

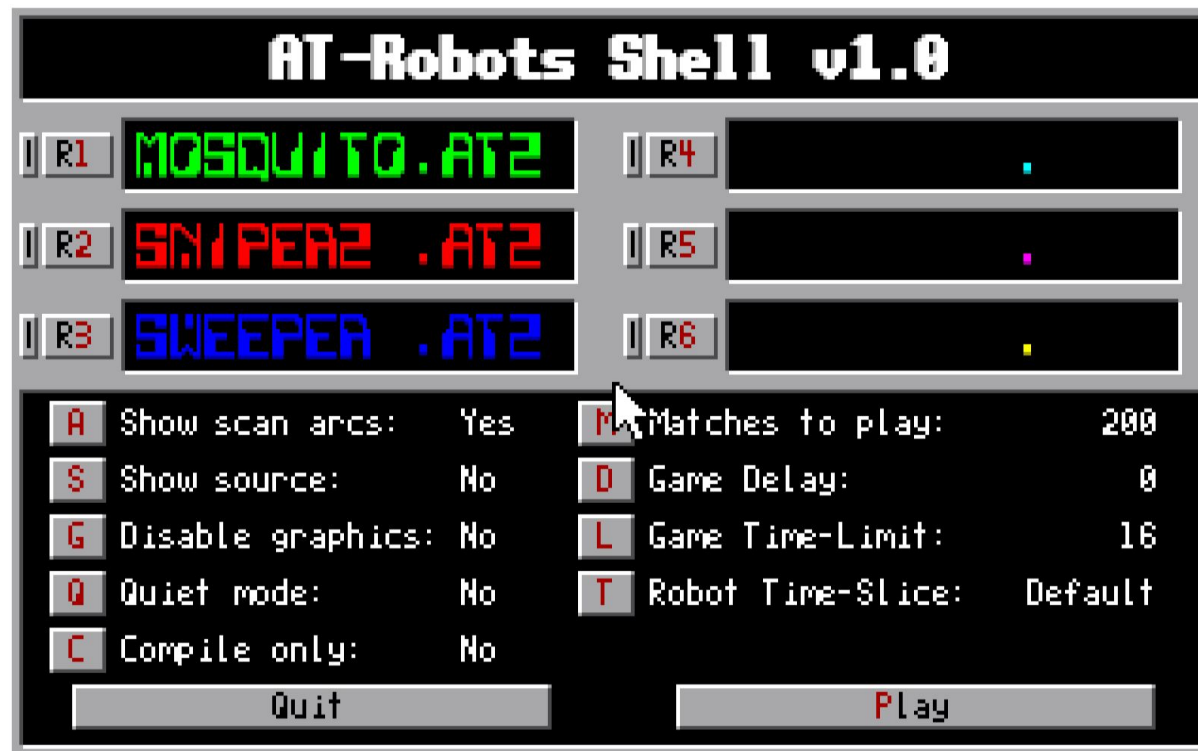
Cycle 1

Team Cerebral

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Introduction

- Our team's goal is to port the classic competitive robot game, ATRobots, to modern operating systems with a more advanced and evolved interface.



Plans

Original:

- Have non-graphical matches working in ATRobots
- Decoding locked robots for our ported ATRobots
- Implement working ATRLock code into GUI



Modified:

- Get as many functions done as possible for ATRobots
 - Only port/work on most important functions we need for basic ATRobots functionality

Features

What we have functioning:

- ATRLock program with GUI for browsing for robot files
- Moving Shapes Demo using QT Creator
- Majority of ATR2 non-graphics related functions ported to C++

What we didn't accomplish yet:

- Final few ATRobots functions (scan, com_transmit, com_receive, out_port, do_missile)

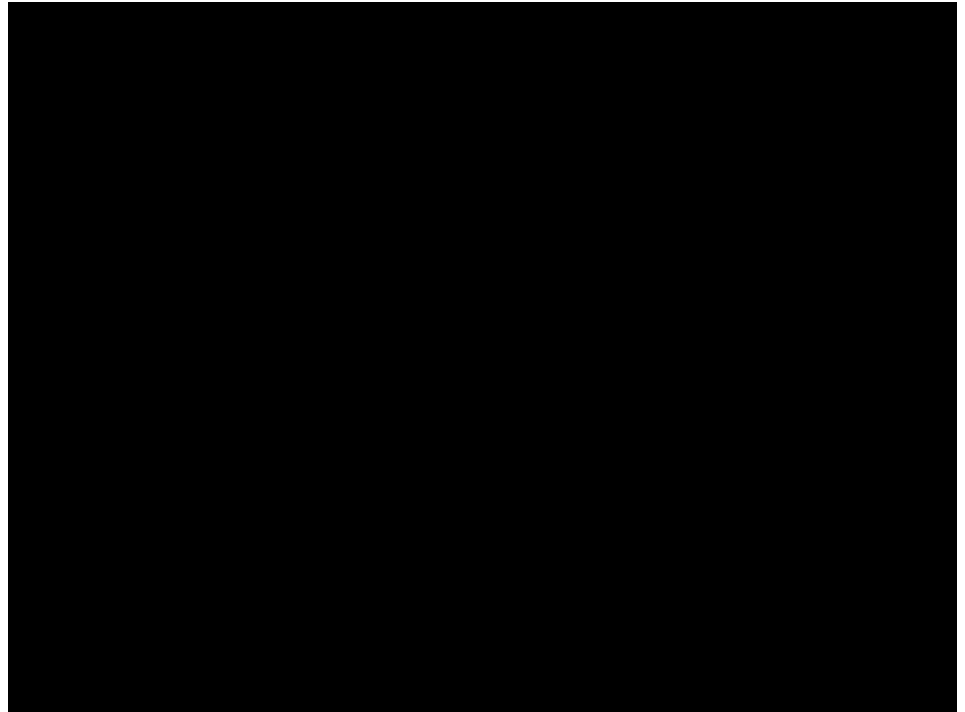
Tools and Process

- ATRobots was split by function
 - Completed major functions (compile, parse1, execute_instruction, do_robot, all initialization functions, most functions from ATR2Func)
 - Only 7 non-graphical functions left to port, expected to be done by Cycle 2
- We discovered our ATRLock didn't lock properly on Mac and Linux machines
 - Line endings were incorrect, unreadable by DOS ATRobots



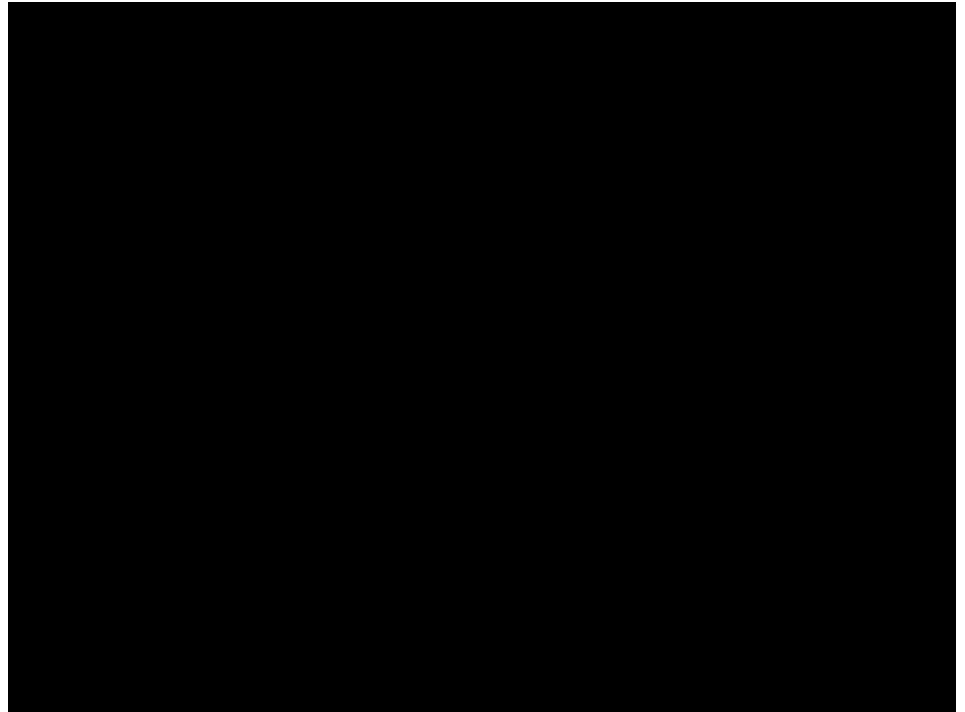
Basic Moving Shapes Demo

- Moving drawn shapes demo
 - Moves a simple shape around the window using the arrow keys.



ATRLock - Demo

- ATRLock Program demo
 - Locking robots
 - Running locked robots in ATRobots
 - Decoding robots



Future Plans

- Finish non-graphical matches
 - Run ATR2 in Command Line and see match results.
 - C++ Functions currently compile error free, but do not yet yield desired results.
- Robot graphics demo
 - Display working graphics for the ATR2 Graphics functions.
 - Finish graphical matches