

view_frames Result

Recorded at time: 1677669614.8810456

robot_2/odom_combined

Broadcaster: /robot_2/robot_pose_ekf
Average rate: 20.202
Buffer length: 4.95
Most recent transform: 1677669614.817
Oldest transform: 1677669609.868

robot_2/base_link

Broadcaster: /robot_2/robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot_2/base_footprint

Broadcaster: /robot_2/robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot_2/chassis

Broadcaster: /robot_2/robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot_2/gyro_link

Broadcaster: /robot_2/robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot_2/laser_link

Broadcaster: /robot_2/robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot_2/left_front_link

Broadcaster: /robot_2/robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot_2/left_wheel_link

Broadcaster: /robot_2/robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot_2/right_front_link

Broadcaster: /robot_2/robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot_2/right_wheel_link