Stress-Testing

Version 0.2

Executive Summary: This note proposes a scenario-based approach to stress-testing based on a modification of a pre-existing probability distribution of returns that incorporates expert encodings of possible scenarios.

1 Introduction

Models of asset returns are used by asset managers and banks to generate *ex ante* risk measures of their holdings. Based on these measures, asset managers make ongoing decisions of asset coverage, diversification, hedging, contingency insurance, drawdown management, portfolio construction, performance attribution and capital allocation. Given their intended application, risk models should perform well in times of high turbulence and around periods in which the risk regime changes abruptly; in times of low risk, or when the regime is stationary, accuracy is important, but not critical. However, oftentimes the opposite happens: risk models work well in "normal" times, when we need them the least, and in turbulent times they are inaccurate, to the point of being counterproductive. Among their shortcomings:

- They under-forecast volatility and VaR during a turbulent period, and overforecast it afterward. Portfolio managers over-deploy risk entering a crisis, and under-deploy after it is over, when they should re-risk aggressively.
- They attribute portfolio returns to factors that explain a small fraction of the portfolio's systematic risk.

The decisions affected by model inadequacy are:

- Leverage Ratios. Managers are overlevered coming into a financial crisis;
- *Capital Allocation*. Because of the large estimation error in risk metrics, capital and risk is misallocated among different strategies and asset classes;

• *Portfolio construction*. Prior to a crisis, certain factors are shown to drive portfolio risk and their exposure is reduced; e.g., size or momentum. During a crisis, a different set of factors is responsible for the losses. Hedging these factors on an ongoing basis may not be feasible because, in addition to driving only a small percentage of total risk, they are responsible for significant profits. An example is short interest.

One approach taken by practitioners to remedy the shortcomings of models of asset returns, factor-based or general ones, is that of *stress-testing* the model. The intuition is to change the inputs to the model beyond its normal operating regime in order to assess the sensitivity of the output – the risk metrics – on these inputs. Beyond this very broad definition, there is little agreement on the theory and practice how stress testing should be. In engineering, where the term originated over a century ago¹, stress-testing means to subject an actual physical system to unusual stimulus. In finance, we stress-test models. Abstractions of real phenomena are not easy to stress. This note is devoted to describing these different approaches, and to recommending best practices. The rest of this document is organized as follows. In the next section we describe the principles stress-testing framework. In the appendix we detail the mathematical formulation of the problem and review the literature.

2 Framework

Our approach to stress-testing rests on two principles, which are shared with all stress-testing alternatives. The first one is that the risk model contains useful information about the true distribution of returns, but is inaccurate and therefore needs to be modified. The second principle is that stress-testing is contingent on the specification of one or more scenarios. They can be based on history (thus generalizing historical stress-testing) but can also go beyond it, by incorporating contextual information and expert judgement. For example, the financial crisis of 2008 was preceded by multiple warning signs, some of which shared by other crises, some new: the softening of the residential real estate market; increase in interbank lending; increase in securitized product; the bankruptcy and forced takeover of one the five largest U.S. investment banks. These signs were not detectable in commercial equities risk models, but could

¹The first occurrence of the term "stress testing" dates back to 1904 in the magazine *Practical Engineer* and refers to material testing.

have been incorporated in a stress-testing model well in advance of the Sept. 2008 crash.

The two steps – stress-test of the model and scenario specification – are inter-dependent. The *inputs* to the process are the risk model, the core portfolio and the scenario. Regarding the first, we assume that the return process is multivariate normal and described by a covariance matrix². The core scenario is the set of our current holdings. Finally, we describe scenarios as a) a sets of portfolios, each of each of which as an associated return; b) a return horizon associated to the scenario; c) a *stress factor*, indicating the deviation from the input risk model. Portfolios allow for great generality. For example, a portfolio could include:

- 1. Sub-portfolios of the portfolio under consideration. For example, we want to investigate the impact of the energy portfolios on the aggregate portfolio;
- 2. Single assets. Is a large drawdown of a single asset a concern, or will its losses/gains be balanced by other highly correlated assets in the portfolio?
- 3. Factors. Factor returns can be expressed as factor-mimicking portfolios

Each portfolio has an associated return. For example, a scenario could consist of the following: "the energy portfolios in my overall portfolios will experience a 3% drawdown over the next month, and the crowding factor will lose 1.5% in the same period.

The *output* of the model is an updated risk model, from which all statistics of interest can be computed. The VaR and expected return of the core portfolios are among the most important, but others could be of interest. For example, we could report the VaR of the sub-portfolios and highlight those that are more vulnerable to losses under a given scenario.

The processing steps are:

1. Compute the conditional distribution of returns under the input risk model and the scenario. The scenario returns affect the returns of the entire asset universe since those are in general dependent.

²The model is extensible to elliptical distributions, but in many applications this generalization should not be needed, since conditional returns are well approximated as normally distributed.

2. Stress the input risk model. The conditional distribution is a function of the input risk model. We allow for deviation from the risk model, and the criteria for this deviation is that a) the distance from the stressed risk model and the input risk model is measured as the relative entropy of the former with respect to the latter and is bounded above by the input stress factor; b) the deviation is in the direction of maximizing the loss of the core portfolio.

The choice of relative entropy is a natural one to measure distance among probability distributions. Some standard references are Aczél *et al.*[AFN74], Csiszár [Csi91, Csi08] and, in Bayesian Statistics, the foundational work of Jaynes [Jai03]. In the context of stress testing, these constraints have been employed by Breuer and Csiszár [BC13, BC16] and Meucci [Meu08].

3 Appendix

3.1 Previous Work and Common Approaches

There is no agreed-upon interpretation of stress-testing in the literature, and the published papers on the subject are few. The most relevant implementation of stress-testing arises from regulations developed in the aftermath of the financial crisis of 2008. Section 164(i)(2) of the Frank-Dodd Act requires that banks with assets over \$10Bn meet stress tests (Dodd-Frank Act Stress Test, or DFAST [Com13]) specified every year by the Deposit Insurance Corporation. In addition, The Federal Reserve of New York requires that banks with assets over \$50Bn meet additional stress tests (Comprehensive Capital Analysis and Review, or CCAR [Boa17, Boa18]). All tests have the objective of determining the viability (capital adequacy and risk management practices) of these lending institutions in regimes of heightened financial and economic stress. The approach is conceptually straightforward: regulators specify only three scenarios: baseline, adverse, and severely adverse, through the release of quarterly data of macroeconomic indicators (Table 1)

It is up to the firms to a) specify the causal model relating asset prices to macroeconomic indicators; b) run the scenarios in this model; c) show good calibration properties under the baseline scenario, and adequacy under the adverse scenarios. The core of the exercise is the first part: model building. In this respect, the term "stress-testing" is almost a misnomer. The main challenge faced by bank risk groups is to persuade the regulators that their models are

credible. The situation faced by an asset manager differs in two important respects. First, we already have a risk model; however, we have reason to believe that the model produces inaccurate forecasts in times of stress. Secondly, our scenarios have higher resolutions than "baseline/adverse/severely adverse", and are greater in number. For example: would happen if the portfolio of manager x lost 10%? Obviously there are correlations between this portfolio and other portfolios in the same firm, so considering the portfolio in isolation underestimating risk; while assuming a 10% loss across all portfolios severely overestimate it. What if just the energy Explorers and Producers have a large drawdown? What if simply their correlations with midstream and energy services increases? In other words, we need a *flexible and intuitive* language to express our hypothesis on what could go wrong.

Let us review the extant literature specifically devoted to stress testing. Auer [Aue18] devotes two pages to stress testing, in which he views the practice as propagating negative scenarios in the portfolio, possibly via non-linear instruments. Andersen *et al.*[ABCD13] as well as Stulz [Stu08] emphasize the importance of *conditional* measures of extreme risk, as opposed to unconditional ones, based on Daníelsson *et al.*[DJVZ16] propose to estimate model risk as the range of forecasts and risk metrics generated by the set of available models. For example, if different GARCH-based models generate VaR estimates that differ by 50%, a measure of the error of the VaR of the baseline model is 50%. Becker and Schmidt [BS13] propose an endogenous stress model, in which factor volatilities and correlations are increasing function of the market state, proxied by drawdown of market indices during a rolling time window. So *et al.*[SWA13], following [RJ00], propose a numerical procedure to change the correlation matrix while maintaining positive-definiteness. Meucci [Meu08] proposes to change the change the model probability distribution in order to meet some constraints.

The approaches share one feature. They can all involve changing the probability distribution of the reference model. The mechanism inducing the change differs, and can be divided in two camps. In the first one [Com13, Boa17, Boa18, Meu08], the user specifies scenarios (or views), and then modifies the model accordingly. A simple example would be that of an asset with daily volatility of 1.5% and zero expected return. Its model-based 1% VaR is -3.5%. If we require that, under an adverse scenario the 1% VaR be -10%, then, assuming that the asset is still normally distributed, it must have a volatility of 4.3%. This volatility, together with that of other assets will be the used to estimate the stress-tested

risk metric of a portfolio³.

In the second approach [DJVZ16, SWA13, RJ00], the user changes some parameters of the model family, and checks the impact on the portfolio. To stick to our previous example, this means that we directly increase the volatility of the asset to 5% and then check the impact on the portfolio.

In the next section we propose an approach that general enough to accommodate both approaches.

4 Appendix: Conditional Expectation for Multivariate Gaussians

Let ξ a random vector distributed according to a multivariate Normal with mean $\mu_{\xi} \in \mathbb{R}^n$ and variance $\Sigma_{\xi} \in \mathbb{R}^{n \times n}$. Partition the vector ξ in two sub-vectors $x \in \mathbb{R}^m$, $y \in \mathbb{R}^{n-m}$. Notation:

$$\xi := \begin{pmatrix} x \\ y \end{pmatrix} \qquad \qquad \mu_{\xi} := \begin{pmatrix} \mu_{x} \\ \mu_{y} \end{pmatrix} \Sigma_{\xi} := \begin{pmatrix} \Sigma_{xx} & \Sigma_{xy} \\ \Sigma_{yx} & \Sigma_{yy} \end{pmatrix}$$

We observe a realization of x, $\tilde{x} \in \mathbb{R}^m$. The conditional distribution of y given x is still Normal, with

$$\tilde{\mu}_{y} = \mu_{y} + \Sigma_{yx} \Sigma_{xx}^{-1} (\tilde{x} - \mu_{x})$$

$$\tilde{\Sigma}_{yy} = \Sigma_{yy} - \Sigma_{yx} \Sigma_{xx}^{-1} \Sigma_{xy}$$
(1)

We generalize the approach as follows: let $A \in \mathbb{R}^{n \times p}$ and $b \in \mathbb{R}^p$. We find the distribution of ξ conditional on the constraint

$$A^{\mathsf{T}}\xi = b$$

The proof is algebraically involved but its strategy is simple: first, perform a variable transformation such that we can use Eqs. (1). Then transform the variables back into the original problem.

³A naïve scenario-based analysis is also a change of probability distribution; we assign p=1 to the scenario.

First of all, we can assume, without loss of generality, the matrix A satisfies $A^{\mathsf{T}}A = I^4$.

- 1. Complete the columns of A to make an orthonormal basis in \mathbb{R}^n . The matrix B is such that its columns are the additional basis vectors. Therefore $H := (A|B) \in \mathbb{R}^{n \times n}$ is an orthonormal matrix⁵.
- 2. Let $\zeta := H^{\mathsf{T}} \xi$. As we did with ξ , partition ζ into two vectors: $u \in \mathbb{R}^m$ and $v \in \mathbb{R}^{n-m}$. From the definition, it is $u = A^{\mathsf{T}} \xi$ and $v = B^{\mathsf{T}} \xi$. Under this change of coordinates, the constraint $A^{\mathsf{T}} \xi = b$ becomes u = b.
- 3. Since ξ is multivariate Gaussian, $\zeta \sim N(H^{\mathsf{T}}\mu_{\xi}, H^{\mathsf{T}}\Sigma_{\xi}H)$. Use for mean and variance of ζ the same notation used for ξ : μ_{u}, μ_{v} , and so on.
- 4. Use the standard conditioning formulas, Eqn. (1), to find the conditional distribution. $v \sim N(\tilde{\mu}_u, \tilde{\Sigma}_{uu})$, with

$$\tilde{\mu}_{v} = \mu_{v} + \Sigma_{vu} \Sigma_{uu}^{-1} (b - \mu_{u})$$

$$\tilde{\Sigma}_{vv} = \Sigma_{vv} - \Sigma_{vu} \Sigma_{uu}^{-1} \Sigma_{uv}$$

5. Transform back to $\xi = H\zeta$. The conditional distribution of ξ has mean and variance

$$\begin{split} \tilde{\mu}_{\xi} &= H \begin{pmatrix} b \\ \tilde{\mu}_{\nu} \end{pmatrix} = Ab + B\tilde{\mu}_{\nu} \\ \tilde{\Sigma}_{\xi} &= H \begin{pmatrix} 0 & 0 \\ 0 & \tilde{\Sigma}_{\nu\nu} \end{pmatrix} H^{\mathsf{T}} = B\tilde{\Sigma}_{\nu\nu}B^{\mathsf{T}} \end{split}$$

$$\boldsymbol{A}^\mathsf{T}\boldsymbol{\xi} = \boldsymbol{b} \Leftrightarrow \boldsymbol{V}\boldsymbol{\Lambda}^\mathsf{T}\boldsymbol{U}^\mathsf{T}\boldsymbol{\xi} = \boldsymbol{b} \Leftrightarrow \boldsymbol{\Lambda}^\mathsf{T}\boldsymbol{U}^\mathsf{T}\boldsymbol{\xi} = \boldsymbol{V}\boldsymbol{b} \Leftrightarrow \boldsymbol{U}[1:n,1:m]^\mathsf{T}\boldsymbol{\xi} = (\boldsymbol{\Lambda}[1:m,1:m])^{-1}\boldsymbol{V}\boldsymbol{b}$$

⁵The columns b_i of B are the eigenvectors of the null space of A^T : $A^Tb_i = 0$. They correspond to the m+1,...,n columns of V in the Singular Value Decomposition of A.

⁴If not, write the SVD of $A = U\Lambda V^{\mathsf{T}}$, with $U \in \mathbb{R}^{n \times n}$, $\Lambda \in \mathbb{R}^{n \times m}$, $V \in \mathbb{R}^{m \times m}$. The matrices U and V are unitary; $\Lambda[1:m,1:m]$ is diagonal and positive definite, and $\Lambda[(m+1):n,1:m]$ is identically zero.

This concludes the proof. However, if we want compact and explicit formulas for $\tilde{\mu}_{\xi}$ and $\tilde{\Sigma}_{\xi}$, then we have to suffer through the algebra.

$$\mu_{u} = A^{\mathsf{T}} \mu_{\xi}$$

$$\mu_{v} = B^{\mathsf{T}} \mu_{\xi}$$

$$\Sigma_{uu} = A^{\mathsf{T}} \Sigma_{\xi} A$$

$$\Sigma_{uv} = A^{\mathsf{T}} \Sigma_{\xi} B$$

$$\Sigma_{vu} = B^{\mathsf{T}} \Sigma_{\xi} A$$

$$\Sigma_{vv} = B^{\mathsf{T}} \Sigma_{\xi} B$$

From which

$$\begin{split} \tilde{\mu}_{v} &= \mu_{v} + \Sigma_{vu} \Sigma_{uu}^{-1} (b - \mu_{u}) \\ \tilde{\Sigma}_{vv} &= \Sigma_{vv} - \Sigma_{vu} \Sigma_{uu}^{-1} \Sigma_{uv} \\ \Rightarrow \tilde{\mu}_{v} &= B^{\mathsf{T}} \mu_{\xi} + B^{\mathsf{T}} \Sigma_{\xi} A (A^{\mathsf{T}} \Sigma_{\xi} A)^{-1} (b - A^{\mathsf{T}} \mu_{\xi}) \\ \tilde{\Sigma}_{vv} &= B^{\mathsf{T}} \Sigma_{\xi} B - B^{\mathsf{T}} \Sigma_{\xi} A (A^{\mathsf{T}} \Sigma_{\xi} A)^{-1} A^{\mathsf{T}} \Sigma_{\xi} B \end{split}$$

So that at last

$$\begin{split} \tilde{\mu}_{\xi} &= Ab + B\tilde{\mu}_{\nu} \\ \tilde{\Sigma}_{\xi} &= B\tilde{\Sigma}_{\nu\nu}B^{\mathsf{T}} \\ \Rightarrow \tilde{\mu}_{\xi} &= Ab + B(B^{\mathsf{T}}\mu_{\xi} + B^{\mathsf{T}}\Sigma_{\xi}A(A^{\mathsf{T}}\Sigma_{\xi}A)^{-1}(b - A^{\mathsf{T}}\mu_{\xi})) \\ &\simeq Ab + \mu_{\xi} + \Sigma_{\xi}A(A^{\mathsf{T}}\Sigma_{\xi}A)^{-1}(b - A^{\mathsf{T}}\mu_{\xi}) \\ \tilde{\Sigma}_{\xi} &= B(B^{\mathsf{T}}\Sigma_{\xi}B - B^{\mathsf{T}}\Sigma_{\xi}A(A^{\mathsf{T}}\Sigma_{\xi}A)^{-1}A^{\mathsf{T}}\Sigma_{\xi}B)B^{\mathsf{T}} \\ &\simeq \Sigma_{\xi} - \Sigma_{\xi}A(A^{\mathsf{T}}\Sigma_{\xi}A)^{-1}A^{\mathsf{T}}\Sigma_{\xi} \end{split}$$

where we have employed the property $BB^{\mathsf{T}} \simeq I$.

The special case where $\mu_{\xi} = 0$ and we are interested in $w^{\mathsf{T}}\xi$ is relevant to our application.

$$w^{\mathsf{T}} \tilde{\mu}_{\xi} = w^{\mathsf{T}} [Ab + \Sigma_{\xi} A (A^{\mathsf{T}} \Sigma_{\xi} A)^{-1}] b$$
$$w^{\mathsf{T}} \tilde{\Sigma}_{\xi} w = w^{\mathsf{T}} [\Sigma_{\xi} - \Sigma_{\xi} A (A^{\mathsf{T}} \Sigma_{\xi} A)^{-1} A^{\mathsf{T}} \Sigma_{\xi}] w$$

The expected return is proportional to b, the scenarios returns.

4.1 Conditioning Factor Returns

The case in which we condition the system based on knowledge of specific factor returns is easy. We use Eq. 1 and a factor model. The model is based on three inputs: the loadings matrix $X \in \mathbb{R}^{n \times m}$, the factor covariance matrix $\Omega \in \mathbb{R}^{m \times m}$ and the idiosycratic diagonal variance matrix $D \in \mathbb{R}^{n \times n}$. The asset covariance matrix is $X\Omega X^T + D$. Assume that the factor returns have zero expected value, a simplifying assumption that is reasonable in practice. We assume that a set of factors is stressed and experiences returns $\tilde{\mu}_x$. The conditional returns of the remaining factors, y, is still normally distributed. Using Eq. 1 we obtain

$$\begin{split} \tilde{\mu}_y = & \Sigma_{yx} \Sigma_{xx}^{-1} \tilde{\mu}_x \\ \tilde{\Sigma}_{yy} = & \Sigma_{yy} - \Sigma_{yx} \Sigma_{xx}^{-1} \Sigma_{xy} \end{split}$$

So that the conditional return and asset covariance matrix is

$$\tilde{\mu}_{\xi} = X \begin{pmatrix} \tilde{\mu}_{x} \\ \tilde{\mu}_{y} \end{pmatrix}$$

$$\tilde{\Sigma}_{\xi} = X_{y} \tilde{\Sigma}_{yy} X_{y}^{\mathsf{T}} + D$$

4.2 The optimization setting

The objective function is the VaR(p) of the PnL portfolio conditional of the scenario returns. This is a weighted sum of the mean and standard deviation:

$$w^{\mathsf{T}}[A + \Sigma_{\xi} A (A^{\mathsf{T}} \Sigma_{\xi} A)^{-1}]b - k_{1}(w^{\mathsf{T}}[\Sigma_{\xi} - \Sigma_{\xi} A (A^{\mathsf{T}} \Sigma_{\xi} A)^{-1} A^{\mathsf{T}} \Sigma_{\xi}]w)^{1/2}$$

We minimize the objective function, by adding a a constraint (or a penalty) on the KL distance of the covariance matrix from the model matrix:

$$\min w^{\mathsf{T}} [A + XA(A^{\mathsf{T}}XA)^{-1}]b$$

$$-k_1(w^{\mathsf{T}} [X - XA(A^{\mathsf{T}}XA)^{-1}A^{\mathsf{T}}X]w)^{1/2}$$

$$+k_2[\operatorname{tr}(\Sigma_{\xi}X^{-1}) - n - \log(|\Sigma_{\xi}X^{-1}|)]$$
s.t. $X > 0$

We decompose

$$\Sigma_{\xi} = U \Lambda_0 U^{\mathsf{T}} \qquad X = U \Lambda U^{\mathsf{T}}$$

The third term simplifies to

$$\sum_{i} \left(\frac{\lambda_{0i}}{\lambda_{i}} - 1 - \log \frac{\lambda_{0i}}{\lambda_{i}} \right)$$

The problem takes an simplified form when A is a column vector. Then, let $k_0 = w^T A b$, $v_1 = U^T A$, $v_2 = U^T w$.

$$\min k_0 + \frac{v_2 \Lambda v_1}{v_1^{\mathsf{T}} \Lambda v_1} b$$

$$- k_1 \left[\frac{(v_1^{\mathsf{T}} \Lambda v_1)(v_2^{\mathsf{T}} \Lambda v_2) - (v_2^{\mathsf{T}} \Lambda v_1)^2}{v_1^{\mathsf{T}} \Lambda v_1} \right]^{1/2}$$

$$+ k_2 \sum_i \left(\frac{\lambda_{0i}}{\lambda_i} - 1 - \log \frac{\lambda_{0i}}{\lambda_i} \right)$$
s.t. $\lambda_i \ge 0$

Finally, we consider a simplified version of this problem. Rather than stress testing the distribution of the conditional PnL (to maximize the VaR), we consider first stress testing the unconditional of the unconditional PnL. After this step, we compute the conditional distribution. The optimization problem becomes

$$\max(w^{\mathsf{T}} X w)^{1/2} - k[\operatorname{tr}(\Sigma_{\xi} X^{-1}) - n - \log(|\Sigma_{\xi} X^{-1}|)]$$

s.t. $X > 0$

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Table 1: Macroeconomic indicators used to define scenarios of the Dodd-Frank Act Stress Test.

U.S. real GDP growth

U.S. nominal GDP growth

U.S. real disposable income growth

U.S. nominal disposable income growth

U.S. unemployment rate

U.S. CPI inflation

U.S. 3-month Treasury rate

U.S. 5-year Treasury yield

U.S. 10-year Treasury yield

U.S. BBB corporate yield

U.S. mortgage rate

U.S. prime rate

U.S. Dow Jones Total Stock Market Index

U.S. House Price Index

U.S. Commercial Real Estate Price Index

U.S. Market Volatility Index (VIX)

Euro area real GDP growth

Euro area inflation

Developing Asia real GDP growth

Developing Asia inflation

Japan real GDP growth

Japan inflation

U.K. real GDP growth

U.K. inflation

Exchange rates