

Traffic Recovery in Complex Networks

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Traffic congestion in traffic networks has so far been studied from the perspective of network planing. The studies on how to efficiently mitigate the congested systems are relatively limited. In this paper, we introduce an algorithm of recovering sequence planning, which is used to detect an efficient recovering sequence of congested links. Following an efficient recovering sequence, we observe that the throughput of a congested traffic network can be recovered to a large extent by reconnecting few congested links. This highlights that the key role that the sequence plays in first-aid repairs in traffic systems. We believe our algorithm is capable of promoting related studies on recovering congested traffic systems.

INTRODUCTION

Modern world depends greatly on the efficient operation of many critical infrastructures such as Internet, airlines, power grid, highways and so on [1]. Such systems are neither regular nor random, which are typically modeled as networks. In the networks, nodes represent the basic units of a system and links stand for the interactions between the nodes [2]. In the studies of traffic networks, further promoting the capacity of the traffic systems is one of the ultimate aims [3–14]. In this regard, most attention has been given to traffic congestion problems in networks. In the past decades, how to avoid traffic congestions as a key question has been extensively investigated.

Network transmission capacity is normally measured by the maximal amount of traffic flow that the network can handle without causing congestion [15]. Knowledge on avoiding traffic congestion is relevant to the planning and controlling of traffic systems. Network planning concerns designing topological structures and deploying resources. Thus, corresponding studies are divide into two categories. We briefly review the progresses in the respective categories here.

Providing a proper network structure for maximizing the capacity of traffic networks is a challenging task. Boccaketti et al. suggest that in transportation networks, the global capacity depends on the load of each link. That is to say the number of the passengers in the airports or the passengers in the subways. By removing a small fraction of nodes, the authors simulated the breakdown of an Internet router or transportation system. They found that homogeneous network does not experience cascading failures due either to random breakdown or to intentional attacks. For the heterogeneous network, cascades triggered by the attack on a key node will lead to serious congestion problem. Thus, homogeneous networks appear to be more resistant to cascading failures than the heterogeneous ones [3]. Toroczkai et al. compared the congestion in gradient networks generated by either random or scale-free substrates, finding that the scale-free gradient networks are less prone to jamming [4, 5]. Roger et al. claim that the system only behaves efficiently when the amount of handled packages is small enough. The network collapses when the traffic exceeds a certain threshold. They found that the collection of models can be split into three groups according to how the network collapses if putting the topological effect aside. In the first group, agents deliver more packets as more packets are stranded. Although their capability decreases, the network is not likely to collapse. In the second group, agents keep delivering the same number of packets regardless of their loads. The processing mechanism leads to a continuous phase transition. Finally, when agents deliver fewer packets as their loads increase, the transition to the congested phase is discontinuous and the network collapses in an inhomogeneous way giving rise to congestion nuclei [6].

In practice it is typically impossible to reform the topological structures of existing traffic systems. The results mentioned above are built on an assumption that all nodes or links are assigned with uniform resources. This simplified scenario allows researchers to study the pure contribution of the network topology, while resources are rarely distributed equally in realistic traffic networks. In this regard Zhang et al. came up with a practical and

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effective approach to allocate the resources. They suggest that allocating more resources to the nodes handling higher volumes of traffic loads and less resources to the less-loaded nodes is helpful to keep the systems from congestion. Their results show that their scheme enhances the transmission capacity of heterogeneous networks by up to two orders of magnitude [7]. Zhao et al. tested two resource allocations: (1) The capacity of delivery of each node is proportional to its degree; (2) The delivery capacity of each node is proportional to its betweenness. They have found that for the former allocation, random networks and scale-free networks are more tolerant to congestion than regular networks and Cayley trees. For the second allocation, the crowded degree is independent of the network topology and size, so they thus claim that the allocation may be useful for communication protocols [8].

Traffic controlling concerns how to route traffic efficiently to mitigate congestion. Daniele et al. tested a trade-off strategy between traffic based and topology based routing on scale-free networks. They found that traffic control is useless in homogeneous networks but may useful in inhomogeneous networks [9]. Gang Yan et al. proposed a routing strategy to improve the transportation efficiency on complex networks. Instead of using the routing strategy for shortest paths, they proposed a generalized routing algorithm to detect the so-called “efficient path”. They take the nodes likely to be congested into consideration, which are normally in the shortest path. Considering the nodes with larger degree are very susceptible to traffic congestion, they suggest that redistributing traffic load in central nodes to other non-central nodes is capable of efficiently refraining the traffic congestion. Their simulation results show that the network capability in processing traffic is improved more than 10 times by routing with the efficient paths [10]. Xiang et al. proposed a global dynamic routing strategy for network systems based on the queue lengths at nodes. Governed by the routing strategy, the traffic capacities of the corresponding networks were further improved. With time delay of updating node queue lengths and the corresponding paths, the system capacity remains constant, while the travel time for packets increases [11]. Tan Fei et al. proposed a routing algorithm that combines static structural properties and dynamic traffic conditions together, which balances the traffic between hubs and peripheral nodes more effectively [12]. Danila et al. proposed an algorithm to balance traffic on a network by minimizing the maximum node betweenness with a path as short as possible. Using the routing table, a network can sustain significantly higher traffic than adopting traditional shortest path routing [13]. Guan et al. investigated the traffic dynamics of a spatial scale-free network where the bandwidth of a link is proportional to its Euclidean distance. They proposed a new routing strategy, considering both Euclidean distance and betweenness centralities of links. They claim that compared with the shortest distance path strategy and the minimum betweenness centralities of links strategy, their strategy under some specific settings can efficiently balance the traffic load and avoid excessive traveling distance which can improve the spatial network capacity and some metrics of transportation efficiency, such as average packets traveling time, average packets waiting time and system throughput, traffic load and so on [14].

Compared with the potential costs of changing the structure of well-established networked systems, resource reallocation, proposals of clever routing criteria seem to be more practical and thus attract the most interest, while the controlling and designing approaches can not completely avoid congestion. Once the transportation system collapse, we need a solution to recover the capacity of the traffic system. In this paper, we investigate the recovering sequence of congested links. Assuming that there are three congested links in a traffic network, while we just have one first-aid repair team in hand, where should we dispatch the team firstly? In this case, there are six possible recovering sequences for us to choose, and it is obviously that different recovering sequence lead to different ends. Clearly, to find the best recovering sequence is a NP hard problem. We will provide a heuristic algorithm in this paper. Our algorithms are based on local structures, the time complexity is thus considerably low, which is applicable to the cases that the response time requirement is relatively high.

Our contributions in this paper are three-fold. Firstly, our algorithms are proposed to recover the congested traffic systems, while previous studies concentrate on the perspective of keeping the systems from congestions. Thus, the motivation and scenario of our algorithms is clearly different from the existing algorithms. Secondly, for two classic network models and two realistic traffic networks, we propose and compare the performance of four algorithms. They are reverse preferential attachment(RPA), reverse add preferential attachment(RAPA), reverse similarity attachment(RSA), reverse local path(RLP). The algorithms are based on a reverse-similarity of nodes, which are rarely reported in the previous studies. Thirdly, through extensive traffic simulations, our results show that our algorithms are capable of detecting a more efficient recovering sequence than existing algorithms.

RELATED WORK

In a network, the probability of connecting a node pair is normally measured in three ways, including local indices, global indices, quasi-local indices. The quasi-local indices require more information than the local indices, while much less than global indices. Considering traffic recovery is normally applied to urgent scenarios, the response time left for administrators is rather , namely, the computation complexity is strictly refrained. In this paper, we provide performance comparison of our algorithm with two classic algorithms: the PA and LP algorithm. We will briefly

introduce these algorithms in the following

(1) The PA algorithm[42]. Since a great number of real networks exhibit a power-law degree distribution, some researchers believe that the degree distribution originates from a preferential attachment between nodes. Inspired by this mechanism, a metric measuring the priority of connecting node x with y is defined as:

$$S_{xy} = k_x * k_y, \quad (1)$$

which is referred to as a ranking score in the studies of link prediction[16].

(2) Local Path Index (LP). Let A be the adjacency matrix, where $A_{xy} = 1$ if x and y are directly connected, otherwise $A_{xy} = 0$. If x and y are not directly connected, $(A^2)_{xy}$ equals the number of common neighbors of node x and y , which is also equal to the number of 2 hops paths of length 2 between x and y . $(A^3)_{xy}$ equals the number of paths of length 3 between x and y . $(A^3)_{xy}$ provides information on the nodes 2 hops away, while its impact on the connecting probability is clearly weaker than $(A^2)_{xy}$. The ranking score matrix[43, 44] is defined as:

$$S = A^2 + \varepsilon A^3. \quad (2)$$

The ranking score of node pair xy is the entry of S in the x th row and y th column. In our experiment, we set $\varepsilon = 0.2$.

(3) The number of common neighbors is a reasonable metric to predict whether two nodes tend to be connected in some social networks. Especially in social networks, the recommendation system is likely to introduce users with common friends to each other. Whereas, the range is a bit limited. For instance, one may meet a lot of strangers in a party, while the similarity is that they all have at least a friend knowing the organizer. Inspired by the fact, we propose a new measurement, called 3-order adjacency index to extend the local index, common neighbors index, to a quasi-local index. $\Gamma^3(x)$ denote the set of neighborhood nodes in 3 hops.

$$S_{xy} = |\Gamma^3(x) \cap \Gamma^3(y)| \quad (3)$$

To recover the traffic capacity of a congested network, we test a series of reversed solutions, in which the priorities of connecting x with y are inversely proportional to the indexes mentioned above. We will show that the priority queues derived by the link prediction metrics mentioned above is not directly applicable to the traffic recovery of respective networks.

DATASETS

To find a proper priority queue for traffic recovery in complex networks, we run a series of Monte Carlo simulations on three kinds of networks. We briefly introduce the networks in the following.

Barabasi-Albert (BA)

Since the BA[45] model can reproduce the degree heterogeneity of a series of traffic networks, including the Internet AS level topology, the logical topology of unstructured P2P distributed systems, and so on. We adopt the BA model to generate a series of scale-free networks, where the degree distribution of which follows a power law $p(k) \propto k^{-3.0}$. Here, $p(k)$ denotes the degree distribution of the networks. In our simulation, we set the mean degree of the network $\langle k \rangle = 4$.

US Air lines (USAir)

The USAir dataset is available from <http://vlado.fmf.uni-lj.si/pub/networks/data/>. The network is extracted from the USAir transportation system. The data contains 332 nodes and 2126 edges. Nodes in the network denote airports and edges denote airlines among these nodes. Notice that the network is a undirected network which means the airline support return flights.

California road network

The California road network dataset is available from Stanford Large Network Dataset Collection (<http://snap.stanford.edu/data/>). The original data contains 1,965,206 nodes and 2,766,607 edges. Considering the network is too large for link prediction and traffic simulation, we select a number of regions from the California road network. Initially, we randomly choose a node and set it to a central node. Next, we adopt the Breadth First Search to extend the region until it reaches the desired size. For example, if we take a node as the central node, the nodes whose distance to the central node is less than r will be included. Here, r denotes the depth of the search. In California road network, if one sets a node labeled 800,120 to the central node and the searching depth to 30, the selected region will be composed of 1,285 nodes and 1,748 edges.

The basic topology statistics of the six networks are summarized in Table I. $|V|$ is the number of vertices and $|E|$ is the number of edges in a given network. D denotes the density of the network which is defined as $\frac{2*|E|}{(|V|-1)*|V|}$ [46]. C

	$ V $	$ E $	D	C	$\langle k \rangle$	$\langle d \rangle$	H
BA256	256	508	0.016	0.075	3.97	3.49	2.17
BA512	512	1020	0.008	0.052	3.98	3.68	2.87
BA1024	1024	2044	0.004	0.030	3.99	4.07	2.78
USAir	332	2126	0.039	0.625	12.81	2.74	3.46
Cal Road 10	121	156	0.021	0.142	2.58	9.54	1.13
Cal Road 20	409	525	0.006	0.101	2.57	17.71	1.17
Cal Road 30	1285	1750	0.002	0.077	2.72	23.28	1.16

TABLE I: statistics of the six networks.

denotes the clustering coefficient[47]. Let k_i be node v_i 's degree. The maximal number of edges among v_i 's neighbors is $k_i * (k_i - 1)/2$, the local clustering coefficient for the vertex v_i is $C_i = \frac{2 * l_i}{k_i * (k_i - 1)}$, where l_i stands for the number of existing edges among v_i 's neighbors. C denotes the average clustering coefficient, which is the arithmetic mean of C_i for all the nodes. $\langle k \rangle$ is the average degree of the network. Here, a shortest path is defined as a path connecting two connected nodes with least edges. Thus, the shortest path distance is the number of edges in the shortest path. $\langle d \rangle$ denotes the arithmetic mean of the lengths of the shortest paths between all the node pairs. Degree heterogeneity is a statistical property, which quantitatively characterizes the fluctuation of the degree sequence of a network. This property was frequently mentioned, while its explicit definition was not manifested until a recent work[48]. To be consistent with previous studies, we denote the degree heterogeneity by H. H is defined as $\frac{\langle k^2 \rangle}{\langle k \rangle^2}$, where $\langle k \rangle$ denotes the average degree [49].

Experimental results

In this section, we will test three algorithms to find the best recovery sequence for the three types of unweighted networks. Next, in order to verify the robustness of our algorithm to the size of networks, we test the algorithms on the BA networks with 256, 512, 1,024 nodes and Cal Road networks with 121, 409, 1,285 nodes.

1.Steps of the traffic recovery simulation

1) In order to test our method we should generate traffic- like topological networks. Here we got three kinds of networks, BA network, USAir network and California road network. To simplify the simulation, they are set to be unweighted and undirected.

2) The next step is to simulate the congestion of the traffic net. We think that in the status of congestion the traffic in the route almost Stagnated, so to some degree it equals the route has been broken. So in this process we randomly select a part of the route, and break them up. Notice that we allow the situation that after the break of the network, there are exists individual nodes.

3) Since we have broken links, so we can use link prediction methods to rank the edges of nonsexist, and determine the sequence of recovery links. One different from link prediction is that in link prediction we will rank all the edges of nonsexist while in route recovery we just need to judge the important of broken edges and recover them in order. Here we have eight methods to recover the routes which was mentioned before.

4)To verify the efficiency of different methods based on link prediction, we have conducted package simulation experiments. Several models have been proposed to simulate packet trafr dynamics on complex networks by introducing random generation of packets in each time step and various routing strategies. We here adopt one widely used before.

At each time step, each node generates $\frac{R}{N}$ packets, where N is the size of the network and R is a parameter tuning the generation rate, i.e., there are R packets generated in the network at each step. When $\frac{R}{N}$ is not an integer, we create $\text{Int}(\frac{R}{N})$ packets determinately and create a packet simultaneously with probability $p = \frac{R}{N} - \text{Int}(\frac{R}{N})$, where $\text{Int}(\frac{R}{N})$ is the integral part of $\frac{R}{N}$ and thus p is the fractional part. The packets are initialized with random destinations. Moreover, we set a transmission capacity C_i to the node i, $i=1,2, \dots, N$, which means that, at each time step, the maximal number of packets transferred by the node i to the next node according to the routing table is C_i . When the node cannot transfer all the packets accumulated in its queue, it deals with them following the rst-in-rst-out rule. Hence, the routing strategy also plays an important role in the trafr dynamics. We see that, in the Internet, the routing strategy of within domains is the shortest path algorithm and, between domains, i.e., for the AS level, the border gateway protocol causes the packets to be transmitted along almost the shortest path[50]. Therefore, in the paper, we adopt the shortest path routing strategy. When a packet reaches its destination through the shortest path routing, the packet will be deleted from the system. In order to analyze the transition from free ow to a congested state, we use the order parameter presented in previous studies[51],

At each time step, R packets are randomly assigned to N nodes. We define the processing capacity of node i as

C_i for all i . For packets queuing at a node, they follow the first-in-first-out rule []. If the traffic at the node exceeds the its capacity, the left packets will accumulate at the node. To keep consistent with the previous studies [50], the routing of packets follows the shortest-path routing. When a packet reaches its destination, it will disappear. In order to measure the traffic capacity, we adopt the order parameter [51] as the evaluating metrics, which is defined as:

$$\mu < R > = \lim_{t \rightarrow \infty} \frac{\langle \Delta w \rangle}{R \Delta t} \quad (4)$$

where $W(t)$ is defined as the number of packets on the network at time step t , and $\Delta W = W(t + \Delta t) - W(t)$, with $\langle \dots \rangle$ indicating averaging over time windows of width t . In other words, the order parameter represents the ratio of the average increased number of packets to the number of generated packets per time step during a long enough time window. When a system in a free flow state, i.e., there is no congestion in the network, the system can handle the generated packets, leading μ to 0. On the contrary, in the congested state, the number of generated packets is too large to be transmitted and the flow remaining in the network will get increasingly large, which will promote the order parameter to approach 1.

2. Metrics for evaluation

We have tested eight methods to recovery the links in the network. Different methods present different priority sequence. First we initialized an array of scores for 8 methods, each entry of which corresponds to a method in [Random, PA, RPA, RAPA, LP, RLP, SA, RSA]. For various congested scenarios, we test all the methods to recover the links respectively. Once a method gets the lowest order parameter in a scenario, it scores 1, which will be recorded in the array. Repeat the experiment for a number of runs, one can find the method with highest score, which is considered as the best solution.

3. Result

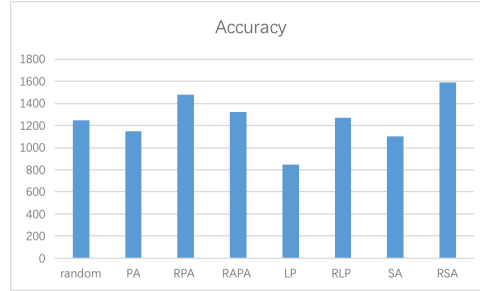


FIG. 1: In this experiment, we first create a California road network, the data was obtained from stanford Datasets. Intersections and endpoints are represented by nodes and the roads connecting these intersections or road endpoints are represented by undirected edges. The network contains 1,965,206 nodes and 2,766,607 edges. Since the network is too large to process, so we need to select a part of the graph. We randomly choose a node from the network, like `nodeId= 800120`, then we regard the node as the central node, next we use the central node to spread out the network, just like BFS algorithm. Here in this experiment, we set the spread level equals 15, and we get the network with 223 nodes and 291 edges.

Since road network has the lowest heterogeneity among BA and USAir, the degree of the nodes in the network mainly lies in 1,2,3,4,5, so it is hard to identify the important of the edges. But from 10,000 round of comparison, our experiment still reveals the Negative Correlation effect in road network. RPA, RAPA, RLP, RSA performs better than random way, and PA, LP, SA performs badly. From the fig1, we can observe that RSA performs best, I think this may be the reason that we have fully utilize the information of one node in the situation of low heterogeneity. This phenomenon also remind us to use more similarity information to improve the performance of road recovery.

USAir is a kind of transportation system. We can see RAPA always performs best, then follows as RLP, RSA. With the increasement of R , although negative way still performs better, but the gap between positive and negative ways are becoming smaller, the reason for this phenomenon may be that at a very small value of R , the congestion level of the roads are not serious, so the recovery of the roads can release the congestion level a lot. But with the increase of R and congestion, the recovery of roads can't change the congestion situation a lot, so the difference between the recovery methods isn't as big as above. Since the performance of negative ways overwhelms positive link prediction methods under different traffic flow rate, so our methods proves to be robustness. Since normal traffic system won't be too congested, so negative methods can be far more better than random recover the routes.

A lot of traffic system can be modeled as BA network. From fig.3 we can see with the increasement of fraction ratio, negative recovery methods perform far more better than random method and positive one's. At the fraction ratio of 0.4, in 1000 round experiment, RSA method performs best in about 600 round comparison, RPA and RAPA

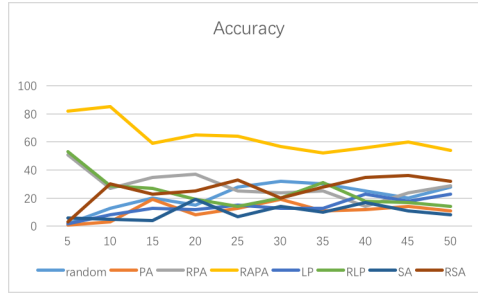


FIG. 2: In order to verify the robust of different methods. We have controlled the value of R. In the above experiment, we create a USAir network, it has 332 nodes and 2126 edges. We then set the ratio of destroyed edges equals to 0.05. Under different R, we got the algorithm's performance as above.

R	5	10	15	20	25	30	35	40	45	50
Order parameter	0.005	0.24	0.34	0.46	0.54	0.60	0.64	0.68	0.70	0.73

TABLE II: Correspond to Fig.2, the average order parameter in different value of R.

performs about 200 round best respectively while other methods almost have no chance in the guidance of traffic recovery. I think there are two reason for the result, with the increasement of fraction ratio, the recovery sequences have more combination so we can differentiate them more easily. Another reason is that big fraction ratio requires more time in the recovery process, in a larger period of time, we can verify our methods more easily.

In fig.4 we can see that when the network contains 100 nodes, eight methods haven't much difference in the traffic recovery, this is mainly because that at a very small network there are no big difference for each node so we can't distinguish them clearly. But when the size of the net reaches a certain scale nodes in the network play roles quite differently, hub nodes and normal nodes can't be the same. When the size of BA network reaches 200, the difference of performance can be observed easily. With the increasement of BA size, negative recovery methods perform better than random method and positive methods. At the size of 500, positive ways almost have no chance in accurately recover the routes in a certain sequence. The reason for that negative methods in larger BA network plays better mainly because the larger BA network has larger heterogeneity, so the nodes play roles differently and we can distinguish them more easily. Normally traffic system won't be too small, they usually contain nodes over 200, so our negative ways can be of use in routes recovery especially the reverse similarity(RSA) method.

CONCLUSION

Traffic problem affect the operation efficiency of the society, current study mainly focus on add new route or rebuild the network. But even the best system can't avoid congestion entirely. Our methods mainly focus on how to recover the routes sequences in a certain order to minimize the negative impact. Inspired by link prediction methods, we have recovered the the route in three strategies. These strategies are positive ways which include PA, LP and SA; negative ways which include RPA, RAPA, RLP and RSA; random way. From our experiment we find that negative ways perform better than the random recover of routes, random way are better than positive ways which is obviously since negative ways and positive ways are reverse methods. Beside the verification of negative link prediction methods in routes recovery. We also find that larger network can improve negative link prediction methods' accuracy; Higher degree heterogeneity improves experiment accuracy also, so negative methods are effective especially for BA like topological; At a high level of congested routes like half of the routes have been broken, negative methods almost have accuracy of 100% in the routes recovery.

Our study is tentative in using link prediction methods solving traffic problem, our result shows a tremendous potential combine link prediction methodology and real traffic problem. Since few people have doing researches in this field, so there are many shortcomings to be further optimized. In lack of real traffic flow data, so we simplified our simulation with a certain rate of packages generated in a certain time step. If possible, further studies can obtain real traffic flow and doing recovery experiment. Also weighted networks deserve to be discussed. In all, our research have found some simple ways to recover the congested ways efficiently, this may a new branch in the traffic problem.

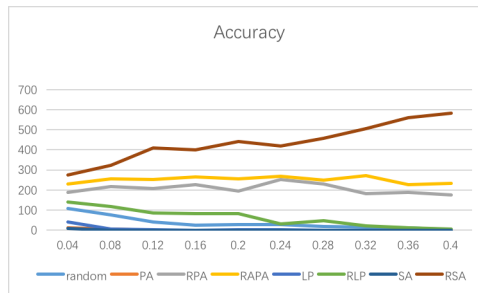


FIG. 3: In order to know how congestion ratio affect the recovery of traffic. We have generate a BA network with 256 nodes and 508 edges, x-axis represent the ratio of congested route. In the above picture, 0.04 means there are $\text{int}(0.04 \times 508)$ edges have been congested. Y-axis represent the accurate prediction sequences in 1000 round experiment. The packages generated in one time step is 10.

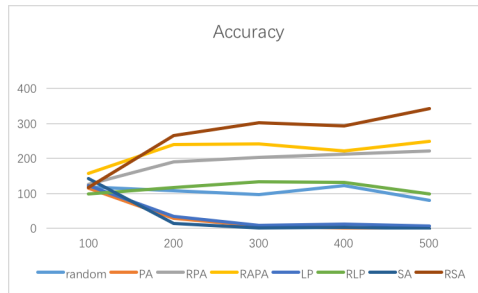


FIG. 4: To test our methods in different size of networks, we have generate five BA networks, they contain nodes with 100, 200, 300, 400, 500 respectively. The probability for each node to generate a package in one time step is 0.02 and the fraction ratio is 0.05.

Author contributions

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