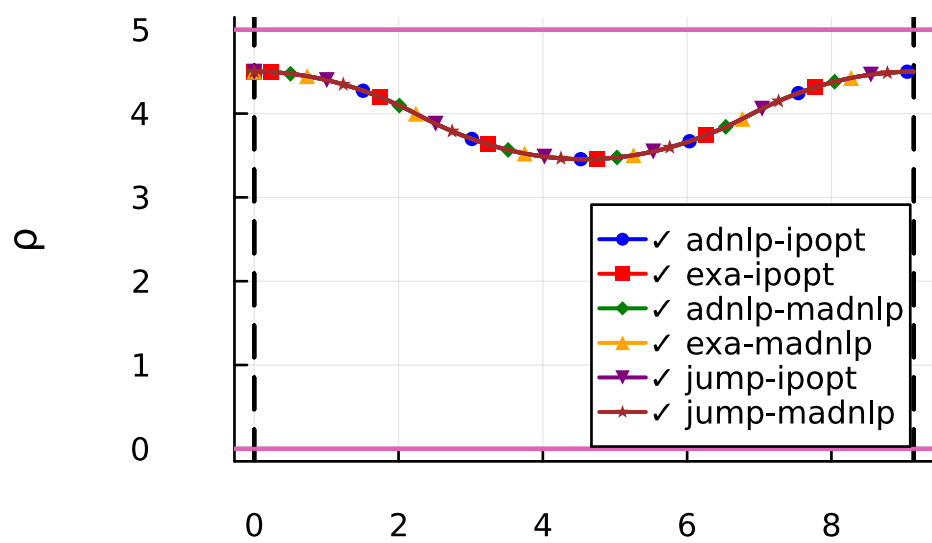
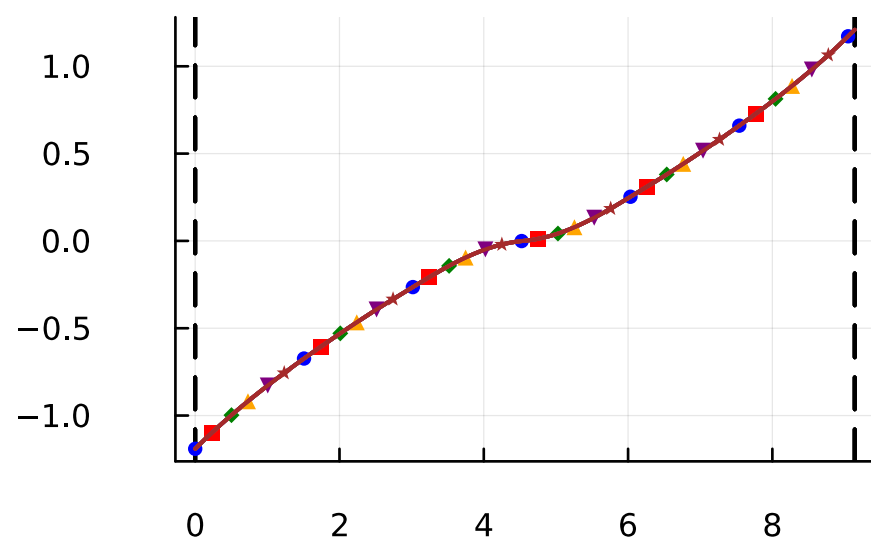
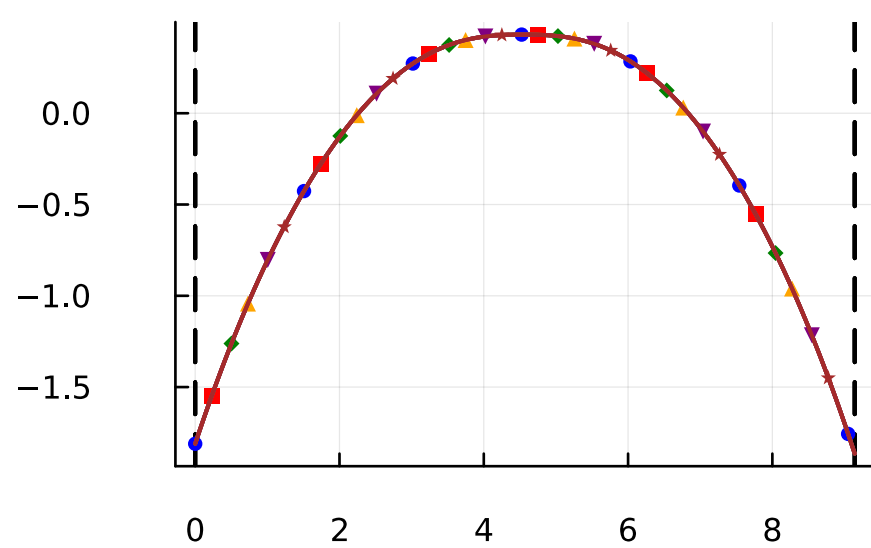
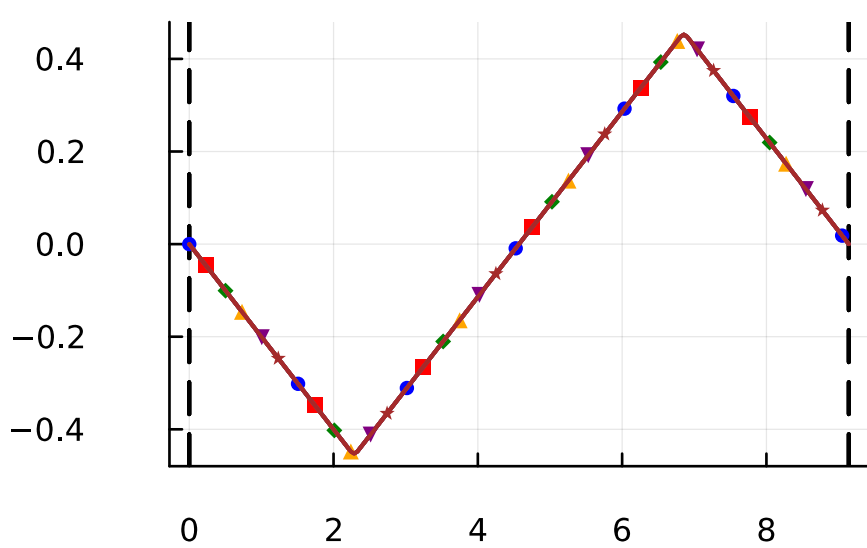
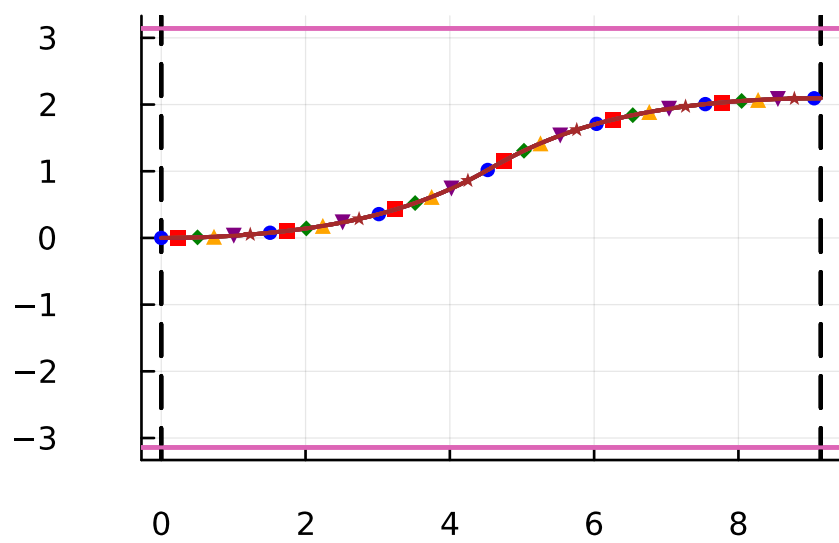


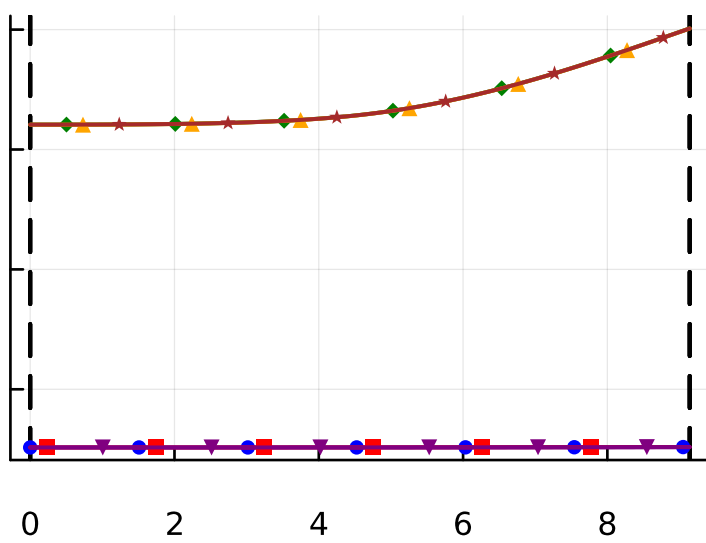
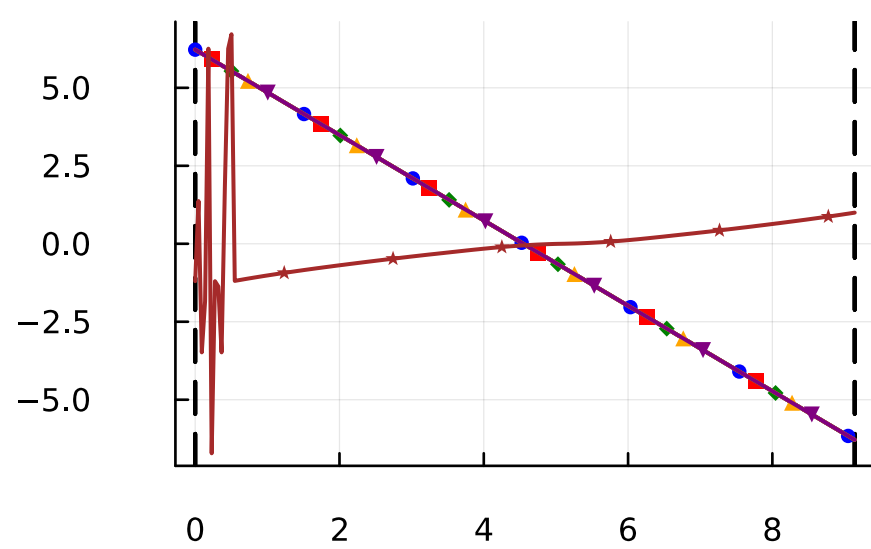
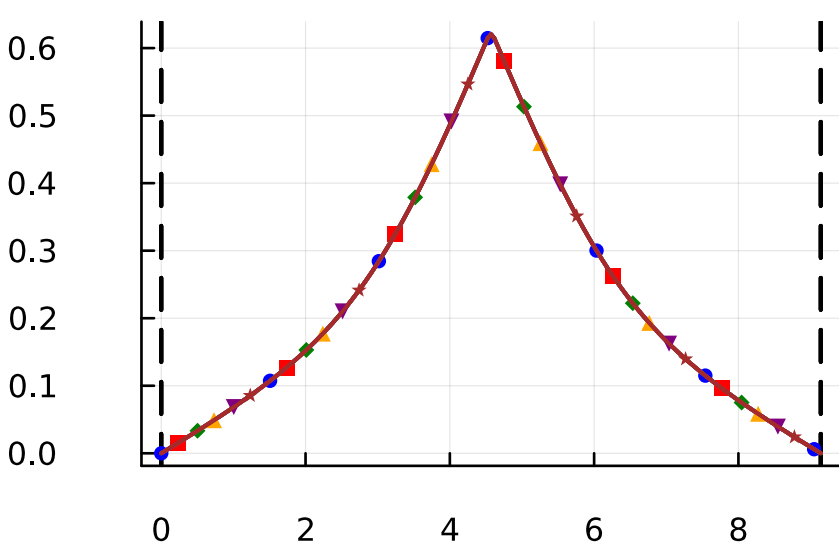
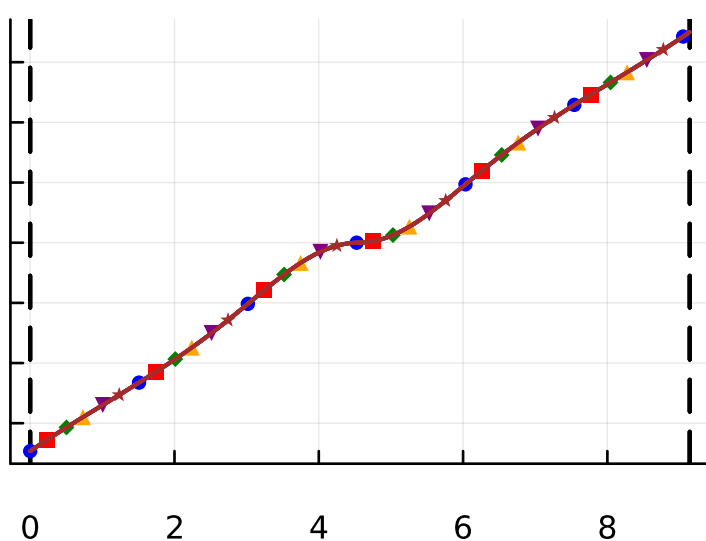
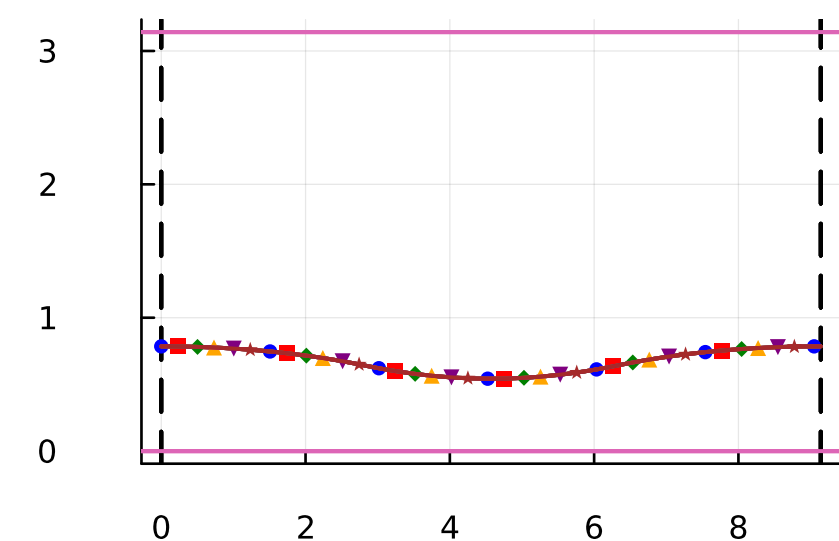
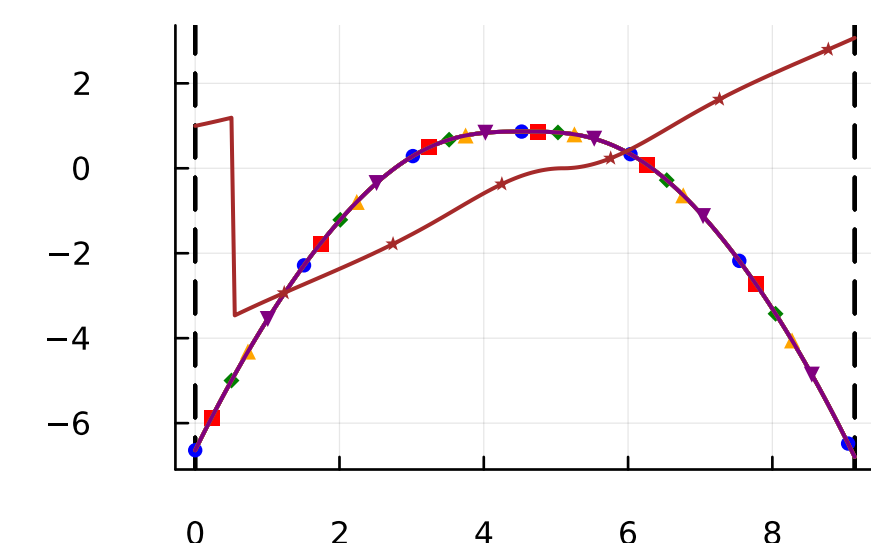
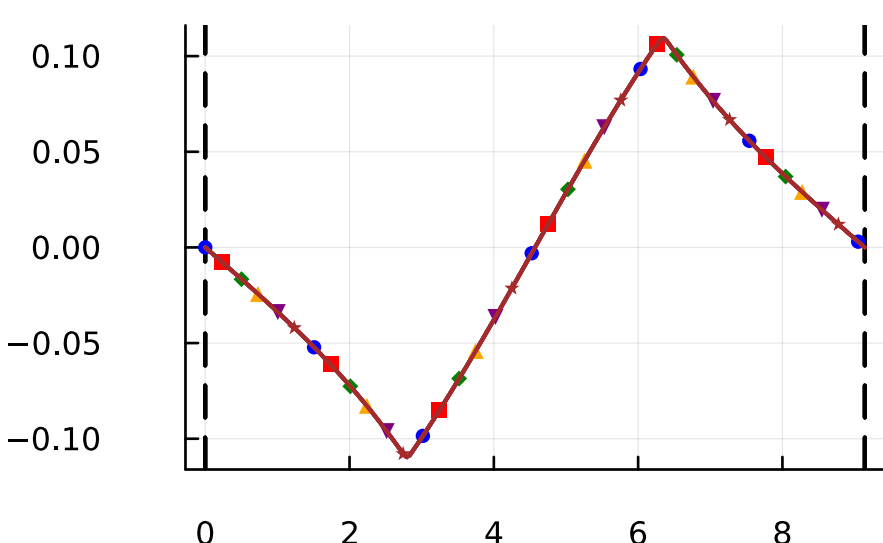
state



costate

 $d\rho$  θ 

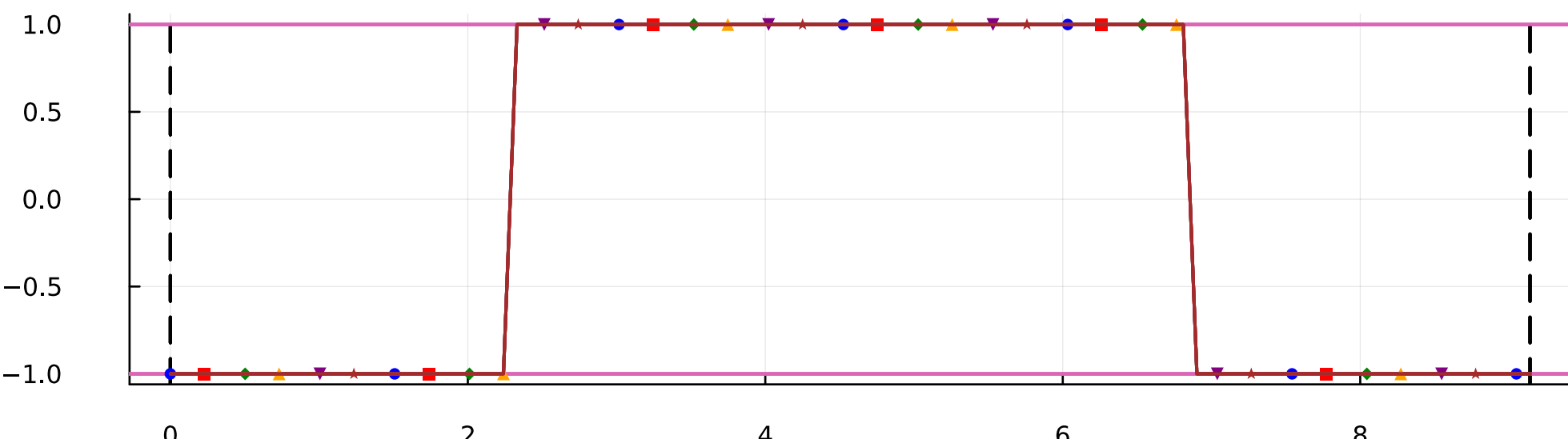
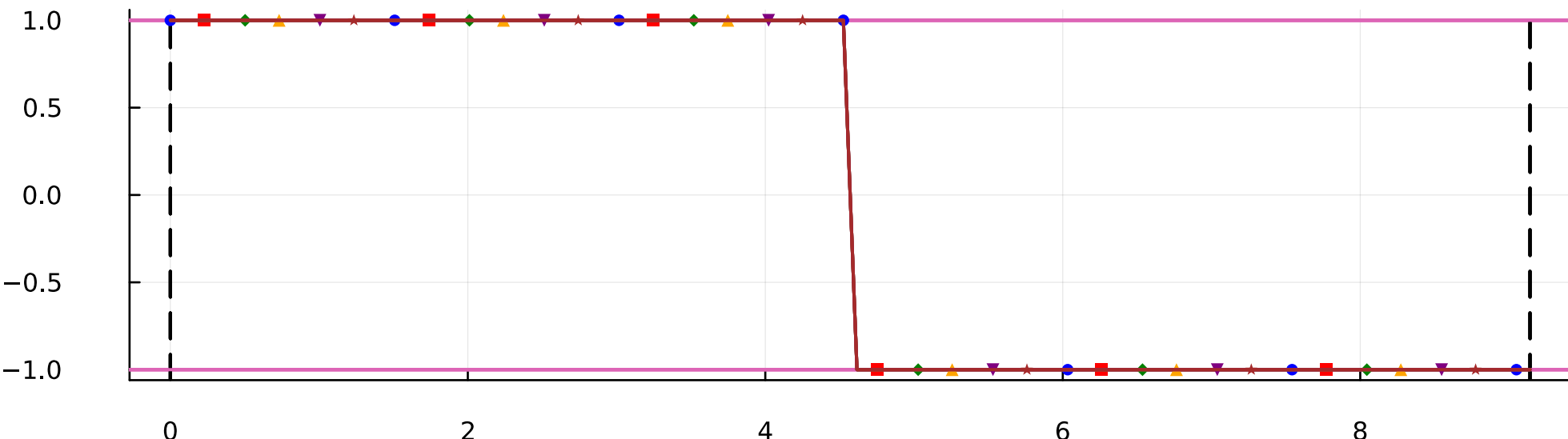
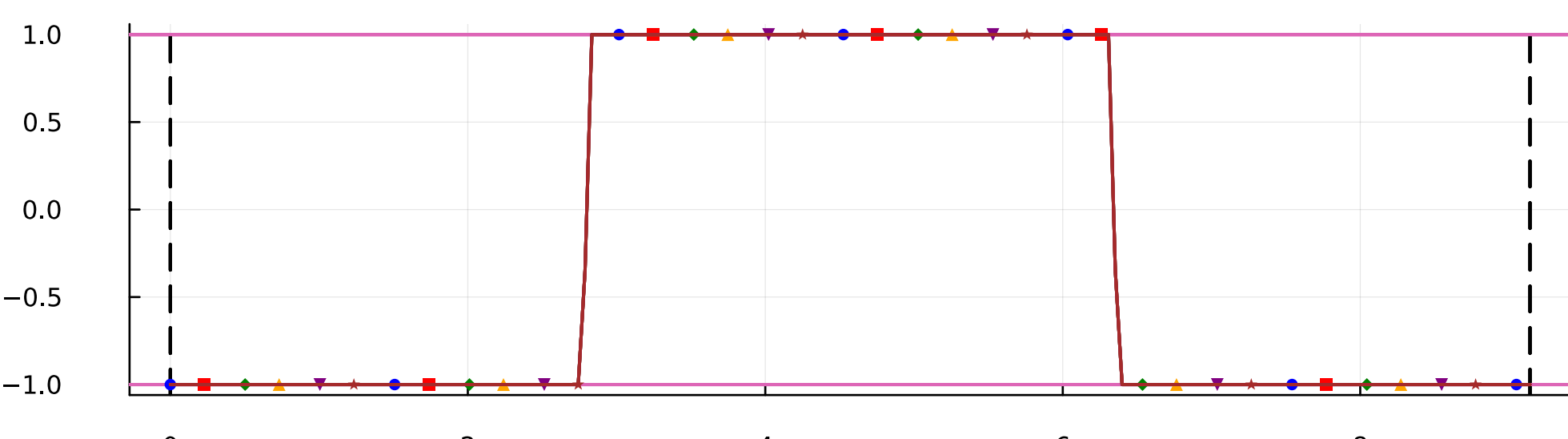
1.36847960×10^0
 1.36847940×10^0
 1.36847920×10^0
 1.36847900×10^0

 $d\theta$  ϕ  $d\phi$ 

t

t

control

 $u\rho$  $u\theta$  $u\phi$ 

t