Image Processing

Lecture Notes: The Point Processing of Images

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Point Processing of Images

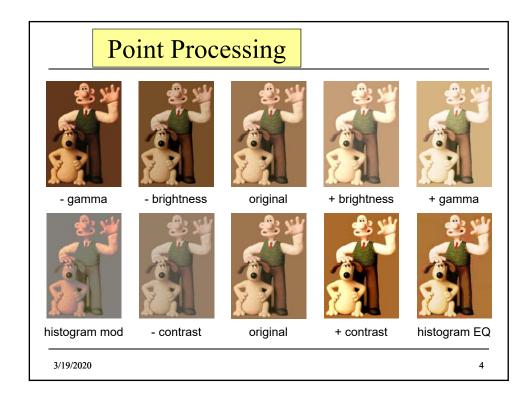
- m In a digital image, point = pixel.
- Point processing transforms a pixel's value as function of its value alone;
- m it does not depend on the values of the pixel's neighbors.

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Point Processing of Images

- m Brightness and contrast adjustment
- m Gamma correction
- m Histogram equalization
- m Histogram matching
- ^m Color correction.

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The Histogram of a Grayscale Image

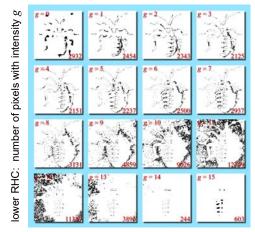
- ^m Let *I* be a 1-band (grayscale) image.
- $_{m}$ I(r,c) is an 8-bit integer between 0 and 255.
- ^m Histogram, h_I , of I:
 - a 256-element array, h_I
 - $h_I(g)$, for g = 1, 2, 3, ..., 256, is an integer
 - $h_I(g)$ = number of pixels in I that have value g-1.

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The Histogram of a Grayscale Image



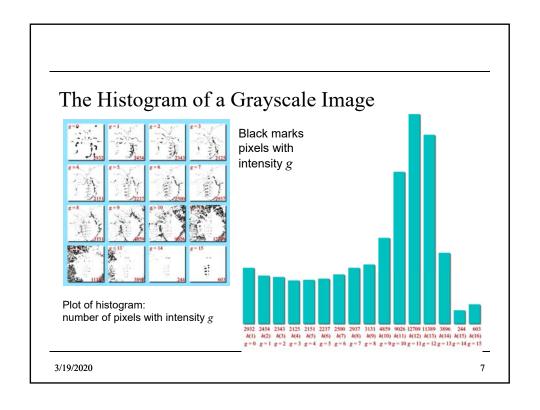
16-level (4-bit) image

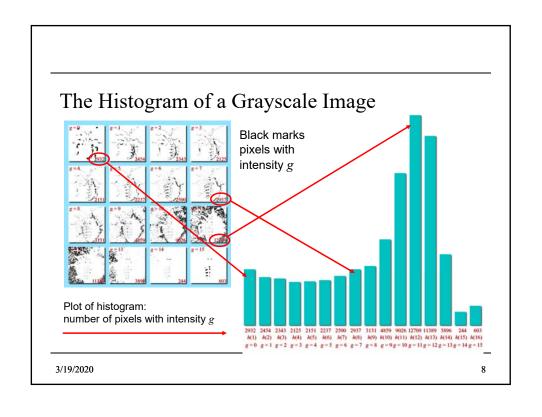


black marks pixels with intensity \boldsymbol{g}

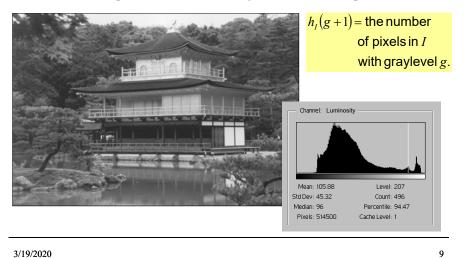
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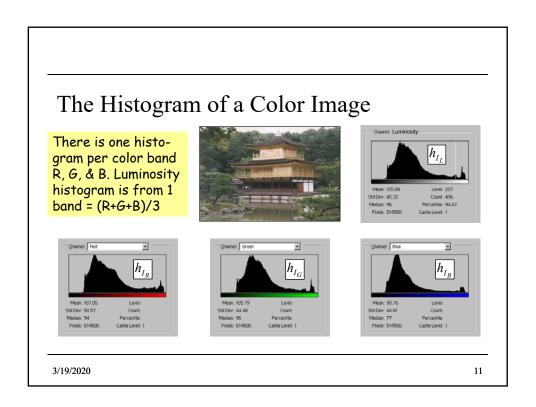


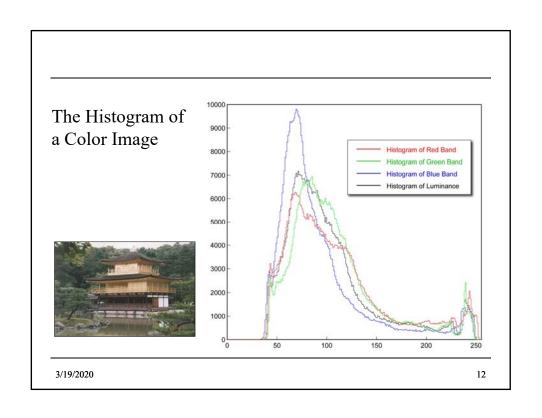
The Histogram of a Grayscale Image



The Histogram of a Color Image

- m If I is a 3-band image (truecolor, 24-bit)
- then I(r,c,b) is an integer between 0 and 255.
- m Either I has 3 histograms:
 - $h_R(g+1) = \#$ of pixels in I(:,:,1) with intensity value g
 - $h_G(g+1) = \#$ of pixels in I(:,:,2) with intensity value g
 - $h_B(g+1) = \#$ of pixels in I(:,:,3) with intensity value g
- m or 1 vector-valued histogram, h(g, 1, b) where
 - h(g+1,1,1) = # of pixels in I with red intensity value g
 - h(g+1,1,2) = # of pixels in I with green intensity value g
 - h(g+1,1,3) = # of pixels in I with blue intensity value g





Value or Luminance Histograms

The value histogram of a 3-band (truecolor) image, *I*, is the histogram of the value image,

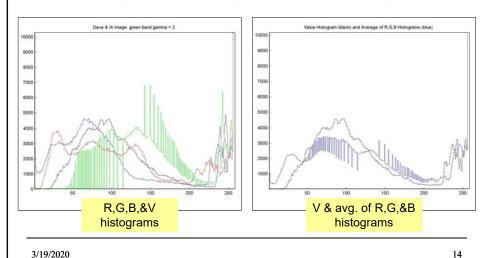
$$V(r,c) = \frac{1}{3} [R(r,c) + G(r,c) + B(r,c)]$$

Where R, G, and B are the red, green, and blue bands of I. The luminance histogram of *I* is the histogram of the luminance image,

$$L(r,c) = 0.299 \cdot R(r,c) + 0.587 \cdot G(r,c) + 0.114 \cdot B(r,c)$$

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Value Histogram vs. Average of R,G,&B Histograms



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Multi-Band Histogram Calculator in Matlab

```
% Multi-band histogram calculator
function h=histogram(I)

[R C B]=size(I);

% allocate the histogram
h=zeros(256,1,B);

% range through the intensity values
for g=0:255
    h(g+1,1,:) = sum(sum(I==g)); % accumulate
end
return;
```

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Multi-Band Histogram Calculator in Matlab

```
% Multi-band histogram calc
                                       Loop through all intensity levels (0-255)
function h=histogram(I)
                                       Tag the elements that have value g.
                                       The result is an RxCxB logical array that
[R C B]=size(I);
                                       has a 1 wherever I(r,c,b) = g and 0's
                                       everywhere else.
                                       Compute the number of ones in each band of
% allocate the histogram
                                       the image for intensity g.
Store that value in the 256x1xB histogram
h=zeros(256,1,B);
% range through the intensi \frac{a^{\dagger} h(g^{+1},1,b)}{a^{\dagger}}
for g=0:255
   h(g+1,1,:) = sum(sum(I==g)); % accumulate
                                         sum(sum(I==q)) computes one number
If B==3, then h(g+1,1,:) contains 3
                                         for each band in the image.
numbers: the number of pixels in
bands 1, 2, & 3 that have intensity g.
```

Point Ops via Functional Mappings

Image: $I \longrightarrow \Phi$, point operator

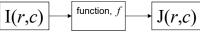
 $J = \Phi[I]$

Input

Output

J

Pixel:



If I(r,c)=gand f(g)=kthen J(r,c)=k.

The transformation of image I into image J is accomplished by replacing each input intensity, g, with a specific output intensity, k, at every location (r,c) where I(r,c) = g.

The rule that associates k with g is usually specified with a function, f, so that f(g) = k.

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Point Ops via Functional Mappings

One-band Image

$$J(r,c) = f(I(r,c)),$$

for all pixels locations (r,c).

Three-band Image

$$J(r,c,b) = f(I(r,c,b)), \text{ or }$$

$$J(r,c,b) = f_b(I(r,c,b)),$$

for b = 1,2,3 and all (r,c).

Point Ops via Functional Mappings

One-band Image

Either all 3 bands are mapped through the same function, f or ...

Three-band Image

$$J(r,c) = f(I(r,c)),$$

for all pixels locations (r,c) .

$$J(r,c,b) = f(I(r,c,b)), \text{ or } J(r,c,b) = f_b(I(r,c,b)),$$

for b = 1,2,3 and all (r,c) ... each band is

... each band is mapped through a separate function, f_b.

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Point Operations using Look-up Tables

A look-up table (LUT) implements a functional mapping.

If k = f(g), for g = 0,...,255, and if k takes on values in $\{0,...,255\}$, ...



... then the LUT that implements fis a 256x1 array whose $(g+1)^{th}$ value is k = f(g).

To remap a 1-band

image, I, to J:

 $J = \mathsf{LUT}(I+1)$

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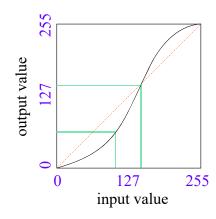
Point Operations using Look-up Tables

If *I* is 3-band, then

- a) each band is mapped separately using the same LUT for each band *or*
- b) each band is mapped using different LUTs one for each band.
 - a) J = LUT(I+1), or
 - b) $J(:,:,b) = LUT_b(I(:,:,b)+1)$ for b = 1,2,3.

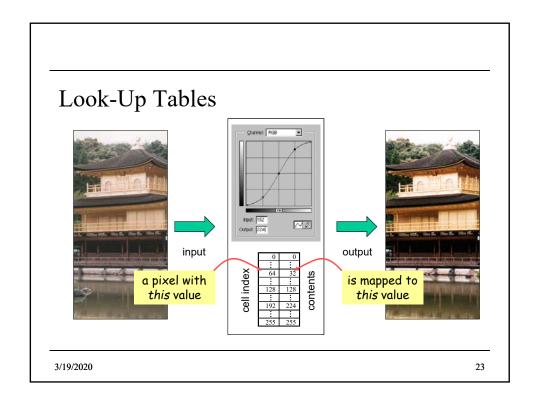
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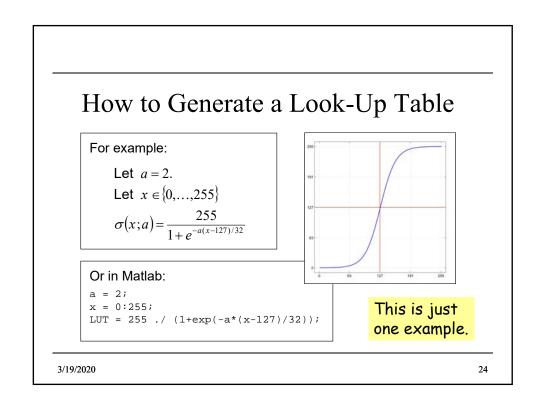
Point Operations = Look-up Table Ops



<i>E.g.</i> :	index	value
	101	64
	102	68
	103	69
	104	70
	105	70
	106	71

input output

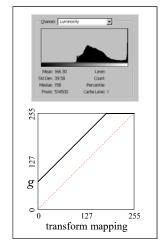




Point Processes: Increase Brightness



$$\begin{split} J_k(r,c) &= \begin{cases} I_k(r,c) + g, \text{ if } & I_k(r,c) + g < 256 \\ 255, & \text{if } & I_k(r,c) + g > 255 \end{cases} \\ g &\geq 0 \text{ and } k \in \big\{1,2,3\big\} \text{ is the band index.} \end{split}$$

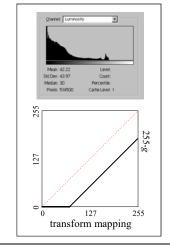


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Point Processes: Decrease Brightness



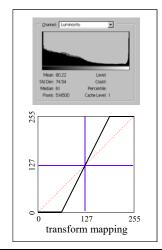
$$\begin{split} J_{\boldsymbol{k}}(\boldsymbol{r},\boldsymbol{c}) &= \begin{cases} 0, & \text{if} \quad I_{\boldsymbol{k}}(\boldsymbol{r},\boldsymbol{c}) - g < 0 \\ I_{\boldsymbol{k}}(\boldsymbol{r},\boldsymbol{c}) - g, & \text{if} \quad I_{\boldsymbol{k}}(\boldsymbol{r},\boldsymbol{c}) \end{cases} \\ g \geq 0 & \text{and} \quad k \in \left\{1,2,3\right\} \text{ is the band index.} \end{split}$$



Point Processes: Increase Contrast



 $\text{Let } T_k(r,c) = a \big[I_k(r,c) - 127 \big] + 127, \text{ where } a > 1.0 \\ J_k(r,c) = \begin{cases} 0, & \text{if } T_k(r,c) < 0, \\ T_k(r,c), & \text{if } 0 \leq T_k(r,c) \leq 255, \\ 255, & \text{if } T_k(r,c) > 255. \end{cases} \quad k \in \{1,2,3\}$

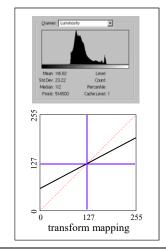


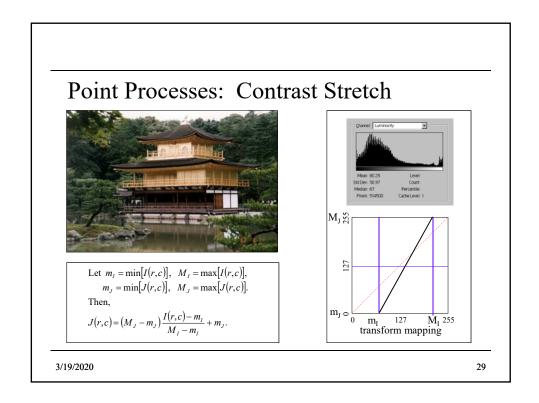
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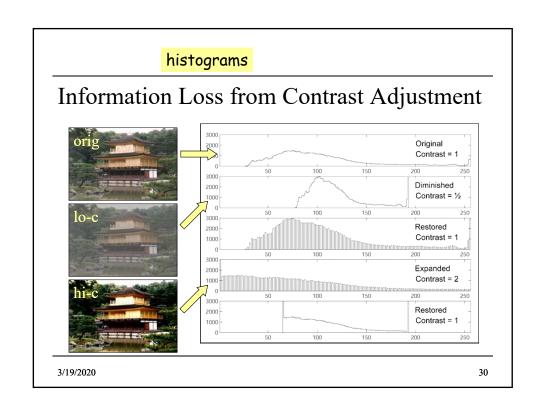
Point Processes: Decrease Contrast

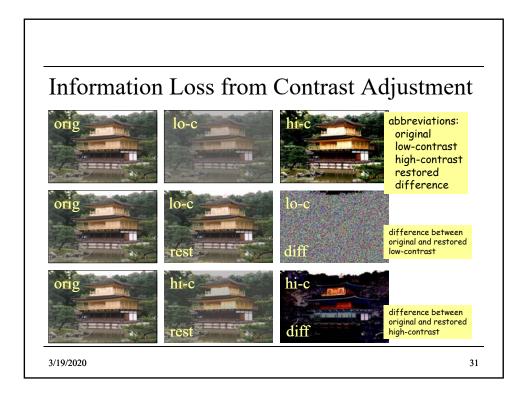


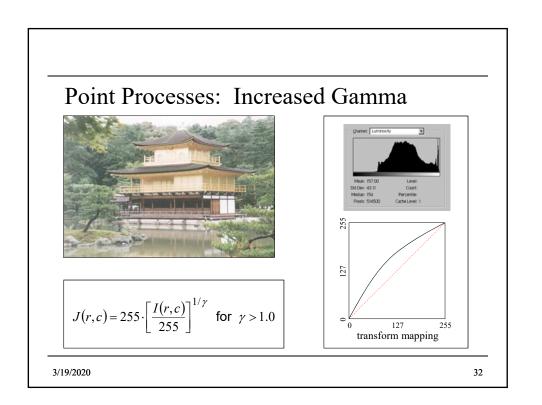
 $T_k(r,c) = a\big[I_k\big(r,c\big) - 127\big] + 127,$ where $0 \le a < 1.0$ and $k \in \{1,2,3\}.$







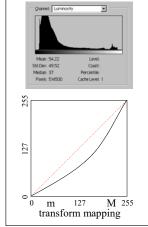


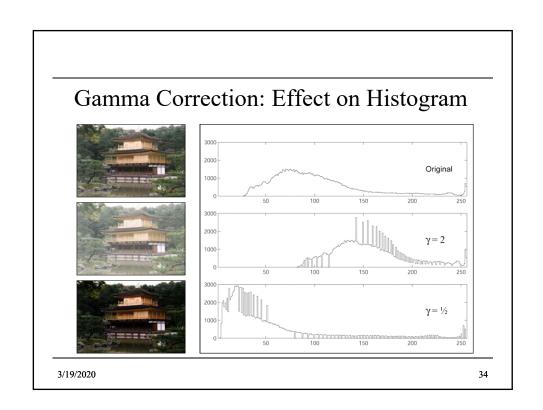


Point Processes: Decreased Gamma



$$J(r,c) = 255 \cdot \left[\frac{I(r,c)}{255} \right]^{1/\gamma}$$
 for $\gamma < 1.0$





The Probability Density Function of an Image

Let
$$A = \sum_{g=0}^{255} h_{I_k}(g+1)$$
. [lower case]

Note that since $h_{I_k}(g+1)$ is the number of pixels in I_k (the k th color band of image I) with value g, A is the number of pixels in I. That is if I is R rows by C columns then $A = R \times C$.

Then, $p_{I_k}(g+1) = \frac{1}{A}h_{I_k}(g+1)$ This is the probability that an arbitrary pixel from I_k has value g.

is the graylevel probability density function of I_k .

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The Probability Density Function of an Image

- $p_{\text{band}}(g+1)$ is the fraction of pixels in (a specific band of) an image that have intensity value g.
- $p_{\text{band}}(g+1)$ is the probability that a pixel randomly selected from the given band has intensity value g.
- Whereas the sum of the histogram $h_{\text{band}}(g+1)$ over all g from 1 to 256 is equal to the number of pixels in the image, the sum of $p_{\text{band}}(g+1)$ over all g is 1.
- p_{band} is the normalized histogram of the band.

The Probability Distribution Function of an Image

Let $\mathbf{q} = [\mathbf{q}_1 \ \mathbf{q}_2 \ \mathbf{q}_3] = I(r,c)$ be the value of a randomly selected pixel from I. Let g be a specific graylevel. The probability that $\mathbf{q}_k \le g$ is given by

$$P_{I_k}(g+1) = \sum_{\gamma=0}^{g} p_{I_k}(\gamma+1) = \frac{1}{A} \sum_{\gamma=0}^{g} h_{I_k}(\gamma+1) = \frac{\sum_{\gamma=0}^{g} h_{I_k}(\gamma+1)}{\sum_{\gamma=0}^{255} h_{I_k}(\gamma+1)},$$

where $h_{lk}(y+1)$ is the histogram of the kth band of I.

This is the probability that any given pixel from I_k has value less than or equal to g.

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The Probability Distribution Function of an Image

Let $\mathbf{q} = [q_1 \ q_2 \ q_3] = I(r,c)$ be the value of a Also called CDF randomly selected pixel from I. Let g be a specific graylevel. The probability that $q_k \le g$ is given by

$$P_{I_k}(g+1) = \sum_{\gamma=0}^{g} p_{I_k}(\gamma+1) = \frac{1}{A} \sum_{\gamma=0}^{g} h_{I_k}(\gamma+1) = \frac{\sum_{\gamma=0}^{g} h_{I_k}(\gamma+1)}{\sum_{\gamma=0}^{255} h_{I_k}(\gamma+1)},$$

where $h_{Ik}(y+1)$ is the histogram of the kth band of I.

This is the probability that any given pixel from I_k has value less than or equal to g.

A.k.a. Cumulative
Distribution Function.

The Probability Distribution Function of an Image

- $P_{\text{band}}(g+1)$ is the fraction of pixels in (a specific band of) an image that have intensity values less than or equal to g.
- $P_{\text{band}}(g+1)$ is the probability that a pixel randomly selected from the given band has an intensity value less than or equal to g.
- $P_{\text{band}}(g+1)$ is the cumulative (or running) sum of $p_{\text{band}}(g+1)$ from 0 through g inclusive.
- $P_{\text{band}}(1) = p_{\text{band}}(1)$ and $P_{\text{band}}(256) = 1$; $P_{\text{band}}(g+1)$ is nondecreasing.

Note: the Probability Distribution Function (PDF, capital letters) and the Cumulative Distribution Function (CDF) are exactly the same things. Both PDF and CDF will refer to it. However, pdf (small letters) is the *density* function.

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Point Processes: Histogram Equalization

Task: remap image I so that its histogram is as close to constant as possible

Let
$$P_I(\gamma+1)$$

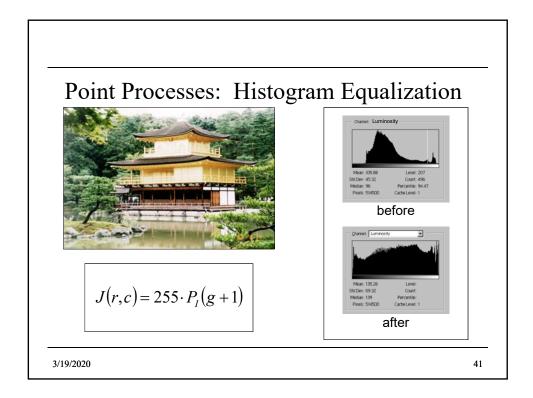
be the cumulative (probability) distribution function of *I*.

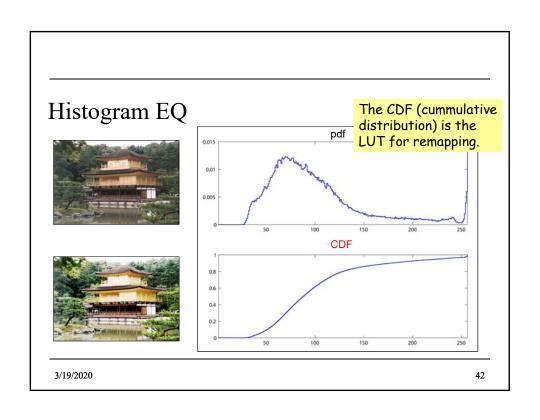
Then J has, as closely as possible, the correct histogram if

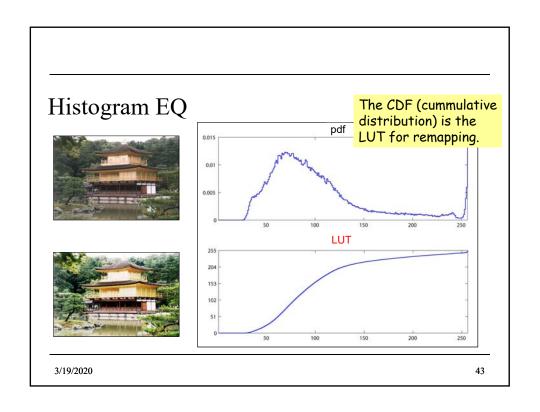
$$J(r,c) = 255 \cdot P_I[I(r,c)+1].$$

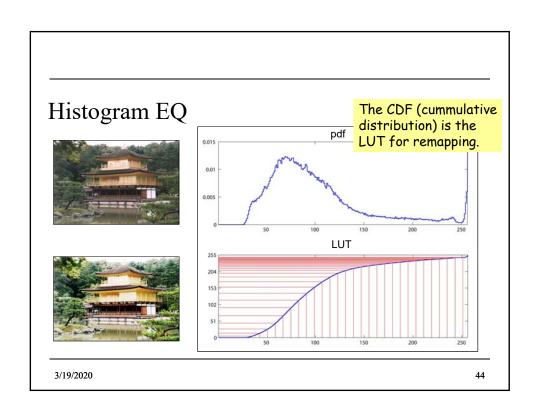
The CDF itself is used as the LUT.

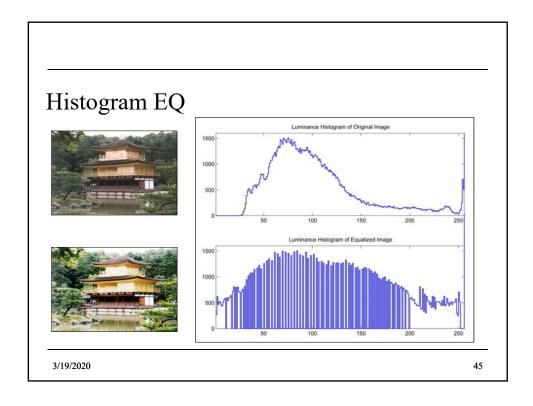
all bands processed similarly











Point Processes: Histogram Equalization

Task: remap image I with min = m_I and max = M_I so that its histogram is as close to constant as possible and has min = m_J and max = M_J .

Let $P_I(\gamma+1)$

be the cumulative (probability) distribution function of *I*.

Then J has, as closely as possible, the correct histogram if

Using intensity extrema

$$J\!\left(r,c\right)\!=\!\left(M_{J}-m_{J}\right)\!\frac{P_{I}\!\left[I\!\left(r,c\right)\!+\!1\right]\!-P_{I}\!\left(m_{I}+1\right)}{1\!-\!P_{I}\!\left(m_{I}+1\right)}+m_{J}.$$

Point Processes: Histogram Matching

Task: remap image I so that it has, as closely as possible, the same histogram as image J.

Because the images are digital it is not, in general, possible to make $h_I \equiv h_J$. Therefore, $p_I \not\equiv p_J$.

Q: How, then, can the matching be done?

A: By matching percentiles.

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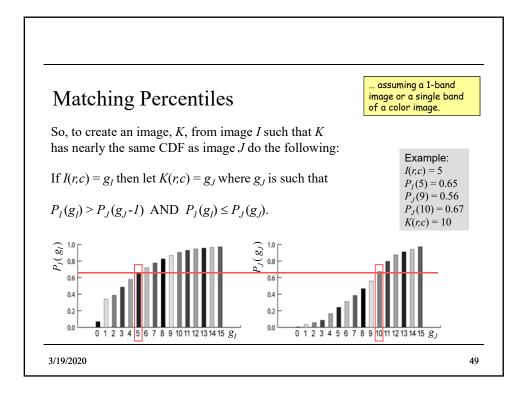
Matching Percentiles

... assuming a 1-band image or a single band of a color image.

Recall:

- The CDF of image *I* is such that $0 \le P_I(g_I) \le 1$.
- $P_I(g_I+1) = c$ means that c is the fraction of pixels in I that have a value less than or equal to g_I .
- 100c is the percentile of pixels in I that are less than or equal to g_I .

To match percentiles, replace all occurrences of value g_I in image I with the value, g_J , from image J whose percentile in J most closely matches the percentile of g_I in image I.



Histogram Matching Algorithm

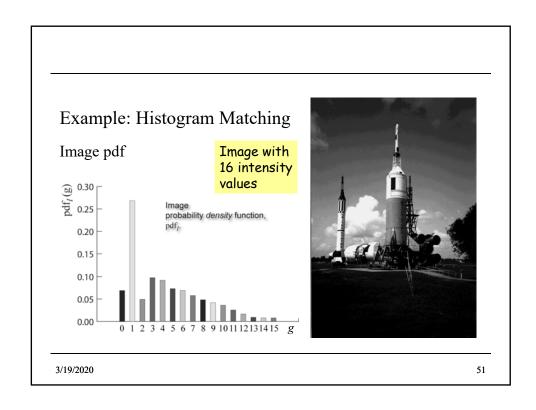
... assuming a 1-band image or a single band of a color image.

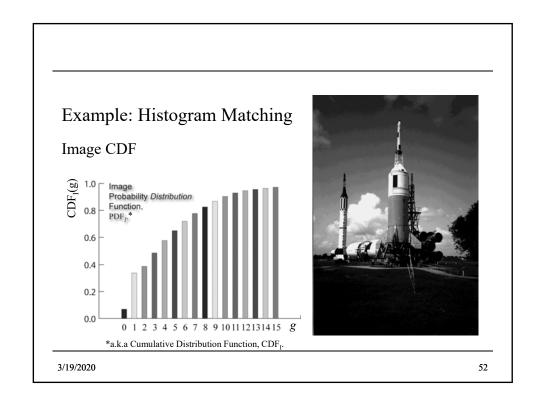
```
[R,C] = \operatorname{size}(I);
K = \operatorname{zeros}(R,C);
g_J = m_J;
\text{for } g_I = m_I \text{ to } M_I
\text{while } g_J < 255 \text{ AND } P_I(g_I+1) < 1 \text{ AND }
P_J(g_J+1) < P_I(g_I+1)
g_J = g_J+1;
\text{end}
K = K + \left[g_J \times \left(I == g_I\right)\right]
end
```

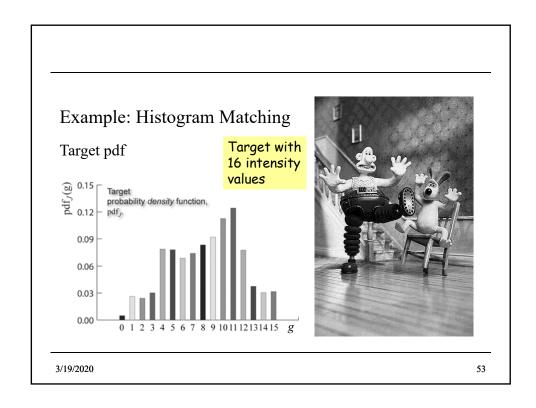
This directly matches image I to image J.

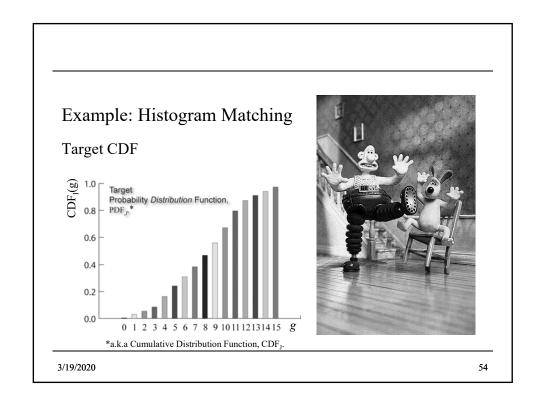
 $P_I(g_I + 1)$: CDF of I $P_J(g_J + 1)$: CDF of J. $m_J = \min J$, $m_J = \max J$, $m_I = \min I$, $M_J = \max I$.

Better to use a LUT. See slide 54.









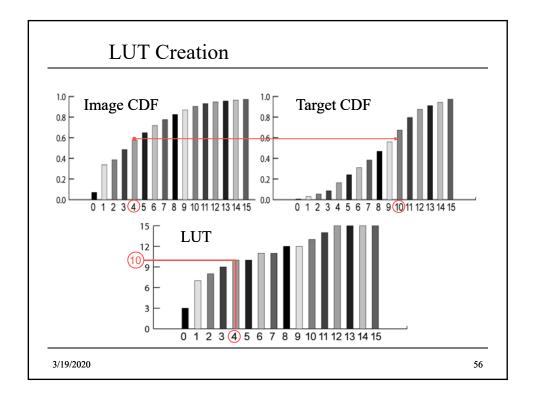
Histogram Matching with a Lookup Table

The algorithm on slide <u>49</u> matches one image to another directly. Often it is faster or more versatile to use a lookup table (LUT). Rather than remapping each pixel in the image separately, one can create a table that indicates to which target value each input value should be mapped. Then

$$K = LUT[I+1]$$

In *Matlab* if the LUT is a 256×1 matrix with values from 0 to 255 and if image *I* is of type **uint8**, it can be remapped with the following code:

K = uint8(LUT(double(I)+1));



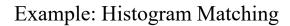
Look Up Table for Histogram Matching

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```
LUT = zeros(256,1); This creates a look-up table which can then be used to remap the image. for g_I = 0 to 255 while P_J(g_J + 1) < P_I(g_I + 1) AND g_J < 255 g_J = g_J + 1; end LUT(g_I + 1) = g_J; P_J(g_J + 1) : CDF \text{ of } J, end LUT(g_I + 1) : Look-Up Table
```

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Input & Target CDFs, LUT and Resultant CDF $\frac{\sum_{0}^{1.0} \sum_{0.8}^{1.0} \sum_{0.6}^{1.0} \sum_{0.6}^{1.$









original

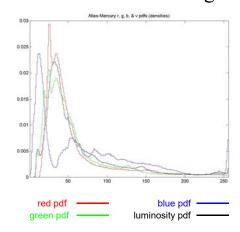
target

remapped

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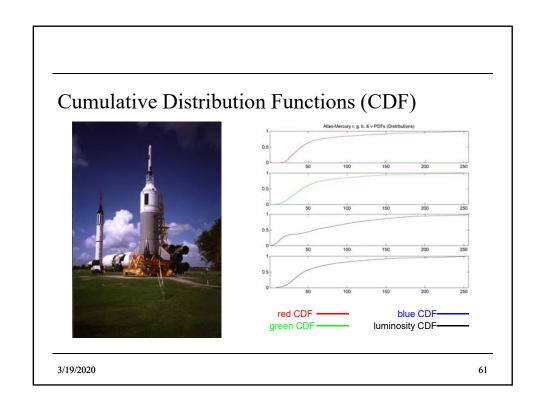
Probability Density Functions of a Color Image

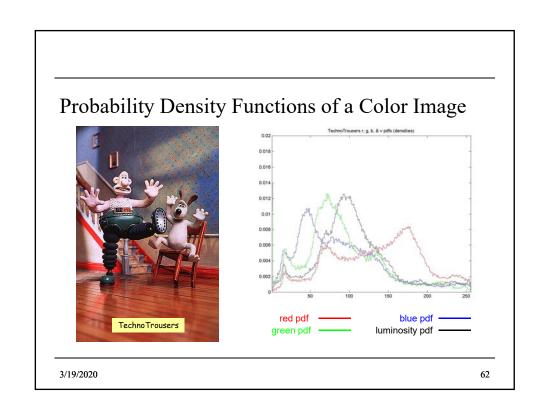


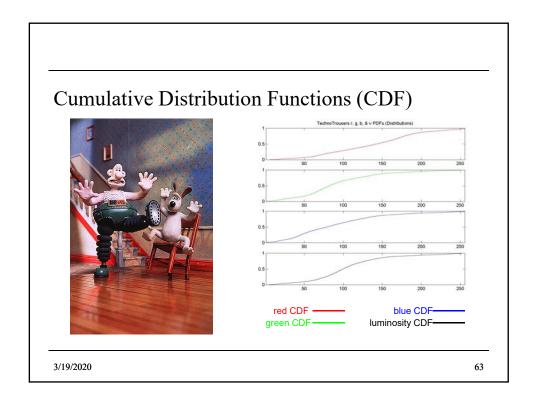


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Remap an Image to have the Lum. CDF of Another







original

target

luminosity remapped

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