

```
mk/PX4/ROMFS/init.d  
rcS
```

```
sh /etc/init.d/rc.APM
```

```
mk/PX4/ROMFS/init.d  
rc.APM
```

```
if ArduPilot start
```

```
build/px4-v2/modules/PX4Firmware/src/firmware/nuttx/  
builtin_commands.c
```

```
ArduPilot_main
```

```
libraries/AP_HAL/  
AP_HAL_Main.h
```

```
#define AP_MAIN __EXPORT ArduPilot_main
```

```
hal.run(argc, argv, CALLBACKS);
```