

Optimal allocation of bacterial resources in a bioreactor

Introduction to optimal control problems

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Summary

- * Introduction to the problem
- * Definition of the model
- * Understanding optimal control theory
- * The biomass maximisation case
- * Calculation of Lie brackets
- * Conclusion

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» Introduction to the problem

The study of living micro-organisms

Bacteria's resource management and compound production in batch bioprocessing are explored using mathematical models, revealing insights at the biology-engineering crossroads.

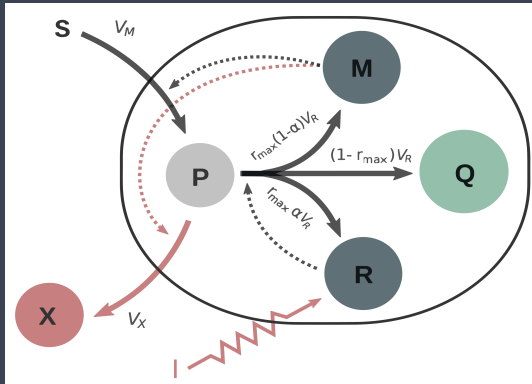
How can one know how to maximize the needs of a bacteria for its optimal development ?

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» Definition of the model

The self-replicator model



The self-replicator model

» Definition of the model

The self-replicator model

- * Initial mass of **substrate S**
- * Transformed into **precursors metabolites P**
- * P produces M , Q and R which catalyze other productions
- * Creation of X , **metabolites of interest**

» Definition of the model

Dynamical system

$$\left\{ \begin{array}{l} \dot{S} = -V_M \\ \dot{P} = V_M - V_X - V_R \\ \dot{R} = r_{max} u V_r \\ \dot{M} = r_{max} (1 - u) V_R \\ \dot{Q} = (1 - r_{max}) V_R \\ \dot{X} = V_X \end{array} \right. \quad (\text{SRM-D})$$

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» Understanding optimal control theory

First approach

Optimal control theory deals with objects that are to be **controlled** meaning that they depend on external factors.
Example for a plant growth :

- * Temperature
- * Lightning
- * Water
- * and much more ...

These are some of the many "controls" that one can try to adjust to maximize the plant growth.

» Understanding optimal control theory

Mathematical explanation

Let's say we want to maximize a plant's height.

This can be modeled as follows : Let $u \in \mathbb{R}$, $x \in \mathbb{R}^2$, $t \in [t_0, t_f]$, $x(t_0) = [h_0, s_0]$, h_0 being the height of the plant at time = 0 and s_0 the thickness of the stem at time = 0.

An example of the control u could be for example the light intensity variation over time, or the variation of temperature over time.

$$\begin{cases} \dot{x}(t) = F_0(x(t)) + u(t) \cdot F_1(x(t)) \\ h(t_f) \longrightarrow \max \end{cases}$$

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» The biomass maximisation case

Finite-time problem

$$\begin{cases} \dot{s} = -w_M(s)(1-r)\mathcal{V} \\ \dot{p} = w_M(s)(1-r) - w_R(p)(1+p)r \\ \dot{r} = (u-r)w_R(p)r \\ \dot{\mathcal{V}} = w_R(p)r\mathcal{V} \end{cases} \quad (\text{WTB-M})$$

» The biomass maximisation case

Finite-time problem

The numerical simulations of (WTB-M) were already done for a infinite-time problem. As a result, we solved the OCP problem for a finite-time horizon.

» The biomass maximisation case

Definition of (*BM — OCP*)

The problem in a finite-time case is modeled as follows

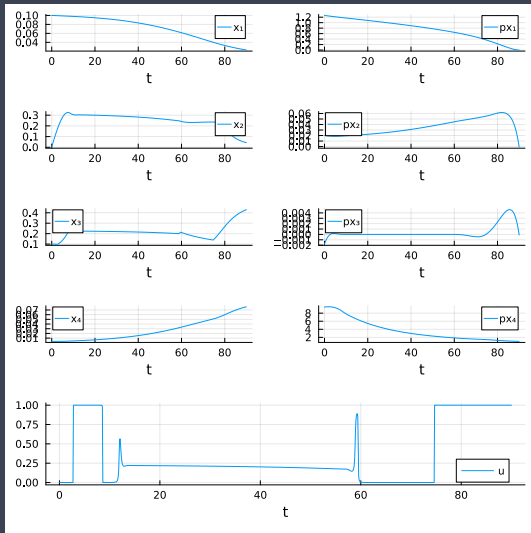
$$\left\{ \begin{array}{l} \mathcal{V}(t_f) \longrightarrow \max \\ \text{using the dynamics of (WTB-M)} \\ \text{using initial conditions (IC)} \\ u \in \mathcal{U} \end{array} \right. \quad (\text{BM-OCP})$$

With (IC) being

$$\begin{aligned} s(0) = s_0 > 0, p(0) = p_0 > 0, x(0) = 0, r(0) = r_0 \in (0, 1), \\ \mathcal{V}(0) = \mathcal{V}_0 > 0 \end{aligned} \quad (\text{IC})$$

» The biomass maximisation case

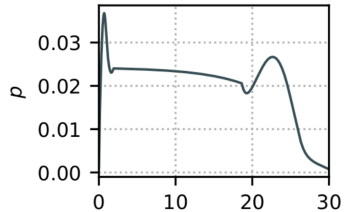
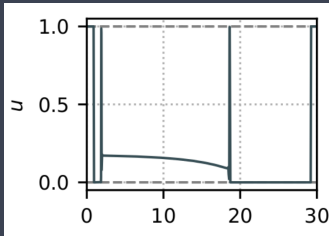
Results of the numerical simulations



Numerical simulations of (BM-OCP)

» The biomass maximisation case

Results of the numerical simulations



Numerical simulations of (BM-OCP)

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» Calculation of Lie brackets

Proposition to be proved

Proposition 4.4

If the *Lie* bracket F_{101} belongs to the span of F_1 and F_{01} , then singular extremals must be of (local) order at least two.

» Introduction to Lie brackets

Lie brackets applied to our case

Since our problem is modeled as follows

$$\varphi(x) = F_0(x) + u \cdot F_1(x)$$

with $x = (s \ p \ r \ \mathcal{V})^t$ with respect to (WTB-M)
 our goal was to compute the *Lie* brackets $F_{01} = [F_0, F_1]$ and
 $F_{101} = [F_1, F_{01}]$ and to make sure that

$$\text{rank}(F_1(\varphi), F_{01}(\varphi)) = \text{rank}(F_1(\varphi), F_{01}(\varphi), F_{101}(\varphi))$$

A *Lie* bracket is defined for vector fields as $[X, Y] = Y'X - X'Y$

» Introduction to Lie brackets

Symbolic calculations

The calculation of *Lie* brackets are involving determinants of 4×4 matrices which can be quite tricky to do by hand.
Hence, we decided to use symbolic calculation with Julia

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» Conclusion

This project was for us a glance at what research really is :

- * hand-calculations are not always possible
- * Julia is great for mathematicians
- * we liked working in english as it helped us getting better