# Lecture 10

Tian Han

## Outline

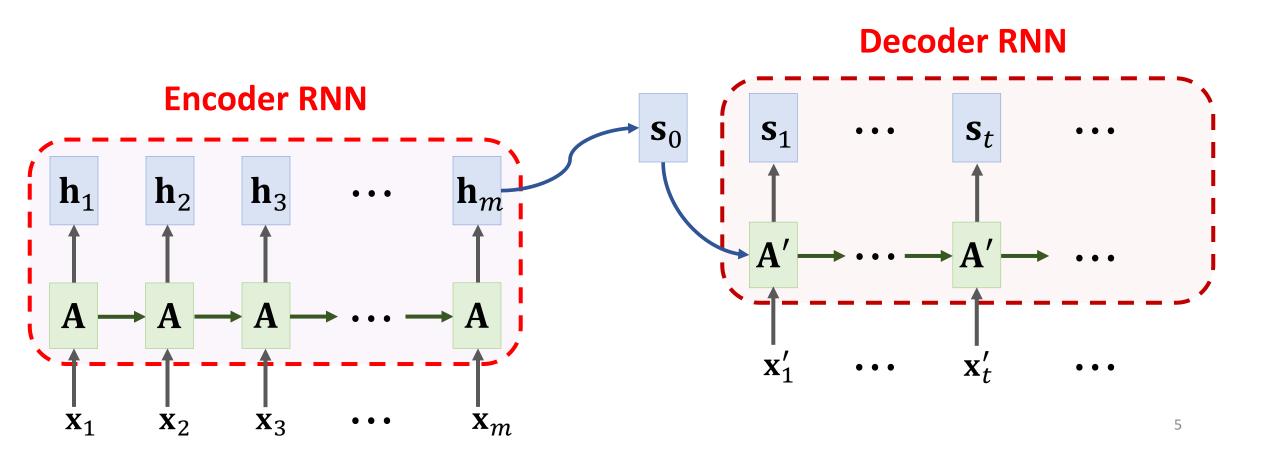
Attention For RNN

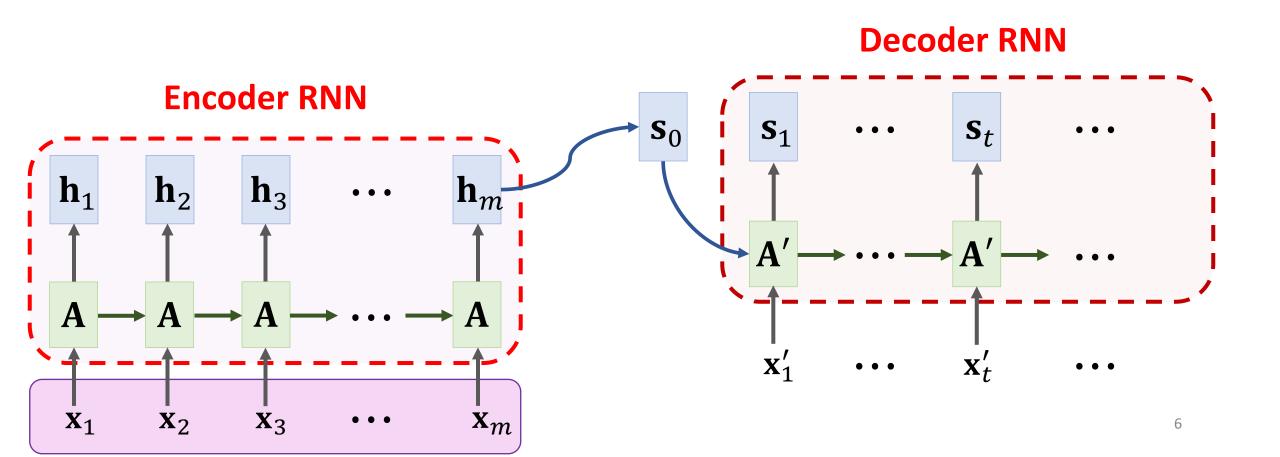
Self-attention

Transformer basic (attention, self-attention layer)

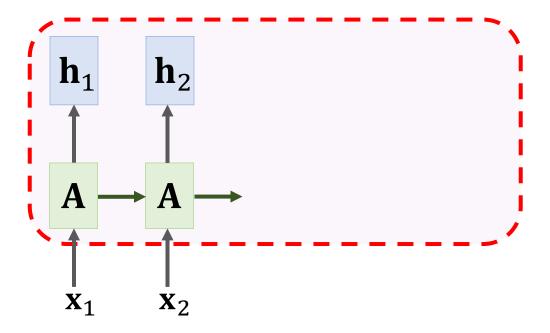
## **Attention for RNNs**

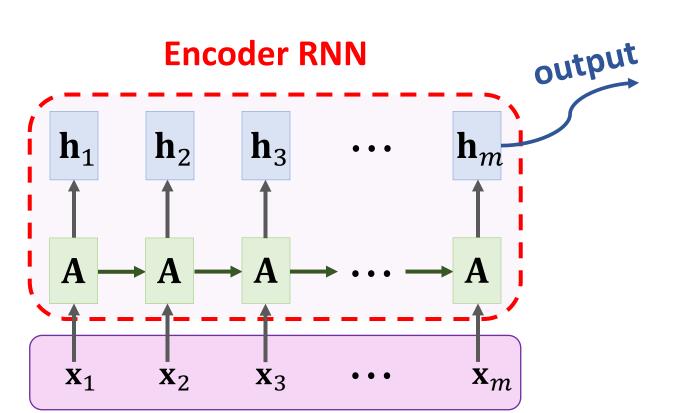
## **Revisiting Seq2Seq Model**

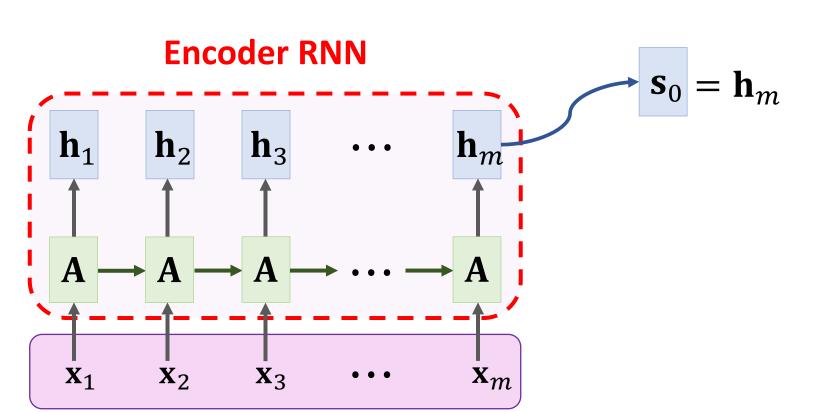


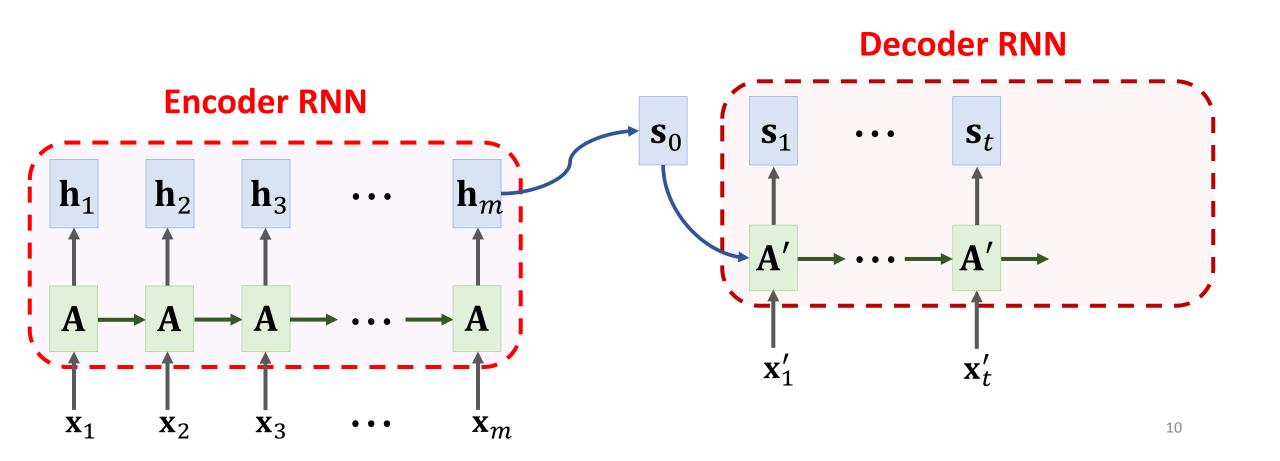


#### **Encoder RNN**

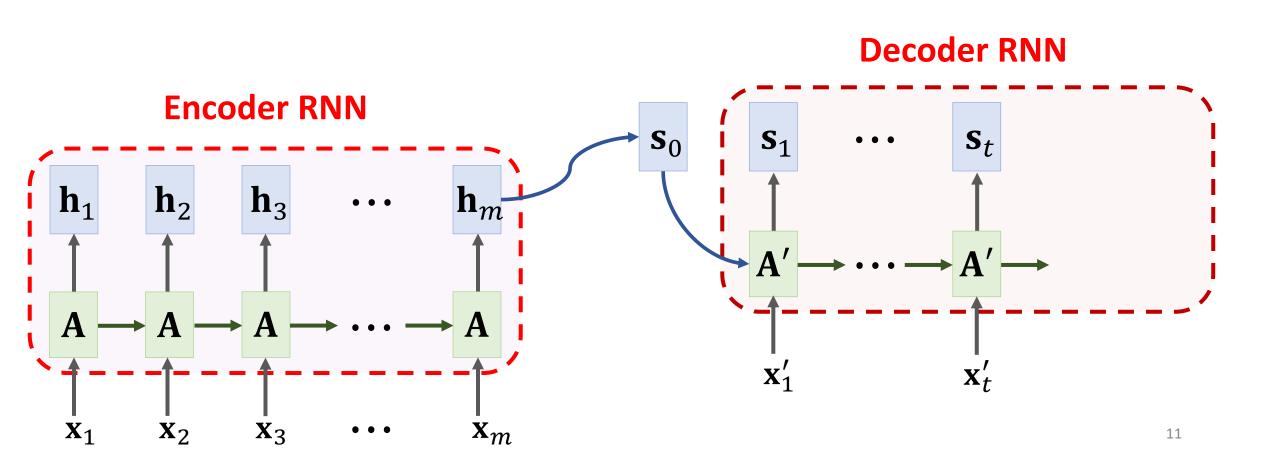




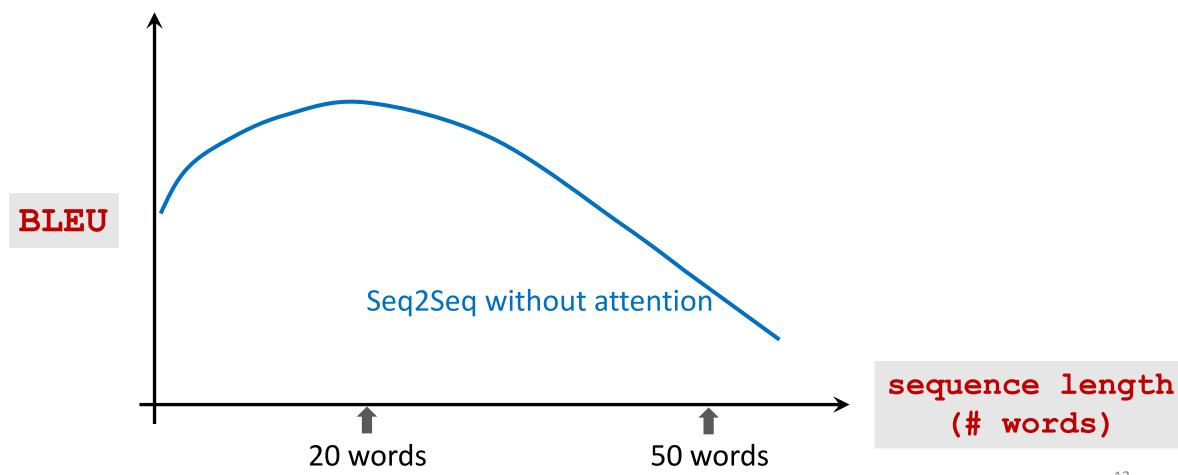




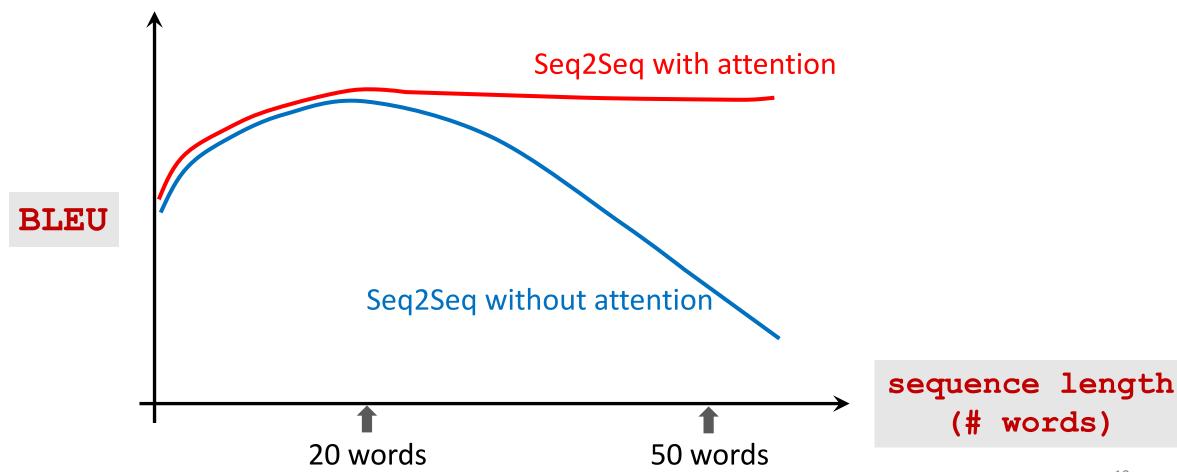
**Shortcoming:** The final state is incapable of remembering a **long** sequence.



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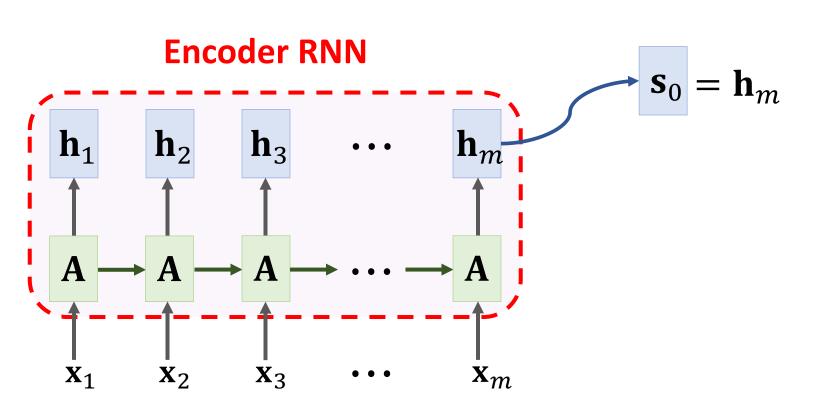
### Attention for Seq2Seq Model

#### Reference

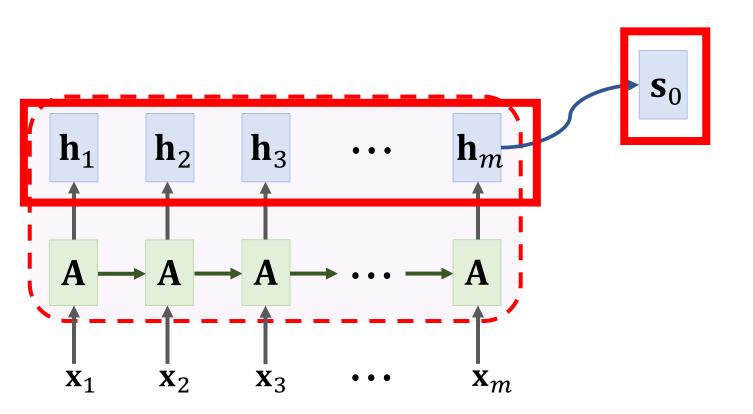
Bahdanau, Cho, & Bengio. Neural machine translation by jointly learning to align and translate.
 In ICLR, 2015.

#### Seq2Seq Model with Attention

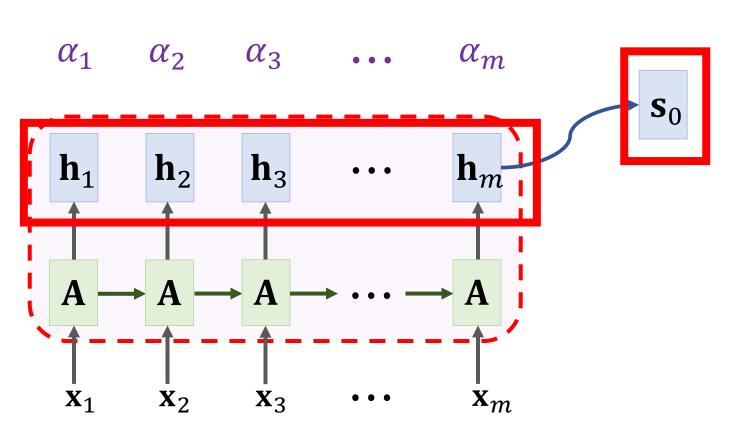
- Attention significantly improves RNN Seq2Seq model.
- With attention, RNN Seq2Seq model does not forget source input.
- With attention, the decoder knows where to focus.
- Downside: much more computation.



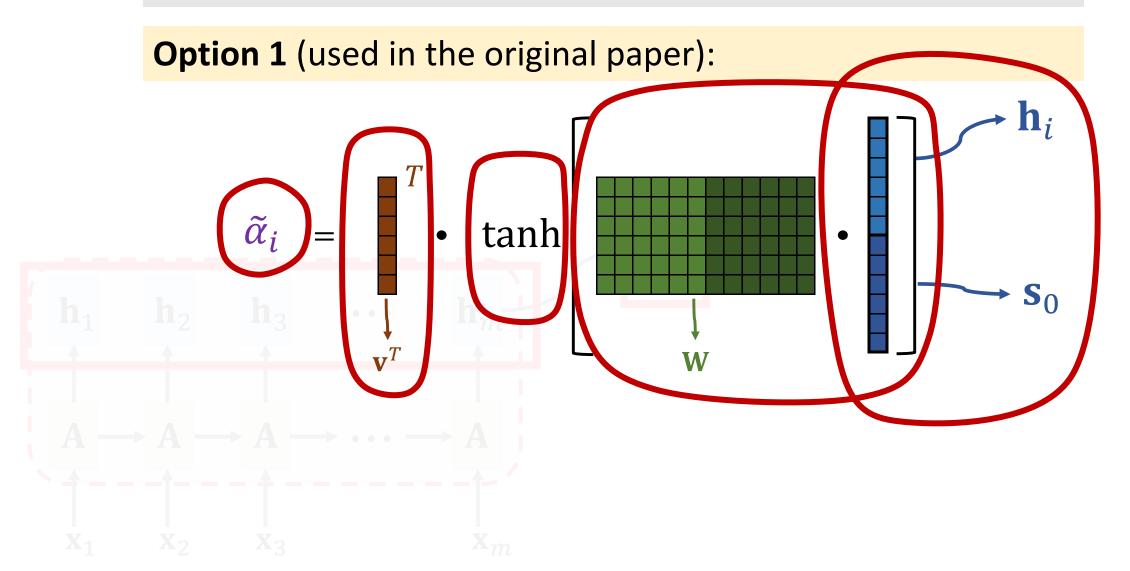
Weight: 
$$\alpha_i = \text{align}(\mathbf{h}_i, \mathbf{s}_0)$$
.



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.

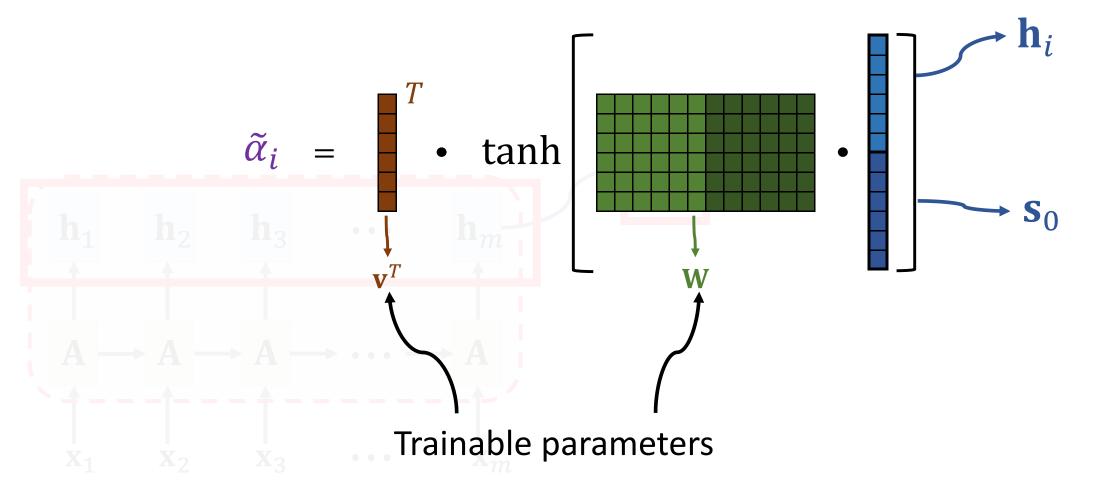


Weight:  $\alpha_i = \operatorname{align}(\mathbf{h}_i, \mathbf{s}_0)$ .



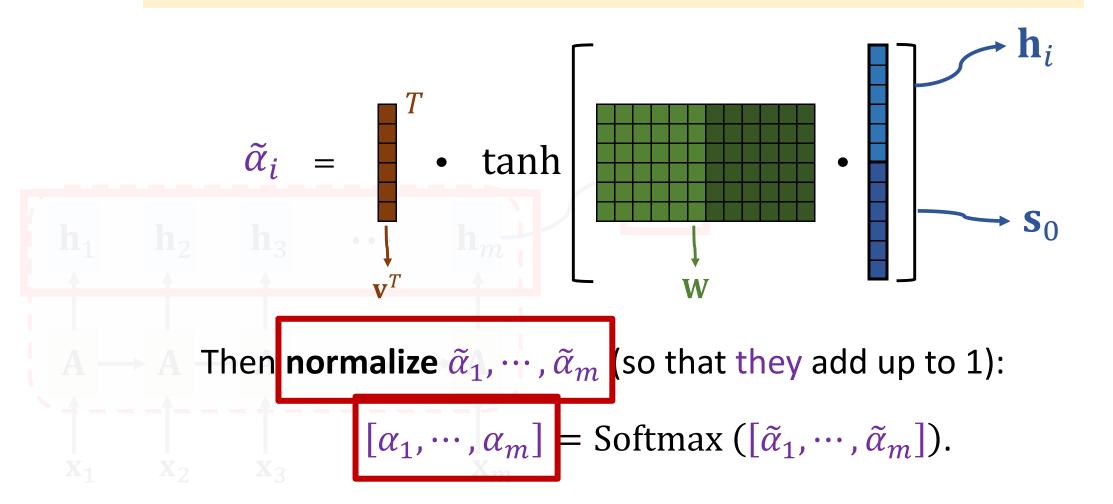
Weight:  $\alpha_i = \operatorname{align}(\mathbf{h}_i, \mathbf{s}_0)$ .

**Option 1** (used in the original paper):



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Weight: 
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.

#### **Option 2** (more popular; the same to Transformer):

#### 1. Linear maps:

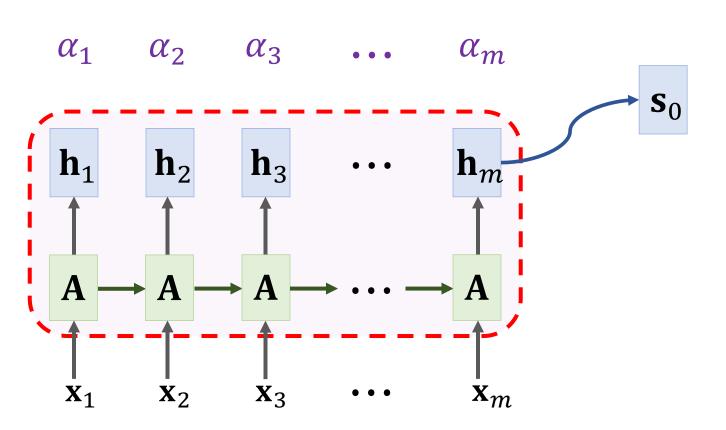
- $\mathbf{k}_i = \mathbf{W}_K \cdot \mathbf{h}_i$ , for i = 1 to m.  $\mathbf{q}_0 = \mathbf{W}_Q \cdot \mathbf{s}_0$ .

#### 2. Inner product:

- $\tilde{\alpha}_i = \mathbf{k}_i^T \mathbf{q}_0$ , for i = 1 to m.
- 3. Normalization:

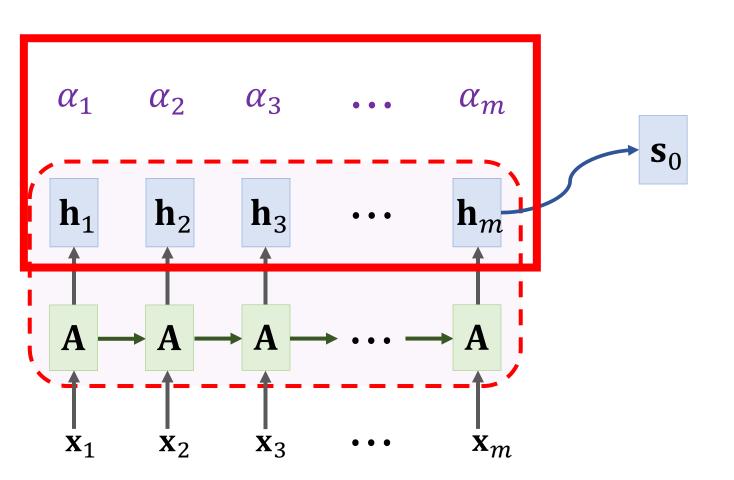
• 
$$[\alpha_1, \dots, \alpha_m] = \text{Softmax}([\tilde{\alpha}_1, \dots, \tilde{\alpha}_m]).$$

Weight: 
$$\alpha_i = \operatorname{align}(\mathbf{h}_i, \mathbf{s}_0)$$
.



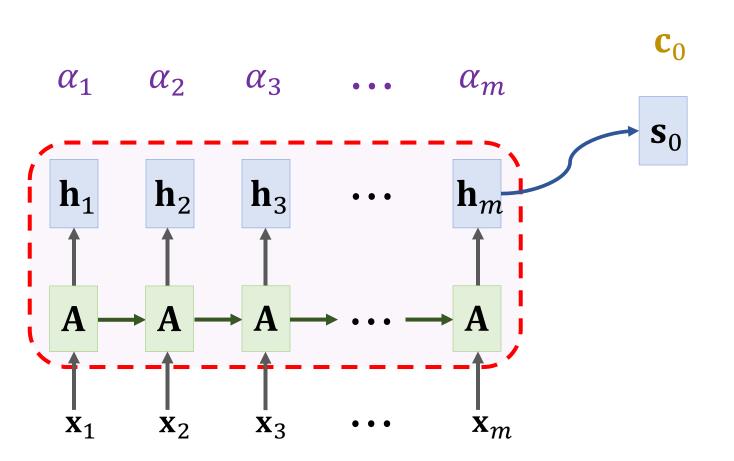
Weight:  $\alpha_i = \operatorname{align}(\mathbf{h}_i, \mathbf{s}_0)$ .

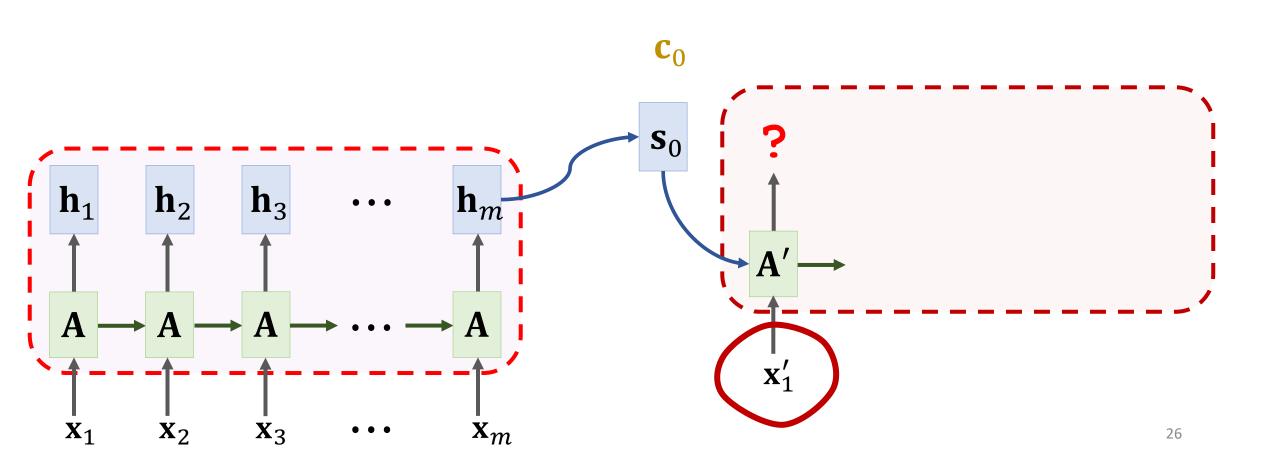
Context vector:  $\mathbf{c}_0 = \alpha_1 \mathbf{h}_1 + \cdots + \alpha_m \mathbf{h}_m$ .



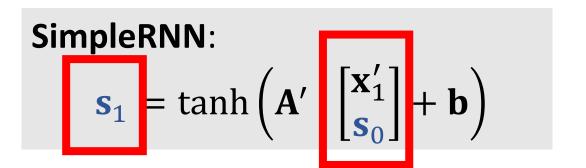
Weight:  $\alpha_i = \operatorname{align}(\mathbf{h}_i, \mathbf{s}_0)$ .

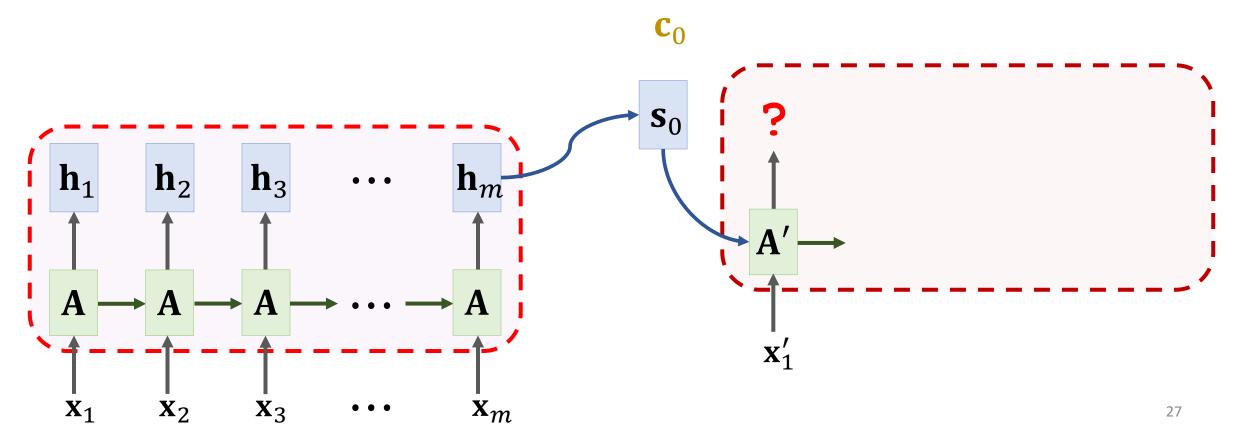
Context vector:  $\mathbf{c}_0 = \alpha_1 \mathbf{h}_1 + \cdots + \alpha_m \mathbf{h}_m$ .





## **SimpleRNN**

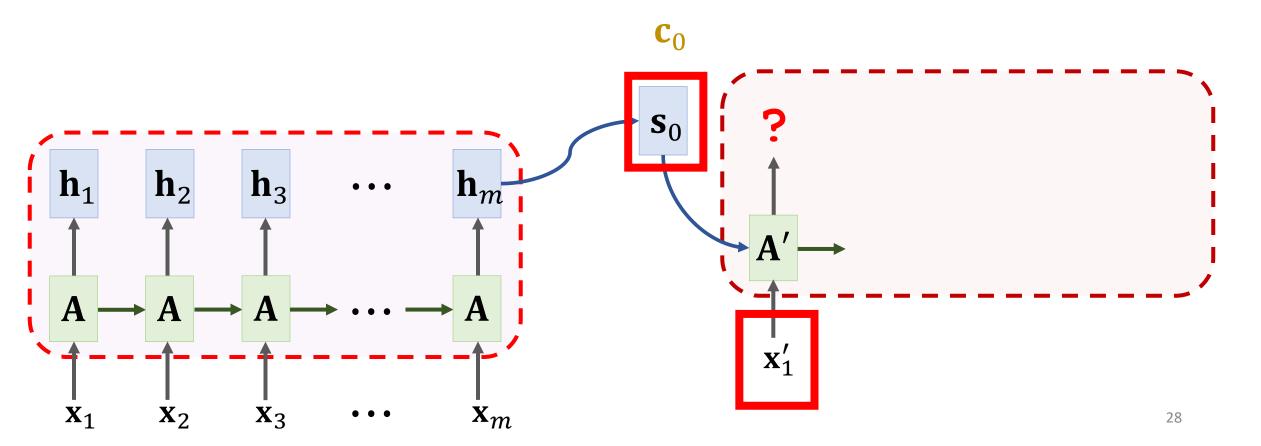




### **SimpleRNN**

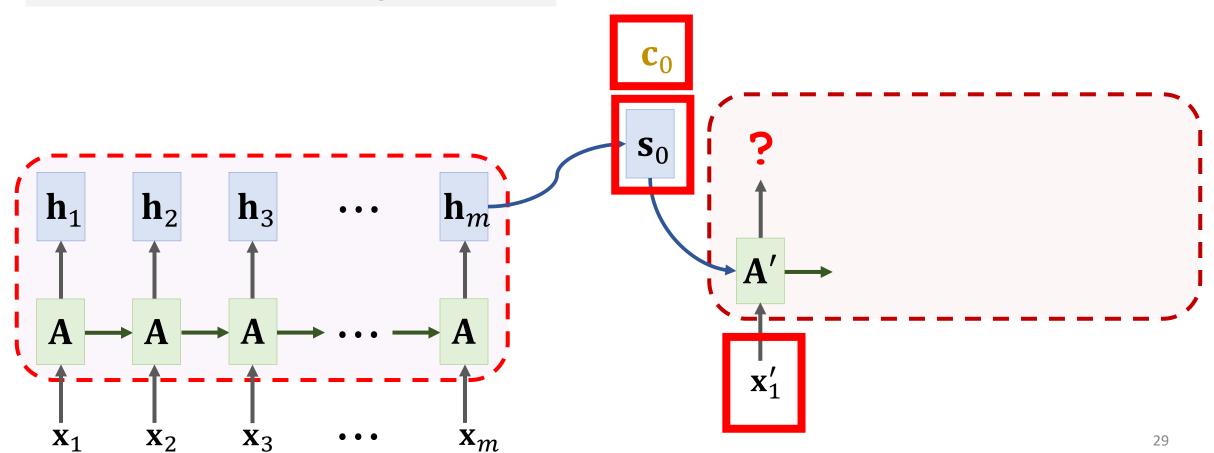
#### SimpleRNN:

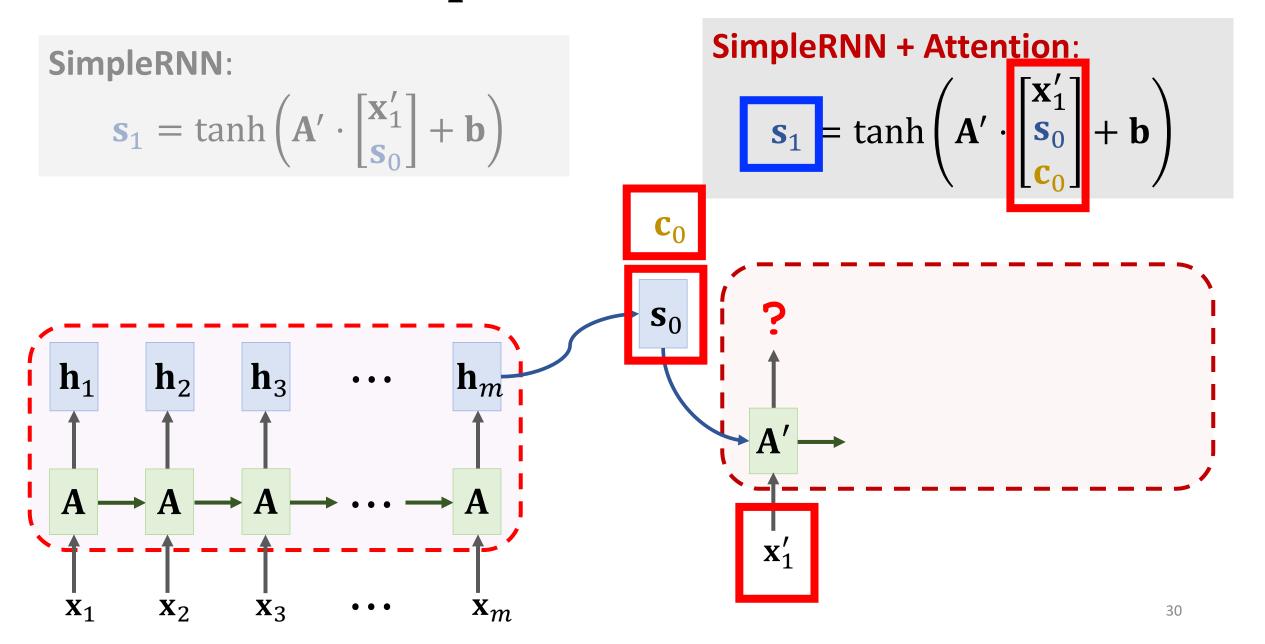
$$\mathbf{s}_1 = \tanh\left(\mathbf{A}' \cdot \begin{bmatrix} \mathbf{x}_1' \\ \mathbf{s}_0 \end{bmatrix} + \mathbf{b}\right)$$

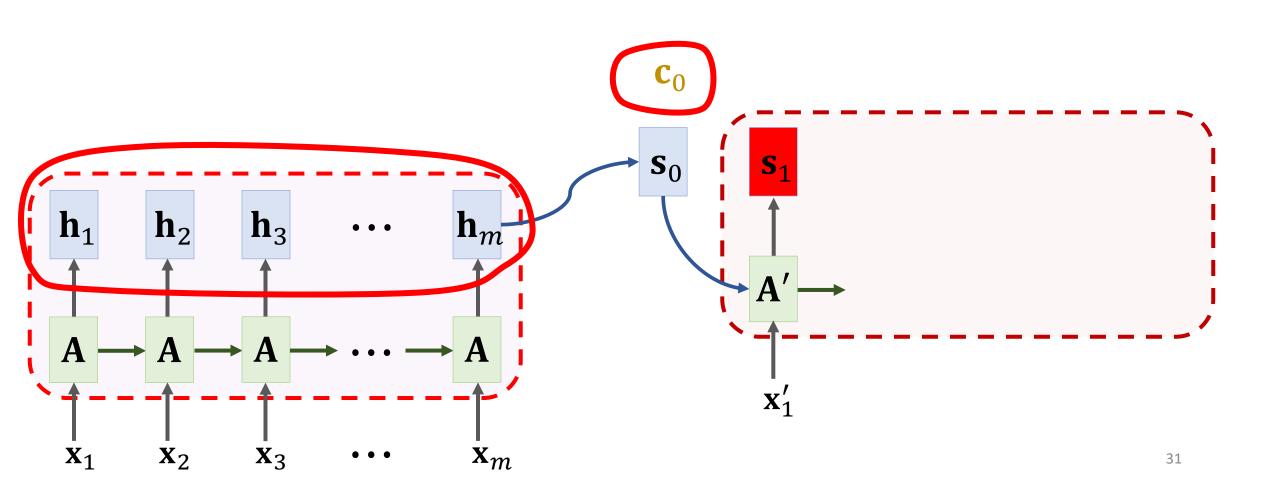


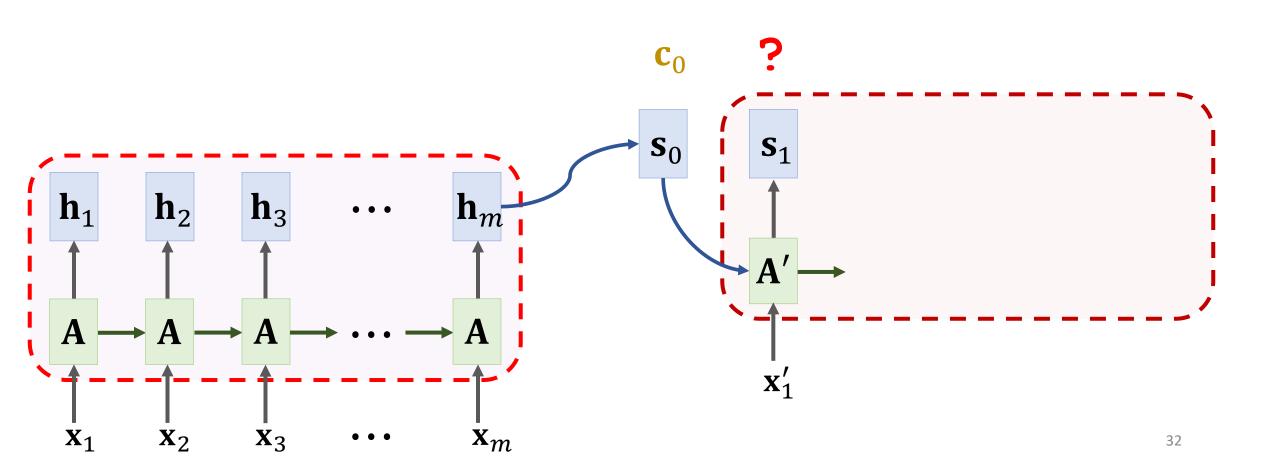
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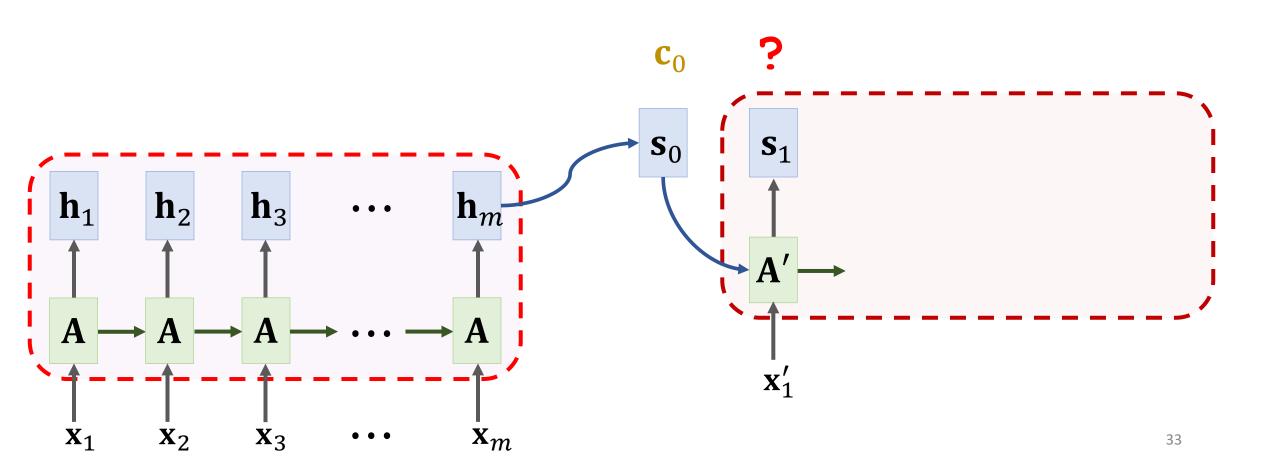




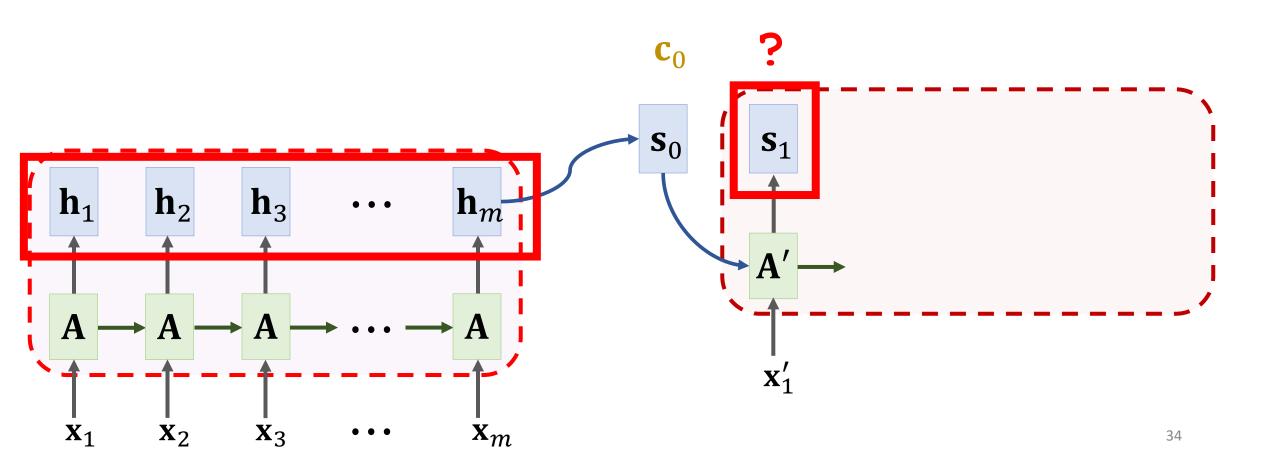




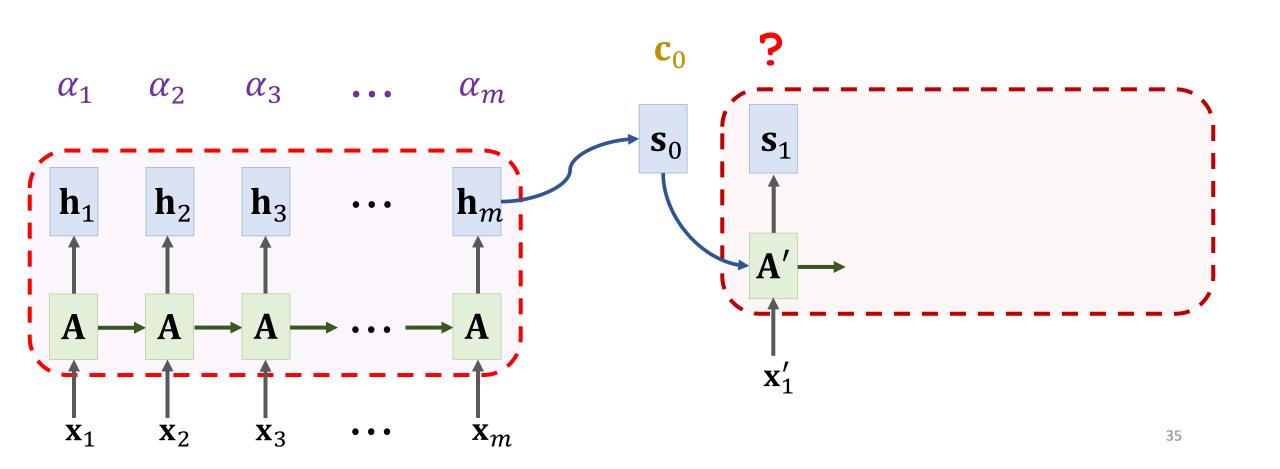
Weight: 
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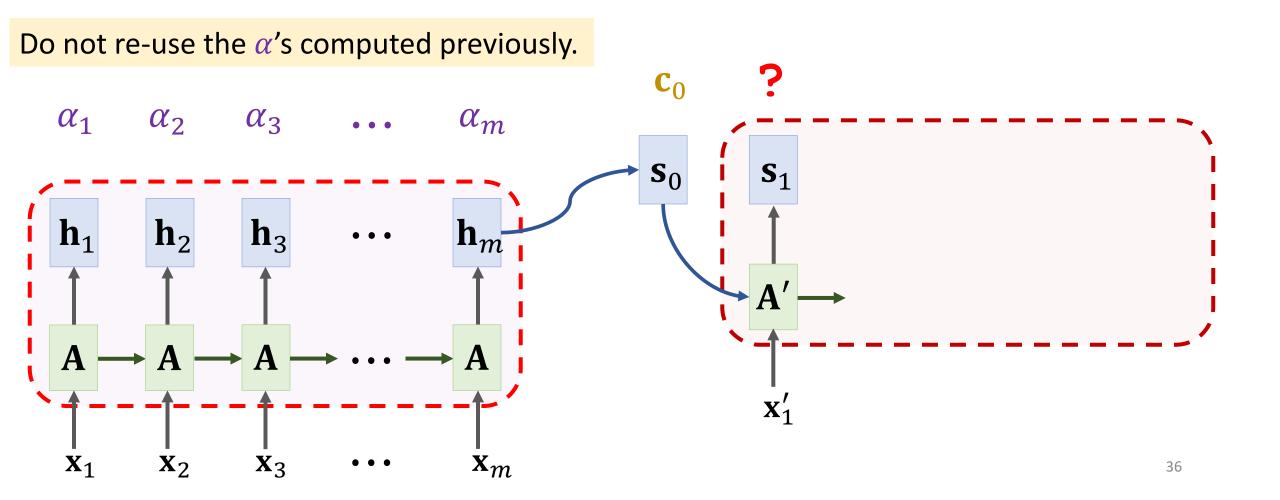
Weight: 
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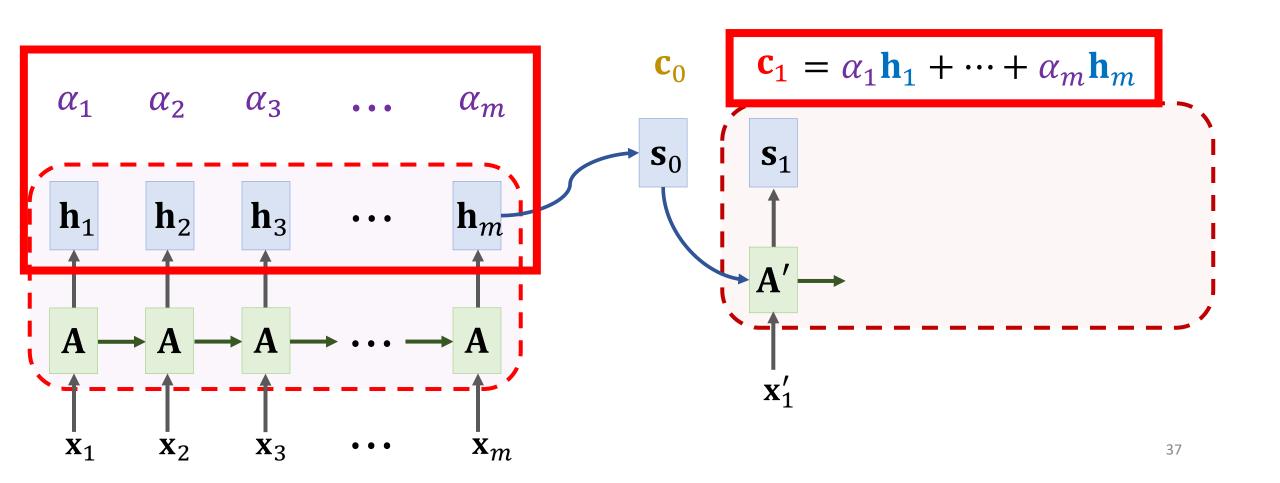
Weight:  $\alpha_i = \operatorname{align}(\mathbf{h}_i, \mathbf{s}_1)$ .

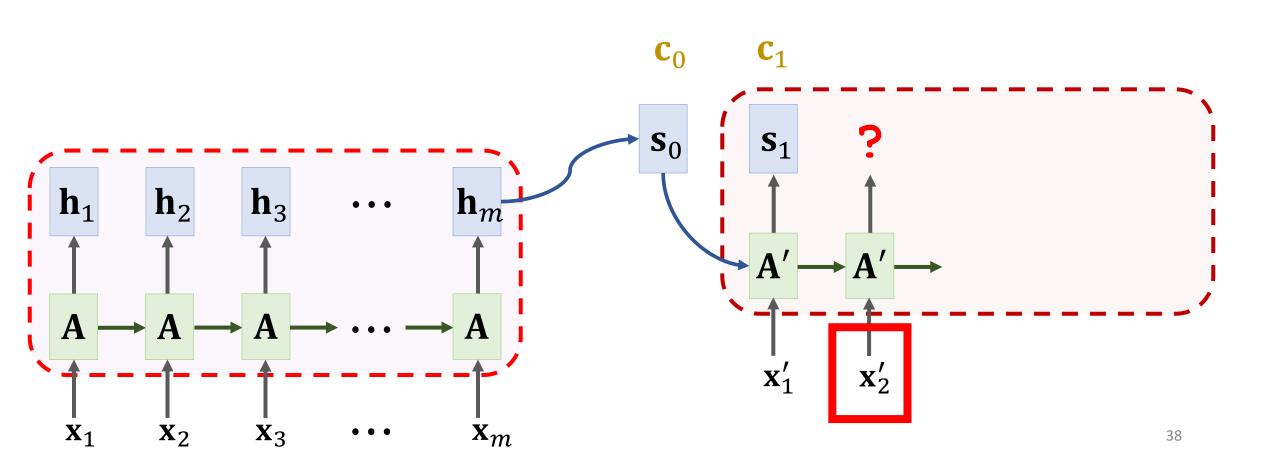


Weight:  $\alpha_i = \operatorname{align}(\mathbf{h}_i, \mathbf{s}_1)$ .

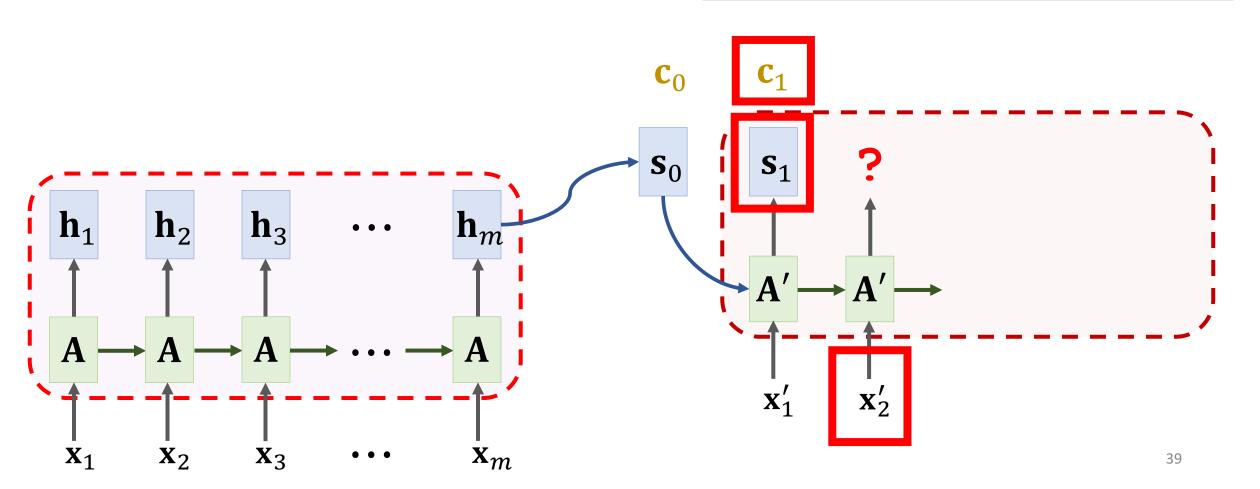


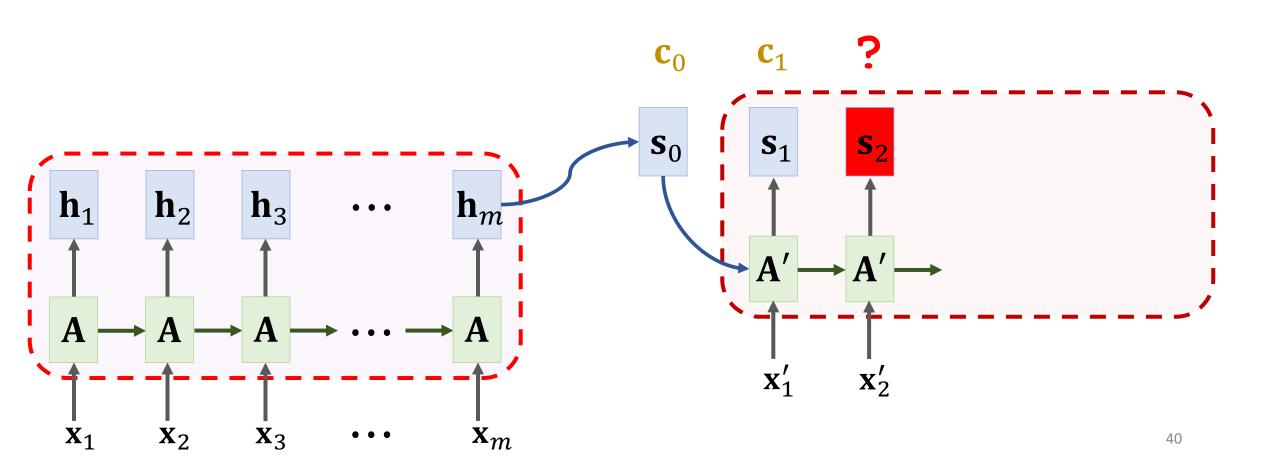
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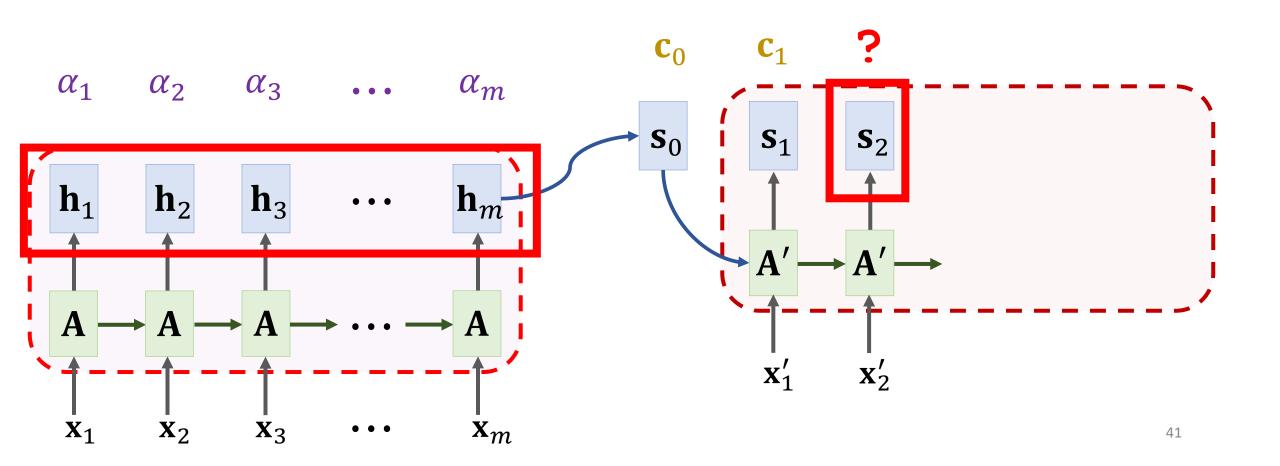


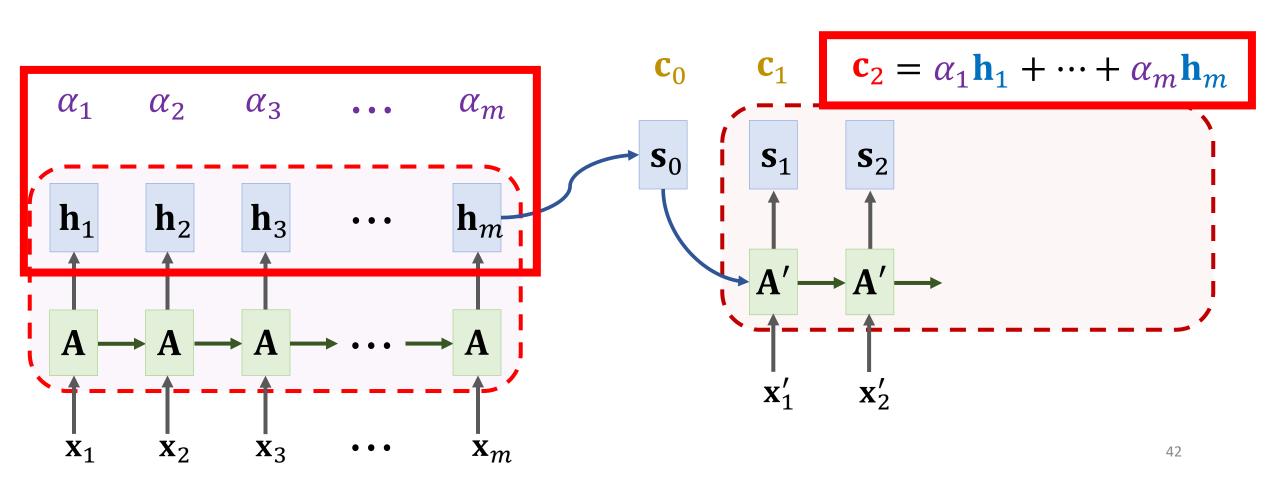


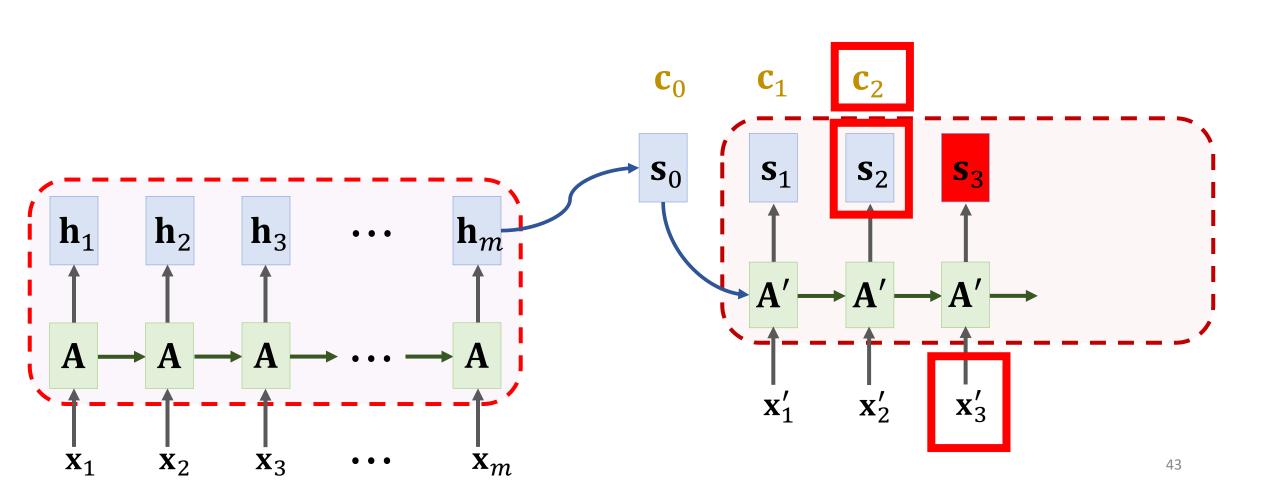
$$\mathbf{s_2} = \tanh\left(\mathbf{A'} \cdot \begin{bmatrix} \mathbf{x}_2' \\ \mathbf{s_1} \\ \mathbf{c_1} \end{bmatrix} + \mathbf{b}\right)$$

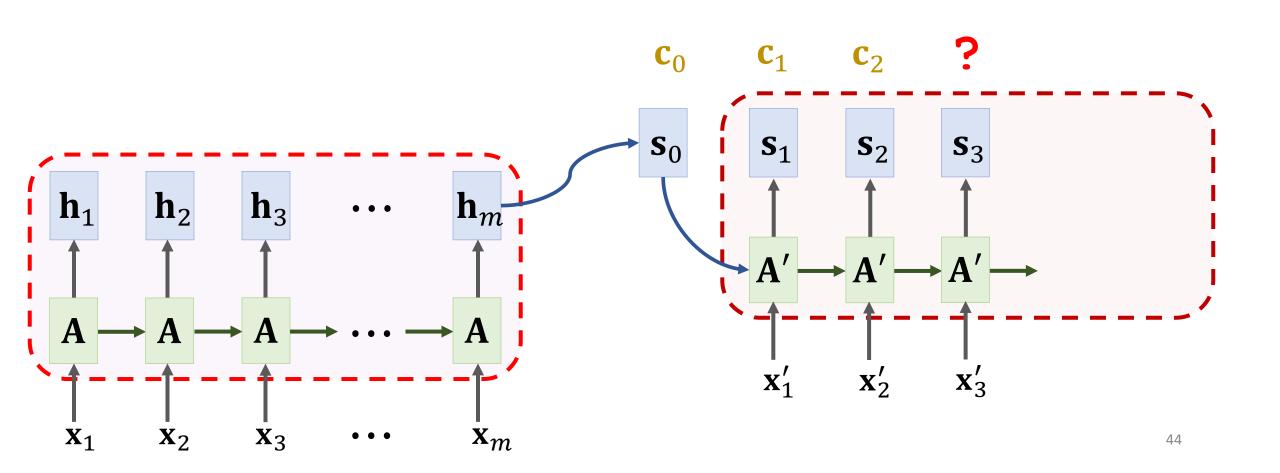


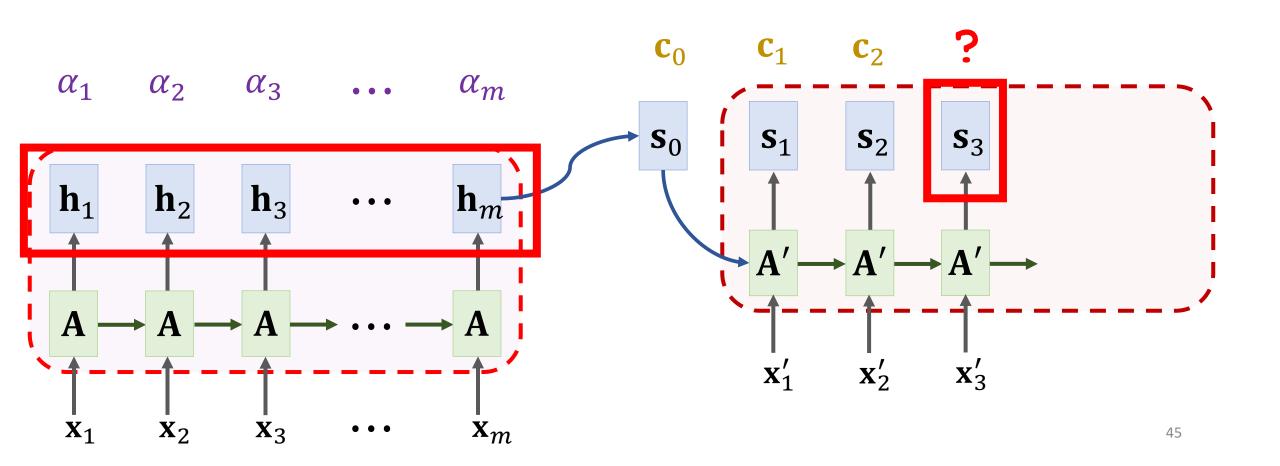


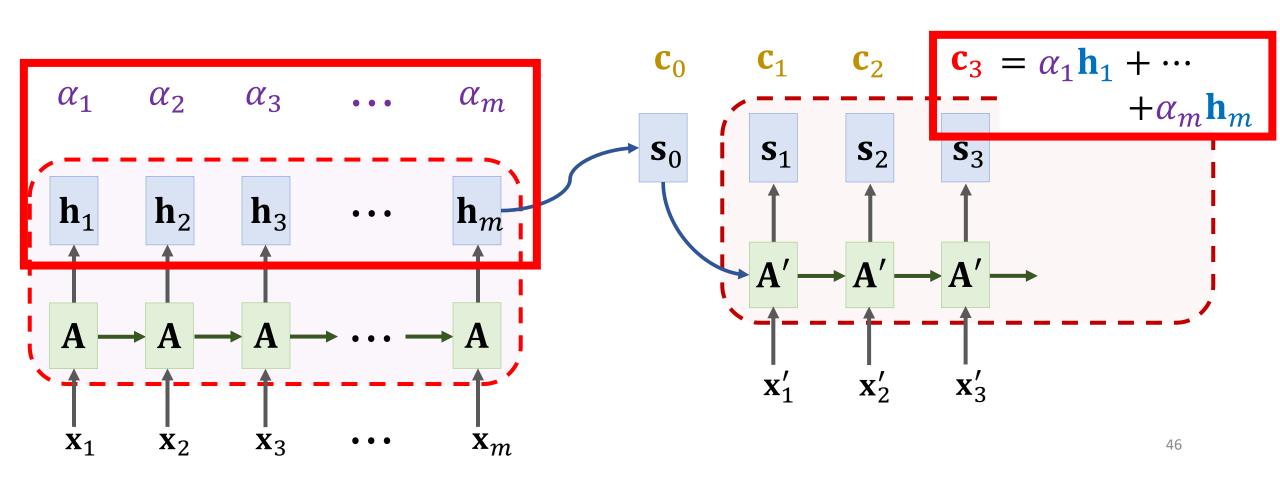


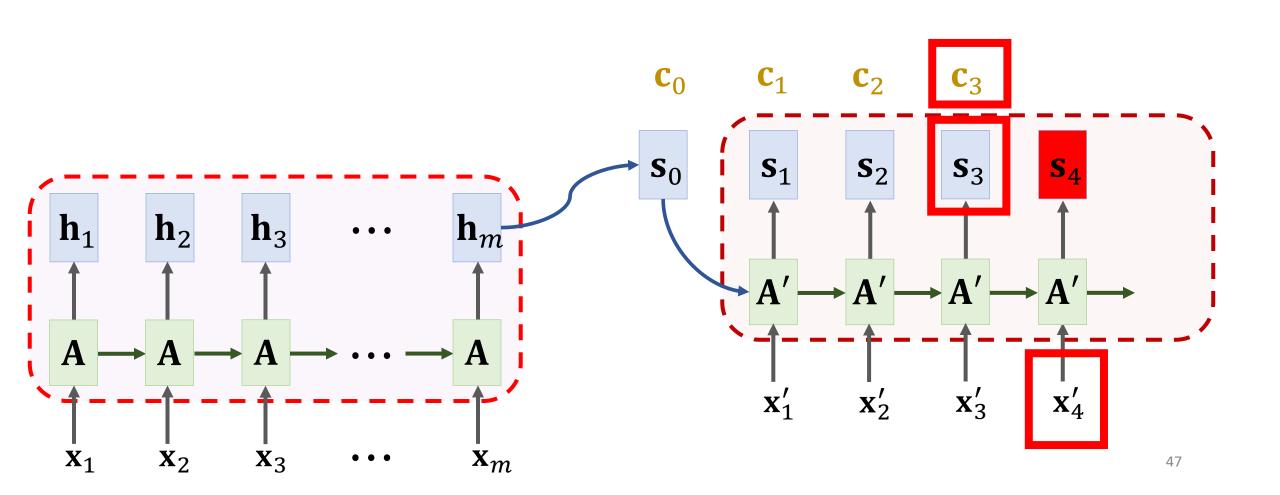


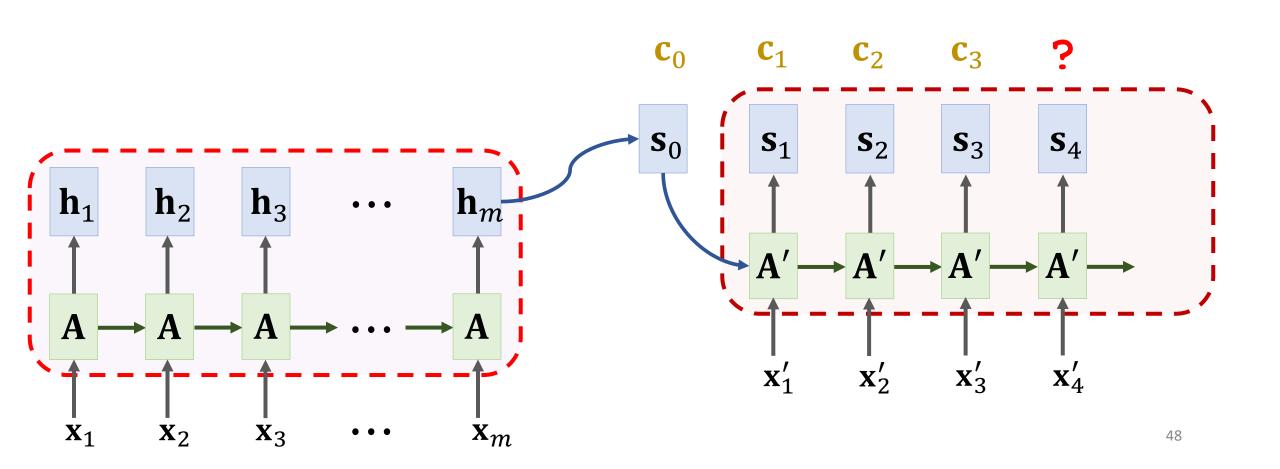


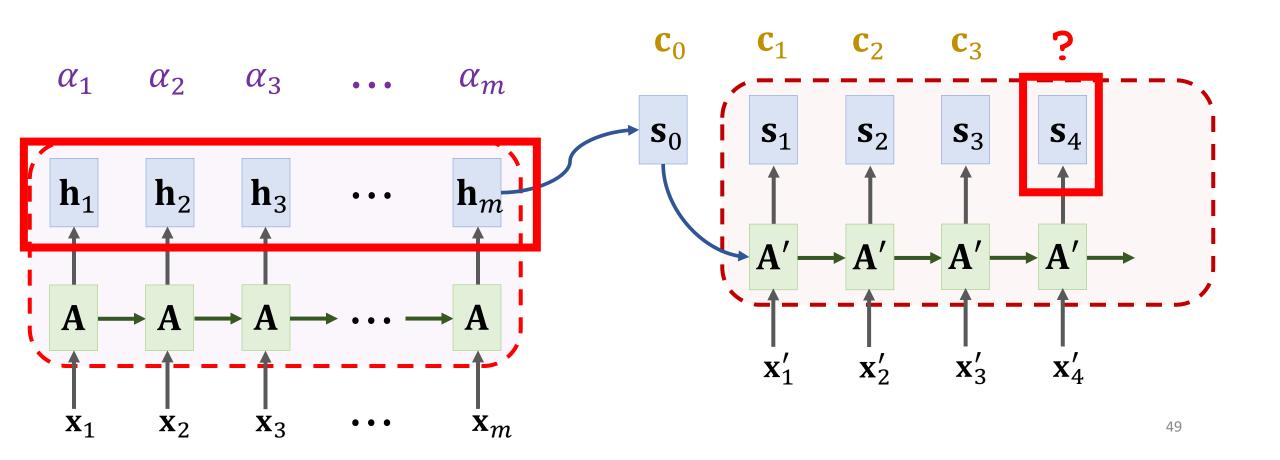


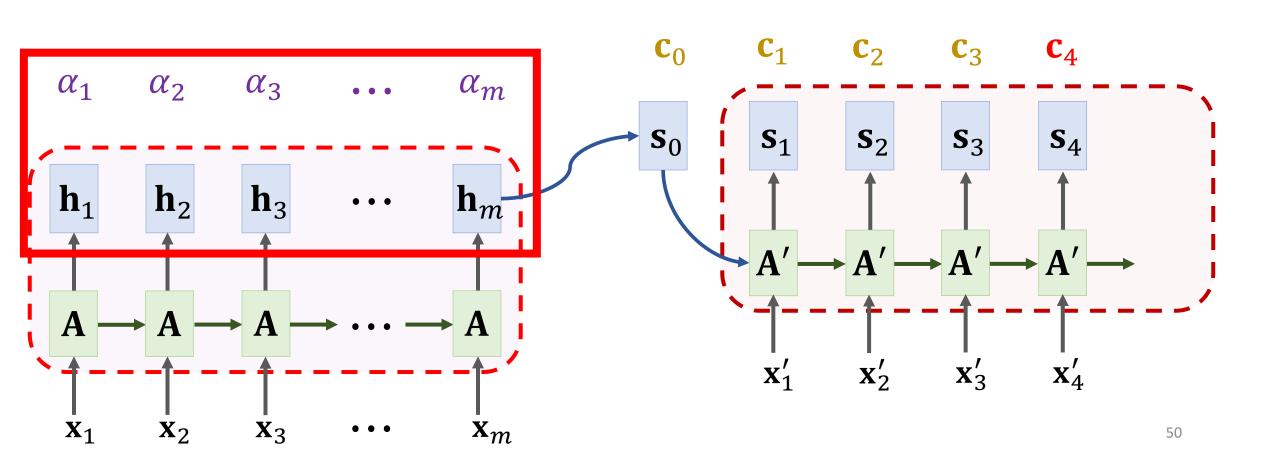


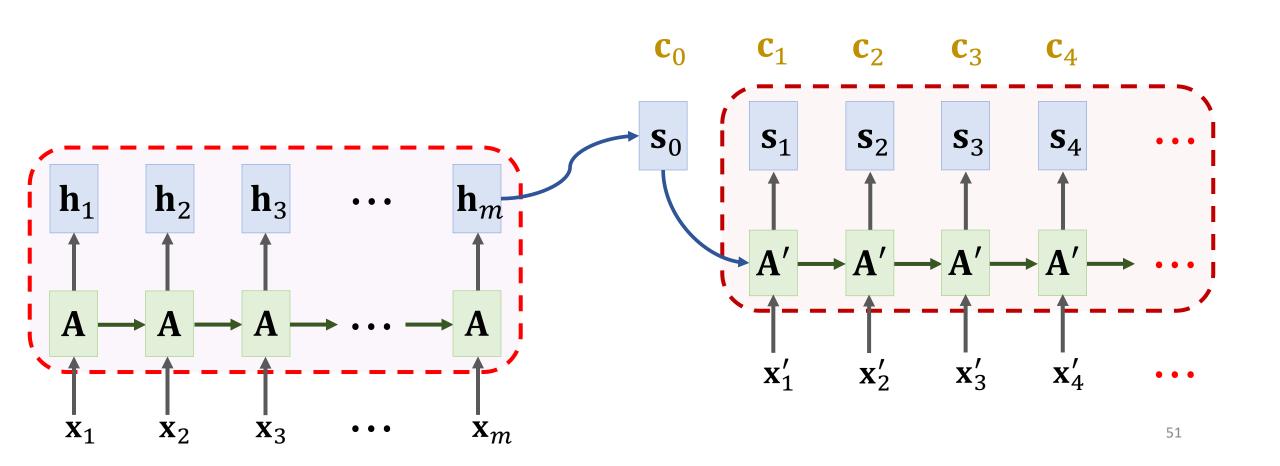






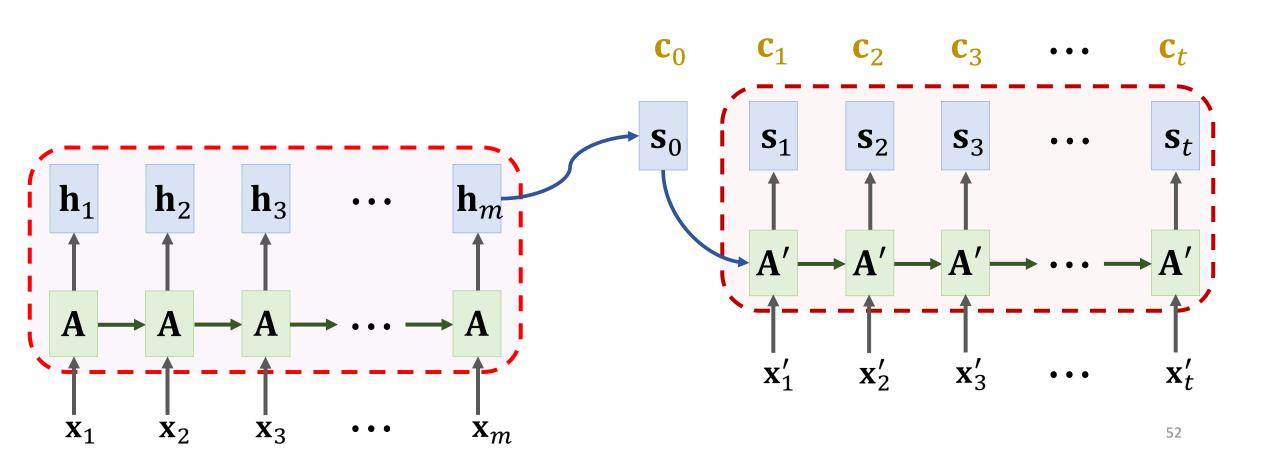






#### **Time Complexity**

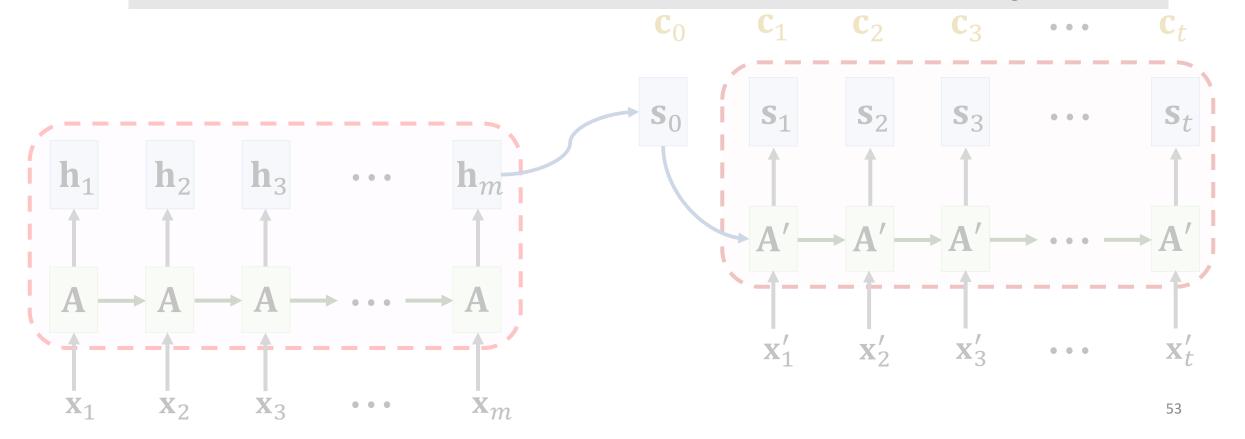
**Question:** What is the total number of  $\alpha$ 's we have computed?



#### **Time Complexity**

**Question:** What is the total number of  $\alpha$ 's we have computed?

- To compute one vector  $\mathbf{c}_{i}$ , we compute m weights:  $\alpha_{1}, \cdots, \alpha_{m}$ .
- The decode has *t* states, so there are a total of *mt* weights.



#### **Comparisons**

**Without Attention** 

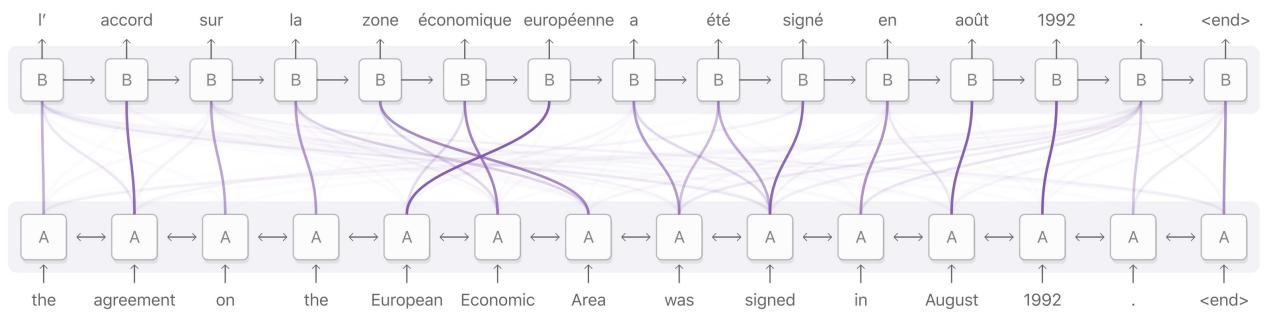
With Attention

Time complexity: O(m + t)

Time complexity: O(mt)

#### **Attention: Weights Visualization**

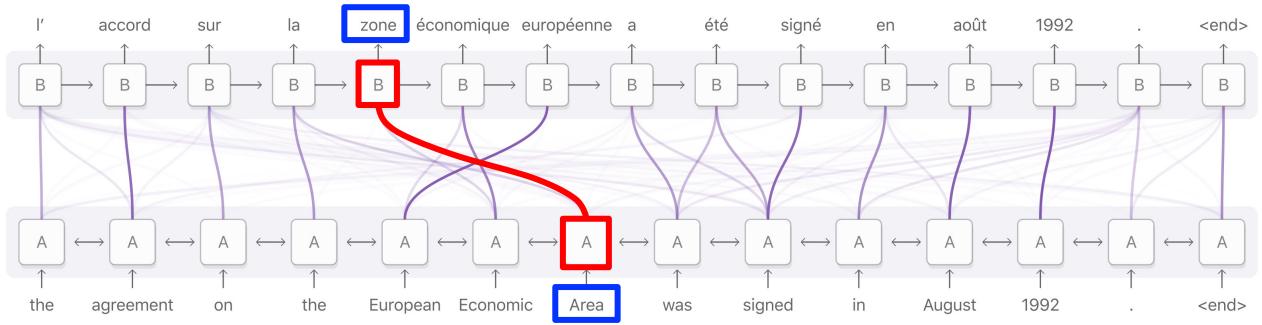
#### **Decoder RNN** (target language: French)



**Encoder RNN** (source language: English)

#### **Attention: Weights Visualization**

#### **Decoder RNN** (target language: French)



**Encoder RNN** (source language: English)

• Standard Seq2Seq model: the decoder looks at only its current state.

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- Attention: decoder additionally looks at all the states of the encoder.
- Attention: decoder knows where to focus.

- Downside: higher time complexity.
  - *m*: source sequence length
  - t: target sequence length
  - Standard Seq2Seq: O(m+t) time complexity
  - Seq2Seq + attention: O(mt) time complexity

# **Self-Attention for RNNs**

#### **Self-Attention**

- Self-Attention [2]: attention [1] beyond Seq2Seq models.
- The self-attention paper uses LSTM.
- To make teaching easy, I replace LSTM by SimpleRNN.

#### **Original paper:**

- Bahdanau, Cho, & Bengio. Neural machine translation by jointly learning to align and translate. In ICLR, 2015.
- Cheng, Dong, & Lapata. Long Short-Term Memory-Networks for Machine Reading. In EMNLP, 2016.

$$\mathbf{c}_0 = \mathbf{0}$$







#### SimpleRNN:

$$\mathbf{h}_1 = \tanh\left(\mathbf{A} \cdot \begin{bmatrix} \mathbf{X}_1 \\ \mathbf{h}_0 \end{bmatrix} + \mathbf{b}\right)$$

 $\mathbf{c}_0$ 



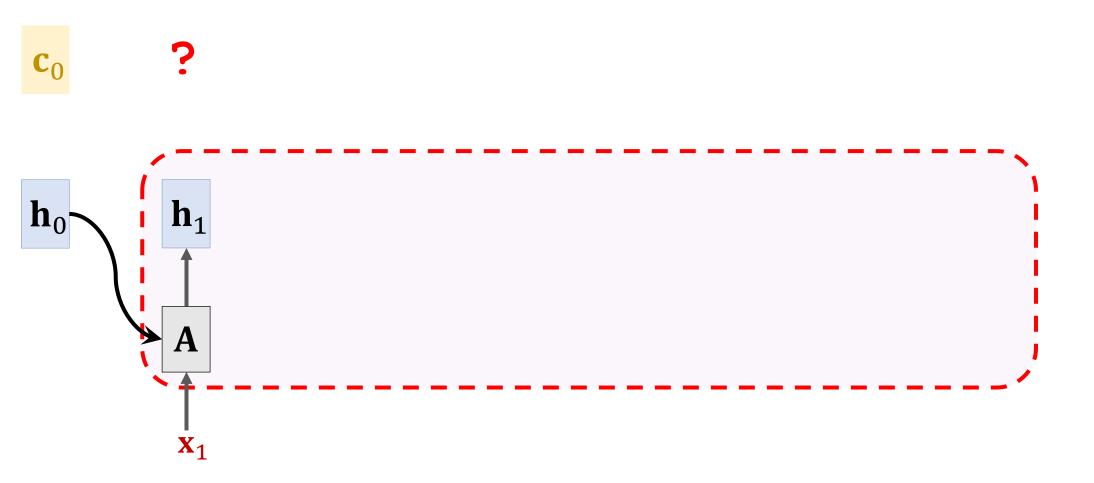
#### SimpleRNN:

$$\mathbf{h}_1 = \tanh\left(\mathbf{A} \cdot \begin{bmatrix} \mathbf{X}_1 \\ \mathbf{h}_0 \end{bmatrix} + \mathbf{b}\right)$$

#### **SimpleRNN** + **Self-Attention**:

$$\mathbf{h_1} = \tanh\left(\mathbf{A} \cdot \begin{bmatrix} \mathbf{X_1} \\ \mathbf{c_0} \end{bmatrix} + \mathbf{b}\right)$$



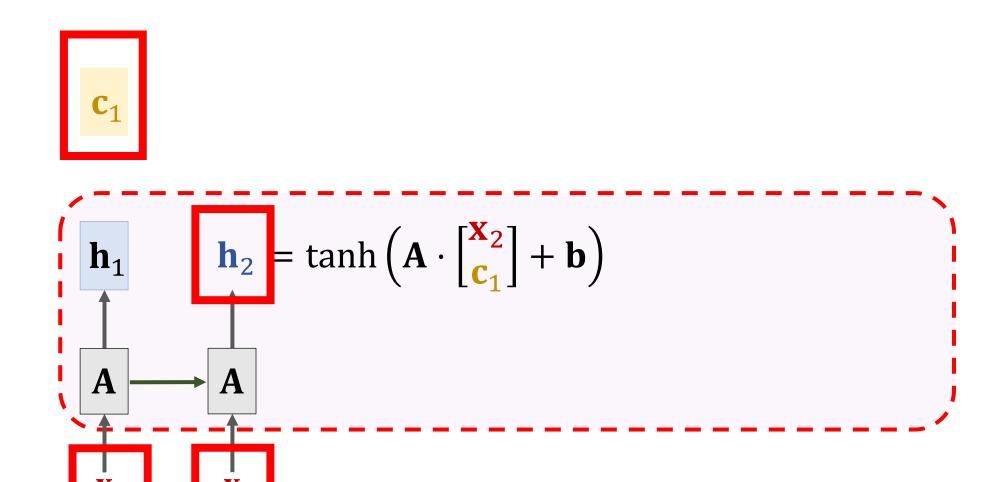




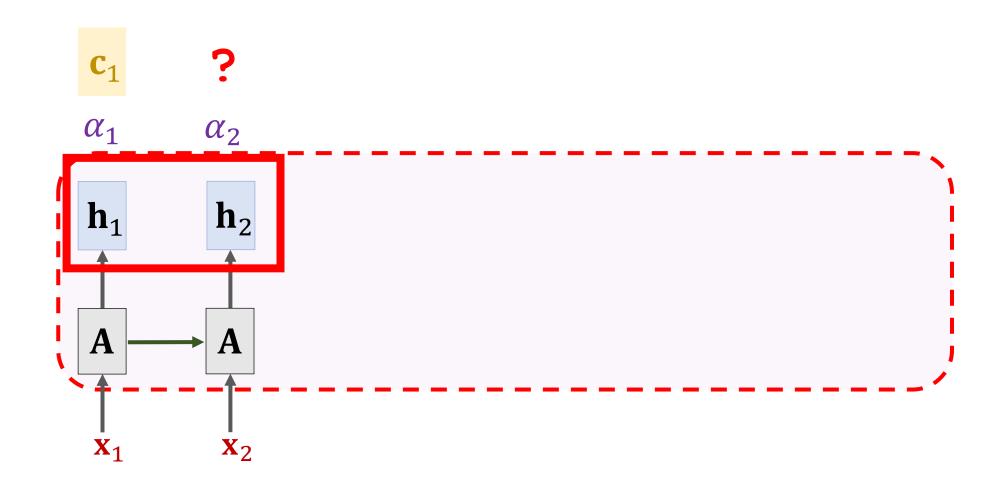


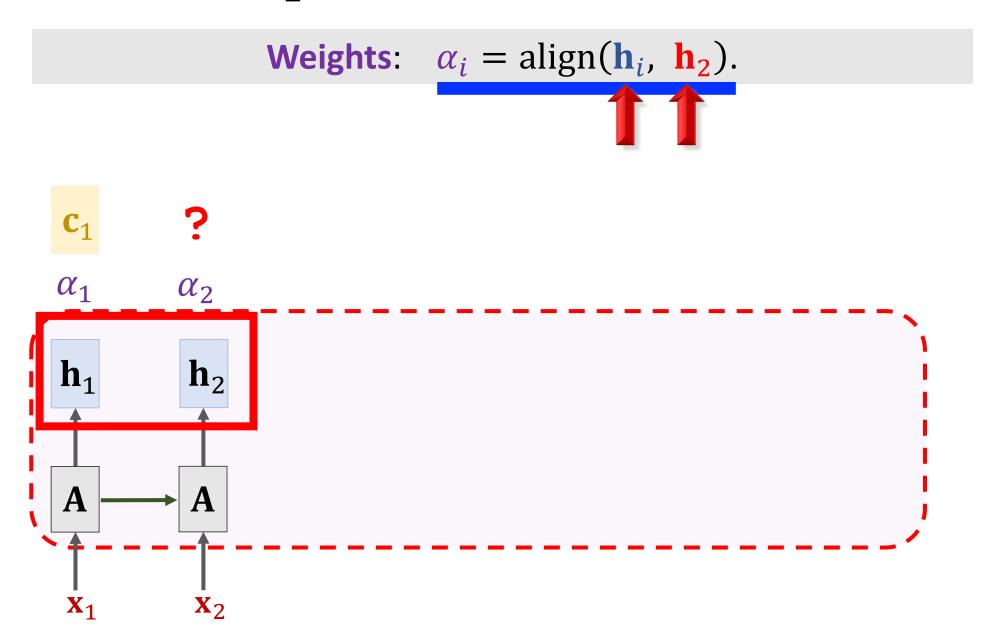
 $\mathbf{c}_1$ 

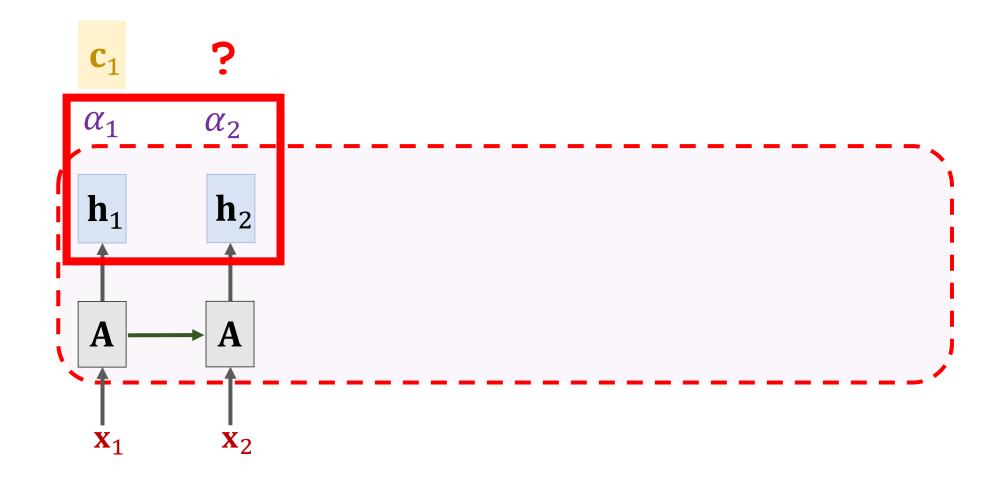


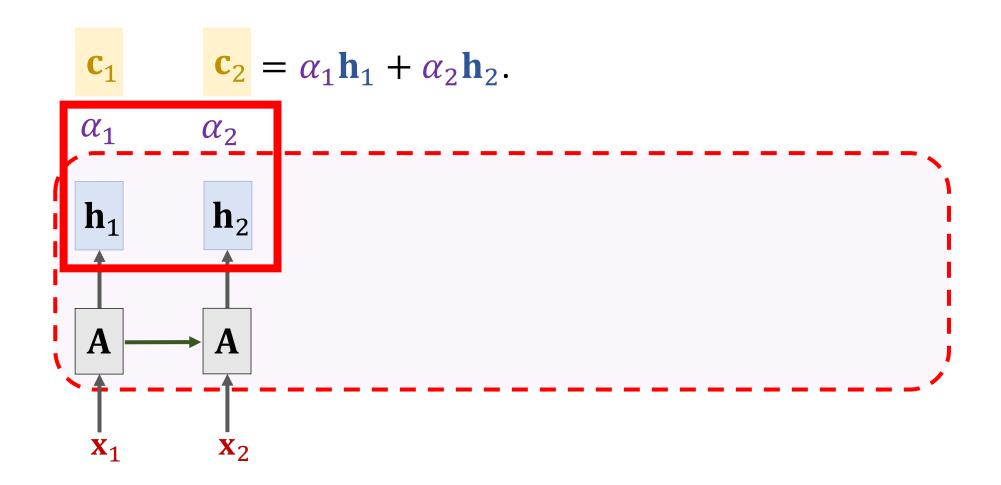


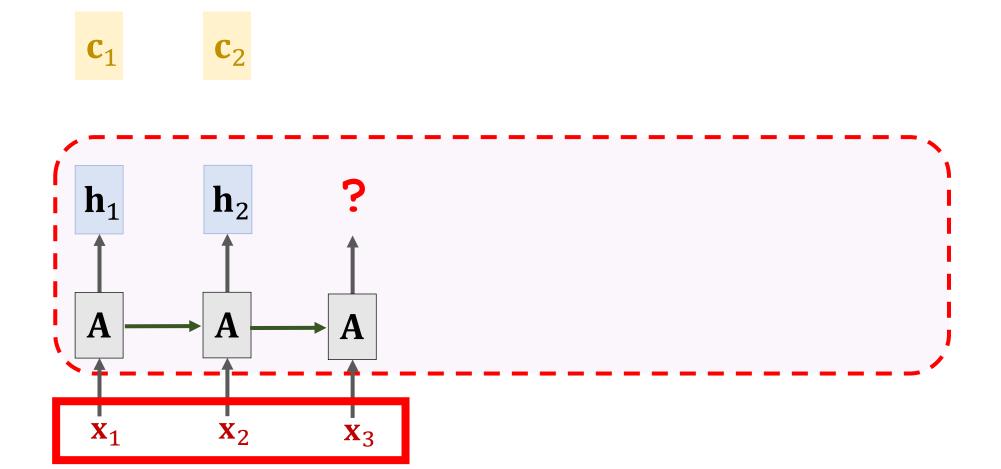


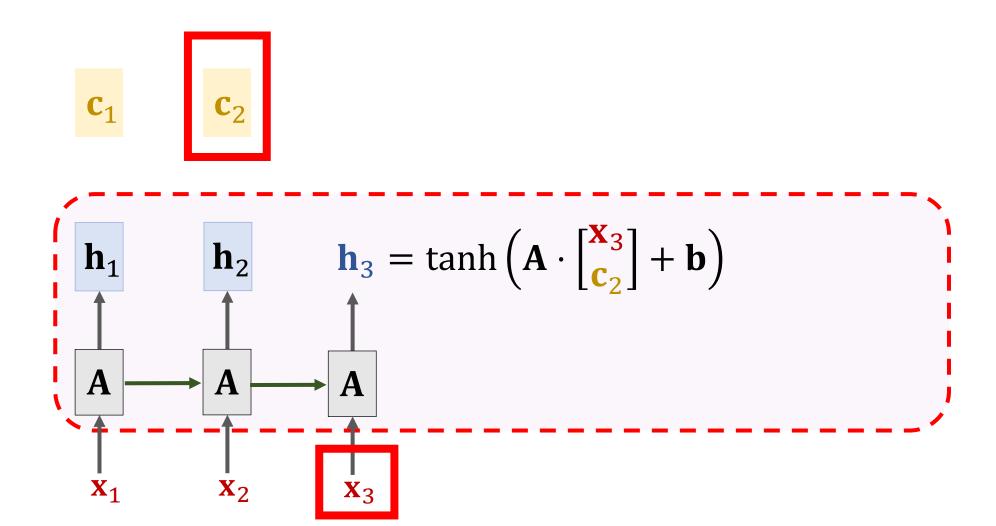


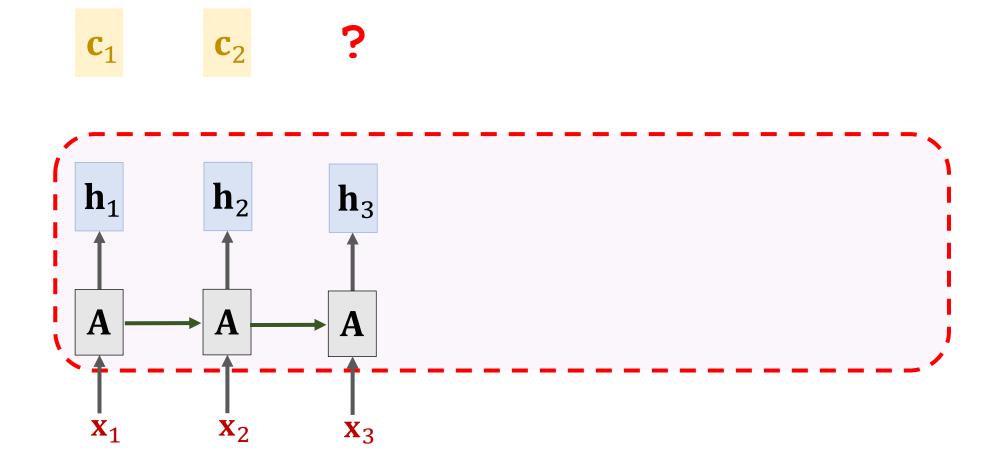


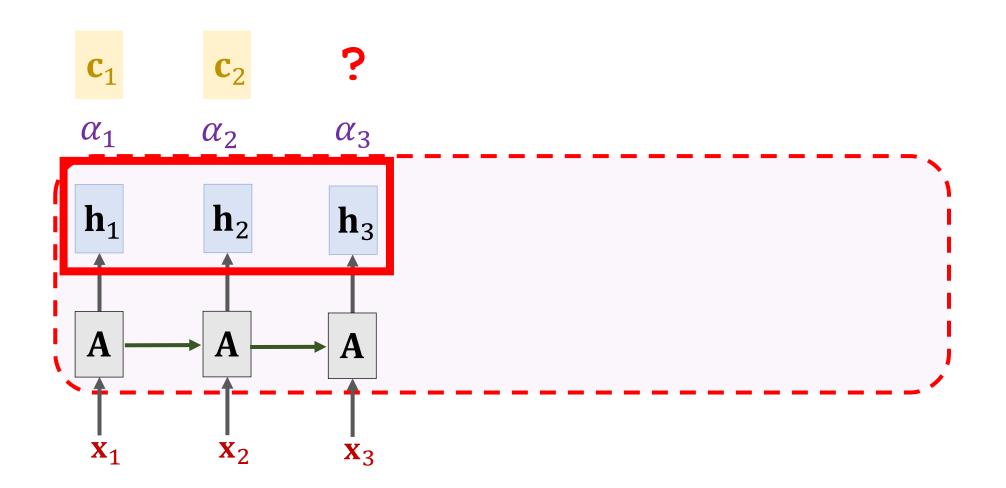


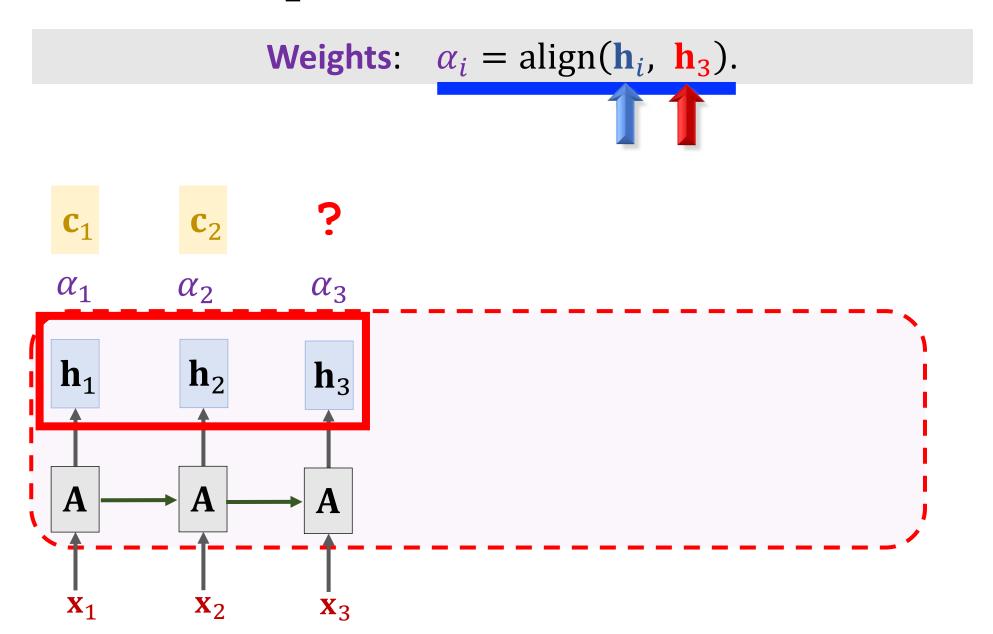


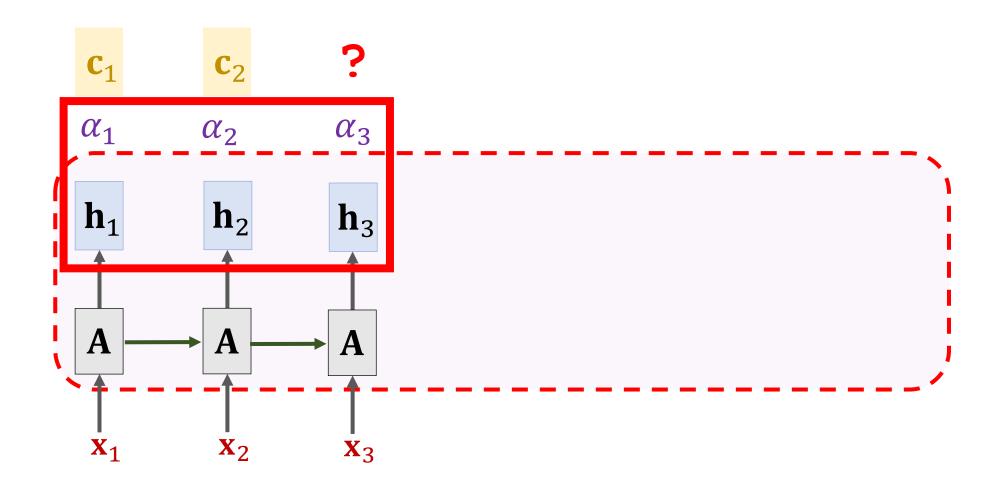


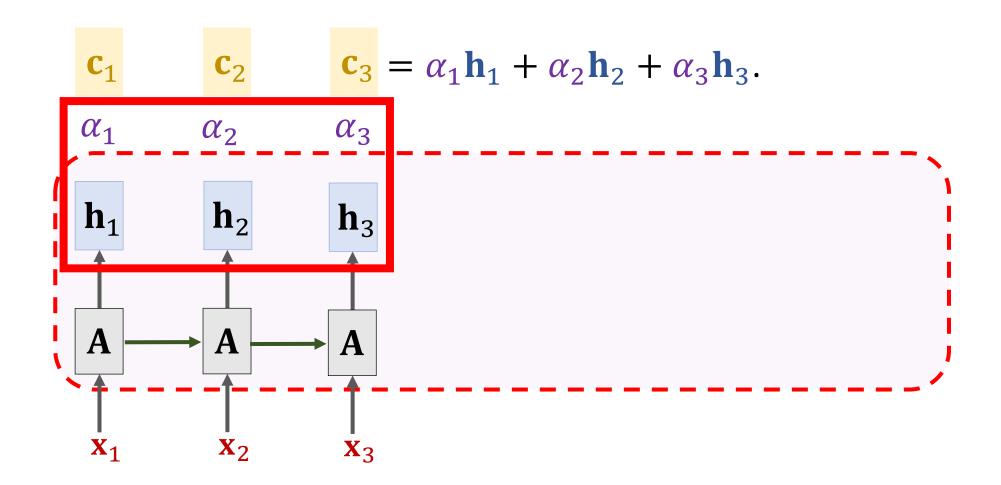


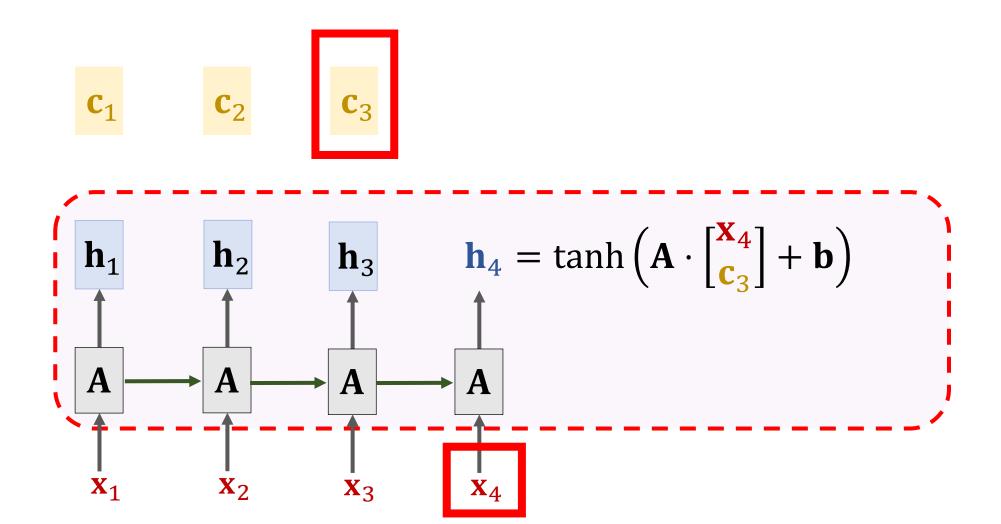


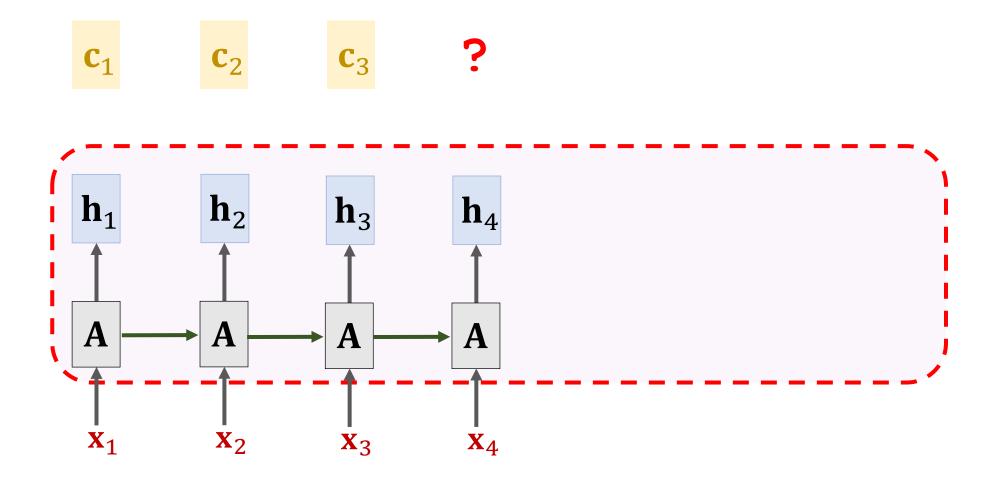




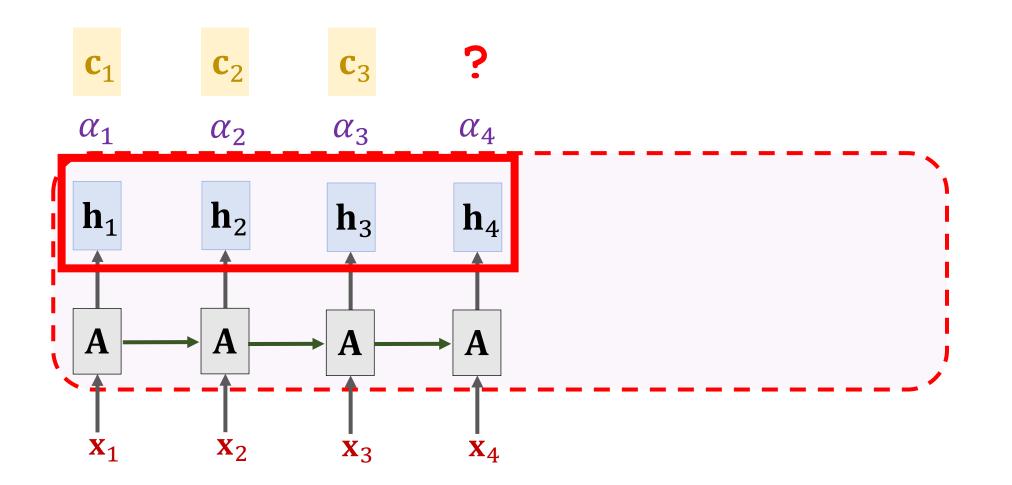


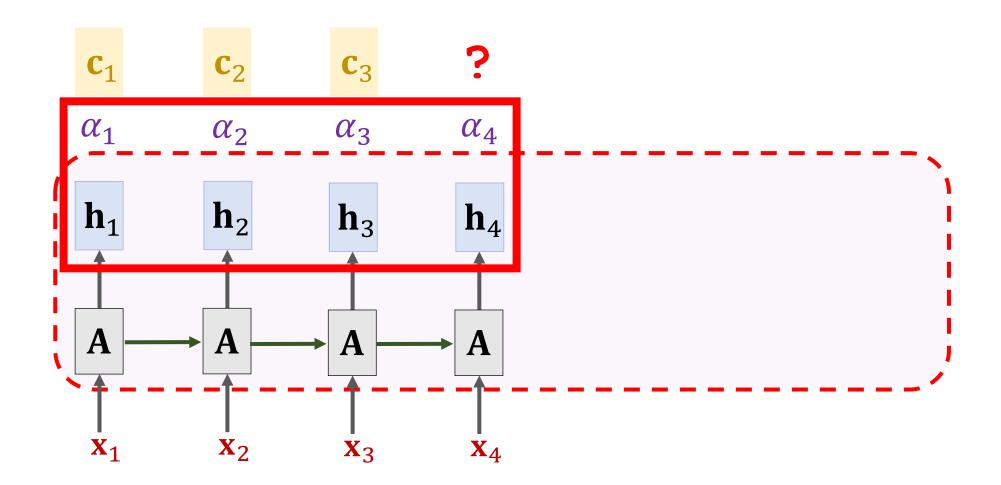




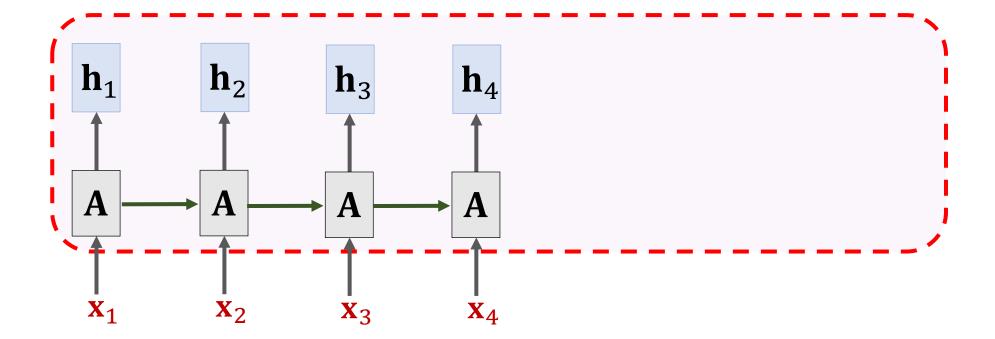


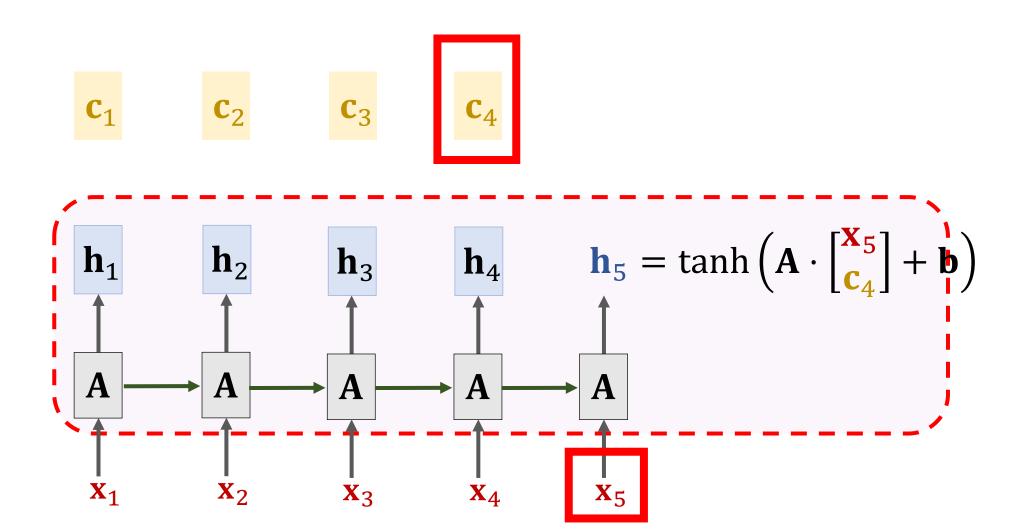
Weights:  $\alpha_i = \text{align}(\mathbf{h}_i, \mathbf{h}_4)$ .

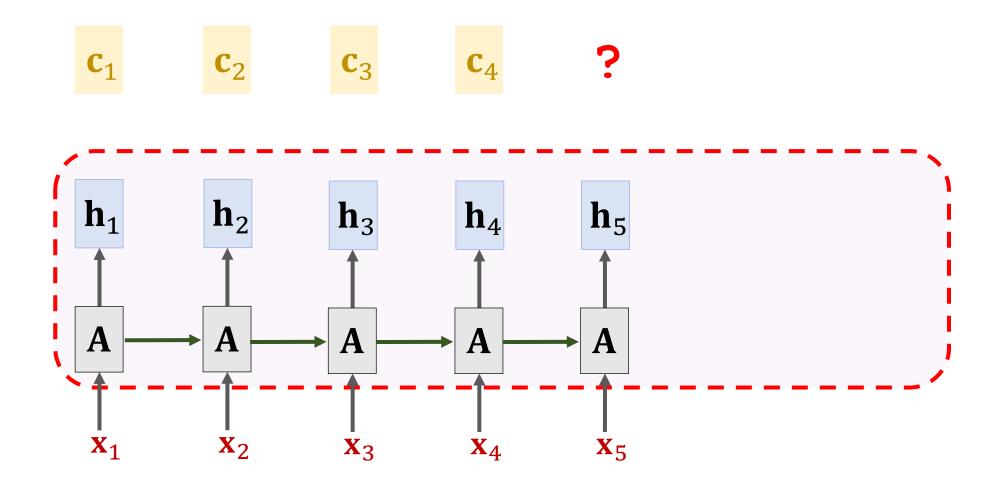




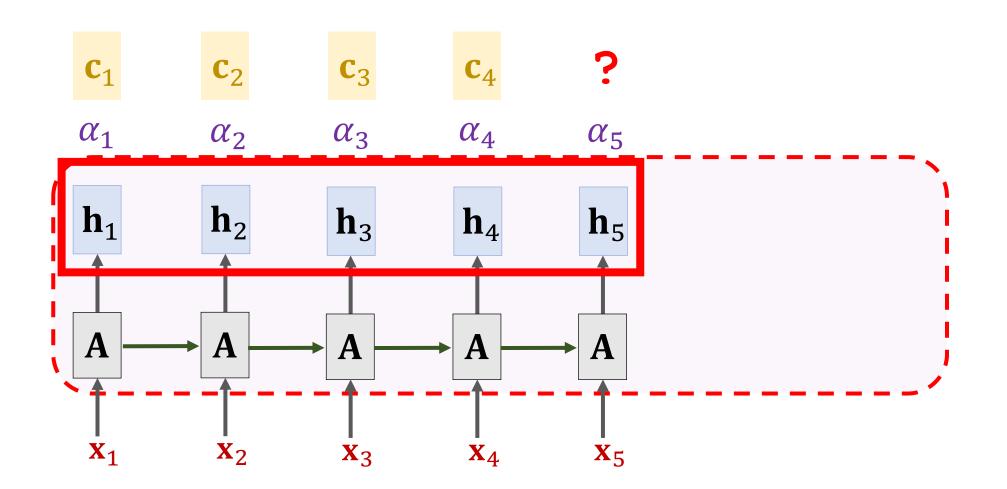
 $\mathbf{c}_1 \qquad \mathbf{c}_2 \qquad \mathbf{c}_3 \qquad \mathbf{c}_4 = \alpha_1 \mathbf{h}_1 + \alpha_2 \mathbf{h}_2 + \alpha_3 \mathbf{h}_3 + \alpha_4 \mathbf{h}_4.$ 

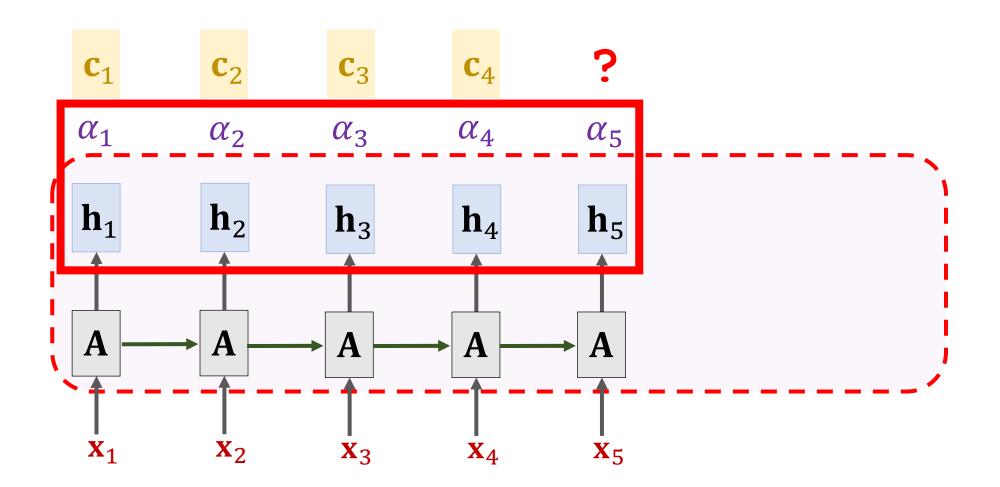


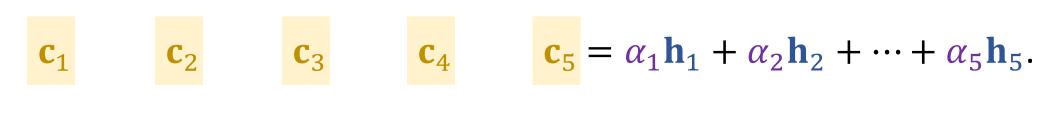


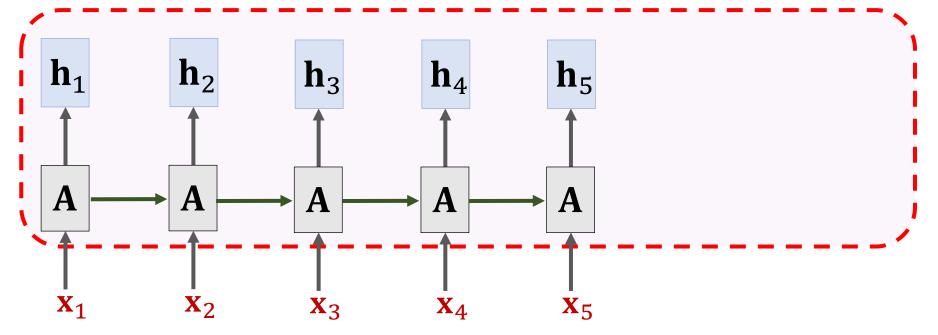


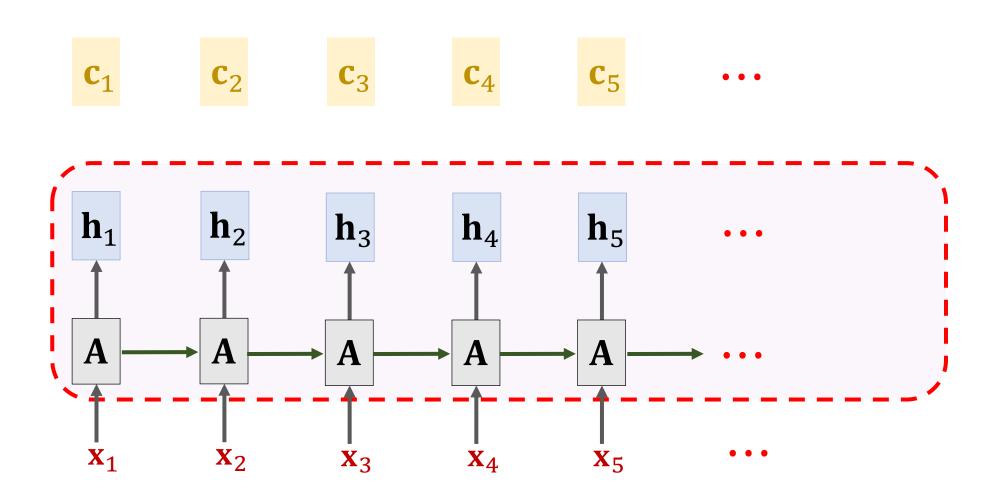
Weights:  $\alpha_i = \text{align}(\mathbf{h}_i, \mathbf{h}_5)$ .











# Summary

• With self-attention, RNN is less likely to forget.

#### Summary

- With self-attention, RNN is less likely to forget.
- Pay attention to the context relevant to the new input.

```
The
The FBI
    FBI is
The
    FBI is chasing
The
The
    FBI is
            chasing a
    FBI is chasing a criminal
The
    FBI is chasing a
                       criminal on
The
            chasing a
    FBI is
                       criminal on the
The
                       criminal on
    FBI is
            chasing a
                                   the run
The
            chasing a
The
    FBI
                       criminal
                               on the run.
```

Figure is from the paper "Long Short-Term Memory-Networks for Machine Reading."

# Transformer Model: Attention without RNN

#### **Transformer Model**

 Original paper: Vaswani et al. Attention Is All You Need. In NIPS, 2017.

#### **Attention Is All You Need**

Ashish Vaswani\* Google Brain avaswani@google.com Noam Shazeer\*
Google Brain
noam@google.com

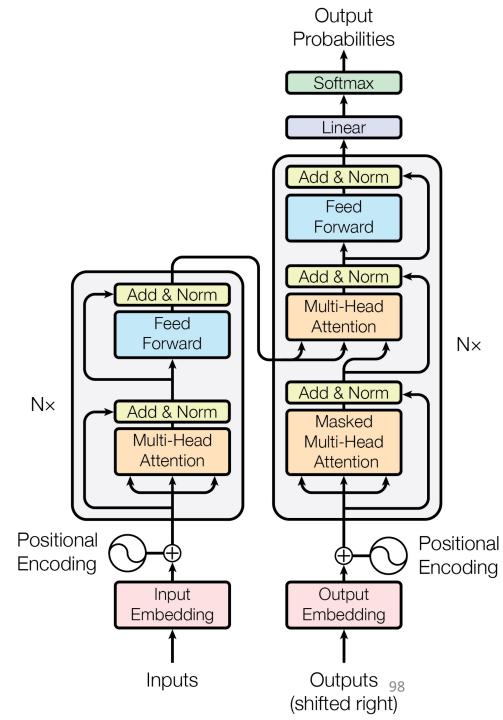
Niki Parmar\* Google Research nikip@google.com Jakob Uszkoreit\* Google Research usz@google.com

Llion Jones\*
Google Research
llion@google.com

Aidan N. Gomez\* †
University of Toronto
aidan@cs.toronto.edu

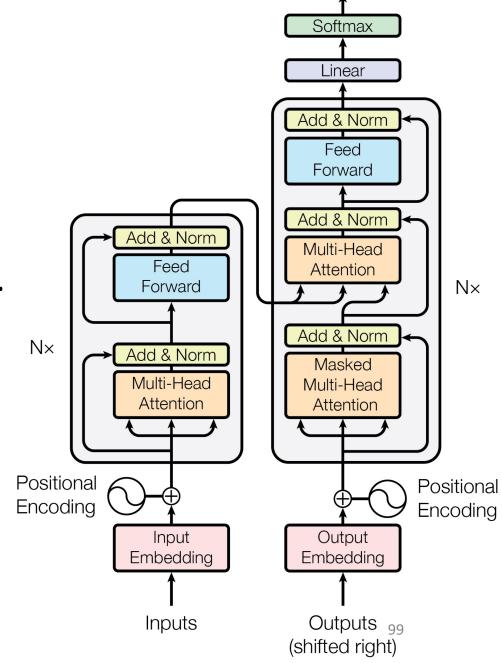
Łukasz Kaiser\* Google Brain lukaszkaiser@google.com

Illia Polosukhin\* † illia.polosukhin@gmail.com



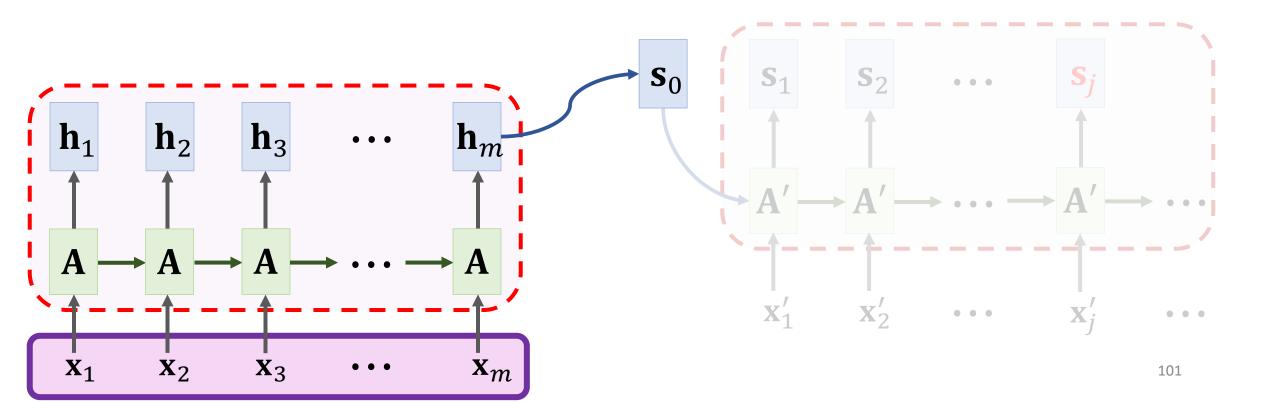
#### **Transformer Model**

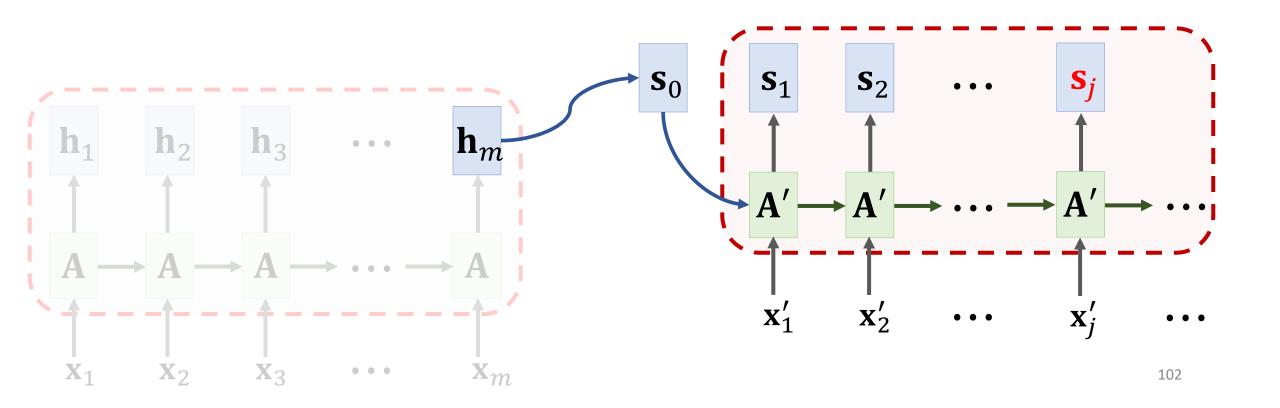
- Transformer is a Seq2Seq model.
- Transformer is not RNN.
- Purely based on attention and dense layers.
- Higher accuracy than RNNs on large datasets.

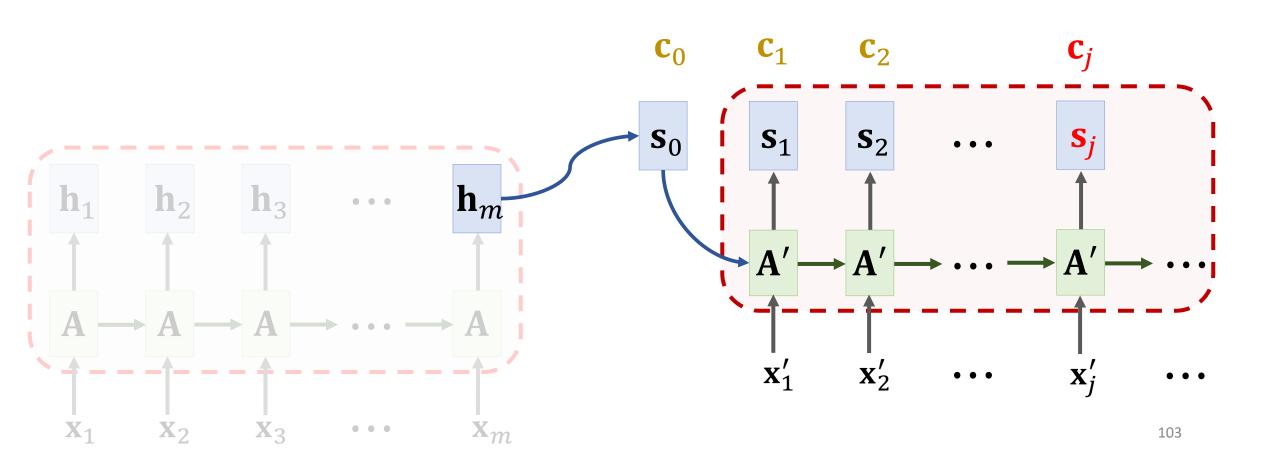


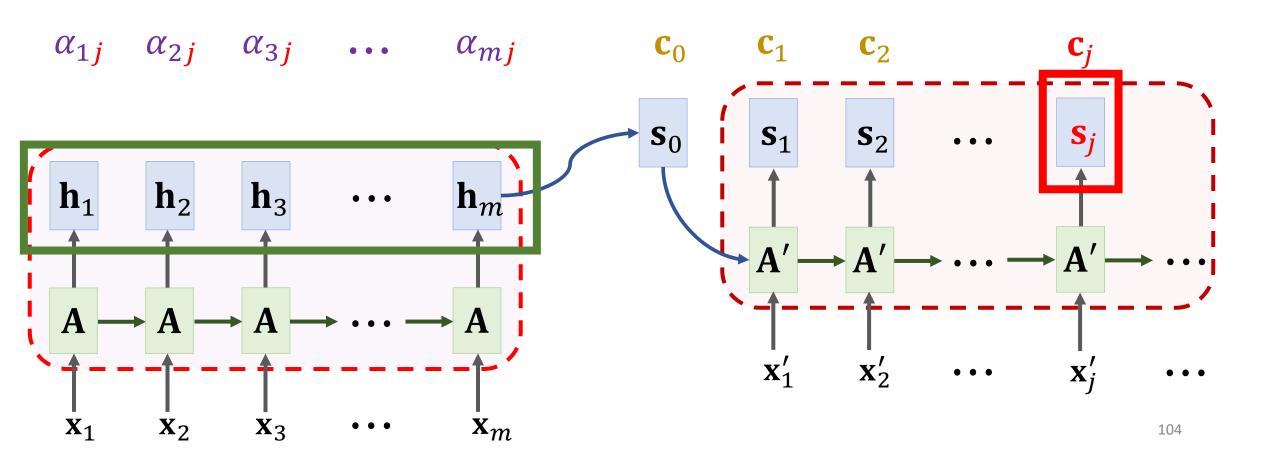
Output Probabilities

# **Revisiting Attention for RNN**

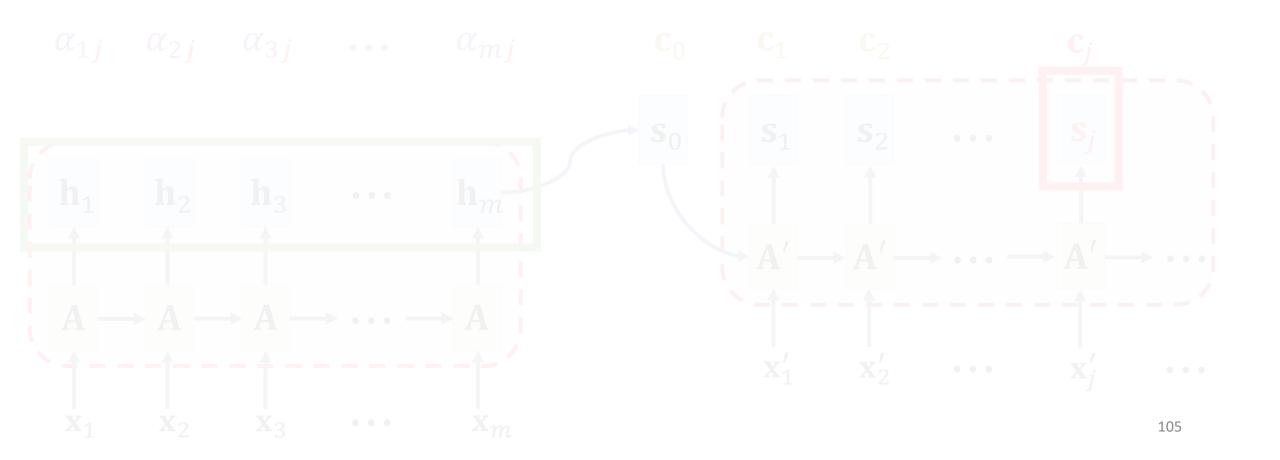


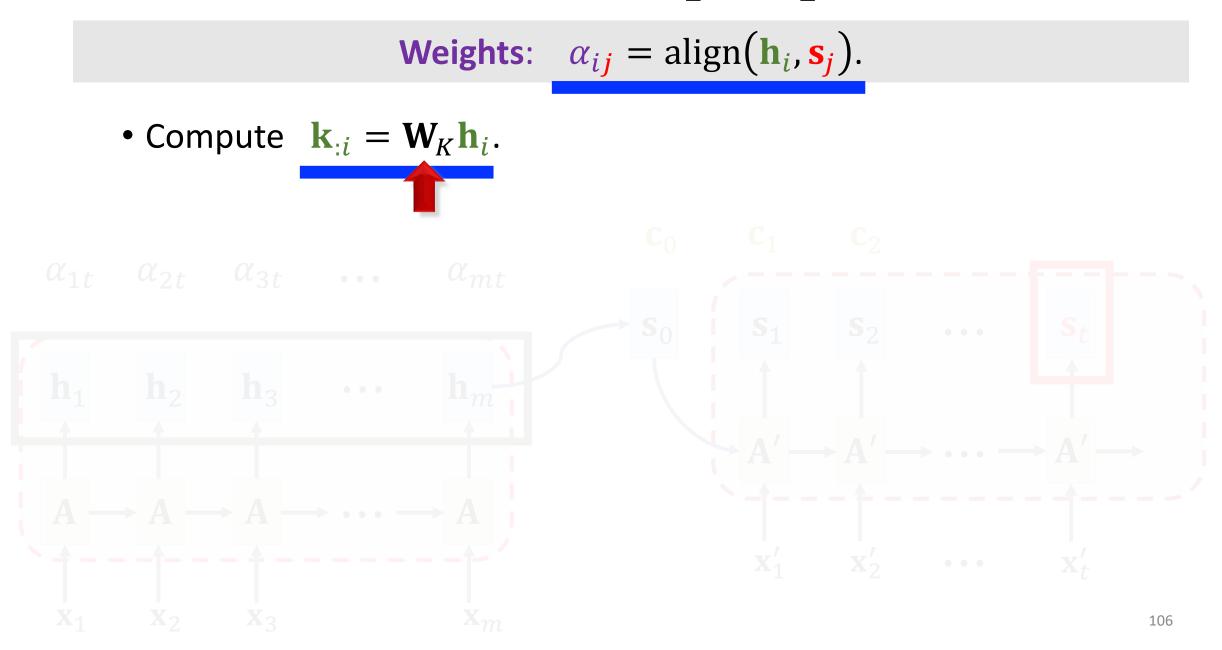






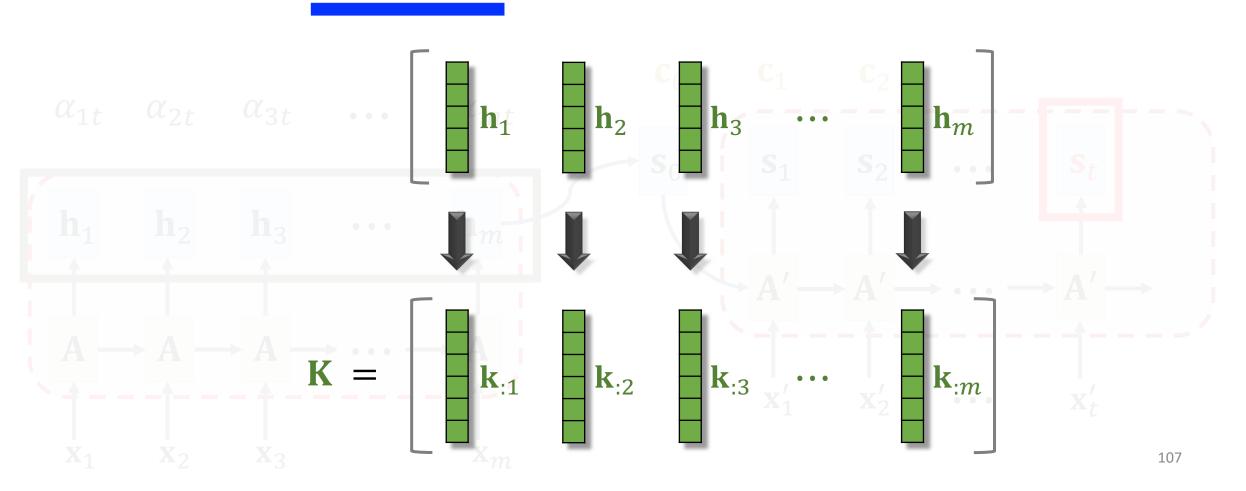
Weights: 
$$\alpha_{ij} = \operatorname{align}(\mathbf{h}_i, \mathbf{s}_j)$$
.

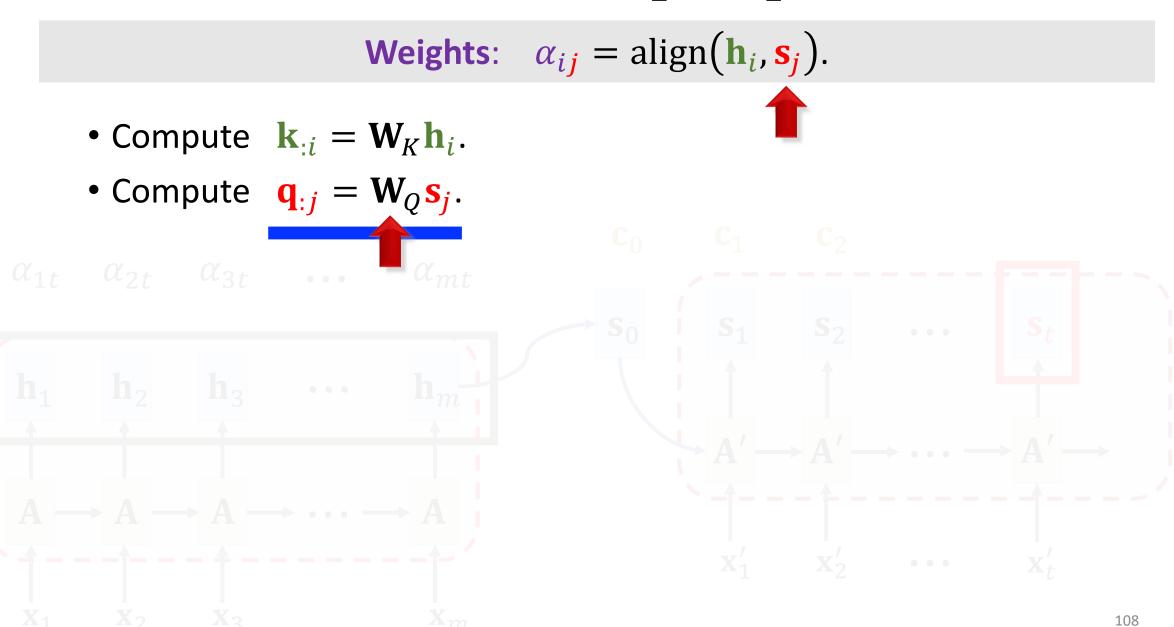




Weights: 
$$\alpha_{ij} = \operatorname{align}(\mathbf{h}_i, \mathbf{s}_j)$$
.

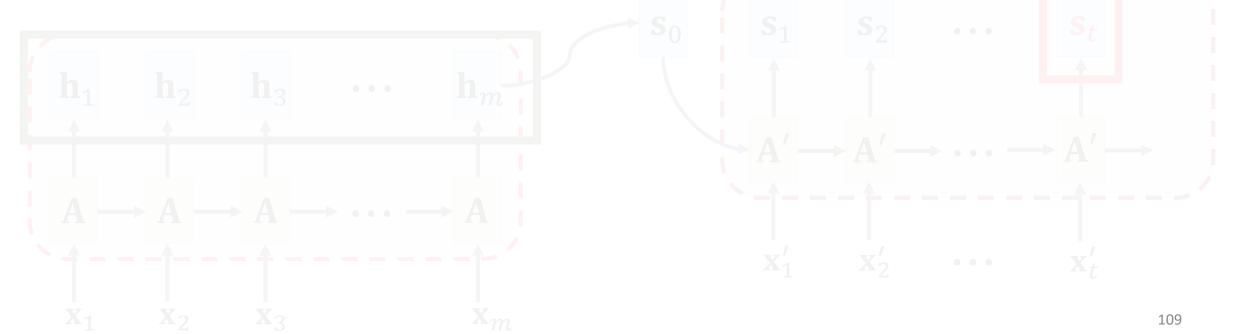
• Compute  $\mathbf{k}_{:i} = \mathbf{W}_K \mathbf{h}_i$ .





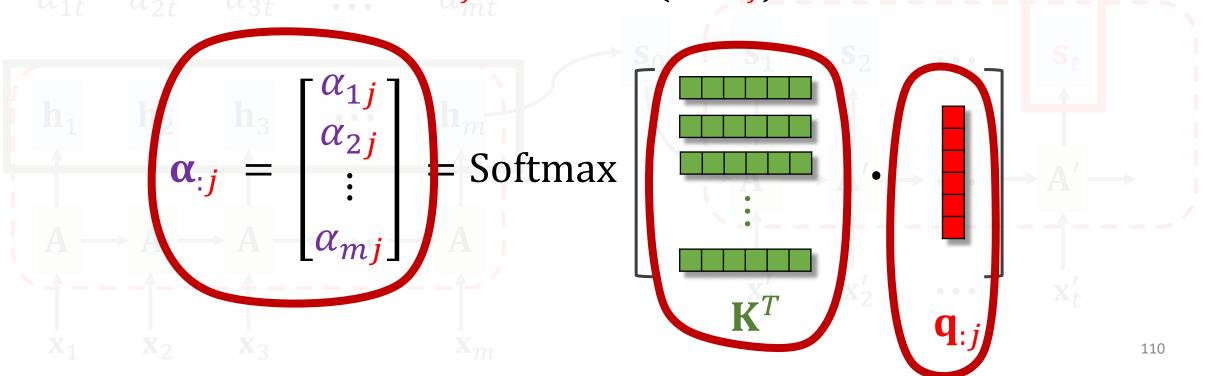
Weights: 
$$\alpha_{ij} = \operatorname{align}(\mathbf{h}_i, \mathbf{s}_j)$$
.

- Compute  $\mathbf{k}_{:i} = \mathbf{W}_K \mathbf{h}_i$ .
- Compute  $\mathbf{q}_{:j} = \mathbf{W}_Q \mathbf{s}_j$ .
- Compute weights:  $\alpha_{:j} = \operatorname{Softmax}(\mathbf{K}^T \mathbf{q}_{:j}) \in \mathbb{R}^m$ .



Weights: 
$$\alpha_{ij} = \operatorname{align}(\mathbf{h}_i, \mathbf{s}_j)$$
.

- Compute  $\mathbf{k}_{:i} = \mathbf{W}_K \mathbf{h}_i$ .
- Compute  $\mathbf{q}_{:j} = \mathbf{W}_Q \mathbf{s}_j$ .
- Compute weights:  $\alpha_{ij} = \text{Softmax}(\mathbf{K}^T \mathbf{q}_{ij}) \in \mathbb{R}^m$ .

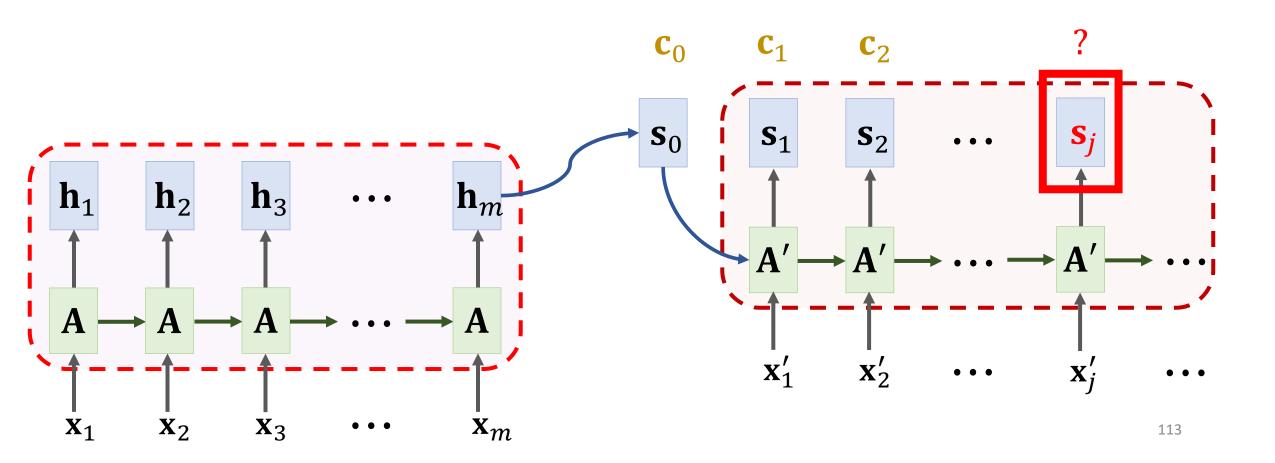


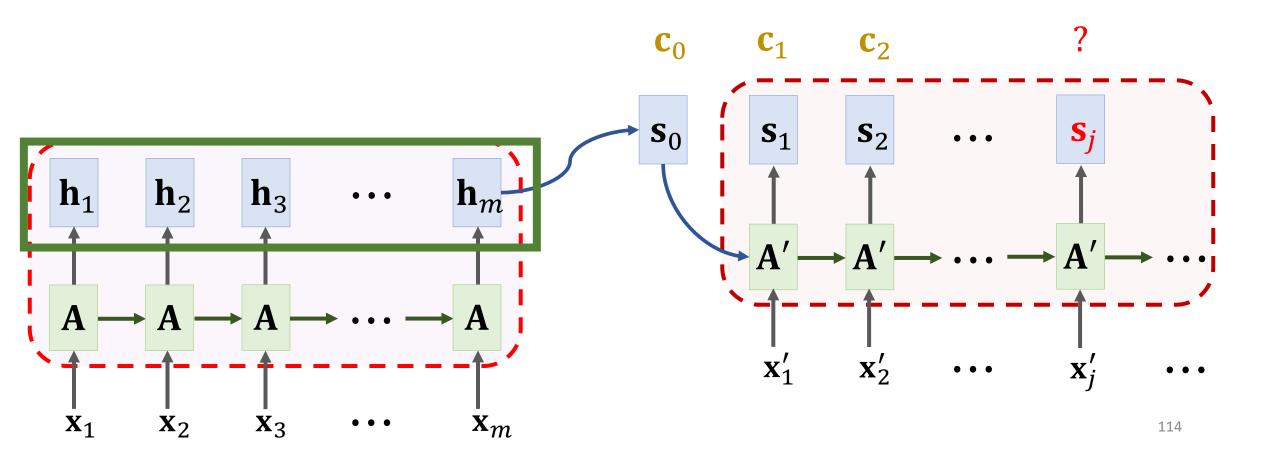
```
Weights: \alpha_{ij} = \operatorname{align}(\mathbf{h}_i, \mathbf{s}_j).
```

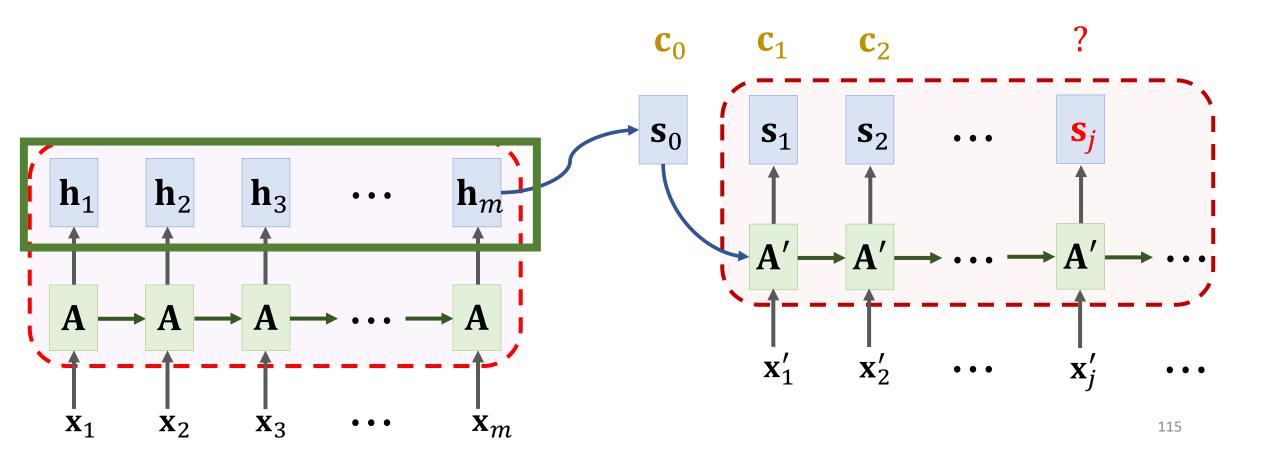
```
• Query: \mathbf{q}_{:i} = \mathbf{W}_O \mathbf{s}_i. (To match others.)
       • Key: \mathbf{k}_{:i} = \mathbf{W}_K \mathbf{h}_i. (To be matched.)
• Value: \mathbf{v}_{:i} = \mathbf{W}_V \mathbf{h}_i. (To be weighted averaged.)
```

Weights: 
$$\alpha_{ij} = \operatorname{align}(\mathbf{h}_i, \mathbf{s}_i)$$
.

• Query:  $\mathbf{q}_{:j} = \mathbf{W}_{Q} \mathbf{s}_{j}$ . (To match others.)
• Key:  $\mathbf{k}_{:i} = \mathbf{W}_{K} \mathbf{h}_{i}$ . (To be matched.)
• Value:  $\mathbf{v}_{:i} = \mathbf{W}_{V} \mathbf{h}_{i}$ . (To be weighted average (To be weighted averaged.) **Context vector:**  $\mathbf{c}_{i} = \alpha_{1i}\mathbf{v}_{:1} + \cdots + \alpha_{mi}\mathbf{v}_{:m}.$ 

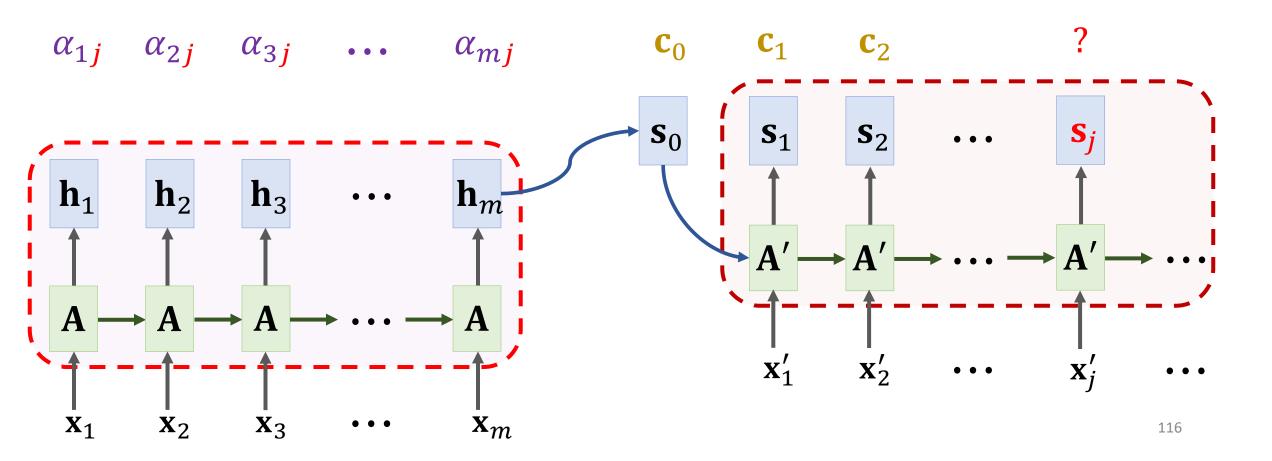


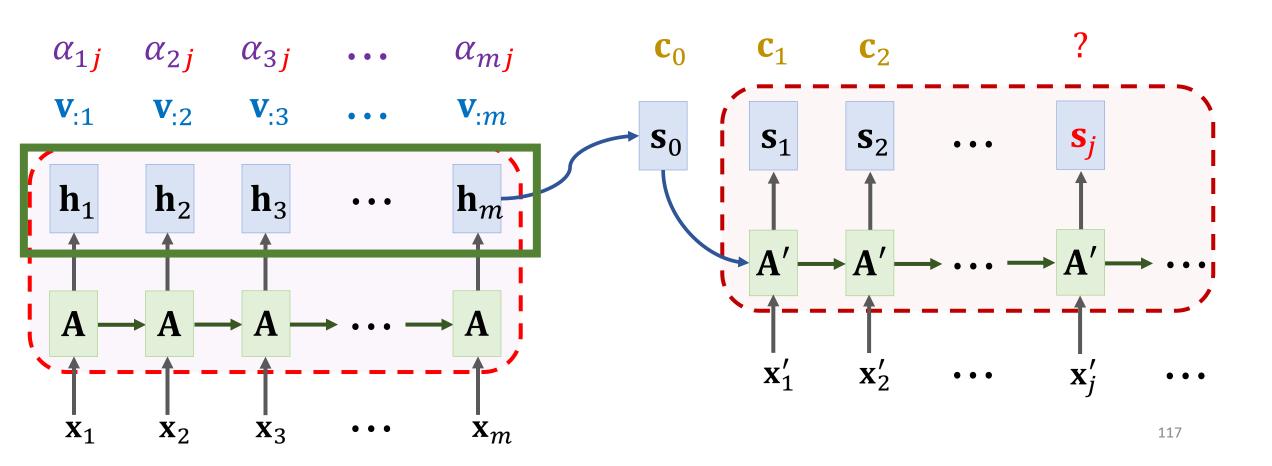


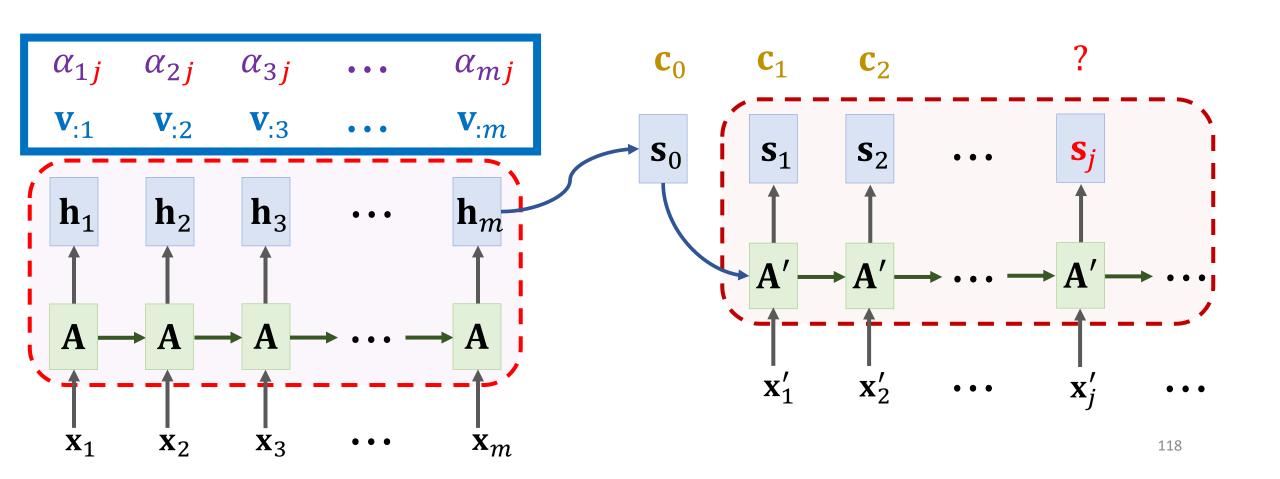


```
Query: \mathbf{q}_{:j} = \mathbf{W}_Q \mathbf{s}_j, Key: \mathbf{k}_{:i} = \mathbf{W}_K \mathbf{h}_i, Value: \mathbf{v}_{:i} = \mathbf{W}_V \mathbf{h}_i.

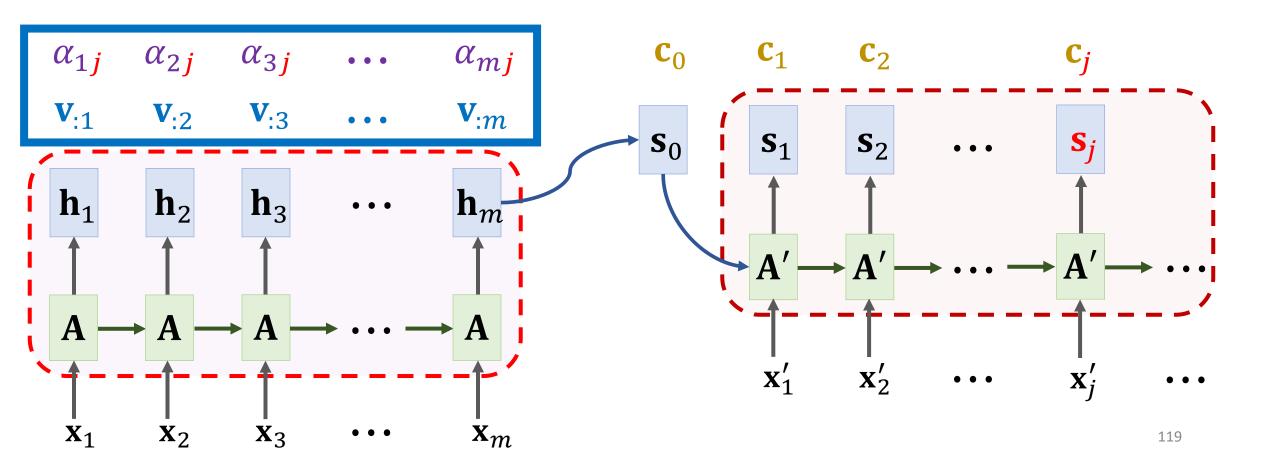
Weights: \alpha_{:j} = \operatorname{Softmax}(\mathbf{K}^T \mathbf{q}_{:j}) \in \mathbb{R}^m.
```



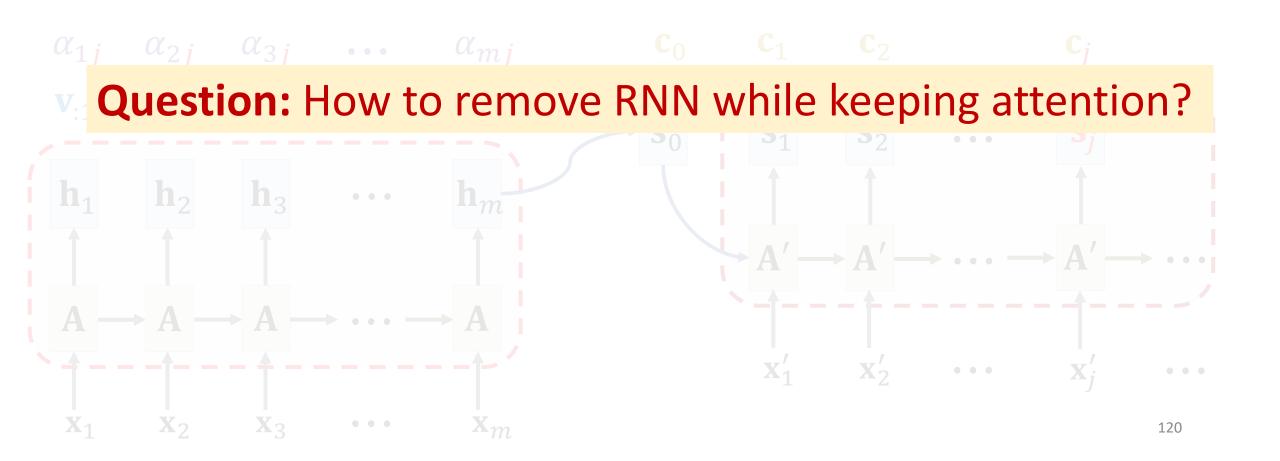




Context vector: 
$$\mathbf{c}_j = \alpha_{1j} \mathbf{v}_{:1} + \cdots + \alpha_{mj} \mathbf{v}_{:m}$$
.



Context vector: 
$$\mathbf{c}_j = \alpha_{1j} \mathbf{v}_{:1} + \cdots + \alpha_{mj} \mathbf{v}_{:m}$$
.



# **Attention without RNN**

- We study Seq2Seq model (encoder + decoder).
- Encoder's inputs are vectors  $\mathbf{x}_1, \mathbf{x}_2, \cdots, \mathbf{x}_m$ .
- Decoder's inputs are vectors  $\mathbf{x}'_1, \mathbf{x}'_2, \cdots, \mathbf{x}'_t$ .

#### **Encoder's inputs:**

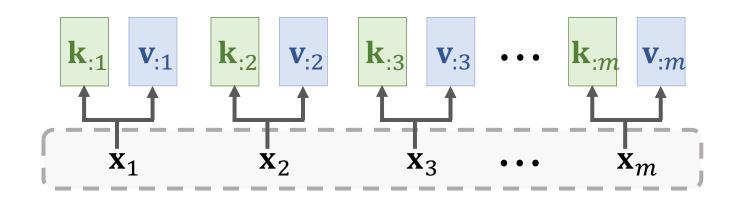
**Decoder's inputs:** 

 $\mathbf{x}_1 \qquad \mathbf{x}_2 \qquad \mathbf{x}_3 \qquad \cdots \qquad \mathbf{x}_m$ 

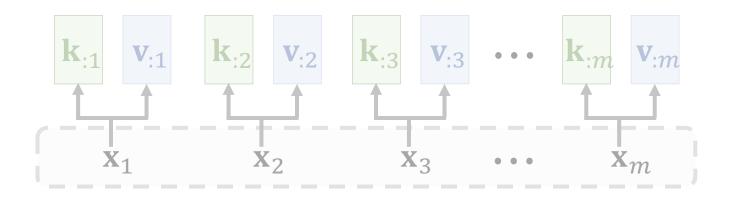
 $\begin{bmatrix} \mathbf{x}_1' & \mathbf{x}_2' & \mathbf{x}_3' & \cdots & \mathbf{x}_t' \end{bmatrix}$ 

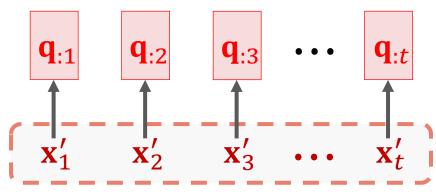
• Keys and values are based on encoder's inputs  $x_1, x_2, \dots, x_m$ .

• Key:  $\mathbf{k}_{:i} = \mathbf{W}_K \mathbf{x}_i$ . • Value:  $\mathbf{v}_{:i} = \mathbf{W}_V \mathbf{x}_i$ .



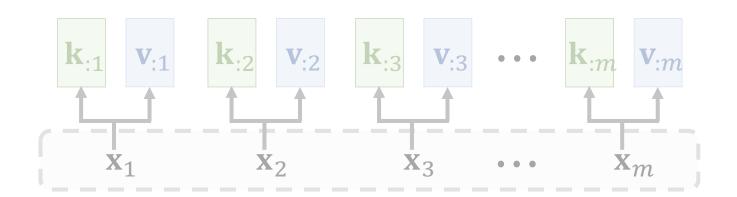
- Keys and values are based on encoder's inputs  $x_1, x_2, \dots, x_m$ .
- Key:  $\mathbf{k}_{:i} = \mathbf{W}_K \mathbf{x}_i$ .
- Value:  $\mathbf{v}_{:i} = \mathbf{W}_{V}\mathbf{x}_{i}$ .
- Queries are based on decoder's inputs  $\mathbf{x}_1', \mathbf{x}_2', \dots, \mathbf{x}_t'$ .
- Query:  $\mathbf{q}_{:j} = \mathbf{W}_Q \mathbf{x}_j'$ .

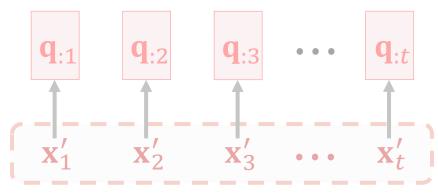




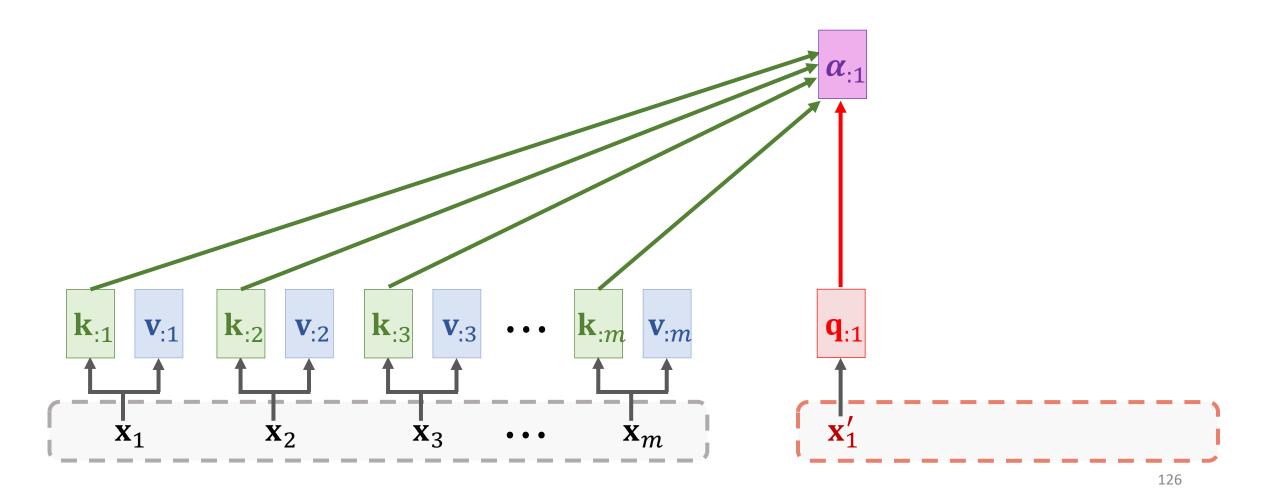
• Keys and values are based on encoder's inputs  $x_1, x_2, \dots, x_m$ .

- Key:  $\mathbf{k}_{:i} = \mathbf{W}_K \mathbf{x}_i$ . Value:  $\mathbf{v}_{:i} = \mathbf{W}_V \mathbf{x}_i$ .
- Queries are based on decoder's inputs  $\mathbf{x}'_1, \mathbf{x}'_2, \cdots, \mathbf{x}'_t$ .
- Query:  $\mathbf{q}_{:j} = \mathbf{W}_Q \mathbf{k}'_j$ .

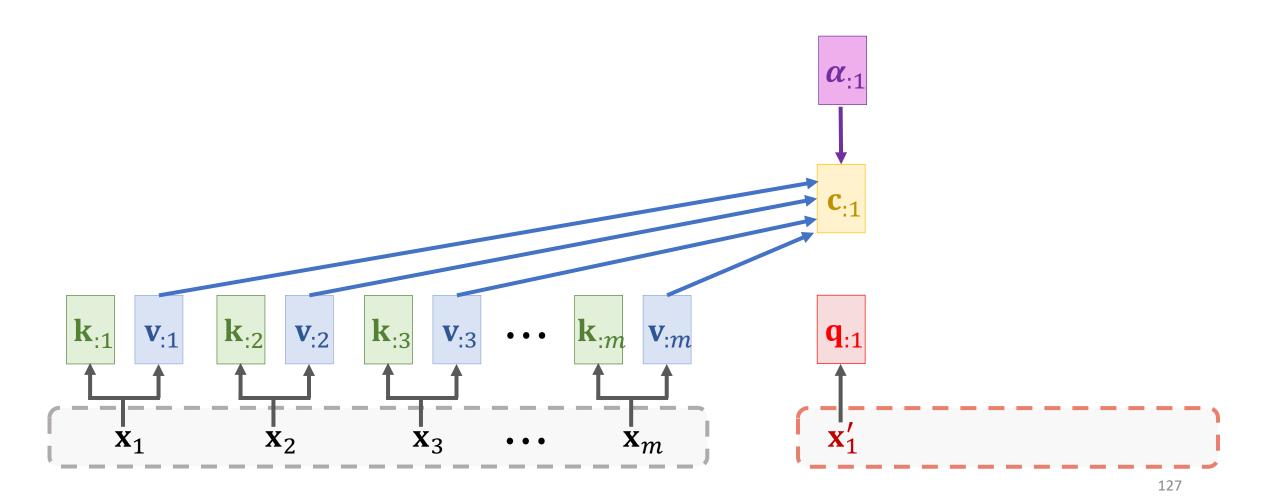




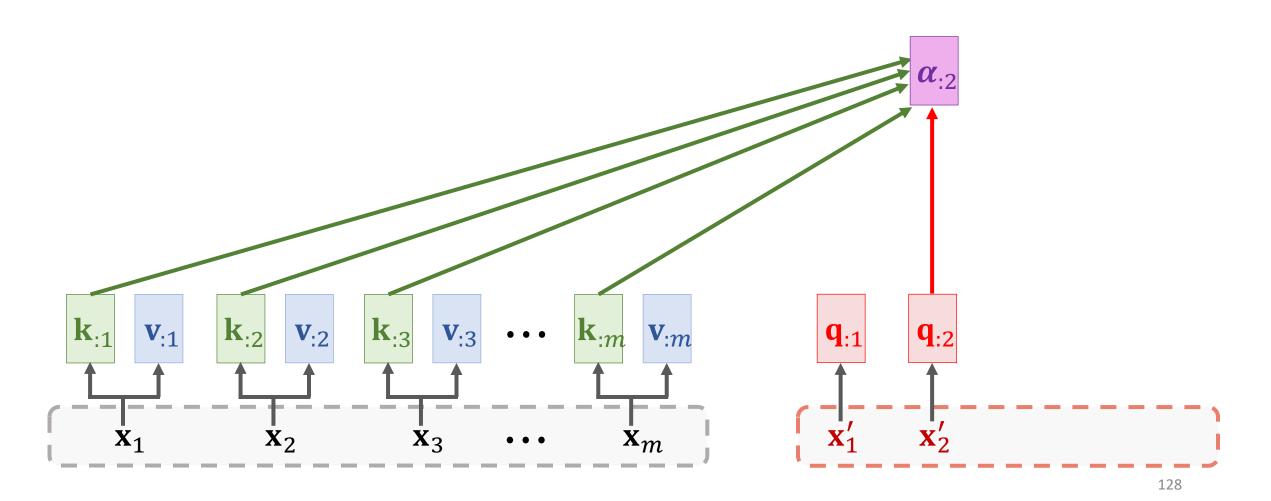
• Compute weights:  $\alpha_{:1} = \text{Softmax}(\mathbf{K}^T \mathbf{q}_{:1}) \in \mathbb{R}^m$ .



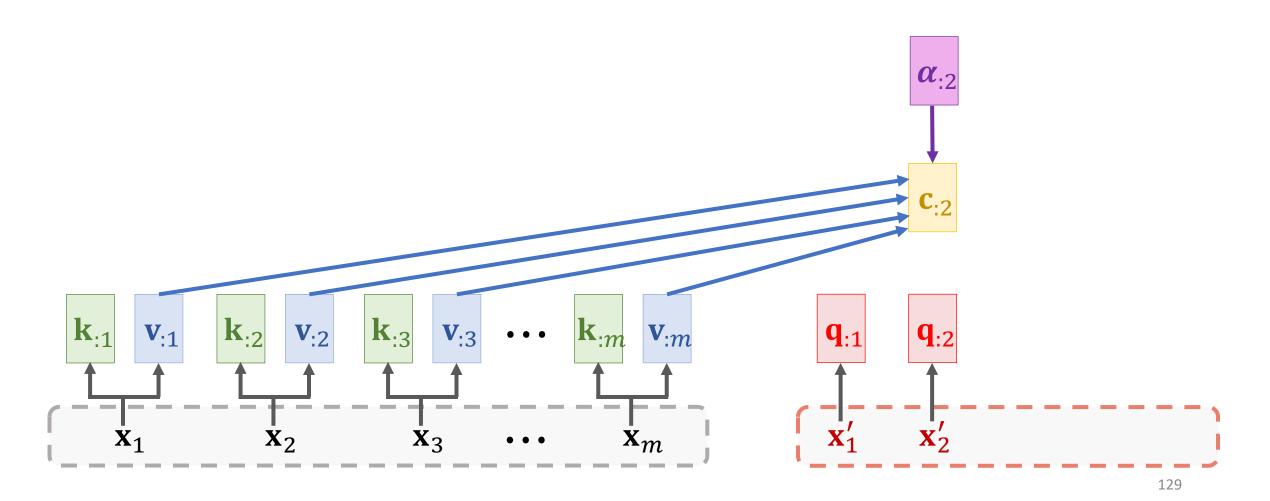
• Compute context vector:  $\mathbf{c}_{:1} = \alpha_{11}\mathbf{v}_{:1} + \cdots + \alpha_{m1}\mathbf{v}_{:m} = \mathbf{V}\alpha_{:1}$ .



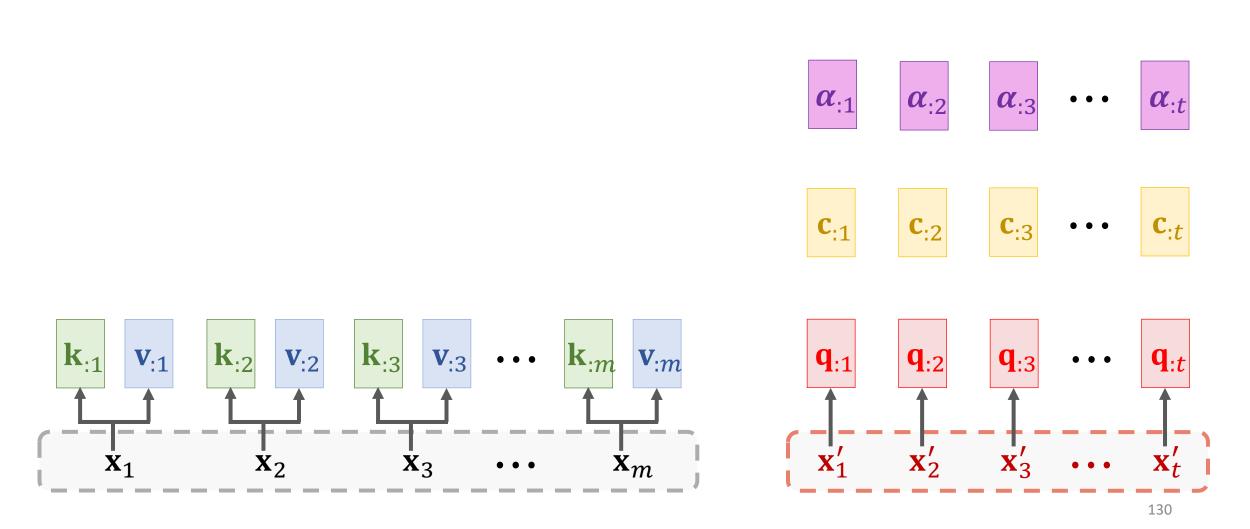
• Compute weights:  $\alpha_{:2} = \text{Softmax}(\mathbf{K}^T \mathbf{q}_{:2}) \in \mathbb{R}^m$ .



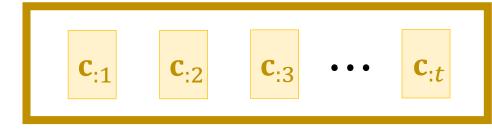
• Compute context vector:  $\mathbf{c}_{:2} = \alpha_{12}\mathbf{v}_{:1} + \cdots + \alpha_{m2}\mathbf{v}_{:m} = \mathbf{V}\alpha_{:2}$ .

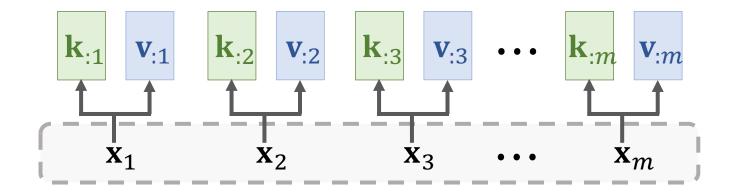


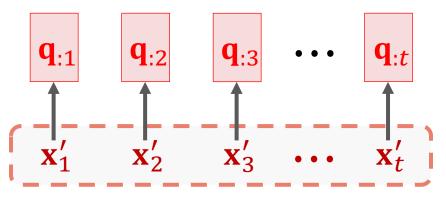
• Compute context vector:  $\mathbf{c}_{:j} = \alpha_{1j} \mathbf{v}_{:1} + \cdots + \alpha_{mj} \mathbf{v}_{:m} = \mathbf{V} \alpha_{:j}$ .



#### **Output of attention layer:**

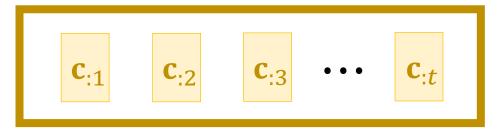


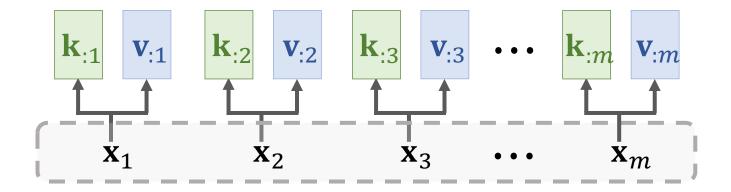


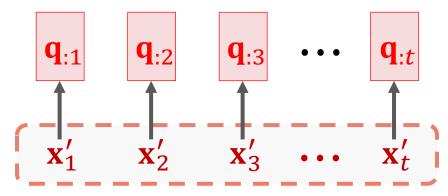


- Here,  $\mathbf{c}_{:j} = \mathbf{V} \cdot \operatorname{Softmax}(\mathbf{K}^T \mathbf{q}_{:j})$ .
- Thus,  $\mathbf{c}_{:j}$  is a function of  $\mathbf{x}_j'$  and  $[\mathbf{x}_1, \cdots, \mathbf{x}_m]$ .

#### **Output of attention layer:**





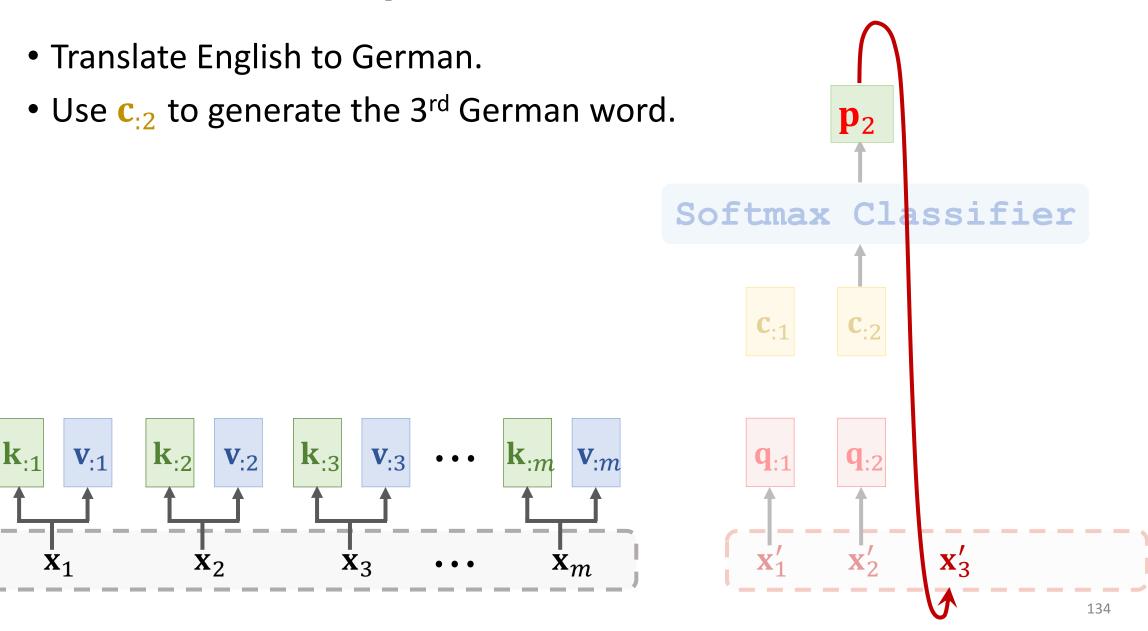


# **Attention Layer for Machine Translation**

Translate English to German.

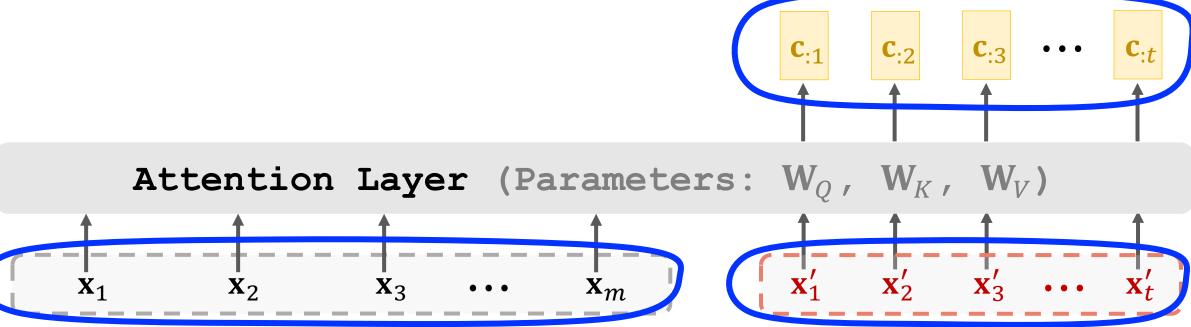
• Use C<sub>2</sub> to generate the 3<sup>rd</sup> German word.  $\mathbf{p}_2$ Softmax Classifier  $\mathbf{k}_{:3}$ **V**:3  $\mathbf{k}_{:2}$  $\mathbf{v}_{:2}$  $\mathbf{q}_{:2}$  $\mathbf{X}_3$  $\mathbf{X}_2$ English 133 German

# **Attention Layer for Machine Translation**



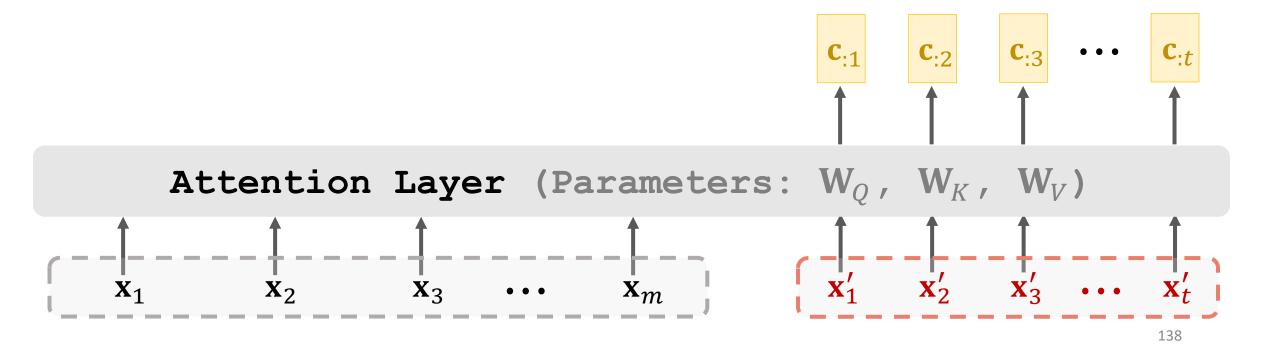
- Attention layer:  $[\mathbf{c}_{:1}, \mathbf{c}_{:2}, \cdots, \mathbf{c}_{:t}] = \operatorname{Attn}(\mathbf{X}, \mathbf{X}').$ 
  - Encoder's inputs:  $\mathbf{X} = [\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_m]$ .
  - Decoder's inputs:  $\mathbf{X}' = [\mathbf{x}_1', \mathbf{x}_2', \cdots, \mathbf{x}_t']$ .
  - Parameters:  $\mathbf{W}_Q$  ,  $\mathbf{W}_K$  ,  $\mathbf{W}_V$  .

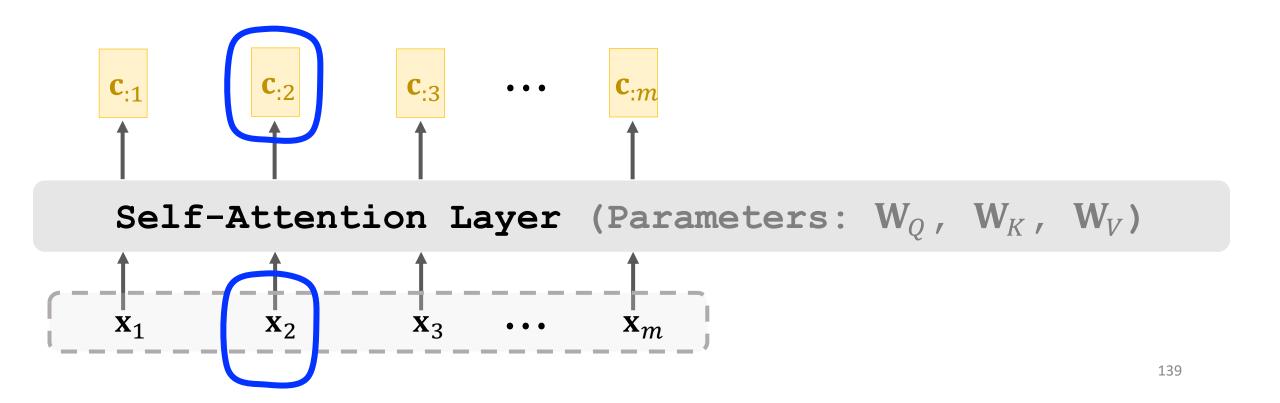
- Attention layer:  $[\mathbf{c}_{:1}, \mathbf{c}_{:2}, \cdots, \mathbf{c}_{:t}] = \operatorname{Attn}(\mathbf{X}, \mathbf{X}')$ .
  - Encoder's inputs:  $\mathbf{X} = [\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_m]$ .
  - Decoder's inputs:  $\mathbf{X}' = [\mathbf{x}'_1, \mathbf{x}'_2, \cdots, \mathbf{x}'_t]$ .
  - Parameters:  $\mathbf{W}_{O}$  ,  $\mathbf{W}_{K}$  ,  $\mathbf{W}_{V}$ .



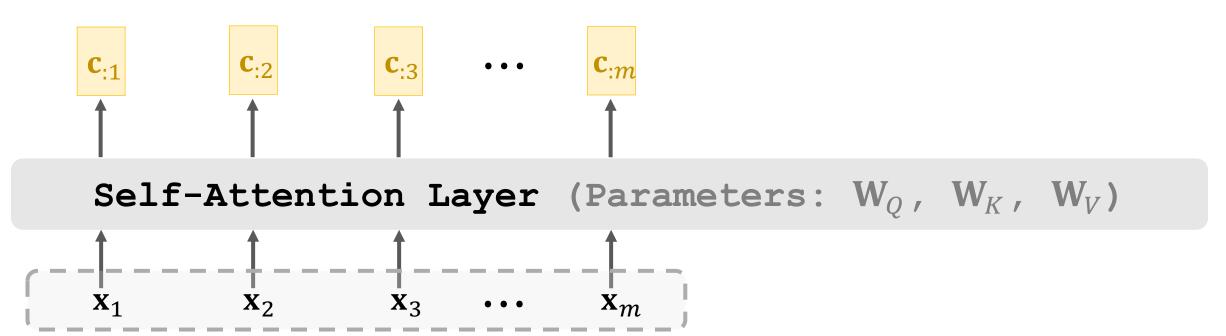
# **Self-Attention** without RNN

• Attention layer:  $[\mathbf{c}_{:1}, \mathbf{c}_{:2}, \cdots, \mathbf{c}_{:t}] = \operatorname{Attn}(\mathbf{X}, \mathbf{X}').$ 



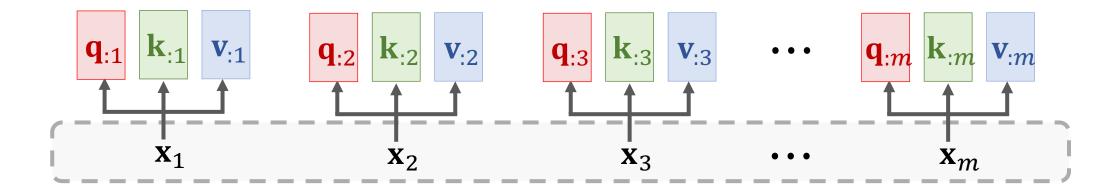


- Self-attention layer:  $[\mathbf{c}_{:1}, \mathbf{c}_{:2}, \cdots, \mathbf{c}_{:m}] = \operatorname{Attn}(\mathbf{X}, \mathbf{X}).$ 
  - Inputs:  $\mathbf{X} = [\mathbf{x}_1, \mathbf{x}_2, \cdots, \mathbf{x}_m]$ .
  - Parameters:  $\mathbf{W}_{O}$  ,  $\mathbf{W}_{K}$  ,  $\mathbf{W}_{V}$  .

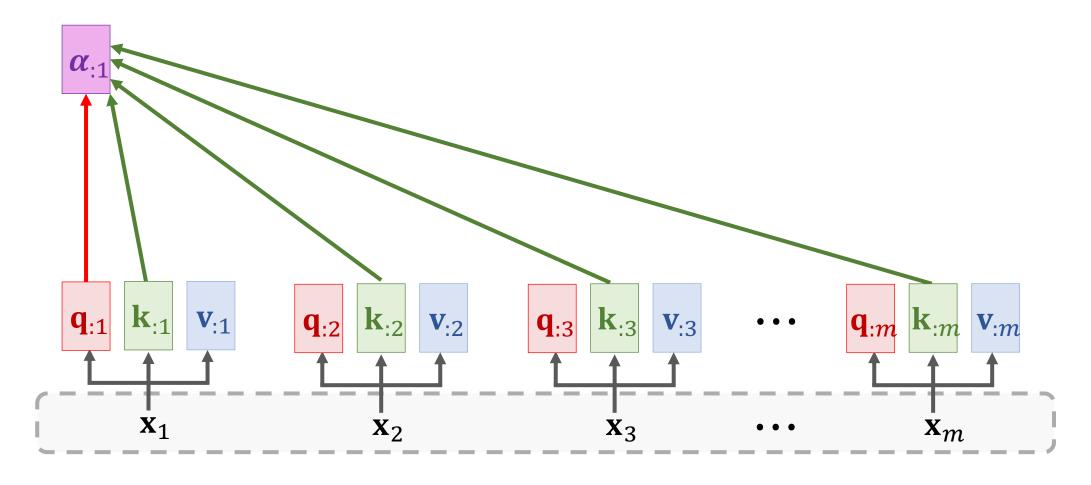


#### Inputs:

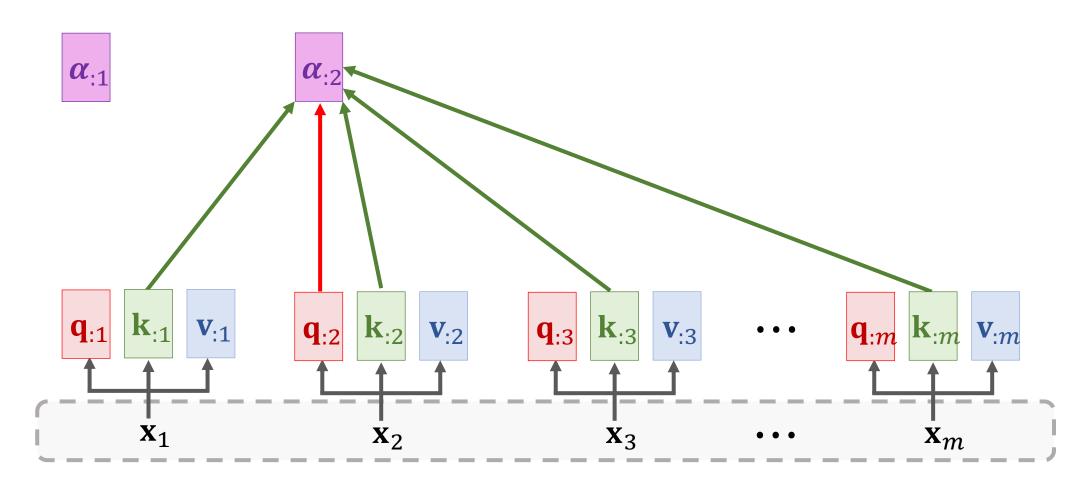




Weights: 
$$\alpha_{:j} = \operatorname{Softmax}(\mathbf{K}^T \mathbf{q}_{:j}) \in \mathbb{R}^m$$
.

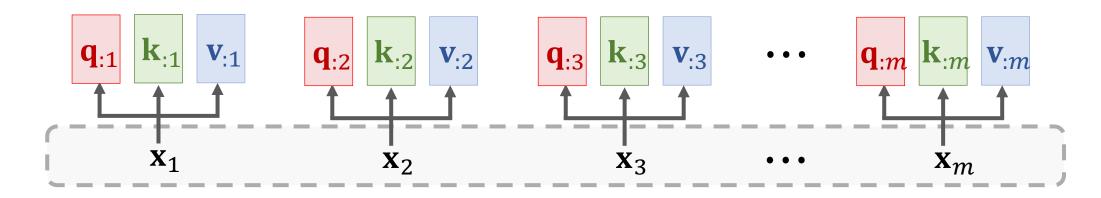


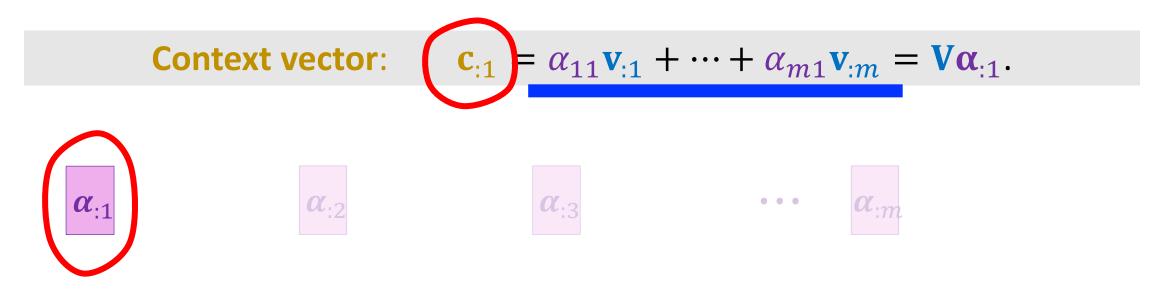
Weights: 
$$\alpha_{:j} = \operatorname{Softmax}(\mathbf{K}^T \mathbf{q}_{:j}) \in \mathbb{R}^m$$
.

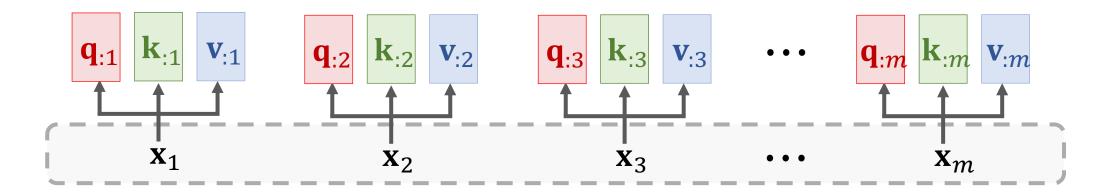


Weights: 
$$\alpha_{:j} = \text{Softmax}(\mathbf{K}^T \mathbf{q}_{:j}) \in \mathbb{R}^m$$
.

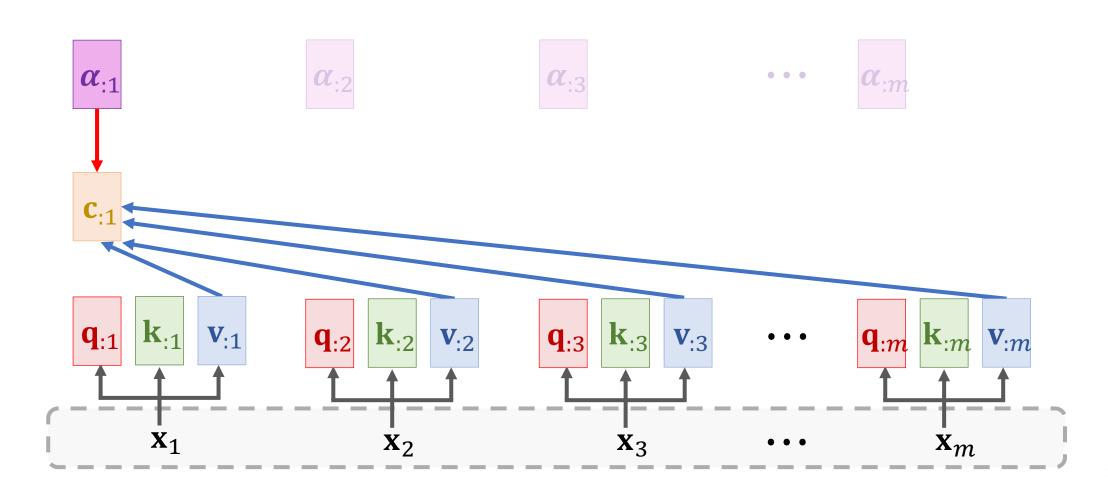




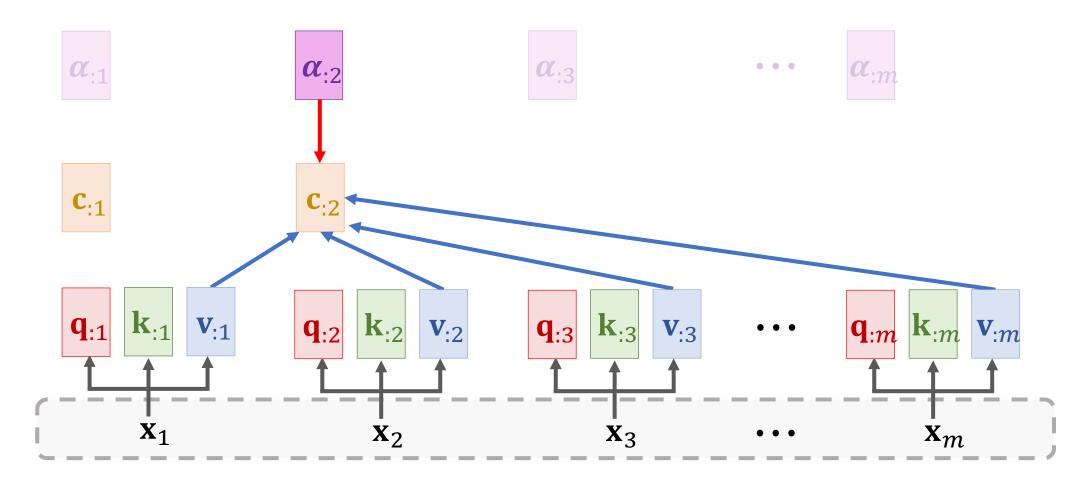




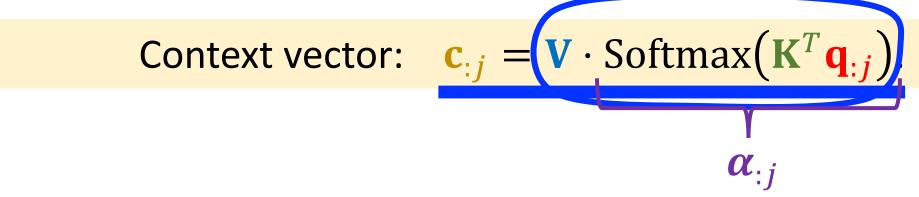
Context vector:  $\mathbf{c}_{:1} = \alpha_{11}\mathbf{v}_{:1} + \cdots + \alpha_{m1}\mathbf{v}_{:m} = \mathbf{V}\alpha_{:1}$ .



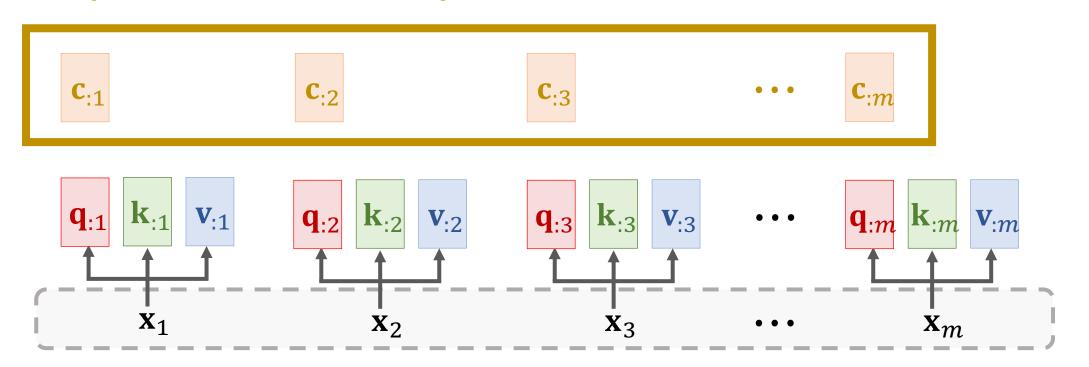
Context vector:  $\mathbf{c}_{:2} = \alpha_{12}\mathbf{v}_{:1} + \cdots + \alpha_{m2}\mathbf{v}_{:m} = \mathbf{V}\boldsymbol{\alpha}_{:2}$ .



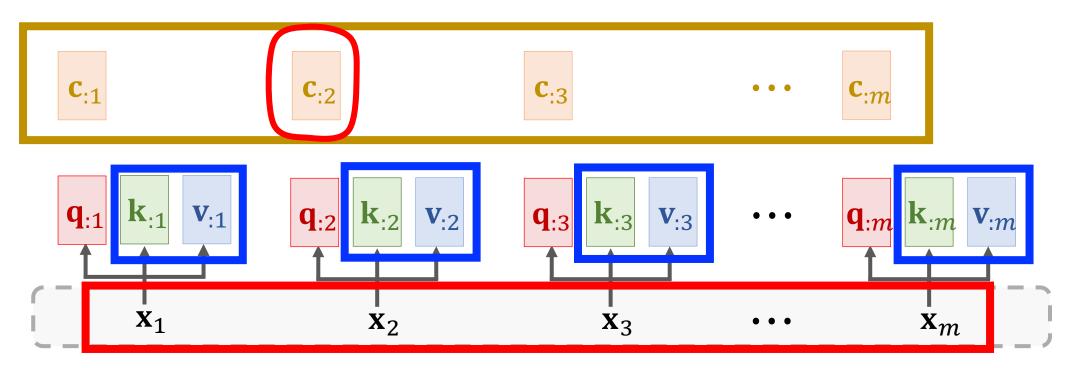
**Context vector:**  $\mathbf{c}_{:j} = \alpha_{1j}\mathbf{v}_{:1} + \dots + \alpha_{mj}\mathbf{v}_{:m} = \mathbf{V}\boldsymbol{\alpha}_{:j}.$ **c**:1 **c**:2 **C**:3  $|\mathbf{k}_{:3}|$  $\mathbf{k}_{:2}$ **v**:2 **V**:3  $\mathbf{q}_{:2}$ **q**:3  $\mathbf{X}_3$  $\mathbf{X}_2$ 



#### **Output of self-attention layer:**

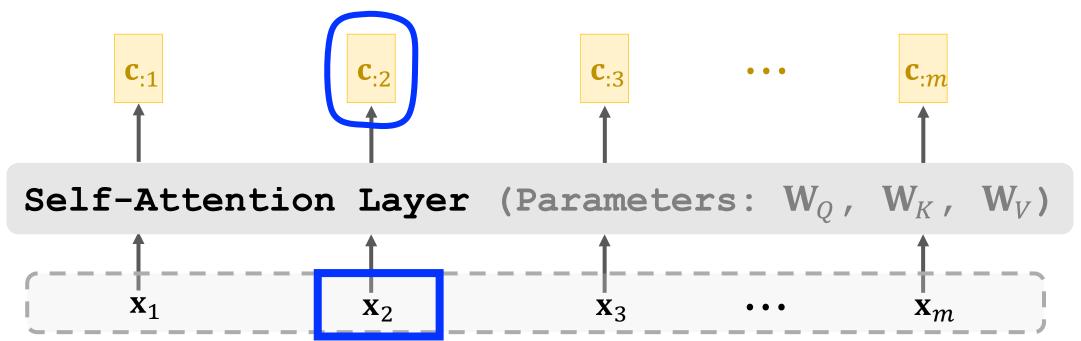


#### **Output of self-attention layer:**



- Self-attention layer:  $[\mathbf{c}_{:1}, \mathbf{c}_{:2}, \cdots, \mathbf{c}_{:m}] = \operatorname{Attn}(\mathbf{X}, \mathbf{X}).$ 
  - Inputs:  $\mathbf{X} = [\mathbf{x}_1, \mathbf{x}_2, \cdots, \mathbf{x}_m]$ .
  - Parameters:  $\mathbf{W}_Q$  ,  $\mathbf{W}_K$  ,  $\mathbf{W}_V$  .

- Self-attention layer:  $[\mathbf{c}_{:1}, \mathbf{c}_{:2}, \cdots, \mathbf{c}_{:m}] = \operatorname{Attn}(\mathbf{X}, \mathbf{X}).$ 
  - Inputs:  $\mathbf{X} = [\mathbf{x}_1, \mathbf{x}_2, \cdots, \mathbf{x}_m]$ .
  - Parameters:  $\mathbf{W}_O$  ,  $\mathbf{W}_K$  ,  $\mathbf{W}_V$ .



# Summary

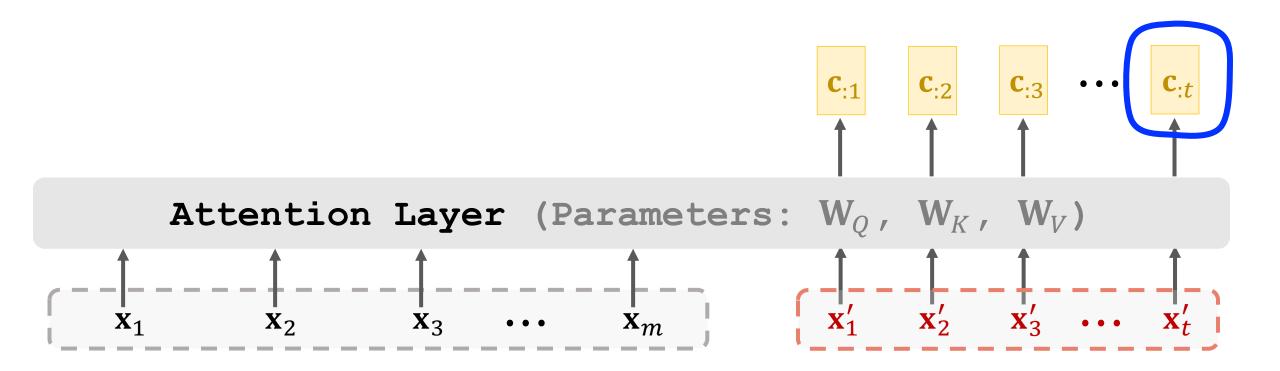
#### Summary

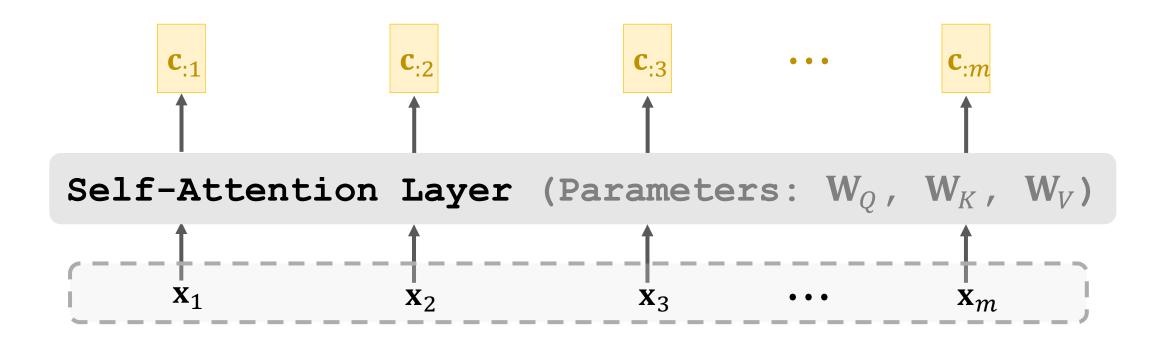
- Attention was originally developed for Seq2Seq RNN models [1].
- Self-attention: attention for all the RNN models (not necessarily Seq2Seq models [2].
- Attention can be used without RNN [3].
- We learned how to build attention layer and self-attention layer.

#### Reference:

- 1. Bahdanau, Cho, & Bengio. Neural machine translation by jointly learning to align and translate. In *ICLR*, 2015.
- 2. Cheng, Dong, & Lapata. Long short-term memory-networks for machine reading. In *EMNLP*, 2016.
- 3. Vaswani et al. Attention is all you need. In NIPS, 2017.

#### **Attention Layer**





## Thank You!