

CS261 Data Structures

Hash Tables

Open Address Hashing

Goals

- Open Address Hashing

Hash Tables: Resolving Collisions

There are two general approaches to resolving collisions:

1. Open address hashing: if a spot is full, probe for next empty spot
2. Chaining (or buckets): keep a collection at each table entry

Open Address Hashing

- All values are stored in an **array**
- Hash value is used to find **initial index**
- If that position is filled, the next position is examined, then the next, and so on until you find the element OR an empty position is found
- The process of looking for an empty position is termed ***probing***, **specifically linear probing** when we look to the next element

Open Address Hashing: Example

Eight element table using Amy's hash function(alphabet position of the 3rd letter of the name):

Already added: Amina, Andy, Alessia, Alfred, and Aspen

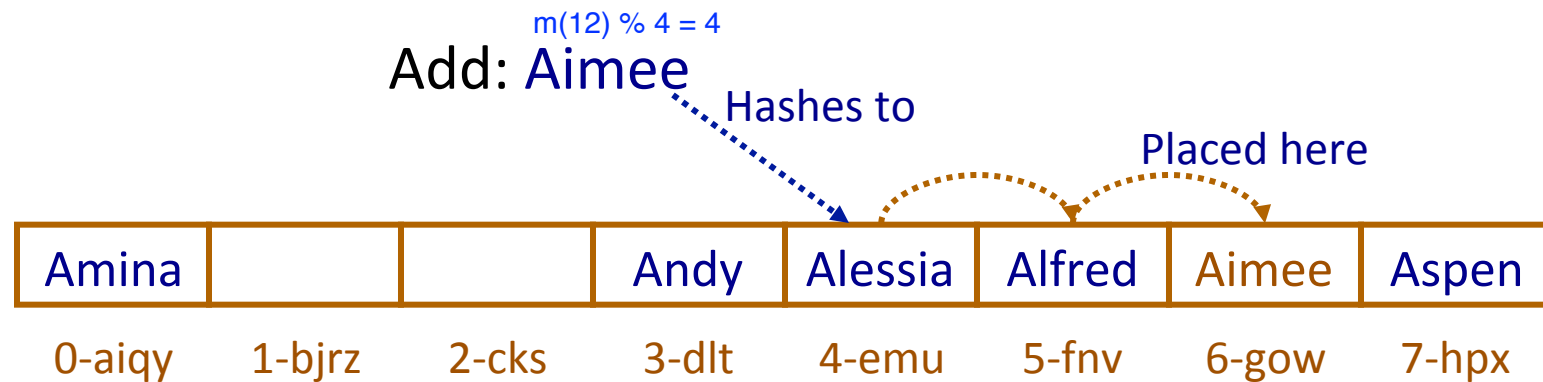
$i(8) \% 8 = 0$			$d(3) \% 8 = 3$	$e(4) \% 8 = 4$	$f(5) \% 8 = 5$		$p(15) \% 8 = 7$
Amina			Andy	Alessia	Alfred		Aspen
0-aiqy	1-bjrz	2-cks	3-dlt	4-emu	5-fnv	6-gow	7-hpx

Note: We've shown where each letter of the alphabet maps to for simplicity here (given a table size of 8) ...so you don't have to calculate it!

e.g. Y is the 25th letter (we use 0 index, so the integer value is 24) and $24 \bmod 8$ is 0

Open Address Hashing: Adding

Now we need to add: Aimee



The hashed index position (4) is filled by Alessia: so we *probe* to find next free location

Open Address Hashing: Adding (cont.)

Suppose **Anne** wants to join:

Add: **Anne**

Hashes to



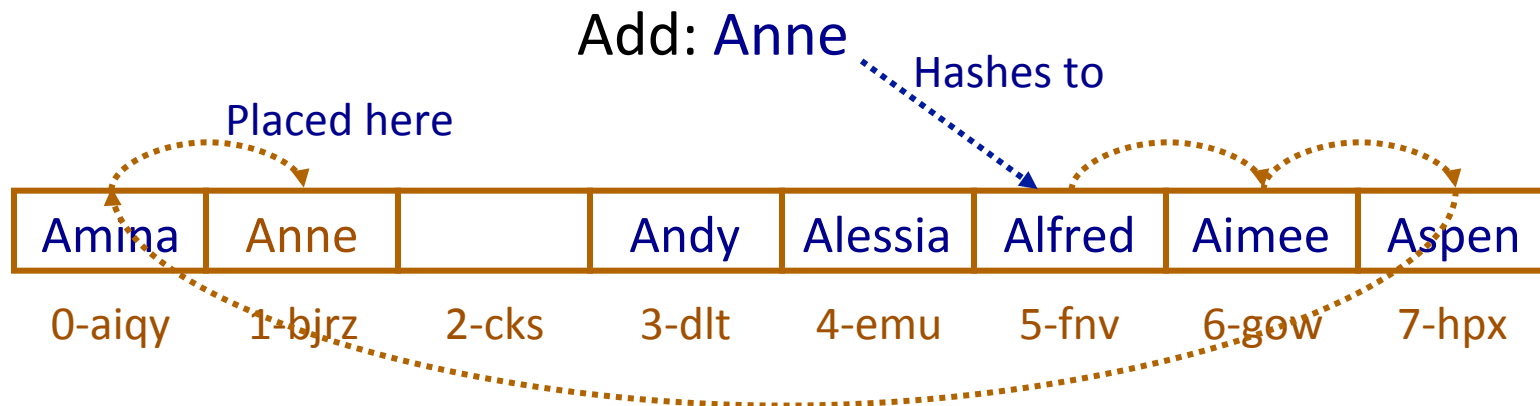
The hashed index position **(5)** is filled by Alfred:

- Probe to find next free location → **what happens when we reach the end of the array**

loop back to beginning of array and look for open slot

Open Address Hashing: Adding (cont.)

Suppose **Anne** wants to join:



The hashed index position **(5)** is filled by Alfred:

- Probe to find next free location
- When we get to end of array, wrap around to the beginning
- Eventually, find position at index **1** open

Open Address Hashing: Adding (cont.)

Finally, **Alan** wants to join:

Add: **Alan**

Hashes to

Placed here

Amina	Anne	Alan	Andy	Alessia	Alfred	Aimee	Aspen
0-aiqy	1-bjrz	2-cks	3-dlt	4-emu	5-fnv	6-gow	7-hpx

The hashed index position **(0)** is filled by Amina:

- Probing finds last free position **(index 2)**
- Collection is now completely filled
- What should we do if someone else wants to join?
(More on this later)

add function

Open Address Hashing: Contains

- Hash to find initial index
- probe forward until
 - value is found, **or** (return 1)
 - *empty location is found* (return 0)

Looking for Aimee:

- Aimee should index to 4, so start at that index
- keep iterating until you find it or hit empty space

Amina			Andy	Alessia	Alfred	Aimee	Aspen
0-aiqy	1-bjrz	2-cks	3-dlt	4-emu	5-fnv	6-gow	7-hpx

- Notice that search time is not uniform

Open Address Hashing: Remove

- Remove is tricky
- What happens if we delete **Anne**, then search for **Alan**?

Remove: **Anne**

Amina	Anne	Alan	Andy	Alessia	Alfred	Aimee	Aspen
0-aiqy	1-bjrz	2-cks	3-dlt	4-emu	5-fnv	6-gow	7-hpx

Find: **Alan**

Hashes to

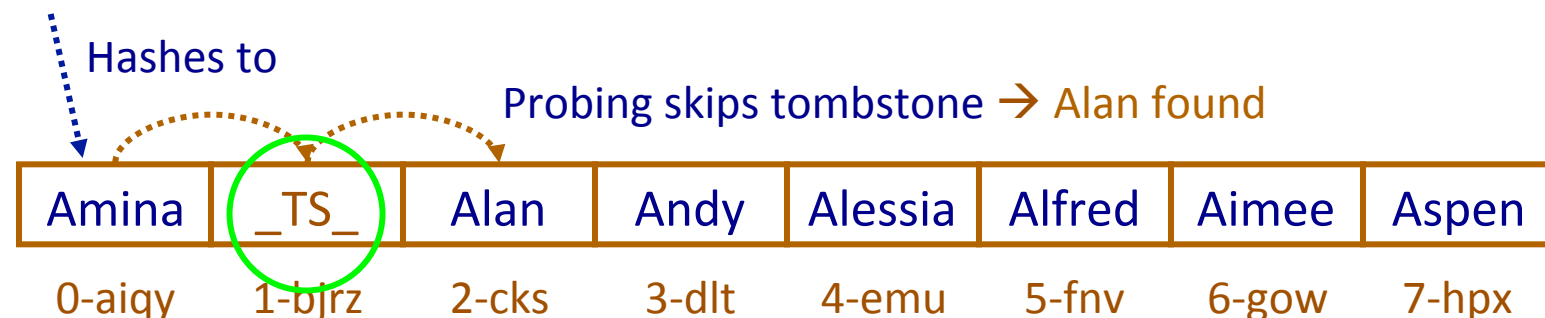
Probing finds null entry → Alan not found

Amina		Alan	Andy	Alessia	Alfred	Aimee	Aspen
0-aiqy	1-bjrz	2-cks	3-dlt	4-emu	5-fnv	6-gow	7-hpx

Open Address Hashing: Handling Remove

- Simple solution: Don't allow removal (e.g. words don't get removed from a spell checker!) good for things like spell checker, cuz words don't often get removed from a language
- Better solution: replace removed item with "tombstone"
 - Special value that marks deleted entry
 - Can be replaced when adding new entry
 - But doesn't halt search during contains or remove

Find: Alan



Hash Table Size: Load Factor

Load factor:

The diagram shows the formula $\lambda = n / m$ in blue. Three orange dotted arrows point from the formula to its components: one from λ to the text 'Load factor', one from n to the text '# of elements', and one from m to the text 'Size of table'.

$$\lambda = n / m$$

- represents the portion of the buckets that are filled
 - For open address hashing, load factor is between 0 and 1 (often somewhere between 0.5 and 0.75)
- empty
- full

Want the load factor to remain small in order to avoid collisions

Clustering

- Assuming uniform distribution of hash values what's the probability that the next value will end up in index 1, 2, 6 ?



- As load factor gets larger, the tendency to cluster increases, resulting in longer search times upon collision
- Also affected by removals with `_TS_`

Hash Tables: Algorithmic Complexity

- Assumptions:
 - Time to compute hash function is constant
 - Worst case analysis \rightarrow All values hash to same position
 - Best case analysis \rightarrow Hash function uniformly distributes the values
- Find element operation:
 - Worst case for open addressing $\rightarrow O(n)$
 - Best case for open addressing $\rightarrow O(1)$

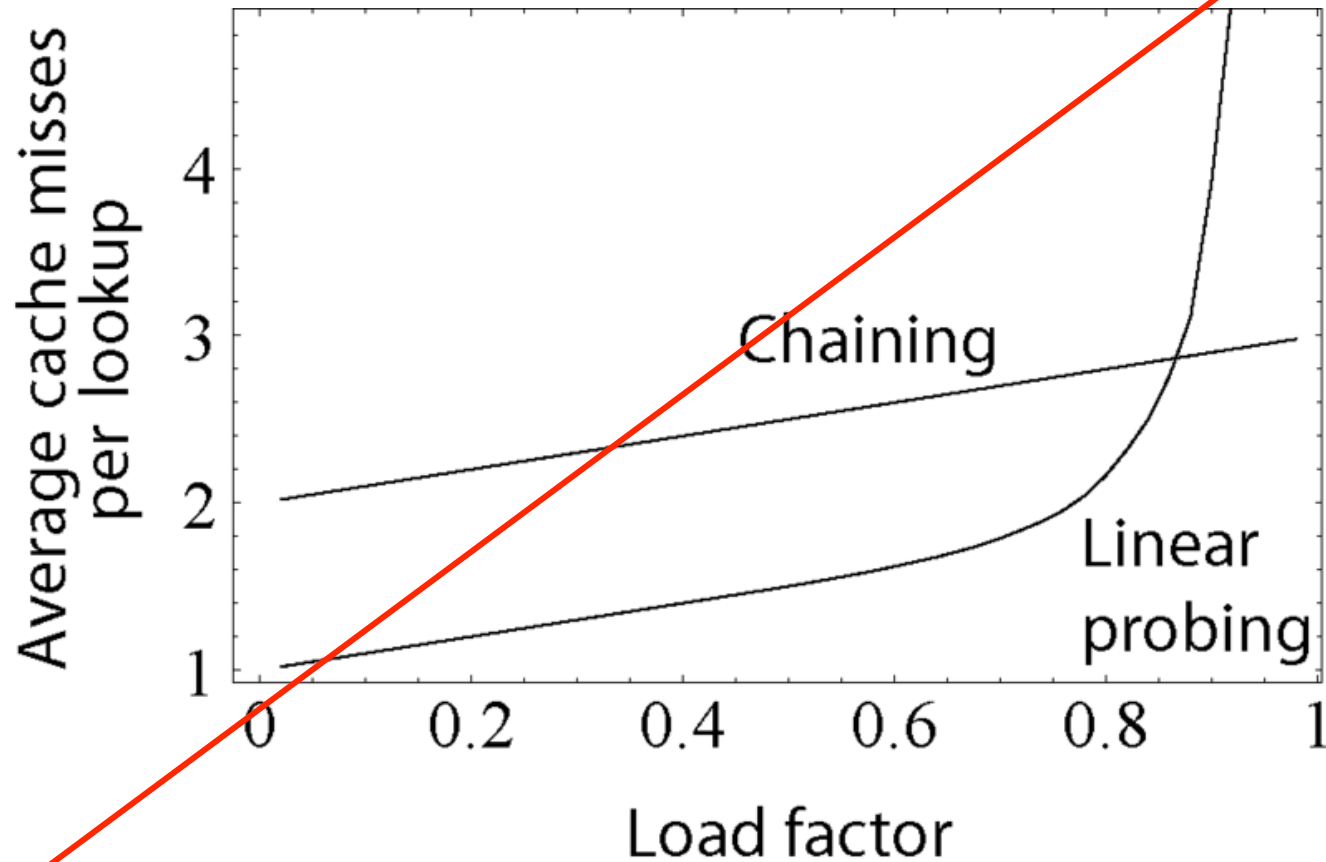
Hash Tables: Average Case

- What about average case for successful, S , and unsuccessful searches, U ?

$$S \approx \frac{1}{2} \left(1 + \frac{1}{1-\lambda} \right) \quad U \approx \frac{1}{2} \left(1 + \frac{1}{(1-\lambda)^2} \right)$$

λ	S	U
0.5	1.5	2.5
0.75	2.5	8.5
0.9	5.5	50.5

Performance vs. Load Factor



http://en.wikipedia.org/wiki/Hash_table

Double Hashing

- Rather than use a linear probe (ie. looking at successive locations)...
 - Use a second hash function to determine the probe step
- Helps to reduce clustering

Large Load Factor: What to do?

- Common solution: When load factor becomes too large (say, bigger than 0.75) → Reorganize
- Create new table with twice the number of positions
- Copy each element, *rehashing* using the new table size, placing elements in new table
- Delete the old table

Hashing in Practice

- Need to find good hash function → uniformly distributes keys to all indices
- Open address hashing:
 - Need to tell if a position is empty or not
 - One solution → store only pointers & check for null ($== 0$)

Your Turn

- Complete Worksheet #37: Open Address Hashing