## networkx.MultiGraph. init

```
__init__ (data=None, name=", **attr)
Initialize a graph with edges, name, graph attributes.
```

#### Parameters data: input graph

Data to initialize graph. If data=None (default) an empty graph is created. The data can be an edge list, or any NetworkX graph object. If the corresponding optional Python packages are installed the data can also be a NumPy matrix or 2d ndarray, a SciPy sparse matrix, or a PyGraphviz graph.

```
name : string, optional (default='')
```

An optional name for the graph.

attr : keyword arguments, optional (default= no attributes)

Attributes to add to graph as key=value pairs.

#### See Also:

convert

# **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G = nx.Graph(name='my graph')
>>> e = [(1,2),(2,3),(3,4)] # list of edges
>>> G = nx.Graph(e)
```

Arbitrary graph attribute pairs (key=value) may be assigned

```
>>> G=nx.Graph(e, day="Friday")
>>> G.graph
{'day': 'Friday'}
```

## networkx.MultiGraph.add node

```
add_node (n, attr_dict=None, **attr)
```

Add a single node n and update node attributes.

Parameters n: node

A node can be any hashable Python object except None.

attr\_dict : dictionary, optional (default= no attributes)

Dictionary of node attributes. Key/value pairs will update existing data associated with the node.

attr: keyword arguments, optional

Set or change attributes using key=value.

#### See Also:

```
add_nodes_from
```

#### **Notes**

A hashable object is one that can be used as a key in a Python dictionary. This includes strings, numbers, tuples of strings and numbers, etc.

On many platforms hashable items also include mutables such as NetworkX Graphs, though one should be careful that the hash doesn't change on mutables.

# **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_node(1)
>>> G.add_node('Hello')
>>> K3 = nx.Graph([(0,1),(1,2),(2,0)])
>>> G.add_node(K3)
>>> G.number_of_nodes()
```

Use keywords set/change node attributes:

```
>>> G.add_node(1,size=10)
>>> G.add_node(3,weight=0.4,UTM=('13S',382871,3972649))
```

# networkx.MultiGraph.add\_nodes\_from

```
add_nodes_from (nodes, **attr)
Add multiple nodes.
```

Parameters nodes: iterable container

A container of nodes (list, dict, set, etc.). The container will be iterated through once.

attr: keyword arguments, optional (default= no attributes)

Update attributes for all nodes in nodes.

#### See Also:

```
add_node
```

## **Examples**

```
>>> G = nx.Graph()  # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_nodes_from('Hello')
>>> K3 = nx.Graph([(0,1),(1,2),(2,0)])
>>> G.add_nodes_from(K3)
>>> sorted(G.nodes())
[0, 1, 2, 'H', 'e', 'l', 'o']
```

Use keywords to update specific node attributes for every node.

```
>>> G.add_nodes_from([1,2], size=10)
>>> G.add_nodes_from([3,4], weight=0.4)
```

## networkx.MultiGraph.remove\_node

```
remove node (n)
```

Remove node n.

Removes the node n and all adjacent edges. Attempting to remove a non-existent node will raise an exception.

Parameters n: node

A node in the graph

### Raises NetworkXError:

If n is not in the graph.

#### See Also:

```
remove nodes from
```

## **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2])
>>> G.edges()
[(0, 1), (1, 2)]
>>> G.remove_node(1)
>>> G.edges()
[]
```

# networkx.MultiGraph.remove\_nodes\_from

```
remove_nodes_from (nodes)
```

Remove multiple nodes.

#### Parameters nodes: iterable container

A container of nodes (list, dict, set, etc.). If a node in the container is not in the graph it is silently ignored.

#### See Also:

```
remove node
```

## **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2])
>>> e = G.nodes()
>>> e
[0, 1, 2]
>>> G.remove_nodes_from(e)
>>> G.nodes()
[]
```

## networkx.MultiGraph.add\_edge

```
add_edge (u, v, key=None, attr_dict=None, **attr)
Add an edge between u and v.
```

The nodes u and v will be automatically added if they are not already in the graph.

Edge attributes can be specified with keywords or by providing a dictionary with key/value pairs. See examples below.

#### **Parameters u,v**: nodes

Nodes can be, for example, strings or numbers. Nodes must be hashable (and not None) Python objects.

key: hashable identifier, optional (default=lowest unused integer)

Used to distinguish multiedges between a pair of nodes.

```
attr_dict : dictionary, optional (default= no attributes)
```

Dictionary of edge attributes. Key/value pairs will update existing data associated with the edge.

attr: keyword arguments, optional

Edge data (or labels or objects) can be assigned using keyword arguments.

### See Also:

```
add_edges_from add a collection of edges
```

#### **Notes**

To replace/update edge data, use the optional key argument to identify a unique edge. Otherwise a new edge will be created.

NetworkX algorithms designed for weighted graphs cannot use multigraphs directly because it is not clear how to handle multiedge weights. Convert to Graph using edge attribute 'weight' to enable weighted graph algorithms.

## **Examples**

The following all add the edge e=(1,2) to graph G:

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> e = (1,2)
>>> G.add_edge(1, 2) # explicit two-node form
>>> G.add_edge(*e) # single edge as tuple of two nodes
>>> G.add_edges_from([(1,2)]) # add edges from iterable container
```

Associate data to edges using keywords:

```
>>> G.add_edge(1, 2, weight=3)
>>> G.add_edge(1, 2, key=0, weight=4) # update data for key=0
>>> G.add_edge(1, 3, weight=7, capacity=15, length=342.7)
```

## networkx.MultiGraph.add edges from

```
add_edges_from (ebunch, attr_dict=None, **attr)
Add all the edges in ebunch.
```

Parameters ebunch: container of edges

Each edge given in the container will be added to the graph. The edges can be:

- 2-tuples (u,v) or
- 3-tuples (u,v,d) for an edge attribute dict d, or
- 4-tuples (u,v,k,d) for an edge identified by key k

attr\_dict : dictionary, optional (default= no attributes)

Dictionary of edge attributes. Key/value pairs will update existing data associated with each edge.

attr: keyword arguments, optional

Edge data (or labels or objects) can be assigned using keyword arguments.

#### See Also:

```
add_edge add a single edge
add_weighted_edges_from convenient way to add weighted edges
```

#### **Notes**

Adding the same edge twice has no effect but any edge data will be updated when each duplicate edge is added.

## **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_edges_from([(0,1),(1,2)]) # using a list of edge tuples
>>> e = zip(range(0,3),range(1,4))
>>> G.add_edges_from(e) # Add the path graph 0-1-2-3

Associate data to edges
>>> G.add_edges_from([(1,2),(2,3)], weight=3)
```

# networkx.MultiGraph.add weighted edges from

```
add_weighted_edges_from(ebunch, **attr)
```

Add all the edges in ebunch as weighted edges with specified weights.

>>> G.add\_edges\_from([(3,4),(1,4)], label='WN2898')

Parameters ebunch: container of edges

Each edge given in the list or container will be added to the graph. The edges must be given as 3-tuples (u,v,w) where w is a number.

attr: keyword arguments, optional (default= no attributes)

Edge attributes to add/update for all edges.

#### See Also:

```
add_edge add a single edge
add_edges_from add multiple edges
```

#### **Notes**

Adding the same edge twice has no effect but any edge data will be updated when each duplicate edge is added.

## **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_weighted_edges_from([(0,1,3.0),(1,2,7.5)])
```

# networkx.MultiGraph.remove\_edge

```
remove_edge (u, v, key=None)
```

Remove an edge between u and v.

#### Parameters u,v: nodes:

Remove an edge between nodes u and v.

**key**: hashable identifier, optional (default=None)

Used to distinguish multiple edges between a pair of nodes. If None remove a single (abritrary) edge between u and v.

#### Raises NetworkXError:

If there is not an edge between u and v, or if there is no edge with the specified key.

#### See Also:

remove edges from remove a collection of edges

## **Examples**

```
>>> G = nx.MultiGraph()
>>> G.add_path([0,1,2,3])
>>> G.remove_edge(0,1)
>>> e = (1,2)
>>> G.remove_edge(*e) # unpacks e from an edge tuple
For multiple edges
>>> G = nx.MultiGraph()
                         # or MultiDiGraph, etc
>>> G.add_edges_from([(1,2),(1,2),(1,2)])
>>> G.remove_edge(1,2) # remove a single (arbitrary) edge
For edges with keys
>>> G = nx.MultiGraph()
                         # or MultiDiGraph, etc
>>> G.add_edge(1,2,key='first')
>>> G.add_edge(1,2,key='second')
>>> G.remove_edge(1,2,key='second')
```

## networkx.MultiGraph.remove\_edges\_from

```
remove_edges_from(ebunch)
```

Remove all edges specified in ebunch.

### Parameters ebunch: list or container of edge tuples :

Each edge given in the list or container will be removed from the graph. The edges can be:

- 2-tuples (u,v) All edges between u and v are removed.
- 3-tuples (u,v,key) The edge identified by key is removed.

### See Also:

remove\_edge remove a single edge

### **Notes**

Will fail silently if an edge in ebunch is not in the graph.

# **Examples**

```
>>> G = nx.MultiGraph() # or MultiDiGraph
>>> G.add_path([0,1,2,3])
>>> ebunch=[(1,2),(2,3)]
>>> G.remove_edges_from(ebunch)

Removing multiple copies of edges

>>> G = nx.MultiGraph()
>>> G.add_edges_from([(1,2),(1,2),(1,2)])
>>> G.remove_edges_from([(1,2),(1,2)])
>>> print G.edges()
[(1, 2)]
>>> G.remove_edges_from([(1,2),(1,2)]) # silently ignore extra copy
>>> print G.edges() # now empty graph
```

## networkx.MultiGraph.add\_star

```
add_star (nlist, **attr)
Add a star.
```

[]

The first node in nlist is the middle of the star. It is connected to all other nodes in nlist.

Parameters nlist: list

A list of nodes.

attr: keyword arguments, optional (default= no attributes)

Attributes to add to every edge in star.

#### See Also:

```
add_path, add_cycle
```

# **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_star([0,1,2,3])
>>> G.add_star([10,11,12],weight=2)
```

## networkx.MultiGraph.add\_path

```
add_path (nlist, **attr)
    Add a path.
```

Parameters nlist: list

A list of nodes. A path will be constructed from the nodes (in order) and added to the graph.

attr: keyword arguments, optional (default= no attributes)

Attributes to add to every edge in path.

#### See Also:

```
add_star,add_cycle
```

## **Examples**

```
>>> G=nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> G.add_path([10,11,12],weight=7)
```

## networkx.MultiGraph.add\_cycle

```
add_cycle (nlist, **attr)
Add a cycle.
```

#### Parameters nlist: list

A list of nodes. A cycle will be constructed from the nodes (in order) and added to the graph.

attr: keyword arguments, optional (default= no attributes)

Attributes to add to every edge in cycle.

#### See Also:

```
add_path, add_star
```

# **Examples**

```
>>> G=nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_cycle([0,1,2,3])
>>> G.add_cycle([10,11,12],weight=7)
```

## networkx.MultiGraph.clear

### clear()

Remove all nodes and edges from the graph.

This also removes the name, and all graph, node, and edge attributes.

## **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> G.clear()
>>> G.nodes()
[]
```

```
>>> G.edges()
```

### Iterating over nodes and edges

```
MultiGraph.nodes([data])
                                              Return a list of the nodes in the graph.
MultiGraph.nodes_iter([data])
                                              Return an iterator over the nodes.
                                              Iterate over the nodes.
MultiGraph.__iter__()
MultiGraph.edges([nbunch, data, keys])
                                              Return a list of edges.
MultiGraph.edges iter([nbunch, data,
                                              Return an iterator over the edges.
keys])
MultiGraph.get_edge_data(u, v[, key,
                                              Return the attribute dictionary associated with edge (u,v).
default])
MultiGraph.neighbors(n)
                                              Return a list of the nodes connected to the node n.
{\tt MultiGraph.neighbors\_iter(n)}
                                              Return an iterator over all neighbors of node n.
MultiGraph.__getitem__(n)
                                              Return a dict of neighbors of node n.
MultiGraph.adjacency_list()
                                              Return an adjacency list representation of the graph.
MultiGraph.adjacency_iter()
                                              Return an iterator of (node, adjacency dict) tuples for all nodes.
                                              Return an iterator of nodes contained in nbunch that are also in
MultiGraph.nbunch_iter([nbunch])
                                              the graph.
```

## networkx.MultiGraph.nodes

nodes (data=False)

Return a list of the nodes in the graph.

Parameters data: boolean, optional (default=False)

If False return a list of nodes. If True return a two-tuple of node and node data dictionary

Returns nlist: list

A list of nodes. If data=True a list of two-tuples containing (node, node data dictionary).

## **Examples**

```
>>> G = nx.Graph()  # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2])
>>> print G.nodes()
[0, 1, 2]
>>> G.add_node(1, time='5pm')
>>> print G.nodes(data=True)
[(0, {}), (1, {'time': '5pm'}), (2, {})]
```

## networkx.MultiGraph.nodes\_iter

```
nodes_iter(data=False)
```

Return an iterator over the nodes.

**Parameters data**: boolean, optional (default=False)

If False the iterator returns nodes. If True return a two-tuple of node and node data dictionary

Returns niter: iterator

An iterator over nodes. If data=True the iterator gives two-tuples containing (node, node data, dictionary)

### **Notes**

If the node data is not required it is simpler and equivalent to use the expression 'for n in G'.

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2])
>>> for n in G:
... print n,
0 1 2
```

## **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2])
>>> for n in G.nodes_iter():
...    print n,
0 1 2
>>> for n,d in G.nodes_iter(data=True):
...    print d,
{} {} {} {}
```

## networkx.MultiGraph.\_\_iter\_\_

```
___iter___()
```

Iterate over the nodes. Use the expression 'for n in G'.

Returns niter: iterator

An iterator over all nodes in the graph.

# **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> for n in G:
... print n,
0 1 2 3
```

# networkx.MultiGraph.edges

```
edges (nbunch=None, data=False, keys=False)
Return a list of edges.
```

Edges are returned as tuples with optional data and keys in the order (node, neighbor, key, data).

Parameters nbunch: iterable container, optional (default= all nodes)

A container of nodes. The container will be iterated through once.

data: bool, optional (default=False)

Return two tuples (u,v) (False) or three-tuples (u,v,data) (True).

keys: bool, optional (default=False)

Return two tuples (u,v) (False) or three-tuples (u,v,key) (True).

### Returns edge\_list: list of edge tuples :

Edges that are adjacent to any node in nbunch, or a list of all edges if nbunch is not specified.

#### See Also:

edges\_iter return an iterator over the edges

### **Notes**

Nodes in nbunch that are not in the graph will be (quietly) ignored.

## **Examples**

```
>>> G = nx.MultiGraph() # or MultiDiGraph
>>> G.add_path([0,1,2,3])
>>> G.edges()
[(0, 1), (1, 2), (2, 3)]
>>> G.edges(data=True) # default edge data is {} (empty dictionary)
[(0, 1, {}), (1, 2, {}), (2, 3, {})]
>>> G.edges(keys=True) # default keys are integers
[(0, 1, 0), (1, 2, 0), (2, 3, 0)]
>>> G.edges(data=True,keys=True) # default keys are integers
[(0, 1, 0, {}), (1, 2, 0, {}), (2, 3, 0, {})]
>>> G.edges([0,3])
[(0, 1), (3, 2)]
>>> G.edges(0)
[(0, 1)]
```

## networkx.MultiGraph.edges\_iter

```
edges_iter (nbunch=None, data=False, keys=False)
```

Return an iterator over the edges.

Edges are returned as tuples with optional data and keys in the order (node, neighbor, key, data).

**Parameters nbunch**: iterable container, optional (default= all nodes)

A container of nodes. The container will be iterated through once.

data: bool, optional (default=False)

If True, return edge attribute dict with each edge.

```
keys: bool, optional (default=False)
```

If True, return edge keys with each edge.

### Returns edge\_iter: iterator

An iterator of (u,v), (u,v,d) or (u,v,key,d) tuples of edges.

#### See Also:

edges return a list of edges

#### **Notes**

Nodes in nbunch that are not in the graph will be (quietly) ignored.

## **Examples**

```
>>> G = nx.MultiGraph() # or MultiDiGraph
>>> G.add_path([0,1,2,3])
>>> [e for e in G.edges_iter()]
[(0, 1), (1, 2), (2, 3)]
>>> list(G.edges_iter(data=True)) # default data is {} (empty dict)
[(0, 1, {}), (1, 2, {}), (2, 3, {})]
>>> list(G.edges(keys=True)) # default keys are integers
[(0, 1, 0), (1, 2, 0), (2, 3, 0)]
>>> list(G.edges(data=True,keys=True)) # default keys are integers
[(0, 1, 0, {}), (1, 2, 0, {}), (2, 3, 0, {})]
>>> list(G.edges_iter([0,3]))
[(0, 1), (3, 2)]
>>> list(G.edges_iter(0))
[(0, 1)]
```

## networkx.MultiGraph.get edge data

```
get_edge_data (u, v, key=None, default=None)
```

Return the attribute dictionary associated with edge (u,v).

Parameters u,v: nodes

### default: any Python object (default=None) :

Value to return if the edge (u,v) is not found.

key: hashable identifier, optional (default=None)

Return data only for the edge with specified key.

Returns edge\_dict : dictionary

The edge attribute dictionary.

### **Notes**

It is faster to use G[u][v][key].

```
>>> G = nx.MultiGraph() # or MultiDiGraph
>>> G.add_edge(0,1,key='a',weight=7)
>>> G[0][1]['a'] # key='a'
{'weight': 7}
```

Warning: Assigning G[u][v][key] corrupts the graph data structure. But it is safe to assign attributes to that dictionary,

```
>>> G[0][1]['a']['weight'] = 10
>>> G[0][1]['a']['weight']
10
>>> G[1][0]['a']['weight']
```

# **Examples**

```
>>> G = nx.MultiGraph() # or MultiDiGraph
>>> G.add_path([0,1,2,3])
>>> G.get_edge_data(0,1)
{0: {}}
>>> e = (0,1)
>>> G.get_edge_data(*e) # tuple form
{0: {}}
>>> G.get_edge_data('a','b',default=0) # edge not in graph, return 0
0
```

# networkx.MultiGraph.neighbors

```
neighbors(n)
```

Return a list of the nodes connected to the node n.

**Parameters n**: node

A node in the graph

Returns nlist: list

A list of nodes that are adjacent to n.

Raises NetworkXError:

If the node n is not in the graph.

### **Notes**

It is usually more convenient (and faster) to access the adjacency dictionary as G[n]:

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_edge('a','b',weight=7)
>>> G['a']
{'b': {'weight': 7}}
```

## **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> G.neighbors(0)
[1]
```

## networkx.MultiGraph.neighbors\_iter

```
neighbors_iter(n)
```

Return an iterator over all neighbors of node n.

### **Notes**

It is faster to use the idiom "in G[0]", e.g. >>> for n in G[0]: ... print n 1

## **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> print [n for n in G.neighbors_iter(0)]
[1]
```

# networkx.MultiGraph.\_\_getitem\_\_

```
qetitem (n)
```

Return a dict of neighbors of node n. Use the expression 'G[n]'.

Parameters n: node

A node in the graph.

**Returns adj\_dict**: dictionary

The adjacency dictionary for nodes connected to n.

### **Notes**

G[n] is similar to G.neighbors(n) but the internal data dictionary is returned instead of a list.

Assigning G[n] will corrupt the internal graph data structure. Use G[n] for reading data only.

## **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> print G[0]
{1: {}}
```

## networkx.MultiGraph.adjacency list

```
adjacency_list()
```

Return an adjacency list representation of the graph.

The output adjacency list is in the order of G.nodes(). For directed graphs, only outgoing adjacencies are included.

Returns adj\_list: lists of lists

The adjacency structure of the graph as a list of lists.

#### See Also:

```
adjacency_iter
```

# **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> G.adjacency_list() # in order given by G.nodes()
[[1], [0, 2], [1, 3], [2]]
```

## networkx.MultiGraph.adjacency\_iter

```
adjacency_iter()
```

Return an iterator of (node, adjacency dict) tuples for all nodes.

This is the fastest way to look at every edge. For directed graphs, only outgoing adjacencies are included.

```
Returns adj_iter: iterator
```

An iterator of (node, adjacency dictionary) for all nodes in the graph.

#### See Also:

```
adjacency_list
```

# **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> [(n,nbrdict) for n,nbrdict in G.adjacency_iter()]
[(0, {1: {}}), (1, {0: {}, 2: {}}), (2, {1: {}, 3: {}}), (3, {2: {}})]
```

## networkx.MultiGraph.nbunch iter

```
nbunch_iter(nbunch=None)
```

Return an iterator of nodes contained in nbunch that are also in the graph.

The nodes in nbunch are checked for membership in the graph and if not are silently ignored.

Parameters nbunch: iterable container, optional (default=all nodes)

A container of nodes. The container will be iterated through once.

**Returns niter**: iterator

An iterator over nodes in nbunch that are also in the graph. If nbunch is None, iterate over all nodes in the graph.

#### Raises NetworkXError:

If nbunch is not a node or or sequence of nodes. If a node in nbunch is not hashable.

#### See Also:

```
Graph.__iter__
```

### **Notes**

When nbunch is an iterator, the returned iterator yields values directly from nbunch, becoming exhausted when nbunch is exhausted.

To test whether nbunch is a single node, one can use "if nbunch in self:", even after processing with this routine.

If nbunch is not a node or a (possibly empty) sequence/iterator or None, a NetworkXError is raised. Also, if any object in nbunch is not hashable, a NetworkXError is raised.

### Information about graph structure

MultiGraph.has_node(n)	Return True if the graph contains the node n.
MultiGraphcontains(n)	Return True if n is a node, False otherwise. Use the expression
$MultiGraph.has\_edge(u, v[, key])$	Return True if the graph has an edge between nodes u and v.
MultiGraph.nodes_with_selfloops()	Return a list of nodes with self loops.
MultiGraph.selfloop_edges([data, keys])	Return a list of selfloop edges.
MultiGraph.order()	Return the number of nodes in the graph.
MultiGraph.number_of_nodes()	Return the number of nodes in the graph.
MultiGraphlen()	Return the number of nodes.
MultiGraph.size([weighted])	Return the number of edges.
$ exttt{MultiGraph.number\_of\_edges}([u,v])$	Return the number of edges between two nodes.
MultiGraph.number_of_selfloops()	Return the number of selfloop edges.
MultiGraph.degree([nbunch, with_labels,])	Return the degree of a node or nodes.
<pre>MultiGraph.degree_iter([nbunch, weighted])</pre>	Return an iterator for (node, degree).

# networkx.MultiGraph.has node

#### $has\_node(n)$

Return True if the graph contains the node n.

Parameters n: node

## **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2])
>>> print G.has_node(0)
True
```

It is more readable and simpler to use

```
>>> 0 in G
True
```

## networkx.MultiGraph. contains

```
__contains__(n)
```

Return True if n is a node, False otherwise. Use the expression 'n in G'.

## **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> print 1 in G
True
```

# networkx.MultiGraph.has\_edge

```
has\_edge(u, v, key=None)
```

Return True if the graph has an edge between nodes u and v.

Parameters u,v: nodes

Nodes can be, for example, strings or numbers.

key: hashable identifier, optional (default=None)

If specified return True only if the edge with key is found.

Returns edge\_ind: bool

True if edge is in the graph, False otherwise.

## **Examples**

Can be called either using two nodes u,v, an edge tuple (u,v), or an edge tuple (u,v,key).

```
>>> G = nx.MultiGraph() # or MultiDiGraph
>>> G.add_path([0,1,2,3])
>>> G.has_edge(0,1) # using two nodes
True
>>> e = (0,1)
>>> G.has_edge(*e) # e is a 2-tuple (u,v)
```

```
True
>>> G.add_edge(0,1,key='a')
>>> G.has_edge(0,1,key='a') # specify key
True
>>> e=(0,1,'a')
>>> G.has_edge(*e) # e is a 3-tuple (u,v,'a')
True

The following syntax are equivalent:
>>> G.has_edge(0,1)
True
>>> 1 in G[0] # though this gives KeyError if 0 not in G
True
```

## networkx.MultiGraph.nodes with selfloops

```
nodes_with_selfloops()
```

Return a list of nodes with self loops.

A node with a self loop has an edge with both ends adjacent to that node.

Returns nodelist: list

A list of nodes with self loops.

#### See Also:

```
selfloop_edges, number_of_selfloops
```

# **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_edge(1,1)
>>> G.add_edge(1,2)
>>> G.nodes_with_selfloops()
[1]
```

# networkx.MultiGraph.selfloop\_edges

```
selfloop_edges (data=False, keys=False)
```

Return a list of selfloop edges.

A selfloop edge has the same node at both ends.

Parameters data: bool, optional (default=False)

Return selfloop edges as two tuples (u,v) (data=False) or three-tuples (u,v,data) (data=True)

keys: bool, optional (default=False)

If True, return edge keys with each edge.

**Returns edgelist**: list of edge tuples

A list of all selfloop edges.

#### See Also:

```
selfloop_nodes, number_of_selfloops
```

## **Examples**

```
>>> G = nx.MultiGraph() # or MultiDiGraph
>>> G.add_edge(1,1)
>>> G.add_edge(1,2)
>>> G.selfloop_edges()
[(1, 1)]
>>> G.selfloop_edges(data=True)
[(1, 1, {})]
>>> G.selfloop_edges(keys=True)
[(1, 1, 0)]
>>> G.selfloop_edges(keys=True, data=True)
[(1, 1, 0, {})]
```

## networkx.MultiGraph.order

```
order()
```

Return the number of nodes in the graph.

Returns nnodes: int

The number of nodes in the graph.

### See Also:

```
number_of_nodes, __len__
```

# networkx.MultiGraph.number\_of\_nodes

```
number_of_nodes()
```

Return the number of nodes in the graph.

Returns nnodes: int

The number of nodes in the graph.

#### See Also:

```
order, __len__
```

# **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2])
>>> print len(G)
3
```

## networkx.MultiGraph.\_\_len\_\_

```
__len__()
```

Return the number of nodes. Use the expression 'len(G)'.

Returns nnodes: int

The number of nodes in the graph.

## **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> print len(G)
4
```

## networkx.MultiGraph.size

```
size (weighted=False)
```

Return the number of edges.

**Parameters weighted**: boolean, optional (default=False)

If True return the sum of the edge weights.

Returns nedges: int

The number of edges in the graph.

#### See Also:

```
number_of_edges
```

# **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> G.size()
3
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_edge('a','b',weight=2)
>>> G.add_edge('b','c',weight=4)
>>> G.size()
2
>>> G.size(weighted=True)
6
```

# networkx.MultiGraph.number\_of\_edges

```
number_of_edges (u=None, v=None)
```

Return the number of edges between two nodes.

**Parameters u,v**: nodes, optional (default=all edges)

If u and v are specified, return the number of edges between u and v. Otherwise return the total number of all edges.

Returns nedges: int

The number of edges in the graph. If nodes u and v are specified return the number of edges between those nodes.

#### See Also:

size

## **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> G.number_of_edges()
3
>>> G.number_of_edges(0,1)
1
>>> e = (0,1)
>>> G.number_of_edges(*e)
```

## networkx.MultiGraph.number of selfloops

```
number_of_selfloops()
```

Return the number of selfloop edges.

A selfloop edge has the same node at both ends.

Returns nloops: int

The number of selfloops.

#### See Also:

```
selfloop_nodes, selfloop_edges
```

# **Examples**

```
>>> G=nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_edge(1,1)
>>> G.add_edge(1,2)
>>> G.number_of_selfloops()
1
```

## networkx.MultiGraph.degree

```
degree (nbunch=None, with_labels=False, weighted=False) Return the degree of a node or nodes.
```

The node degree is the number of edges adjacent to that node.

**Parameters nbunch**: iterable container, optional (default=all nodes)

A container of nodes. The container will be iterated through once.

with\_labels : bool, optional (default=False)

If True return a dictionary of degrees keyed by node.

weighted: bool, optional (default=False)

If True return the sum of edge weights adjacent to the node.

Returns nd: list, or dictionary

A list of node degrees or a dictionary with nodes as keys and degree as values if with\_labels=True).

## **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> G.degree(0)
1
>>> G.degree([0,1])
[1, 2]
>>> G.degree([0,1],with_labels=True)
{0: 1, 1: 2}
```

# networkx.MultiGraph.degree\_iter

```
degree_iter (nbunch=None, weighted=False)
```

Return an iterator for (node, degree).

The node degree is the number of edges adjacent to the node.

**Parameters nbunch**: iterable container, optional (default=all nodes)

A container of nodes. The container will be iterated through once.

weighted : bool, optional (default=False)

If True return the sum of edge weights adjacent to the node.

Returns nd iter: an iterator

The iterator returns two-tuples of (node, degree).

### See Also:

degree

# **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> list(G.degree_iter(0)) # node 0 with degree 1
```

```
[(0, 1)]
>>> list(G.degree_iter([0,1]))
[(0, 1), (1, 2)]
```

## Making copies and subgraphs

```
MultiGraph.copy()

MultiGraph.to_directed()

MultiGraph.subgraph(nbunch[, copy])

Return a copy of the graph.

Return a directed representation of the graph.

Return the subgraph induced on nodes in nbunch.
```

## networkx.MultiGraph.copy

#### copy()

Return a copy of the graph.

Returns G: Graph

A copy of the graph.

#### See Also:

to\_directed return a directed copy of the graph.

### **Notes**

This makes a complete copy of the graph including all of the node or edge attributes.

## **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> H = G.copy()
```

# networkx.MultiGraph.to\_directed

#### to directed()

Return a directed representation of the graph.

### Returns G: MultiDiGraph

A directed graph with the same name, same nodes, and with each edge (u,v,data) replaced by two directed edges (u,v,data) and (v,u,data).

### **Notes**

This is similar to MultiDiGraph(self) which returns a shallow copy. self.to\_undirected() returns a deepcopy of edge, node and graph attributes.

## **Examples**

```
>>> G = nx.Graph() # or MultiGraph, etc
>>> G.add_path([0,1])
>>> H = G.to_directed()
>>> H.edges()
[(0, 1), (1, 0)]

If already directed, return a (deep) copy
>>> G = nx.DiGraph() # or MultiDiGraph, etc
>>> G.add_path([0,1])
>>> H = G.to_directed()
```

## networkx.MultiGraph.subgraph

```
subgraph (nbunch, copy=True)
```

>>> H.edges()
[(0, 1)]

Return the subgraph induced on nodes in nbunch.

The induced subgraph of the graph has the nodes in nbunch as its node set and the edges adjacent to those nodes as its edge set.

Parameters nbunch: list, iterable

A container of nodes. The container will be iterated through once.

```
copy: bool, optional (default=True)
```

If True return a new graph holding the subgraph including copies of all edge and node properties. If False the subgraph is created using the original graph by deleting all nodes not in nbunch (this changes the original graph).

#### Returns G: Graph

A subgraph of the graph. If copy=True a new graph is returned with copies of graph, node, and edge data. If copy=False the subgraph is created in place by modifying the original graph.

#### **Notes**

If copy=True, nodes and edges are copied using copy.deepcopy.

# **Examples**

```
>>> G = nx.Graph()  # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> H = G.subgraph([0,1,2])
>>> print H.edges()
[(0, 1), (1, 2)]
```

## 3.2.4 MultiDiGraph - Directed graphs with self loops and parallel edges

#### Overview

```
MultiDiGraph (data=None, name=", **attr)
```

A directed graph class that can store multiedges.

Multiedges are multiple edges between two nodes. Each edge can hold optional data or attributes.

A MultiDiGraph holds directed edges. Self loops are allowed.

Nodes can be arbitrary (hashable) Python objects with optional key/value attributes.

Edges are represented as links between nodes with optional key/value attributes.

#### Parameters data: input graph

Data to initialize graph. If data=None (default) an empty graph is created. The data can be an edge list, or any NetworkX graph object. If the corresponding optional Python packages are installed the data can also be a NumPy matrix or 2d ndarray, a SciPy sparse matrix, or a PyGraphviz graph.

```
name : string, optional (default='')
```

An optional name for the graph.

**attr**: keyword arguments, optional (default= no attributes)

Attributes to add to graph as key=value pairs.

#### See Also:

```
Graph, DiGraph, MultiGraph
```

### **Examples**

Create an empty graph structure (a "null graph") with no nodes and no edges.

```
>>> G = nx.MultiDiGraph()
```

G can be grown in several ways.

#### **Nodes:**

Add one node at a time:

```
>>> G.add_node(1)
```

Add the nodes from any container (a list, dict, set or even the lines from a file or the nodes from another graph).

```
>>> G.add_nodes_from([2,3])
>>> G.add_nodes_from(range(100,110))
>>> H=nx.path_graph(10)
>>> G.add_nodes_from(H)
```

In addition to strings and integers any hashable Python object (except None) can represent a node, e.g. a customized node object, or even another Graph.

```
>>> G.add_node(H)
```

#### **Edges:**

G can also be grown by adding edges.

Add one edge,

```
>>> G.add_edge(1, 2)
a list of edges,
>>> G.add_edges_from([(1,2),(1,3)])
or a collection of edges,
>>> G.add_edges_from(H.edges())
```

If some edges connect nodes not yet in the graph, the nodes are added automatically. If an edge already exists, an additional edge is created and stored using a key to identify the edge. By default the key is the lowest unused integer.

```
>>> G.add_edges_from([(4,5,dict(route=282)), (4,5,dict(route=37))])
>>> G[4]
{5: {0: {}, 1: {'route': 282}, 2: {'route': 37}}}
```

#### **Attributes:**

Each graph, node, and edge can hold key/value attribute pairs in an associated attribute dictionary (the keys must be hashable). By default these are empty, but can be added or changed using add\_edge, add\_node or direct manipulation of the attribute dictionaries named graph, node and edge respectively.

```
>>> G = nx.MultiDiGraph(day="Friday")
>>> G.graph
{'day': 'Friday'}
```

Add node attributes using add\_node(), add\_nodes\_from() or G.node

```
>>> G.add_node(1, time='5pm')
>>> G.add_nodes_from([3], time='2pm')
>>> G.node[1]
{'time': '5pm'}
>>> G.node[1]['room'] = 714
>>> G.nodes(data=True)
[(1, {'room': 714, 'time': '5pm'}), (3, {'time': '2pm'})]
```

Warning: adding a node to G.node does not add it to the graph.

Add edge attributes using add\_edge(), add\_edges\_from(), subscript notation, or G.edge.

```
>>> G.add_edge(1, 2, weight=4.7 )
>>> G.add_edges_from([(3,4),(4,5)], color='red')
>>> G.add_edges_from([(1,2,{'color':'blue'}), (2,3,{'weight':8})])
>>> G[1][2][0]['weight'] = 4.7
>>> G.edge[1][2][0]['weight'] = 4
```

#### **Shortcuts:**

Many common graph features allow python syntax to speed reporting.

```
>>> 1 in G  # check if node in graph
True
>>> print [n for n in G if n<3]  # iterate through nodes
[1, 2]
>>> print len(G)  # number of nodes in graph
5
>>> print G[1]  # adjacency dict keyed by neighbor to edge attributes
...  # Note: you should not change this dict manually!
{2: {0: {'weight': 4}, 1: {'color': 'blue'}}}
```

The fastest way to traverse all edges of a graph is via adjacency\_iter(), but the edges() method is often more convenient.

#### **Reporting:**

Simple graph information is obtained using methods. Iterator versions of many reporting methods exist for efficiency. Methods exist for reporting nodes(), edges(), neighbors() and degree() as well as the number of nodes and edges.

For details on these and other miscellaneous methods, see below.

### **Adding and Removing Nodes and Edges**

```
MultiDiGraph.__init__(**attr[, data, name])
                                                 Initialize a graph with edges, name, graph attributes.
MultiDiGraph.add_node(n, **attr[, attr_dict])
                                                 Add a single node n and update node attributes.
MultiDiGraph.add_nodes_from(nodes,
                                                 Add multiple nodes.
**attr)
                                                 Remove node n.
MultiDiGraph.remove node(n)
                                                 Remove multiple nodes.
MultiDiGraph.remove nodes from(nbunch)
MultiDiGraph.add_edge(u, v, **attr[, key, ...])
                                                 Add an edge between u and v.
MultiDiGraph.add edges from(ebunch,
                                                 Add all the edges in ebunch.
**attr)
MultiDiGraph.add_weighted_edges_from(ebAndkhall the edges in ebunch as weighted edges with
                                                 specified weights.
...)
                                                 Remove an edge between u and v.
MultiDiGraph.remove_edge(u, v[, key])
MultiDiGraph.remove_edges_from(ebunch)
                                                 Remove all edges specified in ebunch.
MultiDiGraph.add_star(nlist, **attr)
                                                 Add a star.
MultiDiGraph.add_path(nlist, **attr)
                                                 Add a path.
MultiDiGraph.add_cycle(nlist, **attr)
                                                 Add a cycle.
MultiDiGraph.clear()
                                                 Remove all nodes and edges from the graph.
```

## networkx.MultiDiGraph. init

```
__init__(data=None, name=", **attr)
Initialize a graph with edges, name, graph attributes.
```

Parameters data: input graph

Data to initialize graph. If data=None (default) an empty graph is created. The data can be an edge list, or any NetworkX graph object. If the corresponding optional Python packages are installed the data can also be a NumPy matrix or 2d ndarray, a SciPy sparse matrix, or a PyGraphviz graph.

```
name : string, optional (default='')
```

An optional name for the graph.

attr: keyword arguments, optional (default= no attributes)

Attributes to add to graph as key=value pairs.

#### See Also:

convert

## **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G = nx.Graph(name='my graph')
>>> e = [(1,2),(2,3),(3,4)] # list of edges
>>> G = nx.Graph(e)
```

Arbitrary graph attribute pairs (key=value) may be assigned

```
>>> G=nx.Graph(e, day="Friday")
>>> G.graph
{'day': 'Friday'}
```

# networkx.MultiDiGraph.add\_node

```
add_node (n, attr_dict=None, **attr)
```

Add a single node n and update node attributes.

#### Parameters n: node

A node can be any hashable Python object except None.

```
attr_dict : dictionary, optional (default= no attributes)
```

Dictionary of node attributes. Key/value pairs will update existing data associated with the node.

attr: keyword arguments, optional

Set or change attributes using key=value.

#### See Also:

```
add_nodes_from
```

### **Notes**

A hashable object is one that can be used as a key in a Python dictionary. This includes strings, numbers, tuples of strings and numbers, etc.

On many platforms hashable items also include mutables such as NetworkX Graphs, though one should be careful that the hash doesn't change on mutables.

## **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_node(1)
>>> G.add_node('Hello')
>>> K3 = nx.Graph([(0,1),(1,2),(2,0)])
>>> G.add_node(K3)
>>> G.number_of_nodes()
3
```

Use keywords set/change node attributes:

```
>>> G.add_node(1,size=10)
>>> G.add_node(3,weight=0.4,UTM=('13S',382871,3972649))
```

# networkx.MultiDiGraph.add\_nodes\_from

```
add_nodes_from (nodes, **attr)
Add multiple nodes.
```

Parameters nodes: iterable container

A container of nodes (list, dict, set, etc.). The container will be iterated through once.

attr: keyword arguments, optional (default= no attributes)

Update attributes for all nodes in nodes.

### See Also:

add node

## **Examples**

```
>>> G = nx.Graph()  # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_nodes_from('Hello')
>>> K3 = nx.Graph([(0,1),(1,2),(2,0)])
>>> G.add_nodes_from(K3)
>>> sorted(G.nodes())
[0, 1, 2, 'H', 'e', 'l', 'o']
```

Use keywords to update specific node attributes for every node.

```
>>> G.add_nodes_from([1,2], size=10)
>>> G.add_nodes_from([3,4], weight=0.4)
```

## networkx.MultiDiGraph.remove\_node

```
{\tt remove\_node}\:(n)
```

Remove node n.

Removes the node n and all adjacent edges. Attempting to remove a non-existent node will raise an exception.

Parameters n: node

A node in the graph

Raises NetworkXError:

If n is not in the graph.

### See Also:

```
remove_nodes_from
```

## **Examples**

```
>>> G = nx.Graph()  # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2])
>>> G.edges()
[(0, 1), (1, 2)]
>>> G.remove_node(1)
>>> G.edges()
[]
```

# networkx.MultiDiGraph.remove\_nodes\_from

```
{\tt remove\_nodes\_from}\,(nbunch)
```

Remove multiple nodes.

Parameters nodes: iterable container

A container of nodes (list, dict, set, etc.). If a node in the container is not in the graph it is silently ignored.

#### See Also:

remove\_node

## **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2])
>>> e = G.nodes()
>>> e
[0, 1, 2]
>>> G.remove_nodes_from(e)
>>> G.nodes()
[]
```

### networkx.MultiDiGraph.add edge

```
add_edge (u, v, key=None, attr_dict=None, **attr)
Add an edge between u and v.
```

The nodes u and v will be automatically added if they are not already in the graph.

Edge attributes can be specified with keywords or by providing a dictionary with key/value pairs. See examples below.

#### Parameters u,v: nodes

Nodes can be, for example, strings or numbers. Nodes must be hashable (and not None) Python objects.

key: hashable identifier, optional (default=lowest unused integer)

Used to distinguish multiedges between a pair of nodes.

```
attr_dict : dictionary, optional (default= no attributes)
```

Dictionary of edge attributes. Key/value pairs will update existing data associated with the edge.

attr: keyword arguments, optional

Edge data (or labels or objects) can be assigned using keyword arguments.

#### See Also:

```
add_edges_from add a collection of edges
```

#### **Notes**

To replace/update edge data, use the optional key argument to identify a unique edge. Otherwise a new edge will be created.

NetworkX algorithms designed for weighted graphs cannot use multigraphs directly because it is not clear how to handle multiedge weights. Convert to Graph using edge attribute 'weight' to enable weighted graph algorithms.

# **Examples**

The following all add the edge e=(1,2) to graph G:

```
>>> G = nx.MultiDiGraph()
>>> e = (1,2)
>>> G.add_edge(1, 2)  # explicit two-node form
>>> G.add_edge(*e)  # single edge as tuple of two nodes
>>> G.add_edges_from([(1,2)]) # add edges from iterable container
```

Associate data to edges using keywords:

```
>>> G.add_edge(1, 2, weight=3)
>>> G.add_edge(1, 2, key=0, weight=4) # update data for key=0
>>> G.add_edge(1, 3, weight=7, capacity=15, length=342.7)
```

## networkx.MultiDiGraph.add\_edges\_from

```
add_edges_from (ebunch, attr_dict=None, **attr)
Add all the edges in ebunch.
```

Parameters ebunch: container of edges

Each edge given in the container will be added to the graph. The edges can be:

- 2-tuples (u,v) or
- 3-tuples (u,v,d) for an edge attribute dict d, or
- 4-tuples (u,v,k,d) for an edge identified by key k

attr\_dict : dictionary, optional (default= no attributes)

Dictionary of edge attributes. Key/value pairs will update existing data associated with each edge.

attr: keyword arguments, optional

Edge data (or labels or objects) can be assigned using keyword arguments.

#### See Also:

```
add_edge add a single edge
add_weighted_edges_from convenient way to add weighted edges
```

#### **Notes**

Adding the same edge twice has no effect but any edge data will be updated when each duplicate edge is added.

## **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_edges_from([(0,1),(1,2)]) # using a list of edge tuples
>>> e = zip(range(0,3),range(1,4))
>>> G.add_edges_from(e) # Add the path graph 0-1-2-3
Associate data to edges
```

```
>>> G.add_edges_from([(1,2),(2,3)], weight=3)
>>> G.add_edges_from([(3,4),(1,4)], label='WN2898')
```

# networkx.MultiDiGraph.add\_weighted\_edges\_from

```
add_weighted_edges_from(ebunch, **attr)
```

Add all the edges in ebunch as weighted edges with specified weights.

Parameters ebunch: container of edges

Each edge given in the list or container will be added to the graph. The edges must be given as 3-tuples (u,v,w) where w is a number.

attr: keyword arguments, optional (default= no attributes)

Edge attributes to add/update for all edges.

#### See Also:

```
add_edge add a single edge
add_edges_from add multiple edges
```

### **Notes**

Adding the same edge twice has no effect but any edge data will be updated when each duplicate edge is added.

## **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_weighted_edges_from([(0,1,3.0),(1,2,7.5)])
```

## networkx.MultiDiGraph.remove\_edge

```
remove\_edge(u, v, key=None)
```

Remove an edge between u and v.

#### Parameters u,v: nodes:

Remove an edge between nodes u and v.

key: hashable identifier, optional (default=None)

Used to distinguish multiple edges between a pair of nodes. If None remove a single (abritrary) edge between u and v.

#### Raises NetworkXError:

If there is not an edge between u and v, or if there is no edge with the specified key.

### See Also:

remove\_edges\_from remove a collection of edges

# **Examples**

```
>>> G = nx.MultiDiGraph()
>>> G.add_path([0,1,2,3])
>>> G.remove_edge(0,1)
>>> e = (1,2)
>>> G.remove_edge(*e) # unpacks e from an edge tuple
```

## For multiple edges

```
>>> G = nx.MultiDiGraph()
>>> G.add_edges_from([(1,2),(1,2),(1,2)])
>>> G.remove_edge(1,2) # remove a single (arbitrary) edge
```

For edges with keys

```
>>> G = nx.MultiDiGraph()
>>> G.add_edge(1,2,key='first')
>>> G.add_edge(1,2,key='second')
>>> G.remove_edge(1,2,key='second')
```

## networkx.MultiDiGraph.remove\_edges\_from

```
remove_edges_from(ebunch)
```

Remove all edges specified in ebunch.

### Parameters ebunch: list or container of edge tuples :

Each edge given in the list or container will be removed from the graph. The edges can be:

- 2-tuples (u,v) All edges between u and v are removed.
- 3-tuples (u,v,key) The edge identified by key is removed.

#### See Also:

remove\_edge remove a single edge

#### **Notes**

Will fail silently if an edge in ebunch is not in the graph.

## **Examples**

```
>>> G = nx.MultiGraph() # or MultiDiGraph
>>> G.add_path([0,1,2,3])
>>> ebunch=[(1,2),(2,3)]
>>> G.remove_edges_from(ebunch)

Removing multiple copies of edges
```

```
>>> G = nx.MultiGraph()
```

```
>>> G.add_edges_from([(1,2),(1,2),(1,2)])
>>> G.remove_edges_from([(1,2),(1,2)])
>>> print G.edges()
[(1, 2)]
>>> G.remove_edges_from([(1,2),(1,2)]) # silently ignore extra copy
>>> print G.edges() # now empty graph
[]
```

# networkx.MultiDiGraph.add\_star

```
add_star (nlist, **attr)
Add a star.
```

The first node in nlist is the middle of the star. It is connected to all other nodes in nlist.

Parameters nlist: list

A list of nodes.

attr : keyword arguments, optional (default= no attributes)

Attributes to add to every edge in star.

#### See Also:

```
add_path, add_cycle
```

## **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_star([0,1,2,3])
>>> G.add_star([10,11,12], weight=2)
```

## networkx.MultiDiGraph.add\_path

```
add_path (nlist, **attr)
Add a path.
```

#### Parameters nlist: list

A list of nodes. A path will be constructed from the nodes (in order) and added to the graph.

attr : keyword arguments, optional (default= no attributes)

Attributes to add to every edge in path.

#### See Also:

```
add_star,add_cycle
```

## **Examples**

```
>>> G=nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> G.add_path([10,11,12],weight=7)
```

## networkx.MultiDiGraph.add cycle

```
add_cycle (nlist, **attr)
Add a cycle.
```

#### Parameters nlist: list

A list of nodes. A cycle will be constructed from the nodes (in order) and added to the graph.

attr: keyword arguments, optional (default= no attributes)

Attributes to add to every edge in cycle.

#### See Also:

```
add_path,add_star
```

## **Examples**

```
>>> G=nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_cycle([0,1,2,3])
>>> G.add_cycle([10,11,12],weight=7)
```

## networkx.MultiDiGraph.clear

```
clear()
```

Remove all nodes and edges from the graph.

This also removes the name, and all graph, node, and edge attributes.

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> G.clear()
>>> G.nodes()
[]
>>> G.edges()
[]
```

#### Iterating over nodes and edges

```
MultiDiGraph.nodes([data])
                                                Return a list of the nodes in the graph.
                                                Return an iterator over the nodes.
MultiDiGraph.nodes_iter([data])
MultiDiGraph.__iter__()
                                                Iterate over the nodes.
MultiDiGraph.edges([nbunch, data, keys])
                                                Return a list of edges.
MultiDiGraph.edges_iter([nbunch, data,
                                                Return an iterator over the edges.
MultiDiGraph.out_edges([nbunch, data])
                                                Return a list of edges.
MultiDiGraph.out_edges_iter([nbunch,
                                                Return an iterator over the edges.
data, keys])
MultiDiGraph.in_edges([nbunch, data])
                                                Return a list of the incoming edges.
MultiDiGraph.in edges iter([nbunch,
                                                Return an iterator over the incoming edges.
data, keys])
MultiDiGraph.get_edge_data(u, v[, key,
                                                Return the attribute dictionary associated with edge (u,v).
default])
MultiDiGraph.neighbors(n)
                                                Return a list of successor nodes of n.
                                                Return an iterator over successor nodes of n.
MultiDiGraph.neighbors_iter(n)
MultiDiGraph.__getitem__(n)
                                                Return a dict of neighbors of node n.
MultiDiGraph.successors(n)
                                                Return a list of successor nodes of n.
                                                Return an iterator over successor nodes of n.
MultiDiGraph.successors_iter(n)
                                                Return a list of predecessor nodes of n.
MultiDiGraph.predecessors(n)
MultiDiGraph.predecessors_iter(n)
                                                Return an iterator over predecessor nodes of n.
MultiDiGraph.adjacency_list()
                                                Return an adjacency list representation of the graph.
MultiDiGraph.adjacency_iter()
                                                Return an iterator of (node, adjacency dict) tuples for all
MultiDiGraph.nbunch_iter([nbunch])
                                                Return an iterator of nodes contained in nbunch that are also
                                                in the graph.
```

### networkx.MultiDiGraph.nodes

nodes (data=False)

Return a list of the nodes in the graph.

Parameters data: boolean, optional (default=False)

If False return a list of nodes. If True return a two-tuple of node and node data dictionary

Returns nlist: list

A list of nodes. If data=True a list of two-tuples containing (node, node data dictionary).

```
>>> G = nx.Graph()  # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2])
>>> print G.nodes()
[0, 1, 2]
>>> G.add_node(1, time='5pm')
>>> print G.nodes(data=True)
[(0, {}), (1, {'time': '5pm'}), (2, {})]
```

## networkx.MultiDiGraph.nodes iter

```
nodes_iter(data=False)
```

Return an iterator over the nodes.

Parameters data: boolean, optional (default=False)

If False the iterator returns nodes. If True return a two-tuple of node and node data dictionary

Returns niter: iterator

An iterator over nodes. If data=True the iterator gives two-tuples containing (node, node data, dictionary)

#### **Notes**

If the node data is not required it is simpler and equivalent to use the expression 'for n in G'.

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2])
>>> for n in G:
... print n,
0 1 2
```

## **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2])
>>> for n in G.nodes_iter():
...    print n,
0 1 2
>>> for n,d in G.nodes_iter(data=True):
...    print d,
{} {} {}
```

## networkx.MultiDiGraph.\_\_iter\_\_

```
__iter__()
```

Iterate over the nodes. Use the expression 'for n in G'.

Returns niter: iterator

An iterator over all nodes in the graph.

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> for n in G:
```

```
print n,
1 2 3
```

## networkx.MultiDiGraph.edges

```
edges (nbunch=None, data=False, keys=False)
Return a list of edges.
```

Edges are returned as tuples with optional data and keys in the order (node, neighbor, key, data).

**Parameters nbunch**: iterable container, optional (default= all nodes)

A container of nodes. The container will be iterated through once.

data: bool, optional (default=False)

Return two tuples (u,v) (False) or three-tuples (u,v,data) (True).

keys: bool, optional (default=False)

Return two tuples (u,v) (False) or three-tuples (u,v,key) (True).

#### Returns edge\_list: list of edge tuples :

Edges that are adjacent to any node in nbunch, or a list of all edges if nbunch is not specified.

#### See Also:

edges\_iter return an iterator over the edges

#### **Notes**

Nodes in nbunch that are not in the graph will be (quietly) ignored.

```
>>> G = nx.MultiGraph() # or MultiDiGraph
>>> G.add_path([0,1,2,3])
>>> G.edges()
[(0, 1), (1, 2), (2, 3)]
>>> G.edges(data=True) # default edge data is {} (empty dictionary)
[(0, 1, {}), (1, 2, {}), (2, 3, {})]
>>> G.edges(keys=True) # default keys are integers
[(0, 1, 0), (1, 2, 0), (2, 3, 0)]
>>> G.edges(data=True,keys=True) # default keys are integers
[(0, 1, 0, {}), (1, 2, 0, {}), (2, 3, 0, {})]
>>> G.edges([0,3])
[(0, 1), (3, 2)]
>>> G.edges(0)
[(0, 1)]
```

## networkx.MultiDiGraph.edges iter

```
edges_iter (nbunch=None, data=False, keys=False)
```

Return an iterator over the edges.

Edges are returned as tuples with optional data and keys in the order (node, neighbor, key, data).

**Parameters nbunch**: iterable container, optional (default= all nodes)

A container of nodes. The container will be iterated through once.

data: bool, optional (default=False)

If True, return edge attribute dict with each edge.

keys: bool, optional (default=False)

If True, return edge keys with each edge.

**Returns edge\_iter**: iterator

An iterator of (u,v), (u,v,d) or (u,v,key,d) tuples of edges.

See Also:

edges return a list of edges

#### **Notes**

Nodes in nbunch that are not in the graph will be (quietly) ignored.

## **Examples**

```
>>> G = nx.MultiDiGraph()
>>> G.add_path([0,1,2,3])
>>> [e for e in G.edges_iter()]
[(0, 1), (1, 2), (2, 3)]
>>> list(G.edges_iter(data=True)) # default data is {} (empty dict)
[(0, 1, {}), (1, 2, {}), (2, 3, {})]
>>> list(G.edges_iter([0,2]))
[(0, 1), (2, 3)]
>>> list(G.edges_iter(0))
[(0, 1)]
```

## networkx.MultiDiGraph.out\_edges

```
out_edges (nbunch=None, data=False)
Return a list of edges.
```

Edges are returned as tuples with optional data in the order (node, neighbor, data).

**Parameters nbunch**: iterable container, optional (default= all nodes)

A container of nodes. The container will be iterated through once.

data: bool, optional (default=False)

Return two tuples (u,v) (False) or three-tuples (u,v,data) (True).

#### Returns edge\_list: list of edge tuples :

Edges that are adjacent to any node in nbunch, or a list of all edges if nbunch is not specified.

#### See Also:

edges iter return an iterator over the edges

#### **Notes**

Nodes in nbunch that are not in the graph will be (quietly) ignored.

## **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> G.edges()
[(0, 1), (1, 2), (2, 3)]
>>> G.edges(data=True) # default edge data is {} (empty dictionary)
[(0, 1, {}), (1, 2, {}), (2, 3, {})]
>>> G.edges([0,3])
[(0, 1), (3, 2)]
>>> G.edges(0)
[(0, 1)]
```

## networkx.MultiDiGraph.out edges iter

```
out_edges_iter (nbunch=None, data=False, keys=False)
```

Return an iterator over the edges.

Edges are returned as tuples with optional data and keys in the order (node, neighbor, key, data).

Parameters nbunch: iterable container, optional (default= all nodes)

A container of nodes. The container will be iterated through once.

data: bool, optional (default=False)

If True, return edge attribute dict with each edge.

keys: bool, optional (default=False)

If True, return edge keys with each edge.

Returns edge\_iter: iterator

An iterator of (u,v), (u,v,d) or (u,v,key,d) tuples of edges.

#### See Also:

edges return a list of edges

#### **Notes**

Nodes in nbunch that are not in the graph will be (quietly) ignored.

## **Examples**

```
>>> G = nx.MultiDiGraph()
>>> G.add_path([0,1,2,3])
>>> [e for e in G.edges_iter()]
[(0, 1), (1, 2), (2, 3)]
>>> list(G.edges_iter(data=True)) # default data is {} (empty dict)
[(0, 1, {}), (1, 2, {}), (2, 3, {})]
>>> list(G.edges_iter([0,2]))
[(0, 1), (2, 3)]
>>> list(G.edges_iter(0))
[(0, 1)]
```

## networkx.MultiDiGraph.in\_edges

```
in_edges (nbunch=None, data=False)
Return a list of the incoming edges.
```

See Also:

edges return a list of edges

## networkx.MultiDiGraph.in edges iter

```
in_edges_iter (nbunch=None, data=False, keys=False)
Return an iterator over the incoming edges.
```

Parameters nbunch: iterable container, optional (default= all nodes)

A container of nodes. The container will be iterated through once.

data: bool, optional (default=False)

If True, return edge attribute dict with each edge.

**keys**: bool, optional (default=False)

If True, return edge keys with each edge.

Returns in\_edge\_iter: iterator

An iterator of (u,v), (u,v,d) or (u,v,key,d) tuples of edges.

See Also:

edges\_iter return an iterator of edges

## networkx.MultiDiGraph.get\_edge\_data

```
get_edge_data (u, v, key=None, default=None)

Return the attribute dictionary associated with edge (u,v).
```

Parameters u,v: nodes

#### default: any Python object (default=None) :

Value to return if the edge (u,v) is not found.

key: hashable identifier, optional (default=None)

Return data only for the edge with specified key.

Returns edge\_dict : dictionary

The edge attribute dictionary.

### **Notes**

It is faster to use G[u][v][key].

```
>>> G = nx.MultiGraph() # or MultiDiGraph
>>> G.add_edge(0,1,key='a',weight=7)
>>> G[0][1]['a'] # key='a'
{'weight': 7}
```

Warning: Assigning G[u][v][key] corrupts the graph data structure. But it is safe to assign attributes to that dictionary,

```
>>> G[0][1]['a']['weight'] = 10
>>> G[0][1]['a']['weight']
10
>>> G[1][0]['a']['weight']
```

## **Examples**

```
>>> G = nx.MultiGraph() # or MultiDiGraph
>>> G.add_path([0,1,2,3])
>>> G.get_edge_data(0,1)
{0: {}}
>>> e = (0,1)
>>> G.get_edge_data(*e) # tuple form
{0: {}}
>>> G.get_edge_data('a','b',default=0) # edge not in graph, return 0
```

## networkx.MultiDiGraph.neighbors

```
neighbors(n)
```

Return a list of successor nodes of n.

neighbors() and successors() are the same function.

## networkx.MultiDiGraph.neighbors\_iter

```
neighbors_iter (n)
    Return an iterator over successor nodes of n.
    neighbors_iter() and successors_iter() are the same.
```

## networkx.MultiDiGraph. getitem

```
__getitem__ (n)
Return a dict of neighbors of node n. Use the expression 'G[n]'.

Parameters n: node

A node in the graph.
```

Returns adj\_dict : dictionary

The adjacency dictionary for nodes connected to n.

#### **Notes**

G[n] is similar to G.neighbors(n) but the internal data dictionary is returned instead of a list. Assigning G[n] will corrupt the internal graph data structure. Use G[n] for reading data only.

## **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> print G[0]
{1: {}}
```

## networkx.MultiDiGraph.successors

```
successors (n)
Return a list of successor nodes of n.
neighbors() and successors() are the same function.
```

## networkx.MultiDiGraph.successors\_iter

```
successors_iter (n)
Return an iterator over successor nodes of n.
neighbors_iter() and successors_iter() are the same.
```

## networkx.MultiDiGraph.predecessors

#### predecessors(n)

Return a list of predecessor nodes of n.

## networkx.MultiDiGraph.predecessors\_iter

```
predecessors_iter(n)
```

Return an iterator over predecessor nodes of n.

## networkx.MultiDiGraph.adjacency\_list

```
adjacency_list()
```

Return an adjacency list representation of the graph.

The output adjacency list is in the order of G.nodes(). For directed graphs, only outgoing adjacencies are included.

Returns adj\_list: lists of lists

The adjacency structure of the graph as a list of lists.

#### See Also:

adjacency\_iter

## **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> G.adjacency_list() # in order given by G.nodes()
[[1], [0, 2], [1, 3], [2]]
```

## networkx.MultiDiGraph.adjacency\_iter

```
adjacency_iter()
```

Return an iterator of (node, adjacency dict) tuples for all nodes.

This is the fastest way to look at every edge. For directed graphs, only outgoing adjacencies are included.

Returns adj\_iter: iterator

An iterator of (node, adjacency dictionary) for all nodes in the graph.

#### See Also:

adjacency\_list

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> [(n,nbrdict) for n,nbrdict in G.adjacency_iter()]
[(0, {1: {}}), (1, {0: {}}, 2: {}}), (2, {1: {}}, 3: {}}), (3, {2: {}})]
```

## networkx.MultiDiGraph.nbunch iter

```
nbunch_iter (nbunch=None)
```

Return an iterator of nodes contained in nbunch that are also in the graph.

The nodes in nbunch are checked for membership in the graph and if not are silently ignored.

Parameters nbunch: iterable container, optional (default=all nodes)

A container of nodes. The container will be iterated through once.

Returns niter: iterator

An iterator over nodes in nbunch that are also in the graph. If nbunch is None, iterate over all nodes in the graph.

#### Raises NetworkXError:

If nbunch is not a node or or sequence of nodes. If a node in nbunch is not hashable.

#### See Also:

```
Graph.__iter__
```

### **Notes**

When nbunch is an iterator, the returned iterator yields values directly from nbunch, becoming exhausted when nbunch is exhausted.

To test whether nbunch is a single node, one can use "if nbunch in self:", even after processing with this routine.

If nbunch is not a node or a (possibly empty) sequence/iterator or None, a NetworkXError is raised. Also, if any object in nbunch is not hashable, a NetworkXError is raised.

#### Information about graph structure

```
Return True if the graph contains the node n.
MultiDiGraph.has_node(n)
                                                   Return True if n is a node, False otherwise. Use the
MultiDiGraph.__contains__(n)
                                                   expression
MultiDiGraph.has_edge(u, v[, key])
                                                   Return True if the graph has an edge between nodes u
                                                   and v.
MultiDiGraph.nodes_with_selfloops()
                                                   Return a list of nodes with self loops.
                                                   Return a list of selfloop edges.
MultiDiGraph.selfloop_edges([data, keys])
MultiDiGraph.order()
                                                   Return the number of nodes in the graph.
MultiDiGraph.number of nodes()
                                                   Return the number of nodes in the graph.
MultiDiGraph.__len__()
                                                   Return the number of nodes.
MultiDiGraph.size([weighted])
                                                   Return the number of edges.
MultiDiGraph.number_of_edges([u, v])
                                                   Return the number of edges between two nodes.
MultiDiGraph.number_of_selfloops()
                                                   Return the number of selfloop edges.
MultiDiGraph.degree([nbunch, with labels, ...])
                                                   Return the degree of a node or nodes.
MultiDiGraph.degree iter([nbunch,
                                                   Return an iterator for (node, degree).
weighted])
MultiDiGraph.in_degree([nbunch, ...])
                                                   Return the in-degree of a node or nodes.
MultiDiGraph.in_degree_iter([nbunch,
                                                   Return an iterator for (node, in-degree).
weighted])
MultiDiGraph.out_degree([nbunch, ...])
                                                   Return the out-degree of a node or nodes.
                                                   Return an iterator for (node, out-degree).
MultiDiGraph.out_degree_iter([nbunch,
weighted])
```

## networkx.MultiDiGraph.has\_node

```
has\_node(n)
```

Return True if the graph contains the node n.

Parameters n: node

## **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2])
>>> print G.has_node(0)
True

It is more readable and simpler to use
```

>>> 0 **in** G True

## networkx.MultiDiGraph.\_\_contains\_\_

```
\underline{\hspace{0.1cm}}contains\underline{\hspace{0.1cm}}(n)
```

Return True if n is a node, False otherwise. Use the expression 'n in G'.

## **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> print 1 in G
True
```

## networkx.MultiDiGraph.has\_edge

```
has_edge (u, v, key=None)
```

Return True if the graph has an edge between nodes u and v.

Parameters u,v: nodes

Nodes can be, for example, strings or numbers.

key: hashable identifier, optional (default=None)

If specified return True only if the edge with key is found.

Returns edge\_ind: bool

True if edge is in the graph, False otherwise.

## **Examples**

Can be called either using two nodes u,v, an edge tuple (u,v), or an edge tuple (u,v,key).

```
>>> G = nx.MultiGraph()  # or MultiDiGraph
>>> G.add_path([0,1,2,3])
>>> G.has_edge(0,1)  # using two nodes
True
>>> e = (0,1)
>>> G.has_edge(*e)  # e is a 2-tuple (u,v)
True
>>> G.add_edge(0,1,key='a')
>>> G.has_edge(0,1,key='a')  # specify key
True
>>> e=(0,1,'a')
>>> G.has_edge(*e)  # e is a 3-tuple (u,v,'a')
True
```

The following syntax are equivalent:

```
>>> G.has_edge(0,1)
True
>>> 1 in G[0] # though this gives KeyError if 0 not in G
True
```

## networkx.MultiDiGraph.nodes with selfloops

```
nodes_with_selfloops()
```

Return a list of nodes with self loops.

A node with a self loop has an edge with both ends adjacent to that node.

Returns nodelist: list

A list of nodes with self loops.

#### See Also:

```
selfloop_edges, number_of_selfloops
```

## **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_edge(1,1)
>>> G.add_edge(1,2)
>>> G.nodes_with_selfloops()
[1]
```

## networkx.MultiDiGraph.selfloop\_edges

```
selfloop_edges (data=False, keys=False)
```

Return a list of selfloop edges.

A selfloop edge has the same node at both ends.

**Parameters data**: bool, optional (default=False)

Return selfloop edges as two tuples (u,v) (data=False) or three-tuples (u,v,data) (data=True)

**keys**: bool, optional (default=False)

If True, return edge keys with each edge.

**Returns edgelist**: list of edge tuples

A list of all selfloop edges.

#### See Also:

```
selfloop_nodes, number_of_selfloops
```

```
>>> G = nx.MultiGraph() # or MultiDiGraph
>>> G.add_edge(1,1)
>>> G.add_edge(1,2)
>>> G.selfloop_edges()
[(1, 1)]
>>> G.selfloop_edges(data=True)
[(1, 1, {})]
>>> G.selfloop_edges(keys=True)
[(1, 1, 0)]
>>> G.selfloop_edges(keys=True, data=True)
[(1, 1, 0, {})]
```

## networkx.MultiDiGraph.order

```
order()
```

Return the number of nodes in the graph.

Returns nnodes: int

The number of nodes in the graph.

See Also:

```
number_of_nodes, __len__
```

## networkx.MultiDiGraph.number\_of\_nodes

```
number_of_nodes()
```

Return the number of nodes in the graph.

Returns nnodes: int

The number of nodes in the graph.

See Also:

```
order, __len__
```

## **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2])
>>> print len(G)
3
```

## networkx.MultiDiGraph.\_\_len\_\_

```
__len__()
```

Return the number of nodes. Use the expression 'len(G)'.

Returns nnodes: int

The number of nodes in the graph.

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> print len(G)
4
```

## networkx.MultiDiGraph.size

```
size (weighted=False)
```

Return the number of edges.

**Parameters weighted**: boolean, optional (default=False)

If True return the sum of the edge weights.

Returns nedges: int

The number of edges in the graph.

#### See Also:

```
number_of_edges
```

## **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> G.size()
3
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_edge('a','b',weight=2)
>>> G.add_edge('b','c',weight=4)
>>> G.size()
2
>>> G.size(weighted=True)
6
```

## networkx.MultiDiGraph.number of edges

```
number_of_edges (u=None, v=None)
```

Return the number of edges between two nodes.

Parameters u,v: nodes, optional (default=all edges)

If u and v are specified, return the number of edges between u and v. Otherwise return the total number of all edges.

Returns nedges: int

The number of edges in the graph. If nodes u and v are specified return the number of edges between those nodes.

#### See Also:

size

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> G.number_of_edges()
3
>>> G.number_of_edges(0,1)
1
>>> e = (0,1)
>>> G.number_of_edges(*e)
```

## networkx.MultiDiGraph.number\_of\_selfloops

```
number_of_selfloops()
```

Return the number of selfloop edges.

A selfloop edge has the same node at both ends.

Returns nloops: int

The number of selfloops.

#### See Also:

```
selfloop_nodes, selfloop_edges
```

## **Examples**

```
>>> G=nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_edge(1,1)
>>> G.add_edge(1,2)
>>> G.number_of_selfloops()
```

## networkx.MultiDiGraph.degree

degree (nbunch=None, with\_labels=False, weighted=False)

Return the degree of a node or nodes.

The node degree is the number of edges adjacent to that node.

**Parameters nbunch**: iterable container, optional (default=all nodes)

A container of nodes. The container will be iterated through once.

with\_labels : bool, optional (default=False)

If True return a dictionary of degrees keyed by node.

weighted: bool, optional (default=False)

If True return the sum of edge weights adjacent to the node.

Returns nd: list, or dictionary

A list of node degrees or a dictionary with nodes as keys and degree as values if with\_labels=True).

## **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> G.degree(0)
1
>>> G.degree([0,1])
[1, 2]
>>> G.degree([0,1], with_labels=True)
{0: 1, 1: 2}
```

## networkx.MultiDiGraph.degree\_iter

```
degree_iter (nbunch=None, weighted=False)
Return an iterator for (node, degree).
```

The node degree is the number of edges adjacent to the node.

**Parameters nbunch**: iterable container, optional (default=all nodes)

A container of nodes. The container will be iterated through once.

weighted : bool, optional (default=False)

If True return the sum of edge weights adjacent to the node.

Returns nd iter: an iterator

The iterator returns two-tuples of (node, degree).

### See Also:

degree

## **Examples**

```
>>> G = nx.MultiDiGraph()
>>> G.add_path([0,1,2,3])
>>> list(G.degree_iter(0)) # node 0 with degree 1
[(0, 1)]
>>> list(G.degree_iter([0,1]))
[(0, 1), (1, 2)]
```

## networkx.MultiDiGraph.in\_degree

```
in_degree (nbunch=None, with_labels=False, weighted=False)
Return the in-degree of a node or nodes.
```

The node in-degree is the number of edges pointing in to the node.

Parameters nbunch: iterable container, optional (default=all nodes)

A container of nodes. The container will be iterated through once.

with\_labels : bool, optional (default=False)

If True return a dictionary of degrees keyed by node.

```
weighted : bool, optional (default=False)
```

If True return the sum of edge weights adjacent to the node.

**Returns nd**: list, or dictionary

A list of node in-degrees or a dictionary with nodes as keys and in-degree as values if with labels=True).

#### See Also:

```
degree, out_degree, in_degree_iter
```

## **Examples**

```
>>> G = nx.DiGraph() # or MultiDiGraph
>>> G.add_path([0,1,2,3])
>>> G.in_degree(0)
0
>>> G.in_degree([0,1])
[0, 1]
>>> G.in_degree([0,1],with_labels=True)
{0: 0, 1: 1}
```

## networkx.MultiDiGraph.in\_degree\_iter

```
in_degree_iter (nbunch=None, weighted=False)
```

Return an iterator for (node, in-degree).

The node in-degree is the number of edges pointing in to the node.

**Parameters nbunch**: iterable container, optional (default=all nodes)

A container of nodes. The container will be iterated through once.

weighted : bool, optional (default=False)

If True return the sum of edge weights adjacent to the node.

Returns nd\_iter: an iterator

The iterator returns two-tuples of (node, in-degree).

#### See Also:

```
degree, in_degree, out_degree, out_degree_iter
```

```
>>> G = nx.MultiDiGraph()
>>> G.add_path([0,1,2,3])
>>> list(G.in_degree_iter(0)) # node 0 with degree 0
[(0, 0)]
>>> list(G.in_degree_iter([0,1]))
[(0, 0), (1, 1)]
```

## networkx.MultiDiGraph.out\_degree

```
out_degree (nbunch=None, with_labels=False, weighted=False)
Return the out-degree of a node or nodes.
```

The node out-degree is the number of edges pointing out of the node.

Parameters nbunch: iterable container, optional (default=all nodes)

A container of nodes. The container will be iterated through once.

```
with_labels : bool, optional (default=False)
```

If True return a dictionary of degrees keyed by node.

```
weighted : bool, optional (default=False)
```

If True return the sum of edge weights adjacent to the node.

**Returns nd**: list, or dictionary

A list of node out-degrees or a dictionary with nodes as keys and out-degree as values if with\_labels=True).

## **Examples**

```
>>> G = nx.DiGraph() # or MultiDiGraph
>>> G.add_path([0,1,2,3])
>>> G.out_degree(0)
1
>>> G.out_degree([0,1])
[1, 1]
>>> G.out_degree([0,1],with_labels=True)
{0: 1, 1: 1}
```

## networkx.MultiDiGraph.out degree iter

```
out_degree_iter (nbunch=None, weighted=False)
Return an iterator for (node, out-degree).
```

The node out-degree is the number of edges pointing out of the node.

**Parameters nbunch**: iterable container, optional (default=all nodes)

A container of nodes. The container will be iterated through once.

weighted: bool, optional (default=False)

If True return the sum of edge weights adjacent to the node.

Returns nd\_iter: an iterator

The iterator returns two-tuples of (node, out-degree).

#### See Also:

```
degree, in_degree, out_degree, in_degree_iter
```

## **Examples**

```
>>> G = nx.MultiDiGraph()
>>> G.add_path([0,1,2,3])
>>> list(G.out_degree_iter(0)) # node 0 with degree 1
[(0, 1)]
>>> list(G.out_degree_iter([0,1]))
[(0, 1), (1, 1)]
```

#### Making copies and subgraphs

MultiDiGraph.copy()	Return a copy of the graph.
MultiDiGraph.to_undirected()	Return an undirected representation of the digraph.
<pre>MultiDiGraph.subgraph(nbunch[, copy])</pre>	Return the subgraph induced on nodes in nbunch.
MultiDiGraph.reverse([copy])	Return the reverse of the graph.

## networkx.MultiDiGraph.copy

```
copy()
```

Return a copy of the graph.

Returns G: Graph

A copy of the graph.

See Also:

to\_directed return a directed copy of the graph.

#### **Notes**

This makes a complete copy of the graph including all of the node or edge attributes.

## **Examples**

```
>>> G = nx.Graph() # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> H = G.copy()
```

## networkx.MultiDiGraph.to\_undirected

#### to\_undirected()

Return an undirected representation of the digraph.

#### Returns G: MultiGraph

An undirected graph with the same name and nodes and with edge (u,v,data) if either (u,v,data) or (v,u,data) is in the digraph. If both edges exist in digraph and their edge data is different, only one edge is created with an arbitrary choice of which edge data to use. You must check and correct for this manually if desired.

#### **Notes**

This is similar to MultiGraph(self) which returns a shallow copy. self.to\_undirected() returns a deepcopy of edge, node and graph attributes.

## networkx.MultiDiGraph.subgraph

```
subgraph (nbunch, copy=True)
```

Return the subgraph induced on nodes in nbunch.

The induced subgraph of the graph has the nodes in nbunch as its node set and the edges adjacent to those nodes as its edge set.

Parameters nbunch: list, iterable

A container of nodes. The container will be iterated through once.

```
copy : bool, optional (default=True)
```

If True return a new graph holding the subgraph including copies of all edge and node properties. If False the subgraph is created using the original graph by deleting all nodes not in nbunch (this changes the original graph).

#### Returns G: Graph

A subgraph of the graph. If copy=True a new graph is returned with copies of graph, node, and edge data. If copy=False the subgraph is created in place by modifying the original graph.

#### **Notes**

If copy=True, nodes and edges are copied using copy.deepcopy.

## **Examples**

```
>>> G = nx.Graph()  # or DiGraph, MultiGraph, MultiDiGraph, etc
>>> G.add_path([0,1,2,3])
>>> H = G.subgraph([0,1,2])
>>> print H.edges()
[(0, 1), (1, 2)]
```

## networkx.MultiDiGraph.reverse

```
reverse (copy=True)
```

Return the reverse of the graph.

The reverse is a graph with the same nodes and edges but with the directions of the edges reversed.

**Parameters copy**: bool optional (default=True)

If True, return a new DiGraph holding the reversed edges. If False, reverse the reverse graph is created using the original graph (this changes the original graph).

# **OPERATORS**

Operations on graphs; including union, intersection, difference, complement, subgraph.

The following operator functions provide standard relabeling and combining operations for networks.

## 4.1 Graph Manipulation

create_empty_copy(G[, with_nodes])	Return a copy of the graph G with all of the edges removed.
<pre>subgraph(G, nbunch[, copy])</pre>	Return the subgraph induced on nodes in nbunch.
<pre>cartesian_product(G, H[, create_using])</pre>	Return the Cartesian product of G and H.
<pre>compose(G, H[, create_using, name])</pre>	Return a new graph of G composed with H.
<pre>complement(G[, create_using, name])</pre>	Return graph complement of G.
union(G, H[, create_using, rename, name])	Return the union of graphs G and H.
disjoint_union(G, H)	Return the disjoint union of graphs G and H, forcing distinct
	integer
<pre>intersection(G, H[, create_using])</pre>	Return a new graph that contains only the edges that exist in
<pre>difference(G, H[, create_using])</pre>	Return a new graph that contains the edges that exist in
$symmetric\_difference(G, H[,$	Return new graph with edges that exist in
create_using])	
$ exttt{line\_graph}(G)$	Return the line graph of the graph or digraph G.
$ego\_graph(G, n[, center])$	Returns induced subgraph of neighbors centered at node n.
${\sf stochastic\_graph}(G[,copy])$	Return a right-stochastic representation of G.

## 4.1.1 networkx.create\_empty\_copy

```
create_empty_copy (G, with_nodes=True)
```

Return a copy of the graph G with all of the edges removed.

 $Parameters \ G: graph \\$ 

A NetworkX graph

with\_nodes : bool (default=True)

Include nodes.

## 4.1.2 networkx.subgraph

```
subgraph (G, nbunch, copy=True)
```

Return the subgraph induced on nodes in nbunch.

Parameters G: graph

A NetworkX graph

nbunch: list, iterable

A container of nodes that will be iterated through once (thus it should be an iterator or be iterable). Each element of the container should be a valid node type: any hashable type except None. If nbunch is None, return all edges data in the graph. Nodes in nbunch that are not in the graph will be (quietly) ignored.

copy : bool (default True)

If True return a new graph holding the subgraph. Otherwise, the subgraph is created in the original graph by deleting nodes not in nbunch. Warning: this can destroy the graph.

#### **Notes**

subgraph(G) calls G.subgraph()

## 4.1.3 networkx.cartesian\_product

cartesian\_product(G, H, create\_using=None)

Return the Cartesian product of G and H.

**Parameters G,H**: graph

A NetworkX graph

#### **Notes**

Only tested with Graph class.

## 4.1.4 networkx.compose

compose (G, H, create\_using=None, name=None)

Return a new graph of G composed with H.

Composition is the simple union of the node sets and edge sets. The node sets of G and H need not be disjoint.

Parameters G,H: graph

A NetworkX graph

create\_using : NetworkX graph

Use specified graph for result. Otherwise a new graph is created.

name: string

Specify name for new graph

## **Notes**

A new graph is returned, of the same class as G. It is recommended that G and H be either both directed or both undirected.

## 4.1.5 networkx.complement

```
complement (G, create_using=None, name=None)
    Return graph complement of G.

Parameters G: graph
    A NetworkX graph
    create_using: NetworkX graph
    Use specified graph for result. Otherwise a new graph is created.
    name: string
        Specify name for new graph
```

#### **Notes**

Note that complement() does not create self-loops and also does not produce parallel edges for MultiGraphs.

#### 4.1.6 networkx.union

```
union (G, H, create_using=None, rename=False, name=None)
Return the union of graphs G and H.

Graphs G and H must be disjoint, otherwise an exception is raised.

Parameters G,H: graph

A NetworkX graph

create_using: NetworkX graph

Use specified graph for result. Otherwise a new graph is created.

rename: bool (default=False)

Node names of G and H can be changed be specifying the tuple rename=('G-','H-') (for example). Node u in G is then renamed "G-u" and v in H is renamed "H-v".

name: string

Specify name for union graph
```

#### **Notes**

To force a disjoint union with node relabeling, use disjoint\_union(G,H) or convert\_node\_labels\_to integers().

### 4.1.7 networkx.disjoint union

```
\label{eq:disjoint_union} \begin{array}{l} \textbf{disjoint\_union} \ (G, \, H) \\ \text{Return the disjoint union of graphs G and H, forcing distinct integer node labels.} \\ \textbf{Parameters} \ \ \textbf{G,H} : \text{graph} \\ \text{A NetworkX graph} \end{array}
```

#### **Notes**

A new graph is created, of the same class as G. It is recommended that G and H be either both directed or both undirected.

#### 4.1.8 networkx.intersection

```
intersection(G, H, create_using=None)
```

Return a new graph that contains only the edges that exist in both G and H.

The node sets of H and G must be the same.

Parameters G,H: graph

A NetworkX graph

create\_using: NetworkX graph

Use specified graph for result. Otherwise a new graph is created.

#### **Notes**

If you want an new graph of the intersection of node sets of G and H with the edges from G use

```
>>> G=nx.path_graph(3)
>>> H=nx.path_graph(5)
>>> R=G.copy()
>>> R.remove_nodes_from(n for n in G if n not in H)
```

#### 4.1.9 networkx.difference

```
difference(G, H, create_using=None)
```

Return a new graph that contains the edges that exist in in G but not in H.

The node sets of H and G must be the same.

Parameters G,H: graph
A NetworkX graph
create\_using: NetworkX graph

Use specified graph for result. Otherwise a new graph is created.

#### **Notes**

If you want an new graph consisting of the difference of the node sets of G and H with the edges from G use

```
>>> G=nx.path_graph(3)
>>> H=nx.path_graph(5)
>>> R=G.copy()
>>> R.remove_nodes_from(n for n in G if n in H)
```

### 4.1.10 networkx.symmetric difference

```
symmetric_difference(G, H, create_using=None)
```

Return new graph with edges that exist in in either G or H but not both.

The node sets of H and G must be the same.

Parameters G,H: graph

A NetworkX graph

create\_using : NetworkX graph

Use specified graph for result. Otherwise a new graph is created.

## 4.1.11 networkx.line\_graph

#### $line\_graph(G)$

Return the line graph of the graph or digraph G.

The line graph of a graph G has a node for each edge in G and an edge between those nodes if the two edges in G share a common node.

For DiGraphs an edge an edge represents a directed path of length 2.

The original node labels are kept as two-tuple node labels in the line graph.

Parameters G: graph

A NetworkX Graph or DiGraph

#### See Also:

```
convert_node_labels_to_integers
```

#### **Notes**

Not implemented for MultiGraph or MultiDiGraph classes.

## **Examples**

```
>>> G=nx.star_graph(3)
>>> L=nx.line_graph(G)
>>> print sorted(L.edges()) # makes a clique, K3
[((0, 1), (0, 2)), ((0, 1), (0, 3)), ((0, 3), (0, 2))]
```

## 4.1.12 networkx.ego\_graph

```
ego_graph (G, n, center=True)
```

Returns induced subgraph of neighbors centered at node n.

Parameters G: graph

A NetworkX Graph or DiGraph

n: node

A single node

center: bool, optional

If False, do not include center node in graph

## 4.1.13 networkx.stochastic\_graph

```
stochastic_graph(G, copy=True)
```

Return a right-stochastic representation of G.

A right-stochastic graph is a weighted graph in which all of the node (out) neighbors edge weights sum to 1.

Parameters G: graph

A NetworkX graph, must have valid edge weights

copy: boolean, optional

If True make a copy of the graph, otherwise modify original graph

## 4.2 Node Relabeling

convert\_node\_labels\_to\_integers(G[, ...]) Return a copy of G node labels replaced with integers.
relabel\_nodes(G, mapping) Return a copy of G with node labels transformed by mapping.

## 4.2.1 networkx.convert node labels to integers

**convert\_node\_labels\_to\_integers** (*G, first\_label=0, ordering='default', discard\_old\_labels=True*)

Return a copy of G node labels replaced with integers.

Parameters G: graph

A NetworkX graph

first\_label : int, optional (default=0)

An integer specifying the offset in numbering nodes. The n new integer labels are numbered first\_label, ..., n+first\_label.

ordering: string

"default": inherit node ordering from G.nodes() "sorted": inherit node ordering from sorted(G.nodes()) "increasing degree": nodes are sorted by increasing degree "decreasing degree": nodes are sorted by decreasing degree

discard\_old\_labels : bool, optional (default=True)

if True (default) discard old labels if False, create a dict self.node\_labels that maps new labels to old labels

## 4.2.2 networkx.relabel nodes

relabel\_nodes(G, mapping)

Return a copy of G with node labels transformed by mapping.

Parameters G: graph

### A NetworkX graph

#### mapping: dictionary or function

Either a dictionary with the old labels as keys and new labels as values or a function transforming an old label with a new label. In either case, the new labels must be hashable Python objects.

#### See Also:

```
convert_node_labels_to_integers
```

## **Examples**

```
mapping as dictionary
```

```
>>> G=nx.path_graph(3) # nodes 0-1-2
>>> mapping={0:'a',1:'b',2:'c'}
>>> H=nx.relabel_nodes(G, mapping)
>>> print H.nodes()
['a', 'c', 'b']
>>> G=nx.path_graph(26) # nodes 0..25
>>> mapping=dict(zip(G.nodes(), "abcdefghijklmnopqrstuvwxyz"))
>>> H=nx.relabel_nodes(G, mapping) # nodes a..z
>>> mapping=dict(zip(G.nodes(),xrange(1,27)))
>>> G1=nx.relabel_nodes(G, mapping) # nodes 1..26
mapping as function
>>> G=nx.path_graph(3)
>>> def mapping(x):
      return x**2
>>> H=nx.relabel_nodes(G, mapping)
>>> print H.nodes()
[0, 1, 4]
```

## 4.3 Freezing

 $\begin{array}{ll} \texttt{freeze}(G) & \texttt{Modify graph to prevent addition of nodes or edges.} \\ \texttt{is\_frozen}(G) & \texttt{Return True if graph is frozen.} \end{array}$ 

#### 4.3.1 networkx.freeze

#### freeze(G)

Modify graph to prevent addition of nodes or edges.

Parameters G: graph

A NetworkX graph

See Also:

is\_frozen

4.3. Freezing 135

### **Notes**

This does not prevent modification of edge data.

To "unfreeze" a graph you must make a copy.

## **Examples**

```
>>> G=nx.path_graph(4)
>>> G=nx.freeze(G)
>>> G.add_edge(4,5)
...
NetworkXError: Frozen graph can't be modified
```

## 4.3.2 networkx.is\_frozen

```
is\_frozen(G)
```

Return True if graph is frozen."

Parameters G: graph

A NetworkX graph

See Also:

freeze

136

**CHAPTER** 

**FIVE** 

# **ALGORITHMS**

## 5.1 Boundary

Routines to find the boundary of a set of nodes.

Edge boundaries are edges that have only one end in the set of nodes.

Node boundaries are nodes outside the set of nodes that have an edge to a node in the set.

```
edge_boundary(G, nbunch1[, nbunch2]) Return the edge boundary.

node_boundary(G, nbunch1[, nbunch2]) Return the node boundary.
```

## 5.1.1 networkx.edge\_boundary

edge\_boundary (G, nbunch1, nbunch2=None)

Return the edge boundary.

Edge boundaries are edges that have only one end in the given set of nodes.

Parameters G: graph

A networkx graph

nbunch1: list, container

Interior node set

nbunch2: list, container

Exterior node set. If None then it is set to all of the nodes in G not in nbunch1.

Returns elist: list

List of edges

### **Notes**

Nodes in nbunch1 and nbunch2 that are not in G are ignored.

nbunch1 and nbunch2 are usually meant to be disjoint, but in the interest of speed and generality, that is not required here.

## 5.1.2 networkx.node boundary

```
node_boundary (G, nbunch1, nbunch2=None)
```

Return the node boundary.

The node boundary is all nodes in the edge boundary of a given set of nodes that are in the set.

Parameters G: graph

A networkx graph

nbunch1: list, container

Interior node set

nbunch2: list, container

Exterior node set. If None then it is set to all of the nodes in G not in nbunch1.

Returns nlist: list

List of nodes.

#### **Notes**

Nodes in nbunch1 and nbunch2 that are not in G are ignored.

nbunch1 and nbunch2 are usually meant to be disjoint, but in the interest of speed and generality, that is not required here.

## 5.2 Centrality

#### Centrality measures.

betweenness_centrality(G[, normalized,])	Compute betweenness centrality for nodes.
${\tt betweenness\_centrality\_source}(G[,])$	Compute betweenness centrality for a subgraph.
<pre>load_centrality(G[, v, cutoff, normalized,])</pre>	Compute load centrality for nodes.
$edge\_betweenness(G[, normalized,])$	Compute betweenness centrality for edges.
$ ext{degree\_centrality}(G[,v])$	Compute the degree centrality for nodes.
$closeness\_centrality(G[, v, weighted\_edges])$	Compute closeness centrality for nodes.
<pre>eigenvector_centrality(G[, max_iter, tol,])</pre>	Compute the eigenvector centrality for the graph G.

### 5.2.1 networkx.betweenness\_centrality

**betweenness\_centrality** (*G*, normalized=True, weighted\_edges=False)

Compute betweenness centrality for nodes.

Betweenness centrality of a node is the fraction of all shortest paths that pass through that node.

Parameters G: graph

A networkx graph

normalized: bool, optional

If True the betweenness values are normalized by b=b/(n-1)(n-2) where n is the number of nodes in G.

weighted\_edges : bool, optional

Consider the edge weights in determining the shortest paths. If False, all edge weights are considered equal.

Returns nodes: dictionary

Dictionary of nodes with betweeness centrality as the value.

#### See Also:

load\_centrality

#### **Notes**

The algorithm is from Ulrik Brandes, A Faster Algorithm for Betweenness Centrality. Journal of Mathematical Sociology 25(2):163-177, 2001. http://www.inf.uni-konstanz.de/algo/publications/b-fabc-01.pdf

## 5.2.2 networkx.betweenness centrality source

**betweenness\_centrality\_source** (*G, normalized=True, weighted\_edges=False, sources=None*) Compute betweenness centrality for a subgraph.

Enchanced version of the method in centrality module that allows specifying a list of sources (subgraph).

Parameters G: graph

A networkx graph

normalized: bool, optional

If True the betweenness values are normalized by b=b/(n-1)(n-2) where n is the number of nodes in G.

weighted\_edges: bool, optional

Consider the edge weights in determining the shortest paths. If False, all edge weights are considered equal.

sources: node list

A list of nodes to consider as sources for shortest paths.

Returns nodes: dictionary

Dictionary of nodes with betweeness centrality as the value.

#### **Notes**

See Sec. 4 in Ulrik Brandes, A Faster Algorithm for Betweenness Centrality. Journal of Mathematical Sociology 25(2):163-177, 2001. http://www.inf.uni-konstanz.de/algo/publications/b-fabc-01.pdf

This algorithm does not count the endpoints, i.e. a path from s to t does not contribute to the betweenness of s and t.

### 5.2.3 networkx.load centrality

 $load\_centrality$  (G, v=None, cutoff=None, normalized=True,  $weighted\_edges=False$ ) Compute load centrality for nodes.

The load centrality of a node is the fraction of all shortest paths that pass through that node.

5.2. Centrality 139

Parameters G: graph

A networkx graph

normalized: bool, optional

If True the betweenness values are normalized by b=b/(n-1)(n-2) where n is the number of nodes in G.

weighted edges: bool, optional

Consider the edge weights in determining the shortest paths. If False, all edge weights are considered equal.

cutoff: bool, optional

If specified, only consider paths of length <= cutoff.

Returns nodes: dictionary

Dictionary of nodes with centrality as the value.

#### See Also:

betweenness\_centrality

#### **Notes**

Load centrality is slightly different than betweenness. For this load algorithm see the reference Scientific collaboration networks: II. Shortest paths, weighted networks, and centrality, M. E. J. Newman, Phys. Rev. E 64, 016132 (2001).

## 5.2.4 networkx.edge betweenness

 $\verb|edge_betweenness| (G, normalized=True, weighted\_edges=False, sources=None)|$ 

Compute betweenness centrality for edges.

Parameters G: graph

A networkx graph

normalized: bool, optional

If True the betweenness values are normalized by b=b/(n-1)(n-2) where n is the number of nodes in G.

weighted\_edges: bool, optional

Consider the edge weights in determining the shortest paths. If False, all edge weights are considered equal.

sources: node list

A list of nodes to consider as sources for shortest paths.

Returns nodes: dictionary

Dictionary of edges with betweeness centrality as the value.

## 5.2.5 networkx.degree centrality

```
degree_centrality(G, v=None)
```

Compute the degree centrality for nodes.

The degree centrality for a node v is the fraction of nodes it is connected to.

Parameters G: graph

A networkx graph

v: node, optional

Return only the value for node v.

**Returns nodes**: dictionary

Dictionary of nodes with degree centrality as the value.

#### See Also:

betweenness\_centrality,load\_centrality,eigenvector\_centrality

#### **Notes**

The degree centrality is normalized to the maximum possible degree in the graph G. That is, G.degree(v)/(G.order()-1).

### 5.2.6 networkx.closeness\_centrality

```
closeness centrality (G, v=None, weighted edges=False)
```

Compute closeness centrality for nodes.

Closeness centrality at a node is 1/average distance to all other nodes.

Parameters G: graph

A networkx graph

v: node, optional

Return only the value for node v.

weighted\_edges : bool, optional

Consider the edge weights in determining the shortest paths. If False, all edge weights are considered equal.

Returns nodes: dictionary

Dictionary of nodes with closeness centrality as the value.

### See Also:

```
betweenness_centrality, load_centrality, eigenvector_centrality, degree_centrality
```

5.2. Centrality 141

### **Notes**

The closeness centrality is normalized to to n-1 / size(G)-1 where n is the number of nodes in the connected part of graph containing the node. If the graph is not completely connected, this algorithm computes the closeness centrality for each connected part separately.

### 5.2.7 networkx.eigenvector\_centrality

Compute the eigenvector centrality for the graph G.

Uses the power method to find the eigenvector for the largest eigenvalue of the adjacency matrix of G.

**Parameters G**: graph

A networkx graph

max\_iter: interger, optional

Maximum number of iterations in power method.

tol: float, optional

Error tolerance used to check convergence in power method iteration.

nstart: dictionary, optional

Starting value of PageRank iteration for each node.

Returns nodes: dictionary

Dictionary of nodes with eigenvector centrality as the value.

#### See Also:

pagerank

### **Notes**

The eigenvector calculation is done by the power iteration method and has no guarantee of convergence. The iteration will stop after max\_iter iterations or an error tolerance of number\_of\_nodes(G)\*tol has been reached.

For directed graphs this is "right" eigevector centrality. For "left" eigenvector centrality, first reverse the graph with G.reverse().

# 5.3 Clique

Find and manipulate cliques of graphs.

Note that finding the largest clique of a graph has been shown to be an NP-complete problem; the algorithms here could take a long time to run.

http://en.wikipedia.org/wiki/Clique\_problem

find_cliques(G)	Search for all maximal cliques in a graph.
make_max_clique_graph(G[,	Create the maximal clique graph of a graph.
create_using, name])	
$make\_clique\_bipartite(G[, fpos,])$	Create a bipartite clique graph from a graph G.
<pre>graph_clique_number(G[, cliques])</pre>	Return the clique number (size of the largest clique) for G.
$graph_number_of_cliques(G[, cliques])$	Returns the number of maximal cliques in G.
$node\_clique\_number(G[, nodes,$	Returns the size of the largest maximal clique containing each
with_labels,])	given node.
$number\_of\_cliques(G[, nodes, cliques,$	Returns the number of maximal cliques for each node.
])	
cliques_containing_node( $G[$ , nodes,	Returns a list of cliques containing the given node.
cliques,])	

### 5.3.1 networkx.find\_cliques

#### $find\_cliques(G)$

Search for all maximal cliques in a graph.

This algorithm searches for maximal cliques in a graph. maximal cliques are the largest complete subgraph containing a given point. The largest maximal clique is sometimes called the maximum clique.

This implementation is a generator of lists each of which contains the members of a maximal clique. To obtain a list of cliques, use list(find\_cliques(G)). The method essentially unrolls the recursion used in the references to avoid issues of recursion stack depth.

#### See Also:

find\_cliques\_recursive A recursive version of the same algorithm

#### Reference :

Based

http://doi.acm.org/10.1145/362342.362367

as, Tanaka

http://dx.doi.org/10.1016/j.tcs.2006.06.015

and

http://dx.doi.org/10.1016/j.tcs.2008.05.010

### 5.3.2 networkx.make max clique graph

```
make_max_clique_graph (G, create_using=None, name=None)
```

Create the maximal clique graph of a graph.

Finds the maximal cliques and treats these as nodes. The nodes are connected if they have common members in the original graph. Theory has done a lot with clique graphs, but I haven't seen much on maximal clique graphs.

#### **Notes**

This should be the same as make\_clique\_bipartite followed by project\_up, but it saves all the intermediate steps.

5.3. Clique 143

## 5.3.3 networkx.make\_clique\_bipartite

make\_clique\_bipartite(G, fpos=None, create\_using=None, name=None)

Create a bipartite clique graph from a graph G.

Nodes of G are retained as the "bottom nodes" of B and cliques of G become "top nodes" of B. Edges are present if a bottom node belongs to the clique represented by the top node.

Returns a Graph with additional attribute dict B.node\_type which is keyed by nodes to "Bottom" or "Top" appropriately.

if fpos is not None, a second additional attribute dict B.pos is created to hold the position tuple of each node for viewing the bipartite graph.

# 5.3.4 networkx.graph\_clique\_number

#### graph\_clique\_number(G, cliques=None)

Return the clique number (size of the largest clique) for G.

An optional list of cliques can be input if already computed.

## 5.3.5 networkx.graph\_number\_of\_cliques

#### graph\_number\_of\_cliques (G, cliques=None)

Returns the number of maximal cliques in G.

An optional list of cliques can be input if already computed.

### 5.3.6 networkx.node clique number

node\_clique\_number (G, nodes=None, with\_labels=False, cliques=None)

Returns the size of the largest maximal clique containing each given node.

Returns a single or list depending on input nodes. Returns a dict keyed by node if "with\_labels=True". Optional list of cliques can be input if already computed.

### 5.3.7 networkx.number\_of\_cliques

 $\verb|number_of_cliques| (G, nodes=None, cliques=None, with\_labels=False)|$ 

Returns the number of maximal cliques for each node.

Returns a single or list depending on input nodes. Returns a dict keyed by node if "with\_labels=True". Optional list of cliques can be input if already computed.

# 5.3.8 networkx.cliques\_containing\_node

cliques\_containing\_node (G, nodes=None, cliques=None, with\_labels=False)

Returns a list of cliques containing the given node.

Returns a single list or list of lists depending on input nodes. Returns a dict keyed by node if "with\_labels=True". Optional list of cliques can be input if already computed.

# 5.4 Clustering

triangles(G[, nbunch, with_labels])	Compute the number of triangles.
transitivity(G)	Compute transitivity.
<pre>clustering(G[, nbunch, with_labels, weights])</pre>	Compute the clustering coefficient for nodes.
average_clustering( $G$ )	Compute average clustering coefficient.

### 5.4.1 networkx.triangles

triangles (G, nbunch=None, with\_labels=False)

Compute the number of triangles.

Finds the number of triangles that include a node as one of the vertices.

**Parameters G**: graph

A networkx graph

nbunch: container of nodes, optional

Compute triangles for nodes in nbunch. The default is all nodes in G.

with labels: bool, optional:

If True return a dictionary keyed by node label.

Returns out: list or dictionary

Number of trianges

### **Notes**

When computing triangles for the entire graph each triangle is counted three times, once at each node.

Self loops are ignored.

# **Examples**

```
>>> G=nx.complete_graph(5)
>>> print nx.triangles(G,0)
6
>>> print nx.triangles(G,with_labels=True)
{0: 6, 1: 6, 2: 6, 3: 6, 4: 6}
>>> print nx.triangles(G,(0,1))
[6, 6]
```

## 5.4.2 networkx.transitivity

#### transitivity(G)

Compute transitivity.

Finds the fraction of all possible triangles which are in fact triangles. Possible triangles are identified by the number of "triads" (two edges with a shared vertex).

T = 3\*triangles/triads

5.4. Clustering 145

Parameters G: graph

A networkx graph

Returns out: float

Transitivity

# **Examples**

```
>>> G=nx.complete_graph(5)
>>> print nx.transitivity(G)
1 0
```

# 5.4.3 networkx.clustering

clustering(G, nbunch=None, with\_labels=False, weights=False)

Compute the clustering coefficient for nodes.

For each node find the fraction of possible triangles that exist,

$$c_v = \frac{2T(v)}{deg(v)(deg(v) - 1)}$$

where T(v) is the number of triangles through node v.

Parameters G: graph

A networkx graph

nbunch: container of nodes, optional

Limit to specified nodes. Default is entire graph.

with labels: bool, optional:

If True return a dictionary keyed by node label.

weights: bool, optional

If True return fraction of connected triples as dictionary

**Returns out**: float, list, dictionary or tuple of dictionaries

Clustering coefficient at specified nodes

#### **Notes**

The weights are the fraction of connected triples in the graph which include the keyed node. This is useful for computing transitivity.

Self loops are ignored.

# **Examples**

```
>>> G=nx.complete_graph(5)
>>> print nx.clustering(G,0)
1.0
>>> print nx.clustering(G,with_labels=True)
{0: 1.0, 1: 1.0, 2: 1.0, 3: 1.0, 4: 1.0}
```

# 5.4.4 networkx.average clustering

#### $average\_clustering(G)$

Compute average clustering coefficient.

A clustering coefficient for the whole graph is the average,

$$C = \frac{1}{n} \sum_{v \in G} c_v,$$

where n is the number of nodes in G.

Parameters G: graph

A networkx graph

Returns out: float

Average clustering

### **Notes**

This is a space saving routine; it might be faster to use clustering to get a list and then take the average. Self loops are ignored.

# **Examples**

```
>>> G=nx.complete_graph(5)
>>> print nx.average_clustering(G)
1.0
```

## 5.5 Cores

Find and manipulate the k-cores of a graph

find\_cores(G[, with\_labels]) Return the core number for each vertex.

## 5.5.1 networkx.find\_cores

find cores(G, with labels=True)

Return the core number for each vertex.

See: arXiv:cs.DS/0310049 by Batagelj and Zaversnik

If with\_labels is True a dict is returned keyed by node to the core number. If with\_labels is False a list of the core numbers is returned.

5.5. Cores 147

# 5.6 Matching

The algorithm is taken from "Efficient Algorithms for Finding Maximum Matching in Graphs" by Zvi Galil, ACM Computing Surveys, 1986. It is based on the "blossom" method for finding augmenting paths and the "primal-dual" method for finding a matching of maximum weight, both methods invented by Jack Edmonds.

$ exttt{max_weight_matching}(G[,$	Compute a maximum-weighted matching in the undirected,
maxcardinality])	weighted graph G.

## 5.6.1 networkx.max weight matching

max\_weight\_matching(G, maxcardinality=False)

Compute a maximum-weighted matching in the undirected, weighted graph G.

If maxcardinality is True, compute the maximum-cardinality matching with maximum weight among all maximum-cardinality matchings.

The matching is returned as a dictionary, mate, such that mate[v] == w if node v is matched to node w. Unmatched nodes do not occur as a key in mate.

A matching is a subset of edges in which no node occurs more than once. The cardinality of a matching is the number of matched edges. The weight of a matching is the sum of the weights of its edges.

If G is an XGraph, the edge data are used as weight values; if G is a Graph, all edge weights are taken to be 1. Directed graphs and multi-edge graphs are not supported.

This function takes time O(number\_of\_nodes \*\* 3).

If all edge weights are integers, the algorithm uses only integer computations. If floating point weights are used, the algorithm could return a slightly suboptimal matching due to numeric precision errors.

# 5.7 Isomorphism

is_isomorphic(G1, G2[, weighted, rtol, atol])	Returns True if the graphs G1 and G2 are isomorphic and False otherwise.
$could\_be\_isomorphic(G1, G2)$	Returns False if graphs are definitely not isomorphic.
$fast\_could\_be\_isomorphic$ ( $G1$ ,	Returns False if graphs are definitely not isomorphic.
G2)	
${ t faster\_could\_be\_isomorphic}(G1,$	Returns False if graphs are definitely not isomorphic.
G2)	

# 5.7.1 networkx.is\_isomorphic

#### Parameters G1, G2: NetworkX graph instances:

The two graphs G1 and G2 must be the same type.

#### weighted: bool, optional:

Optionally check isomorphism for weighted graphs. G1 and G2 must be valid weighted graphs.

rtol: float, optional:

The relative error tolerance when checking weighted edges

#### atol: float, optional:

The absolute error tolerance when checking weighted edges

#### See Also:

isomorphvf2

#### **Notes**

Uses the vf2 algorithm. Works for Graph, DiGraph, MultiGraph, and MultiDiGraph

## 5.7.2 networkx.could be isomorphic

```
could_be_isomorphic(G1, G2)
```

Returns False if graphs are definitely not isomorphic. True does NOT guarantee isomorphism.

Parameters G1, G2: NetworkX graph instances

The two graphs G1 and G2 must be the same type.

#### **Notes**

Checks for matching degree, triangle, and number of cliques sequences.

### 5.7.3 networkx.fast could be isomorphic

```
fast\_could\_be\_isomorphic(G1, G2)
```

Returns False if graphs are definitely not isomorphic. True does NOT guarantee isomorphism.

Parameters G1, G2: NetworkX graph instances

The two graphs G1 and G2 must be the same type.

#### **Notes**

Checks for matching degree and triangle sequences.

# 5.7.4 networkx.faster\_could\_be\_isomorphic

```
{\tt faster\_could\_be\_isomorphic}\,(\mathit{G1},\,\mathit{G2})
```

Returns False if graphs are definitely not isomorphic. True does NOT guarantee isomorphism.

Parameters G1, G2: NetworkX graph instances

The two graphs G1 and G2 must be the same type.

### **Notes**

Checks for matching degree sequences.

5.7. Isomorphism 149

### 5.7.5 VF2 Algorithm

### **Graph Matcher**

```
GraphMatcher.__init__(G1, G2)
                                                Initialize GraphMatcher.
GraphMatcher.initialize()
                                                Reinitializes the state of the algorithm.
GraphMatcher.is_isomorphic()
                                                Returns True if G1 and G2 are isomorphic graphs.
GraphMatcher.subgraph is isomorphic()
                                                Returns True if a subgraph of G1 is isomorphic to G2.
GraphMatcher.isomorphisms iter()
                                                Generator over isomorphisms between G1 and G2.
GraphMatcher.subgraph isomorphisms ite 6 enerator over isomorphisms between a subgraph of G1
                                                and G2.
GraphMatcher.candidate_pairs_iter()
                                                Iterator over candidate pairs of nodes in G1 and G2.
GraphMatcher.match()
                                                Extends the isomorphism mapping.
GraphMatcher.semantic_feasibility(G1_noReturns True if adding (G1_node, G2_node) is
                                                symantically feasible.
GraphMatcher.syntactic_feasibility(G1_nRedturns True if adding (G1_node, G2_node) is
                                                syntactically feasible.
```

## networkx.GraphMatcher.\_\_init\_\_

```
__init__(G1, G2)
Initialize GraphMatcher.
```

#### Parameters G1,G2: NetworkX Graph or MultiGraph instances. :

The two graphs to check for isomorphism.

# **Examples**

To create a GraphMatcher which checks for syntactic feasibility:

```
>>> G1 = nx.path_graph(4)
>>> G2 = nx.path_graph(4)
>>> GM = nx.GraphMatcher(G1,G2)
```

### networkx.GraphMatcher.initialize

```
initialize()
```

Reinitializes the state of the algorithm.

This method should be redefined if using something other than GMState. If only subclassing GraphMatcher, a redefinition is not necessary.

# networkx.GraphMatcher.is\_isomorphic

```
is isomorphic()
```

Returns True if G1 and G2 are isomorphic graphs.

### networkx.GraphMatcher.subgraph is isomorphic

#### subgraph\_is\_isomorphic()

Returns True if a subgraph of G1 is isomorphic to G2.

## networkx.GraphMatcher.isomorphisms iter

```
isomorphisms_iter()
```

Generator over isomorphisms between G1 and G2.

## networkx.GraphMatcher.subgraph\_isomorphisms\_iter

```
subgraph isomorphisms iter()
```

Generator over isomorphisms between a subgraph of G1 and G2.

### networkx.GraphMatcher.candidate pairs iter

```
candidate_pairs_iter()
```

Iterator over candidate pairs of nodes in G1 and G2.

### networkx.GraphMatcher.match

#### match()

Extends the isomorphism mapping.

This function is called recursively to determine if a complete isomorphism can be found between G1 and G2. It cleans up the class variables after each recursive call. If an isomorphism is found, we yield the mapping.

### networkx.GraphMatcher.semantic feasibility

```
semantic_feasibility(G1_node, G2_node)
```

Returns True if adding (G1\_node, G2\_node) is symantically feasible.

The semantic feasibility function should return True if it is acceptable to add the candidate pair (G1\_node, G2\_node) to the current partial isomorphism mapping. The logic should focus on semantic information contained in the edge data or a formalized node class.

By acceptable, we mean that the subsequent mapping can still become a complete isomorphism mapping. Thus, if adding the candidate pair definitely makes it so that the subsequent mapping cannot become a complete isomorphism mapping, then this function must return False.

The default semantic feasibility function always returns True. The effect is that semantics are not considered in the matching of G1 and G2.

The semantic checks might differ based on the what type of test is being performed. A keyword description of the test is stored in self.test. Here is a quick description of the currently implemented tests:

**test='graph'** Indicates that the graph matcher is looking for a graph-graph isomorphism.

**test='subgraph'** Indicates that the graph matcher is looking for a subgraph-graph isomorphism such that a subgraph of G1 is isomorphic to G2.

5.7. Isomorphism 151

Any subclass which redefines semantic\_feasibility() must maintain the above form to keep the match() method functional. Implementations should consider multigraphs.

# networkx.GraphMatcher.syntactic\_feasibility

```
syntactic_feasibility(G1_node, G2_node)
```

Returns True if adding (G1\_node, G2\_node) is syntactically feasible.

This function returns True if it is adding the candidate pair to the current partial isomorphism mapping is allowable. The addition is allowable if the inclusion of the candidate pair does not make it impossible for an isomorphism to be found.

### **DiGraph Matcher**

```
DiGraphMatcher.__init__(G1, G2)
                                                Initialize DiGraphMatcher.
DiGraphMatcher.initialize()
                                                Reinitializes the state of the algorithm.
DiGraphMatcher.is isomorphic()
                                                Returns True if G1 and G2 are isomorphic graphs.
DiGraphMatcher.subgraph_is_isomorphic() Returns True if a subgraph of G1 is isomorphic to G2.
DiGraphMatcher.isomorphisms iter()
                                                Generator over isomorphisms between G1 and G2.
DiGraphMatcher.subgraph_isomorphisms_itGen@rator over isomorphisms between a subgraph of G1
DiGraphMatcher.candidate_pairs_iter()
                                                Iterator over candidate pairs of nodes in G1 and G2.
DiGraphMatcher.match()
                                                Extends the isomorphism mapping.
DiGraphMatcher.semantic feasibility(G1 Reotherns True if adding (G1 node, G2 node) is
                                                symantically feasible.
...)
DiGraphMatcher.syntactic_feasibility(...)Returns True if adding (G1_node, G2_node) is
                                                syntactically feasible.
```

## networkx.DiGraphMatcher. init

```
__init__(G1, G2)
Initialize DiGraphMatcher.
```

G1 and G2 should be nx.Graph or nx.MultiGraph instances.

# **Examples**

To create a GraphMatcher which checks for syntactic feasibility:

```
>>> G1 = nx.DiGraph(nx.path_graph(4, create_using=nx.DiGraph()))
>>> G2 = nx.DiGraph(nx.path_graph(4, create_using=nx.DiGraph()))
>>> DiGM = nx.DiGraphMatcher(G1,G2)
```

# networkx.DiGraphMatcher.initialize

#### initialize()

Reinitializes the state of the algorithm.

This method should be redefined if using something other than DiGMState. If only subclassing GraphMatcher, a redefinition is not necessary.

# networkx.DiGraphMatcher.is\_isomorphic

#### is\_isomorphic()

Returns True if G1 and G2 are isomorphic graphs.

## networkx.DiGraphMatcher.subgraph\_is\_isomorphic

```
subgraph_is_isomorphic()
```

Returns True if a subgraph of G1 is isomorphic to G2.

## networkx.DiGraphMatcher.isomorphisms\_iter

```
isomorphisms iter()
```

Generator over isomorphisms between G1 and G2.

# networkx.DiGraphMatcher.subgraph\_isomorphisms\_iter

```
subgraph_isomorphisms_iter()
```

Generator over isomorphisms between a subgraph of G1 and G2.

### networkx.DiGraphMatcher.candidate\_pairs\_iter

```
candidate_pairs_iter()
```

Iterator over candidate pairs of nodes in G1 and G2.

### networkx.DiGraphMatcher.match

#### match()

Extends the isomorphism mapping.

This function is called recursively to determine if a complete isomorphism can be found between G1 and G2. It cleans up the class variables after each recursive call. If an isomorphism is found, we yield the mapping.

## networkx.DiGraphMatcher.semantic\_feasibility

```
semantic_feasibility(G1_node, G2_node)
```

Returns True if adding (G1\_node, G2\_node) is symantically feasible.

The semantic feasibility function should return True if it is acceptable to add the candidate pair (G1\_node, G2\_node) to the current partial isomorphism mapping. The logic should focus on semantic information contained in the edge data or a formalized node class.

By acceptable, we mean that the subsequent mapping can still become a complete isomorphism mapping. Thus, if adding the candidate pair definitely makes it so that the subsequent mapping cannot become a complete isomorphism mapping, then this function must return False.

The default semantic feasibility function always returns True. The effect is that semantics are not considered in the matching of G1 and G2.

5.7. Isomorphism 153

The semantic checks might differ based on the what type of test is being performed. A keyword description of the test is stored in self.test. Here is a quick description of the currently implemented tests:

**test='graph'** Indicates that the graph matcher is looking for a graph-graph isomorphism.

**test='subgraph'** Indicates that the graph matcher is looking for a subgraph-graph isomorphism such that a subgraph of G1 is isomorphic to G2.

Any subclass which redefines semantic\_feasibility() must maintain the above form to keep the match() method functional. Implementations should consider multigraphs.

# networkx.DiGraphMatcher.syntactic\_feasibility

```
syntactic_feasibility(G1_node, G2_node)
```

Returns True if adding (G1\_node, G2\_node) is syntactically feasible.

This function returns True if it is adding the candidate pair to the current partial isomorphism mapping is allowable. The addition is allowable if the inclusion of the candidate pair does not make it impossible for an isomorphism to be found.

#### Weighted Graph Matcher

```
WeightedGraphMatcher.__init__(G1, G2[,
                                                 Initialize WeightedGraphMatcher.
...])
WeightedGraphMatcher.initialize()
                                                 Reinitializes the state of the algorithm.
WeightedGraphMatcher.is_isomorphic()
                                                 Returns True if G1 and G2 are isomorphic graphs.
WeightedGraphMatcher.subgraph_is_isomorpReturns True if a subgraph of G1 is isomorphic to G2.
WeightedGraphMatcher.isomorphisms_iter() Generator over isomorphisms between G1 and G2.
WeightedGraphMatcher.subgraph_isomorphisGeneratoric()er isomorphisms between a subgraph of
                                                 G1 and G2.
WeightedGraphMatcher.candidate_pairs_it 4te(ator over candidate pairs of nodes in G1 and G2.
WeightedGraphMatcher.match()
                                                 Extends the isomorphism mapping.
WeightedGraphMatcher.semantic_feasibilitReturns True if mapping G1_node to G2_node is
                                                 semantically feasible.
WeightedGraphMatcher.syntactic feasibil Return True if adding (G1 node, G2 node) is
                                                 syntactically feasible.
```

# networkx.WeightedGraphMatcher. init

```
__init__(G1, G2, rtol=9.999999999999995e-07, atol=1.000000000000001e-09)
Initialize WeightedGraphMatcher.
```

Parameters G1, G2: nx.Graph instances

G1 and G2 must be weighted graphs.

rtol: float, optional

The relative tolerance used to compare weights.

atol: float, optional

The absolute tolerance used to compare weights.

## networkx.WeightedGraphMatcher.initialize

#### initialize()

Reinitializes the state of the algorithm.

This method should be redefined if using something other than GMState. If only subclassing GraphMatcher, a redefinition is not necessary.

### networkx.WeightedGraphMatcher.is\_isomorphic

```
is_isomorphic()
```

Returns True if G1 and G2 are isomorphic graphs.

### networkx.WeightedGraphMatcher.subgraph\_is\_isomorphic

```
subgraph_is_isomorphic()
```

Returns True if a subgraph of G1 is isomorphic to G2.

## networkx.WeightedGraphMatcher.isomorphisms\_iter

```
isomorphisms_iter()
```

Generator over isomorphisms between G1 and G2.

# networkx.WeightedGraphMatcher.subgraph\_isomorphisms\_iter

```
subgraph_isomorphisms_iter()
```

Generator over isomorphisms between a subgraph of G1 and G2.

### networkx.WeightedGraphMatcher.candidate\_pairs\_iter

```
candidate_pairs_iter()
```

Iterator over candidate pairs of nodes in G1 and G2.

### networkx.WeightedGraphMatcher.match

#### match()

Extends the isomorphism mapping.

This function is called recursively to determine if a complete isomorphism can be found between G1 and G2. It cleans up the class variables after each recursive call. If an isomorphism is found, we yield the mapping.

# networkx.WeightedGraphMatcher.semantic\_feasibility

```
semantic_feasibility(G1_node, G2_node)
```

Returns True if mapping G1 node to G2 node is semantically feasible.

5.7. Isomorphism 155

## networkx. Weighted Graph Matcher. syntactic feasibility

```
syntactic_feasibility(G1_node, G2_node)
```

Returns True if adding (G1 node, G2 node) is syntactically feasible.

This function returns True if it is adding the candidate pair to the current partial isomorphism mapping is allowable. The addition is allowable if the inclusion of the candidate pair does not make it impossible for an isomorphism to be found.

#### Weighted DiGraph Matcher

```
WeightedDiGraphMatcher. init (G1, G2[,
                                                 Initialize WeightedGraphMatcher.
WeightedDiGraphMatcher.initialize()
                                                 Reinitializes the state of the algorithm.
WeightedDiGraphMatcher.is isomorphic()
                                                 Returns True if G1 and G2 are isomorphic graphs.
WeightedDiGraphMatcher.subgraph is isomoReturns(True if a subgraph of G1 is isomorphic to G2.
WeightedDiGraphMatcher.isomorphisms_iter Generator over isomorphisms between G1 and G2.
WeightedDiGraphMatcher.subgraph_isomorphGenerator ov() isomorphisms between a subgraph of
                                                 G1 and G2.
WeightedDiGraphMatcher.candidate_pairs_iHera() or over candidate pairs of nodes in G1 and G2.
WeightedDiGraphMatcher.match()
                                                 Extends the isomorphism mapping.
WeightedDiGraphMatcher.semantic_feasibil Returns True if mapping G1_node to G2_node is
                                                 semantically feasible.
WeightedDiGraphMatcher.syntactic_feasibiReturn(s.True if adding (G1_node, G2_node) is
                                                 syntactically feasible.
```

# networkx.WeightedDiGraphMatcher.\_\_init\_\_

```
__init__(G1, G2, rtol=9.999999999999995e-07, atol=1.000000000000001e-09)
Initialize WeightedGraphMatcher.
```

Parameters G1, G2: nx.DiGraph instances

G1 and G2 must be weighted graphs.

rtol: float, optional

The relative tolerance used to compare weights.

atol: float, optional

The absolute tolerance used to compare weights.

# networkx.WeightedDiGraphMatcher.initialize

#### initialize()

Reinitializes the state of the algorithm.

This method should be redefined if using something other than DiGMState. If only subclassing GraphMatcher, a redefinition is not necessary.

## networkx.WeightedDiGraphMatcher.is isomorphic

#### is\_isomorphic()

Returns True if G1 and G2 are isomorphic graphs.

# networkx.WeightedDiGraphMatcher.subgraph\_is\_isomorphic

```
subgraph_is_isomorphic()
```

Returns True if a subgraph of G1 is isomorphic to G2.

### networkx.WeightedDiGraphMatcher.isomorphisms\_iter

```
isomorphisms iter()
```

Generator over isomorphisms between G1 and G2.

# networkx.WeightedDiGraphMatcher.subgraph\_isomorphisms\_iter

```
subgraph_isomorphisms_iter()
```

Generator over isomorphisms between a subgraph of G1 and G2.

### networkx.WeightedDiGraphMatcher.candidate\_pairs\_iter

```
candidate_pairs_iter()
```

Iterator over candidate pairs of nodes in G1 and G2.

### networkx.WeightedDiGraphMatcher.match

#### match()

Extends the isomorphism mapping.

This function is called recursively to determine if a complete isomorphism can be found between G1 and G2. It cleans up the class variables after each recursive call. If an isomorphism is found, we yield the mapping.

### networkx.WeightedDiGraphMatcher.semantic\_feasibility

```
semantic_feasibility(G1_node, G2_node)
```

Returns True if mapping G1\_node to G2\_node is semantically feasible.

## networkx.WeightedDiGraphMatcher.syntactic\_feasibility

```
syntactic_feasibility(G1_node, G2_node)
```

Returns True if adding (G1\_node, G2\_node) is syntactically feasible.

This function returns True if it is adding the candidate pair to the current partial isomorphism mapping is allowable. The addition is allowable if the inclusion of the candidate pair does not make it impossible for an isomorphism to be found.

5.7. Isomorphism 157

#### Weighted MultiGraph Matcher

```
WeightedMultiGraphMatcher.__init__(G1,
                                                  Initialize WeightedGraphMatcher.
G2[,...]
WeightedMultiGraphMatcher.initialize()
                                                  Reinitializes the state of the algorithm.
WeightedMultiGraphMatcher.is_isomorphic()
                                                  Returns True if G1 and G2 are isomorphic graphs.
WeightedMultiGraphMatcher.subgraph_is_isomReturns 2(i) ue if a subgraph of G1 is isomorphic to
WeightedMultiGraphMatcher.isomorphisms_iteGenerator over isomorphisms between G1 and G2.
WeightedMultiGraphMatcher.subgraph isomorpGeneraton over () morphisms between a subgraph
                                                  of G1 and G2.
WeightedMultiGraphMatcher.candidate_pairs_Iterato()over candidate pairs of nodes in G1 and G2.
WeightedMultiGraphMatcher.match()
                                                  Extends the isomorphism mapping.
WeightedMultiGraphMatcher.semantic_feasibility(...)
WeightedMultiGraphMatcher.syntactic_feasibRetimms(True if adding (G1_node, G2_node) is
                                                  syntactically feasible.
```

# networkx.WeightedMultiGraphMatcher.\_\_init\_\_

\_\_init\_\_(G1, G2, rtol=9.999999999999995e-07, atol=1.000000000000001e-09)
Initialize WeightedGraphMatcher.

Parameters G1, G2: nx.MultiGraph instances

G1 and G2 must be weighted graphs.

rtol: float, optional

The relative tolerance used to compare weights.

atol: float, optional

The absolute tolerance used to compare weights.

# networkx.WeightedMultiGraphMatcher.initialize

#### initialize()

Reinitializes the state of the algorithm.

This method should be redefined if using something other than GMState. If only subclassing GraphMatcher, a redefinition is not necessary.

# networkx.WeightedMultiGraphMatcher.is\_isomorphic

### is\_isomorphic()

Returns True if G1 and G2 are isomorphic graphs.

# networkx.WeightedMultiGraphMatcher.subgraph\_is\_isomorphic

# $\verb"subgraph_is_isomorphic" ()$

Returns True if a subgraph of G1 is isomorphic to G2.

# networkx.WeightedMultiGraphMatcher.isomorphisms\_iter

#### isomorphisms\_iter()

Generator over isomorphisms between G1 and G2.

## networkx.WeightedMultiGraphMatcher.subgraph\_isomorphisms\_iter

```
subgraph_isomorphisms_iter()
```

Generator over isomorphisms between a subgraph of G1 and G2.

## networkx.WeightedMultiGraphMatcher.candidate\_pairs\_iter

```
candidate_pairs_iter()
```

Iterator over candidate pairs of nodes in G1 and G2.

### networkx.WeightedMultiGraphMatcher.match

#### match()

Extends the isomorphism mapping.

This function is called recursively to determine if a complete isomorphism can be found between G1 and G2. It cleans up the class variables after each recursive call. If an isomorphism is found, we yield the mapping.

# networkx.WeightedMultiGraphMatcher.semantic\_feasibility

```
semantic_feasibility(Gl\_node, G2\_node)
```

# networkx.WeightedMultiGraphMatcher.syntactic\_feasibility

```
syntactic\_feasibility(Gl\_node, G2\_node)
```

Returns True if adding (G1\_node, G2\_node) is syntactically feasible.

This function returns True if it is adding the candidate pair to the current partial isomorphism mapping is allowable. The addition is allowable if the inclusion of the candidate pair does not make it impossible for an isomorphism to be found.

5.7. Isomorphism 159

#### Weighted MultiDiGraph Matcher

```
WeightedMultiDiGraphMatcher.__init__(G1,
                                                   Initialize WeightedGraphMatcher.
G2)
WeightedMultiDiGraphMatcher.initialize()
                                                   Reinitializes the state of the algorithm.
WeightedMultiDiGraphMatcher.is_isomorphic()Returns True if G1 and G2 are isomorphic graphs.
WeightedMultiDiGraphMatcher.subgraph_is_is_ReturnshTrue)if a subgraph of G1 is isomorphic to
WeightedMultiDiGraphMatcher.isomorphisms_iGenerizator over isomorphisms between G1 and G2.
WeightedMultiDiGraphMatcher.subgraph isomoGeneratorsovereso(norphisms between a subgraph
                                                   of G1 and G2.
WeightedMultiDiGraphMatcher.candidate_pairIterator of candidate pairs of nodes in G1 and G2.
WeightedMultiDiGraphMatcher.match()
                                                   Extends the isomorphism mapping.
WeightedMultiDiGraphMatcher.semantic_feasiRéturnsyTrue if mapping G1_node to G2_node is
                                                   semantically feasible.
WeightedMultiDiGraphMatcher.syntactic feasRetuinstTrue) f adding (G1 node, G2 node) is
                                                   syntactically feasible.
```

# networkx.WeightedMultiDiGraphMatcher.\_\_init\_\_

```
__init__ (G1, G2, rtol=9.999999999999995e-07, atol=1.0000000000000001e-09) Initialize WeightedGraphMatcher.
```

Parameters G1, G2: nx.MultiDiGraph instances

G1 and G2 must be weighted graphs.

rtol: float, optional

The relative tolerance used to compare weights.

atol: float, optional

The absolute tolerance used to compare weights.

# networkx.WeightedMultiDiGraphMatcher.initialize

#### initialize()

Reinitializes the state of the algorithm.

This method should be redefined if using something other than DiGMState. If only subclassing GraphMatcher, a redefinition is not necessary.

# $network x. Weighted Multi Di Graph Matcher. is \_isomorphic$

```
is_isomorphic()
```

Returns True if G1 and G2 are isomorphic graphs.

# networkx.WeightedMultiDiGraphMatcher.subgraph\_is\_isomorphic

```
subgraph_is_isomorphic()
```

Returns True if a subgraph of G1 is isomorphic to G2.

## networkx.WeightedMultiDiGraphMatcher.isomorphisms iter

#### isomorphisms\_iter()

Generator over isomorphisms between G1 and G2.

## networkx.WeightedMultiDiGraphMatcher.subgraph\_isomorphisms\_iter

```
subgraph_isomorphisms_iter()
```

Generator over isomorphisms between a subgraph of G1 and G2.

## networkx.WeightedMultiDiGraphMatcher.candidate\_pairs\_iter

```
candidate_pairs_iter()
```

Iterator over candidate pairs of nodes in G1 and G2.

## networkx.WeightedMultiDiGraphMatcher.match

#### match()

Extends the isomorphism mapping.

This function is called recursively to determine if a complete isomorphism can be found between G1 and G2. It cleans up the class variables after each recursive call. If an isomorphism is found, we yield the mapping.

# networkx.WeightedMultiDiGraphMatcher.semantic\_feasibility

```
semantic_feasibility(G1_node, G2_node)
```

Returns True if mapping G1\_node to G2\_node is semantically feasible.

### networkx.WeightedMultiDiGraphMatcher.syntactic\_feasibility

```
syntactic_feasibility(G1_node, G2_node)
```

Returns True if adding (G1\_node, G2\_node) is syntactically feasible.

This function returns True if it is adding the candidate pair to the current partial isomorphism mapping is allowable. The addition is allowable if the inclusion of the candidate pair does not make it impossible for an isomorphism to be found.

# 5.8 PageRank

```
pagerank(G[, alpha, max_iter, tol, nstart])

pagerank_numpy(G[, alpha, max_iter, tol, ...])

pagerank_scipy(G[, alpha, max_iter, tol, ...])

google_matrix(G[, alpha, nodelist])

Return the PageRank of the nodes in the graph.

Return a NumPy array of the PageRank of G.

Return a SciPy sparse array of the PageRank of G.
```

5.8. PageRank 161

## 5.8.1 networkx.pagerank

PageRank computes the largest eigenvector of the stochastic adjacency matrix of G.

Parameters G: graph

A networkx graph

alpha: float, optional

Parameter for PageRank, default=0.85

max\_iter: interger, optional

Maximum number of iterations in power method.

tol: float, optional

Error tolerance used to check convergence in power method iteration.

nstart: dictionary, optional

Starting value of PageRank iteration for each node.

Returns nodes: dictionary

Dictionary of nodes with value as PageRank

#### **Notes**

The eigenvector calculation is done by the power iteration method and has no guarantee of convergence. The iteration will stop after max\_iter iterations or an error tolerance of number\_of\_nodes(G)\*tol has been reached.

The PageRank algorithm was designed for directed graphs but this algorithm does not check if the input graph is directed and will execute on undirected graphs.

For an overview see: A. Langville and C. Meyer, "A survey of eigenvector methods of web information retrieval." http://citeseer.ist.psu.edu/713792.html

# **Examples**

```
>>> G=nx.DiGraph(nx.path_graph(4))
>>> pr=nx.pagerank(G,alpha=0.9)
```

# 5.8.2 networkx.pagerank\_numpy

## 5.8.3 networkx.pagerank scipy

## 5.8.4 networkx.google\_matrix

google\_matrix(G, alpha=0.84999999999999998, nodelist=None)

### **5.9 HITS**

hits(G[, max_iter, tol, nstart])	Return HITS hubs and authorities values for nodes.
<pre>hits_numpy(G[, max_iter, tol, nodelist])</pre>	Return a NumPy array of the hubs and authorities.
<pre>hits_scipy(G[, max_iter, tol, nodelist])</pre>	Return a SciPy sparse array of the hubs and authorities.
$hub_{matrix}(G[, nodelist])$	Return the HITS hub matrix.
$authority_matrix(G[, nodelist])$	Return the HITS authority matrix.

#### 5.9.1 networkx.hits

**hits** (*G*, *max iter*=100, *tol*=1*e*-08, *nstart*=None)

Return HITS hubs and authorities values for nodes.

Parameters G: graph

A networkx graph

max\_iter: interger, optional

Maximum number of iterations in power method.

tol: float, optional

Error tolerance used to check convergence in power method iteration.

nstart: dictionary, optional

Starting value of each node for power method iteration.

Returns (hubs, authorities): two-tuple of dictionaries

Two dictionaries keyed by node containing the hub and authority values.

#### **Notes**

The eigenvector calculation is done by the power iteration method and has no guarantee of convergence. The iteration will stop after max\_iter iterations or an error tolerance of number\_of\_nodes(G)\*tol has been reached.

The HITS algorithm was designed for directed graphs but this algorithm does not check if the input graph is directed and will execute on undirected graphs.

For an overview see: A. Langville and C. Meyer, "A survey of eigenvector methods of web information retrieval." http://citeseer.ist.psu.edu/713792.html

5.9. HITS 163

## **Examples**

```
>>> G=nx.path_graph(4)
>>> h,a=nx.hits(G)
```

# 5.9.2 networkx.hits\_numpy

# 5.9.3 networkx.hits\_scipy

### 5.9.4 networkx.hub\_matrix

hub\_matrix (*G*, nodelist=None)
Return the HITS hub matrix.

## 5.9.5 networkx.authority\_matrix

**authority\_matrix** (*G*, nodelist=None)
Return the HITS authority matrix.

## 5.10 Traversal

# 5.10.1 Components

Connected components and strongly connected components.

#### **Undirected Graphs**

is_connected(G)	Return True if G is connected.
${\tt number\_connected\_components}(G)$	Return the number of connected components in G.
$ ext{connected\_components}(G)$	Return a list of lists of nodes in each connected component of G.
connected_component_subgraphs(G)	Return a list of graphs of each connected component of G.
node_connected_component(G, n)	Return a list of nodes of the connected component containing node n.

## networkx.is connected

#### $is\_connected(G)$

Return True if G is connected. For undirected graphs only.

# networkx.number\_connected\_components

#### $number\_connected\_components(G)$

Return the number of connected components in G. For undirected graphs only.

### networkx.connected\_components

```
connected\_components(G)
```

Return a list of lists of nodes in each connected component of G.

The list is ordered from largest connected component to smallest. For undirected graphs only.

## networkx.connected component subgraphs

```
connected\_component\_subgraphs(G)
```

Return a list of graphs of each connected component of G.

The list is ordered from largest connected component to smallest. For undirected graphs only.

# **Examples**

Get largest connected component

```
>>> G=nx.path_graph(4)
>>> G.add_edge(5,6)
>>> H=nx.connected_component_subgraphs(G)[0]
```

## networkx.node\_connected\_component

#### $node\_connected\_component(G, n)$

Return a list of nodes of the connected component containing node n.

For undirected graphs only.

#### **Directed Graphs**

```
is_strongly_connected(G)

number_strongly_connected_components(G) Return the number of strongly connected components in G.

strongly_connected_components(G)

strongly_connected_component_subgraphs(Return a list of graphs of each strongly connected components in G.

strongly_connected_component_subgraphs(Return a list of strongly connected components in G.

strongly_connected_components_recursive(Returns list of strongly connected components in G.

kosaraju_strongly_connected_components(Returns list of strongly connected components in G.

...])
```

5.10. Traversal 165

# networkx.is\_strongly\_connected

#### $is\_strongly\_connected(G)$

Return True if G is strongly connected.

### networkx.number\_strongly\_connected\_components

#### $number\_strongly\_connected\_components(G)$

Return the number of strongly connected components in G.

For directed graphs only.

# networkx.strongly\_connected\_components

#### $strongly\_connected\_components(G)$

Returns a list of strongly connected components in G.

Uses Tarjan's algorithm with Nuutila's modifications. Nonrecursive version of algorithm.

#### References:

- R. Tarjan (1972). Depth-first search and linear graph algorithms. SIAM Journal of Computing 1(2):146-160.
- E. Nuutila and E. Soisalon-Soinen (1994). On finding the strongly connected components in a directed graph. Information Processing Letters 49(1): 9-14.

## networkx.strongly connected component subgraphs

#### $strongly\_connected\_component\_subgraphs(G)$

Return a list of graphs of each strongly connected component of G.

The list is ordered from largest connected component to smallest.

For example, to get the largest strongly connected component: >>> G=nx.path\_graph(4) >>> H=nx.strongly\_connected\_component\_subgraphs(G)[0]

# networkx.strongly\_connected\_components\_recursive

#### $strongly\_connected\_components\_recursive(G)$

Returns list of strongly connected components in G.

Uses Tarjan's algorithm with Nuutila's modifications. this recursive version of the algorithm will hit the Python stack limit for large graphs.

## networkx.kosaraju\_strongly\_connected\_components

### $\verb|kosaraju_strongly_connected_components| (\textit{G}, \textit{source=None})$

Returns list of strongly connected components in G.

Uses Kosaraju's algorithm.

### 5.10.2 DAGs

Algorithms for directed acyclic graphs (DAGs).

topological_sort(G[, nbunch])	Return a list of nodes in topological sort order.
<pre>topological_sort_recursive(G[, nbunch])</pre>	Return a list of nodes in topological sort order.
$is\_directed\_acyclic\_graph(G)$	Return True if the graph G is a directed acyclic graph (DAG)

### networkx.topological\_sort

#### topological\_sort(G, nbunch=None)

Return a list of nodes in topological sort order.

A topological sort is a nonunique permutation of the nodes such that an edge from u to v implies that u appears before v in the topological sort order.

Parameters G: NetworkX digraph

**nbunch**: container of nodes (optional)

Explore graph in specified order

#### See Also:

is\_directed\_acyclic\_graph

#### **Notes**

If G is not a directed acyclic graph (DAG) no topological sort exists and the Python keyword None is returned.

This algorithm is based on a description and proof in The Algorithm Design Manual [R25].

#### References

[R25]

#### networkx.topological\_sort\_recursive

#### topological\_sort\_recursive(G, nbunch=None)

Return a list of nodes in topological sort order.

A topological sort is a nonunique permutation of the nodes such that an edge from u to v implies that u appears before v in the topological sort order.

**Parameters G**: NetworkX digraph

**nbunch**: container of nodes (optional)

Explore graph in specified order

#### See Also:

topological\_sort, is\_directed\_acyclic\_graph

5.10. Traversal 167

### **Notes**

If G is not a directed acyclic graph (DAG) no topological sort exists and the Python keyword None is returned.

This is a recursive version of topological sort.

#### networkx.is\_directed\_acyclic\_graph

#### $is\_directed\_acyclic\_graph(G)$

Return True if the graph G is a directed acyclic graph (DAG) or False if not.

**Parameters G**: NetworkX graph

#### 5.10.3 Distance

Shortest paths, diameter, radius, eccentricity, and related methods.

eccentricity(G[, v, sp, with_labels])	Return the eccentricity of node v in G (or all nodes if v is None).
diameter(G[,e])	Return the diameter of the graph G.
radius(G[,e])	Return the radius of the graph G.
periphery(G[,e])	Return the periphery of the graph G.
center(G[,e])	Return the center of graph G.

### networkx.eccentricity

#### eccentricity(G, v=None, sp=None, with\_labels=False)

Return the eccentricity of node v in G (or all nodes if v is None).

The eccentricity is the maximum of shortest paths to all other nodes.

The optional keyword sp must be a dict of dicts of shortest\_path\_length keyed by source and target. That is, sp[v][t] is the length from v to t.

If with\_labels=True return dict of eccentricities keyed by vertex.

#### networkx.diameter

#### diameter(G, e=None)

Return the diameter of the graph G.

The diameter is the maximum of all pairs shortest path.

#### networkx.radius

#### radius(G, e=None)

Return the radius of the graph G.

The radius is the minimum of all pairs shortest path.

#### networkx.periphery

```
periphery(G, e=None)
```

Return the periphery of the graph G.

The periphery is the set of nodes with eccentricity equal to the diameter.

#### networkx.center

```
center(G, e=None)
```

Return the center of graph G.

The center is the set of nodes with eccentricity equal to radius.

#### 5.10.4 Shortest Paths

#### Shortest path algorithms.

```
average shortest path length.
weighted])
shortest path(G, source, target)
                                     Return a list of nodes in a shortest path between source and target.
shortest path length(G,
                                     Return the shortest path length between the source and target.
source, target)
single_source_shortest_path(Return list of nodes in a shortest path between source and all other nodes
source[, cutoff])
                                     reachable from source.
single_source_shortest_path_Returnth(Ghortest path length from source to all reachable nodes.
source)
all_pairs_shortest_path(G[, Return shortest paths between all nodes.
cutoff])
all_pairs_shortest_path_lengRet(Gf, dictionary of shortest path lengths between all nodes in G.
cutoff])
dijkstra_path(G, source, target)
                                     Returns the shortest path from source to target in a weighted
dijkstra_path_length(G,
                                     Returns the shortest path length from source to target in a weighted
source, target)
single_source_dijkstra_path(Return list of nodes in a shortest path between source and all other nodes
                                     reachable from source for a weighted graph.
single_source_dijkstra_path_Returns th (Schortest path lengths from source to all other
source)
single_source_dijkstra(G,
                                     Returns shortest paths and lengths in a weighted graph G.
source[, target, ...])
bidirectional_dijkstra(G,
                                     Dijkstra's algorithm for shortest paths using bidirectional search.
source, target)
bidirectional_shortest_path(Return a list of nodes in a shortest path between source and target.
source, target)
dijkstra_predecessor_and_disReturns (Goo dictionaries representing a list of predecessors of a node and
source)
                                     the distance to each node respectively.
predecessor(G, source[, target,
                                     Returns dictionary of predecessors for the path from source to all
cutoff, ...])
floyd_warshall(G[, huge])
                                     The Floyd-Warshall algorithm for all pairs shortest paths.
```

5.10. Traversal 169

#### networkx.average\_shortest\_path\_length

```
average_shortest_path_length(G, weighted=False)
```

Return the average shortest path length.

Parameters G: NetworkX graph

weighted: bool, optional, default=False

If true use edge weights on path. If False, use 1 as the edge distance.

# **Examples**

```
>>> G=nx.path_graph(4)
>>> print nx.average_shortest_path_length(G)
1.25
```

#### networkx.shortest path

#### shortest\_path(G, source, target)

Return a list of nodes in a shortest path between source and target.

There may be more than one shortest path. This returns only one.

**Parameters G**: NetworkX graph

source: node label

starting node for path

target: node label

ending node for path

# **Examples**

```
>>> G=nx.path_graph(5)
>>> print nx.shortest_path(G,0,4)
[0, 1, 2, 3, 4]
```

#### networkx.shortest path length

```
shortest_path_length (G, source, target)
```

Return the shortest path length between the source and target.

Raise an exception if no path exists.

**Parameters G**: NetworkX graph

source: node label

Starting node for path

target: node label

Ending node for path

#### **Notes**

G is treated as an unweighted graph. For weighted graphs see dijkstra\_path\_length.

# **Examples**

```
>>> G=nx.path_graph(5)
>>> print nx.shortest_path_length(G,0,4)
4
```

### networkx.single\_source\_shortest\_path

```
single_source_shortest_path(G, source, cutoff=None)
```

Return list of nodes in a shortest path between source and all other nodes reachable from source.

There may be more than one shortest path between the source and target nodes - this routine returns only one.

Returns a dictionary of shortest path lengths keyed by target.

```
Parameters G: NetworkX graph

source: node label

starting node for path

cutoff: integer, optional
```

depth to stop the search - only paths of length <= cutoff are returned.

#### See Also:

```
shortest_path
```

# **Examples**

```
>>> G=nx.path_graph(5)
>>> path=nx.single_source_shortest_path(G,0)
>>> path[4]
[0, 1, 2, 3, 4]
```

### networkx.single\_source\_shortest\_path\_length

```
single_source_shortest_path_length(G, source, cutoff=None)
```

Return the shortest path length from source to all reachable nodes.

Returns a dictionary of shortest path lengths keyed by target.

```
Parameters G: NetworkX graph

source: node label

Starting node for path

cutoff: integer, optional

Depth to stop the search - only paths of length <= cutoff are returned.
```

5.10. Traversal 171

## **Examples**

```
>>> G=nx.path_graph(5)
>>> length=nx.single_source_shortest_path_length(G,0)
>>> length[4]
4
>>> print length
{0: 0, 1: 1, 2: 2, 3: 3, 4: 4}
```

#### networkx.all\_pairs\_shortest\_path

#### all\_pairs\_shortest\_path(G, cutoff=None)

Return shortest paths between all nodes.

Returns a dictionary with keys for all reachable node pairs.

```
Parameters G: NetworkX graph

cutoff: integer, optional
```

depth to stop the search - only paths of length <= cutoff are returned.

#### See Also:

```
floyd_warshall
```

# **Examples**

```
>>> G=nx.path_graph(5)
>>> path=nx.all_pairs_shortest_path(G)
>>> print path[0][4]
[0, 1, 2, 3, 4]
```

#### networkx.all\_pairs\_shortest\_path\_length

#### all\_pairs\_shortest\_path\_length(G, cutoff=None)

Return dictionary of shortest path lengths between all nodes in G.

The dictionary only has keys for reachable node pairs.

```
Parameters G: NetworkX graph

cutoff: integer, optional

depth to stop the search - only paths of length <= cutoff are returned.
```

# **Examples**

```
>>> G=nx.path_graph(5)
>>> length=nx.all_pairs_shortest_path_length(G)
>>> print length[1][4]
3
>>> length[1]
{0: 1, 1: 0, 2: 1, 3: 2, 4: 3}
```

#### networkx.dijkstra\_path

```
dijkstra_path(G, source, target)
```

Returns the shortest path from source to target in a weighted graph G.

Uses a bidirectional version of Dijkstra's algorithm.

```
Parameters G: NetworkX graph
```

source : node label

starting node for path

target: node label

ending node for path

#### See Also:

```
bidirectional_dijkstra
```

#### **Notes**

Edge data must be numerical values for Graph and DiGraphs.

# **Examples**

```
>>> G=nx.path_graph(5)
>>> print nx.dijkstra_path(G,0,4)
[0, 1, 2, 3, 4]
```

#### networkx.dijkstra path length

```
dijkstra_path_length(G, source, target)
```

Returns the shortest path length from source to target in a weighted graph G.

Raise an exception if no path exists.

Parameters G: NetworkX graph, weighted

source: node label

starting node for path

target: node label

ending node for path

### See Also:

```
bidirectional_dijkstra
```

## **Notes**

Edge data must be numerical values for Graph and DiGraphs.

5.10. Traversal 173

### **Examples**

```
>>> G=nx.path_graph(5) # a weighted graph by default
>>> print nx.dijkstra_path_length(G,0,4)
```

### networkx.single\_source\_dijkstra\_path

```
single_source_dijkstra_path(G, source)
```

Return list of nodes in a shortest path between source and all other nodes reachable from source for a weighted graph.

Returns a dictionary of shortest path lengths keyed by target.

```
Parameters G: NetworkX graph
source: node label
starting node for path
```

#### See Also:

```
single_source_dijkstra
```

#### **Notes**

Edge data must be numerical values for Graph and DiGraphs.

# **Examples**

```
>>> G=nx.path_graph(5)
>>> path=nx.single_source_dijkstra_path(G,0)
>>> path[4]
[0, 1, 2, 3, 4]
```

#### networkx.single source dijkstra path length

```
\verb|single_source_dijkstra_path_length| (\textit{G}, \textit{source}) \\
```

Returns the shortest path lengths from source to all other reachable nodes in a weighted graph G.

Returns a dictionary of shortest path lengths keyed by target. Uses Dijkstra's algorithm.

```
Parameters G: NetworkX graph
source: node label
Starting node for path
```

#### See Also:

```
single_source_dijkstra
```

#### **Notes**

Edge data must be numerical values for XGraph and XDiGraphs.

### **Examples**

```
>>> G=nx.path_graph(5)
>>> length=nx.single_source_dijkstra_path_length(G,0)
>>> length[4]
4
>>> print length
{0: 0, 1: 1, 2: 2, 3: 3, 4: 4}
```

### networkx.single\_source\_dijkstra

```
single_source_dijkstra(G, source, target=None, cutoff=None)
```

Returns shortest paths and lengths in a weighted graph G.

Uses Dijkstra's algorithm for shortest paths. Returns a tuple of two dictionaries keyed by node. The first dicdtionary stores distance from the source. The second stores the path from the source to that node.

```
Parameters G: NetworkX graph
```

```
source : node label
    Starting node for path
target : node label, optional
    Ending node for path
cutoff : integer or float, optional
```

Depth to stop the search - only paths of length <= cutoff are returned.

#### See Also:

```
single_source_dijkstra_path, single_source_dijkstra_path_length
```

#### **Notes**

Distances are calculated as sums of weighted edges traversed. Edges must hold numerical values for Graph and DiGraphs.

Based on the Python cookbook recipe (119466) at http://aspn.activestate.com/ASPN/Cookbook/Python/Recipe/119466

This algorithm is not guaranteed to work if edge weights are negative or are floating point numbers (overflows and roundoff errors can cause problems).

# **Examples**

```
>>> G=nx.path_graph(5)
>>> length,path=nx.single_source_dijkstra(G,0)
>>> print length[4]
```

5.10. Traversal 175

```
4
>>> print length
{0: 0, 1: 1, 2: 2, 3: 3, 4: 4}
>>> path[4]
[0, 1, 2, 3, 4]
```

### networkx.bidirectional\_dijkstra

#### bidirectional\_dijkstra(G, source, target)

Dijkstra's algorithm for shortest paths using bidirectional search.

Returns a tuple of two dictionaries keyed by node. The first dicdtionary stores distance from the source. The second stores the path from the source to that node.

Raise an exception if no path exists.

```
Parameters G: NetworkX graph
source: node label
Starting node for path
target: node label
Ending node for path
```

#### **Notes**

Distances are calculated as sums of weighted edges traversed.

Edges must hold numerical values for Graph and DiGraphs.

In practice bidirectional Dijkstra is much more than twice as fast as ordinary Dijkstra.

Ordinary Dijkstra expands nodes in a sphere-like manner from the source. The radius of this sphere will eventually be the length of the shortest path. Bidirectional Dijkstra will expand nodes from both the source and the target, making two spheres of half this radius. Volume of the first sphere is pi\*r\*r while the others are 2\*pi\*r/2\*r/2, making up half the volume.

This algorithm is not guaranteed to work if edge weights are negative or are floating point numbers (overflows and roundoff errors can cause problems).

# **Examples**

```
>>> G=nx.path_graph(5)
>>> length,path=nx.bidirectional_dijkstra(G,0,4)
>>> print length
4
>>> print path
[0, 1, 2, 3, 4]
```

#### networkx.bidirectional shortest path

```
bidirectional_shortest_path(G, source, target)
```

Return a list of nodes in a shortest path between source and target.

Also known as shortest\_path()

Parameters G: NetworkX graph

source: node label

starting node for path

target: node label

ending node for path

#### networkx.dijkstra predecessor and distance

```
dijkstra\_predecessor\_and\_distance(G, source)
```

Returns two dictionaries representing a list of predecessors of a node and the distance to each node respectively.

**Parameters G**: NetworkX graph

source: node label

Starting node for path

#### **Notes**

The list of predecessors contains more than one element only when there are more than one shortest paths to the key node.

This routine is intended for use with the betweenness centrality algorithms in centrality.py.

#### networkx.predecessor

```
predecessor(G, source, target=None, cutoff=None, return_seen=None)
```

Returns dictionary of predecessors for the path from source to all nodes in G.

**Parameters G**: NetworkX graph

source: node label

Starting node for path

target: node label, optional

Ending node for path. If provided only predecessors between source and target are

returned

cutoff: integer, optional

Depth to stop the search - only paths of length <= cutoff are returned.

# **Examples**

```
>>> G=nx.path_graph(4)
>>> print G.nodes()
[0, 1, 2, 3]
>>> nx.predecessor(G,0)
{0: [], 1: [0], 2: [1], 3: [2]}
```

5.10. Traversal 177

#### networkx.floyd warshall

#### floyd\_warshall(G, huge=inf)

The Floyd-Warshall algorithm for all pairs shortest paths.

Returns a tuple (distance,path) containing two dictionaries of shortest distance and predecessor paths.

```
Parameters G: NetworkX graph
```

#### See Also:

```
all_pairs_shortest_path, all_pairs_shortest_path_length
```

#### **Notes**

This algorithm is most appropriate for dense graphs. The running time is  $O(n^3)$ , and running space is  $O(n^2)$  where n is the number of nodes in G.

Shortest paths using A\* ("A star") algorithm.

<pre>astar_path(G, source, target[, heuristic])</pre>	Return a list of nodes in a shortest path between source and
<pre>astar_path_length(G, source, target[,</pre>	target Return a list of nodes in a shortest path between source and
heuristic])	target

#### networkx.astar path

```
astar_path (G, source, target, heuristic=None)
```

Return a list of nodes in a shortest path between source and target using the A\* ("A-star") algorithm.

There may be more than one shortest path. This returns only one.

### Parameters G: NetworkX graph

source: node

Starting node for path

target: node

Ending node for path

heuristic: function

A function to evaluate the estimate of the distance from the a node to the target. The function takes two nodes arguments and must return a number.

### See Also:

```
shortest_path, dijkstra_path
```

# **Examples**

```
>>> G=nx.path_graph(5)
>>> print nx.astar_path(G,0,4)
[0, 1, 2, 3, 4]
>>> G=nx.grid_graph(dim=[3,3]) # nodes are two-tuples (x,y)
>>> def dist((x1, y1), (x2, y2)):
```

```
return ((x1 - x2) ** 2 + (y1 - y2) ** 2) ** 0.5
>>> print nx.astar_path(G,(0,0),(2,2),dist)
[(0, 0), (0, 1), (1, 1), (1, 2), (2, 2)]
```

### networkx.astar\_path\_length

```
astar_path_length (G, source, target, heuristic=None)
```

Return a list of nodes in a shortest path between source and target using the A\* ("A-star") algorithm.

Parameters G: NetworkX graph

source: node

Starting node for path

target: node

Ending node for path

heuristic: function

A function to evaluate the estimate of the distance from the a node to the target. The function takes two nodes arguments and must return a number.

#### See Also:

astar\_path

### 5.10.5 Search

Search algorithms.

See also networkx.path.

<pre>dfs_preorder(G[, source, reverse_graph])</pre>	Return list of nodes connected to source in depth-first-search
	preorder.
$dfs_postorder(G[, source,$	Return list of nodes connected to source in depth-first-search
reverse_graph])	postorder.
$dfs\_predecessor(G[, source,$	Return predecessors of depth-first-search with root at source.
reverse_graph])	
$dfs\_successor(G[, source,$	Return succesors of depth-first-search with root at source.
reverse_graph])	
<pre>dfs_tree(G[, source, reverse_graph])</pre>	Return directed graph (tree) of depth-first-search with root at
	source.

### networkx.dfs\_preorder

dfs\_preorder(G, source=None, reverse\_graph=False)

Return list of nodes connected to source in depth-first-search preorder.

Traverse the graph G with depth-first-search from source. Non-recursive algorithm.

5.10. Traversal 179

#### networkx.dfs postorder

### dfs\_postorder (G, source=None, reverse\_graph=False)

Return list of nodes connected to source in depth-first-search postorder.

Traverse the graph G with depth-first-search from source. Non-recursive algorithm.

### networkx.dfs\_predecessor

```
dfs_predecessor (G, source=None, reverse_graph=False)
```

Return predecessors of depth-first-search with root at source.

### networkx.dfs\_successor

```
dfs_successor (G, source=None, reverse_graph=False)
```

Return succesors of depth-first-search with root at source.

### networkx.dfs\_tree

```
dfs_tree (G, source=None, reverse_graph=False)
```

Return directed graph (tree) of depth-first-search with root at source.

If the graph is disconnected, return a disconnected graph (forest).

# 5.11 Bipartite

is_bipartite(G)	Returns True if graph G is bipartite, False if not.
bipartite_sets(G)	Returns bipartite node sets of graph G.
$bipartite\_color(G)$	Returns a two-coloring of the graph.
<pre>project(B, nodes[, create_using])</pre>	Return the projection of the graph onto a subset of nodes.

### 5.11.1 networkx.is bipartite

#### $is\_bipartite(G)$

Returns True if graph G is bipartite, False if not.

Parameters G: NetworkX graph

#### See Also:

bipartite\_color

# **Examples**

```
>>> G=nx.path_graph(4)
>>> print nx.is_bipartite(G)
True
```

# 5.11.2 networkx.bipartite\_sets

# ${\tt bipartite\_sets}\,(G)$

Returns bipartite node sets of graph G.

Raises an exception if the graph is not bipartite.

**Parameters G**: NetworkX graph **Returns** (**X**,**Y**): two-tuple of sets

One set of nodes for each part of the bipartite graph.

#### See Also:

```
bipartite_color
```

# **Examples**

```
>>> G=nx.path_graph(4)
>>> X,Y=nx.bipartite_sets(G)
>>> print X
set([0, 2])
>>> print Y
set([1, 3])
```

# 5.11.3 networkx.bipartite\_color

#### $bipartite\_color(G)$

Returns a two-coloring of the graph.

Raises an exception if the graph is not bipartite.

Parameters G: NetworkX graph

Returns color: dictionary

A dictionary keyed by node with a 1 or 0 as data for each node color.

# **Examples**

```
>>> G=nx.path_graph(4)
>>> c=nx.bipartite_color(G)
>>> print c
{0: 1, 1: 0, 2: 1, 3: 0}
```

# 5.11.4 networkx.project

### project (B, nodes, create\_using=None)

Return the projection of the graph onto a subset of nodes.

The nodes retain their names and are connected in the resulting graph if have an edge to a common node in the original graph.

Parameters B: NetworkX graph

5.11. Bipartite 181

The input graph should be bipartite.

nodes: list or iterable

Nodes to project onto.

Returns Graph: NetworkX graph

A graph that is the projection onto the given nodes.

#### See Also:

```
is_bipartite, bipartite_sets
```

#### **Notes**

Returns a graph that is the projection of the bipartite graph B onto the set of nodes given in list nodes. No attempt is made to verify that the input graph B is bipartite.

# **Examples**

```
>>> B=nx.path_graph(4)
>>> G=nx.project(B,[1,3])
>>> print G.nodes()
[1, 3]
>>> print G.edges()
[(1, 3)]
```

# 5.12 Minimum Spanning Tree

mst(G) Generate a minimum spanning tree of an undirected graph.

### 5.12.1 networkx.mst

 ${\tt mst}\,(G)$ 

Generate a minimum spanning tree of an undirected graph.

Uses Kruskal's algorithm.

**Parameters G**: NetworkX Graph

Returns A generator that produces edges in the minimum spanning tree. :

The edges are three-tuples (u,v,w) where w is the weight. :

#### **Notes**

Modified code from David Eppstein, April 2006 http://www.ics.uci.edu/~eppstein/PADS/

# **Examples**

```
>>> G=nx.cycle_graph(4)
>>> G.add_edge(0,3,weight=2) # assign weight 2 to edge 0-3
>>> mst=nx.kruskal_mst(G) # a generator of MST edges
>>> edgelist=list(mst) # make a list of the edges
>>> print sorted(edgelist)
[(0, 1, {'weight': 1}), (1, 2, {'weight': 1}), (2, 3, {'weight': 1})]
>>> T=nx.Graph(edgelist) # build a graph of the MST.
>>> print sorted(T.edges(data=True))
[(0, 1, {'weight': 1}), (1, 2, {'weight': 1}), (2, 3, {'weight': 1})]
```

**CHAPTER** 

SIX

# **GRAPH GENERATORS**

# 6.1 Atlas

graph\_atlas\_g() Return the list [G0,G1,...,G1252] of graphs as named in the Graph Atlas.

# 6.1.1 networkx.graph\_atlas\_g

#### graph\_atlas\_g()

Return the list [G0,G1,...,G1252] of graphs as named in the Graph Atlas. G0,G1,...,G1252 are all graphs with up to 7 nodes.

#### The graphs are listed:

- 1. in increasing order of number of nodes;
- 2. for a fixed number of nodes, in increasing order of the number of edges;
- 3. for fixed numbers of nodes and edges, in increasing order of the degree sequence, for example 111223 < 112222;
- 4. for fixed degree sequence, in increasing number of automorphisms.

Note that indexing is set up so that for GAG=graph\_atlas\_g(), then G123=GAG[123] and G[0]=empty\_graph(0)

# 6.2 Classic

balanced_tree(r, h[, create_using])	Return the perfectly balanced r-tree of height h.
barbell_graph(m1, m2[,	Return the Barbell Graph: two complete graphs connected by a path.
create_using])	
<pre>complete_graph(n[, create_using])</pre>	Return the Complete graph K_n with n nodes.
complete_bipartite_graph(n1,	Return the complete bipartite graph K_{n1_n2}.
n2[, create_using])	
circular_ladder_graph(n[,	Return the circular ladder graph CL_n of length n.
create_using])	
<pre>cycle_graph(n[, create_using])</pre>	Return the cycle graph C_n over n nodes.
dorogovtsev_goltsev_mendes_gr	a Re(nfn the hierarchically constructed Dorogovtsev-Goltsev-Mendes
])	graph.
<pre>empty_graph([n, create_using])</pre>	Return the empty graph with n nodes and zero edges.
<pre>grid_2d_graph(m, n[, periodic,</pre>	Return the 2d grid graph of mxn nodes, each connected to its nearest
create_using])	neighbors.
<pre>grid_graph(dim[, periodic,</pre>	Return the n-dimensional grid graph.
create_using])	
<pre>hypercube_graph(n[, create_using])</pre>	Return the n-dimensional hypercube.
<pre>ladder_graph(n[, create_using])</pre>	Return the Ladder graph of length n.
$lollipop_graph(m, n[,$	Return the Lollipop Graph; K_m connected to P_n.
create_using])	
null_graph([create_using])	Return the Null graph with no nodes or edges.
<pre>path_graph(n[, create_using])</pre>	Return the Path graph P_n of n nodes linearly connected
star_graph(n[, create_using])	Return the Star graph with n+1 nodes:
<pre>trivial_graph([create_using])</pre>	Return the Trivial graph with one node (with integer label 0)
<pre>wheel_graph(n[, create_using])</pre>	Return the wheel graph: a single hub node connected to each node of
	the (n-1)-node cycle graph.

# 6.2.1 networkx.balanced tree

balanced\_tree (r, h, create\_using=None)

Return the perfectly balanced r-tree of height h.

For r>=2, h>=1, this is the rooted tree where all leaves are at distance h from the root. The root has degree r and all other internal nodes have degree r+1.

number of nodes =  $1+r+r^{**}2+...+r^{**}h = (r^{**}(h+1)-1)/(r-1)$ , number of edges = number of nodes - 1.

Node labels are the integers 0 (the root) up to number\_of\_nodes - 1.

# 6.2.2 networkx.barbell\_graph

barbell\_graph (m1, m2, create\_using=None)

Return the Barbell Graph: two complete graphs connected by a path.

For m1 > 1 and m2 >= 0.

Two identical complete graphs  $K_{m1}$  form the left and right bells, and are connected by a path  $P_{m2}$ .

**The 2\*m1+m2 nodes are numbered** 0,...,m1-1 for the left barbell, m1,...,m1+m2-1 for the path, and m1+m2,...,2\*m1+m2-1 for the right barbell.

The 3 subgraphs are joined via the edges (m1-1,m1) and (m1+m2-1,m1+m2). If m2=0, this is merely two complete graphs joined together.

This graph is an extremal example in David Aldous and Jim Fill's etext on Random Walks on Graphs.

# 6.2.3 networkx.complete\_graph

#### complete\_graph (n, create\_using=None)

Return the Complete graph K\_n with n nodes.

Node labels are the integers 0 to n-1.

### 6.2.4 networkx.complete bipartite graph

### complete\_bipartite\_graph (n1, n2, create\_using=None)

Return the complete bipartite graph  $K_{n1_n2}$ .

Composed of two partitions with n1 nodes in the first and n2 nodes in the second. Each node in the first is connected to each node in the second.

Node labels are the integers 0 to n1+n2-1

# 6.2.5 networkx.circular\_ladder\_graph

#### circular\_ladder\_graph (n, create\_using=None)

Return the circular ladder graph CL\_n of length n.

CL\_n consists of two concentric n-cycles in which each of the n pairs of concentric nodes are joined by an edge.

Node labels are the integers 0 to n-1

### 6.2.6 networkx.cycle graph

#### cycle\_graph (n, create\_using=None)

Return the cycle graph C\_n over n nodes.

C\_n is the n-path with two end-nodes connected.

Node labels are the integers 0 to n-1 If create\_using is a DiGraph, the direction is in increasing order.

### 6.2.7 networkx.dorogovtsev goltsev mendes graph

### dorogovtsev\_goltsev\_mendes\_graph (n, create\_using=None)

Return the hierarchically constructed Dorogovtsev-Goltsev-Mendes graph.

n is the generation. See: arXiv:/cond-mat/0112143 by Dorogovtsev, Goltsev and Mendes.

### 6.2.8 networkx.empty\_graph

#### empty\_graph (n=0, create\_using=None)

Return the empty graph with n nodes and zero edges.

Node labels are the integers 0 to n-1

 $For \ example: >>> G=nx.empty\_graph(10) >>> G.number\_of\_nodes() \ 10 >>> G.number\_of\_edges() \ 0 >>> G.number\_of$ 

6.2. Classic 187

The variable create\_using should point to a "graph"-like object that will be cleaned (nodes and edges will be removed) and refitted as an empty "graph" with n nodes with integer labels. This capability is useful for specifying the class-nature of the resulting empty "graph" (i.e. Graph, DiGraph, MyWeirdGraphClass, etc.).

The variable create\_using has two main uses: Firstly, the variable create\_using can be used to create an empty digraph, network,etc. For example,

```
>>> n=10
>>> G=nx.empty_graph(n,create_using=nx.DiGraph())
```

will create an empty digraph on n nodes.

Secondly, one can pass an existing graph (digraph, pseudograph, etc.) via create\_using. For example, if G is an existing graph (resp. digraph, pseudograph, etc.), then empty\_graph(n,create\_using=G) will empty G (i.e. delete all nodes and edges using G.clear() in base) and then add n nodes and zero edges, and return the modified graph (resp. digraph, pseudograph, etc.).

See also create\_empty\_copy(G).

# 6.2.9 networkx.grid\_2d\_graph

```
grid_2d_graph (m, n, periodic=False, create_using=None)
```

Return the 2d grid graph of mxn nodes, each connected to its nearest neighbors. Optional argument periodic=True will connect boundary nodes via periodic boundary conditions.

# 6.2.10 networkx.grid\_graph

```
grid graph (dim, periodic=False, create using=None)
```

Return the n-dimensional grid graph.

The dimension is the length of the list 'dim' and the size in each dimension is the value of the list element.

E.g. G=grid\_graph(dim=[2,3]) produces a 2x3 grid graph.

If periodic=True then join grid edges with periodic boundary conditions.

# 6.2.11 networkx.hypercube\_graph

```
hypercube_graph (n, create_using=None)
```

Return the n-dimensional hypercube.

Node labels are the integers 0 to 2\*\*n - 1.

# 6.2.12 networkx.ladder\_graph

#### ladder\_graph (n, create\_using=None)

Return the Ladder graph of length n.

This is two rows of n nodes, with each pair connected by a single edge.

Node labels are the integers 0 to 2\*n - 1.

# 6.2.13 networkx.lollipop graph

#### lollipop\_graph (m, n, create\_using=None)

Return the Lollipop Graph; K\_m connected to P\_n.

This is the Barbell Graph without the right barbell.

For m>1 and n>=0, the complete graph K\_m is connected to the path P\_n. The resulting m+n nodes are labelled 0,...,m-1 for the complete graph and m,...,m+n-1 for the path. The 2 subgraphs are joined via the edge (m-1,m). If n=0, this is merely a complete graph.

Node labels are the integers 0 to number\_of\_nodes - 1.

(This graph is an extremal example in David Aldous and Jim Fill's etext on Random Walks on Graphs.)

# 6.2.14 networkx.null\_graph

#### null\_graph (create\_using=None)

Return the Null graph with no nodes or edges.

See empty\_graph for the use of create\_using.

# 6.2.15 networkx.path\_graph

#### path\_graph (n, create\_using=None)

Return the Path graph P\_n of n nodes linearly connected by n-1 edges.

Node labels are the integers 0 to n - 1. If create\_using is a DiGraph then the edges are directed in increasing order.

# 6.2.16 networkx.star graph

```
star_graph (n, create_using=None)
```

**Return the Star graph with n+1 nodes:** one center node, connected to n outer nodes.

Node labels are the integers 0 to n.

# 6.2.17 networkx.trivial\_graph

```
trivial graph (create using=None)
```

Return the Trivial graph with one node (with integer label 0) and no edges.

### 6.2.18 networkx.wheel graph

```
wheel_graph (n, create_using=None)
```

Return the wheel graph: a single hub node connected to each node of the (n-1)-node cycle graph.

Node labels are the integers 0 to n - 1.

6.2. Classic 189

# 6.3 Small

make_small_graph(graph_description[,])	Return the small graph described by graph_description.
<pre>LCF_graph(n, shift_list, repeats[, create_using])</pre>	Return the cubic graph specified in LCF notation.
bull_graph([create_using])	Return the Bull graph.
<pre>chvatal_graph([create_using])</pre>	Return the Chvatal graph.
cubical_graph([create_using])	Return the 3-regular Platonic Cubical graph.
desargues_graph([create_using])	Return the Desargues graph.
diamond_graph([create_using])	Return the Diamond graph.
<pre>dodecahedral_graph([create_using])</pre>	Return the Platonic Dodecahedral graph.
<pre>frucht_graph([create_using])</pre>	Return the Frucht Graph.
heawood_graph([create_using])	Return the Heawood graph, a (3,6) cage.
house_graph([create_using])	Return the House graph (square with triangle on top).
house_x_graph([create_using])	Return the House graph with a cross inside the house square.
<pre>icosahedral_graph([create_using])</pre>	Return the Platonic Icosahedral graph.
<pre>krackhardt_kite_graph([create_using])</pre>	Return the Krackhardt Kite Social Network.
<pre>moebius_kantor_graph([create_using])</pre>	Return the Moebius-Kantor graph.
octahedral_graph([create_using])	Return the Platonic Octahedral graph.
pappus_graph()	Return the Pappus graph.
<pre>petersen_graph([create_using])</pre>	Return the Petersen graph.
<pre>sedgewick_maze_graph([create_using])</pre>	Return a small maze with a cycle.
<pre>tetrahedral_graph([create_using])</pre>	Return the 3-regular Platonic Tetrahedral graph.
truncated_cube_graph([create_using])	Return the skeleton of the truncated cube.
<pre>truncated_tetrahedron_graph([create_using])</pre>	Return the skeleton of the truncated Platonic tetrahedron.
tutte_graph([create_using])	Return the Tutte graph.

# 6.3.1 networkx.make small graph

make\_small\_graph (graph\_description, create\_using=None)

Return the small graph described by graph\_description.

graph\_description is a list of the form [ltype,name,n,xlist]

Here ltype is one of "adjacencylist" or "edgelist", name is the name of the graph and n the number of nodes. This constructs a graph of n nodes with integer labels 0,..,n-1.

If ltype="adjacencylist" then xlist is an adjacency list with exactly n entries, in with the j'th entry (which can be empty) specifies the nodes connected to vertex j. e.g. the "square" graph C\_4 can be obtained by

```
>>> G=nx.make_small_graph(["adjacencylist","C_4",4,[[2,4],[1,3],[2,4],[1,3]]])
```

or, since we do not need to add edges twice,

```
>>> G=nx.make_small_graph(["adjacencylist","C_4",4,[[2,4],[3],[4],[]]])
```

If ltype="edgelist" then xlist is an edge list written as [[v1,w2],[v2,w2],...,[vk,wk]], where vj and wj integers in the range 1,...,n e.g. the "square" graph C\_4 can be obtained by

```
>>> G=nx.make_small_graph(["edgelist","C_4",4,[[1,2],[3,4],[2,3],[4,1]]])
```

Use the create\_using argument to choose the graph class/type.

### 6.3.2 networkx.LCF graph

LCF\_graph (n, shift\_list, repeats, create\_using=None)

Return the cubic graph specified in LCF notation.

LCF notation (LCF=Lederberg-Coxeter-Fruchte) is a compressed notation used in the generation of various cubic Hamiltonian graphs of high symmetry. See, for example, dodecahedral\_graph, desargues\_graph, hea-wood\_graph and pappus\_graph below.

**n (number of nodes)** The starting graph is the n-cycle with nodes 0,...,n-1. (The null graph is returned if n < 0.)

 $shift_list = [s1, s2, ..., sk]$ , a list of integer shifts mod n,

**repeats** integer specifying the number of times that shifts in shift\_list are successively applied to each v\_current in the n-cycle to generate an edge between v\_current and v\_current+shift mod n.

For v1 cycling through the n-cycle a total of k\*repeats with shift cycling through shiftlist repeats times connect v1 with v1+shift mod n

The utility graph  $K_{\{3,3\}}$ 

```
>>> G=nx.LCF_graph(6,[3,-3],3)
```

The Heawood graph

```
>>> G=nx.LCF_graph(14,[5,-5],7)
```

See http://mathworld.wolfram.com/LCFNotation.html for a description and references.

### 6.3.3 networkx.bull graph

**bull\_graph** (*create\_using=None*)
Return the Bull graph.

### 6.3.4 networkx.chvatal graph

```
chvatal_graph (create_using=None) Return the Chvatal graph.
```

# 6.3.5 networkx.cubical\_graph

```
cubical_graph (create_using=None)

Return the 3-regular Platonic Cubical graph.
```

### 6.3.6 networkx.desargues graph

```
desargues_graph (create_using=None)
Return the Desargues graph.
```

6.3. Small 191

### 6.3.7 networkx.diamond graph

**diamond\_graph** (*create\_using=None*)
Return the Diamond graph.

# 6.3.8 networkx.dodecahedral\_graph

dodecahedral\_graph (create\_using=None)
Return the Platonic Dodecahedral graph.

# 6.3.9 networkx.frucht\_graph

**frucht\_graph** (*create\_using=None*)
Return the Frucht Graph.

The Frucht Graph is the smallest cubical graph whose automorphism group consists only of the identity element.

# 6.3.10 networkx.heawood\_graph

heawood\_graph (create\_using=None)
Return the Heawood graph, a (3,6) cage.

# 6.3.11 networkx.house\_graph

house\_graph (create\_using=None)

Return the House graph (square with triangle on top).

### 6.3.12 networkx.house x graph

house\_x\_graph (create\_using=None)

Return the House graph with a cross inside the house square.

### 6.3.13 networkx.icosahedral graph

icosahedral\_graph(create\_using=None)

Return the Platonic Icosahedral graph.

# 6.3.14 networkx.krackhardt\_kite\_graph

krackhardt\_kite\_graph (create\_using=None)

Return the Krackhardt Kite Social Network.

A 10 actor social network introduced by David Krackhardt to illustrate: degree, betweenness, centrality, closeness, etc. The traditional labeling is: Andre=1, Beverley=2, Carol=3, Diane=4, Ed=5, Fernando=6, Garth=7, Heather=8, Ike=9, Jane=10.

# 6.3.15 networkx.moebius\_kantor\_graph

moebius\_kantor\_graph (create\_using=None)
 Return the Moebius-Kantor graph.

### 6.3.16 networkx.octahedral\_graph

octahedral\_graph (create\_using=None)
Return the Platonic Octahedral graph.

# 6.3.17 networkx.pappus\_graph

pappus\_graph()
Return the Pappus graph.

# 6.3.18 networkx.petersen\_graph

**petersen\_graph** (*create\_using=None*)
Return the Petersen graph.

# 6.3.19 networkx.sedgewick\_maze\_graph

 $\verb|sedgewick_maze_graph|| (\textit{create\_using} = None)$ 

Return a small maze with a cycle.

This is the maze used in Sedgewick,3rd Edition, Part 5, Graph Algorithms, Chapter 18, e.g. Figure 18.2 and following. Nodes are numbered 0,..,7

### 6.3.20 networkx.tetrahedral\_graph

tetrahedral\_graph (create\_using=None)
Return the 3-regular Platonic Tetrahedral graph.

### 6.3.21 networkx.truncated cube graph

truncated\_cube\_graph (create\_using=None)

Return the skeleton of the truncated cube.

### 6.3.22 networkx.truncated\_tetrahedron\_graph

truncated\_tetrahedron\_graph (create\_using=None)
Return the skeleton of the truncated Platonic tetrahedron.

# 6.3.23 networkx.tutte\_graph

**tutte\_graph** (*create\_using=None*)
Return the Tutte graph.

6.3. Small 193

# 6.4 Random Graphs

```
Return a random graph G \{n,p\}.
fast_gnp_random_graph(n, p[,
create using, seed])
gnp_random_graph(n, p[, create_using,
                                               Return a random graph G_{n,p}.
seed])
dense_gnm_random_graph(n, m[,
                                               Return the random graph G_{n,m}.
create_using, ...])
                                               Return the random graph G_{n,m}.
gnm_random_graph(n, m[, create_using,
seed])
erdos_renyi_graph(n, p[, create_using,
                                               Return a random graph G_{n,p}.
seed])
binomial_graph(n, p[, create_using, seed])
                                               Return a random graph G_{n,p}.
                                               Return a Newman-Watts-Strogatz small world graph.
newman_watts_strogatz_graph(n, k, p[,
...])
watts_strogatz_graph(n, k, p[, ...])
                                               Return a Watts-Strogatz small-world graph.
connected watts strogatz graph(n,
                                               Return a connected Watts-Strogatz small-world graph.
k, p[, ...])
random_regular_graph(d, n[,
                                               Return a random regular graph of n nodes each with degree d.
create using, seed])
barabasi albert graph(n, m[,
                                               Return random graph using Barabási-Albert preferential
create_using, seed])
                                               attachment model.
                                               Holme and Kim algorithm for growing graphs with powerlaw
powerlaw_cluster_graph(n, m, p[, ...])
random_lobster(n, p1, p2[, create_using,
                                               Return a random lobster.
seed])
random_shell_graph(constructor[, ...])
                                               Return a random shell graph for the constructor given.
random_powerlaw_tree(n[, gamma, ...])
                                               Return a tree with a powerlaw degree distribution.
random_powerlaw_tree_sequence(n[,
                                               Return a degree sequence for a tree with a powerlaw
gamma, ...])
                                               distribution.
```

### 6.4.1 networkx.fast\_gnp\_random\_graph

```
fast_gnp_random_graph (n, p, create_using=None, seed=None)
Return a random graph G_{n,p}.

The G_{n,p} graph choses each of the possible [n(n-1)]/2 edges with probability p.
Sometimes called Erdős-Rényi graph, or binomial graph.

Parameters n: int

The number of nodes.

p: float

Probability for edge creation.

create_using: graph, optional (default Graph)

Use specified graph as a container.

seed: int, optional

Seed for random number generator (default=None).
```

### **Notes**

This algorithm is O(n+m) where m is the expected number of edges m=p\*n\*(n-1)/2.

It should be faster than gnp\_random\_graph when p is small, and the expected number of edges is small, (sparse graph).

#### References

[R11]

# 6.4.2 networkx.gnp\_random\_graph

```
gnp\_random\_graph (n, p, create\_using=None, seed=None)

Return a random graph G_{n,p}.
```

Choses each of the possible [n(n-1)]/2 edges with probability p. This is the same as binomial\_graph and erdos\_renyi\_graph.

Sometimes called Erdős-Rényi graph, or binomial graph.

```
Parameters n: int
```

The number of nodes.

p: float

Probability for edge creation.

create\_using : graph, optional (default Graph)

Use specified graph as a container.

seed: int, optional

Seed for random number generator (default=None).

#### See Also:

```
fast_gnp_random_graph
```

#### **Notes**

This is an O(n^2) algorithm. For sparse graphs (small p) see fast\_gnp\_random\_graph.

#### References

[R14], [R15]

### 6.4.3 networkx.dense gnm random graph

```
{\tt dense\_gnm\_random\_graph} \ (\textit{n, m, create\_using=None, seed=None})
```

Return the random graph  $G_{n,m}$ .

Gives a graph picked randomly out of the set of all graphs with n nodes and m edges. This algorithm should be faster than gnm\_random\_graph for dense graphs.

#### Parameters n: int

The number of nodes.

m: int

The number of edges.

create\_using : graph, optional (default Graph)

Use specified graph as a container.

seed: int, optional

Seed for random number generator (default=None).

#### See Also:

gnm\_random\_graph

#### **Notes**

Algorithm by Keith M. Briggs Mar 31, 2006. Inspired by Knuth's Algorithm S (Selection sampling technique), in section 3.4.2 of

### References

[R7]

# 6.4.4 networkx.gnm\_random\_graph

```
gnm_random_graph (n, m, create_using=None, seed=None)
```

Return the random graph  $G_{n,m}$ .

Gives a graph picked randomly out of the set of all graphs with n nodes and m edges.

### Parameters n: int

The number of nodes.

m: int

The number of edges.

create\_using : graph, optional (default Graph)

Use specified graph as a container.

seed: int, optional

Seed for random number generator (default=None).

# 6.4.5 networkx.erdos\_renyi\_graph

```
erdos_renyi_graph (n, p, create_using=None, seed=None)
```

Return a random graph  $G_{n,p}$ .

Choses each of the possible [n(n-1)]/2 edges with probability p. This is the same as binomial\_graph and erdos\_renyi\_graph.

Sometimes called Erdős-Rényi graph, or binomial graph.

#### Parameters n: int

The number of nodes.

**p**: float

Probability for edge creation.

create\_using : graph, optional (default Graph)

Use specified graph as a container.

seed: int, optional

Seed for random number generator (default=None).

#### See Also:

```
fast_gnp_random_graph
```

### **Notes**

This is an O(n^2) algorithm. For sparse graphs (small p) see fast\_gnp\_random\_graph.

### References

[R8], [R9]

### 6.4.6 networkx.binomial\_graph

```
binomial_graph (n, p, create_using=None, seed=None)
```

Return a random graph  $G_{n,p}$ .

Choses each of the possible [n(n-1)]/2 edges with probability p. This is the same as binomial\_graph and erdos\_renyi\_graph.

Sometimes called Erdős-Rényi graph, or binomial graph.

#### Parameters n: int

The number of nodes.

**p**: float

Probability for edge creation.

create\_using : graph, optional (default Graph)

Use specified graph as a container.

seed: int, optional

Seed for random number generator (default=None).

#### See Also:

```
fast_gnp_random_graph
```

### **Notes**

This is an  $O(n^2)$  algorithm. For sparse graphs (small p) see fast\_gnp\_random\_graph.

#### References

[R3], [R4]

# 6.4.7 networkx.newman watts strogatz graph

**newman\_watts\_strogatz\_graph** (*n*, *k*, *p*, *create\_using=None*, *seed=None*) Return a Newman-Watts-Strogatz small world graph.

Parameters n: int

The number of nodes

k: int

Each node is connected to k nearest neighbors in ring topology

p: float

The probability of adding a new edge for each edge

create\_using : graph, optional (default Graph)

The graph instance used to build the graph.

seed: int, optional

seed for random number generator (default=None)

#### See Also:

```
watts_strogatz_graph
```

#### **Notes**

First create a ring over n nodes. Then each node in the ring is connected with its k nearest neighbors (k-1 neighbors if k is odd). Then shortcuts are created by adding new edges as follows: for each edge u-v in the underlying "n-ring with k nearest neighbors" with probability p add a new edge u-w with randomly-chosen existing node w. In contrast with watts\_strogatz\_graph(), no edges are removed.

### References

[R19]

### 6.4.8 networkx.watts strogatz graph

```
watts_strogatz_graph (n, k, p, create_using=None, seed=None)
Return a Watts-Strogatz small-world graph.
```

Parameters n: int

The number of nodes

k: int

Each node is connected to k nearest neighbors in ring topology

p: float

The probability of rewiring each edge

create\_using : graph, optional (default Graph)

The graph instance used to build the graph.

seed: int, optional

Seed for random number generator (default=None)

#### See Also:

```
newman_watts_strogatz_graph, connected_watts_strogatz_graph
```

### **Notes**

First create a ring over n nodes. Then each node in the ring is connected with its k nearest neighbors (k-1 neighbors if k is odd). Then shortcuts are created by replacing some edges as follows: for each edge u-v in the underlying "n-ring with k nearest neighbors" with probability p replace it with a new edge u-w with uniformly random choice of existing node w.

In contrast with newman\_watts\_strogatz\_graph(), the random rewiring does not increase the number of edges. The rewired graph is not guaranteed to be connected as in connected\_watts\_strogatz\_graph().

#### References

[R26]

# 6.4.9 networkx.connected\_watts\_strogatz\_graph

```
connected_watts_strogatz_graph (n, k, p, tries=100, create_using=None, seed=None) Return a connected Watts-Strogatz small-world graph.
```

Attempt to generate a connected realization by repeated generation of Watts-Strogatz small-world graphs. An exception is raised if the maximum number of tries is exceeded.

#### Parameters n: int

The number of nodes

k: int

Each node is connected to k nearest neighbors in ring topology

p: float

The probability of rewiring each edge

tries: int

Number of attempts to generate a connected graph.

create\_using : graph, optional (default Graph)

The graph instance used to build the graph.

seed: int, optional

The seed for random number generator.

See Also:

newman\_watts\_strogatz\_graph, watts\_strogatz\_graph

# 6.4.10 networkx.random\_regular\_graph

random\_regular\_graph (d, n, create\_using=None, seed=None)

Return a random regular graph of n nodes each with degree d.

The resulting graph G has no self-loops or parallel edges.

Parameters d: int

Degree

**n**: integer

Number of nodes. The value of n\*d must be even.

create\_using : graph, optional (default Graph)

The graph instance used to build the graph.

seed: hashable object

The seed for random number generator.

#### **Notes**

The nodes are numbered form 0 to n-1.

Kim and Vu's paper [R22] shows that this algorithm samples in an asymptotically uniform way from the space of random graphs when  $d = O(n^{**}(1/3-epsilon))$ .

### References

[R21], [R22]

### 6.4.11 networkx.barabasi\_albert\_graph

barabasi\_albert\_graph (n, m, create\_using=None, seed=None)

Return random graph using Barabási-Albert preferential attachment model.

A graph of n nodes is grown by attaching new nodes each with m edges that are preferentially attached to existing nodes with high degree.

Parameters n: int

Number of nodes

 $\mathbf{m}$ : int

Number of edges to attach from a new node to existing nodes

```
create_using : graph, optional (default Graph)
```

The graph instance used to build the graph.

seed: int, optional

Seed for random number generator (default=None).

Returns G: Graph

#### **Notes**

The initialization is a graph with with m nodes and no edges.

### References

[R2]

# 6.4.12 networkx.powerlaw\_cluster\_graph

```
powerlaw_cluster_graph (n, m, p, create_using=None, seed=None)
```

Holme and Kim algorithm for growing graphs with powerlaw degree distribution and approximate average clustering.

#### Parameters n: int

the number of nodes

m: int

the number of random edges to add for each new node

**p**: float,

Probability of adding a triangle after adding a random edge

create\_using : graph, optional (default Graph)

The graph instance used to build the graph.

seed: int, optional

Seed for random number generator (default=None).

#### **Notes**

The average clustering has a hard time getting above a certain cutoff that depends on m. This cutoff is often quite low. Note that the transitivity (fraction of triangles to possible triangles) seems to go down with network size.

It is essentially the Barabási-Albert (B-A) growth model with an extra step that each random edge is followed by a chance of making an edge to one of its neighbors too (and thus a triangle).

This algorithm improves on B-A in the sense that it enables a higher average clustering to be attained if desired.

It seems possible to have a disconnected graph with this algorithm since the initial m nodes may not be all linked to a new node on the first iteration like the B-A model.

### References

[R20]

# 6.4.13 networkx.random\_lobster

```
random_lobster (n, p1, p2, create_using=None, seed=None)
```

Return a random lobster.

A lobster is a tree that reduces to a caterpillar when pruning all leaf nodes.

A caterpillar is a tree that reduces to a path graph when pruning all leaf nodes (p2=0).

#### Parameters n: int

The expected number of nodes in the backbone

**p1**: float

Probability of adding an edge to the backbone

**p2**: float

Probability of adding an edge one level beyond backbone

create\_using : graph, optional (default Graph)

The graph instance used to build the graph.

seed: int, optional

Seed for random number generator (default=None).

# 6.4.14 networkx.random\_shell\_graph

random\_shell\_graph (constructor, create\_using=None, seed=None)

Return a random shell graph for the constructor given.

#### Parameters constructor: a list of three-tuples:

(n,m,d) for each shell starting at the center shell.

 $\mathbf{n}$ : int

The number of nodes in the shell

m: int

The number or edges in the shell

d: float

The ratio of inter-shell (next) edges to intra-shell edges. d=0 means no intra shell edges, d=1 for the last shell

create\_using : graph, optional (default Graph)

The graph instance used to build the graph.

seed: int, optional

Seed for random number generator (default=None).

# **Examples**

```
>>> constructor=[(10,20,0.8),(20,40,0.8)]
>>> G=nx.random_shell_graph(constructor)
```

# 6.4.15 networkx.random\_powerlaw\_tree

```
random_powerlaw_tree (n, gamma=3, create_using=None, seed=None, tries=100)
Return a tree with a powerlaw degree distribution.
```

```
Parameters n: int,

The number of nodes

gamma: float

Exponent of the power-law

create_using: graph, optional (default Graph)

The graph instance used to build the graph.

seed: int, optional

Seed for random number generator (default=None).

tries: int
```

Number of attempts to adjust sequence to make a tree

### **Notes**

A trial powerlaw degree sequence is chosen and then elements are swapped with new elements from a powerlaw distribution until the sequence makes a tree (#edges=#nodes-1).

# 6.4.16 networkx.random\_powerlaw\_tree\_sequence

```
random_powerlaw_tree_sequence (n, gamma=3, seed=None, tries=100)
Return a degree sequence for a tree with a powerlaw distribution.
```

Number of attempts to adjust sequence to make a tree

```
Parameters n: int,

The number of nodes

gamma: float

Exponent of the power-law

seed: int, optional

Seed for random number generator (default=None).

tries: int
```

6.4. Random Graphs

#### **Notes**

A trial powerlaw degree sequence is chosen and then elements are swapped with new elements from a powerlaw distribution until the sequence makes a tree (#edges=#nodes-1).

# 6.5 Degree Sequence

```
configuration_model(deg_sequence[Return a random graph with the given degree sequence.
...])
expected_degree_graph(w[,
                                       Return a random graph G(w) with expected degrees given by w.
create_using, seed])
havel_hakimi_graph(deg_sequence[, Return a simple graph with given degree sequence, constructed using
create_using])
degree_sequence_tree(deg_sequence)/Jake a tree for the given degree sequence.
is_valid_degree_sequence(deg_sequence)True if deg_sequence is a valid sequence of integer degrees
create_degree_sequence(n,
                                       Attempt to create a valid degree sequence of length n using specified
                                       function sfunction(n,**kwds).
**kwds[, ...])
double edge swap(G[, nswap])
                                       Attempt nswap double-edge swaps on the graph G.
connected double edge swap(G[, Attempt nswap double-edge swaps on the graph G.
nswap])
li_smax_graph(degree_seq[,
                                       Generates a graph based with a given degree sequence and
create_using])
                                       maximizing the s-metric.
                                       Return the s-metric of graph.
s_metric(G)
```

# 6.5.1 networkx.configuration\_model

configuration\_model (deg\_sequence, create\_using=None, seed=None)

Return a random graph with the given degree sequence.

The configuration model generates a random pseudograph (graph with parallel edges and self loops) by randomly assigning edges to match the given degree sequence.

Parameters deg sequence : list of integers

Each list entry corresponds to the degree of a node.

create\_using : graph, optional (default MultiGraph)

Return graph of this type. The instance will be cleared.

seed: hashable object, optional

Seed for random number generator.

**Returns G**: MultiGraph

A graph with the specified degree sequence. Nodes are labeled starting at 0 with an index corresponding to the position in deg\_sequence.

#### Raises NetworkXError:

If the degree sequence does not have an even sum.

#### See Also:

is\_valid\_degree\_sequence

### **Notes**

As described by Newman [R5].

A non-graphical degree sequence (not realizable by some simple graph) is allowed since this function returns graphs with self loops and parallel edges. An exception is raised if the degree sequence does not have an even sum.

This configuration model construction process can lead to duplicate edges and loops. You can remove the self-loops and parallel edges (see below) which will likely result in a graph that doesn't have the exact degree sequence specified. This "finite-size effect" decreases as the size of the graph increases.

#### References

[R5]

# **Examples**

```
>>> from networkx.utils import powerlaw_sequence
>>> z=nx.create_degree_sequence(100,powerlaw_sequence)
>>> G=nx.configuration_model(z)

To remove parallel edges:
>>> G=nx.Graph(G)

To remove self loops:
>>> G.remove_edges_from(G.selfloop_edges())
```

### 6.5.2 networkx.expected degree graph

```
Parameters w: list
```

The list of expected degrees.

create\_using : graph, optional (default Graph)

Return graph of this type. The instance will be cleared.

seed: hashable object, optional

The seed for the random number generator.

#### References

[R10]

# **Examples**

```
>>> z=[10 for i in range(100)]
>>> G=nx.expected_degree_graph(z)
```

# 6.5.3 networkx.havel\_hakimi\_graph

havel\_hakimi\_graph (deg\_sequence, create\_using=None)

Return a simple graph with given degree sequence, constructed using the Havel-Hakimi algorithm.

#### Parameters deg\_sequence: list of integers :

Each integer corresponds to the degree of a node (need not be sorted).

create\_using : graph, optional (default Graph)

Return graph of this type. The instance will be cleared. Multigraphs and directed graphs are not allowed.

#### Raises NetworkXException:

For a non-graphical degree sequence (i.e. one not realizable by some simple graph).

#### **Notes**

The Havel-Hakimi algorithm constructs a simple graph by successively connecting the node of highest degree to other nodes of highest degree, resorting remaining nodes by degree, and repeating the process. The resulting graph has a high degree-associativity. Nodes are labeled 1,..., len(deg\_sequence), corresponding to their position in deg\_sequence.

See Theorem 1.4 in [chartrand-graphs-1996]. This algorithm is also used in the function is\_valid\_degree\_sequence.

### References

[R17]

### 6.5.4 networkx.degree sequence tree

degree\_sequence\_tree (deg\_sequence, create\_using=None)

Make a tree for the given degree sequence.

A tree has #nodes-#edges=1 so the degree sequence must have len(deg\_sequence)-sum(deg\_sequence)/2=1

### 6.5.5 networkx.is valid degree sequence

#### is\_valid\_degree\_sequence (deg\_sequence)

Return True if deg\_sequence is a valid sequence of integer degrees equal to the degree sequence of some simple graph.

•deg\_sequence: degree sequence, a list of integers with each entry corresponding to the degree of a node (need not be sorted). A non-graphical degree sequence (i.e. one not realizable by some simple graph) will raise an exception.

See Theorem 1.4 in [R18]. This algorithm is also used in havel\_hakimi\_graph()

### References

[R18]

# 6.5.6 networkx.create degree sequence

```
create_degree_sequence (n, sfunction=None, max_tries=50, **kwds)
```

Attempt to create a valid degree sequence of length n using specified function sfunction(n,\*\*kwds).

#### Parameters n: int

Length of degree sequence = number of nodes

#### sfunction: function:

Function which returns a list of n real or integer values. Called as "sfunction(n,\*\*kwds)".

#### max tries: int:

Max number of attempts at creating valid degree sequence.

### **Notes**

Repeatedly create a degree sequence by calling sfunction(n,\*\*kwds) until achieving a valid degree sequence. If unsuccessful after max\_tries attempts, raise an exception.

For examples of sfunctions that return sequences of random numbers, see networkx. Utils.

# **Examples**

```
>>> from networkx.utils import uniform_sequence
>>> seq=nx.create_degree_sequence(10,uniform_sequence)
```

# 6.5.7 networkx.double\_edge\_swap

```
double_edge_swap(G, nswap=1)
```

Attempt nswap double-edge swaps on the graph G.

Return count of successful swaps. The graph G is modified in place. A double-edge swap removes two randomly choseen edges u-v and x-y and creates the new edges u-x and v-y:

```
u--v u v
becomes | |
x--y x y
```

If either the edge u-x or v-y already exist no swap is performed so the actual count of swapped edges is always <= nswap

Does not enforce any connectivity constraints.

# 6.5.8 networkx.connected double edge swap

```
connected_double_edge_swap(G, nswap=1)
```

Attempt nswap double-edge swaps on the graph G.

Returns count of successful swaps. Enforces connectivity. The graph G is modified in place.

#### **Notes**

A double-edge swap removes two randomly choseen edges u-v and x-y and creates the new edges u-x and v-y:

If either the edge u-x or v-y already exist no swap is performed so the actual count of swapped edges is always <= nswap

The initial graph G must be connected and the resulting graph is connected.

#### References

[R6]

# 6.5.9 networkx.li\_smax\_graph

# li\_smax\_graph (degree\_seq, create\_using=None)

Generates a graph based with a given degree sequence and maximizing the s-metric. Experimental implementation

Maximum s-metrix means that high degree nodes are connected to high degree nodes.

•degree\_seq: degree sequence, a list of integers with each entry corresponding to the degree of a node.

A non-graphical degree sequence raises an Exception.

#### Reference:

The algorithm:

```
STEP 0 - Initialization
A = \{0\}
B = \{1, 2, 3, ..., n\}
0 = \{(i; j), ..., (k, l), ...\} where i < j, i <= k < l and
        d_i * d_j >= d_k * d_l
wA = d 1
dB = sum(degrees)
STEP 1 - Link selection
(a) If |0| = 0 TERMINATE. Return graph A.
(b) Select element(s) (i, j) in O having the largest d_i * d_j , if for
        any i or j either w_i = 0 or w_j = 0 delete (i, j) from 0
(c) If there are no elements selected go to (a).
(d) Select the link (i, j) having the largest value w_i (where for each
        (i, j) w_i is the smaller of w_i and w_j), and proceed to STEP 2.
STEP 2 - Link addition
Type 1: i in A and j in B.
        Add j to the graph A and remove it from the set B add a link
        (i, j) to the graph A. Update variables:
        wA = wA + d_j - 2 and dB = dB - d_j
        Decrement w_i and w_j with one. Delete (i, j) from O
Type 2: i and j in A.
    Check Tree Condition: If dB = 2 * |B| - wA.
        Delete (i, j) from O, continue to STEP 3
    Check Disconnected Cluster Condition: If wA = 2.
        Delete (i, j) from O, continue to STEP 3
    Add the link (i, j) to the graph A
   Decrement w_i and w_j with one, and wA = wA -2
STEP 3
    Go to STEP 1
```

The article states that the algorithm will result in a maximal s-metric. This implementation can not guarantee such maximality. I may have misunderstood the algorithm, but I can not see how it can be anything but a heuristic. Please contact me at sundsdal@gmail.com if you can provide python code that can guarantee maximality. Several optimizations are included in this code and it may be hard to read. Commented code to come.

### 6.5.10 networkx.s\_metric

#### s metric (G)

Return the s-metric of graph.

The s-metric is defined as the sum of the products deg(u)\*deg(v) for every edge (u,v) in G.

#### Parameters G: graph

The graph used to compute the s-metric.

#### Returns s: float

The s-metric of the graph.

#### References

[R23]

# 6.6 Directed

gn_graph(n[, kernel, create_using, seed])	Return the GN digraph with n nodes.
<pre>gnr_graph(n, p[, create_using, seed])</pre>	Return the GNR digraph with n nodes and redirection
	probability p.
<pre>gnc_graph(n[, create_using, seed])</pre>	Return the GNC digraph with n nodes.
scale_free_graph(n[, alpha, beta, gamma,	Return a scale free directed graph.
])	2 1

# 6.6.1 networkx.gn\_graph

```
gn_graph (n, kernel=None, create_using=None, seed=None)
Return the GN digraph with n nodes.
```

The GN (growing network) graph is built by adding nodes one at a time with a link to one previously added node. The target node for the link is chosen with probability based on degree. The default attachment kernel is a linear function of degree.

The graph is always a (directed) tree.

Parameters n: int

The number of nodes for the generated graph.

kernel: function

The attachment kernel.

create\_using : graph, optional (default DiGraph)

Return graph of this type. The instance will be cleared.

seed: hashable object, optional

The seed for the random number generator.

# References

[R12]

# **Examples**

```
>>> D=nx.gn_graph(10)  # the GN graph
>>> G=D.to_undirected()  # the undirected version
```

To specify an attachment kernel use the kernel keyword

```
>>> D=nx.gn_graph(10,kernel=lambda x:x**1.5) # A_k=k^1.5
```

# 6.6.2 networkx.gnr\_graph

```
gnr_graph (n, p, create_using=None, seed=None)
```

Return the GNR digraph with n nodes and redirection probability p.

The GNR (growing network with redirection) graph is built by adding nodes one at a time with a link to one previously added node. The previous target node is chosen uniformly at random. With probability p the link is instead "redirected" to the successor node of the target. The graph is always a (directed) tree.

#### Parameters n: int

The number of nodes for the generated graph.

p: float

The redirection probability.

create\_using : graph, optional (default DiGraph)

Return graph of this type. The instance will be cleared.

seed: hashable object, optional

The seed for the random number generator.

#### References

[R16]

# **Examples**

```
>>> D=nx.gnr_graph(10,0.5) # the GNR graph
>>> G=D.to_undirected() # the undirected version
```

# 6.6.3 networkx.gnc\_graph

```
gnc_graph (n, create_using=None, seed=None)
```

Return the GNC digraph with n nodes.

The GNC (growing network with copying) graph is built by adding nodes one at a time with a links to one previously added node (chosen uniformly at random) and to all of that node's successors.

Parameters n: int

The number of nodes for the generated graph.

create\_using : graph, optional (default DiGraph)

Return graph of this type. The instance will be cleared.

seed: hashable object, optional

The seed for the random number generator.

### References

[R13]

6.6. Directed 211

# 6.6.4 networkx.scale free graph

Return a scale free directed graph.

Parameters n: integer

Number of nodes in graph

alpha: float

Probability for adding a new node connected to an existing node chosen randomly according to the in-degree distribution.

beta: float

Probability for adding an edge between two existing nodes. One existing node is chosen randomly according the in-degree distribution and the other chosen randomly according to the out-degree distribution.

gamma: float

Probability for adding a new node conecgted to an existing node chosen randomly according to the out-degree distribution.

delta\_in: float

Bias for choosing ndoes from in-degree distribution.

delta\_out : float

Bias for choosing ndoes from out-degree distribution.

create\_using : graph, optional (default MultiDiGraph)

Use this graph instance to start the process (default=3-cycle).

seed: integer, optional

Seed for random number generator

#### **Notes**

The sum of alpha, beta, and gamma must be 1.

### References

[R24]

### **Examples**

```
>>> G=nx.scale_free_graph(100)
```

# 6.7 Geometric

random\_geometric\_graph(n, radius[, ...]) Random geometric graph in the unit cube

#### 6.7.1 networkx.random geometric graph

random\_geometric\_graph (n, radius, create\_using=None, repel=0.0, verbose=False, dim=2)
Random geometric graph in the unit cube

Returned Graph has added attribute G.pos which is a dict keyed by node to the position tuple for the node.

# 6.8 Hybrid

kl_connected_subgraph(G, k, l[, low_memory,	Returns the maximum locally (k,l) connected subgraph
])	of G.
$is_kl\_connected(G, k, l[, low\_memory])$	Returns True if G is kl connected

#### 6.8.1 networkx.kl connected subgraph

**kl\_connected\_subgraph** (*G*, *k*, *l*, *low\_memory=False*, *same\_as\_graph=False*)

Returns the maximum locally (k,l) connected subgraph of G.

(k,l)-connected subgraphs are presented by Fan Chung and Li in "The Small World Phenomenon in hybrid power law graphs" to appear in "Complex Networks" (Ed. E. Ben-Naim) Lecture Notes in Physics, Springer (2004)

low\_memory=True then use a slightly slower, but lower memory version same\_as\_graph=True then return a tuple with subgraph and pflag for if G is kl-connected

#### 6.8.2 networkx.is kl connected

```
is_kl_connected (G, k, l, low_memory=False)
    Returns True if G is kl connected
```

# 6.9 Bipartite

```
bipartite_configuration_model(aseqReturn a random bipartite graph from two given degree sequences. bseq[, ...])
bipartite_havel_hakimi_graph(aseq, Return a bipartite graph from two given degree sequences bseq[, ...])
bipartite_reverse_havel_hakimi_gRetum(aschipartite graph from two given degree sequences bseq)
bipartite_alternating_havel_hakiRetumra_bipartite graph from two given degree sequences bipartite_preferential_attachmenCreateapbipartite graph with a preferential attachment model from p)
a given single degree sequence.
bipartite_random_regular_graph(d, UNTESTED: Generate a random bipartite graph.
n[, ...])
```

6.7. Geometric 213

#### 6.9.1 networkx.bipartite configuration model

bipartite\_configuration\_model(aseq, bseq, create\_using=None, seed=None)

Return a random bipartite graph from two given degree sequences.

Parameters aseq: list or iterator

Degree sequence for node set A.

bseq: list or iterator

Degree sequence for node set B.

create\_using : NetworkX graph instance, optional

Return graph of this type.

seed: integer, optional

Seed for random number generator.

Nodes from the set A are connected to nodes in the set B by :

choosing randomly from the possible free stubs, one in A and :

one in B.:

#### **Notes**

The sum of the two sequences must be equal: sum(aseq)=sum(bseq) If no graph type is specified use MultiGraph with parallel edges. If you want a graph with no parallel edges use create\_using=Graph() but then the resulting degree sequences might not be exact.

#### 6.9.2 networkx.bipartite havel hakimi graph

bipartite\_havel\_hakimi\_graph (aseq, bseq, create\_using=None)

Return a bipartite graph from two given degree sequences using a Havel-Hakimi style construction.

Parameters aseq: list or iterator

Degree sequence for node set A.

**bseq**: list or iterator

Degree sequence for node set B.

create\_using: NetworkX graph instance, optional

Return graph of this type.

Nodes from the set A are connected to nodes in the set B by :

connecting the highest degree nodes in set A to:

the highest degree nodes in set B until all stubs are connected. :

#### **Notes**

The sum of the two sequences must be equal: sum(aseq)=sum(bseq) If no graph type is specified use MultiGraph with parallel edges. If you want a graph with no parallel edges use create\_using=Graph() but then the resulting degree sequences might not be exact.

#### 6.9.3 networkx.bipartite reverse havel hakimi graph

bipartite\_reverse\_havel\_hakimi\_graph (aseq, bseq, create\_using=None)

Return a bipartite graph from two given degree sequences using a Havel-Hakimi style construction.

Parameters aseq: list or iterator

Degree sequence for node set A.

**bseq**: list or iterator

Degree sequence for node set B.

create\_using: NetworkX graph instance, optional

Return graph of this type.

Nodes from the set A are connected to nodes in the set B by :

connecting the highest degree nodes in set A to:

the lowest degree nodes in set B until all stubs are connected. :

#### **Notes**

The sum of the two sequences must be equal: sum(aseq)=sum(bseq) If no graph type is specified use MultiGraph with parallel edges. If you want a graph with no parallel edges use create\_using=Graph() but then the resulting degree sequences might not be exact.

# 6.9.4 networkx.bipartite alternating havel hakimi graph

bipartite\_alternating\_havel\_hakimi\_graph(aseq, bseq, create\_using=None)

Return a bipartite graph from two given degree sequences using a alternating Havel-Hakimi style construction.

Parameters aseq: list or iterator

Degree sequence for node set A.

**bseq**: list or iterator

Degree sequence for node set B.

**create\_using**: NetworkX graph instance, optional

Return graph of this type.

Nodes from the set A are connected to nodes in the set B by :

connecting the highest degree nodes in set A to:

alternatively the highest and the lowest degree nodes in set:

B until all stubs are connected. :

#### **Notes**

The sum of the two sequences must be equal: sum(aseq)=sum(bseq) If no graph type is specified use MultiGraph with parallel edges. If you want a graph with no parallel edges use create\_using=Graph() but then the resulting degree sequences might not be exact.

6.9. Bipartite 215

#### 6.9.5 networkx.bipartite preferential attachment graph

```
bipartite_preferential_attachment_graph (aseq, p, create_using=None, seed=None) Create a bipartite graph with a preferential attachment model from a given single degree sequence.
```

Parameters aseq: list or iterator

Degree sequence for node set A.

p: float

Probability that a new bottom node is added.

create\_using: NetworkX graph instance, optional

Return graph of this type.

seed: integer, optional

Seed for random number generator.

#### **Notes**

```
@article{guillaume-2004-bipartite, author = {Jean-Loup Guillaume and Matthieu Latapy}, title = {Bipartite structure of all complex networks}, journal = {Inf. Process. Lett.}, volume = {90}, number = {5}, year = {2004}, issn = {0020-0190}, pages = {215-221}, doi = {http://dx.doi.org/10.1016/j.ipl.2004.03.007}, publisher = {Elsevier North-Holland, Inc.}, address = {Amsterdam, The Netherlands, The Netherlands}, }
```

# 6.9.6 networkx.bipartite\_random\_regular\_graph

```
bipartite_random_regular_graph (d, n, create_using=None, seed=None) UNTESTED: Generate a random bipartite graph.
```

```
Parameters d: integer
```

Degree of graph.

n: integer

Number of nodes in graph.

create\_using : NetworkX graph instance, optional

Return graph of this type.

seed: integer, optional

Seed for random number generator.

#### **Notes**

Nodes are numbered 0...n-1.

#### Restrictions on n and d:

- n must be even
- n > = 2\*d

Algorithm inspired by random\_regular\_graph()

# LINEAR ALGEBRA

# 7.1 Spectrum

adj_matrix(G[, nodelist])	Return adjacency matrix of graph as a numpy matrix.
laplacian(G[, nodelist])	Return standard combinatorial Laplacian of G as a numpy matrix.
normalized_laplacian(G[, nodelist])	Return normalized Laplacian of G as a numpy matrix.
$laplacian\_spectrum(G)$	Return eigenvalues of the Laplacian of G
$ ext{adjacency\_spectrum}(G)$	Return eigenvalues of the adjacency matrix of G

# 7.1.1 networkx.adj\_matrix

#### adj\_matrix(G, nodelist=None)

Return adjacency matrix of graph as a numpy matrix.

This just calls networkx.convert.to\_numpy\_matrix.

If you want a pure python adjacency matrix representation try networkx.convert.to\_dict\_of\_dicts with weighted=False, which will return a dictionary-of-dictionaries format that can be addressed as a sparse matrix.

### 7.1.2 networkx.laplacian

#### laplacian (G, nodelist=None)

Return standard combinatorial Laplacian of G as a numpy matrix.

Return the matrix L = D - A, where

D is the diagonal matrix in which the i'th entry is the degree of node i A is the adjacency matrix.

# 7.1.3 networkx.normalized\_laplacian

#### normalized\_laplacian (G, nodelist=None)

Return normalized Laplacian of G as a numpy matrix.

See Spectral Graph Theory by Fan Chung-Graham. CBMS Regional Conference Series in Mathematics, Number 92, 1997.

# 7.1.4 networkx.laplacian\_spectrum

# ${\tt laplacian\_spectrum}\,(G)$

Return eigenvalues of the Laplacian of G

# 7.1.5 networkx.adjacency\_spectrum

# $\verb"adjacency_spectrum"\,(G)$

Return eigenvalues of the adjacency matrix of G

# CONVERTING TO AND FROM OTHER FORMATS

#### 8.1 Convert

This module provides functions to convert NetworkX graphs to and from other formats.

The preferred way of converting data to a NetworkX graph is through the graph constuctor. The constructor calls the from\_whatever() function which attempts to guess the input type and convert it automatically.

#### 8.1.1 Examples

Create a 10 node random graph from a numpy matrix

```
>>> import numpy
>>> a=numpy.reshape(numpy.random.random_integers(0,1,size=100),(10,10))
>>> D=nx.DiGraph(a)

or equivalently
>>> D=nx.from_whatever(a,create_using=nx.DiGraph())

Create a graph with a single edge from a dictionary of dictionaries
>>> d={0: {1: 1}} # dict-of-dicts single edge (0,1)
>>> G=nx.Graph(d)
```

#### 8.1.2 See Also

For graphviz dot formats see networkx.drawing.nx\_pygraphviz or networkx.drawing.nx\_pydot.

# 8.2 Functions

<pre>from_whatever(thing[, create_using,])</pre>	Make a NetworkX graph from an known type.
<pre>to_dict_of_lists(G[, nodelist])</pre>	Return adjacency representation of graph as a dictionary of
	lists
<pre>from_dict_of_lists(d[, create_using])</pre>	Return a graph from a dictionary of lists.
to_dict_of_dicts(G[, nodelist,	Return adjacency representation of graph as a dictionary of
edge_data])	dictionaries
<pre>from_dict_of_dicts(d[, create_using,</pre>	Return a graph from a dictionary of dictionaries.
])	
$to\_edgelist(G[, nodelist])$	Return a list of edges in the graph.
<pre>from_edgelist(edgelist[, create_using])</pre>	Return a graph from a list of edges.
to_numpy_matrix(G[, nodelist, dtype,	Return the graph adjacency matrix as a NumPy matrix.
order])	
<pre>from_numpy_matrix(A[, create_using])</pre>	Return a graph from numpy matrix adjacency list.
to_scipy_sparse_matrix(G[, nodelist,	Return the graph adjacency matrix as a SciPy sparse matrix.
dtype])	
from_scipy_sparse_matrix(A[,	Return a graph from scipy sparse matrix adjacency list.
create_using])	

#### 8.2.1 networkx.from whatever

from\_whatever (thing, create\_using=None, multigraph\_input=False)

Make a NetworkX graph from an known type.

The preferred way to call this is automatically from the class constructor

```
>>> d={0: {1: {'weight':1}}} # dict-of-dicts single edge (0,1)
>>> G=nx.Graph(d)
instead of the equivalent
```

```
>>> G=nx.from_dict_of_dicts(d)
```

Parameters thing: a object to be converted

**Current known types are:** any NetworkX graph dict-of-dicts dist-of-lists list of edges numpy matrix numpy ndarray scipy sparse matrix pygraphviz agraph

create\_using : NetworkX graph

Use specified graph for result. Otherwise a new graph is created.

multigraph\_input : bool (default False)

If True and thing is a dict\_of\_dicts, try to create a multigraph assuming dict\_of\_dict\_of\_lists. If thing and create\_using are both multigraphs then create a multigraph from a multigraph.

# 8.2.2 networkx.to dict of lists

```
to_dict_of_lists(G, nodelist=None)
```

Return adjacency representation of graph as a dictionary of lists

Parameters G: graph

A NetworkX graph

nodelist: list

Use only nodes specified in nodelist

#### **Notes**

Completely ignores edge data for MultiGraph and MultiDiGraph.

# 8.2.3 networkx.from dict of lists

from\_dict\_of\_lists(d, create\_using=None)

Return a graph from a dictionary of lists.

Parameters d: dictionary of lists

A dictionary of lists adjacency representation.

create\_using : NetworkX graph

Use specified graph for result. Otherwise a new graph is created.

# **Examples**

```
>>> dol= {0:[1]} # single edge (0,1)
>>> G=nx.from_dict_of_lists(dol)
```

or >>> G=nx.Graph(dol) # use Graph constructor

# 8.2.4 networkx.to dict of dicts

to\_dict\_of\_dicts (G, nodelist=None, edge\_data=None)

Return adjacency representation of graph as a dictionary of dictionaries

**Parameters G**: graph

A NetworkX graph

nodelist : list

Use only nodes specified in nodelist

edge data: list, optional

If provided, the value of the dictionary will be set to edge\_data for all edges. This is useful to make an adjacency matrix type representation with 1 as the edge data. If edgedata is None, the edgedata in G is used to fill the values. If G is a multigraph, the edgedata is a dict for each pair (u,v).

# 8.2.5 networkx.from\_dict\_of\_dicts

**from\_dict\_of\_dicts** (*d*, *create\_using=None*, *multigraph\_input=False*)

Return a graph from a dictionary of dictionaries.

8.2. Functions 221

**Parameters d**: dictionary of dictionaries

A dictionary of dictionaries adjacency representation.

create\_using : NetworkX graph

Use specified graph for result. Otherwise a new graph is created.

multigraph input: bool (default False)

When True, the values of the inner dict are assumed to be containers of edge data for multiple edges. Otherwise this routine assumes the edge data are singletons.

#### **Examples**

```
>>> dod= {0: {1:{'weight':1}}} # single edge (0,1)
>>> G=nx.from_dict_of_dicts(dod)
```

or >>> G=nx.Graph(dod) # use Graph constructor

# 8.2.6 networkx.to\_edgelist

to\_edgelist (*G*, nodelist=None)

Return a list of edges in the graph.

Parameters G: graph

A NetworkX graph

nodelist: list

Use only nodes specified in nodelist

### 8.2.7 networkx.from\_edgelist

**from\_edgelist** (*edgelist*, *create\_using=None*)

Return a graph from a list of edges.

Parameters edgelist: list or iterator

Edge tuples

create\_using : NetworkX graph

Use specified graph for result. Otherwise a new graph is created.

# **Examples**

```
>>> edgelist= [(0,1)] # single edge (0,1)
>>> G=nx.from_edgelist(edgelist)
```

or >>> G=nx.Graph(edgelist) # use Graph constructor

# 8.2.8 networkx.to\_numpy\_matrix

to\_numpy\_matrix (*G*, nodelist=None, dtype=None, order=None)
Return the graph adjacency matrix as a NumPy matrix.

Parameters G: graph

The NetworkX graph used to construct the NumPy matrix.

nodelist: list, optional

The rows and columns are ordered according to the nodes in *nodelist*. If *nodelist* is None, then the ordering is produced by G.nodes().

dtype: NumPy data-type, optional

A valid NumPy dtype used to initialize the array. If None, then the NumPy default is used.

order: {'C', 'F'}, optional

Whether to store multidimensional data in C- or Fortran-contiguous (row- or columnwise) order in memory. If None, then the NumPy default is used.

Returns M: NumPy matrix

Graph adjacency matrix.

#### **Notes**

The matrix entries are populated using the 'weight' edge attribute. When an edge does not have the 'weight' attribute, the value of the entry is 1. For multiple edges, the values of the entries are the sums of the edge attributes for each edge.

When *nodelist* does not contain every node in G, the matrix is built from the subgraph of G that is induced by the nodes in *nodelist*.

# **Examples**

# 8.2.9 networkx.from\_numpy\_matrix

from\_numpy\_matrix(A, create\_using=None)

Return a graph from numpy matrix adjacency list.

**Parameters A**: numpy matrix

An adjacency matrix representation of a graph

8.2. Functions 223

create\_using : NetworkX graph

Use specified graph for result. The default is Graph()

#### **Examples**

```
>>> import numpy
>>> A=numpy.matrix([[1,1],[2,1]])
>>> G=nx.from_numpy_matrix(A)
```

# 8.2.10 networkx.to\_scipy\_sparse\_matrix

```
to_scipy_sparse_matrix (G, nodelist=None, dtype=None)
Return the graph adjacency matrix as a SciPy sparse matrix.
```

Parameters G: graph

The NetworkX graph used to construct the NumPy matrix.

nodelist: list, optional

The rows and columns are ordered according to the nodes in *nodelist*. If *nodelist* is None, then the ordering is produced by G.nodes().

dtype: NumPy data-type, optional

A valid NumPy dtype used to initialize the array. If None, then the NumPy default is used.

**Returns** M : SciPy sparse matrix

Graph adjacency matrix.

#### **Notes**

The matrix entries are populated using the 'weight' edge attribute. When an edge does not have the 'weight' attribute, the value of the entry is 1. For multiple edges, the values of the entries are the sums of the edge attributes for each edge.

When *nodelist* does not contain every node in G, the matrix is built from the subgraph of G that is induced by the nodes in *nodelist*.

Uses lil\_matrix format. To convert to other formats see the documentation for scipy.sparse.

# **Examples**

```
>>> G = nx.MultiDiGraph()
>>> G.add_edge(0,1,weight=2)
>>> G.add_edge(1,0)
>>> G.add_edge(2,2,weight=3)
>>> G.add_edge(2,2)
>>> S = nx.to_scipy_sparse_matrix(G, nodelist=[0,1,2])
>>> S.todense()
matrix([[ 0., 2., 0.],
```

```
[ 1., 0., 0.],
[ 0., 0., 4.]])
```

# 8.2.11 networkx.from\_scipy\_sparse\_matrix

**from\_scipy\_sparse\_matrix** (*A*, *create\_using=None*)

Return a graph from scipy sparse matrix adjacency list.

Parameters A: scipy sparse matrix

An adjacency matrix representation of a graph

create\_using : NetworkX graph

Use specified graph for result. The default is Graph()

# **Examples**

```
>>> import scipy.sparse
>>> A=scipy.sparse.eye(2,2,1)
>>> G=nx.from_scipy_sparse_matrix(A)
```

8.2. Functions 225

**CHAPTER** 

NINE

# READING AND WRITING GRAPHS

# 9.1 Adjacency List

Read and write NetworkX graphs as adjacency lists.

Note that NetworkX graphs can contain any hashable Python object as node (not just integers and strings). So writing a NetworkX graph as a text file may not always be what you want: see write\_gpickle and gread\_gpickle for that case.

This module provides the following:

Adjacency list with single line per node: Useful for connected or unconnected graphs without edge data.

```
write_adjlist(G, path) G=read_adjlist(path)
```

Adjacency list with multiple lines per node: Useful for connected or unconnected graphs with or without edge data.

write\_multiline\_adjlist(G, path) read\_multiline\_adjlist(path)

```
read_adjlist(path[, comments, delimiter, ...])
write_adjlist(G, path[, comments, delimiter])
read_multiline_adjlist(path[, comments, ...])
write_multiline_adjlist(G, path[, ...])

Read graph in single line adjacency list format from path.
Write graph G in single-line adjacency list format from path.
Write the graph G in multiline adjacency list format to the file
```

# 9.1.1 networkx.read\_adjlist

```
read_adjlist (path, comments='#', delimiter=' ', create_using=None, nodetype=None)
Read graph in single line adjacency list format from path.
```

#### **Examples**

```
>>> G=nx.path_graph(4)
>>> nx.write_adjlist(G, "test.adjlist")
>>> G=nx.read_adjlist("test.adjlist")
```

path can be a filehandle or a string with the name of the file.

```
>>> fh=open("test.adjlist")
>>> G=nx.read_adjlist(fh)
```

Filenames ending in .gz or .bz2 will be compressed.

```
>>> nx.write_adjlist(G, "test.adjlist.gz")
>>> G=nx.read_adjlist("test.adjlist.gz")
```

nodetype is an optional function to convert node strings to nodetype

For example

```
>>> G=nx.read_adjlist("test.adjlist", nodetype=int)
```

will attempt to convert all nodes to integer type

Since nodes must be hashable, the function nodetype must return hashable types (e.g. int, float, str, frozenset - or tuples of those, etc.)

create\_using is an optional networkx graph type, the default is Graph(), an undirected graph.

```
>>> G=nx.read_adjlist("test.adjlist", create_using=nx.DiGraph())
```

Does not handle edge data: use 'read\_edgelist' or 'read\_multiline\_adjlist'

The comments character (default='#') at the beginning of a line indicates a comment line.

The entries are separated by delimiter (default=' '). If whitespace is significant in node or edge labels you should use some other delimiter such as a tab or other symbol.

Sample format:

```
# source target
a b c
d e
```

# 9.1.2 networkx.write\_adjlist

```
write_adjlist (G, path, comments='#', delimiter=' ')
```

Write graph G in single-line adjacency-list format to path.

See read\_adjlist for file format details.

# **Examples**

```
>>> G=nx.path_graph(4)
>>> nx.write_adjlist(G,"test.adjlist")
```

path can be a filehandle or a string with the name of the file.

```
>>> fh=open("test.adjlist",'w')
>>> nx.write_adjlist(G, fh)
```

Filenames ending in .gz or .bz2 will be compressed.

```
>>> nx.write_adjlist(G, "test.adjlist.gz")
```

The file will use the default text encoding on your system. It is possible to write files in other encodings by opening the file with the codecs module. See doc/examples/unicode.py for hints.

```
>>> import codecs
```

fh=codecs.open("test.adjlist",encoding="utf=8") # use utf-8 encoding nx.write\_adjlist(G,fh)

Does not handle edge data. Use 'write\_edgelist' or 'write\_multiline\_adjlist'

#### 9.1.3 networkx.read multiline adjlist

 $\begin{tabular}{ll} \textbf{read\_multiline\_adjlist} (path, \ comments=`\#', \ delimiter='\ ', \ create\_using=None, \ nodetype=None, \ edgetype=None) \end{tabular}$ 

Read graph in multi-line adjacency list format from path.

#### **Examples**

```
>>> G=nx.path_graph(4)
>>> nx.write_multiline_adjlist(G,"test.adjlist")
>>> G=nx.read_multiline_adjlist("test.adjlist")
```

path can be a filehandle or a string with the name of the file.

```
>>> fh=open("test.adjlist")
>>> G=nx.read_multiline_adjlist(fh)
```

Filenames ending in .gz or .bz2 will be compressed.

```
>>> nx.write_multiline_adjlist(G,"test.adjlist.gz")
>>> G=nx.read_multiline_adjlist("test.adjlist.gz")
```

nodetype is an optional function to convert node strings to nodetype

For example

```
>>> G=nx.read_multiline_adjlist("test.adjlist", nodetype=int)
```

will attempt to convert all nodes to integer type

Since nodes must be hashable, the function nodetype must return hashable types (e.g. int, float, str, frozenset - or tuples of those, etc.)

edgetype is a function to convert edge data strings to edgetype

```
>>> G=nx.read_multiline_adjlist("test.adjlist")
```

create\_using is an optional networkx graph type, the default is Graph(), a simple undirected graph

```
>>> G=nx.read_multiline_adjlist("test.adjlist", create_using=nx.DiGraph())
```

The comments character (default='#') at the beginning of a line indicates a comment line.

The entries are separated by delimiter (default=' '). If whitespace is significant in node or edge labels you should use some other delimiter such as a tab or other symbol.

Example multiline adjlist file format

No edge data:

```
# source target for Graph or DiGraph
a 2
b
c
d 1
e
With edge data::

# source target for XGraph or XDiGraph with edge data
a 2
b edge-ab-data
c edge-ac-data
d 1
e edge-de-data
```

Reading the file will use the default text encoding on your system. It is possible to read files with other encodings by opening the file with the codecs module. See doc/examples/unicode.py for hints.

```
>>> import codecs
>>> fh=codecs.open("test.adjlist",'r',encoding='utf=8') # utf-8 encoding
>>> G=nx.read_multiline_adjlist(fh)
```

# 9.1.4 networkx.write\_multiline\_adjlist

```
write_multiline_adjlist(G, path, delimiter='', comments='#')
```

Write the graph G in multiline adjacency list format to the file or file handle path.

See read\_multiline\_adjlist for file format details.

# **Examples**

```
>>> G=nx.path_graph(4)
>>> nx.write_multiline_adjlist(G,"test.adjlist")
```

path can be a filehandle or a string with the name of the file.

```
>>> fh=open("test.adjlist",'w')
>>> nx.write_multiline_adjlist(G,fh)
```

Filenames ending in .gz or .bz2 will be compressed.

```
>>> nx.write_multiline_adjlist(G,"test.adjlist.gz")
```

The file will use the default text encoding on your system. It is possible to write files in other encodings by opening the file with the codecs module. See doc/examples/unicode.py for hints.

```
>>> import codecs
>>> fh=codecs.open("test.adjlist",'w',encoding='utf=8') # utf-8 encoding
>>> nx.write_multiline_adjlist(G,fh)
```

# 9.2 Edge List

Read and write NetworkX graphs as edge lists.

```
read_edgelist(path[, comments, delimiter, ...]) Read a graph from a list of edges. write_edgelist(G, path[, comments, ...]) Write graph as a list of edges.
```

#### 9.2.1 networkx.read\_edgelist

```
read_edgelist (path, comments='#', delimiter=' ', create_using=None, nodetype=None, edgetype=None)
Read a graph from a list of edges.
```

Parameters path: file or string

File or filename to write. Filenames ending in .gz or .bz2 will be uncompressed.

comments: string, optional

The character used to indicate the start of a comment.

delimiter: string, optional

The string uses to separate values. The default is whitespace.

create\_using : Graph container, optional,

Use specified container to build graph. The default is Graph().

nodetype: int, float, str, Python type, optional

Convert node data from strings to specified type

edgetype: int, float, str, Python type, optional

Convert edge data from strings to specified type and use as 'weight'

Returns G: graph

A networkx Graph or other type specified with create\_using

#### **Notes**

Since nodes must be hashable, the function nodetype must return hashable types (e.g. int, float, str, frozenset - or tuples of those, etc.)

Example edgelist file formats

Without edge data:

```
# source target
a b
a c
d e
```

#### With edge data:

```
# source target data
a b {'weight': 1}
a c {'weight': 3.14159}
d e {'fruit': 'apple'}
```

9.2. Edge List 231

#### **Examples**

```
>>> nx.write_edgelist(nx.path_graph(4), "test.edgelist")
>>> G=nx.read_edgelist("test.edgelist")
>>> fh=open("test.edgelist")
>>> G=nx.read_edgelist(fh)
>>> G=nx.read_edgelist("test.edgelist", nodetype=int)
>>> G=nx.read_edgelist("test.edgelist", create_using=nx.DiGraph())
```

# 9.2.2 networkx.write\_edgelist

```
write_edgelist (G, path, comments='#', delimiter=' ', data=True)
Write graph as a list of edges.

Parameters G: graph
A NetworkX graph

path: file or string
File or filename to write. Filenames ending in .gz or .bz2 will be compressed.

comments: string, optional
The character used to indicate the start of a comment
delimiter: string, optional
The string uses to separate values. The default is whitespace.
data: bool, optional
If True write a string representation of the edge data.
```

#### See Also:

```
networkx.write_edgelist
```

#### **Notes**

With data=True each line will have three string values: the string representation of the source, target, and edge data.

The file will use the default text encoding on your system. It is possible to write files in other encodings by opening the file with the codecs module. See doc/examples/unicode.py for hints.

```
>>> G=nx.path_graph(4)
>>> import codecs
>>> fh=codecs.open("test.edgelist",'w',encoding='utf=8') # utf-8 encoding
>>> nx.write_edgelist(G,fh)
```

# **Examples**

```
>>> G=nx.path_graph(4)
>>> nx.write_edgelist(G, "test.edgelist")

>>> G=nx.path_graph(4)
>>> fh=open("test.edgelist",'w')
>>> nx.write_edgelist(G, fh)

>>> nx.write_edgelist(G, "test.edgelist.gz")
>>> nx.write_edgelist(G, "test.edgelist.gz", data=False)
```

# 9.3 **GML**

Read graphs in GML format. See http://www.infosun.fim.uni-passau.de/Graphlet/GML/gml-tr.html for format specification.

Example graphs in GML format: http://www-personal.umich.edu/~mejn/netdata/

Requires pyparsing: http://pyparsing.wikispaces.com/

read_gml(path)	Read graph in GML format from path.
$write_gml(G, path)$	Write the graph G in GML format to the file or file handle path.
<pre>parse_gml(lines)</pre>	Parse GML graph from a string or iterable.

# 9.3.1 networkx.read\_gml

```
read\_gml(path)
```

Read graph in GML format from path.

Parameters path: filename or filehandle

The filename or filehandle to read from.

Returns G: Graph or DiGraph

Raises ImportError:

If the pyparsing module is not available.

#### See Also:

```
write_qml, parse_qml
```

#### **Notes**

This doesn't implement the complete GML specification for nested attributes for graphs, edges, and nodes.

Requires pyparsing: http://pyparsing.wikispaces.com/

9.3. GML 233

#### References

GML specification: http://www.infosun.fim.uni-passau.de/Graphlet/GML/gml-tr.html

# **Examples**

```
>>> G=nx.path_graph(4)
>>> nx.write_gml(G,'test.gml')
>>> H=nx.read_gml('test.gml')
```

#### 9.3.2 networkx.write gml

```
write_gml (G, path)
```

Write the graph G in GML format to the file or file handle path.

**Parameters path**: filename or filehandle

The filename or filehandle to write. Filenames ending in .gz or .gz2 will be compressed.

#### See Also:

```
read_gml, parse_gml
```

#### **Notes**

The output file will use the default text encoding on your system. It is possible to write files in other encodings by opening the file with the codecs module. See doc/examples/unicode.py for hints.

```
>>> G=nx.path_graph(4)
>>> import codecs
>>> fh=codecs.open('test.gml','w',encoding='iso8859-1') # use iso8859-1
>>> nx.write_gml(G,fh)
```

GML specifications indicate that the file should only use 7bit ASCII text encoding.iso8859-1 (latin-1).

Only a single level of attributes for graphs, nodes, and edges, is supported.

# **Examples**

```
>>> G=nx.path_graph(4)
>>> nx.write_gml(G,"test.gml")
```

path can be a filehandle or a string with the name of the file.

```
>>> fh=open("test.gml",'w')
>>> nx.write_gml(G,fh)
```

Filenames ending in .gz or .bz2 will be compressed.

```
>>> nx.write_gml(G,"test.gml.gz")
```

#### 9.3.3 networkx.parse gml

```
parse_gml (lines)
```

Parse GML graph from a string or iterable.

Parameters lines: string or iterable

Data in GML format.

**Returns** G: Graph or DiGraph

Raises ImportError:

If the pyparsing module is not available.

#### See Also:

```
write_gml, read_gml
```

#### **Notes**

This doesn't implement the complete GML specification for nested attributes for graphs, edges, and nodes.

Requires pyparsing: http://pyparsing.wikispaces.com/

#### References

GML specification: http://www.infosun.fim.uni-passau.de/Graphlet/GML/gml-tr.html

# **Examples**

```
>>> G=nx.path_graph(4)
>>> nx.write_gml(G,'test.gml')
>>> fh=open('test.gml')
>>> H=nx.read_gml(fh)
```

#### 9.4 Pickle

Read and write NetworkX graphs as Python pickles.

Note that NetworkX graphs can contain any hashable Python object as node (not just integers and strings). So writing a NetworkX graph as a text file may not always be what you want: see write\_gpickle and gread\_gpickle for that case.

This module provides the following:

Python pickled format: Useful for graphs with non text representable data.

write\_gpickle(G, path) read\_gpickle(path)

```
read_gpickle(path) Read graph object in Python pickle format write_gpickle(G, path) Write graph object in Python pickle format.
```

9.4. Pickle 235

#### 9.4.1 networkx.read gpickle

```
read_gpickle(path)
```

Read graph object in Python pickle format

G=nx.path\_graph(4) nx.write\_gpickle(G,"test.gpickle") G=nx.read\_gpickle("test.gpickle")

See cPickle.

# 9.4.2 networkx.write\_gpickle

#### write\_gpickle(G, path)

Write graph object in Python pickle format.

This will preserve Python objects used as nodes or edges.

G=nx.path\_graph(4) nx.write\_gpickle(G,"test.gpickle")

See cPickle.

# 9.5 GraphML

Read and write graphs in GraphML format. http://graphml.graphdrawing.org/

The module currently supports simple graphs and not nested graphs or hypergraphs.

```
read_graphml(path) Read graph in GraphML format from path.
parse_graphml(lines) Read graph in GraphML format from string.
```

#### 9.5.1 networkx.read graphml

#### ${\tt read\_graphml}\;(path)$

Read graph in GraphML format from path.

Returns a Graph or DiGraph.

Does not implement full GraphML specification.

# 9.5.2 networkx.parse graphml

#### parse\_graphml (lines)

Read graph in GraphML format from string.

Returns a Graph or DiGraph.

Does not implement full GraphML specification.

# **9.6 LEDA**

Read graphs in LEDA format. See http://www.algorithmic-solutions.info/leda\_guide/graphs/leda\_native\_graph\_fileformat.html

read_leda(path)	Read graph in GraphML format from path.
<pre>parse_leda(lines)</pre>	Parse LEDA.GRAPH format from string or iterable.

# 9.6.1 networkx.read\_leda

#### read\_leda(path)

Read graph in GraphML format from path. Returns an XGraph or XDiGraph.

# 9.6.2 networkx.parse leda

#### parse\_leda(lines)

Parse LEDA.GRAPH format from string or iterable. Returns an Graph or DiGraph.

# **9.7 YAML**

Read and write NetworkX graphs in YAML format. See http://www.yaml.org for documentation.

read_yaml(path)	Read graph from YAML format from path.
<pre>write_yaml(G, path, **kwds[, default_flow_style])</pre>	Write graph G in YAML text format to path.

# 9.7.1 networkx.read\_yaml

#### read\_yaml (path)

Read graph from YAML format from path.

See http://www.yaml.org

# 9.7.2 networkx.write\_yaml

```
write_yaml (G, path, default_flow_style=False, **kwds)
Write graph G in YAML text format to path.
```

See http://www.yaml.org

# 9.8 SparseGraph6

Read graphs in graph6 and sparse6 format. See http://cs.anu.edu.au/~bdm/data/formats.txt

read_graph6(path)	Read simple undirected graphs in graph6 format from path.
parse_graph6(str)	Read undirected graph in graph6 format.
<pre>read_graph6_list(path)</pre>	Read simple undirected graphs in graph6 format from path.
read_sparse6(path)	Read simple undirected graphs in sparse6 format from path.
parse_sparse6(str)	Read undirected graph in sparse6 format.
<pre>read_sparse6_list(path)</pre>	Read simple undirected graphs in sparse6 format from path.

# 9.8.1 networkx.read\_graph6

#### read\_graph6 (path)

Read simple undirected graphs in graph6 format from path. Returns a single Graph.

9.7. YAML 237

# 9.8.2 networkx.parse\_graph6

#### parse\_graph6 (str)

Read undirected graph in graph6 format.

#### 9.8.3 networkx.read\_graph6\_list

#### read\_graph6\_list(path)

Read simple undirected graphs in graph6 format from path. Returns a list of Graphs, one for each line in file.

# 9.8.4 networkx.read\_sparse6

#### read sparse6(path)

Read simple undirected graphs in sparse6 format from path. Returns a single Graph.

# 9.8.5 networkx.parse\_sparse6

#### parse\_sparse6 (str)

Read undirected graph in sparse6 format.

#### 9.8.6 networkx.read\_sparse6\_list

#### read\_sparse6\_list(path)

Read simple undirected graphs in sparse6 format from path. Returns a list of Graphs, one for each line in file.

# 9.9 Pajek

Read graphs in Pajek format.

See http://vlado.fmf.uni-lj.si/pub/networks/pajek/doc/draweps.htm for format information.

This implementation handles only directed and undirected graphs including those with self loops and parallel edges.

read_pajek(path)	Read graph in Pajek format from path.
write_pajek( <b>G</b> , path)	Write in Pajek format to path.
<pre>parse_pajek(lines[, edge_attr])</pre>	Parse pajek format graph from string or iterable.

#### 9.9.1 networkx.read pajek

#### read\_pajek (path)

Read graph in Pajek format from path.

Returns a MultiGraph or MultiDiGraph.

Parameters path: file or string

File or filename to write. Filenames ending in .gz or .bz2 will be compressed.

# **Examples**

```
>>> G=nx.path_graph(4)
>>> nx.write_pajek(G, "test.net")
>>> G=nx.read_pajek("test.net")
```

To create a Graph instead of a MultiGraph use

```
>>> G1=nx.Graph(G)
```

# 9.9.2 networkx.write\_pajek

```
write_pajek (G, path)
Write in Pajek format to path.

Parameters G: graph
A networkx graph
path: file or string
File or filename to write. Filenames ending in .gz or .bz2 will be compressed.
```

# **Examples**

```
>>> G=nx.path_graph(4)
>>> nx.write_pajek(G, "test.net")
```

# 9.9.3 networkx.parse\_pajek

```
parse_pajek (lines, edge_attr=True)
Parse pajek format graph from string or iterable.
```

Primarily used as a helper for read\_pajek().

See Also:

```
read_pajek
```

9.9. Pajek 239

**CHAPTER** 

**TEN** 

# **DRAWING**

# 10.1 Matplotlib

Draw networks with matplotlib (pylab).

#### 10.1.1 See Also

matplotlib: http://matplotlib.sourceforge.net/ pygraphviz: http://networkx.lanl.gov/pygraphviz/

```
draw(G, **kwds[, pos, ax, hold])
                                                       Draw the graph G with matplotlib (pylab).
draw_networkx(G, pos, **kwds[, with_labels])
                                                       Draw the graph G with given node positions pos
draw_networkx_nodes(G, pos, **kwds[, ...])
                                                       Draw nodes of graph G
draw_networkx_edges(G, pos, **kwds[, ...])
                                                       Draw the edges of the graph G
draw_networkx_labels(G, pos, **kwds[, ...])
                                                       Draw node labels on the graph G
draw_networkx_edge_labels(G, pos, **kwds[, ...])
                                                       Draw edge labels.
draw_circular(G, **kwargs)
                                                       Draw the graph G with a circular layout
draw_random(G, **kwargs)
                                                       Draw the graph G with a random layout.
draw_spectral(G, **kwargs)
                                                       Draw the graph G with a spectral layout.
draw_spring(G, **kwargs)
                                                       Draw the graph G with a spring layout
draw_shell(G, **kwargs)
                                                       Draw networkx graph with shell layout
draw_graphviz(G, **kwargs[, prog])
                                                       Draw networkx graph with graphviz layout
```

#### 10.1.2 networkx.draw

```
draw (G, pos=None, ax=None, hold=None, **kwds)

Draw the graph G with matplotlib (pylab).
```

This is a pylab friendly function that will use the current pylab figure axes (e.g. subplot).

pos is a dictionary keyed by vertex with a two-tuple of x-y positions as the value. See networkx.layout for functions that compute node positions.

#### Usage:

```
>>> G=nx.dodecahedral_graph()
>>> nx.draw(G)
>>> nx.draw(G,pos=nx.spring_layout(G))
```

Also see doc/examples/draw\_\*

#### **Parameters**

- *nodelist*: list of nodes to be drawn (default=G.nodes())
- edgelist: list of edges to be drawn (default=G.edges())
- node\_size: scalar or array of the same length as nodelist (default=300)
- node\_color: single color string or numeric/numarray array of floats (default='r')
- node\_shape: node shape (default='o'), or 'so^>v<dph8' see pylab.scatter
- *alpha*: transparency (default=1.0)
- cmap: colormap for mapping intensities (default=None)
- *vmin,vmax*: min and max for colormap scaling (default=None)
- width: line width of edges (default =1.0)
- edge\_color: scalar or array (default='k')
- edge\_cmap: colormap for edge intensities (default=None)
- edge\_vmin,edge\_vmax: min and max for colormap edge scaling (default=None)
- style: edge linestyle (default='solid') (solid|dashed|dotted,dashdot)
- labels: dictionary keyed by node of text labels (default=None)
- font\_size: size for text labels (default=12)
- font\_color: (default='k')
- font\_weight: (default='normal')
- font\_family: (default='sans-serif')
- ax: matplotlib axes instance

for more see pylab.scatter

NB: this has the same name as pylab.draw so beware when using

```
>>> from networkx import *
```

since you will overwrite the pylab.draw function.

A good alternative is to use

```
>>> import pylab as P
>>> import networkx as nx
>>> G=nx.dodecahedral_graph()
and then use
>>> nx.draw(G) # networkx draw()
and >>> P.draw() # pylab draw()
```

#### 10.1.3 networkx.draw networkx

```
draw_networkx (G, pos, with_labels=True, **kwds)
    Draw the graph G with given node positions pos
    Usage:
```

```
>>> G=nx.dodecahedral_graph()
>>> pos=nx.spring_layout(G)
>>> nx.draw_networkx(G,pos)
```

This is same as 'draw' but the node positions *must* be specified in the variable pos. pos is a dictionary keyed by vertex with a two-tuple of x-y positions as the value. See networkx.layout for functions that compute node positions.

An optional matplotlib axis can be provided through the optional keyword ax.

with\_labels contols text labeling of the nodes

Also see:

draw\_networkx\_nodes() draw\_networkx\_edges() draw\_networkx\_labels()

#### 10.1.4 networkx.draw\_networkx\_nodes

Draw nodes of graph G

This draws only the nodes of the graph G.

pos is a dictionary keyed by vertex with a two-tuple of x-y positions as the value. See networkx.layout for functions that compute node positions.

nodelist is an optional list of nodes in G to be drawn. If provided only the nodes in nodelist will be drawn.

see draw\_networkx for the list of other optional parameters.

#### 10.1.5 networkx.draw\_networkx\_edges

Draw the edges of the graph G

This draws only the edges of the graph G.

pos is a dictionary keyed by vertex with a two-tuple of x-y positions as the value. See networkx.layout for functions that compute node positions.

edgelist is an optional list of the edges in G to be drawn. If provided, only the edges in edgelist will be drawn.

edgecolor can be a list of matplotlib color letters such as 'k' or 'b' that lists the color of each edge; the list must be ordered in the same way as the edge list. Alternatively, this list can contain numbers and those number are mapped to a color scale using the color map edge\_cmap. Finally, it can also be a list of (r,g,b) or (r,g,b,a) tuples, in which case these will be used directly to color the edges. If the latter mode is used, you should not provide a value for alpha, as it would be applied globally to all lines.

For directed graphs, "arrows" (actually just thicker stubs) are drawn at the head end. Arrows can be turned off with keyword arrows=False.

See draw\_networkx for the list of other optional parameters.

10.1. Matplotlib 243

#### 10.1.6 networkx.draw networkx labels

Draw node labels on the graph G

pos is a dictionary keyed by vertex with a two-tuple of x-y positions as the value. See networkx.layout for functions that compute node positions.

labels is an optional dictionary keyed by vertex with node labels as the values. If provided only labels for the keys in the dictionary are drawn.

See draw\_networkx for the list of other optional parameters.

#### 10.1.7 networkx.draw networkx edge labels

Draw edge labels.

pos is a dictionary keyed by vertex with a two-tuple of x-y positions as the value. See networkx.layout for functions that compute node positions.

labels is an optional dictionary keyed by edge tuple with labels as the values. If provided only labels for the keys in the dictionary are drawn. If not provided the edge data is used as a label.

See draw\_networkx for the list of other optional parameters.

#### 10.1.8 networkx.draw\_circular

draw\_circular(G, \*\*kwargs)

Draw the graph G with a circular layout

#### 10.1.9 networkx.draw random

draw\_random(G, \*\*kwargs)

Draw the graph G with a random layout.

#### 10.1.10 networkx.draw spectral

draw\_spectral(G, \*\*kwargs)

Draw the graph G with a spectral layout.

#### 10.1.11 networkx.draw spring

draw\_spring(G, \*\*kwargs)

Draw the graph G with a spring layout

#### 10.1.12 networkx.draw\_shell

draw\_shell(G, \*\*kwargs)

Draw networkx graph with shell layout

#### 10.1.13 networkx.draw graphviz

**draw\_graphviz** (*G*, *prog='neato'*, \*\*kwargs)

Draw networkx graph with graphviz layout

# 10.2 Graphviz AGraph (dot)

Interface to pygraphviz AGraph class.

# 10.2.1 Examples

```
>>> G=nx.complete_graph(5)
>>> A=nx.to_agraph(G)
>>> H=nx.from_agraph(A)
```

#### 10.2.2 See Also

Pygraphviz: http://networkx.lanl.gov/pygraphviz

from_agraph(A[, create_using])	Return a NetworkX Graph or DiGraph from a PyGraphviz graph.
to_agraph( $\mathbf{N}$ )	Return a pygraphviz graph from a NetworkX graph N.
write_dot(G, path)	Write NetworkX graph G to Graphviz dot format on path.
read_dot(path)	Return a NetworkX graph from a dot file on path.
<pre>graphviz_layout(G[, prog, root, args])</pre>	Create node positions for G using Graphviz.
<pre>pygraphviz_layout(G[, prog, root, args])</pre>	Create node positions for G using Graphviz.

# 10.2.3 networkx.from\_agraph

from\_agraph (A, create\_using=None)

Return a NetworkX Graph or DiGraph from a PyGraphviz graph.

**Parameters** A: PyGraphviz AGraph

A graph created with PyGraphviz

create\_using : NetworkX graph class instance

The output is created using the given graph class instance

#### **Notes**

The Graph G will have a dictionary G.graph\_attr containing the default graphviz attributes for graphs, nodes and edges.

Default node attributes will be in the dictionary G.node\_attr which is keyed by node.

Edge attributes will be returned as edge data in G. With edge\_attr=False the edge data will be the Graphviz edge weight attribute or the value 1 if no edge weight attribute is found.

#### **Examples**

```
>>> K5=nx.complete_graph(5)
>>> A=nx.to_agraph(K5)
>>> G=nx.from_agraph(A)
>>> G=nx.from_agraph(A)
```

# 10.2.4 networkx.to agraph

```
to_agraph(N)
```

Return a pygraphviz graph from a NetworkX graph N.

Parameters N: NetworkX graph

A graph created with NetworkX

#### **Notes**

If N has an dict N.graph\_attr an attempt will be made first to copy properties attached to the graph (see from\_agraph) and then updated with the calling arguments if any.

# **Examples**

```
>>> K5=nx.complete_graph(5)
>>> A=nx.to_agraph(K5)
```

# 10.2.5 networkx.write\_dot

```
write_dot(G, path)
```

Write NetworkX graph G to Graphviz dot format on path.

Parameters G: graph

A networkx graph

path: filename

Filename or file handle to write.

# 10.2.6 networkx.read\_dot

```
read_dot (path)
```

Return a NetworkX graph from a dot file on path.

Parameters path: file or string

File name or file handle to read.

#### 10.2.7 networkx.graphviz layout

```
graphviz_layout (G, prog='neato', root=None, args=")
Create node positions for G using Graphviz.

Parameters G: NetworkX graph
A graph created with NetworkX

prog: string
Name of Graphviz layout program

root: string, optional

Root node for twopi layout

args: string, optional

Extra arguments to Graphviz layout program

Returns: dictionary
```

Dictionary of x,y, positions keyed by node.

#### **Notes**

This is a wrapper for pygraphviz\_layout.

# **Examples**

```
>>> G=nx.petersen_graph()
>>> pos=nx.graphviz_layout(G)
>>> pos=nx.graphviz_layout(G,prog='dot')
```

#### 10.2.8 networkx.pygraphviz layout

```
pygraphviz_layout (G, prog='neato', root=None, args=") Create node positions for G using Graphviz.
```

Parameters G: NetworkX graph

A graph created with NetworkX

prog : string

Name of Graphviz layout program

root: string, optional

Root node for twopi layout

args: string, optional

Extra arguments to Graphviz layout program

Returns: dictionary

Dictionary of x,y, positions keyed by node.

#### **Examples**

```
>>> G=nx.petersen_graph()
>>> pos=nx.graphviz_layout(G)
>>> pos=nx.graphviz_layout(G,prog='dot')
```

# 10.3 Graphviz with pydot

Import and export NetworkX graphs in Graphviz dot format using pydot.

Either this module or nx\_pygraphviz can be used to interface with graphviz.

#### 10.3.1 See Also

Pydot: http://www.dkbza.org/pydot.html Graphviz: http://www.research.att.com/sw/tools/graphviz/ DOT Language: http://www.graphviz.org/doc/info/lang.html

from_pydot(P)	Return a NetworkX graph from a Pydot graph.
to_pydot(N[, strict])	Return a pydot graph from a NetworkX graph N.
write_dot(G, path)	Write NetworkX graph G to Graphviz dot format on path.
read_dot(path)	Return a NetworkX graph from a dot file on path.
<pre>graphviz_layout(G[, prog, root, args])</pre>	Create node positions for G using Graphviz.
<pre>pydot_layout(G, **kwds[, prog, root])</pre>	Create node positions using Pydot and Graphviz.

# 10.3.2 networkx.from\_pydot

```
from_pydot(P)
```

Return a NetworkX graph from a Pydot graph.

Parameters P: Pydot graph

A graph created with Pydot

# **Examples**

```
>>> K5=nx.complete_graph(5)
>>> A=nx.to_pydot(K5)
>>> G=nx.from_pydot(A)
```

# 10.3.3 networkx.to\_pydot

to\_pydot (N, strict=True)

Return a pydot graph from a NetworkX graph N.

**Parameters N**: NetworkX graph

A graph created with NetworkX

#### **Examples**

```
>>> K5=nx.complete_graph(5)
>>> P=nx.to_pydot(K5)
```

#### 10.3.4 networkx.write\_dot

```
write_dot(G, path)
```

Write NetworkX graph G to Graphviz dot format on path.

Parameters G: graph

A networkx graph

path: filename

Filename or file handle to write.

#### 10.3.5 networkx.read\_dot

```
read_dot (path)
```

Return a NetworkX graph from a dot file on path.

Parameters path: file or string

File name or file handle to read.

## 10.3.6 networkx.graphviz\_layout

```
graphviz_layout (G, prog='neato', root=None, args=") Create node positions for G using Graphviz.
```

Parameters G: NetworkX graph

arameters of the two tax graph

A graph created with NetworkX

prog : string

Name of Graphviz layout program

root: string, optional

Root node for twopi layout

args: string, optional

Extra arguments to Graphviz layout program

Returns: dictionary

Dictionary of x,y, positions keyed by node.

#### **Notes**

This is a wrapper for pygraphviz\_layout.

#### **Examples**

```
>>> G=nx.petersen_graph()
>>> pos=nx.graphviz_layout(G)
>>> pos=nx.graphviz_layout(G,prog='dot')
```

### 10.3.7 networkx.pydot\_layout

```
pydot_layout (G, prog='neato', root=None, **kwds) Create node positions using Pydot and Graphviz.
```

Returns a dictionary of positions keyed by node.

## **Examples**

```
>>> G=nx.complete_graph(4)
>>> pos=nx.pydot_layout(G)
>>> pos=nx.pydot_layout(G,prog='dot')
```

## 10.4 Graph Layout

Node positioning algorithms for graph drawing.

```
circular_layout(G[, dim, scale])
random_layout(G[, dim])
shell_layout(G[, nlist, dim, scale])
spring_layout(G[, dim, pos, fixed, ...])
spectral_layout(G[, dim, weighted, scale])

spectral_layout(G[, dim, weighted, scale])

Position nodes on a circle.

Position nodes in concentric circles.
Position nodes using Fruchterman-Reingold force-directed algorithm.
Position nodes using the eigenvectors of the graph Laplacian.
```

## 10.4.1 networkx.circular\_layout

A dictionary of positions keyed by node

#### **Notes**

This algorithm currently only works in two dimensions and does not try to minimize edge crossings.

#### **Examples**

```
>>> G=nx.path_graph(4)
>>> pos=nx.circular_layout(G)
```

## 10.4.2 networkx.random\_layout

```
random_layout (G, dim=2)
```

## 10.4.3 networkx.shell\_layout

```
shell_layout (G, nlist=None, dim=2, scale=1) Position nodes in concentric circles.
```

```
Parameters G: NetworkX graph
```

nlist: list of lists

List of node lists for each shell.

dim: int

Dimension of layout, currently only dim=2 is supported

scale: float

Scale factor for positions

#### Returns dict::

A dictionary of positions keyed by node

#### **Notes**

This algorithm currently only works in two dimensions and does not try to minimize edge crossings.

### **Examples**

```
>>> G=nx.path_graph(4)
>>> shells=[[0],[1,2,3]]
>>> pos=nx.shell_layout(G,shells)
```

## 10.4.4 networkx.spring\_layout

**spring\_layout** (*G*, *dim=2*, *pos=None*, *fixed=None*, *iterations=50*, *weighted=True*, *scale=1*) Position nodes using Fruchterman-Reingold force-directed algorithm.

10.4. Graph Layout 251

```
Parameters G: NetworkX graph
```

dim: int

Dimension of layout

pos: dict

Initial positions for nodes as a dictionary with node as keys and values as a list or tuple.

fixed: list

Nodes to keep fixed at initial position.

iterations: int

Number of iterations of spring-force relaxation

weighted: boolean

If True, use edge weights in layout

scale: float

Scale factor for positions

#### Returns dict::

A dictionary of positions keyed by node

### **Examples**

```
>>> G=nx.path_graph(4)
>>> pos=nx.spring_layout(G)
```

# The same using longer function name >>> pos=nx.fruchterman\_reingold\_layout(G)

#### 10.4.5 networkx.spectral\_layout

```
spectral_layout (G, dim=2, weighted=True, scale=1)
```

Position nodes using the eigenvectors of the graph Laplacian.

Parameters G: NetworkX graph

dim: int

Dimension of layout

weighted: boolean

If True, use edge weights in layout

scale: float

Scale factor for positions

#### Returns dict::

A dictionary of positions keyed by node

#### **Notes**

Directed graphs will be considered as unidrected graphs when positioning the nodes.

For larger graphs (>500 nodes) this will use the SciPy sparse eigenvalue solver (ARPACK).

## **Examples**

```
>>> G=nx.path_graph(4)
>>> pos=nx.spectral_layout(G)
```

10.4. Graph Layout 253

**CHAPTER** 

## **ELEVEN**

# **EXCEPTIONS**

Base exceptions and errors for NetworkX.

#### ${\bf class} \; {\bf NetworkXException} \; (\,)$

Base class for exceptions in NetworkX.

#### class NetworkXError()

Exception for a serious error in NetworkX

## **UTILITIES**

Helpers for NetworkX.

These are not imported into the base networkx namespace but can be accessed, for example, as

```
>>> import networkx
>>> networkx.utils.is_string_like('spam')
True
```

## 12.1 Helper functions

is_string_like(obj)	Check if obj is string.
<pre>flatten(obj[, result])</pre>	Return flattened version of (possibly nested) iterable object.
iterable(obj)	Return True if obj is iterable with a well-defined len()
<pre>is_list_of_ints(intlist)</pre>	Return True if list is a list of ints.
_get_fh(path[, mode])	Return a file handle for given path.

## 12.1.1 networkx.utils.is\_string\_like

```
is_string_like (obj)

Check if obj is string.
```

#### 12.1.2 networkx.utils.flatten

```
flatten (obj, result=None)
```

Return flattened version of (possibly nested) iterable object.

#### 12.1.3 networkx.utils.iterable

```
iterable(obj)
```

Return True if obj is iterable with a well-defined len()

## 12.1.4 networkx.utils.is\_list\_of\_ints

### is\_list\_of\_ints(intlist)

Return True if list is a list of ints.

#### 12.1.5 networkx.utils. get fh

```
_get_fh (path, mode='r')
```

Return a file handle for given path.

Path can be a string or a file handle.

Attempt to uncompress/compress files ending in '.gz' and '.bz2'.

## 12.2 Data structures and Algorithms

UnionFind.union(\*objects) Find the sets containing the objects and merge them all.

#### 12.2.1 networkx.utils.UnionFind.union

union (\*objects)

Find the sets containing the objects and merge them all.

## 12.3 Random sequence generators

pareto_sequence(n[,	Return sample sequence of length n from a Pareto distribution.
exponent])	
$powerlaw\_sequence(n[,$	Return sample sequence of length n from a power law distribution.
exponent])	
uniform_sequence(n)	Return sample sequence of length n from a uniform distribution.
cumulative_distribution(distribution)rmalized cumulative distribution from discrete distribution.	
discrete_sequence(n[,	Return sample sequence of length n from a given discrete distribution or
distribution,])	discrete cumulative distribution.

#### 12.3.1 networkx.utils.pareto\_sequence

```
pareto_sequence (n, exponent=1.0)
```

Return sample sequence of length n from a Pareto distribution.

#### 12.3.2 networkx.utils.powerlaw\_sequence

```
powerlaw_sequence(n, exponent=2.0)
```

Return sample sequence of length n from a power law distribution.

#### 12.3.3 networkx.utils.uniform\_sequence

#### $uniform_sequence(n)$

Return sample sequence of length n from a uniform distribution.

#### 12.3.4 networkx.utils.cumulative distribution

#### cumulative\_distribution (distribution)

Return normalized cumulative distribution from discrete distribution.

#### 12.3.5 networkx.utils.discrete\_sequence

discrete\_sequence (n, distribution=None, cdistribution=None)

Return sample sequence of length n from a given discrete distribution or discrete cumulative distribution.

One of the following must be specified.

distribution = histogram of values, will be normalized

cdistribution = normalized discrete cumulative distribution

## 12.4 SciPy random sequence generators

<pre>scipy_pareto_sequence(n[, exponent])</pre>	Return sample sequence of length n from a Pareto distribution.
scipy_powerlaw_sequence(n[,	Return sample sequence of length n from a power law
exponent])	distribution.
scipy_poisson_sequence(n[, mu])	Return sample sequence of length n from a Poisson distribution.
scipy_uniform_sequence(n)	Return sample sequence of length n from a uniform
	distribution.
scipy_discrete_sequence(n[,	Return sample sequence of length n from a given discrete
distribution])	distribution

#### 12.4.1 networkx.utils.scipy\_pareto\_sequence

#### scipy\_pareto\_sequence (n, exponent=1.0)

Return sample sequence of length n from a Pareto distribution.

#### 12.4.2 networkx.utils.scipy\_powerlaw\_sequence

#### scipy\_powerlaw\_sequence (n, exponent=2.0)

Return sample sequence of length n from a power law distribution.

#### 12.4.3 networkx.utils.scipy\_poisson\_sequence

#### $scipy_poisson_sequence(n, mu=1.0)$

Return sample sequence of length n from a Poisson distribution.

#### 12.4.4 networkx.utils.scipy\_uniform\_sequence

#### scipy uniform sequence(n)

Return sample sequence of length n from a uniform distribution.

## 12.4.5 networkx.utils.scipy\_discrete\_sequence

 $\verb|scipy_discrete_sequence| (n, \textit{distribution=False})$ 

Return sample sequence of length n from a given discrete distribution

distribution=histogram of values, will be normalized

260 Chapter 12. Utilities

**CHAPTER** 

#### **THIRTEEN**

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262 Chapter 13. License

**CHAPTER** 

## **FOURTEEN**

# **CITING**

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264 Chapter 14. Citing

## **CREDITS**

NetworkX was originally written by Aric Hagberg, Dan Schult, and Pieter Swart with the help of many others.

Thanks to Guido van Rossum for the idea of using Python for implementing a graph data structure http://www.python.org/doc/essays/graphs.html

Thanks to David Eppstein for the idea of representing a graph G so that "for n in G" loops over the nodes in G and G[n] are node n's neighbors.

Thanks to all those who have improved NetworkX by contributing code, bug reports (and fixes), documentation, and input on design, features, and the future of NetworkX.

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- Katy Bold contributed the Karate Club graph
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**CHAPTER** 

### SIXTEEN

## **GLOSSARY**

#### dictionary FIXME

ebunch An iteratable container of edge tuples like a list, iterator, or file.

edge Edges are either two-tuples of nodes (u,v) or three tuples of nodes with an edge attribute dictionary (u,v,dict).

**edge attribute** Edges can have arbitrary Python objects assigned as attributes by using keyword/value pairs when adding an edge assigning to the G.edge[u][v] attribute dictionary for the specified edge u-v.

hashable An object is hashable if it has a hash value which never changes during its lifetime (it needs a \_\_hash\_\_() method), and can be compared to other objects (it needs an \_\_eq\_\_() or \_\_cmp\_\_() method). Hashable objects which compare equal must have the same hash value.

Hashability makes an object usable as a dictionary key and a set member, because these data structures use the hash value internally.

All of Python's immutable built-in objects are hashable, while no mutable containers (such as lists or dictionaries) are. Objects which are instances of user-defined classes are hashable by default; they all compare unequal, and their hash value is their id().

Definition from http://docs.python.org/glossary.html

**nbunch** An nbunch is any iterable container of nodes that is not itself a node in the graph. It can be an iterable or an iterator, e.g. a list, set, graph, file, etc..

**node** A node can be any hashable Python object except None.

**node attribute** Nodes can have arbitrary Python objects assigned as attributes by using keyword/value pairs when adding a node or assigning to the G.node[n] attribute dictionary for the specified node n.

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270 Bibliography

## **MODULE INDEX**

#### Ν

```
networkx.algorithms.bipartite, 180
networkx.algorithms.boundary, 137
networkx.algorithms.centrality, 138
networkx.algorithms.clique, 142
networkx.algorithms.cluster, 145
networkx.algorithms.core, 147
networkx.algorithms.hits, 163
networkx.algorithms.matching, 148
networkx.algorithms.mst, 182
networkx.algorithms.pagerank, 161
networkx.algorithms.traversal.astar, 178
networkx.algorithms.traversal.component,
       164
networkx.algorithms.traversal.dag, 167
networkx.algorithms.traversal.distance,
networkx.algorithms.traversal.path, 169
networkx.algorithms.traversal.search,
networkx.convert, 219
networkx.drawing.layout, 250
networkx.drawing.nx_agraph, 245
networkx.drawing.nx_pydot, 248
networkx.drawing.nx_pylab, 241
networkx.exception, 255
networkx.operators, 129
networkx.readwrite.adjlist, 227
networkx.readwrite.edgelist, 231
networkx.readwrite.gml, 233
networkx.readwrite.gpickle, 235
networkx.readwrite.graphml, 236
networkx.readwrite.leda, 236
networkx.readwrite.nx_yaml, 237
networkx.readwrite.pajek, 238
networkx.readwrite.sparsegraph6,237
networkx.utils, 257
```

272 Module Index

# **INDEX**

Symbols	add_edges_from() (MultiGraph method), 74
•	add_node() (DiGraph method), 39
contains() (DiGraph method), 57	add_node() (Graph method), 13
contains() (Graph method), 28	add_node() (MultiDiGraph method), 98
contains() (MultiDiGraph method), 117	add_node() (MultiGraph method), 71
contains() (MultiGraph method), 87	add_nodes_from() (DiGraph method), 40
getitem() (DiGraph method), 53	add_nodes_from() (Graph method), 14
getitem() (Graph method), 25	add_nodes_from() (MultiDiGraph method), 99
getitem() (MultiDiGraph method), 114	
getitem() (MultiGraph method), 84	add_nodes_from() (MultiGraph method), 71
init() (DiGraph method), 38	add_path() (DiGraph method), 45
init() (DiGraphMatcher method), 152	add_path() (Graph method), 19
init() (Graph method), 12	add_path() (MultiDiGraph method), 105
init() (GraphMatcher method), 150	add_path() (MultiGraph method), 77
init() (MultiDiGraph method), 98	add_star() (DiGraph method), 45
init() (MultiGraph method), 70	add_star() (Graph method), 18
init() (WeightedDiGraphMatcher method), 156	add_star() (MultiDiGraph method), 104
init() (WeightedGraphMatcher method), 154	add_star() (MultiGraph method), 77
init() (WeightedMultiDiGraphMatcher method), 160	add_weighted_edges_from() (DiGraph method), 43
init() (WeightedMultiGraphMatcher method), 158	add_weighted_edges_from() (Graph method), 17
iter() (DiGraph method), 48	add_weighted_edges_from() (MultiDiGraph method),
iter() (Graph method), 22	102
iter() (MultiDiGraph method), 108	add_weighted_edges_from() (MultiGraph method), 75
iter() (MultiGraph method), 80	adj_matrix() (in module networkx), 217
len() (DiGraph method), 59	adjacency_iter() (DiGraph method), 55
_len_() (Graph method), 31	adjacency_iter() (Graph method), 26
len() (MultiDiGraph method), 120	adjacency_iter() (MultiDiGraph method), 115
len() (MultiGraph method), 90	adjacency_iter() (MultiGraph method), 85
get_fh() (in module networkx.utils), 258	adjacency_list() (DiGraph method), 54
_6.2_ () (	adjacency_list() (Graph method), 26
A	adjacency_list() (MultiDiGraph method), 115
add_cycle() (DiGraph method), 46	adjacency_list() (MultiGraph method), 85
add_cycle() (Graph method), 19	adjacency_spectrum() (in module networkx), 218
add_cycle() (MultiDiGraph method), 105	all_pairs_shortest_path() (in module networkx), 172
add_cycle() (MultiGraph method), 78	all_pairs_shortest_path_length() (in module networkx),
•	172
add_edge() (DiGraph method), 41	astar_path() (in module networkx), 178
add_edge() (Graph method), 15	astar_path_length() (in module networkx), 179
add_edge() (MultiDiGraph method), 101	authority_matrix() (in module networkx), 164
add_edge() (MultiGraph method), 73	average_clustering() (in module networkx), 147
add_edges_from() (DiGraph method), 42	average_shortest_path_length() (in module networkx),
add_edges_from() (Graph method), 16	170
add_edges_from() (MultiDiGraph method), 102	

В	connected_component_subgraphs() (in module net-
balanced_tree() (in module networkx), 186	workx), 165
barabasi_albert_graph() (in module networkx), 200	connected_components() (in module networkx), 165
barbell_graph() (in module networkx), 186	connected_double_edge_swap() (in module networkx),
betweenness_centrality() (in module networkx), 138	208
betweenness_centrality_source() (in module networkx), 139	connected_watts_strogatz_graph() (in module networkx), 199
bidirectional_dijkstra() (in module networkx), 176	<pre>convert_node_labels_to_integers() (in module networkx),</pre>
bidirectional_shortest_path() (in module networkx), 176	134
binomial_graph() (in module networkx), 197	copy() (DiGraph method), 65
bipartite_alternating_havel_hakimi_graph() (in module	copy() (Graph method), 34
networkx), 215	copy() (MultiDiGraph method), 126
bipartite_color() (in module networkx), 181	copy() (MultiGraph method), 93
bipartite_configuration_model() (in module networkx),	could_be_isomorphic() (in module networkx), 149
214	create_degree_sequence() (in module networkx), 207
bipartite_havel_hakimi_graph() (in module networkx),	create_empty_copy() (in module networkx), 129 cubical_graph() (in module networkx), 191
214	cumulative_distribution() (in module networkx.utils), 259
bipartite_preferential_attachment_graph() (in module networkx), 216	cycle_graph() (in module networkx), 187
bipartite_random_regular_graph() (in module networkx),	<b>D</b>
216	D
bipartite_reverse_havel_hakimi_graph() (in module net-	degree() (DiGraph method), 61
workx), 215	degree() (Graph method), 32
bipartite_sets() (in module networkx), 181	degree() (MultiDiGraph method), 122
bull_graph() (in module networkx), 191	degree() (MultiGraph method), 91
0	degree_centrality() (in module networkx), 141
C	degree_iter() (DiGraph method), 62
candidate_pairs_iter() (DiGraphMatcher method), 153	degree_iter() (Graph method), 33
candidate_pairs_iter() (GraphMatcher method), 151	degree_iter() (MultiDiGraph method), 123
candidate_pairs_iter() (WeightedDiGraphMatcher	degree_iter() (MultiGraph method), 92
method), 157	degree_sequence_tree() (in module networkx), 206
candidate_pairs_iter() (WeightedGraphMatcher method),	dense_gnm_random_graph() (in module networkx), 195
155	desargues_graph() (in module networkx), 191
candidate_pairs_iter() (WeightedMultiDiGraphMatcher	dfs_postorder() (in module networkx), 180 dfs_predecessor() (in module networkx), 180
method), 161	dfs_preorder() (in module networkx), 179
candidate_pairs_iter() (WeightedMultiGraphMatcher	dfs_successor() (in module networkx), 179
method), 159	dfs_tree() (in module networkx), 180
cartesian_product() (in module networkx), 130 center() (in module networkx), 169	diameter() (in module networkx), 168
chvatal_graph() (in module networkx), 109	diamond_graph() (in module networkx), 192
circular_ladder_graph() (in module networkx), 191	dictionary, 267
circular_layout() (in module networkx), 187	difference() (in module networkx), 132
clear() (DiGraph method), 46	DiGraph() (in module networkx), 36
clear() (Graph method), 20	dijkstra_path() (in module networkx), 173
clear() (MultiDiGraph method), 106	dijkstra_path_length() (in module networkx), 173
clear() (MultiGraph method), 78	dijkstra_predecessor_and_distance() (in module net-
cliques_containing_node() (in module networkx), 144	workx), 177
closeness_centrality() (in module networkx), 141	discrete_sequence() (in module networkx.utils), 259
clustering() (in module networkx), 146	disjoint_union() (in module networkx), 131
complement() (in module networkx), 131	dodecahedral_graph() (in module networkx), 192
complete_bipartite_graph() (in module networkx), 187	dorogovtsev_goltsev_mendes_graph() (in module net-
complete_graph() (in module networkx), 187	workx), 187
compose() (in module networkx), 130	double_edge_swap() (in module networkx), 207
configuration model() (in module networky) 204	draw() (in module networkx), 241

get_edge_data() (Graph method), 23 get_edge_data() (MultiDiGraph method), 113 get_edge_data() (MultiGraph method), 82 gn_graph() (in module networkx), 210 gnc_graph() (in module networkx), 211 gnm_random_graph() (in module networkx), 196 gnp_random_graph() (in module networkx), 195 gnr_graph() (in module networkx), 211 google_matrix() (in module networkx), 163 Graph() (in module networkx), 9 graph_atlas_g() (in module networkx), 185 graph_clique_number() (in module networkx), 144
graph_number_of_cliques() (in module networkx), 144
graphviz_layout() (in module networkx), 247, 249
grid_2d_graph() (in module networkx), 188
grid_graph() (in module networkx), 188
Н
has_edge() (DiGraph method), 57 has_edge() (Graph method), 28
has_edge() (MultiDiGraph method), 118
has_edge() (MultiGraph method), 87
has_node() (DiGraph method), 56
has_node() (Graph method), 28
has_node() (MultiDiGraph method), 117
has_node() (MultiGraph method), 86
hashable, 267
havel_hakimi_graph() (in module networkx), 206
heawood_graph() (in module networkx), 192
hits() (in module networkx), 163
hits_numpy() (in module networkx), 164
hits_scipy() (in module networkx), 164
house_graph() (in module networkx), 192
house_x_graph() (in module networkx), 192
hub_matrix() (in module networkx), 164 hypercube_graph() (in module networkx), 188
hypercube_graph() (in module networks), 188
icosahedral_graph() (in module networkx), 192
in_degree() (DiGraph method), 62
in_degree() (MultiDiGraph method), 123
in_degree_iter() (DiGraph method), 63
in_degree_iter() (MultiDiGraph method), 124
in_edges() (DiGraph method), 52
in_edges() (MultiDiGraph method), 112
in_edges_iter() (DiGraph method), 52
in_edges_iter() (MultiDiGraph method), 112
initialize() (DiGraphMatcher method), 152
initialize() (GraphMatcher method), 150
initialize() (WeightedDiGraphMatcher method), 156
initialize() (WeightedGraphMatcher method), 155
initialize() (WeightedMultiDiGraphMatcher method), 160
initialize() (WeightedMultiGraphMatcher method), 158

intersection() (in module networkx), 132 is_bipartite() (in module networkx), 180 is_connected() (in module networkx), 164 is_directed_acyclic_graph() (in module networkx), 168 is_frozen() (in module networkx), 136 is_is_accomplice() (DiGraph Motokay mathed), 153	match() (WeightedGraphMatcher method), 155 match() (WeightedMultiDiGraphMatcher method), 161 match() (WeightedMultiGraphMatcher method), 159 max_weight_matching() (in module networkx), 148 moebius_kantor_graph() (in module networkx), 193
is_isomorphic() (DiGraphMatcher method), 153	mst() (in module networkx), 182
is_isomorphic() (GraphMatcher method), 150	MultiDiGraph() (in module networkx), 95
is_isomorphic() (in module networkx), 148 is_isomorphic() (WeightedDiGraphMatcher method), 157	MultiGraph() (in module networkx), 67
is_isomorphic() (WeightedGraphMatcher method), 157 is_isomorphic() (WeightedGraphMatcher method), 155	N
is_isomorphic() (WeightedMultiDiGraphMatcher	
method), 160	nbunch, 267
is_isomorphic() (WeightedMultiGraphMatcher method),	nbunch_iter() (DiGraph method), 55
158	nbunch_iter() (Graph method), 27
is_kl_connected() (in module networkx), 213	nbunch_iter() (MultiDiGraph method), 116
is_list_of_ints() (in module networkx., 213	nbunch_iter() (MultiGraph method), 86
is_string_like() (in module networkx.utils), 257	neighbors() (DiGraph method), 53
is_strongly_connected() (in module networkx, 166	neighbors() (Graph method), 24
is_valid_degree_sequence() (in module networkx), 206	neighbors() (MultiGraph method), 113
isomorphisms_iter() (DiGraphMatcher method), 153	neighbors () (MultiGraph method), 83
isomorphisms_iter() (GraphMatcher method), 151	neighbors_iter() (DiGraph method), 53 neighbors_iter() (Graph method), 25
isomorphisms_iter() (WeightedDiGraphMatcher	neighbors_iter() (MultiDiGraph method), 114
method), 157	neighbors_iter() (MultiGraph method), 84
isomorphisms_iter() (WeightedGraphMatcher method),	networkx.algorithms.bipartite (module), 180
155	networkx.algorithms.boundary (module), 137
isomorphisms_iter() (WeightedMultiDiGraphMatcher	networkx.algorithms.contrality (module), 137
method), 161	networkx.algorithms.clique (module), 142
isomorphisms_iter() (WeightedMultiGraphMatcher	networkx.algorithms.cluster (module), 145
method), 159	networkx.algorithms.core (module), 147
iterable() (in module networkx.utils), 257	networkx.algorithms.hits (module), 163
	networkx.algorithms.matching (module), 148
K	networkx.algorithms.mst (module), 182
kl_connected_subgraph() (in module networkx), 213	networkx.algorithms.pagerank (module), 161
kosaraju_strongly_connected_components() (in module	networkx.algorithms.traversal.astar (module), 178
networkx), 166	networkx.algorithms.traversal.component (module), 164
krackhardt_kite_graph() (in module networkx), 192	networkx.algorithms.traversal.dag (module), 167
1	networkx.algorithms.traversal.distance (module), 168
L	networkx.algorithms.traversal.path (module), 169
ladder_graph() (in module networkx), 188	networkx.algorithms.traversal.search (module), 179
laplacian() (in module networkx), 217	networkx.convert (module), 219
laplacian_spectrum() (in module networkx), 218	networkx.drawing.layout (module), 250
LCF_graph() (in module networkx), 191	networkx.drawing.nx_agraph (module), 245
li_smax_graph() (in module networkx), 208	networkx.drawing.nx_pydot (module), 248
line_graph() (in module networkx), 133	networkx.drawing.nx_pylab (module), 241
load_centrality() (in module networkx), 139	networkx.exception (module), 255
lollipop_graph() (in module networkx), 189	networkx.operators (module), 129
N /	networkx.readwrite.adjlist (module), 227
M	networkx.readwrite.edgelist (module), 231
make_clique_bipartite() (in module networkx), 144	networkx.readwrite.gml (module), 233
make_max_clique_graph() (in module networkx), 143	networkx.readwrite.gpickle (module), 235
make_small_graph() (in module networkx), 190	networkx.readwrite.graphml (module), 236
match() (DiGraphMatcher method), 153	networkx.readwrite.leda (module), 236
match() (GraphMatcher method), 151	networkx.readwrite.nx_yaml (module), 237
match() (Weighted Di Graph Matcher method) 157	networkx.readwrite.paiek (module), 238

networkx.readwrite.sparsegraph6 (module), 237 networkx.utils (module), 257 NetworkXError (class in networkx), 255	out_edges() (MultiDiGraph method), 110 out_edges_iter() (DiGraph method), 51 out_edges_iter() (MultiDiGraph method), 111
NetworkXException (class in networkx), 255 newman_watts_strogatz_graph() (in module networkx),	Р
node, 267 node attribute, 267 node boundary() (in module networkx), 138 node_clique_number() (in module networkx), 144 node_connected_component() (in module networkx), 165 nodes() (DiGraph method), 47 nodes() (Graph method), 20 nodes() (MultiDiGraph method), 107 nodes() (MultiGraph method), 79 nodes_iter() (DiGraph method), 48 nodes_iter() (Graph method), 21 nodes_iter() (MultiDiGraph method), 108 nodes_iter() (MultiGraph method), 79 nodes_with_selfloops() (DiGraph method), 58 nodes_with_selfloops() (Graph method), 29 nodes_with_selfloops() (MultiDiGraph method), 118 nodes_with_selfloops() (MultiGraph method), 88 normalized_laplacian() (in module networkx), 217 null_graph() (in module networkx), 189 number_connected_components() (in module networkx), 165 number_of_cliques() (in module networkx), 144 number_of_edges() (DiGraph method), 60	pagerank() (in module networkx), 162 pagerank_numpy() (in module networkx), 162 pagerank_scipy() (in module networkx), 163 pappus_graph() (in module networkx), 193 pareto_sequence() (in module networkx.utils), 258 parse_gml() (in module networkx), 235 parse_graph6() (in module networkx), 238 parse_graphml() (in module networkx), 236 parse_leda() (in module networkx), 237 parse_pajek() (in module networkx), 239 parse_sparse6() (in module networkx), 238 path_graph() (in module networkx), 189 periphery() (in module networkx), 169 petersen_graph() (in module networkx), 169 petersen_graph() (in module networkx), 193 powerlaw_cluster_graph() (in module networkx), 201 powerlaw_sequence() (in module networkx), 177 predecessors() (DiGraph method), 54 predecessors() (MultiDiGraph method), 54 predecessors_iter() (DiGraph method), 54 predecessors_iter() (MultiDiGraph method), 115 project() (in module networkx), 181 pydot_layout() (in module networkx), 250 pygraphviz_layout() (in module networkx), 247
number_of_edges() (Graph method), 31 number_of_edges() (MultiDiGraph method), 121 number_of_edges() (MultiGraph method), 90 number_of_nodes() (DiGraph method), 59 number_of_nodes() (Graph method), 30 number_of_nodes() (MultiDiGraph method), 120 number_of_nodes() (MultiGraph method), 89 number_of_selfloops() (DiGraph method), 61 number_of_selfloops() (Graph method), 32 number_of_selfloops() (MultiDiGraph method), 122 number_of_selfloops() (MultiDiGraph method), 91 number_strongly_connected_components() (in module networkx), 166	radius() (in module networkx), 168 random_geometric_graph() (in module networkx), 213 random_layout() (in module networkx), 251 random_lobster() (in module networkx), 202 random_powerlaw_tree() (in module networkx), 203 random_powerlaw_tree_sequence() (in module networkx), 203 random_regular_graph() (in module networkx), 200 random_shell_graph() (in module networkx), 202 read_adjlist() (in module networkx), 227 read_dot() (in module networkx), 246, 249
0	read_edgelist() (in module networkx), 231 read_gml() (in module networkx), 233
octahedral_graph() (in module networkx), 193 order() (DiGraph method), 59 order() (Graph method), 30 order() (MultiDiGraph method), 120 order() (MultiGraph method), 89 out_degree() (DiGraph method), 64 out_degree() (MultiDiGraph method), 125 out_degree_iter() (DiGraph method), 64 out_degree_iter() (MultiDiGraph method), 125	read_gpickle() (in module networkx), 236 read_graph6() (in module networkx), 237 read_graph6_list() (in module networkx), 238 read_graphml() (in module networkx), 236 read_leda() (in module networkx), 237 read_multiline_adjlist() (in module networkx), 229 read_pajek() (in module networkx), 238 read_sparse6() (in module networkx), 238 read_sparse6_list() (in module networkx), 238
out_edges() (DiGraph method), 50	read_vaml() (in module networkx), 237

relabel_nodes() (in module networkx), 134	single_source_shortest_path() (in module networkx), 171
remove_edge() (DiGraph method), 44	single_source_shortest_path_length() (in module net-
remove_edge() (Graph method), 17	workx), 171
remove_edge() (MultiDiGraph method), 103	size() (DiGraph method), 60
remove_edge() (MultiGraph method), 75	size() (Graph method), 31
remove_edges_from() (DiGraph method), 44	size() (MultiDiGraph method), 121
remove_edges_from() (Graph method), 18	size() (MultiGraph method), 90
remove_edges_from() (MultiDiGraph method), 104	spectral_layout() (in module networkx), 252
remove_edges_from() (MultiGraph method), 76	spring_layout() (in module networkx), 251
remove_node() (DiGraph method), 40	star_graph() (in module networkx), 189
remove_node() (Graph method), 14	stochastic_graph() (in module networkx), 134
remove_node() (MultiDiGraph method), 100	strongly_connected_component_subgraphs() (in module
remove_node() (MultiGraph method), 72	networkx), 166
remove_nodes_from() (DiGraph method), 41	strongly_connected_components() (in module networkx),
remove_nodes_from() (Graph method), 15	166
remove_nodes_from() (MultiDiGraph method), 100	strongly_connected_components_recursive() (in module
remove_nodes_from() (MultiGraph method), 72	networkx), 166
reverse() (DiGraph method), 66	subgraph() (DiGraph method), 66
reverse() (MultiDiGraph method), 127	subgraph() (Graph method), 35
0	subgraph() (in module networkx), 129
S	subgraph() (MultiDiGraph method), 127
s_metric() (in module networkx), 209	subgraph() (MultiGraph method), 94
scale_free_graph() (in module networkx), 212	$subgraph\_is\_isomorphic()  (DiGraphMatcher  method),$
scipy_discrete_sequence() (in module networkx.utils),	153
260	subgraph_is_isomorphic() (GraphMatcher method), 151
scipy_pareto_sequence() (in module networkx.utils), 259	subgraph_is_isomorphic() (WeightedDiGraphMatcher
scipy_poisson_sequence() (in module networkx.utils),	method), 157
259	subgraph_is_isomorphic() (WeightedGraphMatcher
scipy_powerlaw_sequence() (in module networkx.utils),	method), 155
259	subgraph_is_isomorphic() (WeightedMultiDiGraph-
scipy_uniform_sequence() (in module networkx.utils),	Matcher method), 160
259	subgraph_is_isomorphic() (WeightedMultiGraphMatcher
sedgewick_maze_graph() (in module networkx), 193	method), 158
selfloop_edges() (DiGraph method), 58	subgraph_isomorphisms_iter() (DiGraphMatcher
selfloop_edges() (Graph method), 29	method), 153
selfloop_edges() (MultiDiGraph method), 119	subgraph_isomorphisms_iter() (GraphMatcher method),
selfloop_edges() (MultiGraph method), 88	151
semantic_feasibility() (DiGraphMatcher method), 153	subgraph_isomorphisms_iter() (WeightedDiGraph-
semantic_feasibility() (GraphMatcher method), 151	Matcher method), 157
semantic_feasibility() (WeightedDiGraphMatcher	subgraph_isomorphisms_iter() (WeightedGraphMatcher
method), 157	method), 155
semantic_feasibility() (WeightedGraphMatcher method),	subgraph_isomorphisms_iter() (WeightedMultiDiGraph-
155	Matcher method), 161
semantic_feasibility() (WeightedMultiDiGraphMatcher	subgraph_isomorphisms_iter() (WeightedMultiGraph-
method), 161	Matcher method), 159
semantic_feasibility() (WeightedMultiGraphMatcher	successors() (DiGraph method), 54
method), 159	successors() (MultiDiGraph method), 114
shell_layout() (in module networkx), 251	successors_iter() (DiGraph method), 54
shortest_path() (in module networkx), 170	successors_iter() (MultiDiGraph method), 114
shortest_path_length() (in module networkx), 170	symmetric_difference() (in module networkx), 133
single_source_dijkstra() (in module networkx), 175	syntactic_feasibility() (DiGraphMatcher method), 154
single_source_dijkstra_path() (in module networkx), 174	syntactic_feasibility() (GraphMatcher method), 152
single_source_dijkstra_path_length() (in module net-	syntactic_feasibility() (WeightedDiGraphMatcher
workx), 174	method), 157

```
syntactic feasibility() (WeightedGraphMatcher method),
         156
syntactic feasibility()
                       (WeightedMultiDiGraphMatcher
         method), 161
syntactic feasibility()
                          (WeightedMultiGraphMatcher
         method), 159
Т
tetrahedral_graph() (in module networkx), 193
to agraph() (in module networkx), 246
to dict of dicts() (in module networkx), 221
to_dict_of_lists() (in module networkx), 220
to directed() (Graph method), 34
to_directed() (MultiGraph method), 93
to edgelist() (in module networkx), 222
to numpy matrix() (in module networkx), 223
to pydot() (in module networkx), 248
to scipy sparse matrix() (in module networkx), 224
to_undirected() (DiGraph method), 65
to_undirected() (MultiDiGraph method), 126
topological_sort() (in module networkx), 167
topological_sort_recursive() (in module networkx), 167
transitivity() (in module networkx), 145
triangles() (in module networkx), 145
trivial_graph() (in module networkx), 189
truncated_cube_graph() (in module networkx), 193
truncated_tetrahedron_graph() (in module networkx), 193
tutte graph() (in module networkx), 193
U
uniform sequence() (in module networkx.utils), 258
union() (in module networkx), 131
union() (UnionFind method), 258
W
watts_strogatz_graph() (in module networkx), 198
wheel graph() (in module networkx), 189
write_adjlist() (in module networkx), 228
write_dot() (in module networkx), 246, 249
write edgelist() (in module networkx), 232
write gml() (in module networkx), 234
write gpickle() (in module networkx), 236
write_multiline_adjlist() (in module networkx), 230
write pajek() (in module networkx), 239
write_yaml() (in module networkx), 237
```