# [Higher Math] Midterm Review

## Relations

- Equivalence Relation (?)
- Types of relations
- Functions as relations

## **Functions**

#### **General Notes**

**Definition:** Take two sets, X and Y. A function  $f: X \to Y$  (a function from X to Y) is a collection of ordered pairs (x,y) such that  $x \in X$  and  $y \in Y$ .

• The condition for these ordered pairs to be considered a function is that they follow the Vertical Line Test (VLT). Anoterh way to put this is that each input only ever has one output!

More formally, we can say that  $\forall x \in X$ , the function (x,y) only ever has one y. In these scenarios, we tend to use the "negative" definition, and say that if  $(x_1,y_1) \in f$  and  $(x_1,y_2) \in f$ , then  $y_1=y_2$ .

Some important definitions are as follows:

- Image (Range): The image of  $f:X \to Y$  is basically all the values in Y that values  $x \in X$  map to. In order words, it's the "range" of the function.
  - o However, we use the term image because this refers to the "range" of a specific set. You can imagine that you have a function  $f(x)=x^2$  defined over all the real numbers. The range is  $(0,\infty)$ , but let's say that we only cared about the inputs  $\{1,2,3\}$ . Then, the image of this set of the function would be  $\{1,4,9\}$ .
- **PreImage (Domain):** This is a fancy word for domain, but it's basically like all the elements  $x \in X$  that map to values  $y \in Y$ . In the above example, take something like  $\{1,4,9\}$  as output values for the function  $f(x) = x^2$ . Then, we can say the preimage of this set is  $\{1,2,3\}$  because those are the values that map to those outputs.

There are three types of "mappings". Consider the function f:A o B where  $a\in A$  and  $b\in B$ .

- Injective (one-to-one): If f(a) = f(b), then a = b. Another way to say this is that every input value only maps to one output value. You will never have a case where your function has something like f(1) = f(3).
- **Surjective (onto):** For all  $b \in B$ , there exists some  $a \in A$  such that f(a) = b. This is basically saying that every possible output (in set B) guarentees to have some input from set A that can map to it.
- **Bijective:** Both surjective and injective!
  - NOTE: If they ever ask about the inverse of a function, this is only possible with a
    bijective function! If you think about it, it makes sense why you can only have an
    inverse (that is a function) if the properties of injectivity and surjectivity are satisfied.

## **Example Problems**

Problem 1 (HW 5): Give the following definitions:

ullet a function f:X o Y

A function f:X o Y (a function from X to Y) is a collection of ordered pairs (x,y) such that  $x\in X$  and  $y\in Y$ , and  $\forall x\in X$ , the function (x,y) only ever has one y.

• for  $A \subset X$ , the set f(A)

$$f(A) = \{ f(a) \in Y : \forall a \in A \}$$
 (1)

 $\bullet \ \ {\rm for} \ C \subset Y \text{, the set} \ f^{-1}(C) \\$ 

$$f^{-1}(C) = \{ a \in A : \forall c \in C, f(a) = c \}$$
 (2)

**Injective Proof:** By definitino of injectivity, we have that if f(a) = f(b), then a = b.

Take any element of  $x\in A\cap B$ . It should be obvious that  $f(x)\in f(A)$  and  $f(x)\in f(B)$ . Now, take any element  $y\in f(A)\cap f(B)$ . Assume that  $x_1\in A\implies f(x_1)=y$  and  $x_2\in B\implies f(x_2)=y$  Then,  $f(x_1)=f(x_2)=y$  and we know that  $x_1=x_2$  and so that  $x_1\in A\cap B$ . This means that double inclusion so we good.

## Limits

$$(|a| - |b|)^2 = |a|^2 + |b|^2 - 2|a||b| \implies |a| + |b|$$
(3)

### Example 4 HW 7

 $0<|x|<\delta \implies 0<|x-M|<\epsilon$  . Assume that  $\delta=rac{1}{x}$  . this means that  $x\sin(x)$  and around x=0,

Fix some M. Now, define  $x=rac{1}{\pi(M+1)} o f(x_0)=\pi(M+1)>M$ . Thus, your bound fails.

Limits:

$$3x^2 - 3 < \epsilon \iff \delta = \sqrt{4}$$