

# Correcting for measurement uncertainty in space weather

Magnetosheath control of the cross polar cap potential

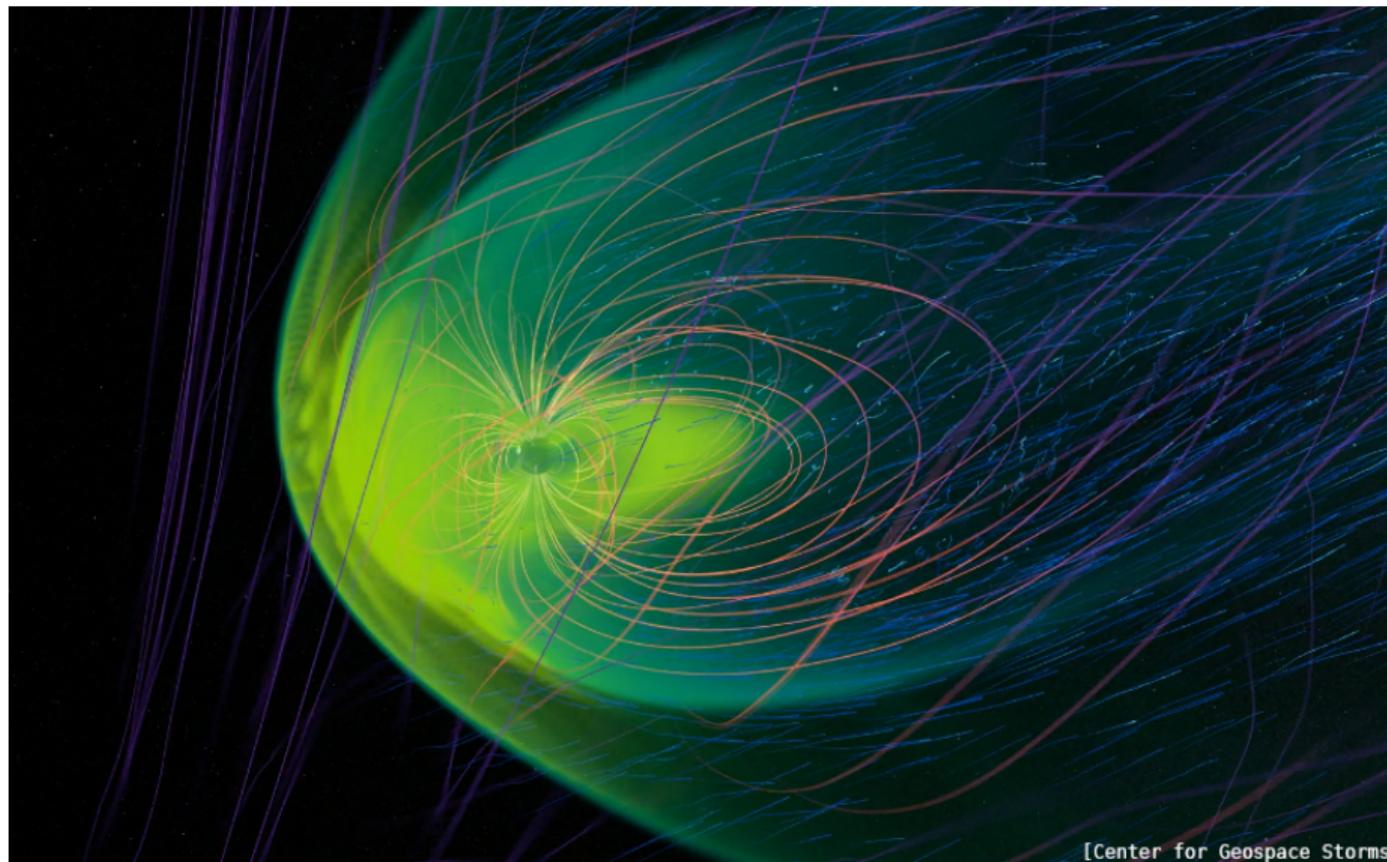
**Connor O'Brien<sup>1</sup>, Brian Walsh<sup>1</sup>, Evan Thomas<sup>2</sup>**

November 8, 2024

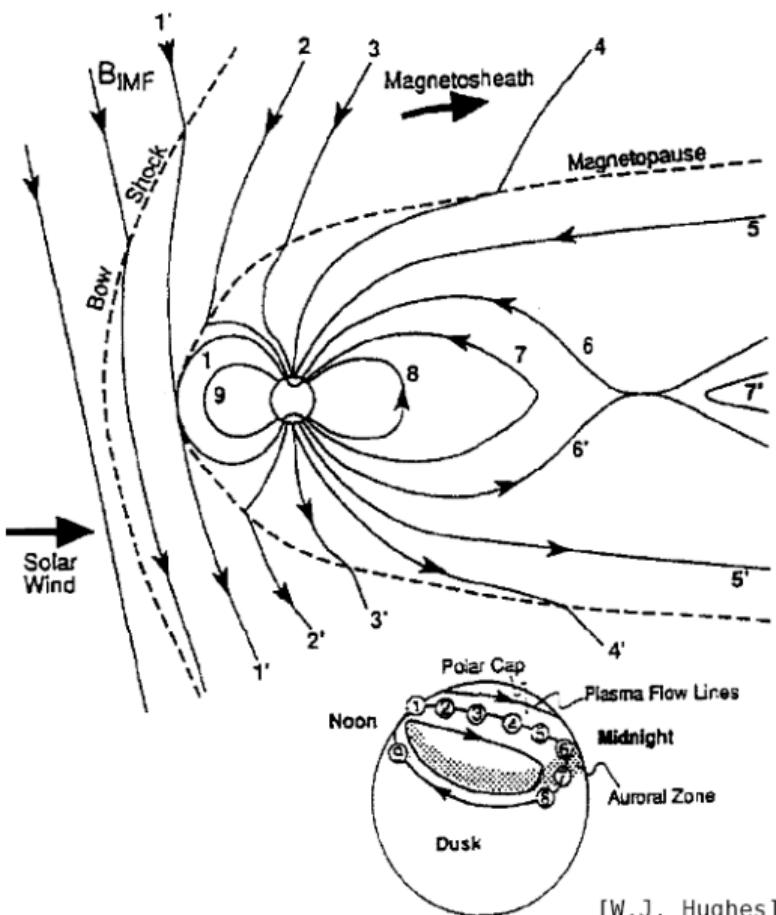
1: Center for Space Physics, Boston University, Boston, MA, USA

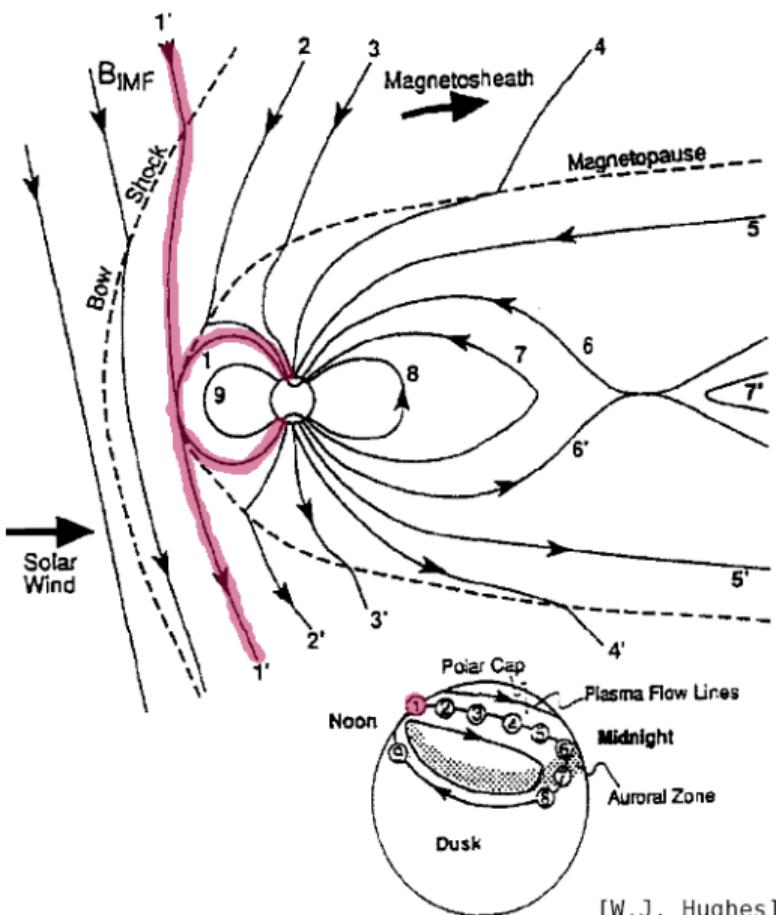
2: Thayer School of Engineering, Dartmouth College, Hanover, NH, USA

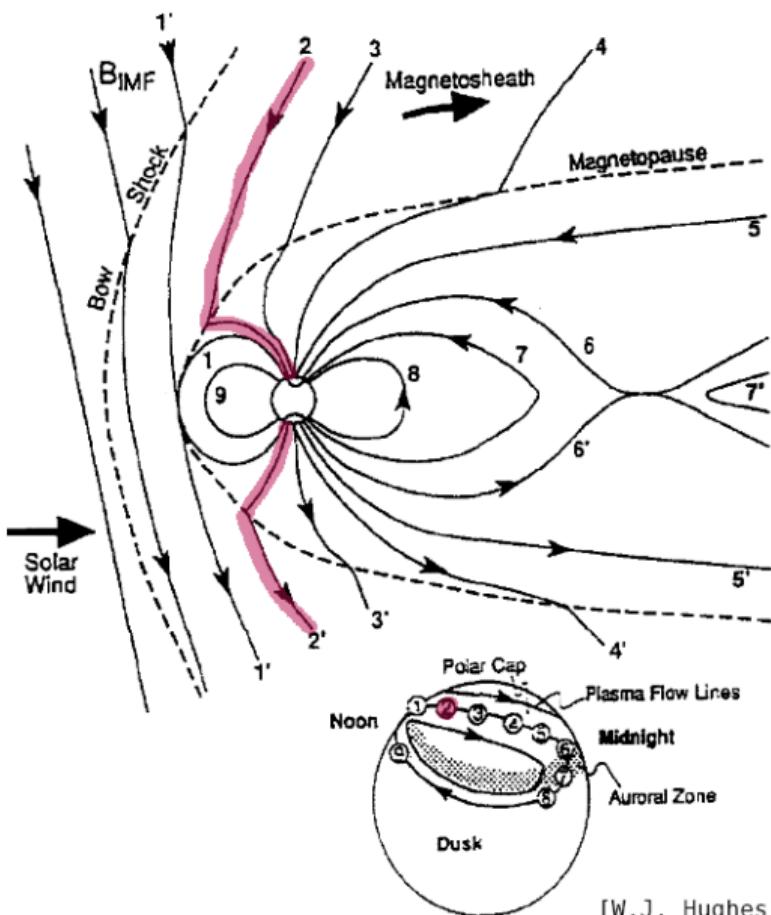


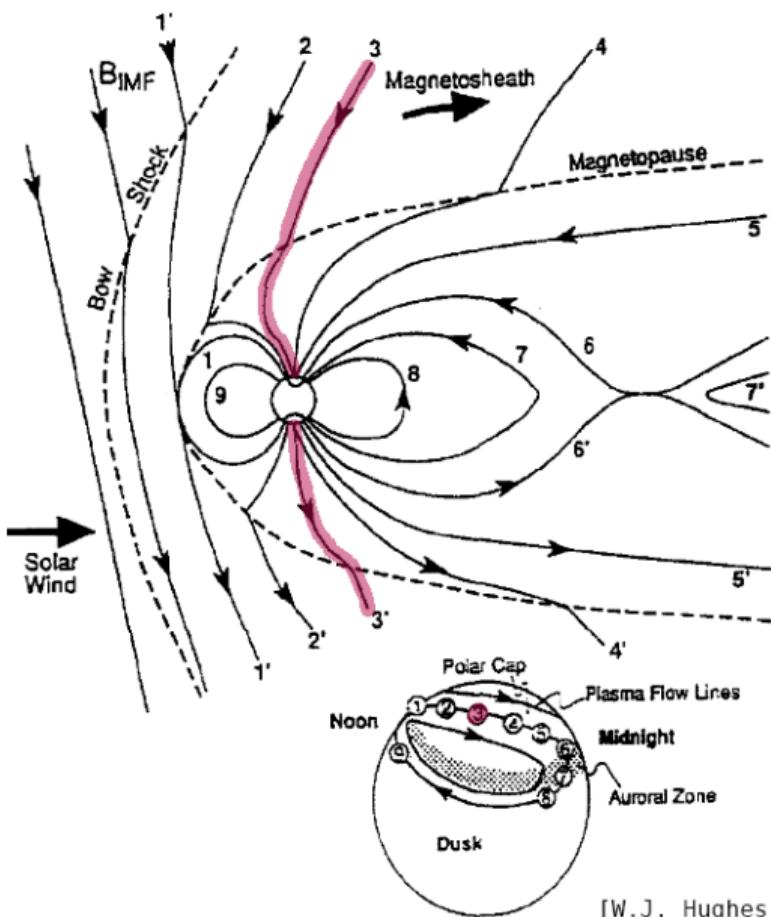


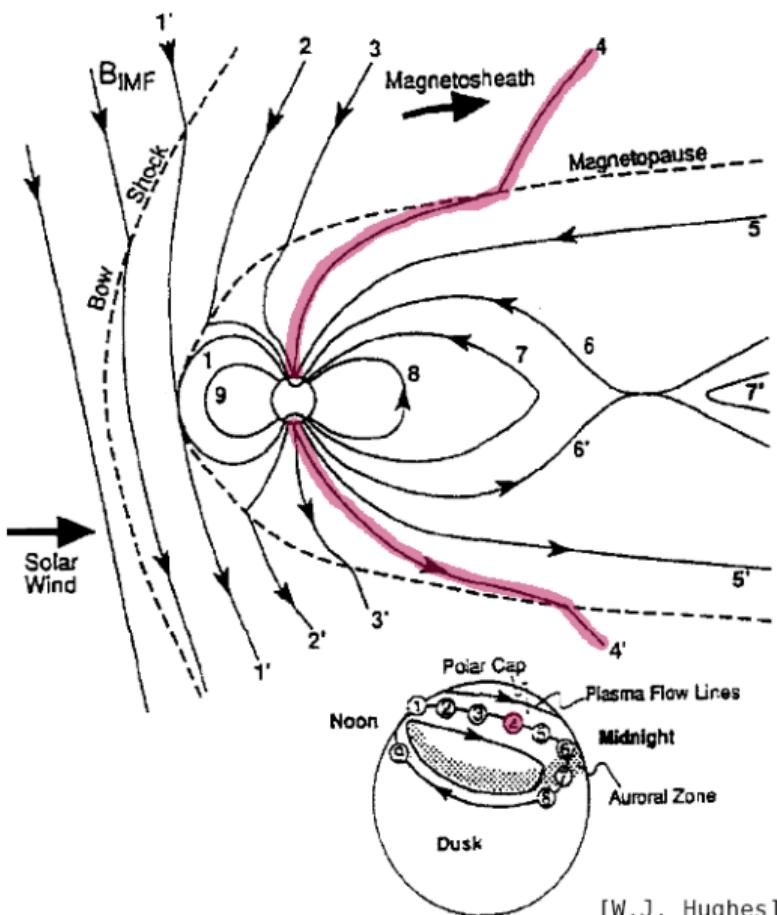
[Center for Geospace Storms]

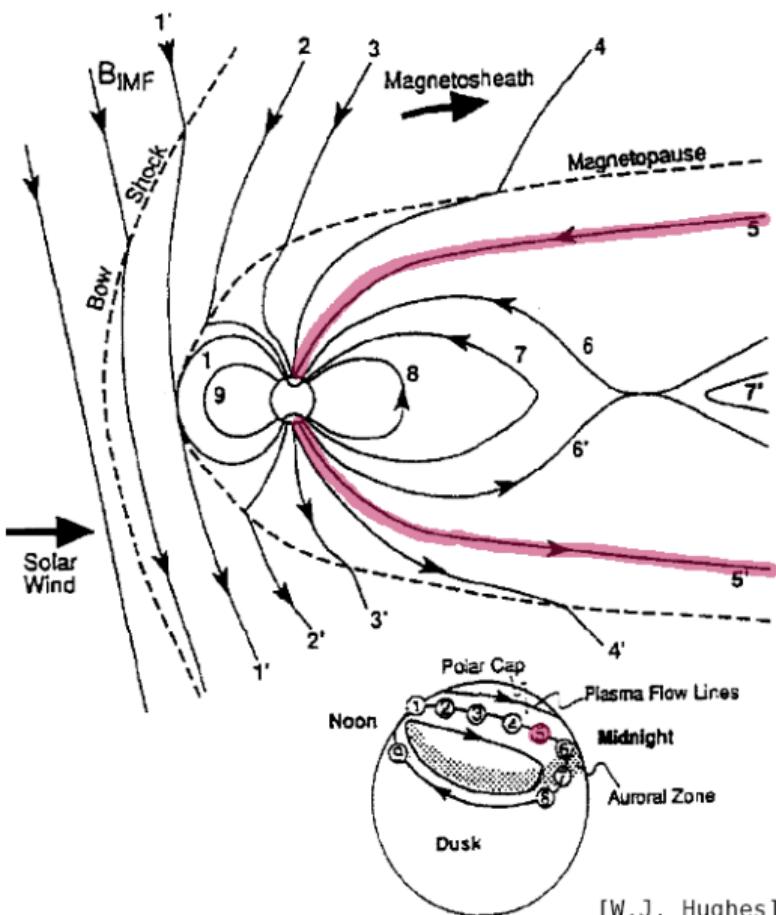


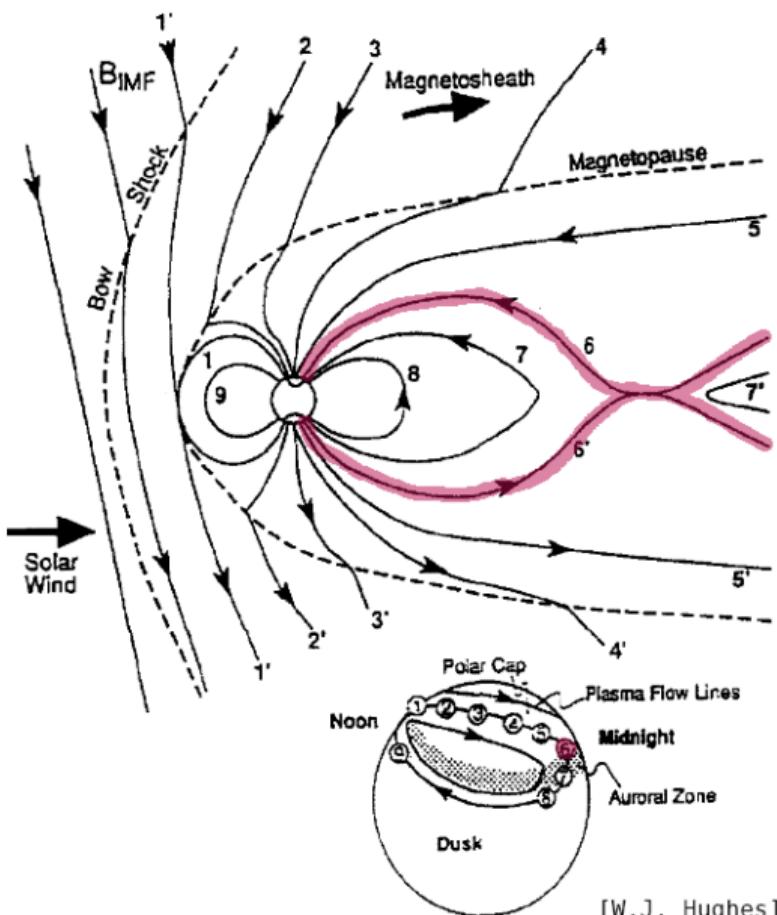


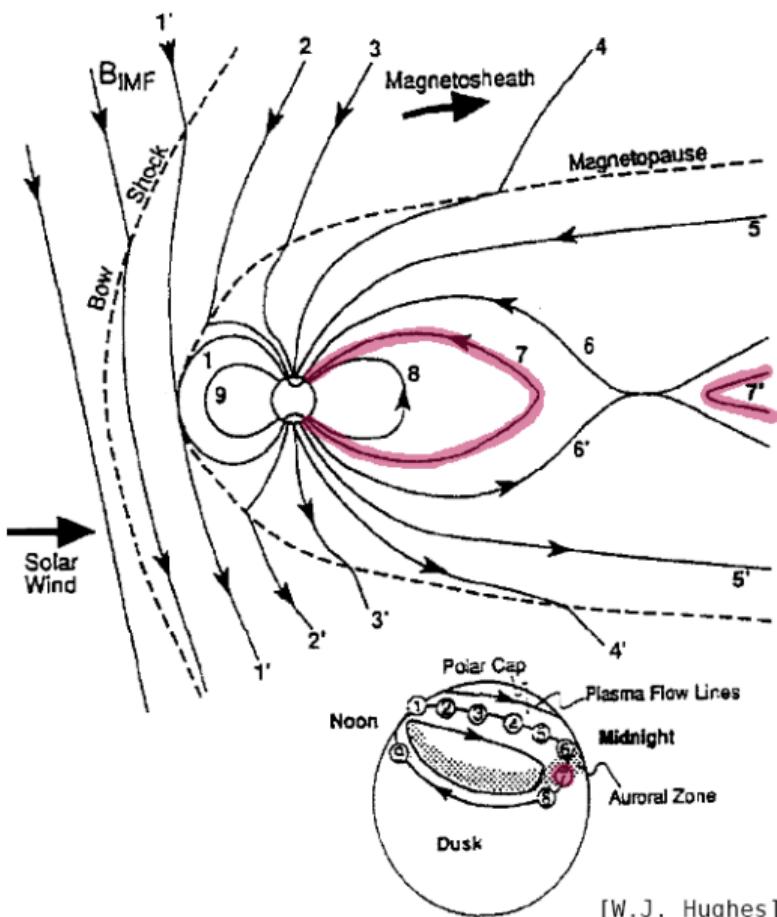


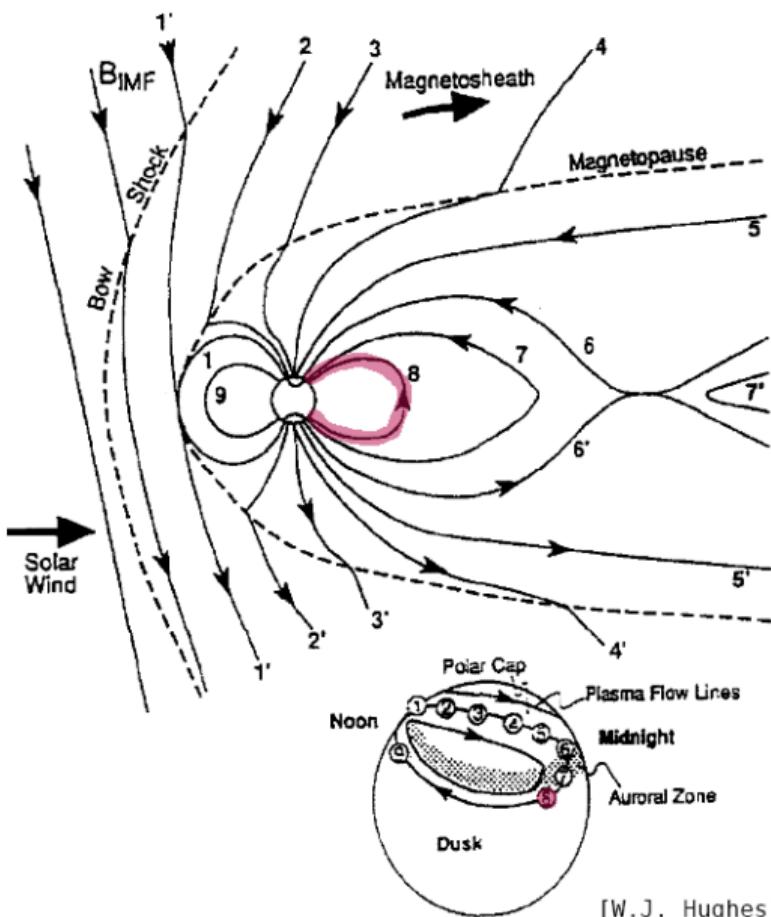


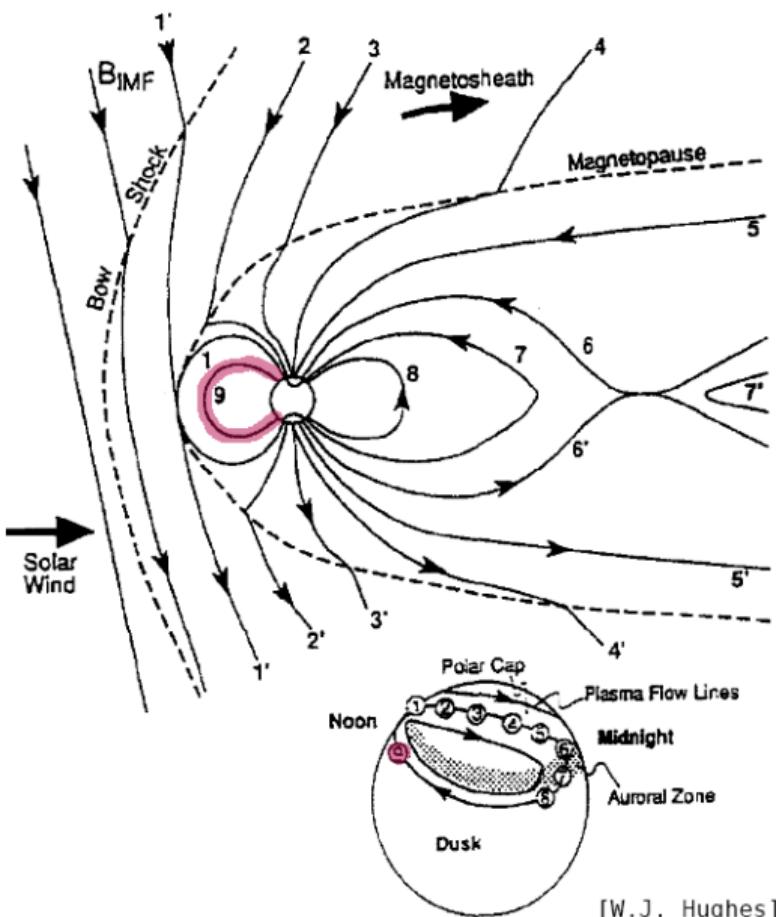




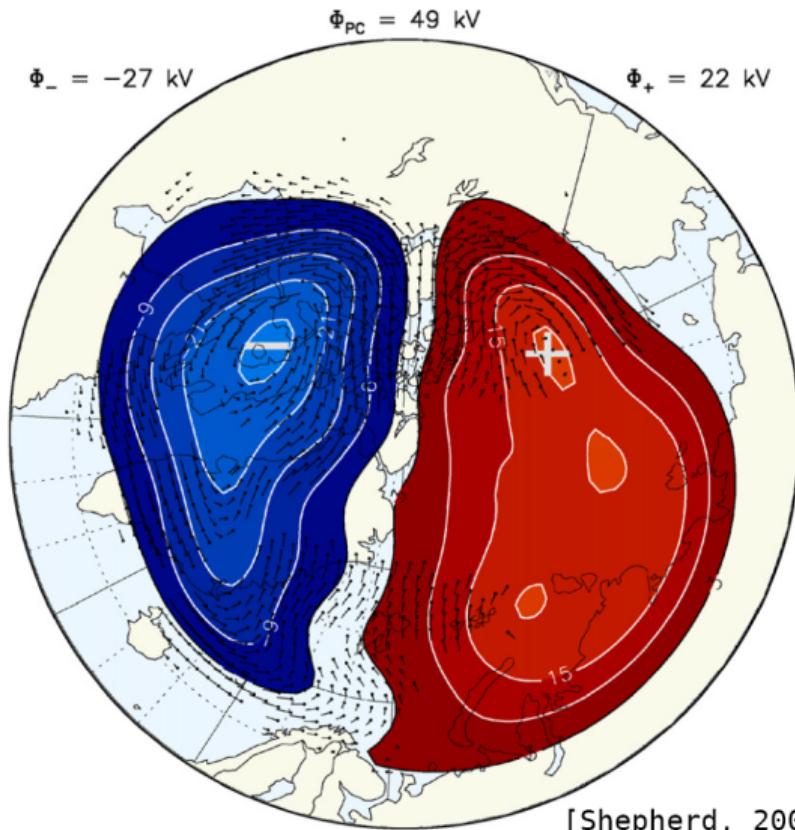


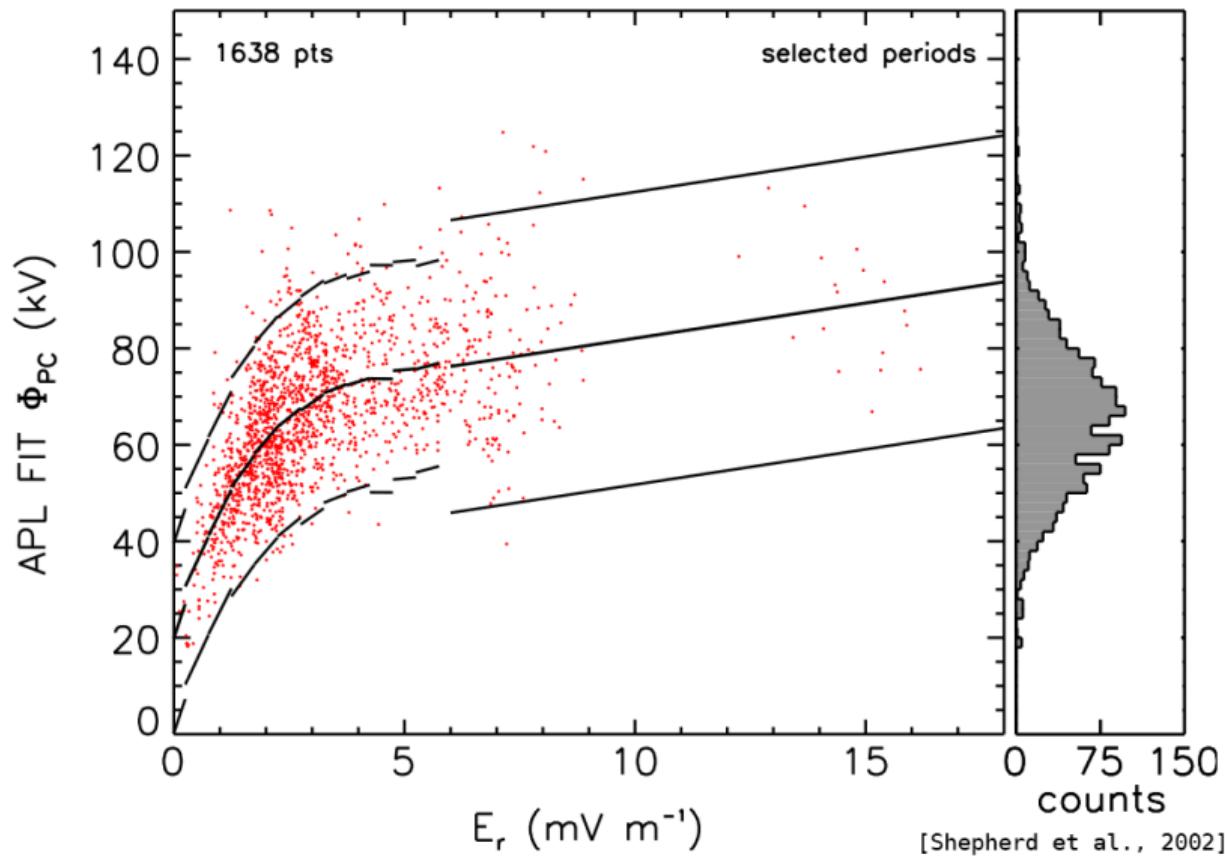


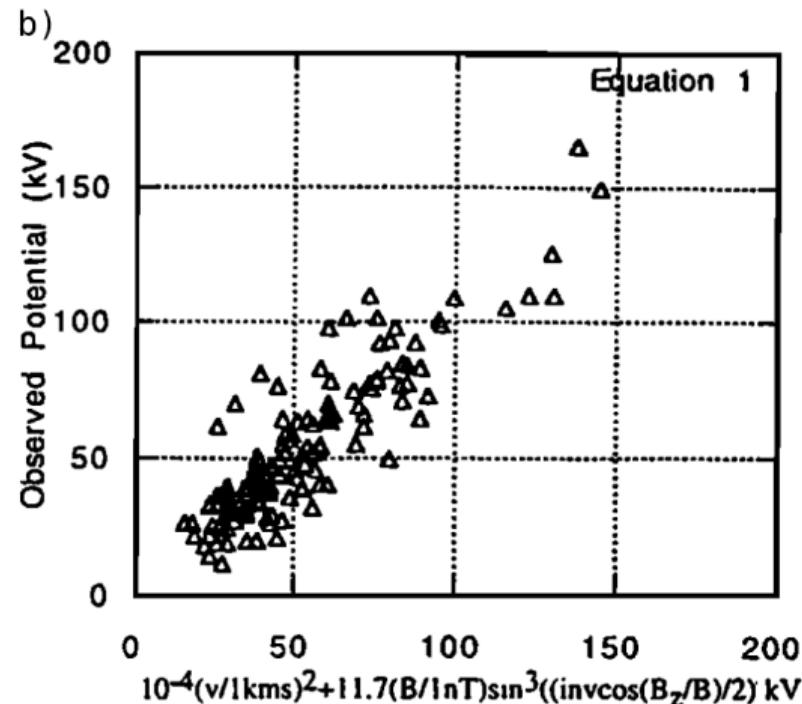
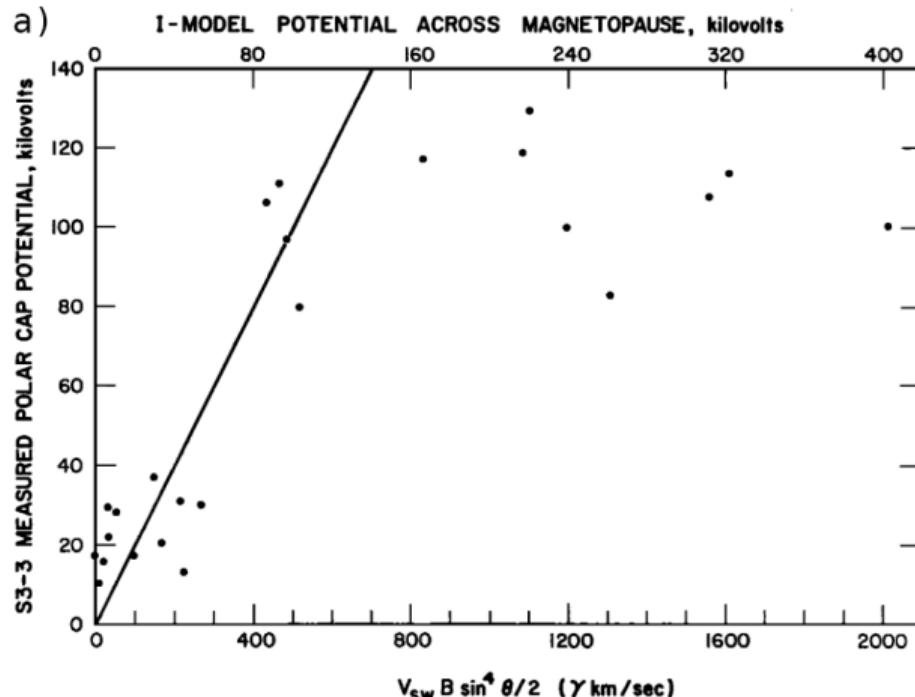




- Plasma moving perpendicular to  $\vec{B}$  in a collisionless environment necessitates a convection electric field (Ohm's law):  
$$\vec{E} = \vec{v} \times \vec{B}.$$
- The size of the convection potential is called the polar cap potential  $\phi_{PC}$ .
- This electric field is *notionally* the reconnection electric field at the magnetopause applied to the ionosphere.
- **How does  $\phi_{PC}$  respond to the solar wind electric field?**







a) Wygant et al. 1983, saturation at  $E_M = 0.5\text{mV/m}$  b) Boyle et al. 1997, no saturation

Consider the dependent variable  $Y$

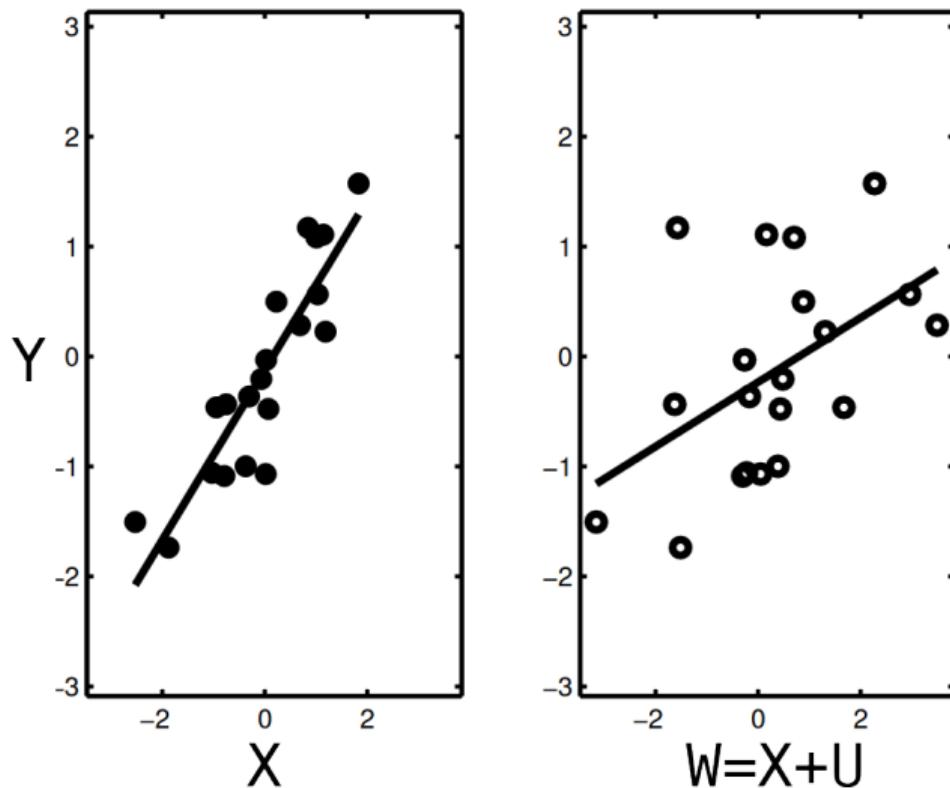
$$Y = \beta_X X + \beta_0 + \epsilon \quad (1)$$

Where  $\epsilon$  is some random error.

When trying to determine  $\beta_X$  and  $\beta_0$ , we can't regress  $Y$  on  $X$ . We only have access to the error prone measurement of  $X$  we call  $W$ :

$$W = X + U \quad (2)$$

If  $U$  is uncorrelated with  $X$ , regressing  $Y$  on  $W$  gives an underestimate of  $\beta_X$ .

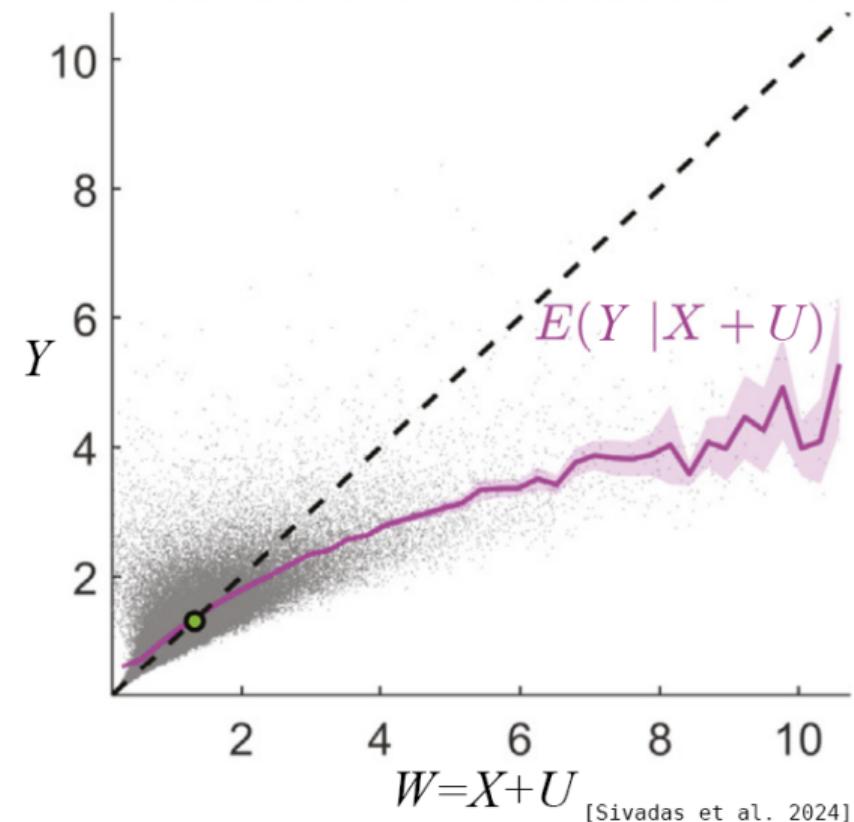


[Carroll, 2006]

If  $U$  is correlated with  $X$ , regressing  $Y$  on  $W$  creates an apparent nonlinear relationship between  $Y$  and  $W$ .

The correlation between  $X$  and  $U$  controls the amount and direction of the bias.

**Could this bias from measurement uncertainty be responsible for disagreement about  $\phi_{PC}$  saturation?**



What part of the variation of  $\phi_{PC}$  with respect to solar wind driving is physics, and what part is just uncertainty?

## Solar Wind and Magnetosheath Data

# PRIME

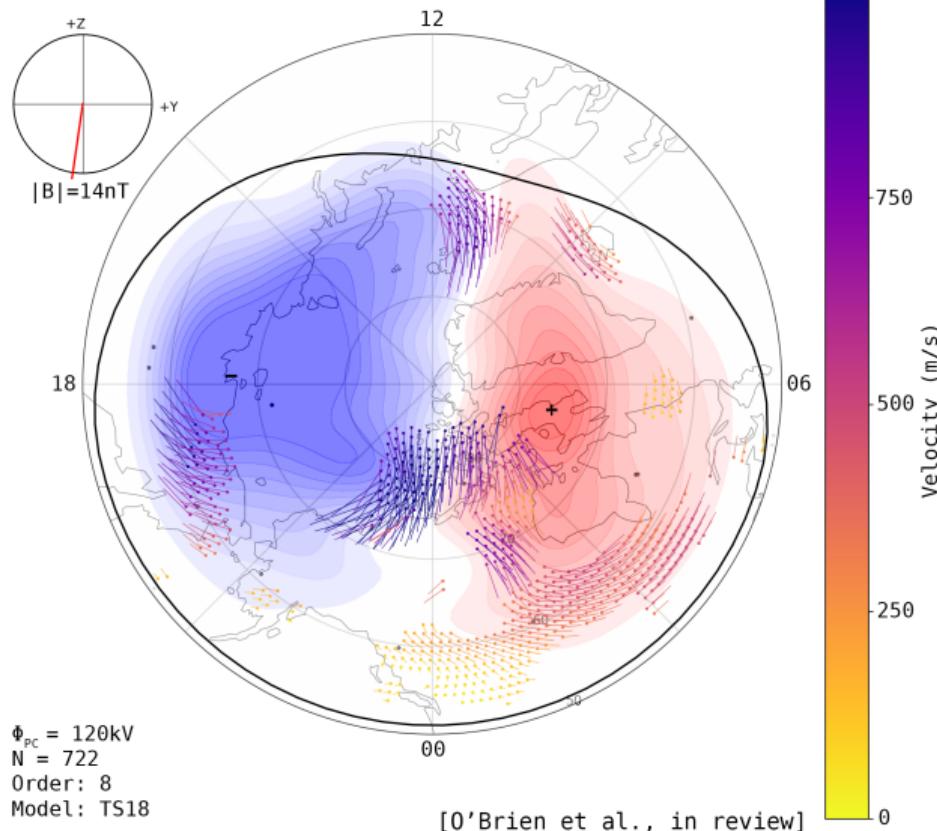
- Probabilistic solar wind prediction algorithm
- Predicts solar wind just upstream of Earth's bow shock using solar wind data from L1
- Propagation location:  $13.25R_E$  upstream of Earth on Sun-Earth line
- Used to obtain 2min-cadence  $\vec{v}_{ion}$ ,  $\vec{B}$ , and  $n_E$  with uncertainties from 2013-2022

# PRIME [SH]

- Probabilistic magnetosheath prediction algorithm
- Predicts plasma and magnetic field in dayside magnetosheath using solar wind data from L1
- Propagation location: Middle of magnetosheath  $0.5 - 1R_E$  downstream of bow shock
- Used to obtain 2min-cadence  $\vec{v}_{ion}$ ,  $\vec{B}$ ,  $n_{ion}$ ,  $T_{\perp}$ , and  $T_{\parallel}$  with uncertainties from 2013-2022

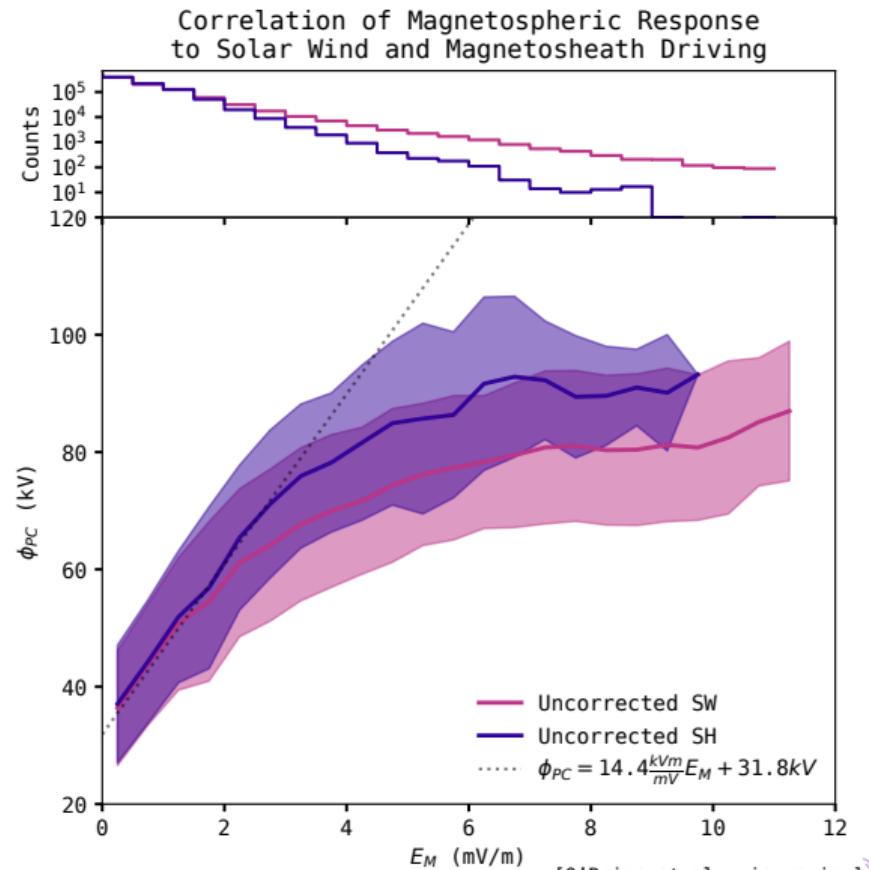
From both datasets, we calculate  $\vec{E}_M = v_X B_Z$  in GSM coordinates.

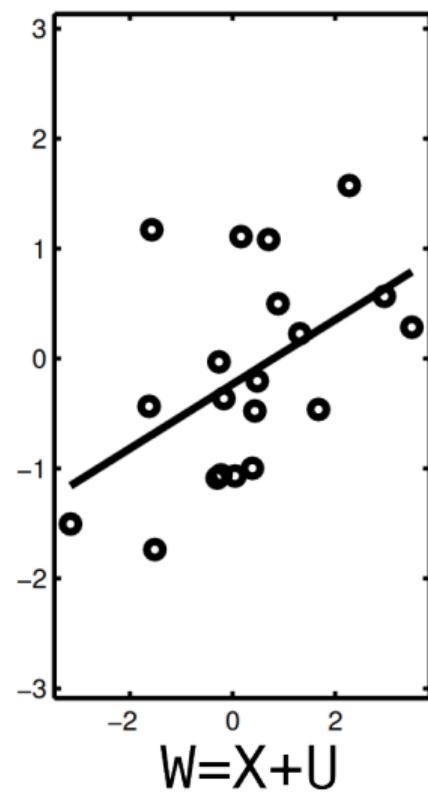
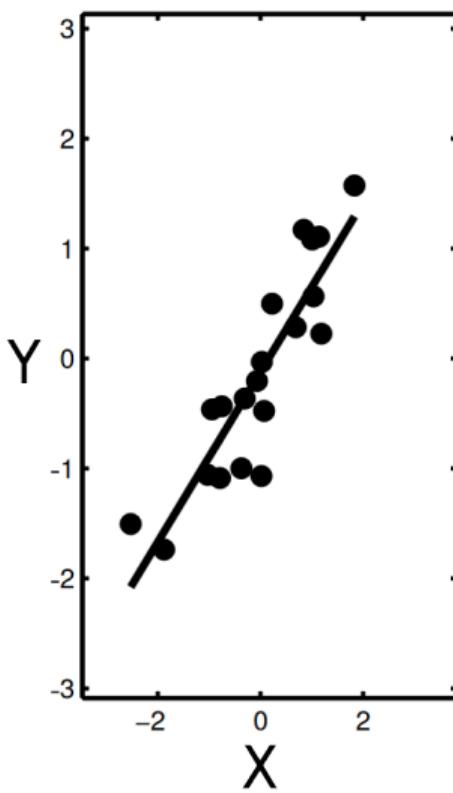
## 2013-03-17 Geomagnetic Storm (09:06 UTC)



- SuperDARN is a network of 30+ HF coherent backscatter radars in the northern and southern hemispheres.
- SuperDARN is used to measure plasma convection vectors once every 2 minutes for 10 years (2013-2022).
- Then, spherical harmonics are fit to the convection maps to get  $\phi_{PC}$ .

- $\phi_{PC}$  is correlated with the solar wind and magnetosheath  $E_M$
- An initially linear relationship (dotted line) becomes nonlinear and saturates for both regimes
- $\phi_{PC}$  saturates with respect to solar wind  $E_M > 3.5 \text{ mV/m}$
- $\phi_{PC}$  saturates with respect to magnetosheath  $E_M > 4.5 \text{ mV/m}$
- **Is this a symptom of regression bias?**





[Carroll, 2006]

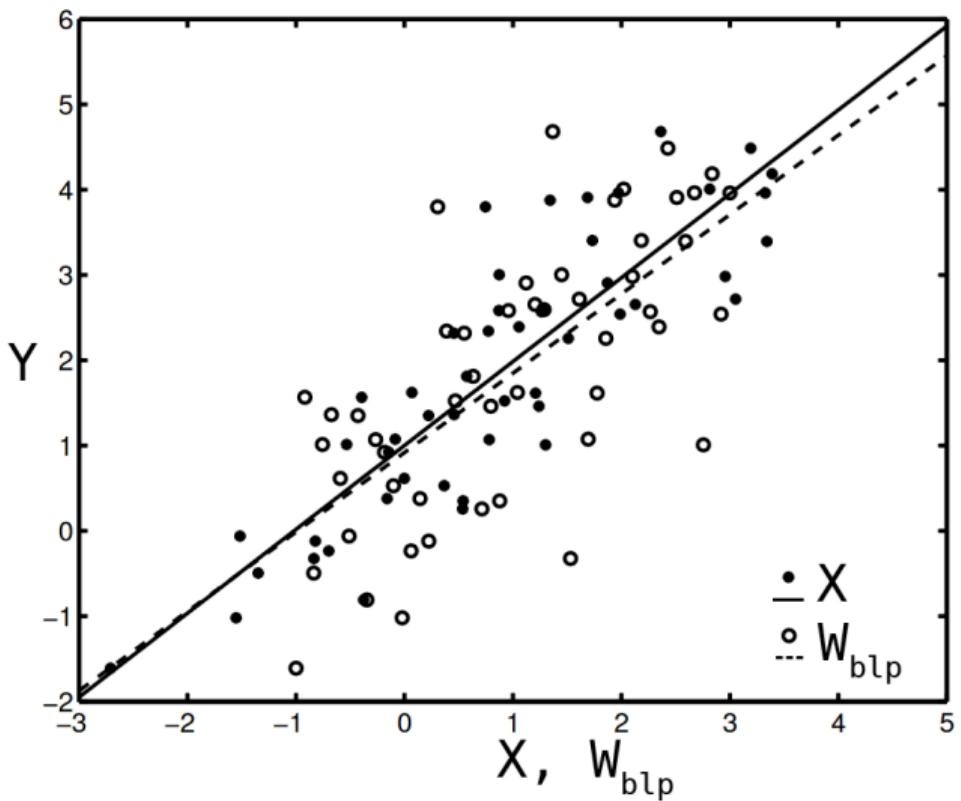
Regressing  $Y$  on  $W$  does not estimate the true slope  $\beta_X$ . Rather it estimates

$$Y = \beta_X^* W + \beta_0^* \quad (3)$$

In the *specific* case where  $X$  is normally distributed with mean  $\mu_X$  and variance  $\sigma_X^2$  it has been shown that

$$\beta_X^* = \frac{\sigma_X^2}{\sigma_X^2 + \sigma_U^2} \beta_X = \lambda \beta_X \quad (4)$$

where  $\sigma_U^2$  is the variance of the measurement error  $U$ .



[Carroll, 2006]

Define the “best linear predictor” of  $X$  given  $W$  to be

$$W_{blp} = (1 - \lambda)\mu_x + \lambda W \quad (5)$$

One can see that  $X = W_{blp} + U^*$ , where  $U^*$  is *uncorrelated with  $X$ !* Substituting into the true relationship between  $Y$  and  $X$  yields

$$Y = \beta_0 + \beta_X W_{blp} + \beta_X U^* \quad (6)$$

where the error  $\beta_X U^*$  is *uncorrelated with  $W_{blp}$ !*

Thus, regressing  $Y$  on  $W_{blp}$  gives an unbiased estimate of the true relationship between  $Y$  and  $X$ .

There are two issues with naively adapting this procedure to our data:

- $E_M$  is *lognormally* distributed in the solar wind and magnetosheath.
- The variation of  $\phi_{PC}$  with  $E_M$  need not be linear.

Both of these issues can be resolved by doing analysis in logspace. Denoting the error-prone estimate of  $E_M$  from PRIME and PRIME-SH as  $E_M^*$ , we have the best linear predictor of  $E_M$  in logspace:

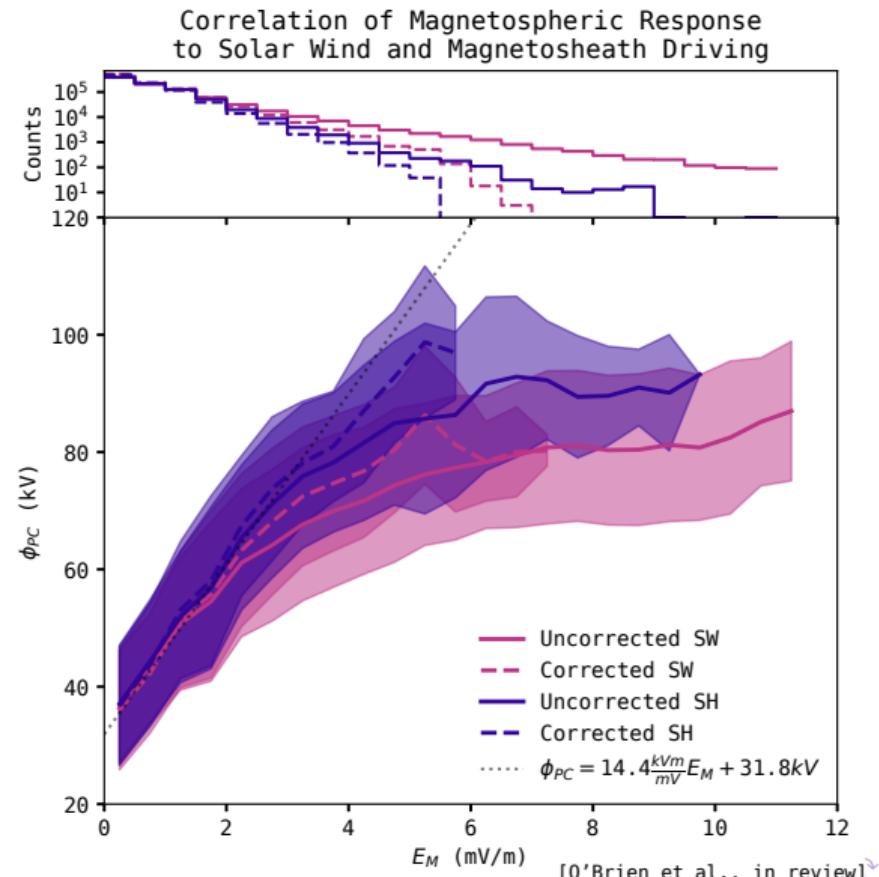
$$\log(E_M)_{bip} = (1 - \lambda)\mu_{\log(E_M^*)} + \lambda\log(E_M^*) \quad (7)$$

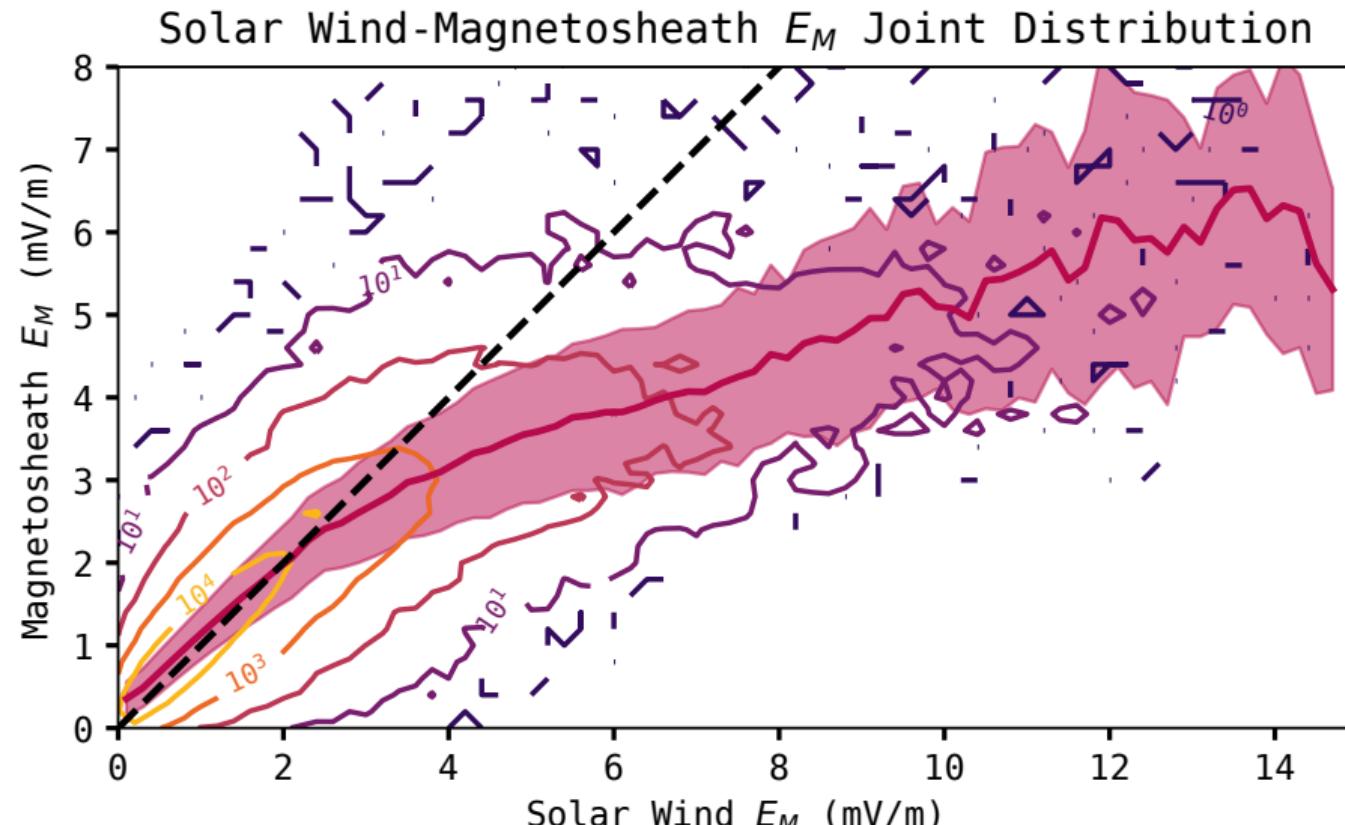
with  $\lambda = \frac{\sigma_{E_M^*}^2}{\sigma_{E_M^*}^2 + \sigma_U^2}$  calculable directly from PRIME and PRIME-SH's error estimates. Take the inverse log of each side to obtain the unbiased estimate of  $E_M$ :

$$E_M = e^{(1-\lambda)\mu_{\log(E_M^*)}} E_M^{*\lambda} \quad (8)$$

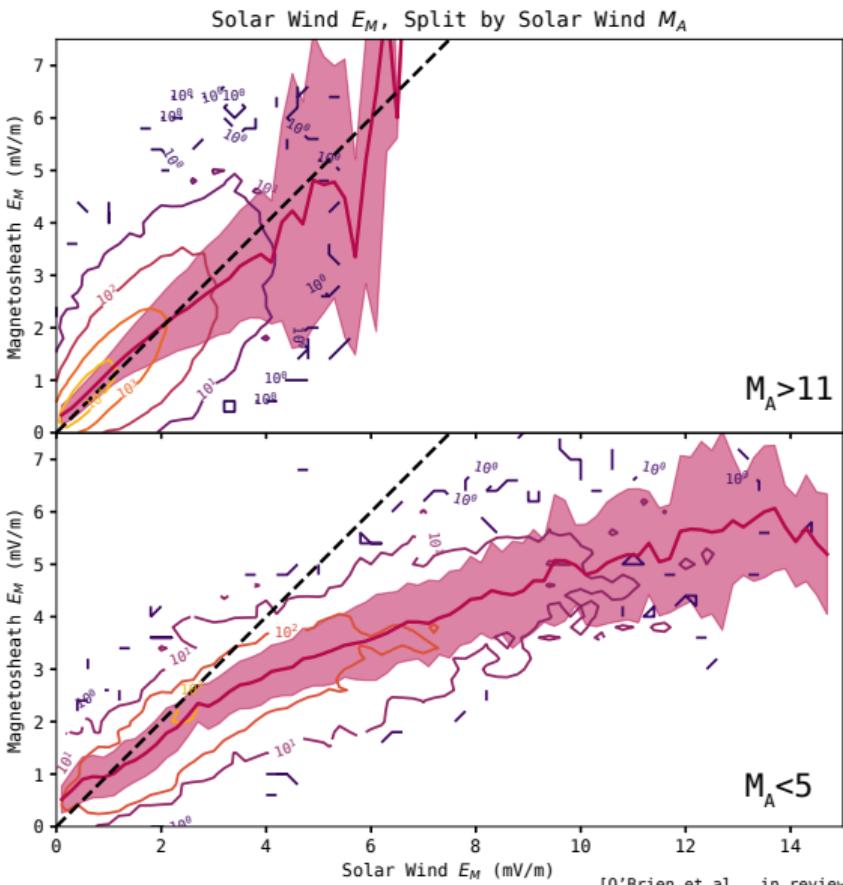
- $\phi_{PC}$  saturates less with the bias-corrected  $E_M$  in the solar wind and magnetosheath.
- $\phi_{PC}$  saturates with respect to the corrected solar wind  $E_M > 4.5 \text{ mV/m}$
- $\phi_{PC}$  does not appear to saturate with respect to the corrected magnetosheath  $E_M$ !

**This implies there is some process in the magnetosheath reducing  $E_M$  relative to its value in the solar wind.**





[O'Brien et al., in review]

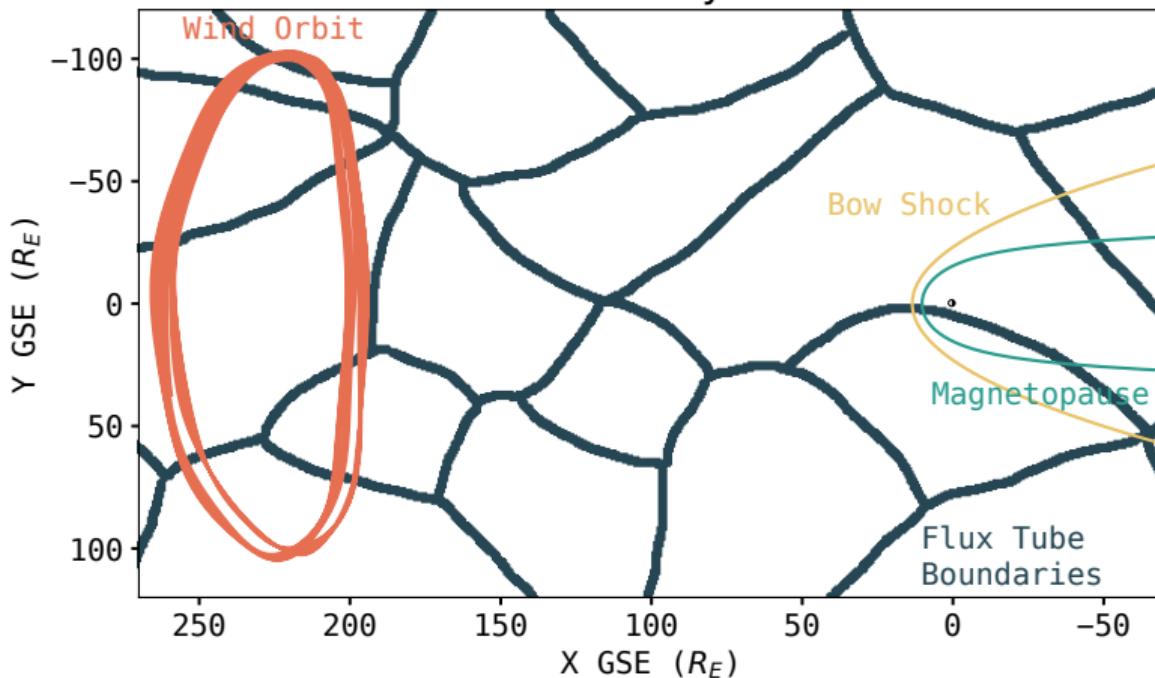


[O'Brien et al., in review]

## Conclusions:

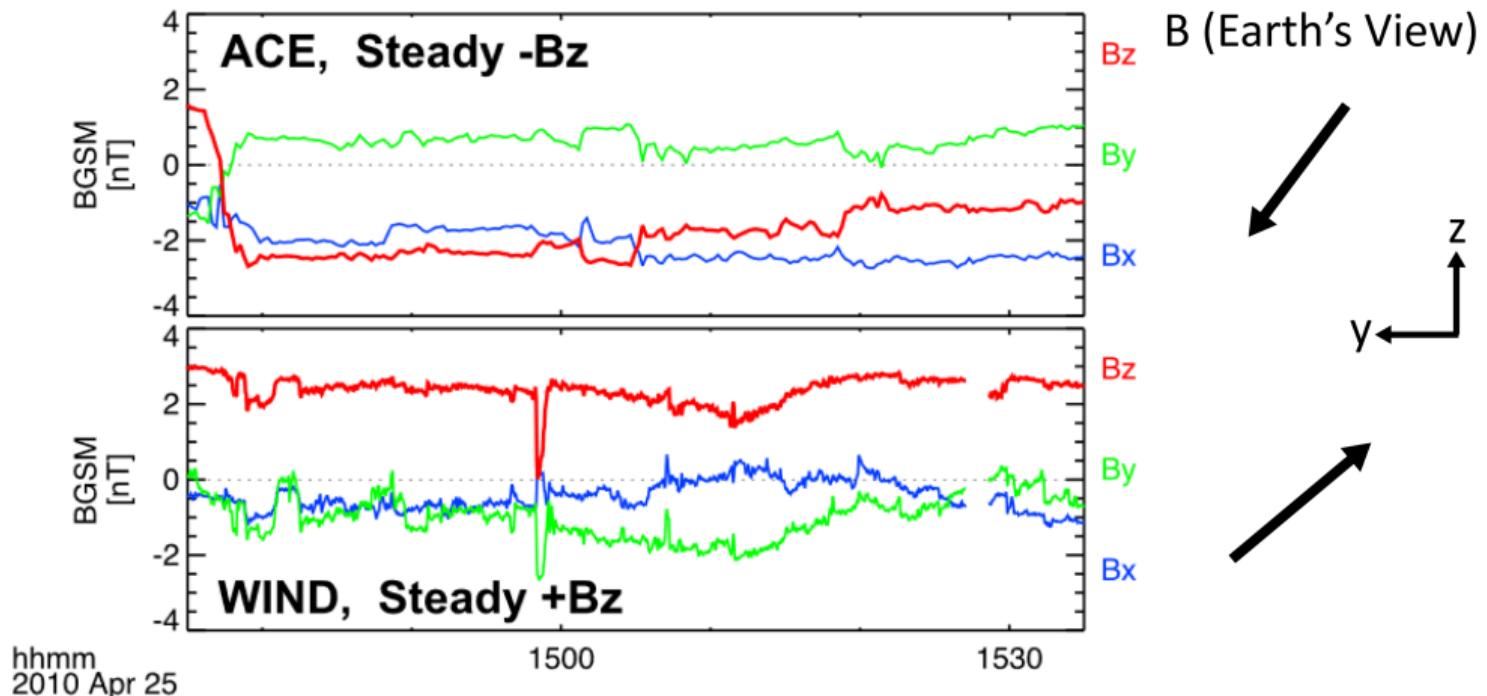
- Measurement uncertainty strongly affects statistical studies of solar wind-magnetosphere coupling.
- The  $\phi_{PC}$  response to the magnetosheath electric field is linear after correcting for input uncertainty.
- Observed  $\phi_{PC}$  saturation is associated with low solar wind  $M_A$ .

## L1-Earth System

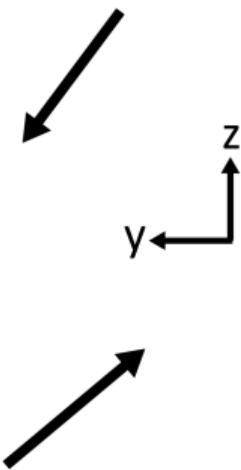


- The only continuous solar wind monitors are located at L1, 1,500,000km away from Earth
- There is no continuous monitor in the plasma actually contacting the magnetopause (the magnetosheath)

## Solar Wind Uncertainty

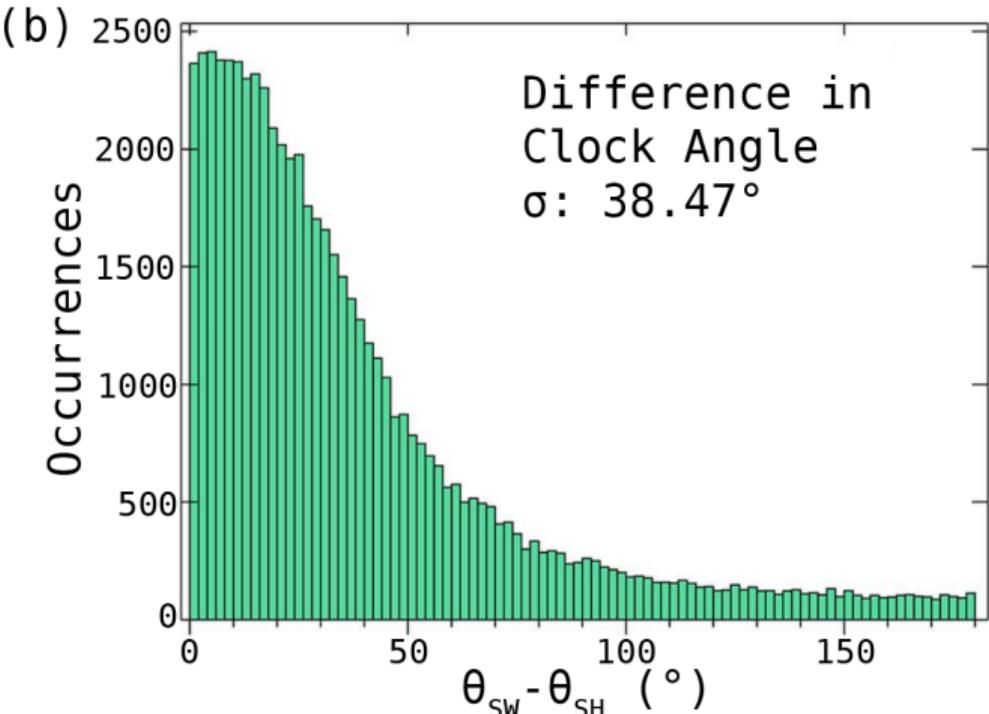
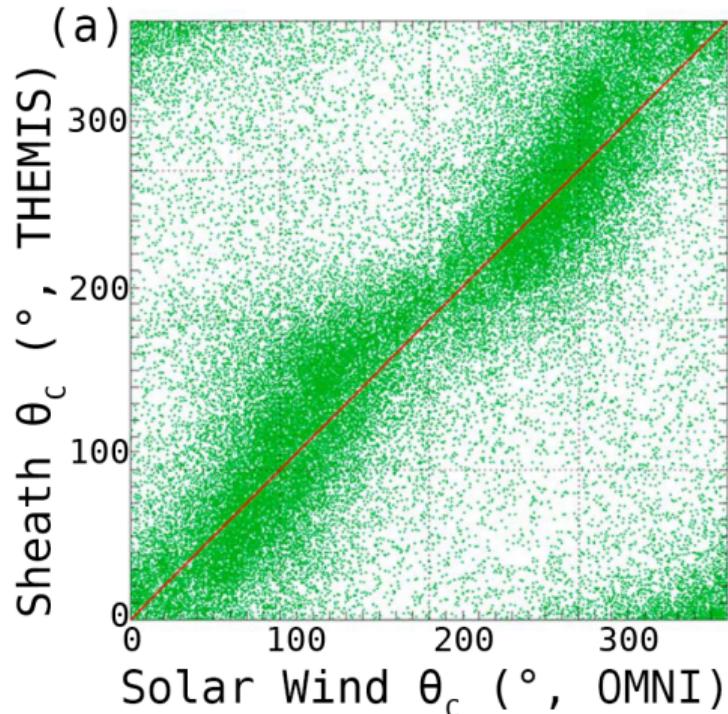


B (Earth's View)



Discrepancy in the interplanetary magnetic field between two L1 monitors (Walsh et al. 2019). Both monitors measure  $B_Z$  to be steady but of opposite sign.

## Bow Shock Effects



Difference in IMF clock angle between solar wind (OMNI) and magnetosheath (THEMIS) measurements. (Walsh et al. 2019)

Continuous Rank Probability Score (CRPS) loss function:

$$CRPS = \int_{-\infty}^{\infty} [C(y) - H(y - y_{obs})]^2 dy$$

$C(y)$ : Cumulative distribution  $H(y - y_{obs})$ : Heaviside function

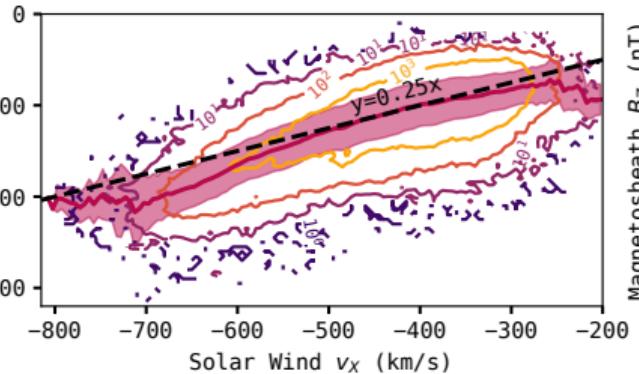
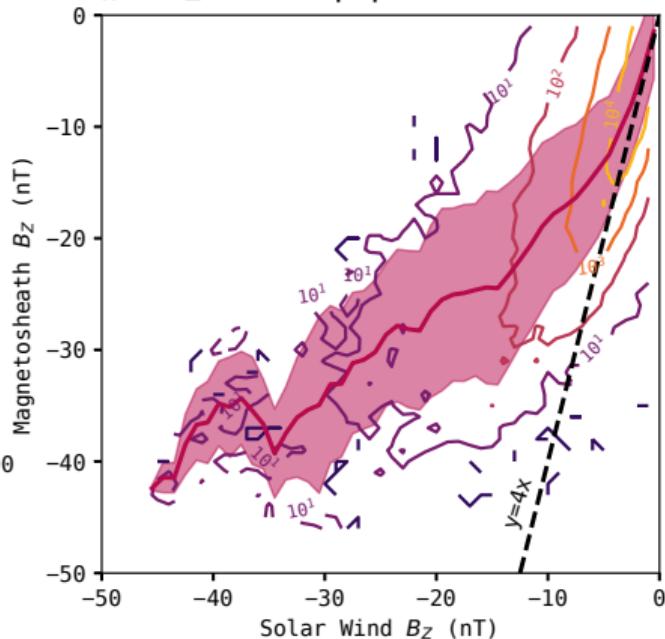
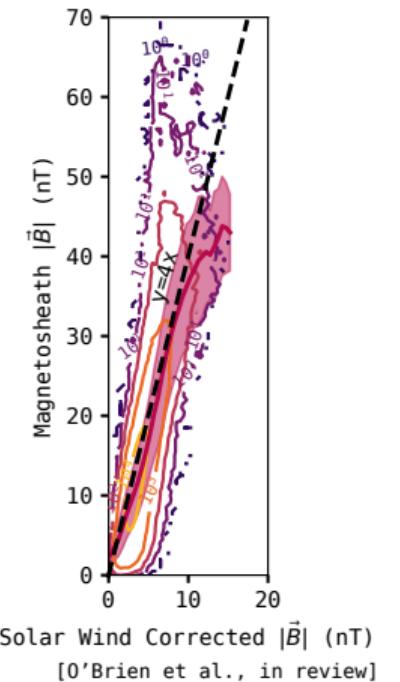
For a Gaussian distribution with mean  $\mu$  and variance  $\sigma^2$  this becomes

$$CRPS(\mu, \sigma) = \sigma \left[ \frac{y_{obs} - \mu}{\sigma} \operatorname{erf} \left( \frac{(y_{obs} - \mu)}{\sqrt{2}\sigma} \right) + \sqrt{\frac{2}{\pi}} \exp \left( -\frac{(y_{obs} - \mu)^2}{2\sigma^2} \right) - \operatorname{sqrt} \frac{1}{\pi} \right]$$

This function is often better than the negative log likelihood for training models because it:

- Symmetrically punishes over- and underconfident predictions
- Collapses to the mean absolute error for  $\sigma \rightarrow 0$
- Has the same unit as the variable of interest

## Solar Wind-Magnetosheath $v_x$ , $B_z$ , and $|\vec{B}|$ Joint Distributions

Magnetosheath  $v_x$  (km/s)Solar Wind  $v_x$  (km/s)Solar Wind  $B_z$  (nT)Solar Wind Corrected  $|\vec{B}|$  (nT)

[O'Brien et al., in review]

The components of  $E_M$  along with the total magnetic field magnitude  $|\vec{B}|$ , with regression recalibration applied to correct for measurement uncertainty.