

## Exercise Sheet: Linear Maps

1. Determine which of the following maps  $L$  are linear.
  - (a)  $L : \mathbb{R}^3 \rightarrow \mathbb{R}^2$  defined by  $L(x, y, z) = (3x - 2y + z, 3x - 2y)$ .
  - (b)  $L : \mathbb{R}^3 \rightarrow \mathbb{R}^3$  defined by  $L(x, y, z) = (x, y - 1, z)$ .
  - (c)  $L : \mathbb{R}^2 \rightarrow \mathbb{R}$  defined by  $L(x, y) = xy$ .
  - (d)  $L : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  defined by  $L(x, y) = (x, -y)$  (the reflection by  $x$ -axis).
  - (e)  $L : \mathbb{R}^2 \rightarrow \mathbb{R}$  defined by  $L(x, y) = \max\{x, y\}$ .
  - (f)  $L : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  defined by  $L(x, y) = (0, 1)$ .
  - (g)  $L : M_{m \times n} \rightarrow M_{n \times m}$  defined by  $L(A) = A^T$ .
2. Suppose a linear  $T$  transforms  $(1, 1)$  to  $(2, 2)$  and  $(2, 0)$  to  $(0, 0)$ .
  - (a) Find  $T(2, 2)$ .
  - (b) Find  $T(3, 1)$ .
  - (c) Find the matrix representation for  $T$  with respect to the standard basis of  $\mathbb{R}^2$ .
  - (d)  $v = (a, b)$ , for  $a, b \in \mathbb{R}$ .
  - (e) Find  $T^2(2, 2)$ .
3. Find the matrix representation with respect to standard bases for the following linear maps
  - (a) the projection from the space  $\mathbb{R}^3$  onto the  $x - y$  plane.
  - (b) the reflection from the space  $\mathbb{R}^3$  through the  $x - y$  plane.
  - (c)  $L : \mathbb{R}^2 \rightarrow \mathbb{R}^3$  such that  $L(x, y) = (2x - y, 3x + 4y, x - 5y)$ .
  - (d) the  $\phi$ -rotation from  $\mathbb{R}^2$  to itself.
4. Find the range and kernel of  $T$ :
  - (a)  $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  defined by  $T(v_1, v_2) = (v_2, v_1)$ ;
  - (b)  $T : \mathbb{R}^3 \rightarrow \mathbb{R}^2$  defined by  $T(v_1, v_2, v_3) = (v_1, v_2)$  (the projection);
  - (c)  $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  defined by  $T(v_1, v_2) = (0, 0)$ ;
  - (d)  $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  defined by  $T(v_1, v_2) = (v_1, v_1)$ ;
  - (e)  $T : \mathbb{R}^2 \rightarrow \mathbb{R}^3$  defined by  $T(x, y) = (2x - y, 3x + 4y, x - 5y)$ .

5. Let  $L : M_{n \times n} \rightarrow M_{n \times n}$  be the map such that  $L(A) = \frac{A - A^T}{2}$ .
  - (a) Show that  $L$  is linear.
  - (b) Describe the kernel of  $L$ , and determine its dimension.
  - (c) What is the image of  $L$ ?
6. For the following transformations from  $\mathbb{R}^2$  to  $\mathbb{R}^2$ . Find  $T(T(v))$ 
  - (a)  $T(v) = -v$ ;
  - (b)  $T(v) = v + (1, 1)$ ;
  - (c)  $T(v) = 90^\circ \text{ rotation} = (-v_2, v_1)$ ;
7. Let  $L : V \rightarrow W$  be a linear map such that  $\ker(L) = \{0\}$ . Show that if  $v_1, v_2, \dots, v_n$  are linearly independent of  $V$ , then  $L(v_1), L(v_2), \dots, L(v_n)$  are linearly independent elements of  $W$ .
8. Let  $L : V \rightarrow W$  be a linear map on finite dimensional spaces  $V$  and  $W$ . Then,
 
$$\dim V = \dim \ker(L) + \dim \operatorname{Im}(L).$$