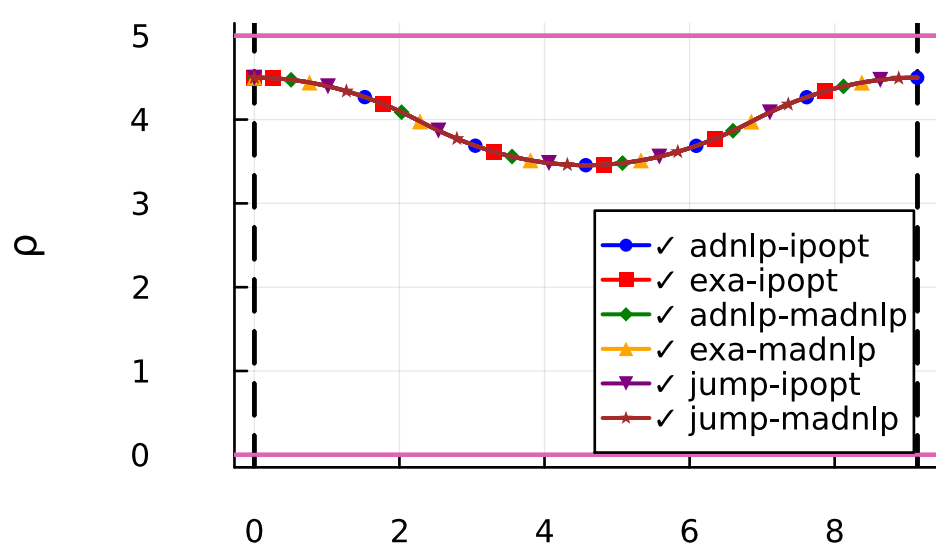
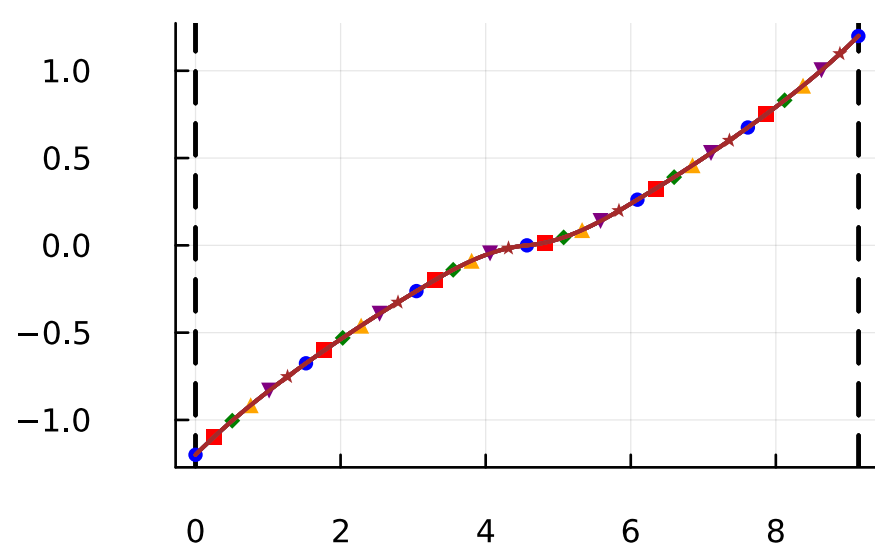
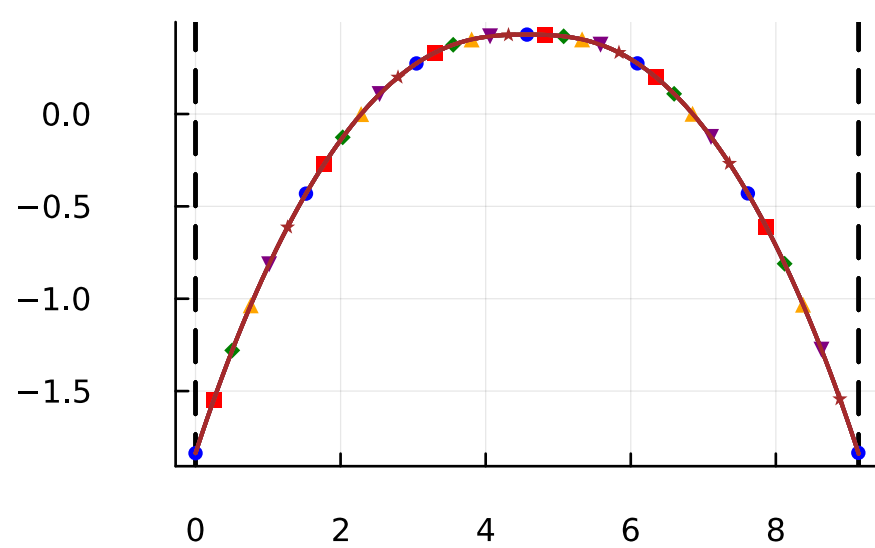
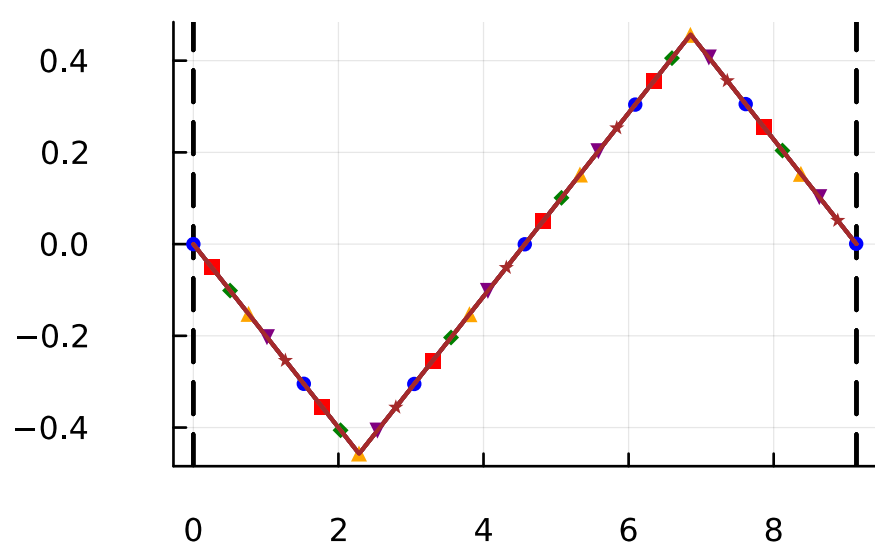
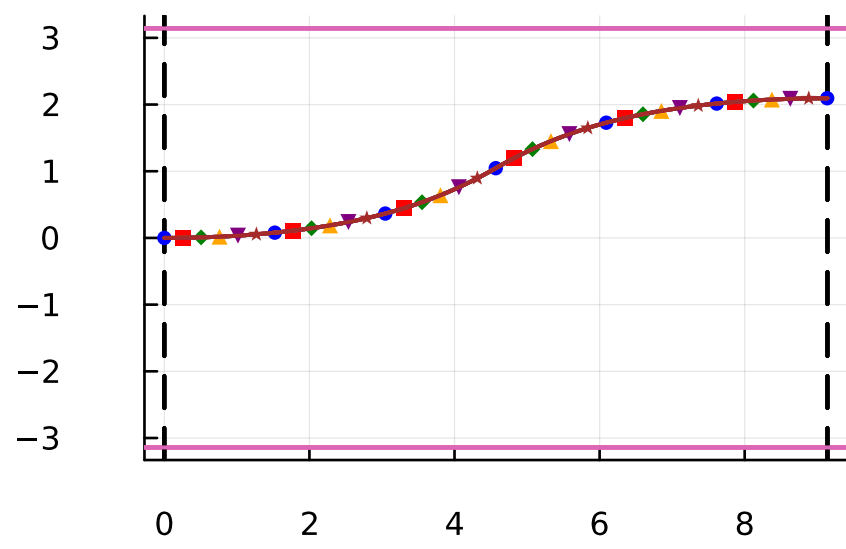
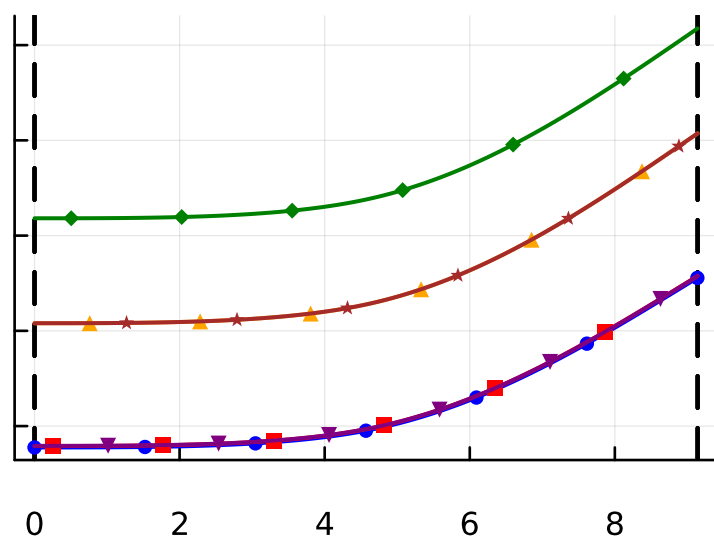
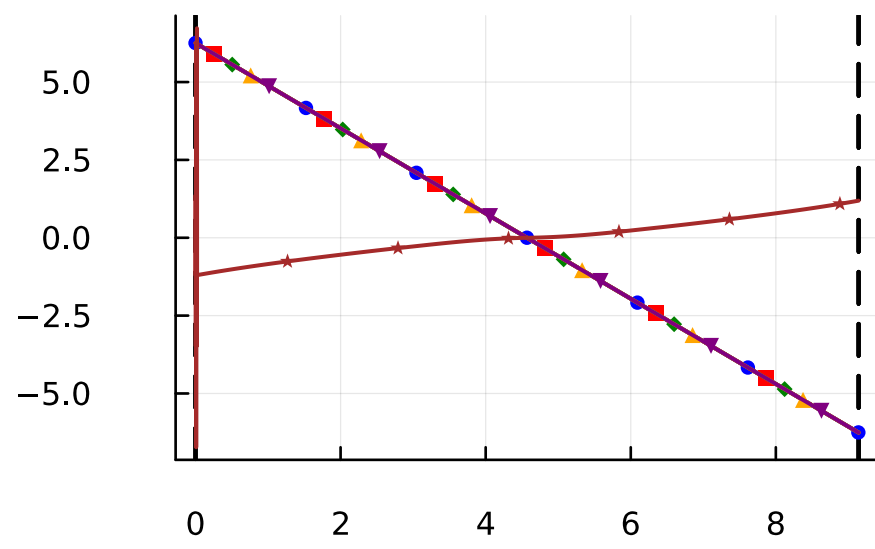
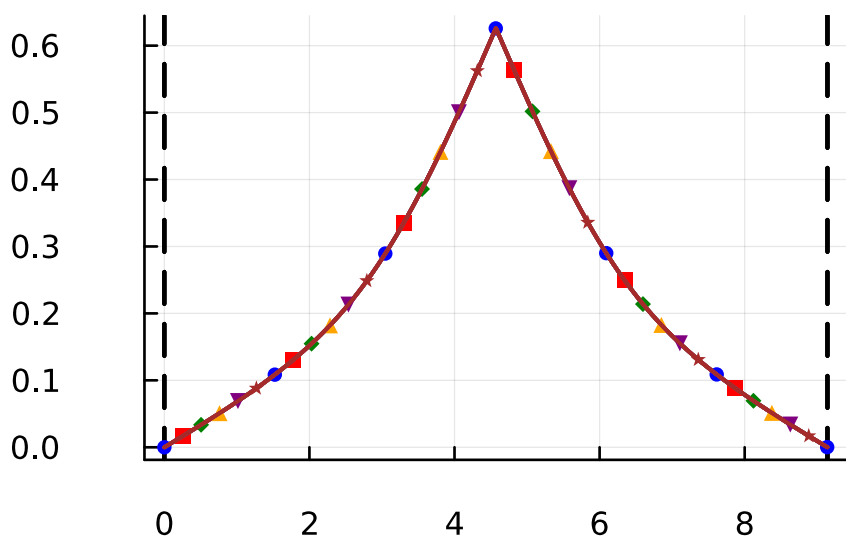
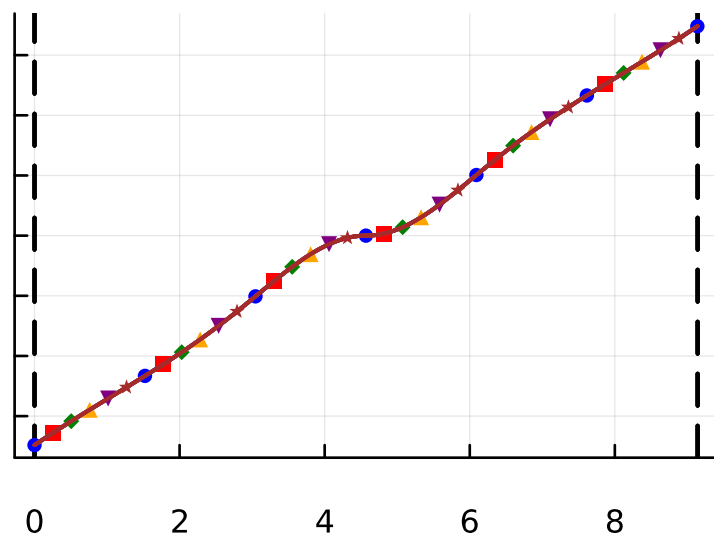
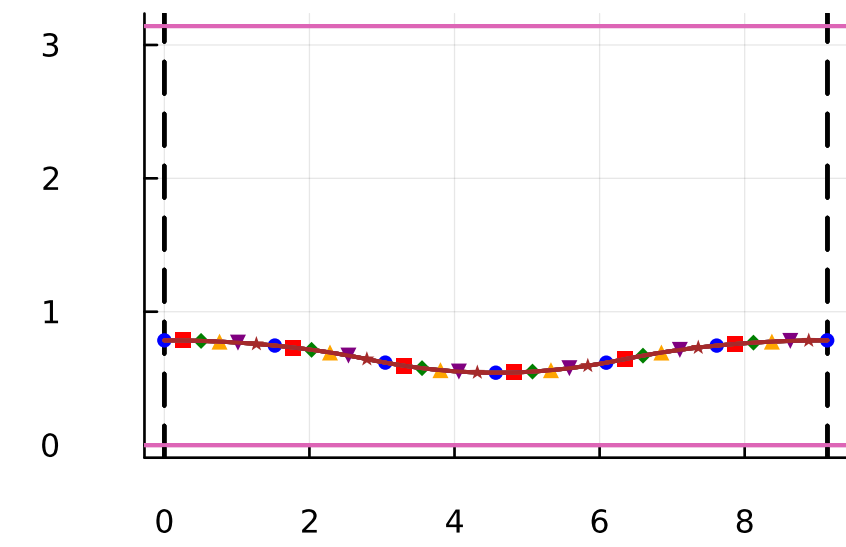
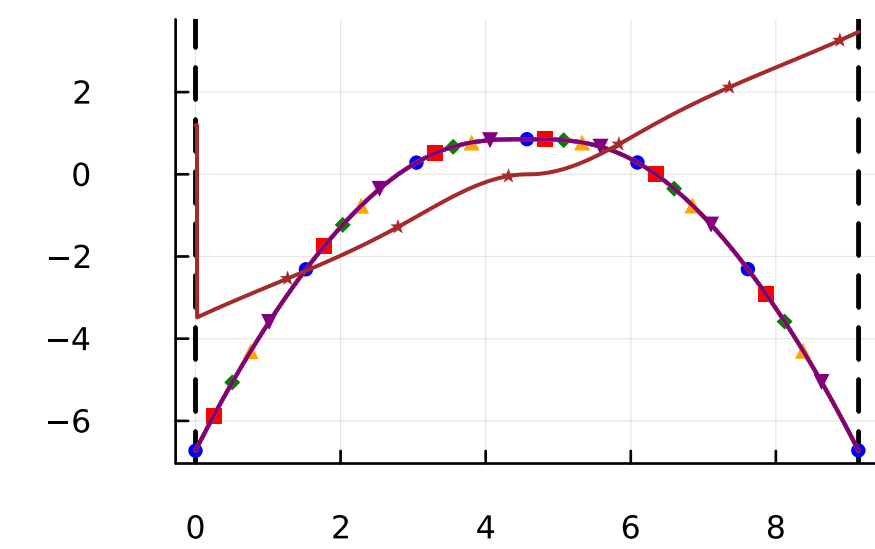
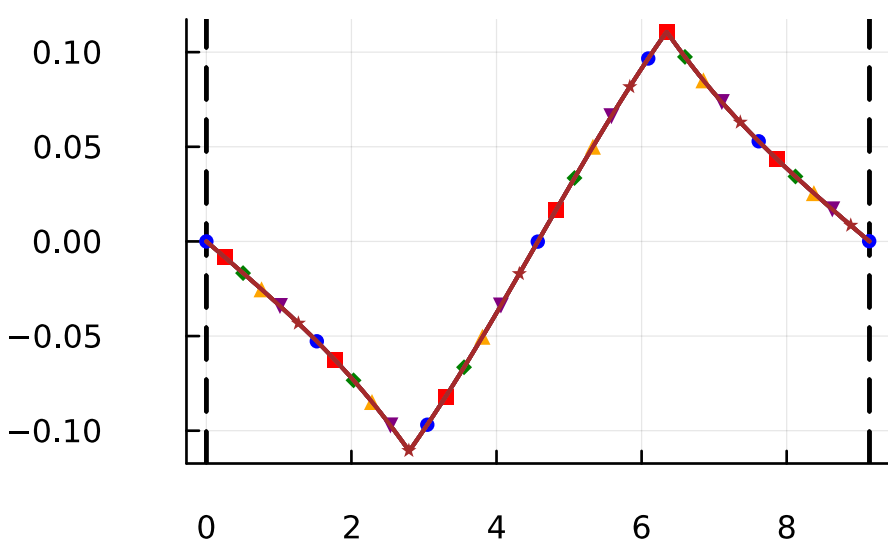


state



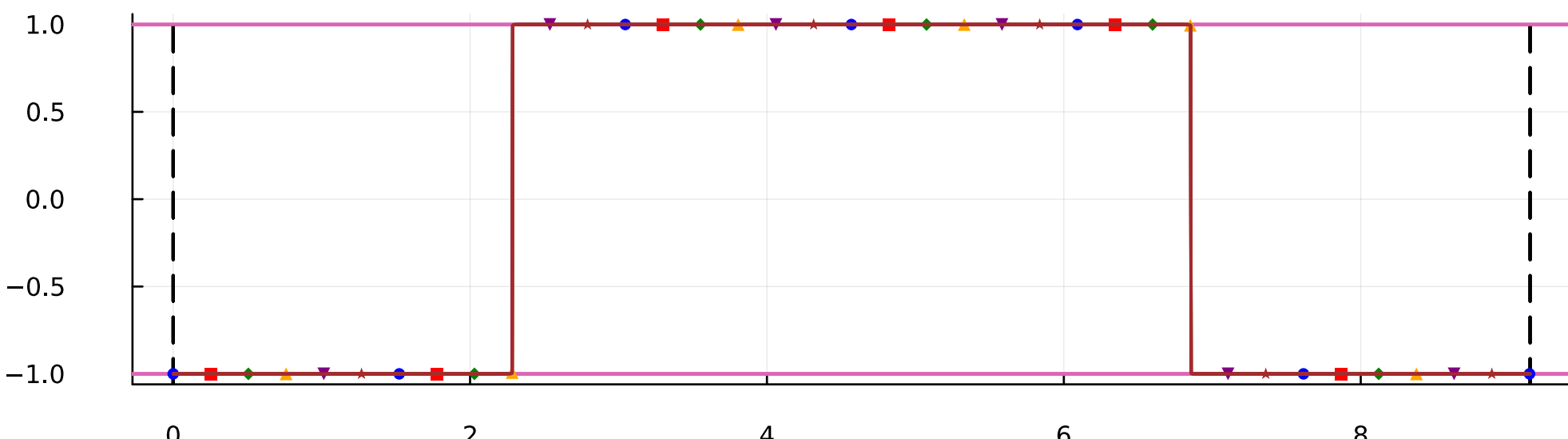
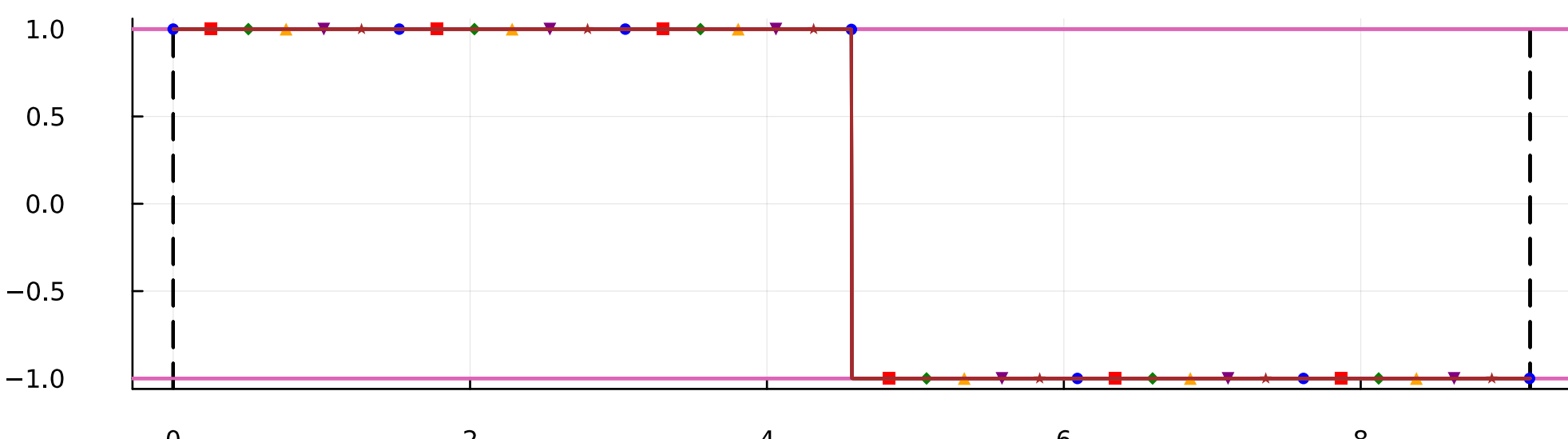
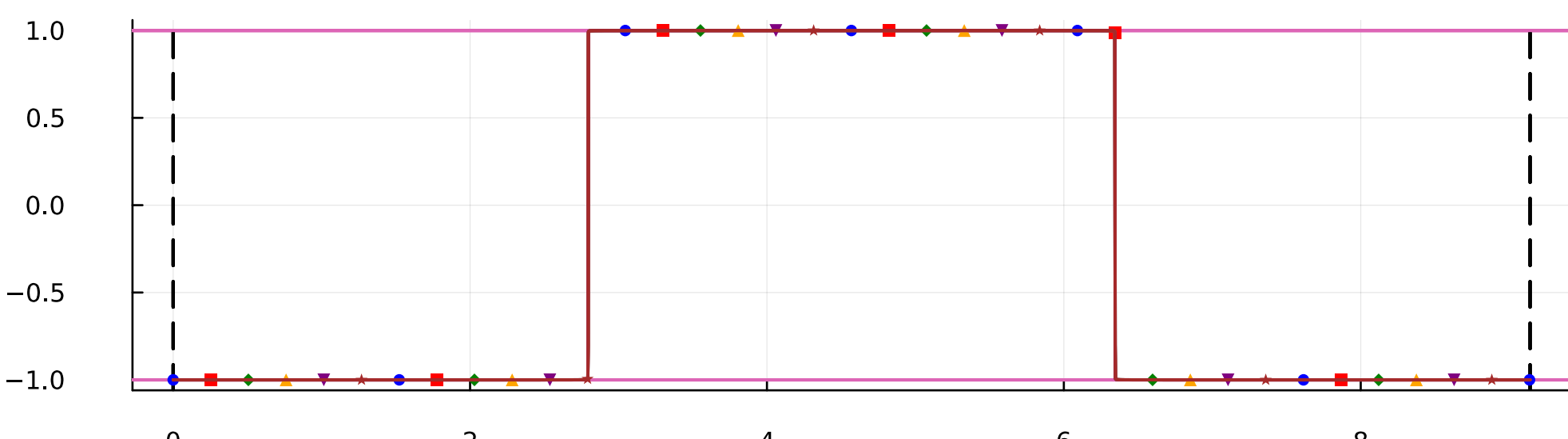
costate

 $d\rho$  θ  1.3685780×10^0 1.3685760×10^0 1.3685740×10^0 1.3685720×10^0 1.3685700×10^0  $d\theta$  ϕ  $d\phi$ 

t

t

control

 $u\rho$  $u\theta$  $u\phi$ 

t