

HOW TO SOLVE THE PROBLEMS IN OUR PROJECT?

Tikhonov regularization: consider the item-item graph Tikhonov regularization

$$\min_{\mathbf{X} \in \mathbb{R}^{U \times I}} \|\mathbf{Y} - \mathbf{X}\|_F^2 + \mu \text{tr}(\mathbf{X}^\top \mathbf{L} \mathbf{X}) \quad (30)$$

where $\|\cdot\|_F$ is the Frobenius norm and matrix $\mathbf{X} \in \mathbb{R}^{U \times I}$ is the full rating matrix.

Equivalently, for the i th item, $i = 1, \dots, I$, the regularization problem has the form to solve the ratings $\mathbf{x}_i \in \mathbb{R}^U$ for all users

$$\min_{\mathbf{x}_i \in \mathbb{R}^U} \|\mathbf{y}_i - \mathbf{x}_i\|_2^2 + \mu \mathbf{x}_i^\top \mathbf{L} \mathbf{x}_i. \quad (31)$$

Let us write the objective out as the following form (subscript i omitted)

$$\begin{aligned} & (\mathbf{y} - \mathbf{x})^\top (\mathbf{y} - \mathbf{x}) + \mu \mathbf{x}^\top \mathbf{L} \mathbf{x} \\ & = (\mathbf{x}^\top \mathbf{x} - 2\mathbf{y}^\top \mathbf{x} + \mathbf{y}^\top \mathbf{y}) + \mu \mathbf{x}^\top \mathbf{L} \mathbf{x} \end{aligned} \quad (32)$$

which is a convex function w.r.t., \mathbf{x} . We can find its gradient as follows

$$\nabla_{\mathbf{x}} = 2\mathbf{x} - 2\mathbf{y} + 2\mu \mathbf{L} \mathbf{x}. \quad (33)$$

Since above gradient has a zeros, i.e., $\nabla_{\mathbf{x}} = \mathbf{0} \in \mathbb{R}^U$ has a closed-form solution, we can find the optimum \mathbf{x}^* as

$$\begin{aligned} \nabla_{\mathbf{x}} &= \mathbf{0} \\ (\mathbf{I} + \mu \mathbf{L}) \mathbf{x} &= \mathbf{y} \\ \mathbf{x}^* &= (\mathbf{I} + \mu \mathbf{L})^{-1} \mathbf{y}. \end{aligned} \quad (34)$$

matrix form solution

Intuitively, the solution in the matrix form should be

$$\mathbf{X}^* = (\mathbf{I} + \mu \mathbf{L})^{-1} \mathbf{Y}. \quad (35)$$

But can you find this solution starting from the objective function of the matrix form? Try it with matrix cookbook.

other regularizers

Depends on if we have a closed-form gradient? closed-form solution from setting the gradient as zero? then we choose the way of solving the problem

- adjacency based 2-norm variation measure $\|\mathbf{x} - \mathbf{A}_n \mathbf{x}\|_2^2$:
- total variation 1-norm $\|\mathbf{x} - \mathbf{A}_n \mathbf{x}\|_1$: check the ISTA algorithm based on soft-thresholding
- SLIM method has two regularizers: $\|\mathbf{w}\|_2^2 + \|\mathbf{w}\|_1$

In the case of other regularizers, you could replace the term $\text{tr}(\mathbf{X}^\top \mathbf{L} \mathbf{X})$ in (30) or $\mathbf{x}_i^\top \mathbf{L} \mathbf{x}_i$ in (31) by the corresponding regularizers. For instance, the total variation 1-norm one would have the form in the vector fashion:

$$\min_{\mathbf{x}_i \in \mathbb{R}^U} \|\mathbf{y}_i - \mathbf{x}_i\|_2^2 + \mu \|\mathbf{x}_i - \mathbf{A}_n \mathbf{x}_i\|_1. \quad (36)$$

In the matrix form, there is an equivalent form too as follows:

$$\min_{\mathbf{X} \in \mathbb{R}^{U \times I}} \|\mathbf{Y} - \mathbf{X}\|_2^2 + \mu \|\mathbf{X} - \mathbf{A}_n \mathbf{X}\|_1. \quad (37)$$

Here $\|\mathbf{X} - \mathbf{A}_n \mathbf{X}\|_1$ is hard to handle, which is also one of the reasons why we recommend to solve the problem in the vector form.

For another example, the regularizer $\|\mathbf{x} - \mathbf{A}_n \mathbf{x}\|_2^2$. The problem of the vector form is

$$\min_{\mathbf{x}_i \in \mathbb{R}^U} \|\mathbf{y}_i - \mathbf{x}_i\|_2^2 + \mu \|\mathbf{x}_i - \mathbf{A}_n \mathbf{x}_i\|_2^2. \quad (38)$$

In the matrix form, it is

$$\min_{\mathbf{X} \in \mathbb{R}^{U \times I}} \|\mathbf{Y} - \mathbf{X}\|_2^2 + \mu \|\mathbf{X} - \mathbf{A}_n \mathbf{X}\|_F. \quad (39)$$

Basically, $\|\mathbf{X}\|_F$ is a matrix version of the vector norm $\|\mathbf{x}\|_2$.

ℓ_1 norm

Let us have a closer look at the ℓ_1 norm, the u th element

$$(\|\mathbf{x}\|_1)_u = \begin{cases} x_u, & \text{if } x_u > 0 \\ -x_u, & \text{if } x_u < 0 \\ 0, & \text{if } x_u = 0. \end{cases} \quad (40)$$

What about its gradient? Technically, we cannot find the gradient, why? Check the plot of $|x|$, at $x = 0$ there are indefinite gradients. Thus, so-called subgradient is introduced.

$$(\nabla_{\mathbf{x}} \|\mathbf{x}\|_1)_u = \begin{cases} 1, & \text{if } x_u > 0 \\ -1, & \text{if } x_u < 0 \\ [-1, 1], & \text{if } x_u = 0. \end{cases} \quad (41)$$

Putting this subgradient together with the gradient of the data fitting term, the u th gradient has the form

$$0 = \begin{cases} x_u - y_u + \mu, & \text{if } x_u > 0 \\ x_u - y_u - \mu, & \text{if } x_u < 0 \\ [-y_u - \mu, y_u + \mu], & \text{if } x_u = 0 \end{cases} \quad (42)$$

Then, we have the optimum \mathbf{x}^* with the u th entry

$$x_u = \begin{cases} y_u - \mu, & \text{if } x_u > 0 \text{ or } y_u \geq \mu \\ y_u + \mu, & \text{if } x_u < 0 \text{ or } y_u \leq -\mu \\ 0, & \text{if } -\mu \leq y_u \leq \mu. \end{cases} \quad (43)$$

We also write above operator as, known as soft-thresholding operator

$$\mathbf{x} = S_\mu(\mathbf{y}) := (|\mathbf{y}| - \mu)_+ \text{sign}(\mathbf{y}). \quad (44)$$

The famous ISTA algorithm is a method with soft-thresholding the gradient-descent step.

final notes

We introduce these for the sake of understanding what optimization is doing, why ℓ_1 norm is more involved than ℓ_2 norm. But for this research project, we still also suggest to use the well-known iterative algorithms, e.g., sgd, adam, coordinate descent. These algorithms are all well embedded in python packages or in other languages.