

```

#include <mbed.h>

#include <MMA7455.h>

#include <LM75B.h>

#include <display.h>


//Declare output object for LED1
DigitalOut led1(LED1);


// Initialise Joystick
typedef enum {JLT = 0, JRT, JUP, JDN, JCR} btnId_t;
static DigitalIn jsBtns[] = {P5_0, P5_4, P5_2, P5_1, P5_3}; // LFT, RGHT, UP, DWN, CTR
bool jsPrsdAndRlsd(btnId_t b);


//Object to manage the accelerometer
MMA7455 acc(P0_27, P0_28);
bool accInit(MMA7455& acc); //prototype of init routine
int32_t accVal[3];


//Input object for the potentiometer
AnalogIn pot(p15);
float potVal = 0.0;


Display *screen = Display::theDisplay();
//This is how you call a static method of class Display
//Returns a pointer to an object that manages the display screen


//Timer interrupt and handler
void timerHandler(); //prototype of handler function
int tickCt = 0;

```

```

    /*****
*****

```

```

    /*****STRUCTS AND
ENUMS*****

```

```

    /*****
*****

```

```

    typedef struct{
        int x, y;
        int vx, vy;
        int colour;
    } ball_t;

```

```

    typedef enum{ // the position of each wall with the right
cordinates

```

```

        LEFTWALL = 0,
        RIGHTWALL = 480,
        TOPWALL = 10,
        BOTTOMWALL = 272
    } walls_t;

```

```

    /*****
*****

```

```

    /*****VARIABLES*****
*****

```

```

    /*****
*****

```

```

    void InitMagic();
    void magicTimeCheck();

```

```
magicTimeInterval, magicTimeDuration;
```

```
int magicTime, ticker, magicTimeCt,
```

```
int paddle;
```

```
int lineX;
```

```
int lineLength;
```

```
int score;
```

```
int scrInc = 1;
```

```
int total;
```

```
int multiplier;
```

```
int remainingBalls;
```

```
/*  
*****/  

```

```
/*  
*****FUNCTION  
PROTOTYPES*****  
*/  

```

```
/*  
*****/  

```

```
ball_t initBallAndBat(ball_t b);
```

```
void ballRendering(ball_t b);
```

```
ball_t moveBall(ball_t b);
```

```
ball_t readDevices(ball_t b);
```

```
void renderPaddle(int x);
```

```
void waitForStart();
```

```
int initialiseGame();
```

```
int chekcBtmWall(ball_t b);
```

```
void initDevices();
```

```
void displayUpdate(ball_t b);
```

```
void scorePoint();
```

```
void gameOver(ball_t b);
```

```
ball_t ball;
```

```
ball_t b;
```

```
/*  
*****  
*/
```

```
/*  
*****MAIN  
FUNCTION*****  
*/
```

```
/*  
*****  
*/
```

```
int main() {
```

```
    // Initialise the display
```

```
    Ticker ticktock;
```

```
    ticktock.attach(&timerHandler, 1);
```

```
    ball_t ball;
```

```
    int inPlay;
```

```
    initDevices();
```

```
    remainingBalls = initialiseGame();
```

```
    while(true){
```

```
        while(remainingBalls > 0){
```

```
            waitForStart();
```

```
            inPlay = 1;
```

```
            InitMagic();
```

```
            ball = initBallAndBat(ball);
```

```
            displayUpdate(ball);
```

```
            ballRendering(ball);
```

```
            ball = moveBall(ball);
```

```
            while(inPlay){
```

```
                magicTimeCheck();
```

```
                displayUpdate(ball);
```

```

ballRendering(ball);
ball = readDevices(ball);
ball = moveBall(ball);
renderPaddle(paddle);
inPlay = chekcBtmWall(ball);
if(!inPlay){
    gameOver(ball);
}

wait(0.005); //5
milliseconds

}

}

screen->setCursor(2,2);
screen->printf("GAME OVER! Your Total
score : %d , Press center on joystic to reset ", total);
waitForStart();
total = 0;
remainingBalls = initialiseGame();
}

}

/*****
*****/

/*****BALL AND PADDLE MOVEMENT +
OBSTACLE*****/

```

```

/*****
*****/

```

```

ball_t initBallAndBat(ball_t b){ // takes ball_t as @param

    //randomise b.vx's sign and b.vy using rand
    int random = rand()% 2;
    int random2 = rand()% 2;

    //randomise bat and ball starting positions
    paddle = 160 + rand() % (321 - 160); // randomises
the position fo the paddle/Bat

    b.x = 160 + rand() % (281 - 160); // randomises the
position of ball

    b.y = 40;
    if(random == 0){
        b.vx = 1;
    }else{
        b.vx = -1;
    }

    //randomise 2 different speeds for the ball, and pick
one.

    if(random2 == 0){
        b.vy = 2;
    }else if(random2 == 1){
        b.vy = 3;
    }

    //randomise the length and the postion of the extra
obstacle

    lineX = 0 + rand() % (0 - 281);

```

```

        lineLength = 40 + rand() % (40 - 201);

        b.colour = BLUE;

        return b;
    }

void ballRendering(ball_t b){
    screen->fillCircle(b.x, b.y, 5, WHITE);
}

/*****
*****/

/*****COLLISION CHECKS AND
MOVEMENT*****/

/*****
*****/

ball_t moveBall(ball_t b){
    //side wall and top wall collision checks
    if(((b.x + b.vx) >= RIGHTWALL) || ((b.x + b.vx) <=
LEFTWALL)){

        b.vx = -b.vx;

    }

    else if(((b.y + b.vy) <= TOPWALL)){
        multiplier++;
        scorePoint();
        b.vy = -b.vy;
    }

    //bat collision checks

```

```

else if(((b.y + b.vy) >= 258) && ((b.x + b.vx) >= paddle) &&
((b.x + b.vx) <= (paddle + 40))){

    b.vy = -b.vy;

}

//obstacle collision checks - accounts for variable y velocity
(2 - 3)

else if((((b.y + b.vy) == 60) || ((b.y + b.vy) == 61) || ((b.y +
b.vy) == 59)) &&

((b.x + b.vx) >= lineX) &&
((b.x + b.vx) <= lineX + lineLength)){

    b.vy = -b.vy;

}

if (magicTime) {
    b.colour = RED;
}else{
    b.colour = BLUE;
}

b.x += b.vx;
b.y += b.vy;
screen->fillCircle(b.x, b.y, 5, b.colour);
return b;
}

int chekcBtmWall(ball_t b){
    return b.y + b.vy < 272;
}

void renderPaddle(int x){

```



```
screen->fillRect(paddle, 258, 40, 4, BLACK);
```

```
}
```

```
    /*****  
***** /
```

```
    /*****DRAW OBJECTS ON SCREEN AND BAT  
CONTROLS*****/
```

```
    /*****  
***** /
```

```
ball_t readDevices(ball_t b){  
    acc.read(accVal[0], accVal[1], accVal[2]);  
    screen->fillRect(paddle, 258, 40, 4, WHITE); // clear  
old bat  
    // check for inputs and possible boundary oversteps  
    if (jsBtns[1].read() == 0) {  
        if((paddle - 1) >= LEFTWALL){  
            paddle -= 2;  
        }  
    } else if (jsBtns[0].read() == 0) {  
        if(((paddle + 1) + 40) <= RIGHTWALL){  
            paddle += 2;  
        }  
    } else if (accVal[0] < -10){  
        if((paddle - 1) >= LEFTWALL){  
            paddle -= 2;  
        }  
    } else if (accVal[0] > 10){  
        if(((paddle + 1) + 40) <= RIGHTWALL){  
            paddle += 2;  
        }  
    }  
}
```

based on them

```
    }  
}  
//check for potentiometer readings, change speed  
  
potVal = pot.read();  
if(potVal < 0.33f){  
    if(b.vy < 0){  
        b.vy = -1;  
    }else{  
        b.vy = 1;  
    }  
}else if((potVal > 0.33f)&&(potVal <=0.66f)){  
    if(b.vy < 0){  
        b.vy = -2;  
    }else{  
        b.vy = 2;  
    }  
}else if((potVal > 0.66f)&&(potVal <= 1)){  
    if(b.vy < 0){  
        b.vy = -3;  
    }else{  
        b.vy = 3;  
    }  
}  
return b;  
}
```

```
    /*****  
    *****/
```

```

/*****MAGIC TIME AND INTERRUPT AND
SCORE*****/

```

```

/*****
*****/

```

```

void timerHandler() {
    if(ticker){
        tickCt++;
        if(tickCt== 11){
            tickCt = 0;
        }
    }

    else if (magicTime) {
        magicTimeCt++;
        if (magicTimeCt==11){
            magicTimeCt = 0;
        }
    }
}

```

```

void InitMagic(){
    ticker = 1;
    magicTime = 0;
    magicTimeInterval = 5 + rand() % (11-5);
    magicTimeDuration = 2 + rand() % (11-2);
}

```

```

void magicTimeCheck(){
    if (tickCt == magicTimeInterval){
        ticker = 0;
        magicTime = 1;
    }
}

```

```

        tickCt = 0;

    }else if (magicTimeCt == magicTimeDuration){

        ticker = 1;

        magicTime = 0;

        magicTimeCt = 0 ;

        magicTimeInterval = 5 + rand() % (11-5);

        magicTimeDuration = 2 + rand() % (11-2);

    }

}

```

```

void scorePoint(){

    if ((multiplier % 5 ) == 0){

        scrInc = 1 + (multiplier / 5);

    }

    if (magicTime) {

        score += (2 * scrInc);

    }

    else{

        score += scrInc;

    }

}

```

```

/*****
*****/

```

```

/*****DEVICE INITIALISATION AND GAME
INIT*****/

```

```

/*****
*****/

```

```

int initialiseGame(){

    // sets balls left to 5

```

```

        return 5;
    }

    void initDevices(){
        screen->fillScreen(WHITE);
        screen->setTextColor(BLACK, WHITE);
        // Initialise accelerometer and temperature sensor
    }

    /*****
    *****/

    /*****DISPLAY*****/
    *****/

    /*****
    *****/

    void displayUpdate(ball_t b){
        screen->setCursor(2,2);
        screen->printf("Score: [%d] | multiplier: [%d] |
Total: [%d] | Balls remaining: [%d] ",
score, multiplier, total, remainingBalls);
        screen->drawLine(lineX, 60, lineX + lineLength, 60,
GREEN);
    }

    /*****
    *****/

    /*****START ANG GAME
OVER*****/

```

```

/*****
*****/

```

```

        void waitForStart(){
            while (!jsPrsdAndRlsd(JCR)){
                //do nothing!
            }
        }

        void gameOver(ball_t b){
            remainingBalls--;
            screen->fillCircle(b.x, b.y, 5, WHITE);
            screen->fillRect(paddle, 258, 40, 4, WHITE);
            screen->drawLine(lineX, 60, lineX + lineLength, 60,
WHITE);

            multiplier = 0;
            total += score;
            score = 0;
            scrInc = 1;
            magicTime = 0;
            ticker = 0;
            tickCt = 0;
            magicTimeCt = 0;

        }

```

/\* Definition of Joystick press capture function

- \* b is one of JLEFT, JRIGHT, JUP, JDOWN - from enum, 0, 1, 2, 3
- \* Returns true if this Joystick pressed then released, false otherwise.
- \*
- \* If the value of the button's pin is 0 then the button is being pressed,
- \* just remember this in savedState.
- \* If the value of the button's pin is 1 then the button is released, so

```
* if the savedState of the button is 0, then the result is true, otherwise
* the result is false. */
```

```
bool jsPrsdAndRlsd(btnId_t b) {
    bool result = false;
    uint32_t state;
    static uint32_t savedState[5] = {1,1,1,1,1};
    //initially all 1s: nothing pressed
    state = jsBtns[b].read();
    if ((savedState[b] == 0) && (state == 1)) {
        result = true;
    }
    savedState[b] = state;
    return result;
}
```

```
bool accInit(MMA7455& acc) {
    bool result = true;
    if (!acc.setMode(MMA7455::ModeMeasurement)) {
        // screen->printf("Unable to set mode for MMA7455!\n");
        result = false;
    }
    if (!acc.calibrate()) {
        // screen->printf("Failed to calibrate MMA7455!\n");
        result = false;
    }
    // screen->printf("MMA7455 initialised\n");
    return result;
}
```