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# Lecture Notes and Exercises in Introductory Abstract Algebra

Adopted from lectures, notes, and exercises by

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# Chapter 0

# **Foundations**

### 0.1 Prerequisites, conventions, and notation

We will assume the reader is familiar with the concept of a set, set-builder notation, and basic set operations. By convention, the set of natural numbers  $\mathbb{N}$  will be taken to start from 1.

### 0.2 Sets and relations

**Definition 0.2.1.** For two sets A and B, any subset of  $A \times B$  is called a relation, and for all (a, b) in this relation, we say a is related to b, denoted, for example, by  $a \sim b$ .

**Definition 0.2.2.** A relation  $a \sim b$  is called an equivalence relation if it is

- 1. reflexive: for every a, we have  $a \sim a$ ;
- 2. symmetric: for every a, b such that  $a \sim b$ , we have  $b \sim a$ ; and
- 3. transitive: for every a, b, c such that  $a \sim b$  and  $b \sim c$ , we have  $a \sim c$ .

**Definition 0.2.3.** The set  $[a] = \{b \mid a \sim b\}$  is called the equivalence class of a.

**Theorem 0.2.4.** Let  $\sim$  be an equivalence relation on a set X. Then, the equivalence classes are disjoint and form a partition of X.

*Proof.* Let  $x_1, x_2 \in X$  and consider the equivalence classes  $[x_1]$  and  $[x_2]$ . Suppose they are not disjoint. Then, there exists a y such that  $y \in [x_1] \cap [x_2]$ , so  $x_1 \sim y$  and  $x_2 \sim y$ . By the symmetric property,  $x_1 \sim y$  and  $y \sim x_2$ , so by the transitive property,  $x_1 \sim x_2$ .

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Now let x \in [x_1]. Then, x_1 \sim x, and since x_1 \sim x_2, we have x_2 \sim x, so x \in [x_2]. Thus, [x_1] \subseteq [x_2], and similarly, [x_2] \subseteq [x_1], so [x_1] = [x_2].
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# 0.3 Examples of proofs

**Claim 0.3.1** (For a direct proof). The product of two odd numbers is odd.

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*Proof.* Let a and b be odd. Then, a = 2n + 1 and b = 2k + 1 for some  $n, k \in \mathbb{Z}$ , so we have

$$ab = (2n + 1)(2k + 1) = 4nk + 2n + 2k + 1 = 2(2nk + n + k) + 1$$

which is odd since  $2nk + n + k \in \mathbb{Z}$ .

**Claim 0.3.2** (For a proof by contraposition). Let  $n \in \mathbb{Z}$ . If  $n^2$  is odd, then n is odd.

*Proof.* Suppose *n* is even. Then, n = 2k for some  $k \in \mathbb{Z}$ , so

$$n^2 = (2k)^2 = 4k^2 = 2(2k^2)$$

which is even since  $2k^2 \in \mathbb{Z}$ . Hence, if  $n^2$  is odd, then n is odd.

**Claim 0.3.3** (For a proof by contradiction). Let  $p \in \mathbb{Z}$ . If p is prime, then  $\sqrt{p} \notin \mathbb{Q}$ .

*Proof.* Suppose  $\sqrt{p} \in \mathbb{Q}$ . Then, there exist some  $a,b \in \mathbb{Z}$ ,  $b \neq 0$  such that  $\sqrt{p} = a/b$ . Without loss of generality, assume  $\gcd(a,b) = 1$ . We see

$$p = \left(\frac{a}{b}\right)^2 = \frac{a^2}{b^2} \iff pb^2 = a^2 \implies p \mid a^2,$$

and since p is prime, we see  $p \mid a$ . There must then exist some  $n \in \mathbb{Z}$  such that a = np, so

$$pb^2 = a^2 = (np)^2 = n^2p^2 \iff b^2 = n^2p \implies p \mid b^2 \iff p \mid b.$$

Thus, p divides both a and b, but this is a contradiction since gcd(a,b) = 1. Hence,  $\sqrt{p} \notin \mathbb{Q}$ .

**Claim 0.3.4** (For a proof by induction). Let  $n \in \mathbb{N}$ . If  $n \ge 5$ , then  $n! \ge 2^n$ .

*Proof.* For our base step, we see 5! = 120 and  $2^5 = 32$ , so  $5! \ge 2^5$ .

As our inductive hypothesis, assume  $k! \ge 2^k$  for some  $k \ge 5$ . Then,

$$(k+1)k! \ge (k+1)2^k \ge 6 \cdot 2^k \ge 2 \cdot 2^k = 2^{k+1} \implies (k+1)! \ge 2^{k+1}$$
.

Hence,  $n! \ge 2^n$  for all  $n \ge 5$ .

Note that this does not address the fact that  $4! \ge 2^4$ .

### Solved exercises

#### **Set operations**

For each of the following, find  $A \cap B$ ,  $A \cup B$ ,  $A \setminus B$ ,  $B \setminus A$ ,  $A \times B$ , and  $B \times A$ .

**Exercise 0.1.** Let  $A = \{-1, 1\}$  and  $B = \{1, 2, 3\}$ .

Solution. We have

$$A \cap B = \{1\},\$$
 $A \cup B = \{-1, 1, 2, 3\},\$ 
 $A \setminus B = \{-1\},\$ 
 $B \setminus A = \{2, 3\},\$ 
 $A \times B = \{(-1, 1), (-1, 2), (-1, 3), (1, 1), (1, 2), (1, 3)\},\$ 
 $B \times A = \{(1, -1), (1, 1), (2, -1), (2, 1), (3, -1), (3, 1)\}.$ 

**Exercise 0.2.** Let A = [-1, 1] and B = (0, 3].

Solution. We have

$$A \cap B = (0,1],$$
  
 $A \cup B = [-1,3],$   
 $A \setminus B = [-1,0],$   
 $B \setminus A = (1,3],$   
 $A \times B = \{(a,b) \mid a \in [-1,1], b \in (0,3]\},$   
 $B \times A = \{(b,a) \mid b \in (0,3], a \in [-1,1]\}.$ 

**Exercise 0.3.** Let A = (1, 3) and  $B = [0, \infty)$ .

Solution. We have

$$A \cap B = (1,3),$$
  
 $A \cup B = [0,\infty),$   
 $A \setminus B = \emptyset,$   
 $B \setminus A = [0,1] \cup [3,\infty),$   
 $A \times B = \{(a,b) \mid a \in (1,3), b \in [0,\infty)\},$   
 $B \times A = \{(b,a) \mid b \in [0,\infty), a \in (1,3)\}.$ 

#### **Proofs**

Let  $a, b, c \in \mathbb{N}$  where a and b are coprime. Prove the following.

**Exercise 0.4.** If  $a \mid bc$ , then  $a \mid c$ .

*Solution.* Suppose  $a \mid bc$ . Then, there exists some  $n \in \mathbb{Z}$  such that na = bc, so  $b \mid na$ . Now suppose n is not a multiple of b. Then, a and b must share a common factor greater than 1, but a and b are coprime, so this is impossible. Therefore, n must be a multiple of b; that is, there exists some  $k \in \mathbb{Z}$  such that n = kb, so

$$na = bc \iff \frac{n}{b}a = c \iff \frac{bk}{b}a = c \iff ka = c \implies a \mid c.$$

**Exercise 0.5.** If  $a \mid c$  and  $b \mid c$ , then  $ab \mid c$ .

*Solution.* Suppose  $a \mid c$  and  $b \mid c$ . Then, c is a multiple of a, and c is a multiple of b. Let  $p_1p_2\cdots p_n$  be the prime factorization of a, and let  $q_1q_2\cdots q_k$  be the prime factorization of b. Since a and b are coprime, we see  $\{p_1, p_2, \ldots, p_n\} \cap$ 

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 $\{q_1,q_2,\ldots,q_k\}=\varnothing$ , so the prime factorization of c must include all of the  $p_i$ s and all of the  $q_i$ s. Therefore, c is a multiple of  $p_1p_2\cdots p_nq_1q_2\cdots q_k=ab$ , so  $ab\mid c$ .

### Chapter 1

# Groups and Subgroups

### 1.1 Groups

**Definition 1.1.1.** Let *S* be a set. A mapping

$$\begin{array}{cccc} \odot: & S \times S & \to & S \\ & (x,y) & \mapsto & x \odot y \end{array}$$

is called a law of composition on *S*.

Note that S is necessarily closed under the operation defined by such a law. Examples include addition of natural numbers and multiplication of  $n \times n$  matrices. Subtraction of natural numbers, however, is not closed and therefore not a law of composition.

**Definition 1.1.2.** A law of composition  $\odot$  on S is called associative if for every  $x, y, z \in S$ , we have  $(x \odot y) \odot z = x \odot (y \odot z)$ . The law  $\odot$  is called commutative if for every  $x, y \in S$ , we have  $x \odot y = y \odot x$ .

**Definition 1.1.3.** Let *G* be a set and  $\odot$  be a law of composition on *G*. A pair  $(G, \odot)$  is called a group if

- 1. ⊙ is associative;
- 2. there exists a neutral element  $e \in G$  such that for every  $g \in G$ , we have  $g \odot e = e \odot g = g$ ; and
- 3. for every  $g \in G$ , there exists an inverse element  $g^{-1} \in G$  such that  $g \odot g^{-1} = g^{-1} \odot g = e$ .

A group whose law is commutative is called abelian.

We will typically refer to a group by its set and denote compositions of its elements using multiplicative notation ab if commutativity is not assumed, or additive notation a+b if commutativity is assumed; in the latter case, the inverse of a is denoted -a.

**Proposition 1.1.4.** The neutral element of a group is unique.

*Proof.* Let *G* be a group, and let  $e_1, e_2 \in G$  such that for every  $g \in G$ , we have

$$e_1g = ge_1 = g$$
 and  $e_2g = ge_2 = g$ .

Then, in particular,  $e_1e_2 = e_1$  and  $e_1e_2 = e_2$ , so  $e_1 = e_2$ .

**Proposition 1.1.5.** Let *G* be a group. For every  $g \in G$ , its inverse element  $g^{-1}$  is unique.

*Proof.* Let  $g \in G$ . Suppose  $h_1$  and  $h_2$  are both inverses of g. Then,

$$gh_1 = h_1g = e$$
 and  $gh_2 = h_2g = e$ ,

so

$$h_1 = h_1 e = h_1(gh_2) = (h_1g)h_2 = eh_2 = h_2.$$

**Proposition 1.1.6.** Let *G* be a group, and let  $g, h, i \in G$ . Then,

- 1.  $(g^{-1})^{-1} = g;$
- 2.  $(gh)^{-1} = h^{-1}g^{-1}$ ;
- 3. the equations gx = h and xg = h have unique solutions  $x \in G$ ; and
- 4. if gi = hi or ig = ih, then g = h.

These can be proven with straightforward computations.

### 1.2 Subgroups

**Definition 1.2.1.** Let  $(G, \odot)$  be a group, and let  $H \subseteq G$ . If  $(H, \odot|_{H \times H})$  is a group, it is called a subgroup of G.

**Theorem 1.2.2.** Let *G* be a group, and let  $H \subseteq G$ ,  $H \neq \emptyset$ . Then, *H* is a subgroup of *G* if and only if for every  $x, y \in H$ , we have  $xy^{-1} \in H$ .

*Proof.* First note that by uniqueness of the neutral element, the neutral element of a subgroup must be the same as that of its parent group, and further, the inverse of an element of a subgroup must be the same as the inverse of that element in the parent group.

- (⇒) Suppose *H* is a subgroup of *G*. Let  $x, y \in H$ . Since *H* is a group,  $y^{-1} \in H$ , so  $xy^{-1} \in H$ .
- (⇐) Suppose that for every  $x, y \in H$ , we have  $xy^{-1} \in H$ . In particular, since  $H \neq \emptyset$ , we can take some  $h \in H$  to see  $hh^{-1} = e_G \in H$ , so  $h^{-1} = e_G h^{-1} \in H$ . This means  $(y^{-1})^{-1} = y \in H$ . Thus,  $xy \in H$ , so H is closed under the law of composition on G. Further, since this law is associative on G, it is also associative on H. Hence, we have demonstrated the criteria for H to be a group.

To denote the set of integer multiples of some  $n \in \mathbb{Z}$ , we will use the notation  $n\mathbb{Z} = \{k \in \mathbb{Z} \mid k \equiv 0 \pmod{n}\}.$ 

**Proposition 1.2.3.** Let  $n \in \mathbb{Z}$ . Then,  $(n\mathbb{Z}, +)$  is a subgroup of  $(\mathbb{Z}, +)$ .

*Proof.* We see  $0 \in n\mathbb{Z}$  for all  $n \in \mathbb{Z}$ , so  $n\mathbb{Z} \neq \emptyset$ . Let  $a, b \in n\mathbb{Z}$ . Then, a = kn and b = ln for some  $k, l \in \mathbb{Z}$ , so we have

$$a + (-b) = a - b = kn - ln = (k - l)n \in n\mathbb{Z}.$$

Hence, by Theorem 1.2.2,  $(n\mathbb{Z}, +)$  is a subgroup of  $(\mathbb{Z}, +)$ .

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**Proposition 1.2.4.** Every subgroup of  $(\mathbb{Z}, +)$  is of the form  $(n\mathbb{Z}, +)$  for some  $n \in \mathbb{Z}$ .

*Proof.* Let H be a subgroup of  $(\mathbb{Z}, +)$ . If  $H = \{0\}$ , then  $H = 0\mathbb{Z}$ . Otherwise, let  $k \in H \setminus \{0\}$ . Without loss of generality, take k to be positive. Now let  $S = H \cap \mathbb{Z}^+$ . Since  $k \in S$ , we see  $S \neq \emptyset$ , so S has a minimal element, say n.

Since  $n \in H$ , we see  $n\mathbb{Z} \subseteq H$ . Additionally, rewriting k in terms of its Euclidean division by n as k = nq + r where  $q, r \in \mathbb{Z}$ ,  $0 \le r < n$ , we see r = k - nq. Since n is minimal, we must have r = 0. Thus,  $k = nq \in n\mathbb{Z}$ , so  $H \subseteq n\mathbb{Z}$ . Hence,  $H = n\mathbb{Z}$ .

**Proposition 1.2.5.** Let *G* be a group, and let  $S \subseteq G$ . Then, there exists a unique subgroup *H* of *G* such that

- 1.  $S \subseteq H$  and
- 2. if H' is a subgroup of G and  $S \subseteq H'$ , then H is a subgroup of H'.

*Proof A.* Let X be the set of all subgroups of G that contain S. Since  $G \in X$ , we see  $X \neq \emptyset$ . Now let  $H = \cap_{J \in X} J$ . We see  $S \subseteq H$ . Finally, let  $x, y \in H$ . Then,  $x, y \in J$  for all  $J \in X$ , and since each J is a subgroup of G, we have  $xy^{-1} \in J$  for all  $J \in X$ . Thus,

$$xy^{-1} \in \bigcap_{J \in X} J = H,$$

so, by Theorem 1.2.2, *H* is a subgroup of *G*.

Now suppose there exist two subgroups  $H_1$ ,  $H_2$  satisfying 1 and 2. Then,  $S \subseteq H_1$  and  $S \subseteq H_2$ . Since  $H_2$  is a subgroup of G containing S, by 2 we have  $H_1 \subseteq H_2$ ; likewise,  $H_2 \subseteq H_1$ , so  $H_1 = H_2$ . Hence, H is unique.

Alternatively, we can use a constructive proof:

*Proof B.* Let  $H = \{g_1^{\pm 1}g_2^{\pm 1}\cdots g_k^{\pm 1}\mid g_1,g_2,\ldots,g_k\in S\}$ . Then,  $S\subseteq H$ . Further, let  $x,y\in H$ . Then,  $x=g_1^{\pm 1}g_2^{\pm 1}\cdots g_n^{\pm 1}$  and  $y=h_1^{\pm 1}h_2^{\pm 1}\cdots h_m^{\pm 1}$  for some  $g_1,g_2,\ldots,g_n,h_1,h_2,\ldots,h_m\in S$ , so

$$\begin{split} xy^{-1} &= g_1^{\pm 1} g_2^{\pm 1} \cdots g_n^{\pm 1} (h_1^{\pm 1} h_2^{\pm 1} \cdots h_m^{\pm 1})^{-1} \\ &= g_1^{\pm 1} g_2^{\pm 1} \cdots g_n^{\pm 1} (h_m^{\pm 1})^{-1} \cdots (h_2^{\pm 1})^{-1} (h_1^{\pm 1})^{-1} \\ &= g_1^{\pm 1} g_2^{\pm 1} \cdots g_n^{\pm 1} h_m^{\pm 1} \cdots h_2^{\pm 1} h_1^{\mp 1} \in H. \end{split}$$

Thus, H is a subgroup of G. Uniqueness can be shown in the same way as in Proof A.

**Definition 1.2.6.** The subgroup H from Proposition 1.2.5 is called the subgroup generated by S, denoted  $\langle S \rangle$ . This is, in other words, the smallest subgroup of G that contains S. When  $\langle S \rangle = G$  for some group G, we say S generates G. When this S is finite, we say G is finitely generated.

**Definition 1.2.7.** A group generated by one element, say x, is called a cyclic group, denoted  $\langle x \rangle$ .

We will use the notation  $x^n$  to denote an element x of a group composed with itself n times.

**Proposition 1.2.8.** Let *G* be a group, and let  $g \in G$ . Then,

- 1.  $\langle g \rangle = \langle \{g\} \rangle = \{g^m \mid m \in \mathbb{Z}\};$
- 2.  $\langle g \rangle$  is infinite if and only if there does not exist an  $m \in \mathbb{N}$  such that  $g^m = e$ ; and
- 3. if  $\langle g \rangle$  is finite, then  $|\langle g \rangle| = \min\{m \in \mathbb{N} \mid g^m = e\}$ .

Proof.

- 1. Since  $\langle g \rangle$  is a group, it must contain all compositions of g with itself, i.e.  $g^m$  for all  $m \in \mathbb{N}$ , as well as its inverse  $g^{-1}$  and the inverses of those compositions, so at the minimum,  $\langle g \rangle$  contains  $\{g^m \mid m \in \mathbb{Z}\}$ , which is a subgroup of G. Hence,  $\langle g \rangle = \{g^m \mid m \in \mathbb{Z}\}$ .
- 2. Suppose  $\langle g \rangle$  is finite. Equivalently, there exist some  $n, k \in \mathbb{Z}$ ,  $n \neq k$  such that  $g^n = g^k$ ; without loss of generality, take n > k. We see

$$g^n = g^k \iff g^n g^{-k} = g^k g^{-k} \iff g^{n-k} = e$$

i.e. there exists an  $m = n - k \in \mathbb{N}$  such that  $g^m = e$ . Hence,  $\langle g \rangle$  is infinite if and only if such an m does not exist.

3. From the proof for 2, it follows that if  $\langle g \rangle$  is finite, then the set  $\{m \in \mathbb{N} \mid g^m = e\}$  is nonempty and therefore has a least element, say n. We see  $\{e,g,g^2,\ldots,g^{n-1}\}\subseteq \langle g \rangle$ . Let  $g^k \in \langle g \rangle$  for some  $k \in \mathbb{Z}$ . We can rewrite k in terms of its Euclidean division by n as k=nq+r for some  $q,r \in \mathbb{Z}$ ,  $0 \le r < n$ , giving us

$$g^{k} = g^{nq+r} = (g^{n})^{q} g^{r} = e^{q} g^{r} = g^{r} \in \{e, g, g^{2}, \dots, g^{n-1}\},$$
so  $\langle g \rangle \subseteq \{e, g, g^{2}, \dots, g^{n-1}\}$ . Hence,  $\langle g \rangle = \{e, g, g^{2}, \dots, g^{n-1}\}$ , so  $|\langle g \rangle| = g^{n}$ 

**Definition 1.2.9.** Let x be some element in a group. Then, the cardinality of  $\langle x \rangle$  is called the order of x, denoted  $\operatorname{ord}(x)$ .

#### 1.3 Cosets

**Definition 1.3.1.** Let G be a group and H be a subgroup of G, and let  $g \in G$ . Then, the set

$$gH = \{gh \mid h \in H\}$$

is called the left coset of H associated with g, and the set

$$Hg = \{hg \mid h \in H\}$$

is called the right coset of H associated with g.

**Theorem 1.3.2.** Let *G* be a group and *H* be a subgroup of *G*, and let  $x, y \in G$ . Then, the relations  $\sim_l$  and  $\sim_r$  on *G* such that

$$x \sim_l y \iff x^{-1}y \in H \text{ and } x \sim_r y \iff xy^{-1} \in H$$

are equivalence relations.

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*Proof.* By Definition 0.2.2, we have three criteria for  $\sim_l$  to be an equivalence relation:

- 1. We see  $x^{-1}x = e \in H$ , so  $x \sim_I x$  (reflexive).
- 2. Suppose  $x \sim_l y$ . Then,  $x^{-1}y \in H$ , so  $(x^{-1}y)^{-1} = y^{-1}x \in H$ ; therefore,  $y \sim_l x$  (symmetric).
- 3. Let  $z \in G$ . Suppose  $x \sim_l y$  and  $y \sim_l z$ . Then,  $x^{-1}y, y^{-1}z \in H$ , so  $(x^{-1}y)(y^{-1}z) \in H$  and

$$(x^{-1}y)(y^{-1}z) = x^{-1}(yy^{-1})z = x^{-1}z;$$

thus,  $x \sim_l z$  (transitive).

Hence,  $\sim_l$  is an equivalence relation. The same for  $\sim_r$  can be proven similarly.

**Corollary 1.3.3** (Alternative definition of the left and right cosets). Let G be a group and H be a subgroup of G, and take  $\sim_l$  and  $\sim_r$  as defined in Theorem 1.3.2. Then, the left cosets of H in G are the equivalence classes of  $\sim_l$ , and the right cosets are the equivalence classes of  $\sim_r$ .

**Corollary 1.3.4.** Let *G* be a group and *H* be a subgroup of *G*. The left cosets of *H* in *G* form a partition of *G*. The same applies for the right cosets.

We will use the notation G/H to denote to denote the set of left cosets of H in G and  $H \setminus G$  to denote the set of right cosets.

**Proposition 1.3.5.** Let G be a group and H be a subgroup of G. Then, there exists a bijection between G/H and  $H\backslash G$ . It follows that the number of left cosets is equal to the number of right cosets when finite.

Proof. Consider the mapping

$$\begin{array}{ccc} f: & G/H & \to & H\backslash G \\ & xH & \mapsto & Hx^{-1} \end{array}.$$

Let  $x, y \in G$ . By Corollary 1.3.3, we see

$$xH = yH \iff y^{-1}x \in H \iff (y^{-1}x)^{-1} \in H \iff x^{-1}y \in H$$
$$\iff Hx^{-1} = Hy^{-1},$$

so f is well-defined and injective. We also see that for every  $Hy \in H \setminus G$ , we have  $f(y^{-1}H) = Hy$ , so f is surjective. Hence, f is a bijection.

**Definition 1.3.6.** Let G be a group and H be a subgroup of G. The cardinality of G/H is called the index of H in G, denoted G: H.

**Proposition 1.3.7.** Let G be a group and H be a subgroup of G. Then, there exists a bijection between any two cosets of H in G. It follows that if H is finite, then all the cosets are finite and have the same cardinality.

*Proof.* Let  $g \in G$ . Consider the mapping

$$\begin{array}{cccc} f_g: & H & \to & gH \\ & h & \mapsto & gh \end{array}.$$

By the definition of gH, we see  $f_g$  is well-defined and surjective. Let  $h, h' \in H$  such that gh = gh'. Then, by Proposition 1.1.6, we see h = h', so  $f_g$  is injective. Hence,  $f_g$  is a bijection.

**Theorem 1.3.8** (Lagrange's theorem). Let G be a finite group and H be a subgroup of G. Then, the order of every subgroup of H divides the order of G.

*Proof.* By Corollary 1.3.4, we see G is the union of the left cosets, which are necessarily disjoint, so |G| is the sum of the cardinalities of the cosets. By Proposition 1.3.7, the cardinalities of the cosets are the same and equal to |H|, so

$$|G| = [G:H]|H|.$$

**Corollary 1.3.9.** Let *G* be a group and *H*, *K* be subgroups of *G* where  $K \subseteq H$ . Then,

$$[G:K] = [G:H][H:K].$$

**Corollary 1.3.10.** Let *G* be a group, and let  $g \in G$ . If *G* is finite, then ord(g) divides |G|. It follows that  $g^{|G|} = e$ .

**Corollary 1.3.11.** Let *G* be a finite group. If |G| is prime, then, *G* is cyclic; in other words,  $G = \langle g \rangle$  for all  $g \in G \setminus \{e\}$ .

### 1.4 Normal subgroups

**Definition 1.4.1.** Let G be a finite group and H be a subgroup of G. If for every  $g \in G$ , we have gH = Hg, i.e. the left and right cosets are the same, then H is called a normal subgroup of G.

**Theorem 1.4.2.** Let G be a finite group and H be a subgroup of G. Then, H is a normal subgroup of G if and only if for every  $g \in G$  and  $h \in H$ , we have  $ghg^{-1} \in H$ .

Proof.

(⇒) Suppose H is a normal subgroup of G. Then, for all  $g \in G$ , we have gH = Hg, so for all  $h \in H$ , we have  $gh \in Hg$ . This means there exists some  $k \in H$  such that gh = kg, so

$$ghg^{-1} = kgg^{-1} = k$$
.

Hence,  $ghg^{-1} \in H$ .

(⇐) Suppose for every  $g \in G$  and  $h \in H$ , we have  $ghg^{-1} \in H$ . Let  $x \in jH$  for some  $j \in G$ . Then, there exists some  $k \in H$  such that

$$x = jk = jk(j^{-1}j) = (jkj^{-1})j \in Hj$$
,

so  $jH \subseteq Hj$ . Similarly, it can be shown that  $Hj \subseteq jH$ ; hence, jH = Hj.

**Theorem 1.4.3.** Let G be a group and H be a normal subgroup of G. Then, G/H can be given a group structure with the composition law

*Proof.* We have three criteria for  $(G/H, \emptyset)$  to be a group:

1. Let  $x_1, x_2, y_1, y_2 \in G$  such that  $x_1H = x_2H$  and  $y_1H = y_2H$ . Since H is a normal subgroup, for all  $h \in H$ , there exists some  $h' \in H$  such that  $y_1h = h'y_2$ , so  $x_1y_1h = x_1h'y_2$ . Similarly, there exists some  $h'' \in H$  such that  $x_1h' = h''x_2$ , so

$$x_1y_1h = x_1h'y_2 = h''x_2y_2.$$

This means that  $(x_1y_1)H = H(x_2y_2)$ , so since H is a normal subgroup,  $(x_1y_1)H = (x_2y_2)H$ . Thus,  $\emptyset$  is well-defined. Associativity follows from the law of composition on G.

2. Since  $H = e_G H$ , we have, for all  $gH \in G/H$ ,

$$H \otimes gH = e_G H \otimes gH = (e_G g)H = gH$$
,

and, similarly,  $gH \otimes H = gH$ , so we have the neutral element H.

3. Let  $gH \in G/H$ . Naturally, the inverse of gH is  $g^{-1}H$ :

$$(gg^{-1})H = e_G H = H.$$

### Solved exercises

### Groups

Determine whether the following are groups, and show why or why not.

**Exercise 1.1.** Consider  $(\{1,0,-1\},+)$  where + is standard addition.

*Solution.* Notice 
$$1 + 1 = 2 \notin \{1, 0, -1\}$$
, so  $(\{1, 0, -1\}, +)$  is not a group. □

**Exercise 1.2.** Consider  $(\mathbb{R}, \odot)$  where  $\odot$  is defined such that for  $x, y \in \mathbb{R}$ , we have  $x \odot y = xy + (x^2 - 1)(y^2 - 1)$ .

Solution. Notice

$$2 \odot (3 \odot 4) = 2 \odot ((3)(4) + (3^2 - 1)(4^2 - 1)) = 2 \odot 132$$
$$= (2)(132) + (2^2 - 1)(132^2 - 1) = 52533,$$

while

$$(2 \odot 3) \odot 4 = ((2)(3) + (2^2 - 1)(3^2 - 1)) \odot 4 = 30 \odot 4$$
  
=  $(30)(4) + (30^2 - 1)(4^2 - 1) = 13605$ ,

so  $\odot$  is not associative. Hence,  $(\mathbb{R}, \odot)$  is not a group.

**Exercise 1.3.** Consider  $(\mathbb{R}^+, \odot)$  where  $\odot$  is defined such that for  $x, y \in \mathbb{R}^+$ , we have  $x \odot y = \sqrt{x^2 + y^2}$ .

*Solution.* Notice that for all  $x \in \mathbb{R}^+$ ,

$$x \odot 0 = \sqrt{x^2 + 0^2} = \sqrt{x^2} = x$$

so 0 is the neutral element under  $\odot$ ; however,  $0 \notin \mathbb{R}^+$ , so  $(\mathbb{R}^+, \odot)$  is not a group.

**Exercise 1.4.** Consider  $(\mathbb{R} \setminus \{-1\}, \odot)$  where  $\odot$  is defined such that for  $x, y \in \mathbb{R} \setminus \{-1\}$ , we have  $x \odot y = x + y + xy$ .

*Solution.* Suppose there exists a pair (x, y) such that  $x \odot y = -1$ . Then,

$$x + y + xy = -1$$

$$y(1 + x) = -1 - x$$

$$y = -\frac{1 + x}{1 + x}$$

$$y = -1$$

so such a pair cannot be in  $(\mathbb{R}\setminus\{-1\})\times(\mathbb{R}\setminus\{-1\})$ ; thus,  $\odot$  is a law of composition on  $\mathbb{R}\setminus\{-1\}$ . We also see

$$(x \odot y) \odot z = (x + y + xy) \odot z = (x + y + xy) + z + (x + y + xy)z$$
  
= x + y + xy + z + xz + yz + xyz  
= x + (y + z + yz) + x(y + z + yz) = x \odots (y + z + yz)  
= x \odots (y \odots z),

so  $\odot$  is associative. Finally, notice that for all  $x \in \mathbb{R} \setminus \{-1\}$ , we have

$$x \odot 0 = x + 0 + x(0) = x$$

(neutral element), and

$$x \odot -\frac{x}{1+x} = x - \frac{x}{1+x} + x\left(-\frac{x}{1+x}\right) = x - \frac{x}{1+x} - \frac{x^2}{1+x}$$
$$= \frac{x(1+x) - x}{1+x} - \frac{x^2}{1+x} = \frac{x^2}{1+x} - \frac{x^2}{1+x} = 0$$

(inverse). Hence,  $(\mathbb{R} \setminus \{-1\}, \odot)$  is a group.

**Exercise 1.5.** Consider  $(C, \cdot)$  where  $C = \{z \in \mathbb{C} \mid |c| = 1\}$  and  $\cdot$  is standard multiplication.

*Solution.* Since *C* is the unit circle, we can uniquely represent each  $z \in C$  in polar form as  $z = e^{i\theta}$  for some  $\theta \in (-\pi, \pi]$ , and we know  $e^{i\theta} \in C$  for all  $\theta \in \mathbb{R}$ . Let  $e^{i\theta_1}$ ,  $e^{i\theta_2} \in C$ . Then,

$$e^{i\theta_1} \cdot e^{i\theta_2} = e^{i\theta_1 + i\theta_2} = e^{i(\theta_1 + \theta_2)} \in C$$

so standard multiplication is a law of composition on C, and we know standard multiplication is associative. The neutral element under standard multiplication is  $1 = e^{i(0)} \in C$ . Finally, notice that for all  $e^{i\theta} \in C$ ,

$$e^{i\theta} \cdot e^{i(-\theta)} = e^{i\theta - i\theta} = e^0 = 1$$

(inverse). Hence,  $(C, \cdot)$  is a group.

**Exercise 1.6.** Consider  $(\operatorname{SL}_n(\mathbb{R}), \cdot)$  where  $\operatorname{SL}_n(\mathbb{R})$  is the set of all  $n \times n$  matrices over  $\mathbb{R}$  with determinant 1 and  $\cdot$  is standard matrix multiplication.

*Solution.* Let  $A, B \in SL_n(\mathbb{R})$ . Then,

$$det(AB) = det(A) \ det(B) = (1)(1) = 1,$$

so  $AB \in SL_n(\mathbb{R})$ . Thus, standard matrix multiplication is a law of composition on  $SL_n(\mathbb{R})$ , and we know standard matrix multiplication is associative. The neutral element under standard matrix multiplication is  $I_n$  and  $det(I_n) = 1$ , so  $I_n \in SL_n(\mathbb{R})$ . Finally, taking  $A^{-1}$  as the standard matrix inverse, we see

$$\det(A^{-1}) = \frac{1}{\det(A)} = \frac{1}{1} = 1,$$

so  $A^{-1} \in \mathrm{SL}_n(\mathbb{R})$ . Hence,  $(\mathrm{SL}_n(\mathbb{R}), \cdot)$  is a group.

**Exercise 1.7.** Consider  $(Q, \cdot)$  where  $Q = \{\pm I_2, \pm I, \pm J, \pm K\}$ ,

$$I_2 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$
  $I = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$   $J = \begin{bmatrix} 0 & i \\ i & 0 \end{bmatrix}$   $K = \begin{bmatrix} i & 0 \\ 0 & -i \end{bmatrix}$ ,

and  $\cdot$  is standard matrix multiplication.

*Solution.* For  $I_2$ , I, J, and K, we have the composition table

and we know for any matrices A and B,

$$(-A)B = A(-B) = -AB$$
 and  $(-A)(-B) = AB$ ,

so standard matrix multiplication is a law of composition on Q. We also know standard matrix multiplication is associative. The neutral element under standard matrix multiplication of  $2 \times 2$  matrices is  $I_2 \in Q$ . Finally, from the composition table, we have the inverses

$$I_2^{-1} = I_2$$
  $I^{-1} = -I$   $J^{-1} = -J$   $K^{-1} = -K$ 

and from these we see

$$(-I_2)^{-1} = -I_2$$
  $(-I)^{-1} = I$   $(-J)^{-1} = J$   $(-K)^{-1} = K$ .

Hence,  $(Q, \cdot)$  is a group.

**Exercise 1.8.** Consider  $(H, \cdot)$  where H is the set of upper triangular  $3 \times 3$  matrices over  $\mathbb{R}$  whose diagonal entries are all 1 and  $\cdot$  is standard matrix multiplication.

*Solution.* Let  $a, b, c, x, y, z \in \mathbb{R}$ . Then,

$$\begin{bmatrix} 1 & x & y \\ 0 & 1 & z \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & a & b \\ 0 & 1 & c \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & a+x & b+xc+y \\ 0 & 1 & c+z \\ 0 & 0 & 1 \end{bmatrix} \in H,$$

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so standard matrix multiplication is a law of composition on H, and we know standard matrix multiplication is associative. The neutral element under standard matrix multiplication of  $3 \times 3$  matrices is  $I_3 \in H$ . Finally, computing the standard matrix inverse, we see

$$\begin{bmatrix} 1 & x & y \\ 0 & 1 & z \\ 0 & 0 & 1 \end{bmatrix}^{-1} = \begin{bmatrix} 1 & -x & xz - y \\ 0 & 1 & -z \\ 0 & 0 & 1 \end{bmatrix} \in H.$$

Hence,  $(H, \cdot)$  is a group.

### **Subgroups**

For each of the following, determine whether *H* is a subgroup of *G*, and show why or why not.

**Exercise 1.9.** Let  $G = (\mathbb{R}, +)$  and  $H = \{-1, 0, 1\}$ .

*Solution.* Notice  $1 + 1 = 2 \notin H$ . Hence, *H* is not a subgroup of *G*. □

**Exercise 1.10.** Let  $G = (\mathbb{R}, +)$  and  $H = \mathbb{R} \setminus \{0\}$ .

*Solution.* The neutral element of G is  $0 \notin H$ . Hence, H is not a subgroup of G.

**Exercise 1.11.** Let  $G = (\mathbb{C} \setminus \{0\}, \cdot)$  and  $H = \mathbb{R} \setminus \{0\}$ .

*Solution.* Let  $h_1, h_2 \in H = \mathbb{R} \setminus \{0\}$ . Then, since  $h_1, h_2 \neq 0$ , we have

$$h_1 h_2^{-1} = h_1 \cdot \frac{1}{h_2} = \frac{h_1}{h_2} \in \mathbb{R} \setminus \{0\} = H.$$

Hence, *H* is a subgroup of *G*.

**Exercise 1.12.** Let  $G = (\mathbb{R} \setminus \{0\}, \cdot)$  and  $H = \{-1, 1\}$ .

Solution. We see

$$(-1)^{-1} = \frac{1}{-1} = -1$$
 and  $1^{-1} = \frac{1}{1} = 1$ ,

so

$$-1 \cdot (-1)^{-1} = -1 \cdot -1 = 1 \in H,$$
  $-1 \cdot 1^{-1} = -1 \cdot 1 = -1 \in H,$   $1 \cdot (-1)^{-1} = 1 \cdot -1 = -1 \in H,$   $1 \cdot 1^{-1} = 1 \cdot 1 = 1 \in H.$ 

Hence, *H* is a subgroup of *G*.

**Exercise 1.13.** Let  $G = (\mathbb{C} \setminus \{0\}, \cdot)$  and  $H = \{e^{i(2\pi k)/n} \mid k \in \{0, 1, ..., n-1\}\}$  for some  $n \in \mathbb{N}$ .

*Solution.* Let  $h_1,h_2\in H$ . Then,  $h_1=e^{i(2\pi k)/n}$  and  $h_2=e^{i(2\pi l)/n}$  for some  $k,l\in\{0,1,\ldots,n-1\}$ , so

$$h_2^{-1} = \left(e^{i(2\pi l)/n}\right)^{-1} = e^{-i(2\pi l)/n},$$

and we see

$$h_1 h_2^{-1} = e^{i(2\pi k)/n} \cdot e^{-i(2\pi l)/n} = e^{i(2\pi (k-l))/n}.$$

Let  $m = (k - l) \mod n$ . Then,

$$h_1 h_2^{-1} = e^{i(2\pi(k-l))/n} = e^{i(2\pi m)/n} \in H.$$

Hence, *H* is a subgroup of *G*.

**Exercise 1.14.** Let  $G = (GL_n(\mathbb{R}), \cdot)$  where  $GL_n(\mathbb{R})$  is the set of all invertible  $n \times n$  matrices over  $\mathbb{R}$ , and let  $H = (SL_n(\mathbb{R}), \cdot)$ .

*Solution.* Let  $A, B \in H = \mathrm{SL}_n(\mathbb{R})$ . Then,

$$\det(A) = \det(B) = 1 \neq 0,$$

so  $A^{-1}$  and  $B^{-1}$  exist and

$$\det(B^{-1}) = \frac{1}{\det(B)} = \frac{1}{1} = 1.$$

Therefore,

$$\det(AB^{-1}) = \det(A)\det(B^{-1}) = 1 \cdot 1 = 1$$

so  $AB^{-1} \in H$ . Hence, H is a subgroup of G.

### Cyclic groups

**Exercise 1.15.** Let *G* be a group, and let  $x \in G$  where x is of order k. Prove that if m is an integer such that  $x^m = e_G$ , then  $k \mid m$ .

*Solution.* Since x is of order k, we have by definition that k is the smallest positive integer such that  $x^k = e_G$ . Suppose  $x^m = e_G$  for some  $m \in \mathbb{Z}$ . We can rewrite m in terms of its Euclidean division by k as m = kq + r for some  $q, r \in \mathbb{Z}$  where  $0 \le r < k$ , giving us

$$x^{m} = x^{kq+r} = x^{kq}x^{r} = (x^{k})^{q}x^{r} = e_{G}^{q}x^{r} = x^{r}.$$

so  $x^r = e_G$ . Since r < k and k is minimal, we must have r = 0, so m = kq. Hence,  $k \mid m$ .

# Chapter 2

# **Relations Between Groups**

### 2.1 Group homomorphisms

**Definition 2.1.1.** Let  $(G, \odot)$  and  $(G', \emptyset)$  be groups. A mapping  $\phi : G \to G'$  is called a group homomorphism if for every  $x, y \in G$ , we have

$$\phi(x \odot y) = \phi(x) \oslash \phi(y).$$

**Definition 2.1.2.** A group homomorphism is called an isomorphism if it is a bijection. A group G is called isomorphic to a group G' if there exists an isomorphism  $\phi: G \to G'$ . We denote this by  $G \simeq G'$ .

**Proposition 2.1.3.** Let  $\phi:(G,\odot)\to (G',\odot)$  be a homomorphism. Then,

- 1.  $\phi(e_G) = e_{G'}$ ; and
- 2. for all  $g \in G$ , we have  $\phi(g^{-1}) = (\phi(g))^{-1}$ .

Proof.

1. By definition, for all  $x \in G'$ , we have  $x \oslash (x)^{-1} = (x)^{-1} \oslash x = e_{G'}$ . In particular,

$$e_{G'} = \phi(e_G) \oslash (\phi(e_G))^{-1} = (\phi(e_G))^{-1} \oslash \phi(e_G).$$

Since  $\phi$  is a homomorphism, we also have

$$\phi(e_G) = \phi(e_G \odot e_G)$$

$$\phi(e_G) = \phi(e_G) \oslash \phi(e_G)$$

$$\phi(e_G) \oslash (\phi(e_G))^{-1} = \phi(e_G) \oslash \phi(e_G) \oslash (\phi(e_G))^{-1}$$

$$e_{G'} = \phi(e_G) \oslash e_{G'}$$

$$e_{G'} = \phi(e_G).$$

2. By definition,  $(\phi(g))^{-1}$  is the inverse of  $\phi(g)$  in G'. We see

$$\phi(g^{-1}) \oslash \phi(g) = \phi(g^{-1} \odot g) = \phi(e_G) = e'_G,$$

so  $\phi(g^{-1})$  is also the inverse of  $\phi(g)$  in G'. Hence, by uniqueness of the inverse,

$$\phi(g^{-1}) = (\phi(g))^{-1}$$
.

**Definition 2.1.4.** Let  $\phi : G \to G'$  be a homomorphism. The set

$$im(\phi) = {\phi(g) \mid g \in G}$$

is called the image of  $\phi$ .

**Proposition 2.1.5.** Let  $\phi : G \to G'$  be a homomorphism. Then,  $\operatorname{im}(\phi)$  is a subgroup of G'.

*Proof.* Let  $x, y \in \text{im}(\phi)$ . Then, there exist some  $u, v \in G$  such that  $\phi(u) = x$  and  $\phi(v) = y$ , so

$$xy^{-1} = \phi(u)(\phi(v))^{-1} = \phi(u)\phi(v^{-1}) = \phi(uv^{-1}).$$

Since  $uv^{-1} \in G$ , we see  $xy^{-1} \in \text{im}(\phi)$ . Hence,  $\text{im}(\phi)$  is a subgroup of G'.

**Definition 2.1.6.** Let  $\phi: G \to G'$  be a homomorphism. The set

$$\ker(\phi) = \{ g \in G \mid \phi(g) = e_{G'} \}$$

is called the kernel of  $\phi$ .

**Theorem 2.1.7.** Let  $\phi : G \to G'$  be a homomorphism. Then,  $\phi$  is injective if and only if  $\ker(\phi) = \{e_G\}$ .

Proof.

- (⇒) Suppose  $\phi$  is injective. Since  $\phi(e_G) = e_{G'}$ , we know  $\{e_G\} \subseteq \ker(\phi)$ . Let  $x \in \ker(\phi)$ . Then,  $\phi(x) = e_{G'} = \phi(e_G)$ , so since  $\phi$  is injective,  $x = e_G$ , which implies  $\ker(\phi) \subseteq \{e_G\}$ . Hence,  $\{e_G\} = \ker(\phi)$ .
- $(\Leftarrow)$  Suppose  $\ker(\phi) = \{e_G\}$ . Let  $x, y \in G$  such that  $\phi(x) = \phi(y)$ . Then,

$$e_{G'} = \phi(x)(\phi(x))^{-1} = \phi(y)(\phi(x))^{-1} = \phi(y)\phi(x^{-1}) = \phi(yx^{-1}).$$

Thus,  $yx^{-1} \in \ker(\phi)$ , so  $yx^{-1} = e_G$ , which implies y = x. Hence,  $\phi$  is injective.

**Theorem 2.1.8.** Let  $\phi: G \to G'$  be a homomorphism. Then,  $\ker(\phi)$  is a normal subgroup of G.

*Proof.* Let  $g \in G$  and  $x \in \ker(\phi)$ . Then,  $\phi(x) = e_{G'}$ , so

$$\phi(gxg^{-1}) = \phi(g)\phi(x)\phi(g^{-1}) = \phi(g)e_{G'}(\phi(g))^{-1} = \phi(g)(\phi(g))^{-1} = e_{G'}.$$

**Theorem 2.1.9.** Let *G* be a group and *H* be a subgroup of *G*. Then, *H* is a normal subgroup of *G* if and only if there exists a surjective homomorphism  $\phi : G \to G'$  for some group G' such that  $H = \ker(\phi)$ .

*Proof.* Suppose *H* is a normal subgroup of *G*. Consider the mapping

$$\phi: G \to G/H$$

$$g \mapsto gH$$

where G/H has group structure as given in Theorem 1.4.3. Let  $x, y \in G$ . We see

$$\phi(xy) = (xy)H = xHyH = \phi(x)\phi(y),$$

so  $\phi$  is a homomorphism, surjective by construction. Now let  $k \in \ker(\phi)$ . Since H is the neutral element of G/H, this means  $\phi(k) = kH = H$ , which is true if and only if  $k \in H$ . Hence,  $\ker(\phi) = H$ . The converse is a direct consequence of Theorem 2.1.8.

**Theorem 2.1.10.** Let  $\phi: G \to G'$  be an isomorphism. Then,  $\phi^{-1}$  is an isomorphism.

*Proof.* Let ⊙ denote the law of composition for group G and  $\emptyset$  denote the law for G', let  $f = \phi^{-1}$ , and let  $x, y \in G'$ . f is clearly well-defined, and we see

$$\phi(f(x)\odot f(y)) = \phi(f(x)) \oslash \phi(f(y)) = x \oslash y = \phi(f(x \oslash y)).$$

Since  $\phi$  is injective, this implies  $f(x) \odot f(y) = f(x \odot y)$ , so f is a homomorphism. Injectivity and surjectivity can be easily verified. Hence, f is an isomorphism.

**Theorem 2.1.11** (Fundamental theorem on homomorphisms). Let  $\phi: G \to G'$  be a homomorphism. Then, the mapping

$$\psi: G/\ker(\phi) \to \operatorname{im}(\phi)$$
$$g \ker(\phi) \mapsto \phi(g)$$

is an isomorphism.

*Proof.* We have four criteria for  $\psi$  to be an isomorphism:

1. Let g, h be such that  $g \ker(\phi) = h \ker(\phi)$ . Then,  $h^{-1}g \in \ker(\phi)$ , so

$$\phi(h^{-1}g) = e_{G'}$$
$$(\phi(h))^{-1}\phi(g) = e_{G'}$$
$$\phi(g) = \phi(h).$$

Thus,  $\psi$  is well-defined.

2. Let  $g \ker(\phi)$ ,  $h \ker(\phi) \in G/\ker(\phi)$ . Then,

$$\psi(g \ker(\phi) h \ker(\phi)) = \psi((gh) \ker(\phi)) = \phi(gh) = \phi(g) \phi(h)$$
$$= \psi(g \ker(\phi)) \psi(h \ker(\phi)),$$

so  $\psi$  is a homomorphism.

- 3. Let  $g \ker(\phi) \in \ker(\psi)$ . Then,  $\psi(g \ker(\phi)) = e_{G'}$ , so  $g \in \ker(\phi)$ , which implies  $g \ker(\phi) = \ker(\phi)$ . Thus, by Theorem 2.1.7,  $\psi$  is injective.
- 4.  $\psi$  is surjective by construction since it maps to im( $\phi$ ).

This theorem is also known as the first isomorphism theorem.

# 2.2 Permutation groups

**Proposition 2.2.1.** Let X be a set, and let S(X) be the set of all bijections from X to X. Then,  $(S(X), \circ)$ , where  $\circ$  is composition of mappings, is a group.

*Proof.* We have three criteria for  $(S(X), \circ)$  to be a group:

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1. Let  $\sigma, \tau \in \mathcal{S}(X)$ . Then,  $\sigma \circ \tau$  is a mapping from X to X. Let  $x, y \in X$  such that  $(\sigma \circ \tau)(x) = (\sigma \circ \tau)(y)$ . Then, since  $\sigma$  and  $\tau$  are injective, we have

$$\sigma(\tau(x)) = \sigma(\tau(y))$$
$$\tau(x) = \tau(y)$$
$$x = y,$$

so  $\sigma \circ \tau$  is injective, and any injective mapping from a set to itself is also surjective. Thus,  $\sigma \circ \tau \in \mathcal{S}(X)$ , and we know composition of mappings is associative.

2. The neutral element is naturally the identity mapping id:

$$(\sigma \circ \mathrm{id})(x) = \sigma(\mathrm{id}(x)) = \sigma(x) = \mathrm{id}(\sigma(x)) = (\mathrm{id} \circ \sigma)(x).$$

3. Since every  $\sigma \in S(X)$  is injective, every  $\sigma$  has an inverse mapping.

**Definition 2.2.2.** Take S(X) as defined in Proposition 2.2.1 for some set X. A subgroup of S(X) is called a permutation group. Any mapping in such a group is called a permutation.

**Theorem 2.2.3** (Cayley's theorem). Every group is isomorphic to a permutation group.

*Proof.* Let G be a group. For each  $a \in G$ , we define a mapping

$$\sigma_a: G \to G \\
g \mapsto ag.$$

For some  $b \in G$ , let  $x, y \in G$  such that  $\sigma_b(x) = \sigma_b(y)$ . Then, bx = by, so left cancellation implies x = y. Thus,  $\sigma_b$  is injective, and any injective mapping from a set to itself is also surjective, so  $\sigma_b \in \mathcal{S}(G)$ .

Now, we define a mapping

$$\begin{array}{ccc} \phi: & G & \to & \mathcal{S}(G) \\ & g & \mapsto & \sigma_g \end{array}.$$

Let  $a, b \in G$ . Then, for all  $x \in G$ , we have

$$\phi(ab)(x) = \sigma_{ab}(x) = abx = a\sigma_b(x) = \sigma_a(\sigma_b(x)) = \phi(a) \circ \phi(b),$$

so  $\phi$  is a homomorphism. If  $a \in \ker(\phi)$ , then  $\phi(a) = \sigma_a = \mathrm{id}$ , which is true if and only if for all  $x \in G$ , we have

$$\phi(a)(x) = \sigma_a(x) = ax = x \iff a = e_G.$$

Thus,  $\ker(\phi) = \{e_G\}$ , so  $\phi$  is injective. By Proposition 2.1.5,  $\operatorname{im}(\phi)$  is a subgroup of S(X); hence, we can construct an isomorphism  $\psi : G \to \operatorname{im}(\phi)$ .

**Definition 2.2.4.** Let  $A = \{1, 2, ..., n\}$  for some  $n \in \mathbb{N}$ . Then,  $S_n = S(A)$  is called the symmetric group on n elements.

More generally,  $S_n$  can be used to describe the group of permutations of any finite set. Since any finite set is isomorphic to a subset of  $\mathbb{N}$ , we can apply this definition by assigning a label in A to each element. The results we will show for  $S_n$  therefore apply with this generalization as well.

Note that for any  $n \in \mathbb{N}$ , we have  $|S_n| = n!$ . This may be familiar if you recall the notion of a permutation of a set as a rearrangement of its elements. The notation may also be familiar—consider the following permutation  $\sigma \in S_5$ :

$$1 \mapsto 3$$

$$2 \mapsto 2$$

$$3 \mapsto 5$$

$$4 \mapsto 4$$

$$5 \mapsto 1$$

This can be written as

$$\sigma = \begin{pmatrix} 1 & 2 & 3 & 4 & 5 \\ 3 & 2 & 5 & 4 & 1 \end{pmatrix}.$$

**Definition 2.2.5.** Let  $\sigma = S_n$ . The set

$$supp(\sigma) = \{i \in \{1, 2, ..., n\} \mid \sigma(i) \neq i\}$$

is called the support of  $\sigma$ .

**Proposition 2.2.6.** Let  $\sigma, \tau \in S_n$ . If  $supp(\sigma) \cap supp(\tau) = \emptyset$ , then  $\sigma \circ \tau = \tau \circ \sigma$ .

*Proof.* Let  $i \in \{1, 2, ..., n\}$ . We have three cases:

1. Suppose  $i \notin \text{supp}(\sigma) \cup \text{supp}(\tau)$ . Then,  $\sigma(i) = \tau(i) = i$ , so

$$(\sigma \circ \tau)(i) = \sigma(\tau(i)) = \sigma(i) = i = \tau(i) = \tau(\sigma(i)) = (\tau \circ \sigma)(i).$$

2. Suppose  $i \in \text{supp}(\sigma)$ . Then,  $i \notin \text{supp}(\tau)$ , so

$$(\sigma \circ \tau)(i) = \sigma(\tau(i)) = \sigma(i),$$

and since  $i \in \text{supp}(\sigma)$ , we have  $\sigma(i) \in \text{supp}(\sigma)$ , so  $\sigma(i) \notin \text{supp}(\tau)$ . Thus,

$$(\tau \circ \sigma)(i) = \tau(\sigma(i)) = \sigma(i) = (\sigma \circ \tau)(i).$$

3. If  $i \in \text{supp}(\tau)$ , the proof can be done in the same way as in the above case.

Hence, 
$$\sigma \circ \tau = \tau \circ \sigma$$
.

#### **Cycles**

**Definition 2.2.7.** An element  $\sigma \in S_n$  is called a cycle if there exists some  $x \in \{1, 2, ..., n\}$  such that  $\text{supp}(\sigma) = \{\sigma^i(x) \mid i \in \mathbb{N}\}$ . Let  $l = |\text{supp}(\sigma)|$ . We denote the cycle

$$\left(x,\sigma(x),\ldots,\sigma^{l-1}(x)\right)$$

where l is called its length. A cycle of length 2 is called a transposition.

**Proposition 2.2.8.** Let  $\sigma$  be a cycle of length l. Then,  $\operatorname{ord}(\sigma) = l$ .

This follows by construction.

**Proposition 2.2.9.** Let  $\sigma \in S_n$ , and let  $A = \{1, 2, ..., n\}$ . Then, the relation  $\sim$  on A defined such that for all  $a, b \in A$ ,

 $a \sim b \iff$  there exists some  $k \in \mathbb{Z}$  such that  $b = \sigma^k(a)$ 

is an equivalence relation.

*Proof.* We have three criteria for  $\sim$  to be an equivalence relation:

- 1. Since  $a = \sigma^0(a)$ , we have  $a \sim a$  (reflexive).
- 2. Suppose  $a \sim b$ . Then,  $b = \sigma^k(a)$  for some  $k \in \mathbb{Z}$ , so  $a = \sigma^{-k}(b)$ . Thus,  $b \sim a$  (symmetric).
- 3. Let  $c \in A$ . Suppose  $a \sim b$  and  $b \sim c$ . Then,  $b = \sigma^k(a)$  and  $c = \sigma^m(b)$  for some  $k, m \in \mathbb{Z}$ , so  $c = \sigma^m(\sigma^k(a)) = \sigma^{m+k}(a)$ . Thus,  $a \sim c$  (transitive).

**Corollary 2.2.10** (Alternative definition of a cycle). Take  $\sim$  as defined in Proposition 2.2.9 for some  $\sigma \in S_n$ . Then,  $\sigma$  is a cycle if and only if  $\sim$  has at most one equivalence class containing more than one element.

**Theorem 2.2.11.** Let  $\sigma \in S_n$ . Then, there exist some unique cycles  $\tau_1, \tau_2, \dots, \tau_k$  with disjoint supports such that  $\sigma = \tau_1 \circ \tau_2 \circ \dots \circ \tau_k$ . In other words, every permutation of a finite set can be decomposed as the product of unique cycles with disjoint supports.

*Proof.* Let  $A_1, A_2, ..., A_k$  be the equivalence classes of  $\sim$ , and let  $\tau_1, \tau_2, ..., \tau_k$  be the cycles defined such that

$$\tau_i(x) = \begin{cases} \sigma(x), & x \in A_i \\ x, & \text{otherwise.} \end{cases}$$

We see  $\sigma = \tau_1 \circ \tau_2 \circ \cdots \circ \tau_k$ , and since  $A_1, A_2, \ldots, A_k$  are necessarily disjoint,  $\tau_1, \tau_2, \ldots, \tau_k$  have disjoint supports.

**Definition 2.2.12.** Let  $\sigma \in S_n$  with decomposition  $\sigma = \tau_1 \circ \tau_2 \circ \cdots \circ \tau_k$  as given by Theorem 2.2.11. Let  $l_1, l_2, \ldots, l_k$  denote the lengths of  $\tau_1, \tau_2, \ldots, \tau_k$ , respectively, where  $l_1 \geq l_2 \geq \cdots \geq l_k$ . The sequence  $(l_1, l_2, \ldots, l_k)$  is called the **type** of  $\sigma$ .

**Proposition 2.2.13.** Let  $\sigma \in S_n$  with type  $(l_1, l_2, \dots, l_k)$ . Then,

$$\operatorname{ord}(\sigma) = \operatorname{lcm}\{l_1, l_2, \dots, l_k\}.$$

*Proof.* We can decompose  $\sigma$  into cycles as  $\sigma = \tau_1 \circ \tau_2 \circ \cdots \circ \tau_k$  where  $\tau_1, \tau_2, \ldots, \tau_k$  have length  $l_1, l_2, \ldots, l_k$ , respectively. Since the  $\tau_i$ s have disjoint supports, they commute, so for every  $m \in \mathbb{N}$ , we have

$$\sigma^m = \tau_1^m \circ \tau_2^m \circ \cdots \circ \tau_k^m.$$

Since  $\operatorname{ord}(\tau_i) = l_i$  for  $1 \le i \le k$ , we see that if  $\sigma^m = \operatorname{id}$ , then m is a multiple of each of the  $l_i$ s. Hence, by definition,  $\operatorname{ord}(\sigma)$  is the lowest such m.

### Transpositions and alternating groups

**Corollary 2.2.14** (to Theorem 2.2.11). Every permutation in  $S_n$  can be decomposed as the product of transpositions.

**Proposition 2.2.15.** Let  $\sigma \in S_n$ . Either all transposition decompositions of  $\sigma$  are the product of an even number of transpositions, or all of them are the product of an odd number of transpositions.

*Proof.* Consider the group of permutations of the rows of the  $n \times n$  identity matrix  $I_n$ . Let us call this group P. As remarked following Definition 2.2.4,  $P \simeq S_n$ . We know  $\det(I_n) = 1$ , and transposing any two rows of a square matrix changes the sign of its determinant.

Let  $\rho \in P$ , and let  $A = \rho(I_n)$ . Suppose  $\rho$  can be decomposed as an even number of transpositions. Then,  $\det(A) = 1$ . Now suppose  $\rho$  can also be decomposed as an odd number of transpositions. Then,  $\det(A) = -1$ , a contradiction. Hence, no  $\rho \in P$  can be decomposed into the product of both an even number and an odd number of transpositions.

**Definition 2.2.16.** Let  $\sigma \in S_n$ , and let k be the number of transpositions in some transposition decomposition of  $\sigma$ . The number  $\varepsilon(\sigma) = (-1)^k$  is called the signature of  $\sigma$ . The permutation  $\sigma$  is called even if k is even or odd if k is odd.

**Proposition 2.2.17.** Let  $\mathcal{A}_n = \{ \sigma \in \mathcal{S}_n \mid \epsilon(\sigma) = 1 \}$ . Then,  $\mathcal{A}_n$  is a normal subgroup of  $\mathcal{S}_n$ .

*Proof.* Let  $\alpha \in \mathcal{A}_n$  and  $\sigma \in \mathcal{S}_n$ . For some  $k, m \in \mathbb{N}$ ,  $\alpha$  can be decomposed as the product of some number 2k of transpositions and  $\sigma$  can be decomposed as the product of some number m of transpositions, so there exists a decomposition of  $\sigma \circ \alpha \circ \sigma^{-1}$  into some number m + 2k + m = 2(m + k) of transpositions. Since 2(m + k) is even,  $\sigma \circ \alpha \circ \sigma^{-1} \in \mathcal{A}_n$ . Hence, by Theorem 1.4.2,  $\mathcal{A}_n$  is a normal subgroup of  $\mathcal{S}_n$ .

We can alternatively show that the mapping

$$\epsilon: (S_n, \circ) \rightarrow (\{-1, 1\}, \cdot)$$
 $\sigma \mapsto \epsilon(\sigma)$ 

is a group homomorphism and that  $\mathcal{A}_n = \ker(\epsilon)$ . By Theorem 2.1.8, this implies  $\mathcal{A}_n$  is a normal subgroup of  $\mathcal{S}_n$ .

**Definition 2.2.18.**  $\mathcal{A}_n$  as defined in Proposition 2.2.17 is called the alternating group on n elements.

# 2.3 Finitely generated abelian groups

Recall the Cartesian product of two sets *A* and *B*:

$$A \times B = \{(a, b) \mid a \in A, b \in B\}.$$

We can give group structure to the Cartesian product of an arbitrary number of groups.

**Proposition 2.3.1.** Let  $G_1$  and  $G_2$  be two groups. The set  $G_1 \times G_2$  together with the law of composition

$$\bigcirc : (G_1 \times G_2) \times (G_1 \times G_2) \to G_1 \times G_2 ((a_1, a_2), (b_1, b_2)) \mapsto (a_1b_1, a_2b_2)$$

is a group.

*Proof.* We have three criteria for  $(G_1 \times G_2, \odot)$  to be a group:

1. Let  $(a_1, a_2), (b_1, b_2), (c_1, c_2) \in G_1 \times G_2$ . Then,

$$((a_1, a_2) \odot (b_1, b_2)) \odot (c_1, c_2) = (a_1b_1, a_2b_2) \odot (c_1, c_2)$$

$$= ((a_1b_1)c_1, (a_2b_2)c_2)$$

$$= (a_1(b_1c_1), a_2(b_2c_2))$$

$$= (a_1, a_2) \odot (b_1c_1, b_2c_2)$$

$$= (a_1, a_2) \odot ((b_1, b_2) \odot (c_1, c_2)),$$

so  $\odot$  is associative.

2. Let  $e_1$  be the neutral element of  $G_1$  and  $e_2$  be the neutral element of  $G_2$ . Naturally, the neutral element of  $G_1 \times G_2$  is then  $(e_1, e_2)$ :

$$(a_1, a_2) \odot (e_1, e_2) = (a_1e_1, a_2e_2) = (a_1, a_2).$$

3. Naturally, the inverse of  $(a_1, a_2)$  is  $(a_1^{-1}, a_2^{-1})$ :

$$(a_1, a_2) \odot (a_1^{-1}, a_2^{-1}) = (a_1 a_2^{-1}, a_2 a_2^{-1}) = (e_1, e_2).$$

**Corollary 2.3.2.** Let  $\{G_i\}_{i\in I}$  be a family of groups for some non-empty (perhaps infinite) index set I. The set

$$\prod_{i\in I} G_i = \{(g_i)_{i\in I} \mid g_i \in G_i \text{ for all } i\in I\},$$

where  $(g_i)_{i \in I}$  denotes the sequence of  $g_i$ s as a touple, together with the law of composition  $\odot$  defined such that for all  $(g_i)_{i \in I}$ ,  $(h_i)_{i \in I} \in \{G_i\}_{i \in I}$ , we have

$$(g_i)_{i\in I}\odot(h_i)_{i\in I}=(g_ih_i)_{i\in I}$$

is a group.

**Corollary 2.3.3.** Let  $\{G_i\}_{i\in I}$  be a family of abelian groups for some non-empty index set I. The set

$$\bigoplus_{i \in I} G_i = \{(g_i)_{i \in I} \mid g_i \in G_i \text{ for all } i \in I, g_i \neq e_i \text{ for only finitely many } i \in I\},$$

where  $e_i$  denotes the neutral element of group  $G_i$ , together with the law of composition  $\odot$  given in Corollary 2.3.2, is a group. Furthermore,  $\bigoplus_{i \in I} G_i = \prod_{i \in I} G_i$  when I is finite; otherwise,  $\bigoplus_{i \in I} G_i$  is a proper subgroup of  $\prod_{i \in I} G_i$ .

**Definition 2.3.4.** Let  $\{G_i\}_{i\in I}$  be a family of groups for some non-empty index set I. The group  $\prod_{i\in I} G_i$  from Corollary 2.3.2 is called the direct product of the  $G_i$ s.

If the  $G_i$ s are abelian, the group  $\bigoplus_{i \in I} G_i$  from Corollary 2.3.3 is called the direct sum of the  $G_i$ s.

For a finite family of groups  $\{G_1, G_2, \dots, G_n\}$ , we can denote their direct sum as

$$G_1 \oplus G_2 \oplus \cdots \oplus G_n$$
.

# 2.4 Group action on a set

# 2.5 Sylow's theorem (?)

### Solved exercises

### Group homomorphisms

We define the mapping

$$f: (\mathbb{R}, +) \to (\mathbb{C} \setminus \{0\}, \cdot)$$
$$x \mapsto e^{i(2\pi x)}$$

where  $(\mathbb{R}, +)$  and  $(\mathbb{C} \setminus \{0\}, \cdot)$  are presumed to be groups (this can be shown).

**Exercise 2.1.** Show that f is a group homomorphism.

*Solution.* Let  $x, y \in \mathbb{R}$ . Then,

$$f(x+y) = e^{i(2\pi(x+y))} = e^{i(2\pi x) + i(2\pi y)} = e^{i(2\pi x)} \cdot e^{i(2\pi y)} = f(x) \cdot f(y)$$

so *f* is a group homomorphism.

**Exercise 2.2.** Find ker(f).

*Solution.* We know  $e_{\mathbb{C}} = 1$ , so

$$\ker(f) = \{ x \in \mathbb{R} \mid e^{i(2\pi x)} = 1 \} = \mathbb{Z}.$$

**Exercise 2.3.** Find im(f).

Solution. By definition, we have

$$im(f) = \{e^{i(2\pi x)} \in \mathbb{C} \setminus \{0\} \mid x \in \mathbb{R}\} = \{z \in \mathbb{C} \mid |z| = 1\},\$$

which is the complex unit circle group, often denoted  $\mathbb{T}$ .

**Exercise 2.4.** Construct an isomorphism from f using the fundamental theorem on homomorphisms.

Solution. We define

$$\psi: \begin{array}{ccc} (\mathbb{R},+)/\mathrm{ker}(f) & \to & \mathrm{im}(f) \\ x\mathrm{ker}(f) & \mapsto & f(x) \end{array} \equiv \begin{array}{ccc} (\mathbb{R},+)/\mathbb{Z} & \to & \mathbb{T} \\ x\mathbb{Z} & \mapsto & e^{i(2\pi x)} \end{array} .$$

### **Isomorphisms**

Let *G* be a group. For each  $a \in G$ , we define the mapping

$$\begin{array}{cccc} f_a: & G & \to & G \\ & x & \mapsto & axa^{-1} \end{array}.$$

**Exercise 2.5.** Show that  $f_a$  is an isomorphism.

*Solution.* Let  $x, y \in G$ . Then,

$$f_a(xy) = a(xy)a^{-1} = ax(a^{-1}a)ya^{-1} = (axa^{-1})(aya^{-1}) = f_a(x)f_a(y),$$

so  $f_a$  is a group homomorphism. Additionally, for every z in the codomain G, we have  $z = f_a(a^{-1}za)$ , so  $f_a$  is surjective, and any surjective mapping between two sets of the same cardinality is also injective. Hence,  $f_a$  is an isomorphism.  $\Box$ 

**Exercise 2.6.** Show that for all  $x \in G$ , we have  $\operatorname{ord}(f_a(x)) = \operatorname{ord}(x)$ .

*Solution.* Let  $n = \operatorname{ord}(x)$ . Then, n is the minimal positive integer such that

$$x^{n} = e_{G}$$

$$ax^{n}a^{-1} = ae_{G}a^{-1}$$

$$ax^{n}a^{-1} = aa^{-1}$$

$$f_{a}(x^{n}) = e_{G}$$

Since  $f_a$  is a homomorphism,  $f_a(x^n) = (f_a(x))^n$ . Hence,  $\operatorname{ord}(f_a(x)) = n$ .

### The dihedral group

Let p be a prime number greater than or equal to 3, and let G be a group of cardinality 2p.

**Exercise 2.7.** What can we say if G has an element of order 2p?

*Solution.* Let  $g \in G$  such that  $\operatorname{ord}(g) = 2p$ . Then, since  $\langle g \rangle \subseteq G$  and

$$|\langle g \rangle| = \operatorname{ord}(g) = 2p = |G|,$$

we see  $G = \langle g \rangle$ . Hence, G is a cyclic group.

Now assume G has no element of order 2p.

**Exercise 2.8.** Show that G has an element of order p.

*Solution.* Let H be a subgroup of G. By Lagrange's theorem, |H| divides |G|, so  $|H| \in \{1,2,p,2p\}$ . Let  $g \in G \setminus \{e\}$ . Since  $\langle g \rangle$  is a subgroup of G and since, by assumption,  $\operatorname{ord}(g) \neq 2p$ , we see  $\operatorname{ord}(g) \in \{2,p\}$ .

Suppose *G* does not have an element of order *p*. Then, for all  $x, y \in G \setminus \{e\}$ , we have  $\operatorname{ord}(x) = \operatorname{ord}(y) = 2$ , so  $x^2 = y^2 = e$ . Thus,

$$(xy)(xy) = e$$

$$xyxyy = ey$$

$$xyx = y$$

$$xxyx = xy$$

$$yx = xy,$$

so *G* is abelian. We therefore have that  $\{e, x, y, xy\}$  is a subgroup of *G* of order 4, a contradiction. Hence, *G* has an element of order *p*.

**Exercise 2.9.** Let  $a \in G$  such that ord(a) = p, let H be the subgroup of G generated by a, and let  $b \in G \setminus H$ . Show that

$$G = \{e, a, a^2, \dots, a^{p-1}, b, ba, ba^2, \dots, ba^{p-1}\}.$$

*Solution.* Since  $b \notin H$ , we see

$$H = \langle a \rangle = \{e, a, a^2, \dots, a^{p-1}\}$$
 and  $bH = \{b, ba, ba^2, \dots, ba^{p-1}\}$ 

are cosets of H in G, each of cardinality p. Since the cosets are disjoint, we have  $|H \cup bH| = 2p = |G|$ , so

$$G = H \cup bH = \{e, a, a^2, \dots, a^{p-1}, b, ba, ba^2, \dots, ba^{p-1}\}.$$

**Exercise 2.10.** Show that  $b^2 = e$ .

*Solution.* We have shown that for every  $g \in G$ , we have  $g \in H$  or  $g \in bH$ . Since  $b \notin H$ , there does not exist any  $n \in \mathbb{Z}$  such that  $a^n = b$ . Suppose  $b^2 \in bH$ . Then, there exists some  $n \in \mathbb{Z}$  such that

$$b^{2} = ba^{n}$$

$$bb = ba^{n}$$

$$b^{-1}bb = b^{-1}ba^{n}$$

$$b = a^{n},$$

a contradiction. Thus,  $b^2 \in H$ , so there exists some  $m \in \mathbb{Z}$  such that  $b^2 = a^m$ .

We have also shown that for every  $g \in G \setminus \{e\}$ , we have  $\operatorname{ord}(g) = 2$  or  $\operatorname{ord}(g) = p$ . Suppose  $\operatorname{ord}(b) = p$ . Then,  $b^p = e$ . By Bézout's theorem, since  $\gcd(2, p) = 1$ , there exist some  $k, l \in \mathbb{Z}$  such that 2k + pl = 1. Thus,

$$b = b^1 = b^{2k+pl} = b^{2k} b^{pl} = (b^2)^k (b^p)^l = (b^2)^k = (a^m)^l = a^{mk}$$

a contradiction. Hence, ord(b) = 2.

**Exercise 2.11.** Show that  $ab = ba^{p-1}$ .

*Solution.* We have shown that for every  $g \in G \setminus H$ , we have  $g^2 = e$ . Thus,

$$(ba^{p-1})^2 = e$$

$$ba^{p-1}ba^{p-1} = e$$

$$ba^{p-1}ba^p = a$$

$$ba^{p-1}be = a$$

$$ba^{p-1}bb = ab$$

$$ba^{p-1} = ab$$

**Exercise 2.12.** We define the dihedral group  $\mathcal{D}_n$  as the group of symmetries of the regular n-gon, consisting of n rotations of angle  $2\pi k/n$  for  $k \in \{0, 1, ..., n-1\}$  and n reflections about the lines intersecting its center and each vertex. It

can be shown that for any rotation  $r \in \mathcal{D}_n$  and any reflection  $s \in \mathcal{D}_n$ , r and s generate  $\mathcal{D}_n$ ; that is,

$$\mathcal{D}_n = \{ id, r, r^2, \dots, r^{n-1}, sr, sr^2, \dots, sr^{n-1} \}.$$

Show that  $G \simeq \mathcal{D}_v$ .

*Solution.* Let r be a rotation in  $\mathcal{D}_p$ , and let s be a reflection in  $\mathcal{D}_p$ . Consider the mapping  $\phi : G \to \mathcal{D}_p$  such that for all  $n \in \mathbb{Z}$ ,

$$\phi(a^n) = r^n, \qquad \qquad \phi(ba^n) = sr^n.$$

Let  $n, m \in \mathbb{Z}$ . Any composition of elements in G is of one of the following forms:

$$a^{n}a^{m} = a^{n+m}$$
,  
 $a^{n}ba^{m} = (a^{n-1}a)ba^{m} = a^{n-1}(ba^{p-1})a^{m} = a^{n-1}ba^{p-1+m} = \cdots = ba^{n(p-1)+m}$ ,  
 $ba^{n}a^{m} = ba^{n+m}$ ,  
 $ba^{n}ba^{m} = b(ba^{n(p-1)+m}) = a^{n(p-1)+m}$ .

Thus,  $\phi$  is well-defined, and it can be shown through straightforward computations that for all  $x, y \in G$ , we have  $\phi(xy) = \phi(x) \phi(y)$ , so  $\phi$  is a homomorphism.

Since every element of G maps to a unique element in  $\mathcal{D}_p$ , we see  $\phi$  is injective. Additionally, since

$$\mathcal{D}_p = \{\mathrm{id}, r, r^2, \dots, r^{p-1}, sr, sr^2, \dots, sr^{p-1}\},\$$

we see each element of  $\mathcal{D}_p$  is reached by some element of G, so  $\phi$  is surjective. Hence,  $\phi$  is an isomorphism.

# Chapter 3

# Rings and Fields

# 3.1 Rings

**Definition 3.1.1.** Let R be a set, and let + and  $\cdot$  be two laws of composition on R. The triple  $(R, +, \cdot)$  is called a ring if

- 1. (R, +) is an abelian group;
- 2. · is associative; and
- 3. · is distributive over +, i.e. for all  $x, y, z \in R$ , we have

$$(x + y) \cdot z = x \cdot z + y \cdot z$$
 and  $z \cdot (x + y) = z \cdot x + z \cdot y$ .

Let  $(R, +, \cdot)$  be a ring, and let  $a, b \in R$ . For the neutral element of R under +, we will use the notation 0 or  $0_R$ ; for the inverse of a under +, we will use the notation -a; and for the composition  $a \cdot b$ , we will use the notation ab. We will also assume the conventional order of operations, i.e. that  $\cdot$  comes before +.

**Proposition 3.1.2.** Let  $(R, +, \cdot)$  be a ring. Then,

- 1. for all  $a \in R$ , we have a(0) = 0a = 0; and
- 2. for all  $a, b \in R$ , we have

$$a(-b) = (-a)b = -(ab)$$
 and  $(-a)(-b) = ab$ .

Proof.

1. We can rewrite 0 as 0 + 0 and use the distributive property:

$$a(0) = a(0+0) 0a = (0+0)a$$

$$a(0) = a(0) + a(0) 0a = 0a + 0a$$

$$a(0) - (a(0)) = a(0) + a(0) - (a(0)) 0a - (0a) = 0a + 0a - (0a)$$

$$0 = a(0) 0 = 0a.$$

2. Note that for any  $x, y \in R$ , we have x = y if and only if x - y = 0. Thus, since

$$a(-b) + (ab) = a(-b + b) = a(0) = 0,$$

we have a(-b) = -(ab). Similarly, we can show (-a)b = (-ab). By substitution, we then see

$$(-a)(-b) - (ab) = (-a)(-b) + a(-b) = (-a+a)(-b) = 0(-b) = 0,$$
  
so  $(-a)(-b) = ab$ .

**Definition 3.1.3.** A ring  $(R, +, \cdot)$  is called

- 1. **commutative** if  $\cdot$  is commutative;
- 2. a ring with identity if there exists some  $u \in R$  such that for every  $a \in R$ , we have au = ua = a; or
- 3. an integral domain if it is a commutative ring with identity and for all  $a, b \in R$ , if ab = 0, then a = 0 or b = 0.

As with groups, we will also typically denote a ring  $(R, +, \cdot)$  simply by its set R. We will also denote the element  $u \in R$  from Definition 3.1.3 by 1 or  $1_R$ .

**Proposition 3.1.4.** Let *R* be a ring with identity. Then,

- 1. the element  $1 \in R$  is unique; and
- 2. if there exist  $b, c \in R$  such that ab = ca = 1 for some  $a \in R$ , then b = c.

Proof.

- 1. Suppose there exist  $u, v \in R$  such that for every  $a \in R$ , we have au = ua = a and av = va = a. Then, in particular, u = uv = v.
- 2. By the associative property, we see

$$b = 1b = (ca)b = c(ab) = c(1) = c.$$

**Definition 3.1.5.** Let R be a commutative ring with identity. An element  $a \in R \setminus \{0\}$  is called a zero divisor if there exists some  $b \in R \setminus \{0\}$  such that ab = 0.

**Proposition 3.1.6.** Let *R* be a commutative ring with identity. Then, the following are equivalent:

- 1. *R* has no zero divisors;
- 2. *R* is an integral domain;
- 3. for every  $a, b, c \in R$  where  $a \neq 0$ , if ab = ac, then b = c.

*Proof.* Clearly, R is an integral domain if and only if R has no zero divisors. Now, let  $a \in R \setminus \{0\}$  and suppose for all  $b, c \in R$ , we have

$$ab = ac$$

$$ab - ac = 0$$

$$a(b - c) = 0.$$

Since  $a \neq 0$ , we see by definition R is an integral domain if and only if this implies b-c=0 or, equivalently, b=c.

**Definition 3.1.7.** Let R be a ring with identity. An element  $a \in R$  is called a unit if there exists some  $a^{-1} \in R$  such that  $aa^{-1} = a^{-1}a = 1$ . The set of units of R is denoted  $R^*$ .

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**Proposition 3.1.8.** Let *R* be a ring with identity. Then,  $(R^*, \cdot)$  is a group.

*Proof.* We have three criteria for  $(R^*, \cdot)$  to be a group:

1. Let  $a, b \in R^*$ . Then, there exist some  $a^{-1}, b^{-1} \in R$  such that

$$aa^{-1} = a^{-1}a = 1$$
 and  $bb^{-1} = b^{-1}b = 1$ .

Since associativity follows from the ring, we have

$$(ab)(b^{-1}a^{-1}) = a(bb^{-1})a^{-1} = a(1)a^{-1} = aa^{-1} = 1,$$
  
 $(b^{-1}a^{-1})(ab) = b^{-1}(a^{-1}a)b = b^{-1}(1)b = b^{-1}b = 1.$ 

Thus,  $\cdot$  is an associative law of composition on  $R^*$ .

- 2. For every  $a \in R^*$ , we have 1a = a(1) = a, so 1 is the neutral element.
- 3. By construction,  $a^{-1}$  is then the inverse of a.

**Definition 3.1.9.** A ring R is called a field if it is a commutative ring with identity and all its nonzero elements are units, i.e.  $R \setminus \{0\} = R^*$ .

**Proposition 3.1.10.** Let *R* be a ring with identity. Every unit of *R* is not a zero divisor.

*Proof.* Let  $a \in R^*$ . Then, there exists some  $a^{-1} \in R$  such that  $aa^{-1} = a^{-1}a = 1$ . Suppose a is a zero divisor. Then, there exists some  $b \in R \setminus \{0\}$  such that ab = ba = 0, so

$$(aa^{-1})b = (a^{-1}a)b = a^{-1}(ab) = a^{-1}(0) = 0$$
 and  $(aa^{-1})b = 1b = b$ ,

which implies b = 0, a contradiction. Hence, a cannot be a zero divisor.

Corollary 3.1.11. Any field is an integral domain.

**Theorem 3.1.12.** Any finite integral domain is a field.

*Proof.* Let R be a finite integral domain, and let  $a \in R \setminus \{0\}$ . Consider the mapping

$$\begin{array}{cccc} f: & R & \to & R \\ & x & \mapsto & ax \end{array}.$$

Let  $x, x' \in R$  such that ax = ax'. Since R is an integral domain, left cancellation implies x = x', so f is injective. Further, since f is an injective map between finite sets of the same cardinality, f is also surjective, so there exists some  $b \in R$  such that  $f(b) = ab = 1 \in R$ , and since an integral domain is necessarily commutative, we also have ba = 1. Hence, a is a unit, so  $R \setminus \{0\} = R^*$ .

**Definition 3.1.13.** Let  $(R, +, \cdot)$  be a ring, and let  $S \subseteq R$ . If  $(S, +, \cdot)$  is a ring, it is called a subring of R.

**Theorem 3.1.14.** Let *R* be a ring, and let  $S \subseteq R$ ,  $S \neq \emptyset$ . Then, *S* is a subring of *R* if and only if for every  $a, b \in S$ , we have  $a - b \in S$  and  $ab \in S$ .

*Proof.* For S to be a ring, (S, +) must be an abelian group. Since  $S \subseteq R$ , this is the case if and only if (S, +) is a subgroup of (R, +) which, by Theorem 1.2.2, is true if and only if for all  $a, b \in S$ , we have  $a - b \in S$ .

Associativity and distributivity of  $\cdot$  follow from the parent ring R. Hence, all that remains is that S is closed under  $\cdot$ , i.e. for all  $a, b \in S$ , we have  $ab \in S$ .

**Definition 3.1.15.** Let *R* be a ring with identity, and let

$$K = \{ n \in \mathbb{N} \mid \underbrace{1_R + \dots + 1_R}_{n \text{ times}} = 0 \}.$$

The number

$$char(R) = \begin{cases} 0, & K = \emptyset \\ \min(K), & \text{otherwise} \end{cases}$$

is called the characteristic of *R*.

**Proposition 3.1.16.** The characteristic of an integral domain is either 0 or prime.

*Proof.* Let R be an integral domain, and let  $n = \operatorname{char}(R)$ . If n = 0, we are finished; for the other case, since n cannot be 1, take n > 1. Suppose n is not prime. Then, there exist  $p, q \in \mathbb{Z}^+$ , p, q < n such that n = pq, so

$$0_{R} = \underbrace{1_{R} + \dots + 1_{R}}_{n \text{ times}} = \underbrace{1_{R} + \dots + 1_{R}}_{p \text{ times}}$$

$$= \underbrace{(1_{R} + \dots + 1_{R}) + \dots + (1_{R} + \dots + 1_{R})}_{p \text{ times}}$$

$$= \underbrace{(1_{R} + \dots + 1_{R}) 1_{R} + \dots + (1_{R} + \dots + 1_{R}) 1_{R}}_{p \text{ times}}$$

$$= \underbrace{(1_{R} + \dots + 1_{R}) 1_{R} + \dots + (1_{R} + \dots + 1_{R}) 1_{R}}_{p \text{ times}}$$

$$= \underbrace{(1_{R} + \dots + 1_{R}) (1_{R} + \dots + 1_{R})}_{p \text{ times}}.$$

Since *R* is an integral domain, this implies

$$\underbrace{1_R + \dots + 1_R}_{p \text{ times}} = 0_R \quad \text{or} \quad \underbrace{1_R + \dots + 1_R}_{q \text{ times}} = 0_R,$$

which is a contradiction.

### Homomorphisms of rings

**Definition 3.1.17.** Let  $(R, +, \cdot)$  and  $(S, \oplus, \odot)$  be two rings. A mapping  $\phi : R \to S$  is called a homomorphism of rings if for all  $x, y \in R$ , we have

$$\phi(x + y) = \phi(x) \oplus \phi(y)$$
 and  $\phi(x \cdot y) = \phi(x) \odot \phi(y)$ .

A homomorphism of rings that is a bijection is called an isomorphism.

**Proposition 3.1.18.** Let  $(R, +, \cdot)$  and  $(S, \oplus, \odot)$  be two rings. If there exists a homomorphism of rings  $\phi : R \to S$ , then there exists a group homomorphism  $\psi : (R, +) \to (S, \oplus)$ .

Do this proof! Proof.

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**Proposition 3.1.19.** Let  $\phi : R \to S$  be a homomorphism of rings. Then,  $\phi$  is an isomorphism if and only if there exists a unique isomorphism  $\rho : S \to R$  such that  $\rho \circ \phi = \mathrm{id}_R$  and  $\phi \circ \rho = \mathrm{id}_S$ .

Proof. \_\_\_\_\_\_ Do this proof!

**Definition 3.1.20.** Let  $\phi$  be a homomorphism of rings. The image and kernel of the underlying group homomorphism  $\psi$  from Proposition 3.1.18 are called the image and kernel of  $\phi$ .

**Proposition 3.1.21.** Let  $\phi : R \to S$  be a homomorphism of rings. Then,

- 1.  $im(\phi)$  is a subring of *S*;
- 2.  $\ker(\phi)$  is a subring of R;
- 3.  $\phi$  is injective if and only if  $\ker(\phi) = \{0_R\}$ ;
- 4.  $\phi$  is surjective if and only if  $im(\phi) = S$ ; and
- 5. for every  $x \in R$  and  $y \in \ker(\phi)$ , we have  $xy \in \ker(\phi)$ .

Proof. \_\_\_\_\_ Do this proof!

### 3.2 Ideals

**Definition 3.2.1.** Let *R* be a ring. A non-empty  $I \subseteq R$  is called an ideal of *R* if

- 1. (I, +) is a subgroup of (R, +) and
- 2. for all  $x \in R$  and  $i \in I$ , we have  $xi \in I$  and  $ix \in I$ .

**Definition 3.2.2.** Let *R* be a commutative ring with identity. An ideal *I* of *R* is called

- 1. **prime** if for every  $x, y \in R$ , if  $xy \in I$ , then  $x \in I$  or  $y \in I$ ; or
- 2.  $\max$  if  $I \neq R$  and if there exists an ideal J such that  $I \subseteq J$ , then I = J or J = R.

# 3.3 Arithmetic in integral domains

# 3.4 Polynomials

Solved exercises