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**Prove true parameters of ML2P model are a minimum of VAE loss**

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We define the true and predicted probability of student  $j$  answering item  $i$  correctly with  $P_{ij}$  and  $\hat{P}_{ij}$ , respectively. The former comes from the ML2P model, and the latter is the output of a neural network. We assume the more simple case, where  $\Theta \sim \mathcal{N}(0, I)$ , rather than  $\mathcal{N}(\mu, \Sigma)$ .

$$\begin{aligned} P_{ij} &= \frac{1}{1 + \exp\left(-\sum_{k=1}^K a_{ik}\theta_{jk} + b_i\right)} \\ \hat{P}_{ij} &= \frac{1}{1 + \exp\left(-\sum_{k=1}^K \hat{a}_{ik}(\hat{\theta}_{jk} + \varepsilon_k \hat{\sigma}_k) + \hat{b}_i\right)} \end{aligned} \quad (1)$$

Note that  $P_{ij}$  is unknown, and we instead have a response sequence  $\vec{u}_j = (u_{1j}, \dots, u_{nj})^\top$  with  $u_{ij} = \text{Bern}(P_{ij})$ . This also means that  $\mathbb{E}[u_{ij}] = P_{ij}$ . The variables  $\hat{a}_{ik}$ ,  $\hat{b}_i$ ,  $\hat{\theta}_{ik}$ , and are parameter estimates from the VAE. The first two are parameters in the neural network, and the ability estimates are taken from feeding responses to the encoder, i.e.,  $\hat{\Theta}_j = \text{Encoder}(\vec{u}_j)$ . The noise  $\varepsilon = (\varepsilon_k)_{1 \leq k \leq K} \sim \mathcal{N}(0, I)$  is introduced by the sampling operation in the VAE.

The loss function for a VAE is given by

$$\begin{aligned} \mathcal{L}(\vec{u}_j) &= -\sum_{i=1}^n \left[ u_{ij} \log(\hat{P}_{ij}) + (1 - u_{ij}) \log(1 - \hat{P}_{ij}) \right] + \mathbb{E}_{q_\alpha(\hat{\theta}|\vec{u}_j)} \log\left(\frac{q_\alpha(\hat{\theta}|\vec{u}_j)}{p(\theta)}\right) \\ &= \mathcal{L}_{\text{REC}} + \mathcal{L}_{\text{KL}} \end{aligned} \quad (2)$$

We break up the VAE loss into two terms, the reconstruction loss  $\mathcal{L}_{\text{REC}}$  and the KL-divergence loss  $\mathcal{L}_{\text{KL}}$ . In the latter, the distribution  $q_\alpha(\hat{\theta}|\vec{u}_j)$  is the output of the encoder, and  $p(\theta)$  is the assumed prior distribution of  $\Theta$ , which we set to be  $\mathcal{N}(0, I)$ .

We write  $P_{ij} = \mathbb{E}(u_{ij})$ , and similarly define a new “expected” loss function:

$$\begin{aligned} \mathcal{L}_{\mathbb{E}}(P_j) &= \mathbb{E}_{u_j}[\mathcal{L}(u_{:j})] \\ &= -\sum_{i=1}^n (P_{ij} \log(\hat{P}_{ij}) + (1 - P_{ij}) \log(1 - \hat{P}_{ij})) + \mathbb{E}_{q_\alpha(\hat{\theta}|u_j)} \log\left(\frac{q_\alpha(\hat{\theta}|u_j)}{p(\theta)}\right) \\ &= \mathcal{L}_{\mathbb{E}[\text{REC}]} + \mathcal{L}_{\mathbb{E}[\text{KL}]} \end{aligned} \quad (3)$$

Notice that calculation of this “expected loss” requires the unknown  $P_{ij}$ . But when we have large amounts of data, we can think of  $P_{ij}$  as the average value of the response  $u_{ij}$ , so using this unknown value here is justified.

Define  $z_i = a_{i:} \cdot \theta_{j:} - b_i$  and  $\hat{z}_i = \hat{a}_{i:} \cdot (\hat{\theta}_{j:} + \varepsilon \cdot \hat{\sigma}) - \hat{b}_i$ . Note that  $z_i$  is fixed, dependent on the data, and does not depend on any parameters of the neural network.  $\hat{z}_i$  is the input to the final layer of the decoder, and the VAE output is  $\hat{P}_{ij} = \sigma(\hat{z}_i)$ , where  $\sigma(\cdot)$  is the sigmoidal activation function. We compute derivatives of the expected loss function, looking individually at the reconstruction and KL terms.

$$\begin{aligned} \frac{\partial \mathcal{L}_{\mathbb{E}[\text{REC}]} }{\partial \hat{z}_i} &= \frac{-1}{1 + e^{-z_i}} \cdot \frac{1}{1 + e^{\hat{z}_i}} - \frac{1}{1 + e^{z_i}} \cdot \frac{-1}{1 + e^{-\hat{z}_i}} \\ &= \frac{-1}{(1 + e^{-z_i})(1 + e^{\hat{z}_i})} + \frac{1}{(1 + e^{z_i})(1 + e^{-\hat{z}_i})} \\ &= \frac{-1}{(1 + e^{-a_{ik}\theta_{jk} + b_i})(1 + e^{\hat{a}_{ik}(\hat{\theta}_{jk} + \varepsilon_k \hat{\sigma}_k) - \hat{b}_i})} + \frac{1}{(1 + e^{a_{ik}\theta_{jk} - b_i})(1 + e^{-\hat{a}_{ik}(\hat{\theta}_{jk} + \varepsilon_k \hat{\sigma}_k) - \hat{b}_i})} \end{aligned} \quad (4)$$

$$\begin{aligned}
\frac{\partial \mathcal{L}_{\mathbb{E}[\text{REC}]}}{\partial \hat{a}_{ik}} &= \frac{\partial \mathcal{L}_{\mathbb{E}[\text{REC}]}}{\partial \hat{z}_i} \frac{\partial \hat{z}_i}{\partial \hat{a}_{ik}} = \frac{\partial \mathcal{L}_{\mathbb{E}[\text{REC}]}}{\partial \hat{z}_i} (\hat{\theta}_{jk} + \varepsilon_k \hat{\sigma}_k) \\
\frac{\partial \mathcal{L}_{\mathbb{E}[\text{REC}]}}{\partial \hat{b}_i} &= \frac{\partial \mathcal{L}_{\mathbb{E}[\text{REC}]}}{\partial \hat{z}_i} \frac{\partial \hat{z}_i}{\partial \hat{b}_i} = \frac{\partial \mathcal{L}_{\mathbb{E}[\text{REC}]}}{\partial \hat{z}_i} (-1) \\
\frac{\partial \mathcal{L}_{\mathbb{E}[\text{REC}]}}{\partial \hat{\theta}_{ik}} &= \frac{\partial \mathcal{L}_{\mathbb{E}[\text{REC}]}}{\partial \hat{z}_i} \frac{\partial \hat{z}_i}{\partial \hat{\theta}_{ik}} = \frac{\partial \mathcal{L}_{\mathbb{E}[\text{REC}]}}{\partial \hat{z}_i} (\hat{a}_{ik})
\end{aligned} \tag{5}$$

Rather than setting these to zero and solving, we show that the most intuitive solution,  $\hat{a}_{ik} = a_{ik}$ ,  $\hat{b}_i = b_i$ , and  $\hat{\theta}_{jk} = \theta_{jk}$ , is in fact a minimum of the expected loss function. But first, we must take another expectation over the random variable  $\varepsilon \sim \mathcal{N}(0, I)$ . Obviously, we have that  $\mathbb{E}[\varepsilon_k] = 0$ ; this makes our calculations very simple. Notice that we have

$$\begin{aligned}
&\mathbb{E}_{\varepsilon} \left[ \frac{\partial \mathcal{L}_{\mathbb{E}[\text{REC}]}}{\partial \hat{z}_i} \right] \Big|_{\hat{a}_{ik}=a_{ik}, \hat{b}_i=b_i, \hat{\theta}_{jk}=\theta_{jk}} \\
&= \frac{-1}{(1 + e^{-a_{ik}\theta_{jk}+b_i})(1 + e^{a_{ik}(\theta_{jk}+0\hat{\sigma}_k)-b_i})} + \frac{1}{(1 + e^{a_{ik}\theta_{jk}-b_i})(1 + e^{-a_{ik}(\theta_{jk}+0\hat{\sigma}_k)+b_i})} \\
&= 0
\end{aligned} \tag{6}$$

Therefore we clearly have

$$\begin{aligned}
&\mathbb{E}_{\varepsilon} \left[ \frac{\partial \mathcal{L}_{\mathbb{E}[\text{REC}]}}{\partial \hat{a}_{ik}} \right] \Big|_{\hat{a}_{ik}=a_{ik}, \hat{b}_i=b_i, \hat{\theta}_{jk}=\theta_{jk}} \\
&= \mathbb{E}_{\varepsilon} \left[ \frac{\partial \mathcal{L}_{\mathbb{E}[\text{REC}]}}{\partial \hat{b}_i} \right] \Big|_{\hat{a}_{ik}=a_{ik}, \hat{b}_i=b_i, \hat{\theta}_{jk}=\theta_{jk}} \\
&= \mathbb{E}_{\varepsilon} \left[ \frac{\partial \mathcal{L}_{\mathbb{E}[\text{REC}]}}{\partial \hat{\theta}_{jk}} \right] \Big|_{\hat{a}_{ik}=a_{ik}, \hat{b}_i=b_i, \hat{\theta}_{jk}=\theta_{jk}} \\
&= 0 \quad \forall i, j, k
\end{aligned} \tag{7}$$

This proves that the true parameters give a local minimum for the expected reconstruction error in the VAE loss. And because the expected cross-entropy loss function  $\mathcal{L}_{\mathbb{E}[\text{REC}]}$  is non-negative, the reconstruction error at the true IRT paramters is a global minimum.

We now consider the Kullback-Leibler divergence term in the expected loss function. Assuming independent latent traits, we have

any chance this is unique?

$$\mathcal{L}_{KL} = \mathbb{E}_{q(\theta|u)} \left[ \log \left( \frac{q(\hat{\theta}|u)}{p(\theta)} \right) \right] = KL(q(\hat{\theta}|u) || p(\theta)) = -\frac{1}{2} \sum_{k=1}^K (1 + \log(\hat{\sigma}_k^2) - \hat{\theta}_k^2 - \hat{\sigma}_k^2) \tag{8}$$

It is clear that this regularization term is minimized (and equal to zero) when  $\hat{\theta}_{jk} = 0$  and  $\hat{\sigma}_{jk} = 1$ . But what happens when we plug in the “true” student ability values as before? We have

$$\mathcal{L}_{KL} \Big|_{\hat{\theta}=\theta, \hat{\sigma}=\sigma} = KL(p(\theta|u) || p(\theta)) \tag{9}$$

Notice that this is the KL divergence between the **true posterior**  $p(\theta|u)$  and the **true prior**  $p(\theta)$ . This is interpreted as the average difference of number of bits required to encode samples of  $p(\theta|u)$  using a code optimized for  $p(\theta)$ , rather than one optimized for  $p(\theta|u)$ . We should be okay with accepting this loss, since the true posterior is not actually known, and we are just using the prior as a reference.

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TODO: try to show that this is a global minimum for the full VAE loss function. Also take derivatives of the KL loss w.r.t  $\hat{\theta}_{jk}$ . The Q-matrix may help with an identifiability issue (existence of other local minimums) in solving the system  $(a_{ik}\theta_{jk} + b_i)_{jk} = z_i$ . The Q-matrix *may* make the solution unique.

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