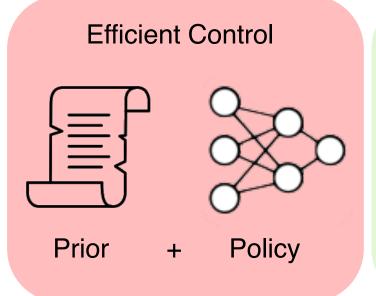
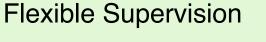
Task-relevant Autonomy Goal-cycles Multi-goal Multi-robot Auto-grasp







Detic

Dino

SAM

Text + Segment + Depth