
AutoML project: Tuning a majority voting ensemble consisting of random forest classifier, gradient boosting classifier and SVM classifier using DEHB

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Abstract The AutoML system tunes a ML pipeline of an imputer, an optional sampler, an optional standardizer and a choice of three models. Since the tasks are imbalanced tabular data, a random forest classifier, a gradient boosting classifier and a SVM classifier are reasonable choices, which should yield a good overall prediction by majority voting. I used DEHB as an optimizer, which combines the advantages of differential evolutions and hyperband, i.e., generating promising new hyperparameter configurations for longer training based on initial cheap evaluations. Overall, the improvement in performance compared to the untuned random forest classifier baseline is 0.6% to 25.3%. Thus the AutoML system outperforms the baseline across all datasets by balanced accuracy and it is significantly different for 9 out of 10 datasets by the McNemar test. The source code is available at: https://github.com/constantin-crailsheim/automl_imbalanced

1 Introduction

The objective of the AutoML system is to yield good performance as measured by the balanced accuracy on imbalanced tabular datasets and be able to deal with missing values. Thus, it optimizes a ML pipeline consisting of five elements. First, a choice of two imputers replaces missing values. Then, an optional sampling method is applied to deal with imbalance in the targets, which consists of both under- and oversampling methods. Next, the pre-processed integer features are rounded such that they do not take values that would not appear in the training data. After optionally normalizing all features, three different models were fitted, i.e., a random forest classifier, a gradient boosting classifier and a SVM classifier. The choice of pre-processing and the hyperparameters of the model were optimized by DEHB, which is a computationally cheap optimizer that works well on discrete search spaces. The final predictions are derived by majority voting of the individual predictions of the best pipelines for each model. This means that the overall predictions should be good of the errors of the model are not too correlated.

2 Method

This section outlines the specific choices of the AutoML system and how it will be optimized and evaluated. The choices of the imputation strategy of `sklearn.impute` are:

- The `SimpleImputer` is an univariate imputer, which completes missing values with a descriptive statistic per feature. I chose the median, since it is less sensitive to outliers than the mean.
- The `KNNImputer` replaces missing values by the mean value of its 5 nearest neighbors as default based on Euclidian distance of their non-missing observations of the same feature.

The choices of data-level sampling method to yield balanced dataset of `imblearn` are:

- SMOTE as an oversampling approach generates new samples of the minority class by interpolating between existing observations of the minority class, where no distinction is made between easy and hard samples.

- TomekLinks as an undersampling approach removes samples from the majority class, if they are nearest neighbors to a minority class sample, thus removing noisy borderline samples of the majority class.
- SMOTETomek, which combines SMOTE and Tomek links.
- No sampling method, which would allow algorithmic-level methods to deal with the imbalanced data.

The above pre-processing methods could generate numeric values for features that should contain only integers (e.g., ordinal categorical features), since they impute missing values by means or medians and generate new samples by interpolation. Thus, another layer is added to the pipeline, which rounds all observations of those features to an integer.

The last step of pre-processing is the choice of whether to apply the `StandardScaler` of `sklearn.preprocessing` to standardize the features. This will be in particular useful for the SVM, since an RBF kernel assumes features centered around zero and similar variance across features.

Subsequently, the hyperparameters of the three models of the ensemble were optimized, where the search space was defined with the `ConfigSpace` package. For almost all hyperparameters, the default was set to the default specified for each model. The search space was mostly chosen such that it is centered around the default while accounting for log scale. In those cases where the default would be at the lower end of a reasonable search space, the upper bound was chosen higher.

The first model in the ensemble is a `RandomForestClassifier` from `sklearn.ensemble`. It can handle all data types well and generalizes well by having a low variance due to ensembling over relatively uncorrelated models. The hyperparameters, which will all be sampled uniformly, are:

Hyperparameter	Data type	Search space	Default	Other
criterion	Categorical	{gini, entropy, log_loss}	gini	
max_depth	Integer	[5,15]	10	
min_samples_split	Integer	[1, 32]	2	Log scale
min_samples_leaf	Integer	[1, 16]	1	Log scale
max_features	Integer	[0.1, 0.9]	0.5	
class_weight	Categorical	{balanced, balanced_subsample, None}	None	

The `class_weight` is an algorithm-level method that deals with imbalanced data and will only have an effect if no data-level sampling method was used, since in that case the dataset passed to the model will be balanced.

The second model in the stack is a `GradientBoostingClassifier` from `sklearn.ensemble`. It has strong predictive performance by iteratively fitting weak learners on the error of the previous learner and has similar advantages as the `RandomForestClassifier`. The hyperparameters are:

Hyperparameter	Data type	Search space	Default	Other
loss	Categorical	{log_loss, exponential}	log_loss	
learning_rate	Float	[0.01, 1]	0.1	Log scale
criterion	Categorical	{friedman_mse, squared_error}	friedman_mse	
min_samples_split	Integer	[1, 32]	2	Log scale
min_samples_leaf	Integer	[1, 16]	1	Log scale
max_depth	Integer	[2,10]	3	

The third model in the stack is a Support Vector Classifier (SVC) from `sklearn.svm`. This model works in particular well on easily to separate datasets, on small datasets and in high-dimensional spaces (GeeksforGeeks, 2023). The hyperparameters are:

Hyperparameter	Data type	Search space	Default	Other
C	Float	[0.1, 10]	1.0	Log scale
kernel	Categorical	{linear, poly, rbf, sigmoid}	rbf	
shrinking	Boolean	{True, False}	True	
tol	Float	[1e-4, 1e-2]	1e-3	
class_weight	Categorical	{balanced, None}	None	

To optimize the hyperparameter of the AutoML system, I used DEHB by Awad et al. (2021), which combines differential evolution and hyperband. Differential evolution constructs a new mutant vector from three random parents and then generates the offspring by randomly selecting values from the new mutant vector with probability p and otherwise from one of the corresponding parents. Hyperband allows to search the whole search space with cheap evaluations and only trains more costly models on promising areas of the search space. The algorithm starts by sampling N random hyperparameter configurations, which are evaluated at the lowest budget. Then the best $1/\eta$ of these configurations are evaluated at a η -times higher budget and this process is repeated until the highest fidelity (denoted here by f) is reached, thus $N = \eta^{f-1}$. After completing one iteration, the algorithm restarts with new instantiations and evaluates these at the second lowest fidelity, thereby hedging against bad initializations. DEHB combines both approaches by generating the hyperparameter configurations for the next fidelity by differential evolution from the lower fidelity as parent pool. The authors state that DEHB is computationally cheap with high speed-up gains compared to BOHB. Furthermore, it has strong final performance for discrete search spaces, which I have for various hyperparameters. The authors experiments have shown that DEHB also outperforms SMAC by mean ranks across all chosen benchmarks. For those reasons, I chose DEHB as an efficient optimizer for this problem.

For the optimization, I set $\eta = 3$ and $f = 4$, which implies an initial population of $N = 3^3 = 27$. I set the budget for the `RandomForestClassifier` and the `GradientBoostingClassifier`, as indicated by the number of trees in the forest, to a minimum of 10 and maximum of 270. For SVC, the budget is indicated by the maximum number of iterations and I set it to a minimum of 500 and maximum of 13500. However, the runtime between the lowest and largest budget did not differ too much since the SVM optimizer most likely already converged in most cases and the evaluation was relatively cheap compared to the forest based classifiers for most datasets. Thus, the SVC mostly benefits from differential evolution and the successive halving element is not as important since many configurations can be tested irrespectively. Hence, I allocated 40% of the maximum cost to optimizing the forest based models and 20% to optimizing the SVC.

To evaluate the performance of the AutoML system, I used 3-fold external and 4-fold internal cross-validation. I used stratified CV to ensure that the class imbalance of the targets is preserved in each fold. Given a total budget of 3600 seconds per dataset, a total of 1200 second could be used to optimize the AutoML system in each fold. Since the budget is not that larger after accounting for cross-validation, I tuned only a selection of hyperparameters of the actual model and the hyperparameters of the preprocessing functions were kept at their default values.

After the optimization routine, all three models are passed to the `VotingClassifier` and fitted with their incumbent configurations. Then the imbalance sampling is removed from the pipeline to not sample from the test set. Thus, the final AutoML system is an ensemble of three models with majority voting for the final classification.

3 Experiments

I used a M1 Pro chip with 32 GB from 2021 to run the optimization. The external cross-validation performance in terms of balanced accuracy of the AutoML system vs. the untuned RandomForestClassifier baseline for each dataset id is shown below:

Model	976	980	1002	1018	1019	1021	1040	1053	1461	41160
Baseline	0.962	0.939	0.547	0.554	0.989	0.932	0.960	0.594	0.695	0.571
AutoML system	0.990	0.982	0.806	0.809	0.997	0.957	0.992	0.657	0.838	0.743
Improvement	0.027	0.043	0.259	0.254	0.008	0.025	0.032	0.063	0.143	0.172
McNemar test	37.19	30.94	927.63	906.28	8.75	11.40	1.86	287.88	660.02	117.14

Hence, the AutoML system outperforms the baseline across all datasets with an improvement between 0.6% and 25.3%. To evaluate whether the two algorithms are significantly different, I used the McNemar test, which was computed over the concatenated predictions of all folds. The reference distribution is χ_1^2 and thus the algorithms would be significantly different at the 5%-level if the test statistic is larger than 3.84, which is the case for all datasets except for dataset 1040. However, for this dataset the balanced accuracy is still 3.2% better and above 99%.

The plots of the trajectories for each dataset are in appendix A. For dataset 976, 980 1019, the SVC is the top performing estimator, followed by the GradientBoostingClassifier and the RandomForestClassifier. For the other datasets, the ranking is not as clear. For the last two datasets, the SVC has the worst performance, most likely since SVMs are costlier to fit given the large number of observations and less iterations to tune the hyperparameters were possible. However, the overall performance of the AutoML system is still similar to the best individual models due to majority voting. The benchmarks are usually outperformed after at most 50 seconds, except for the last two datasets due to the underperforming SVC. The final externally cross-validated performance is a bit lower than the performances of the individual algorithms for a few datasets, since the performance of the individual algorithms tends to be overly optimistic due to the hyperparameters being tuned on that specific fold.

The chosen incumbents for each model for all datasets are shown in the appendix. The key trends are as following: The preferred sampling method for RandomForestClassifier and SVC is quite mixed, but for the GradientBoostingClassifier only oversampling or mixed methods were considered better. As expected, SVC uses the StandardScaler for all datasets except 1019. If no sampling method was chosen, the imbalance was always accounted for by class weights. Lastly, the RandomForestClassifier prefers deeper trees than the GradientBoostingClassifier.

4 Conclusion

The AutoML system outperforms the benchmark across all datasets and has thus has proven to be useful. However, some improvements are still possible if a larger budget would be available. The hyperparameters of the pre-processing methods could be also tuned to fit better to each dataset and algorithm. Furthermore, a stacking classifier could be trained on the three algorithms, which would allow to find the best combination of the predictions of each individual algorithm for the final prediction of the AutoML system. This would be in particular beneficial to the last two datasets, where the ensemble performance was significantly worse than the two best individual performances. I conducted experiments with stacking, but the training on the final incumbents with the highest budgets took fairly long, thus I decided to use the budget rather to improve the performance of the individual estimators.

References

- Awad, N., Mallik, N., and Hutter, F. (2021). DEHB: Evolutionary hyberband for scalable, robust and efficient hyperparameter optimization. In Zhou, Z., editor, *Proceedings of the Thirtieth International Joint Conference on Artificial Intelligence, IJCAI-21*, pages 2147–2153. ijcai.org.
- GeeksforGeeks (2023). Support vector machine in machine learning. <https://www.geeksforgeeks.org/support-vector-machine-in-machine-learning/>.

A Trajectories

The following plots show the trajectories of the incumbent performance for all three models evaluated with internal cross-validation in each fold over runtime. Furthermore, the external cross-validation of the untuned random forest classifier baseline is plotted as grey horizontal line and the external cross-validation of the final performance of the AutoML system is plotted as purple dot at the maximum runtime per model in each fold.

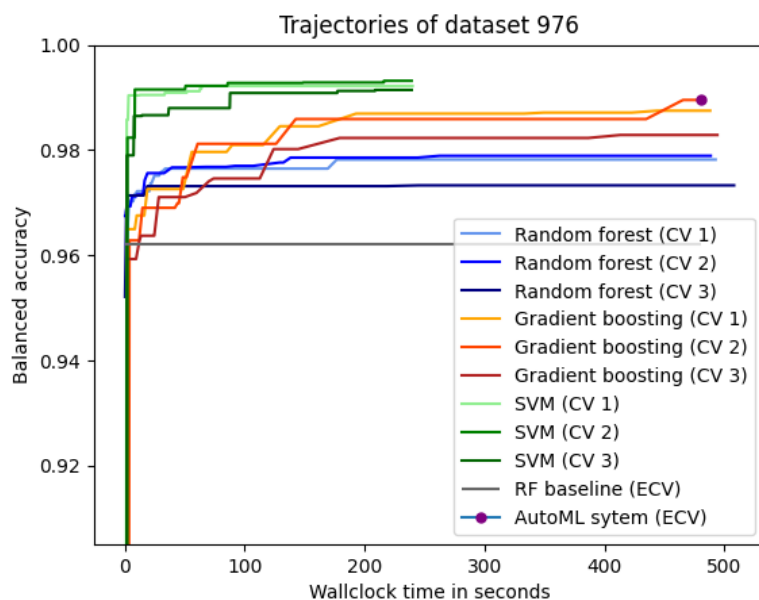


Figure 1: Trajectories for dataset 976 with 9961 observations and 14 features.

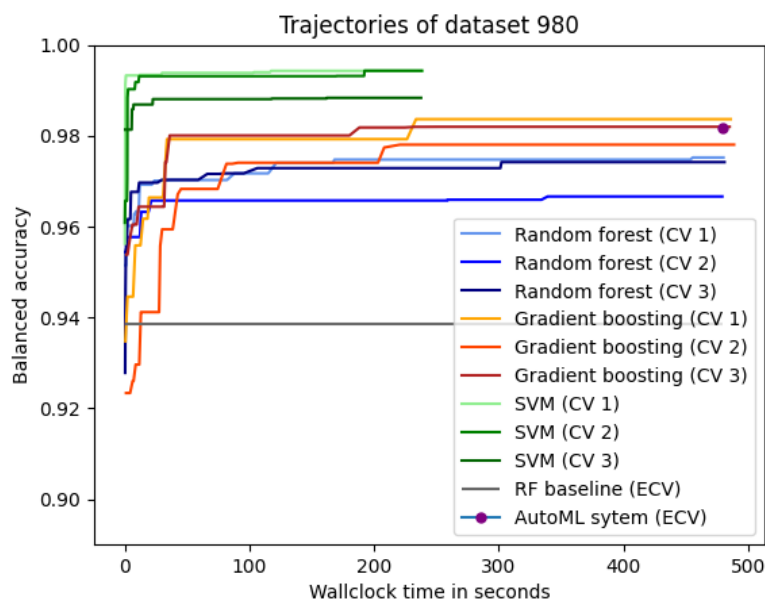


Figure 2: Trajectories for dataset 980 with 5620 observations and 64 features.

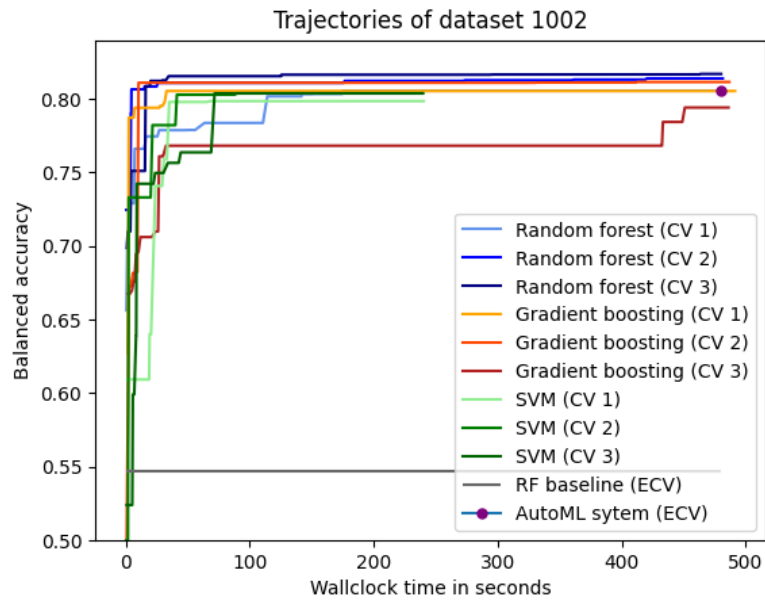


Figure 3: Trajectories for dataset 1002 with 7485 observations and 55 features.

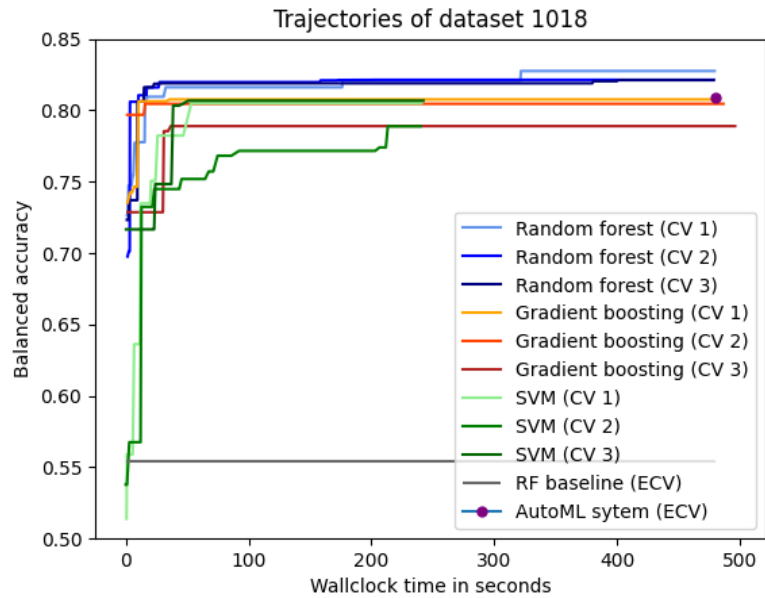


Figure 4: Trajectories for dataset 1018 with 8844 observations and 56 features.

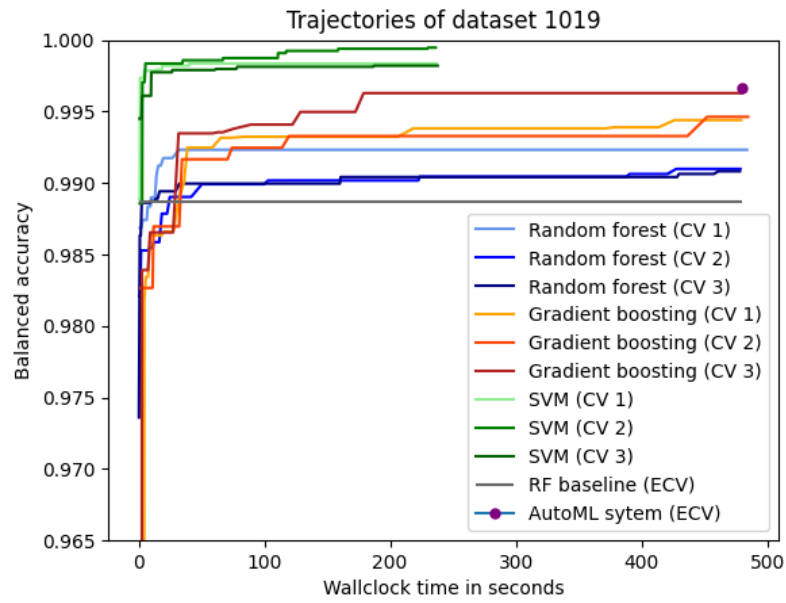


Figure 5: Trajectories for dataset 1019 with 10992 observations with 16 features

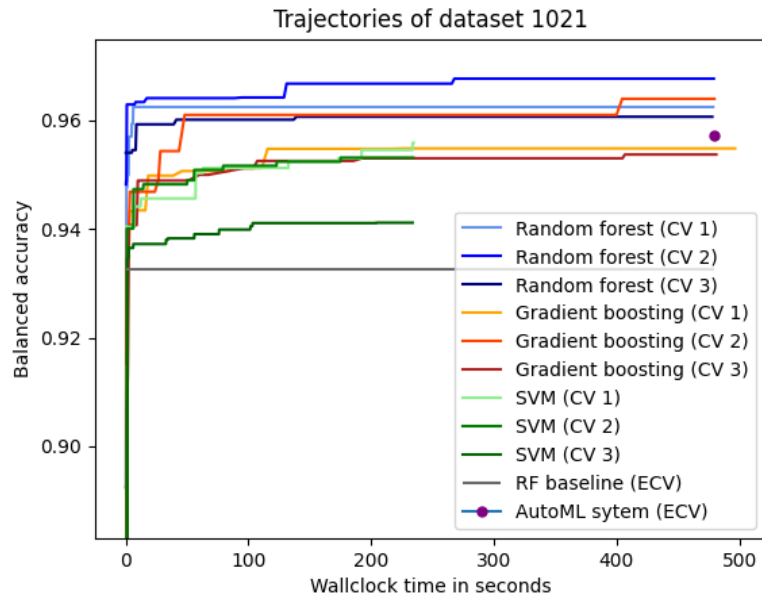


Figure 6: Trajectories for dataset 1021 with 5473 observations and 10 features.

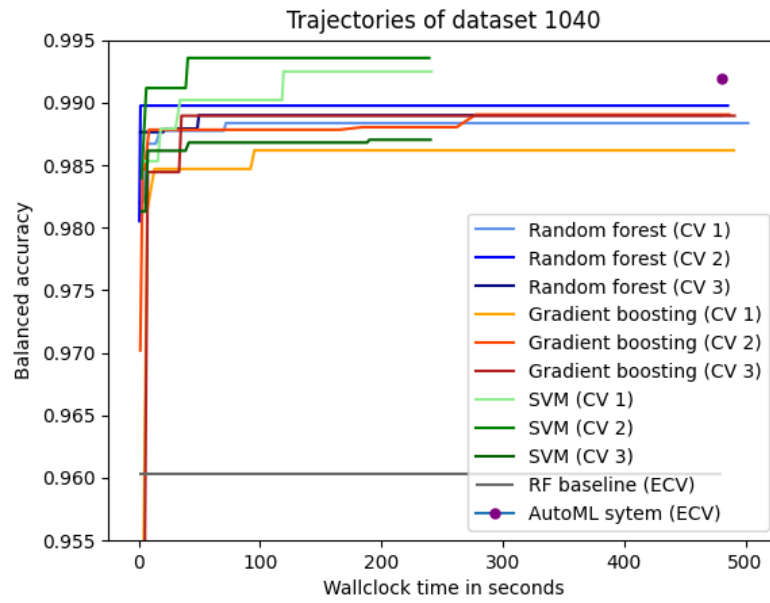


Figure 7: Trajectories for dataset 1040 with 14395 observations and 108 features.

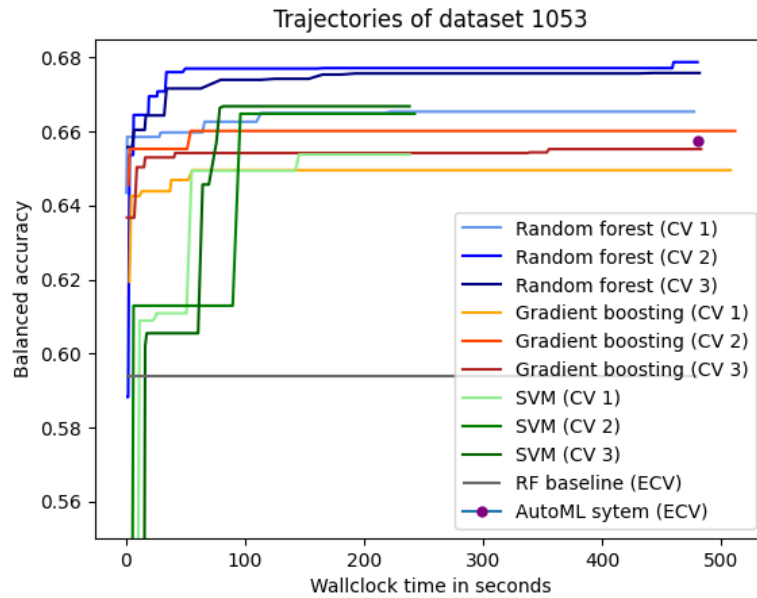


Figure 8: Trajectories for dataset 1053 with 10885 observations and 21 features.

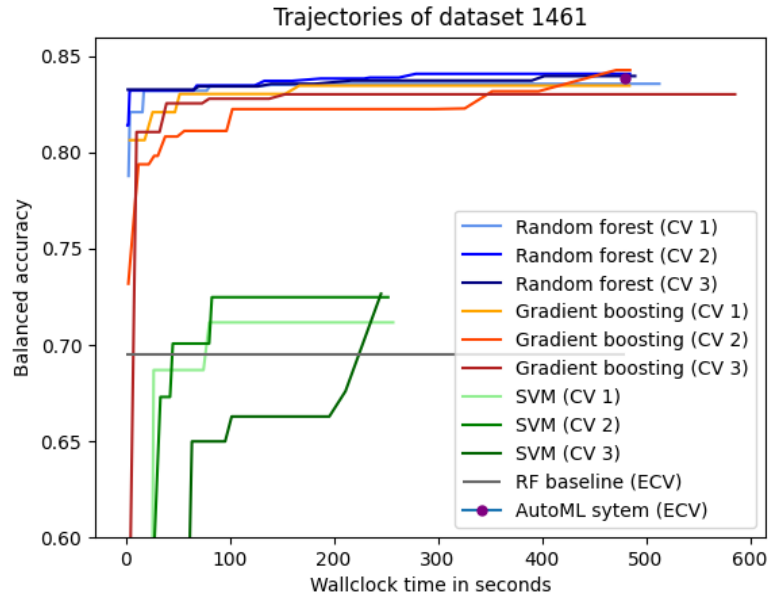


Figure 9: Trajectories for dataset 1461 with 45221 observations and 16 features.

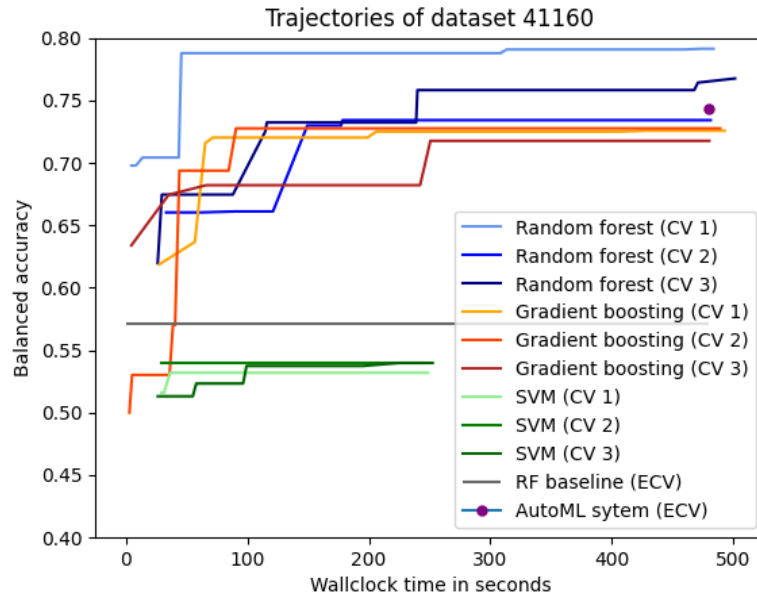


Figure 10: Trajectories for dataset 41660 with 31406 observations and 22 features.

B Incumbent hyperparameter

The following tables shows the incumbent hyperparameter configurations for each algorithm and each dataset in each fold.

Table 1: Incumbent hyperparameters configurations for the random forest classifier

Dataset ID	CV fold	Imputer	Sampler	Scaler	Criterion	Max depth	Min samples per split	Min samples per leaf	Max features	Class weight
976	1	Simple	SMOTETomek	True	entropy	19	6	1	0.527	balanced_subsample
976	2	Simple	SMOTETomek	True	log_loss	25	1	1	0.419	balanced_subsample
976	3	Simple	SMOTE	False	entropy	18	4	2	0.676	balanced
980	1	KNN	SMOTE	False	entropy	22	4	8	0.190	balanced_subsample
980	2	Simple	SMOTE	True	entropy	7	9	8	0.202	balanced_subsample
980	3	Simple	SMOTE	True	entropy	7	2	3	0.357	balanced
1002	1	KNN	Tomek	True	entropy	5	4	5	0.152	balanced
1002	2	KNN	SMOTE	True	entropy	6	13	1	0.106	None
1002	3	Simple	None	True	entropy	5	8	6	0.262	balanced
1018	1	KNN	Tomek	False	gini	5	10	1	0.188	balanced_subsample
1018	2	KNN	None	False	entropy	6	24	4	0.116	balanced
1018	3	Simple	Tomek	True	entropy	5	2	9	0.127	balanced_subsample
1019	1	KNN	SMOTETomek	True	entropy	17	4	2	0.664	balanced_subsample
1019	2	Simple	SMOTETomek	True	log_loss	21	3	3	0.295	None
1019	3	Simple	SMOTETomek	False	entropy	20	3	6	0.464	balanced
1021	1	KNN	SMOTETomek	True	gini	13	2	7	0.203	balanced
1021	2	Simple	SMOTETomek	False	gini	9	4	5	0.416	balanced
1021	3	KNN	SMOTE	False	entropy	14	4	9	0.568	balanced
1040	1	KNN	Tomek	True	log_loss	12	1	15	0.513	balanced
1040	2	KNN	SMOTE	True	log_loss	6	32	3	0.285	balanced_subsample
1040	3	Simple	None	True	log_loss	17	1	5	0.365	balanced_subsample
1053	1	KNN	Tomek	False	log_loss	8	10	16	0.590	balanced_subsample
1053	2	Simple	Tomek	True	gini	12	24	4	0.400	balanced
1053	3	KNN	Tomek	False	entropy	25	9	14	0.555	balanced
1461	1	Simple	None	False	entropy	11	5	16	0.628	balanced
1461	2	Simple	None	False	gini	9	10	1	0.390	balanced
1461	3	KNN	Tomek	False	entropy	15	8	15	0.765	balanced_subsample
41160	1	Simple	Tomek	False	log_loss	12	28	11	0.811	balanced
41160	2	Simple	Tomek	False	gini	10	3	5	0.379	balanced
41160	3	KNN	None	True	gini	12	5	9	0.851	balanced

Table 2: Incumbent hyperparameters configurations for the gradient boosting classifier

Dataset ID	CV fold	Imputer	Sampler	Scaler	Loss	Learning rate	Criterion	Min samples per split	Min samples per leaf	Max depth
976	1	Simple	SMOTE	False	exponential	0.603	squared_error	2	7	6
976	2	Simple	SMOTETomek	True	log_loss	0.522	squared_error	23	3	5
976	3	Simple	SMOTETomek	True	exponential	0.815	squared_error	5	3	3
980	1	Simple	SMOTE	True	log_loss	0.598	squared_error	7	4	4
980	2	KNN	SMOTETomek	True	log_loss	0.432	friedman_mse	9	7	3
980	3	Simple	SMOTETomek	True	exponential	0.322	squared_error	6	1	5
1002	1	KNN	SMOTETomek	True	log_loss	0.010	squared_error	3	7	2
1002	2	KNN	SMOTETomek	False	log_loss	0.013	squared_error	7	6	2
1002	3	KNN	SMOTE	True	exponential	0.021	friedman_mse	12	7	4
1018	1	KNN	SMOTETomek	True	log_loss	0.061	friedman_mse	6	1	3
1018	2	Simple	SMOTETomek	True	log_loss	0.185	squared_error	6	12	3
1018	3	KNN	SMOTE	True	exponential	0.054	friedman_mse	2	1	3
1019	1	Simple	SMOTE	True	exponential	0.398	squared_error	31	4	4
1019	2	Simple	SMOTETomek	True	log_loss	0.158	friedman_mse	7	1	3
1019	3	Simple	SMOTE	False	exponential	0.666	friedman_mse	5	6	4
1021	1	KNN	SMOTETomek	True	exponential	0.018	friedman_mse	7	6	5
1021	2	Simple	SMOTE	False	log_loss	0.034	squared_error	3	4	5
1021	3	KNN	SMOTETomek	True	log_loss	0.141	friedman_mse	7	3	6
1040	1	KNN	SMOTETomek	True	log_loss	0.048	friedman_mse	5	3	4
1040	2	Simple	SMOTE	False	exponential	0.588	friedman_mse	4	3	3
1040	3	Simple	SMOTE	False	log_loss	0.410	friedman_mse	20	7	3
1053	1	KNN	SMOTETomek	True	exponential	0.014	squared_error	15	1	3
1053	2	Simple	SMOTETomek	False	exponential	0.021	squared_error	7	3	3
1053	3	KNN	SMOTETomek	True	log_loss	0.270	squared_error	8	8	2
1461	1	KNN	SMOTETomek	False	exponential	0.092	squared_error	7	4	7
1461	2	KNN	SMOTETomek	False	log_loss	0.035	friedman_mse	4	7	5
1461	3	Simple	SMOTETomek	False	log_loss	0.111	friedman_mse	8	5	8
41160	1	Simple	SMOTE	False	log_loss	0.023	friedman_mse	16	2	11
41160	2	Simple	SMOTE	False	exponential	0.043	friedman_mse	30	2	9
41160	3	Simple	SMOTETomek	False	log_loss	0.058	squared_error	5	3	11

Table 3: Incumbent hyperparameters configurations for the SVM classifier

Dataset ID	CV fold	Imputer	Sampler	Scaler	C	Kernel	Shrinking	Tolerance	Class weight
976	1	KNN	SMOTETomek	True	8.489	rbf	True	0.0085	balanced
976	2	Simple	None	True	8.670	rbf	False	0.0016	balanced
976	3	Simple	None	True	4.036	rbf	False	0.0005	balanced
980	1	Simple	SMOTETomek	True	2.230	poly	False	0.0040	balanced
980	2	KNN	Tomek	True	0.893	poly	True	0.0030	balanced
980	3	KNN	None	False	1.061	rbf	True	0.0006	balanced
1002	1	KNN	SMOTETomek	True	0.161	linear	True	0.0017	balanced
1002	2	KNN	Tomek	True	0.199	linear	False	0.0003	balanced
1002	3	Simple	SMOTE	True	0.169	linear	False	0.0025	balanced
1018	1	Simple	SMOTETomek	True	0.213	sigmoid	True	0.0007	None
1018	2	Simple	Tomek	True	0.621	poly	True	0.0001	balanced
1018	3	KNN	SMOTETomek	True	0.113	linear	True	0.0039	balanced
1019	1	Simple	None	False	2.186	poly	True	0.0062	balanced
1019	2	Simple	SMOTETomek	False	6.871	rbf	True	0.0040	None
1019	3	Simple	Tomek	False	7.892	rbf	True	0.0003	balanced
1021	1	Simple	None	True	6.803	rbf	True	0.0058	balanced
1021	2	Simple	Tomek	True	7.117	rbf	True	0.0011	balanced
1021	3	Simple	Tomek	True	6.244	rbf	True	0.0005	balanced
1040	1	KNN	SMOTE	True	0.218	linear	True	0.0019	None
1040	2	KNN	SMOTETomek	True	0.143	linear	True	0.0001	balanced
1040	3	KNN	SMOTE	True	1.384	sigmoid	False	0.0012	balanced
1053	1	Simple	None	True	0.851	rbf	True	0.0009	balanced
1053	2	Simple	SMOTE	True	0.384	rbf	True	0.0009	balanced
1053	3	Simple	Tomek	True	0.900	rbf	False	0.0012	balanced
1461	1	Simple	None	True	0.363	sigmoid	False	0.0004	balanced
1461	2	KNN	Tomek	True	0.399	sigmoid	False	0.0004	balanced
1461	3	Simple	SMOTETomek	True	0.526	rbf	False	0.0003	balanced
41160	1	Simple	SMOTETomek	True	0.190	sigmoid	True	0.0002	balanced
41160	2	KNN	SMOTE	True	0.586	sigmoid	True	0.0007	balanced
41160	3	KNN	SMOTETomek	True	1.275	rbf	False	0.0037	None

C Information about datasets

Dataset ID	Observations	Features
976	9961	14
980	5620	64
1002	7485	55
1018	8844	56
1019	10992	16
1021	5473	10
1040	14395	108
1053	10885	21
1461	45221	16
41160	31406	22