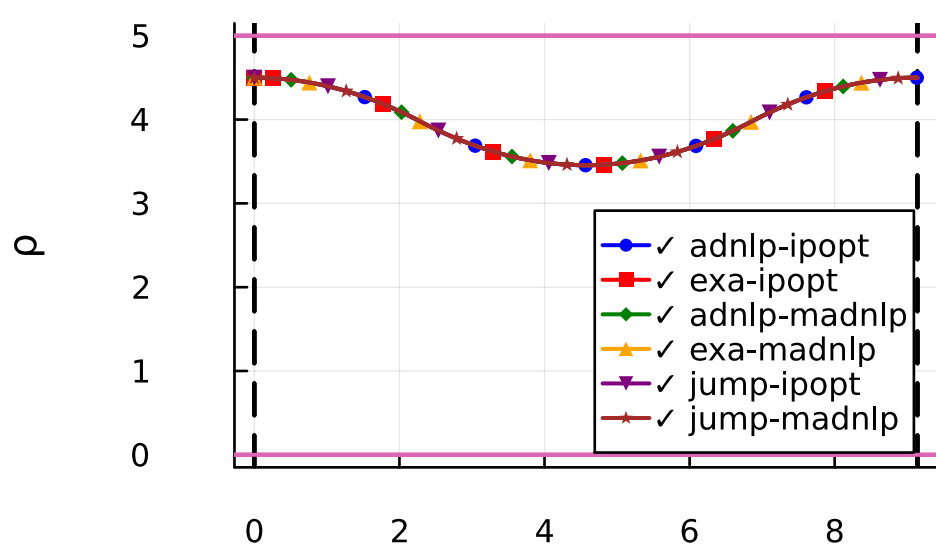
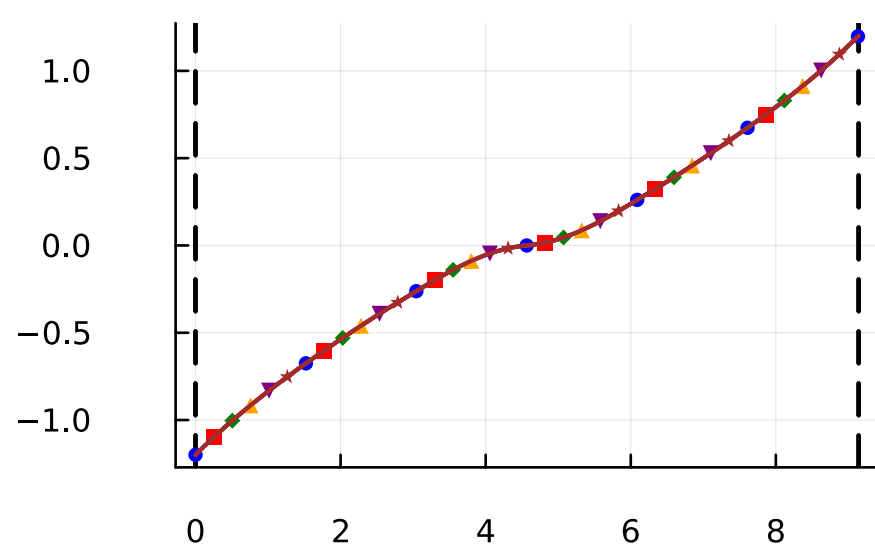
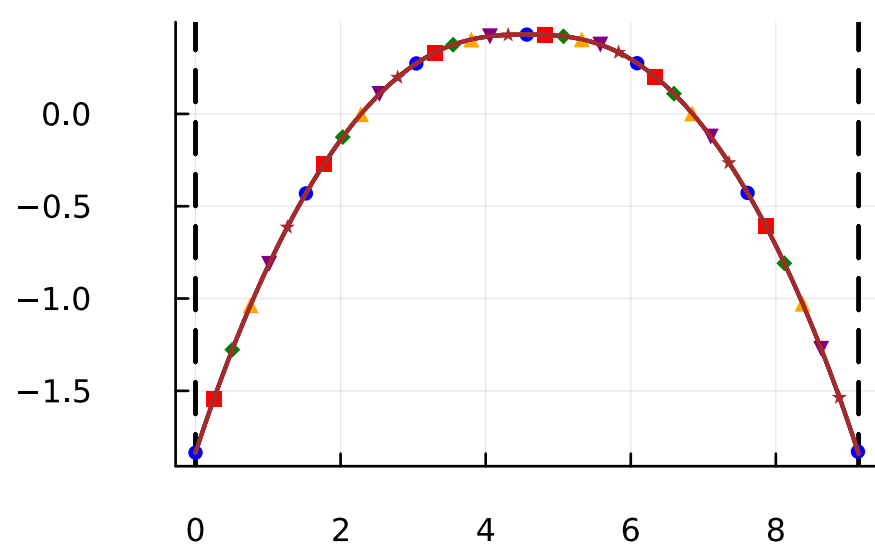
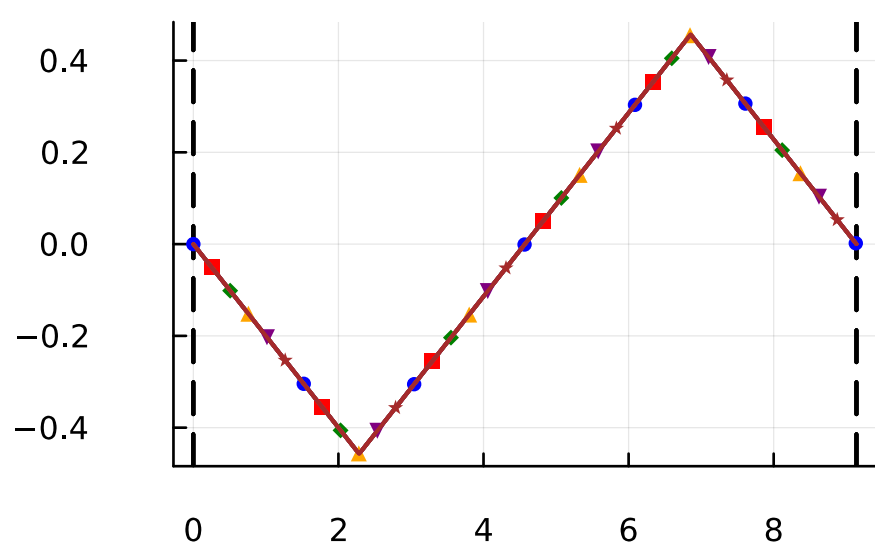
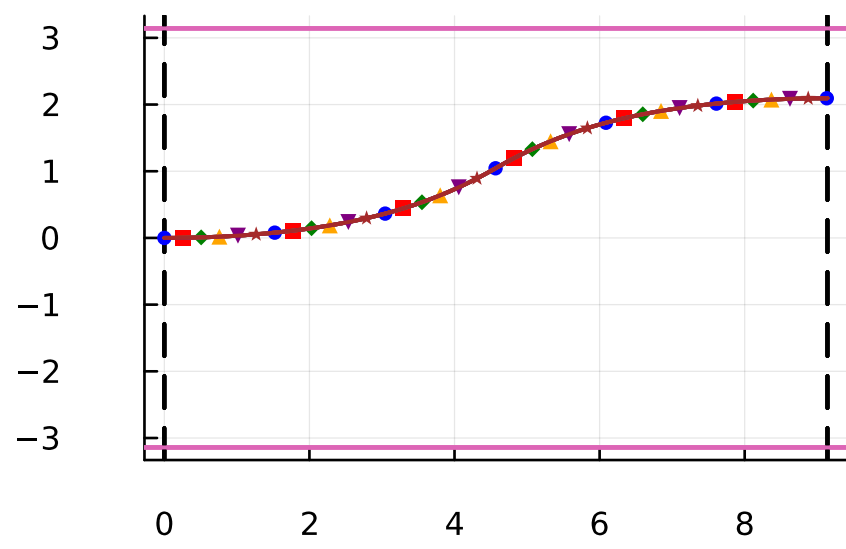


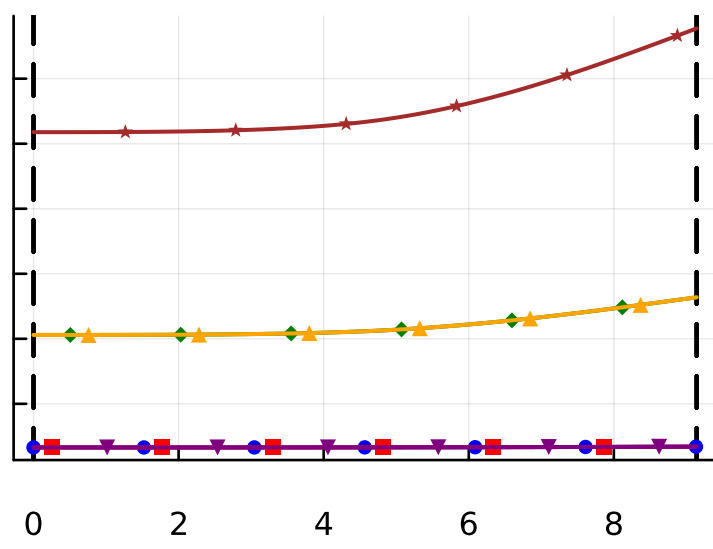
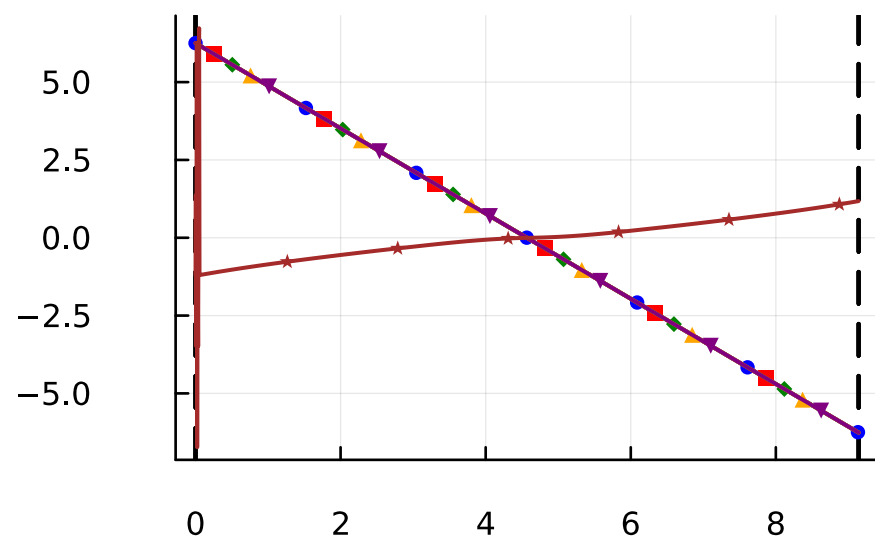
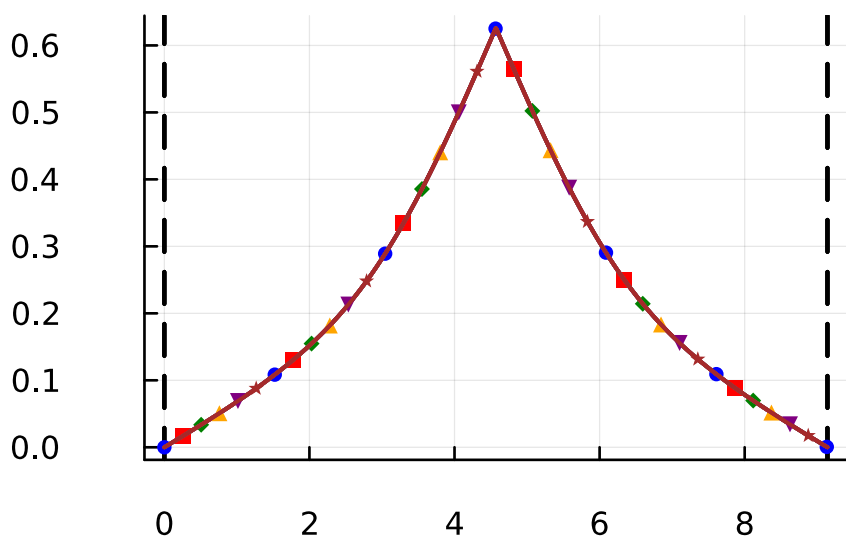
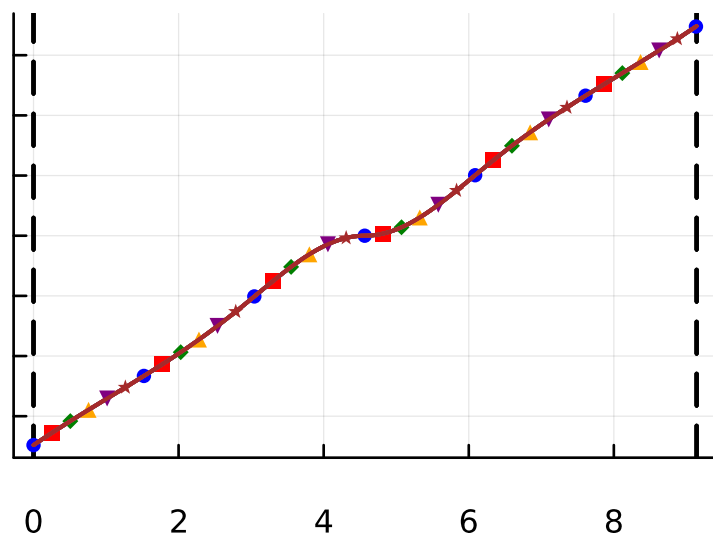
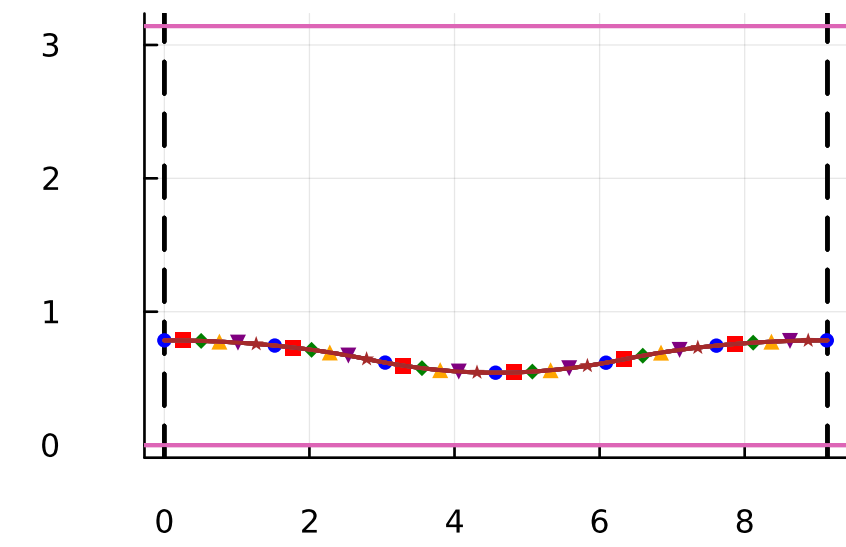
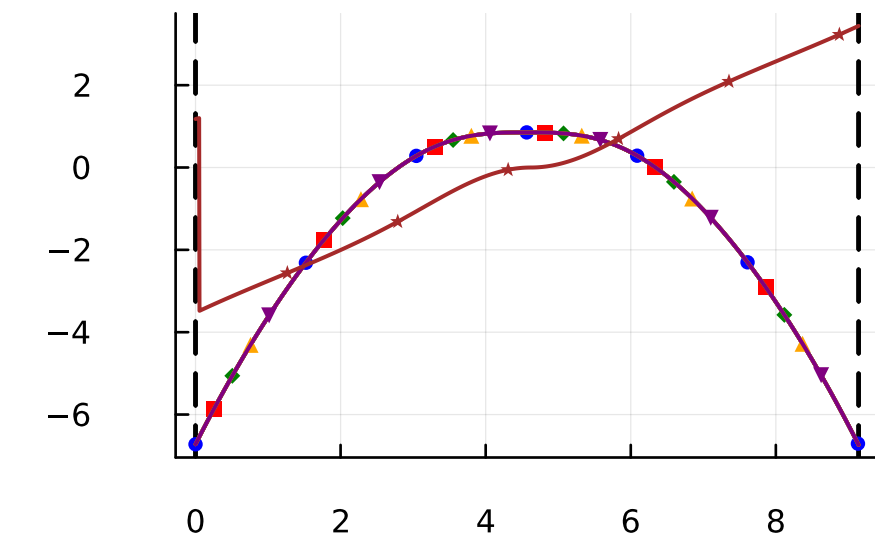
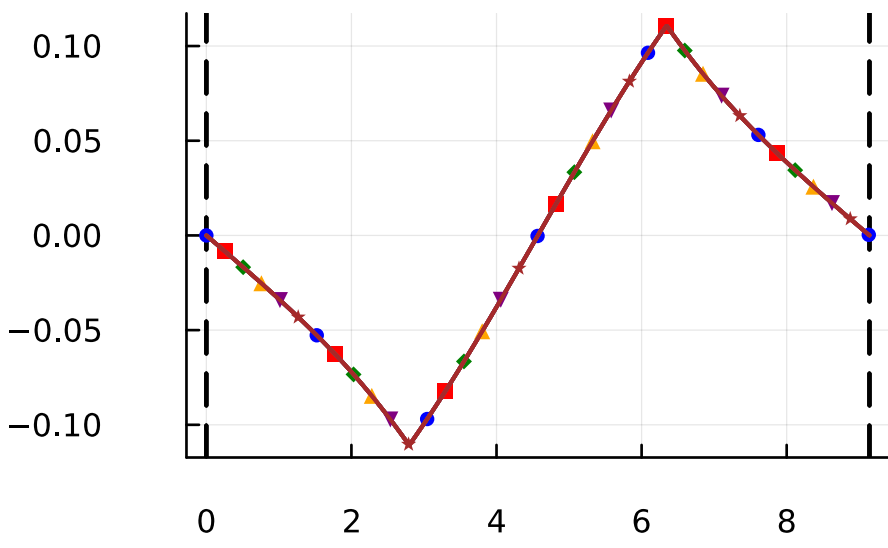
state



costate

 $d\rho$  θ 

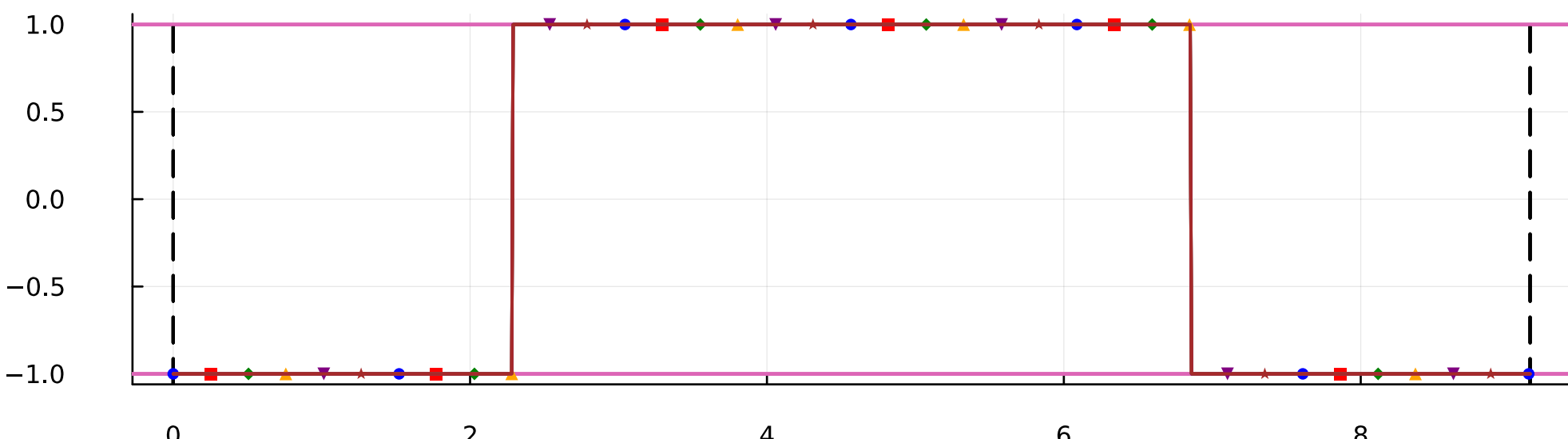
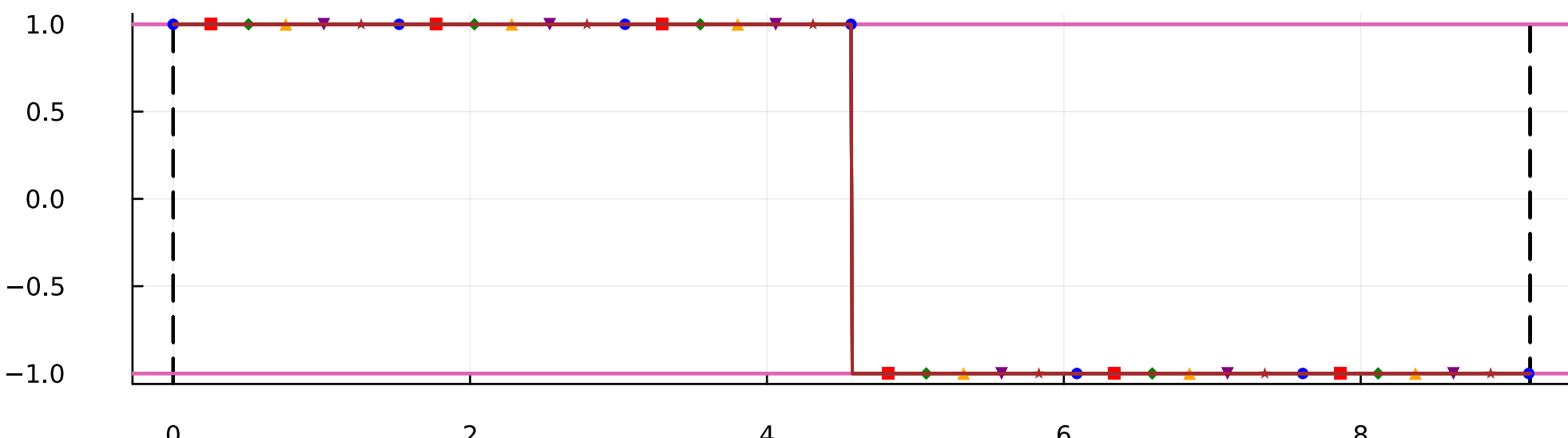
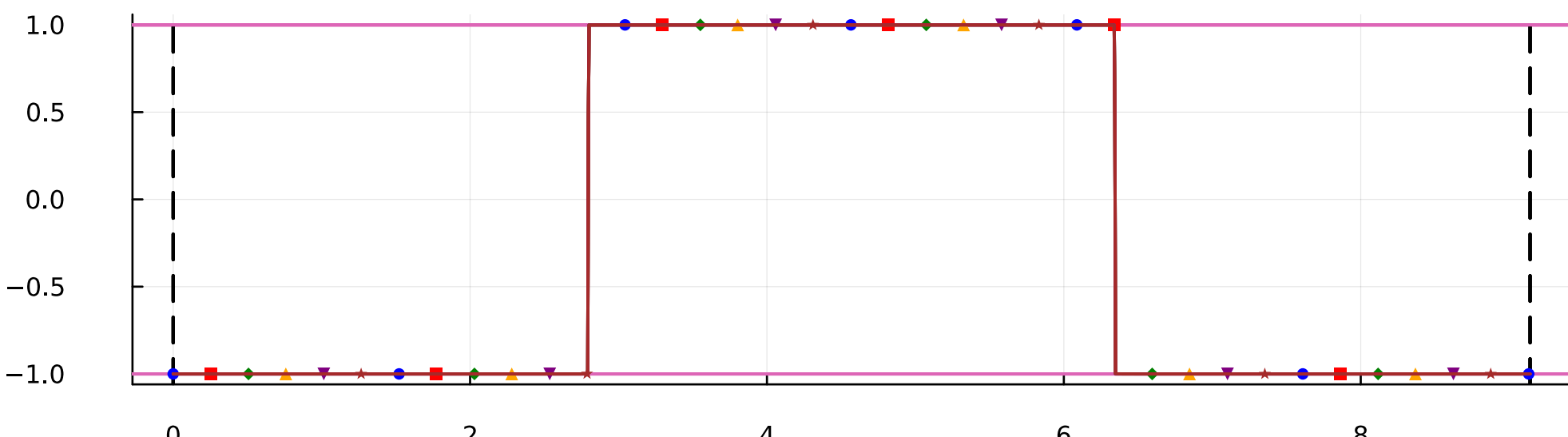
1.3686260×10^0
 1.3686250×10^0
 1.3686240×10^0
 1.3686230×10^0
 1.3686220×10^0
 1.3686210×10^0

 $d\theta$  ϕ  $d\phi$ 

t

t

control

 $u\rho$  $u\theta$  $u\phi$ 

t