

UTS SAFE WORK METHOD STATEMENT (SWMS)

1. FACULTY/SUBJECT			
Faculty/Subject title		Sensors and Control	
Subject supervisor/coordinator		Gavin Paul	
SWMS prepared by		Connor Rudd & Claire Matthews	
2. WORK ACTIVITY DESCRIPTION			
Describe the work activity E.g. Operating, Handling, Using.. Include names of hazardous equipment, substances or materials used, and any quantities and concentrations of substance(s) or reaction products.		This project aims to develop a colour-based automated sorting system utilizing a DoBot robot and an RGB-D camera to detect and categorize objects by colour. Once detected the colours will be picked and placed into corresponding locations. Essential hazard equipment includes the DoBot robot and imaging sensors (RGB-D camera), which are integral to the automation process.	
3. HAZARDS: Choose those hazard types that will need to have control measures in Section 4			
Work Environment <ul style="list-style-type: none"> Working in Remote Locations Working Outdoors/fieldwork Clinical/Industrial setting Poor ventilation/Air quality Temperature extremes Working at Height Slip/Trip/Fall hazards 	Plant <ul style="list-style-type: none"> Noise Vibration Working with compressed air Lifts Hoists or Cranes Moving parts (Crushing, friction, cut, stab, shear hazards) Pressure Vessels or Boilers 	Chemical <ul style="list-style-type: none"> Hazardous Chemicals use Skin/eye irritant Sensitiser Mutagen Carcinogen Toxic to reproduction Aquatic toxicity Toxic Corrosive Dangerous when wet 	Ergonomic/Manual Handling <ul style="list-style-type: none"> Repetitive or awkward movements Lifting heavy objects Over reaching Working above shoulder or below knee height Poor workstation set up
Electrical <ul style="list-style-type: none"> Plug in equipment High voltage Exposed wiring Exposed conductors 	Radiation <ul style="list-style-type: none"> Ionising Radiation Non-ionising radiation (Lasers, Microwaves, Ultraviolet light) 	Biological <ul style="list-style-type: none"> Sharps/Needles Cytotoxins Pathogens/infectious materials Infectious materials Communicable diseases Animal/insects Work with fungi/bact/viruses 	Psychosocial <ul style="list-style-type: none"> Aggressive or violent clients/students Working in isolation Working with timeframes Staffing issues
4. CONTROLS MEASURES: Choose those that apply for hazards identified			
Eliminate/Isolate/Substitute / Engineering Controls <ul style="list-style-type: none"> Remove hazard Restrict access Redesign equipment Guarding / Barriers / Fume Cupboard / exhaust Biosafety cabinet Use safer materials/substances Ventilation Regular maintenance of equipment Redesign of workspace / workflow 	Admin specific: Licenses/permits Work Methods <ul style="list-style-type: none"> Training Information or Instruction Licensing or certification of operators Test and tag electrical equipment Restricted access Regular breaks Task rotation Work in pairs Document Chemical risk assessment Ladder / Sling register 	Emergency Response Systems <ul style="list-style-type: none"> First aid kit Chemical spill kit Safety shower Eye wash station Emergency Stop button Remote Communication Mechanism 	
Other controls not listed			

5. PPE REQUIRED (Tick those that apply) ☒



EYE
PROTECTION

☐


HEARING
PROTECTION

☐


CLOSED-IN
FOOTWEAR
MUST BE WORN

☒


HAND
PROTECTION

☐


FACE
SHIELD

☐


PROTECTIVE
CLOTHING

☐


RESPIRATORY
PROTECTION

☐


LONG HAIR MUST
BE CONTAINED

☒


HEAD
PROTECTION

☐

6. EMERGENCY EQUIPMENT



EMERGENCY
SHOWER

☐


EMERGENCY
SPILL
KIT
INSIDE

☐


EMERGENCY
EYEWASH

☐

7. WORK ACTIVITY STEPS

BEFORE YOU START:

- Safety Induction course
- Inspect wires and cabling
- Know load specs
- Shutdown robot
- Clean work area, return everything to start pose
- Electrically isolate
- Clean robot (if needed)
- Power on robot
- Announce start of robot movements (warn people around)

STEPS IN WORK ACTIVITY:

1. Check all cameras and sensors are clear and receiving data
2. Stand next to e-stop button
3. Stand next to laptop/control system
4. Supervise entire movement and remain outside workspace area
5. Let people around know when activating
6. Power off robot
7. Enter workspace
8. Inspect results

EMERGENCY PROCEDURES:

- Press emergency button
- Activate fire alarm
- Remove all people in proximity
- Call emergency services

TRAINING REQUIRED:

- CoBot Rapid Global Induction
- Supervisor of use

8. SIGN OFF

PREPARED BY:

LAB SUPERVISOR

DATE: 28/08/24NAME: CONNOR RUDD, NORA
SULAIMAN & CLAIRE MATTHEWSNAME: MICHAEL LEEREVIEW DATE: 28/08/2024