

Exercise Sheet: Linear Maps

1. Determine which of the following maps L are linear.
 - (a) $L : \mathbb{R}^3 \rightarrow \mathbb{R}^2$ defined by $L(x, y, z) = (3x - 2y + z, 3x - 2y)$.
 - (b) $L : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ defined by $L(x, y, z) = (x, y - 1, z)$.
 - (c) $L : \mathbb{R}^2 \rightarrow \mathbb{R}$ defined by $L(x, y) = xy$.
 - (d) $L : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ defined by $L(x, y) = (x, -y)$ (the reflection by x -axis).
 - (e) $L : \mathbb{R}^2 \rightarrow \mathbb{R}$ defined by $L(x, y) = \max\{x, y\}$.
 - (f) $L : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ defined by $L(x, y) = (0, 1)$.
 - (g) $L : M_{m \times n} \rightarrow M_{n \times m}$ defined by $L(A) = A^T$.
2. Suppose a linear T transforms $(1, 1)$ to $(2, 2)$ and $(2, 0)$ to $(0, 0)$.
 - (a) Find $T(2, 2)$.
 - (b) Find $T(3, 1)$.
 - (c) Find the matrix representation for T with respect to the standard basis of \mathbb{R}^2 .
 - (d) $v = (a, b)$, for $a, b \in \mathbb{R}$.
 - (e) Find $T^2(2, 2)$.
3. Find the matrix representation with respect to standard bases for the following linear maps
 - (a) the projection from the space \mathbb{R}^3 onto the $x - y$ plane.
 - (b) the reflection from the space \mathbb{R}^3 through the $x - y$ plane.
 - (c) $L : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ such that $L(x, y) = (2x - y, 3x + 4y, x - 5y)$.
 - (d) the ϕ -rotation from \mathbb{R}^2 to itself.
4. Find the range and kernel of T :
 - (a) $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ defined by $T(v_1, v_2) = (v_2, v_1)$;
 - (b) $T : \mathbb{R}^3 \rightarrow \mathbb{R}^2$ defined by $T(v_1, v_2, v_3) = (v_1, v_2)$ (the projection);
 - (c) $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ defined by $T(v_1, v_2) = (0, 0)$;
 - (d) $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ defined by $T(v_1, v_2) = (v_1, v_1)$;
 - (e) $T : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ defined by $T(x, y) = (2x - y, 3x + 4y, x - 5y)$.

5. Let $L : M_{n \times n} \rightarrow M_{n \times n}$ be the map such that $L(A) = \frac{A - A^T}{2}$.
- (a) Show that L is linear.
 - (b) Describe the kernel of L , and determine its dimension.
 - (c) What is the image of L ?
6. For the following transformations from \mathbb{R}^2 to \mathbb{R}^2 . Find $T(T(v))$
- (a) $T(v) = -v$;
 - (b) $T(v) = v + (1, 1)$;
 - (c) $T(v) = 90^\circ$ rotation $= (-v_2, v_1)$;
7. Let $L : V \rightarrow W$ be a linear map such that $\ker(L) = \{0\}$. Show that if v_1, v_2, \dots, v_n are linearly independent of V , then $L(v_1), L(v_2), \dots, L(v_n)$ are linearly independent elements of W .
8. Let $L : V \rightarrow W$ be a linear map on finite dimensional spaces V and W . Then,

$$\dim V = \dim \text{Ker}(L) + \dim \text{Im}(L).$$