

## Overview

- Likelihood principle (11 lectures)
- Bayesian inference (2 lectures)
- Decision theory (3 lectures)
- Multivariate analysis (2 lectures)
- Nonparametric inference & Monte Carlo techniques (6 lectures)

Books:

- Theory of point estimation - Lehmann & Casella
- “Asymptotic Statistics” - van der Vaart
- “Statistical Inference” - Casella & Berger
- “Intro to Multivariate Statistical Analysis” - Anderson

## Introduction

Goal: Make inference about unknown probability distributions based on access to random samples.

Consider a real valued random variable  $X$  on a probability space  $\Omega$  with distribution function

$$F(t) = \mathbb{P}(\omega \in \Omega : X(\omega) \leq t) \quad \forall t \in \mathbb{R}$$

When  $X$  is discrete,  $F(t) = \sum_{x \leq t} f(x)$ , where  $f$  is the pmf of  $X$ .

When  $X$  is continuous,  $F(t) = \int_{-\infty}^t f(s)ds$ , where  $f$  is the pdf of  $X$ .

For all the results in this course, we assume either pdf or pmf exists.

Often, the distribution of  $X$  is parameterised by an unknown value  $\theta$ . The goal is to infer something about  $\theta$  based on (iid) samples  $X_1, \dots, X_n$ .

**Definition.** A *statistical model* for a sample from  $X$  is any family of probability distributions  $\{P_\theta : \theta \in \Theta\}$  for the law of  $X$ . When  $P_\theta$  has a pmf (pdf)  $f(\cdot, \theta)$ , this is also written as  $\{f(\cdot, \theta) : \theta \in \Theta\}$ . The index set  $\Theta$  is the *parameter space*.

**Example.**

- (i)  $\mathcal{N}(\theta, 1); \theta \in \Theta = \mathbb{R}$ .
- (ii)  $\mathcal{N}(\mu, \sigma^2), \theta = (\mu, \sigma^2) \in \Theta = \mathbb{R} \times (0, \infty)$ .
- (iii)  $\text{Exp}(\theta); \theta \in \Theta = (0, \infty)$ .

(iv)  $\mathcal{N}(\theta, 1)$ ;  $\theta \in \Theta = [-1, 1]$ .

**Remark:** for a variable  $X$  with distribution  $P$ , the model  $\{P_\theta : \theta \in \Theta\}$  is *correctly specified* if there exists  $\theta \in \Theta$  such that  $P = P_\theta$ . For instance, if  $X \sim \mathcal{N}(2, 1)$ , the model in (i) is correctly specified, but the model in (iv) is not.

In the case of a correctly specified model, we often use  $\theta_0$  to denote the “true value” of the parameter. We also say  $\{X_1, \dots, X_n\}$  are iid from a model  $\{P_\theta : \theta \in \Theta\}$  in the case of a correctly specified model.

**Statistical goals:**

- Estimation: construct  $\hat{\theta} = \hat{\theta}(X_1, \dots, X_n)$  such that  $\hat{\theta}$  is close to  $\theta_0$  when  $X_i \sim P_{\theta_0}$ .
- Hypothesis testing: determine whether the null hypothesis  $H_0 : \theta = \theta_0$  or the alternative hypothesis  $H_1 : \theta \neq \theta_0$  is true, using a test  $\psi_n = \psi(X_1, \dots, X_n)$  such that  $\psi_n = 0$  when  $H_0$  is true and  $\psi_n = 1$  when  $H_1$  is true, with high probability.
- Inference: find confidence intervals (confidence sets)  $\mathcal{C}_n = \mathcal{C}(X_1, \dots, X_n)$  such that for some  $0 < \alpha < 1$  we have  $\mathbb{P}_\theta(\theta \in \mathcal{C}_n) \geq 1 - \alpha$ , for all  $\theta \in \Theta$ , where  $\alpha$  is the significance level.

## 1 The Likelihood Principle

Suppose  $X_1, \dots, X_n$  are iid from a Poisson model  $\{\text{Poi}(\theta) : \theta \geq 0\}$  with numerical values  $X_i = x_i$ , for all  $1 \leq i \leq n$ . The joint distribution of the sample is

$$f(x_1, \dots, x_n; \theta) = \mathbb{P}_\theta(X_1 = x_1, \dots, X_n = x_n) = \prod_{i=1}^n \left( e^{-\theta} \frac{\theta^{x_i}}{x_i!} \right) = e^{-n\theta} \prod_{i=1}^n \frac{\theta^{x_i}}{x_i!} = L_n(\theta)$$

We can think of  $L_n(\theta)$  as a random function from  $\Theta$  to  $\mathbb{R}$ , where the randomness comes from  $\{X_i\}_{i=1}^n$ . This is the probability of occurrence of the observed sample  $(X_1 = x_1, \dots, X_n = x_n)$ , as a function of the unknown parameter  $\theta$ .

The idea of the likelihood principle is to find  $\theta$  which maximises  $L_n(\theta)$ , or equivalently  $l_n(\theta) = \log L_n(\theta)$ . In the example, we have

$$l_n(\theta) = -n\theta + \log(\theta) \sum_{i=1}^n x_i - \sum_{i=1}^n \log(x_i!)$$

Setting  $l'_n(\theta) = 0$  gives

$$-n + \frac{1}{\theta} \sum_{i=1}^n x_i = 0$$

and the solution is  $\hat{\theta}_{\text{mle}} = \frac{1}{n} \sum_{i=1}^n x_i$ , which is the sample mean. One can also check that  $l_n''(\theta) < 0$  for all  $\theta > 0$ . When all  $X_i$ 's are 0, one can check that maximising  $l_n(\theta)$  is equivalent to maximising  $-n\theta$ , so  $\hat{\theta}_{\text{mle}} = 0$  in this case.

### Maximum likelihood estimator

Suppose  $\{f(\cdot, \theta) : \theta \in \Theta\}$  is a statistical model of pdfs/pmfs for the distribution of a random variable  $X$ , and  $X_1, \dots, X_n$  are iid copies of  $X$ .

Define the *likelihood function*

$$L_n(\theta) = \prod_{i=1}^n f(x_i, \theta)$$

the *log likelihood function*

$$l_n(\theta) = \log L_n(\theta) = \sum_{i=1}^n \log f(x_i, \theta)$$

and the *normalised log likelihood function*

$$\bar{l}_n(\theta) = \frac{1}{n} l_n(\theta) = \frac{1}{n} \sum_{i=1}^n \log f(x_i, \theta)$$

**Definition.** The *maximum likelihood estimator* is any element  $\hat{\theta} = \hat{\theta}_{\text{mle}} = \hat{\theta}_{\text{mle}}(X_1, \dots, X_n) \in \Theta$  for which  $L_n(\hat{\theta}) = \max_{\theta \in \Theta} L_n(\theta)$ .

**Remark:** the definition of MLE can be generalised to non-iid data, provided a joint pdf/pmf of  $(X_1, \dots, X_n)$  can be specified.

**Example.**

- (i) For  $X_i \sim \text{Poi}(\theta)$ ,  $\theta \geq 0$ , we calculated  $\hat{\theta}_{\text{mle}} = \frac{1}{n} \sum_{i=1}^n X_i = \bar{X}_n$ .
- (ii) For  $X_i \sim \mathcal{N}(\mu, \sigma^2)$ ,  $\theta = (\mu, \sigma^2) \in \mathbb{R} \times (0, \infty)$ , we have  $\hat{\mu}_{\text{mle}} = \bar{X}_n$  and  $\hat{\sigma}^2 = \frac{1}{n} \sum_{i=1}^n (X_i - \bar{X}_n)^2$  (see Example sheet).
- (iii) In the Gaussian linear model  $Y = X\theta + \varepsilon$ , with a known  $X \in \mathbb{R}^{n \times p}$ , unknown  $\theta \in \mathbb{R}^p$ , and  $\varepsilon \sim \mathcal{N}(0, I_n)$ , the observations  $(Y_1, \dots, Y_n)$  are not iid, but a joint distribution  $f(Y_1, \dots, Y_n; \theta)$  can still be specified. The MLE is the least squares estimator (see Example sheet).

**Definition.** For  $\Theta \subseteq \mathbb{R}^p$  and  $l_n$  differentiable at  $\theta$ , the *score function*  $S_n$  is

$$S_n(\theta) = \begin{pmatrix} \frac{\partial}{\partial \theta_1} l_n(\theta) \\ \vdots \\ \frac{\partial}{\partial \theta_p} l_n(\theta) \end{pmatrix}$$

Solving for a root of  $S_n(\theta)$  is a common heuristic for maximising  $l_n(\theta)$ . In many cases, it is a necessary and sufficient condition.

**Note:** derivatives are taken with respect to  $\theta$ , not the  $x_i$ 's.

### Information geometry

Recall that if  $X$  is a random variable with distribution  $P_\theta$  on some space  $\mathcal{X} \subseteq \mathbb{R}^d$ , and  $g : \mathcal{X} \rightarrow \mathbb{R}$  is a function, then

$$E_\theta[g(X)] = \int_{\mathcal{X}} g(x) dP_\theta(x) = \int_{\mathcal{X}} g(x) f(x, \theta) dx$$

if  $X$  has a pdf  $f(x, \theta)$ , and

$$\mathbb{E}_\theta[g(X)] = \sum_{x \in \mathcal{X}} g(x) f(x, \theta)$$

if  $X$  has a pmf  $f(x, \theta)$

**Theorem 1.1.** Consider a model  $\{f(\cdot, \theta) : \theta \in \Theta\}$ , where  $f(\cdot, \theta)$  is a pdf/pmf and  $f(x, \theta) > 0$  for all  $x, \theta$ . Also suppose the model is correctly specified, with  $\theta_0$  equal to the true parameter, and  $\mathbb{E}_{\theta_0}[|\log(f(X, \theta))|] < \infty$  for all  $\theta \in \Theta$ . Then the function defined by  $l(\theta) = \mathbb{E}_{\theta_0}[\log(f(X, \theta))]$  is maximised at  $\theta_0$ .

*Proof.* Consider the case when  $X$  has a pdf (discrete case is analogous). For all  $\theta \in \Theta$ , we have

$$\begin{aligned} l(\theta) - l(\theta_0) &= \mathbb{E}_{\theta_0}[\log(f(X, \theta))] - \mathbb{E}_{\theta_0}[\log(f(X, \theta_0))] \\ &= \mathbb{E}_{\theta_0} \left[ \log \left( \frac{f(X, \theta)}{f(X, \theta_0)} \right) \right] \end{aligned}$$

Jensen's inequality:  $\mathbb{E}[\varphi(Z)] \leq \varphi(\mathbb{E}[Z])$  for any random variable  $Z$  and concave function  $\varphi$ .

Since  $\log$  is concave,

$$\begin{aligned} l(\theta) - l(\theta_0) &\leq \log \left( \mathbb{E}_{\theta_0} \left[ \frac{f(X, \theta)}{f(X, \theta_0)} \right] \right) \\ &= \log \left( \int_{\mathcal{X}} \frac{f(x, \theta)}{f(x, \theta_0)} f(x, \theta_0) dx \right) = \log 1 = 0 \end{aligned} \quad (*)$$

□

**Remark:** under the assumption of “strict identifiability of the model parameterisation”, i.e.,

$$f(\cdot, \theta) = f(\cdot, \theta') \iff \theta = \theta'$$

the inequality (\*) is strict, since equality occurs in Jensen only when  $\varphi$  is linear or  $Z$  is constant.

**Remark:** the quantity  $l(\theta_0) - l(\theta)$  computed above can be written as

$$\text{KL}(P_{\theta_0}, P_{\theta}) = \int_{\mathcal{X}} f(x, \theta_0) \log \left( \frac{f(x, \theta_0)}{f(x, \theta)} \right) dx$$

and is the Kullback-Leibler divergence in information theory. It is a “distance” between distributions. Maximising  $l(\theta)$  is equivalent to minimising KL.

## Fisher information

We consider the gradient and Hessian of the likelihood function.

**Theorem 1.2.** *For a parametric model  $\{f(\cdot, \theta) : \theta \in \Theta\}$ , “regular enough” so integration and differentiation can be interchanged, we have  $\mathbb{E}_{\theta}[\nabla_{\theta} \log(f(X, \theta))] = 0$  for all  $\theta \in \text{int}(\Theta)$ .*

*Proof.* We write the expectation

$$\begin{aligned} \mathbb{E}_{\theta}[\nabla_{\theta} \log(f(X, \theta))] &= \int_{\mathcal{X}} (\nabla_{\theta} \log f(x, \theta)) f(x, \theta) dx \\ &= \int_{\mathcal{X}} \frac{\nabla_{\theta} f(x, \theta)}{f(x, \theta)} f(x, \theta) dx \\ &= \nabla_{\theta} \left( \int_{\mathcal{X}} f(x, \theta) dx \right) = \nabla_{\theta}(1) = 0 \end{aligned}$$

□

**Remark:** in particular, when  $\theta_0 \in \text{int}(\Theta)$ , then  $\mathbb{E}_{\theta_0}[\nabla_{\theta} \log(f(X, \theta))] = 0$ .

**Definition.** For a parameter space  $\Theta \subseteq \mathbb{R}^p$ , the *Fisher information* matrix is defined by

$$I(\theta) = \mathbb{E}_{\theta} \left[ (\nabla_{\theta} \log f(X, \theta)) (\nabla_{\theta} \log f(X, \theta))^T \right], \quad \forall \theta \in \text{int}(\Theta)$$

in other words,

$$I_{ij}(\theta) = \mathbb{E}_{\theta} \left[ \frac{\partial}{\partial \theta_i} \log f(X, \theta) \frac{\partial}{\partial \theta_j} \log f(X, \theta) \right]$$

**Remark:** in 1 dimension, we have

$$I(\theta) = \mathbb{E}_{\theta} \left[ \left( \frac{d}{d\theta} \log f(X, \theta) \right)^2 \right] = \text{Var}_{\theta} \left[ \frac{d}{d\theta} \log f(X, \theta) \right]$$

Thus  $I_{\theta_0}$  describes random variations of  $S_n(\theta_0)$  about its mean. This in turn will help quantify the precision of  $\hat{\theta}$ , a zero of  $S_n(\hat{\theta}) = 0$ , about  $\theta_0$ .

**Theorem 1.3.** *Under the same regularity assumptions as the previous theorem*

$$I(\theta) = -\mathbb{E}_{\theta} [\nabla_{\theta}^2 \log(f(X, \theta))], \quad \forall \theta \in \text{int}(\Theta)$$

i.e.,

$$I_{ij}(\theta) = -\mathbb{E}_{\theta} \left[ \frac{\partial^2}{\partial \theta_i \partial \theta_j} \log f(X, \theta) \right]$$

*Proof.* We write

$$\nabla_{\theta}^2 \log f(X, \theta) = \nabla_{\theta} \left( \frac{\nabla_{\theta} f(X, \theta)}{f(X, \theta)} \right) = \frac{\nabla_{\theta}^2 f(X, \theta)}{f(X, \theta)} - \frac{\nabla_{\theta} f(X, \theta) \nabla_{\theta} f(X, \theta)^T}{f(X, \theta)^2}$$

note that

$$\mathbb{E} \left[ \frac{\nabla_{\theta}^2 f(X, \theta)}{f(X, \theta)} \right] = \int_{\mathcal{X}} \nabla_{\theta}^2 f(X, \theta) dx = \nabla_{\theta}^2 \int_{\mathcal{X}} f(X, \theta) dx = 0$$

Therefore

$$\begin{aligned} -\mathbb{E}_{\theta} [\nabla_{\theta}^2 \log f(X, \theta)] &= \mathbb{E}_{\theta} \left[ \frac{\nabla_{\theta} f(X, \theta) \nabla_{\theta} f(X, \theta)^T}{f^2(X, \theta)} \right] \\ &= \mathbb{E} \left[ \frac{\nabla_{\theta} f(X, \theta)}{f(X, \theta)} \left( \frac{\nabla_{\theta} f(X, \theta)}{f(X, \theta)} \right)^T \right] \\ &= \mathbb{E}_{\theta} [(\nabla_{\theta} \log f(X, \theta))(\nabla_{\theta} \log f(X, \theta))^T] \\ &= I(\theta) \end{aligned}$$

□

**Remark:** continuing the previous remark, in 1 dimension

$$\text{Var}_{\theta} \left[ \frac{d}{d\theta} \log f(X, \theta) \right] = I(\theta) = -\mathbb{E}_{\theta} \left[ \frac{d^2}{d\theta^2} \log f(X, \theta) \right]$$

this relates the variance of the score function and the curvature of  $l$ , both of which are relevant to describing the quality of the MLE  $\hat{\theta}$  as an approximation to  $\theta_0$ .

Suppose now  $X = (X_1, \dots, X_n)$  is a vector of iid copies of a random variable. Let  $I(\theta) = \mathbb{E}_\theta[(\nabla_\theta \log f(X_{i_1}, \theta))(\nabla_\theta \log f(X_{i_1}, \theta))^T]$  be the Fisher information of one copy of the random variable, and let

$$I_n(\theta) = \mathbb{E}_\theta[(\nabla_\theta \log f(X_1, \dots, X_n, \theta))(\nabla_\theta \log f(X_1, \dots, X_n, \theta))^T]$$

denotes the Fisher information of the random vector  $X$ .

**Theorem 1.4.** *In the setting described above, the Fisher information “tensorizes”*

$$I_n(\theta) = nI(\theta)$$

*Proof.* By independence,  $f(X_1, \dots, X_n, \theta) = \prod_{i=1}^n f(X_i, \theta)$ . Then  $\log f(X_1, \dots, X_n, \theta) = \sum_{i=1}^n \log f(X_i, \theta)$ . We write

$$\begin{aligned} I_n(\theta) &= \mathbb{E}_\theta[(\nabla_\theta \log f(X_1, \dots, X_n, \theta))(\nabla_\theta \log f(X_1, \dots, X_n, \theta))^T] \\ &= \mathbb{E}_\theta \left[ \left( \sum_{i=1}^n \nabla_\theta \log f(X_i, \theta) \right) \left( \sum_{i=1}^n \nabla_\theta \log f(X_i, \theta) \right)^T \right] \end{aligned}$$

Recall that  $\mathbb{E}_\theta[\nabla_\theta \log f(X_i, \theta)] = 0$ . Thus, by independence, all but the “diagonal” terms of the product remain, so

$$I_n(\theta) = \sum_{i=1}^n \mathbb{E}_\theta[(\nabla_\theta \log f(X_i, \theta))(\nabla_\theta \log f(X_i, \theta))^T] = nI(\theta)$$

□

## Cramer-Rao bound

**Theorem 1.5** (Cramer-Rao bound). *Let  $\{f(\cdot, \theta) : \theta \in \Theta\}$  be a “regular” statistical model with  $\Theta \subseteq \mathbb{R}$ . Let  $\tilde{\theta} = \tilde{\theta}(X_1, \dots, X_n)$  be an unbiased estimator of  $\theta$  based on  $n$  iid observations from the model. For all  $\theta \in \text{int}(\Theta)$ , we have*

$$\text{Var}_\theta(\tilde{\theta}) = \mathbb{E}_\theta[(\tilde{\theta} - \theta)^2] \geq \frac{1}{nI(\theta)}$$

*Proof.* Recall the Cauchy-Schwarz inequality:

$$(\mathbb{E}[YZ])^2 \leq \mathbb{E}[Y]^2 \mathbb{E}[Z]^2$$

for random variables  $Y, Z$ . In particular, we will take  $Y = \tilde{\theta} - \theta$  and  $Z = \frac{d}{d\theta} \log f(X_1, \dots, X_n, \theta)$ .

Note that  $\mathbb{E}_\theta[Y^2] = \mathbb{E}_\theta[(\tilde{\theta} - \theta)^2]$ . Also, by the previous theorem,

$$\mathbb{E}_\theta[Z^2] = I_n(\theta) = nI(\theta)$$

Furthermore,

$$\begin{aligned}\mathbb{E}_\theta[YZ] &= \mathbb{E}_\theta \left[ \tilde{\theta} \frac{d}{d\theta} \log f(X_1, \dots, X_n, \theta) \right] - \underbrace{\theta \mathbb{E}_\theta \left[ \frac{d}{d\theta} \log f(X_1, \dots, X_n, \theta) \right]}_{=0} \\ &= \int_{\mathcal{X}} \tilde{\theta}(X_1, \dots, X_n) \frac{\frac{d}{d\theta} f(X_1, \dots, X_n, \theta)}{f(X_1, \dots, X_n, \theta)} f(X_1, \dots, X_n) dx_1 \dots dx_n \\ &= \frac{d}{d\theta} \int_{\mathcal{X}} \tilde{\theta}(X_1, \dots, X_n) f(X_1, \dots, X_n, \theta) dx_1 \dots dx_n = \frac{d}{d\theta} \mathbb{E}_\theta[\tilde{\theta}] = 1\end{aligned}$$

and the result follows from Cauchy-Schwarz.  $\square$

**Remark:** if  $\tilde{\theta}$  is not unbiased, the same proof shows that

$$\text{Var}_\theta(\tilde{\theta}) \geq \frac{\left( \frac{d}{d\theta} \mathbb{E}_\theta[\tilde{\theta}] \right)^2}{nI(\theta)}$$

The Cramer-Rao bound is about a variance of an estimate, hence is univariate in nature. Here is one multivariate generalisation. Suppose  $\Theta \subseteq \mathbb{R}^p$  and  $\Phi : \Theta \rightarrow \mathbb{R}$  is differentiable. Suppose  $\tilde{\Phi}$  is an unbiased estimator of  $\Phi(\theta)$  based on iid observations  $(X_1, \dots, X_n)$  from a model  $\{f(\cdot, \theta) : \theta \in \Theta\}$ .

**Theorem 1.6.** For all  $\theta \in \text{int}(\Theta)$ , we have

$$\text{Var}_\theta(\tilde{\Phi}) \geq \frac{1}{n} \nabla_\theta \Phi(\theta)^T (I^{-1}(\theta)) \nabla_\theta \Phi(\theta)$$

*Proof.* Omitted. Can be derived using Cauchy-Schwarz.  $\square$

**Example.** Suppose  $\Phi(\theta) = \alpha^T \theta$ . Then  $\nabla_\theta \Phi(\theta) = \alpha$  so the lower bound is

$$\text{Var}_\theta(\tilde{\Phi}) \geq \frac{1}{n} \alpha^T I^{-1}(\theta) \alpha$$

In the example sheet, we will consider the special case of  $\begin{pmatrix} X_1 \\ X_2 \end{pmatrix} \sim \mathcal{N}(\theta, \Sigma)$

where  $\theta = \begin{pmatrix} \theta_1 \\ \theta_2 \end{pmatrix} \in \mathbb{R}^2$  and  $\Sigma \in \mathbb{R}^{2 \times 2}$  is a known matrix. Let the sample size be  $n = 1$ .

Case 1: consider estimating  $\theta_1$  when  $\theta_2$  is known. This is a one-dimensional estimation problem, and we denote the Fisher information  $I_1(\theta)$ .

Case 2: consider estimating  $\theta_1$  when  $\theta_2$  is unknown. We can take  $\Phi(\theta) = \theta_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}^T \theta$  in the theorem above to obtain a lower bound

$$I_\Phi(\theta) = \nabla_\theta \Phi(\theta)^T I(\theta)^{-1} \nabla_\theta \Phi(\theta)$$



of the variance of an unbiased estimator.

We will show that  $I_1(\theta)^{-1} < I_\Phi(\theta)$ , unless  $X_1$  and  $X_2$  are independent (i.e. unless  $\Sigma$  is diagonal).

## Asymptotic theory of the MLE

Cramer-Rao is concerned with unbiased estimators, but not all estimators, even MLE's are unbiased.

On the other hand, a reasonable property to expect is *asymptotic unbiasedness*:  $\mathbb{E}_\theta[\tilde{\theta}_n] \rightarrow \theta$  as  $n \rightarrow \infty$ , when  $\tilde{\theta}_n$  is computed from  $n$  iid samples from  $P_\theta$ .

A stronger but related concept is *consistency*:  $\tilde{\theta}_n \rightarrow \theta$  as  $n \rightarrow \infty$  (where convergence is defined in a precise way to be discussed later).

For consistent estimators, a reasonable optimality criterion is *asymptotic efficiency*:  $n \text{Var}_\theta(\tilde{\theta}_n) \rightarrow I(\theta)^{-1}$  as  $n \rightarrow \infty$ , when  $\tilde{\theta}_n$  is computed from  $n$  iid samples from  $P_\theta$  (and  $p = 1$ ).

Note that Cramer-Rao does not imply that  $\liminf_{n \rightarrow \infty} n \text{Var}_{\theta}(\tilde{\theta}_n) \geq I(\theta)^{-1}$  for any consistent estimator. However, this is true under appropriate regularity conditions.

Now, we will show that the MLE is always (under regularity conditions) asymptotically efficient. In fact

$$\hat{\theta}_{\text{mle}} \approx \mathcal{N}\left(\theta, \frac{I(\theta)^{-1}}{n}\right), \text{ for any } \theta \in \text{int}(\Theta) \text{ and } n \text{ sufficiently large}$$

## Stochastic Convergence

We now introduce several basic definitions/results that will be used without proof.

**Definition.** Let  $\{X_n\}_{n \geq 0}$  and  $X$  be random vectors in  $\mathbb{R}^k$ , defined on a probability space  $(\Omega, \mathcal{A}, \mathbb{P})$ . So  $X : \Omega \rightarrow \mathbb{R}^k$ ,  $\mathcal{A}$  is the set of measurable sets (“events”).

1. We say  $X_n$  converges to  $X$  *almost surely*, or  $X_n \xrightarrow{\text{a.s.}} X$  as  $n \rightarrow \infty$ , if

$$\begin{aligned} \mathbb{P}(\omega \in \Omega : \|X_n(\omega) - X(\omega)\|_2 \rightarrow 0 \text{ as } n \rightarrow \infty) \\ = \mathbb{P}(\|X_n - X\|_2 \rightarrow 0 \text{ as } n \rightarrow \infty) = 1 \end{aligned}$$

2. We say that  $X_n$  converges to  $X$  *in probability*, or  $X_n \xrightarrow{P} X$  as  $n \rightarrow \infty$ , if for all  $\varepsilon > 0$ ,

$$\mathbb{P}(\|X_n - X\|_2 > \varepsilon) \rightarrow 0$$

3. We say that  $X_n$  converges to  $X$  *in distribution*, or  $X_n \xrightarrow{d} X$  as  $n \rightarrow \infty$ , if

$$\mathbb{P}(X_n \prec t) \rightarrow \mathbb{P}(X \prec t), \forall t \text{ where } t \mapsto \mathbb{P}(X \prec t) \text{ is continuous}$$

we write  $\{X \prec t\}$  as a shorthand for  $\{X_{(1)} \leq t_1, \dots, X_{(k)} \leq t_k\}$ . For  $k = 1$ , this simply means

$$\mathbb{P}(X_n \leq t) \rightarrow \mathbb{P}(X \leq t)$$

i.e convergence of the usual cdf.

**Theorem 1.7.** *Almost sure convergence implies convergence in probability, which implies convergence in distribution. i.e*

$$X_n \xrightarrow{\text{a.s.}} X \implies X_n \xrightarrow{P} X \implies X_n \xrightarrow{d} X$$

*Proof.* See Probability & Measure. □

**Theorem 1.8** (Continuous mapping theorem). *If  $\{X_n\}$  and  $X$  take values in  $\mathcal{X} \subseteq \mathbb{R}^d$  and  $g : \mathcal{X} \rightarrow \mathbb{R}$  is continuous, then*

$$X_n \xrightarrow{\text{a.s./P/d}} X \implies g(X_n) \xrightarrow{\text{a.s./P/d}} g(X)$$

*Proof.* See Probability & Measure.  $\square$

**Theorem 1.9** (Slutsky's lemma). *Let  $X_n \xrightarrow{d} X$  and  $Y_n \xrightarrow{d} c$ , where  $c$  is deterministic (i.e non-stochastic). As  $n \rightarrow \infty$ , we have*

1.  $Y_n \xrightarrow{P} c$
2.  $X_n + Y_n \xrightarrow{d} X + c$
3. When  $Y_n$  is one-dimensional,  $X_n Y_n \xrightarrow{d} cX$ , and if  $c \neq 0$ ,  $\frac{X_n}{Y_n} \xrightarrow{d} \frac{X}{c}$
4. If  $\{A_n\}_{n \geq 0}$  are random matrices such that  $\{A_n\}_{ij} \xrightarrow{P} A_{ij}$  for all  $(i, j)$ , where  $A$  is deterministic, then  $A_n X_n \xrightarrow{d} AX$

*Proof.* See Probability & Measure.  $\square$

**Theorem 1.10.** *If  $X_n \xrightarrow{d} X$  as  $n \rightarrow \infty$ , then  $\{X_n\}_{n \geq 0}$  is bounded in probability, or  $X_n = O_p(1)$ : for all  $\varepsilon > 0$ , there exists  $M(\varepsilon) < \infty$  such that for all  $n \geq 0$*

$$\mathbb{P}(\|X_n\|_2 > M(\varepsilon)) < \varepsilon$$

*Proof.* See Probability & Measure.  $\square$

## Law of Large Numbers (LLN)

Many results in statistics are based on convergence of averages of iid random variables.

**Theorem 1.11** (Weak LLN). *Let  $X_1, \dots, X_n$  be iid copies of  $X$  with  $\text{Var}(X) < \infty$ . As  $n \rightarrow \infty$ , we have  $\bar{X}_n = \frac{1}{n} \sum_{i=1}^n X_i \xrightarrow{P} \mathbb{E}(X)$ .*

**Theorem 1.12** (Strong LLN). *Let  $X_1, \dots, X_n$  be iid copies of  $X \sim P$  on  $\mathbb{R}^k$ , such that  $\mathbb{E}[\|X\|_2] < \infty$ . Then as  $n \rightarrow \infty$  we have*

$$\bar{X}_n = \frac{1}{n} \sum_{i=1}^n X_i \xrightarrow{a.s.} \mathbb{E}[X]$$

We only prove the weak law or large numbers:

*Proof.* We will apply Chebyshev's inequality:

$$\mathbb{P}(|Z - \mu| \geq \varepsilon) \leq \frac{\text{Var}(Z)}{\varepsilon^2}$$

where  $\mu = \mathbb{E}[Z]$ . Take  $Z_n = \frac{1}{n} \sum_{i=1}^n (X_i - \mathbb{E}(X))$  for a fixed  $\varepsilon > 0$ . Then

$$\mathbb{P}(|\bar{X}_n - \mathbb{E}(X)| \geq \varepsilon) = \mathbb{P}(|Z_n| \geq \varepsilon) \leq \frac{\text{Var}(Z_n)}{\varepsilon^2}$$

So it suffices to show  $\text{Var}(Z_n) \rightarrow 0$ . By independence of the  $X_i$ 's, we have

$$\text{Var}(Z_n) = \frac{1}{n^2} \sum_{i=1}^n \text{Var}(X_i) = \frac{\text{Var}(X)}{n} \rightarrow 0$$

since  $\text{Var}(X) < \infty$ .  $\square$

## Central Limit Theorem (CLT)

We now present a finer-grained characterisation of the behaviour of  $\bar{X}_n$ . The stochastic fluctuations of  $\bar{X}_n$  around  $\mathbb{E}(X)$  are of the order  $\frac{1}{\sqrt{n}}$  and look normally distributed.

**Theorem 1.13** (CLT). *Let  $X_1, \dots, X_n$  be iid copies of  $X \sim P$  on  $\mathbb{R}$ , such that  $\text{Var}(X) = \sigma^2 < \infty$ . As  $n \rightarrow \infty$ , we have*

$$\sqrt{n} \left( \frac{1}{n} \sum_{i=1}^n X_i - \mathbb{E}(X) \right) \xrightarrow{d} \mathcal{N}(0, \sigma^2)$$

*Proof.* Omitted. □

**Remark:** the CLT is useful for constructing confidence intervals. Suppose  $X_1, \dots, X_n$  is a sequence of iid copies of a random variable with mean  $\mu_0$  and variance  $\sigma^2$ , and let  $\alpha \in (0, 1)$ . Define the confidence region

$$\mathcal{C}_n = \left\{ \mu \in \mathbb{R} : |\mu - \bar{X}_n| \leq \frac{\sigma z_\alpha}{\sqrt{n}} \right\}$$

where  $z_\alpha$  is defined such that  $\mathbb{P}(|Z| \leq z_\alpha) = 1 - \alpha$ , for  $Z \in \mathcal{N}(0, 1)$ . Then we can compute

$$\begin{aligned} \mathbb{P}(\mu_0 \in \mathcal{C}_n) &= \mathbb{P} \left( \left| \frac{1}{n} \sum_{i=1}^n \frac{X_i - \mu_0}{\sigma} \right| \leq \frac{z_\alpha}{\sqrt{n}} \right) \\ &= \mathbb{P} \left( \sqrt{n} \left| \frac{1}{n} \sum_{i=1}^n \tilde{X}_i - \mathbb{E}(\tilde{X}) \right| \leq z_\alpha \right) \\ &\rightarrow \mathbb{P}(|Z| \leq z_\alpha) = 1 - \alpha \end{aligned}$$

where  $\tilde{X}_i = \frac{X_i - \mu_0}{\sigma}$ , is a zero mean, variance 1 random variable. So  $\mathcal{C}_n$  is an asymptotic level  $(1 - \alpha)$  confidence interval.

**Theorem 1.14** (Multivariate CLT). *Let  $X_1, \dots, X_n$  be iid copies of  $X \sim P$  on  $\mathbb{R}^k$ , such that  $\text{Cov}(X) = \Sigma$  is positive definite. As  $n \rightarrow \infty$  we have*

$$\sqrt{n} \left( \frac{1}{n} \sum_{i=1}^n X_i - \mathbb{E}(X) \right) \xrightarrow{d} \mathcal{N}(0, \Sigma)$$

**Remark:** recall that a random vector  $X \in \mathbb{R}^k$  has a normal distribution with mean  $\mu \in \mathbb{R}^k$  and covariance  $\Sigma \in \mathbb{R}^{k \times k}$ , denoted by  $X \sim \mathcal{N}(\mu, \Sigma)$ , if the pdf is

$$f(x) = \frac{1}{(2\pi)^{k/2}} \frac{1}{|\det(\Sigma)|^{1/2}} \exp \left( -\frac{1}{2} (x - \mu)^T \Sigma^{-1} (x - \mu) \right)$$

**Remark:** as a consequence of one of the theorems above, we also have

$$\frac{1}{n} \sum_{i=1}^n X_i - \mathbb{E}(X) = \mathcal{O}_p \left( \frac{1}{\sqrt{n}} \right)$$

## Consistency of the MLE

**Definition.** Consider iid draws  $X_1, \dots, X_n$  from the parametric model  $\{P_\theta : \theta \in \Theta\}$ . An estimator  $\tilde{\theta}_n = \tilde{\theta}_n(X_1, \dots, X_n)$  is *consistent* if  $\tilde{\theta}_n \xrightarrow{P} \theta$  as  $n \rightarrow \infty$ , whenever the  $X_i$ 's are drawn from  $P_\theta$ . We also write  $\tilde{\theta}_n \xrightarrow{P_\theta} \theta$ .

We will show that the MLE is unique and consistent under the following regularity assumptions:

Let  $\{f(\cdot, \theta) : \theta \in \Theta\}$  be a statistical model of pdf's/pmf's on  $\mathcal{X} \subseteq \mathbb{R}^d$  such that

1.  $f(x, \theta) > 0$  for all  $x \in \mathcal{X}$ ,  $\theta \in \Theta$
2. The function  $f(x, \cdot) : \theta \mapsto f(x, \theta)$  is continuous for all  $x \in \mathcal{X}$ .
3. The set  $\Theta \subseteq \mathbb{R}^p$  is compact.
4. For any  $\theta, \theta' \in \Theta$ ,  $f(\cdot, \theta) = f(\cdot, \theta')$  if and only if  $\theta = \theta'$  (strict identifiability)
5.  $\mathbb{E}_\theta [\sup_{\theta'} |\log f(X, \theta')|] < \infty$  for all  $\theta \in \Theta$ .

These will be referred to as “the usual regularity conditions” in this course and its Examples sheets/Exams.

**Remarks:**

- Assumptions 1 and 4 are required to apply the strict version of Jensen's inequality to deduce that  $\theta_0$  is the unique maximum of  $l(\theta) = \mathbb{E}_{\theta_0} [\log f(X, \theta)]$ .
- Assumption 5 implies that continuity of the function  $\theta \mapsto \log f(x, \theta)$  carries over to continuity of  $\theta \mapsto \mathbb{E}_\theta [\log f(X, \theta)] = l(\theta)$ , according to the Dominated Convergence Theorem.

**Theorem 1.15** (\*Dominated Convergence Theorem\*). *If a sequence of (measurable) functions  $\{f_n\}$  converges pointwise to a function  $f : \mathcal{X} \rightarrow \mathbb{R}$  such that  $|f_n(x)| \leq g(x)$  for all  $x \in \mathcal{X}$ , for some function  $g : \mathcal{X} \rightarrow \mathbb{R}$  such that  $\mathbb{E}[|g(X)|] < \infty$ , where  $X$  is a random variable taking values in  $\mathcal{X}$ , then*

$$\mathbb{E}|f_n(X) - f(X)| \rightarrow 0 \text{ as } n \rightarrow \infty$$

In particular, for any sequence  $\theta_n \rightarrow \theta$  in  $\Theta$ , we can define  $f_n(x) = \log(f(x, \theta_n))$  and  $g(x) = \sup_{\theta'} |\log f(x, \theta')|$  and conclude that  $l(\theta_n) \rightarrow l(\theta)$ .

**Theorem 1.16.** *Let  $X_1, \dots, X_n$  be iid samples of a model  $\{f(\cdot, \theta) : \theta \in \Theta\}$  satisfying the above assumptions. Then an MLE exists, and any MLE is consistent.*

*Proof.* Note that the mapping  $\theta \mapsto \bar{l}_n(\theta) = \frac{1}{n} \sum_{i=1}^n \log f(x_i, \theta)$  is continuous on the compact set  $\Theta$ . Thus a maximiser exists, so the MLE is well-defined.

To prove consistency, let  $\theta_0$  denote the true parameter. We use (without proof) the fact that under the regularity assumptions, we have the uniform convergence

$$\sup_{\theta \in \Theta} |\bar{l}_n(\theta) - l(\theta)| \xrightarrow{P_{\theta_0}} 0$$

(This is somewhat stronger than the LLN, which concerns convergence just at fixed  $\theta$ )

Now define  $\Theta_\varepsilon = \{\theta \in \Theta : \|\theta - \theta_0\|_2 \geq \varepsilon\}$ , for arbitrary  $\varepsilon > 0$ . We will show that for any sequence of MLE's  $\{\hat{\theta}_n\}$ , we have  $\mathbb{P}(\hat{\theta}_n \in \Theta_\varepsilon) \rightarrow 0$  as  $n \rightarrow \infty$ .

Note that since  $\Theta_\varepsilon$  is the intersection of  $\Theta$  with a closed set, it is also compact. Thus, there exists  $\theta_\varepsilon \in \Theta_\varepsilon$  such that  $l(\theta_\varepsilon) = \sup_{\theta \in \Theta_\varepsilon} l(\theta) := c(\varepsilon) < l(\theta_0)$ , since  $\theta_0$  is the unique maximiser of  $l$ .

Let  $\delta(\varepsilon) > 0$  be such that  $\delta(\varepsilon) < \frac{l(\theta_0) - c(\varepsilon)}{2}$ . We now write

$$\begin{aligned} \sup_{\theta \in \Theta_\varepsilon} \bar{l}_n(\theta) &\leq \sup_{\theta \in \Theta_\varepsilon} l(\theta) + \sup_{\theta \in \Theta_\varepsilon} (\bar{l}_n(\theta) - l(\theta)) \\ &\leq \sup_{\theta \in \Theta_\varepsilon} l(\theta) + \sup_{\theta \in \Theta} |\bar{l}_n(\theta) - l(\theta)| \end{aligned}$$

Consider the sequence of events

$$A_n(\varepsilon) = \left\{ \sup_{\theta \in \Theta} |\bar{l}_n(\theta) - l(\theta)| \leq \delta(\varepsilon) \right\}$$

By the assumed uniform convergence statement, we have  $\mathbb{P}(A_n(\varepsilon)) \rightarrow 1$  as  $n \rightarrow \infty$ .

We now argue that  $A_n(\varepsilon) \subseteq \{\hat{\theta}_n \notin \Theta_\varepsilon\}$ , which then implies the desired result.

Indeed, on the events  $\{A_n(\varepsilon)\}$ , we have

$$\sup_{\theta \in \Theta_\varepsilon} \bar{l}_n(\theta) \leq c(\varepsilon) + \delta(\varepsilon) < l(\theta_0) - \delta(\varepsilon) \leq \bar{l}_n(\theta_0)$$

Thus, the MLE cannot lie in  $\Theta_\varepsilon$ , completing the proof.  $\square$

**Remark:** the proof can be simplified under additional properties of the likelihood function, such as differentiability and/or uniqueness of zeros. This can be useful in situations where  $\Theta$  is not compact (see Example sheet).