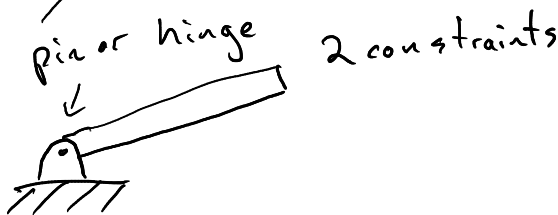
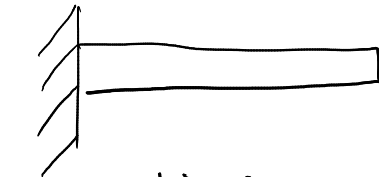


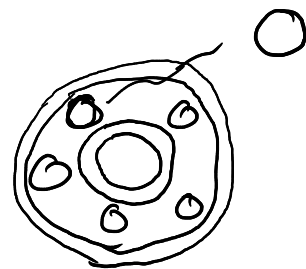
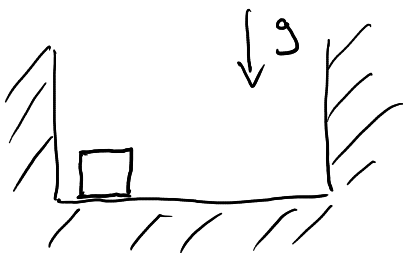
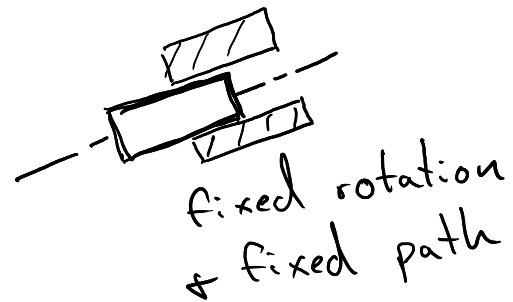
$$\begin{array}{r}
 6 \\
 -2 \\
 -2 \\
 -1 \\
 \hline
 1 \text{ DOF}
 \end{array}$$

Constraints

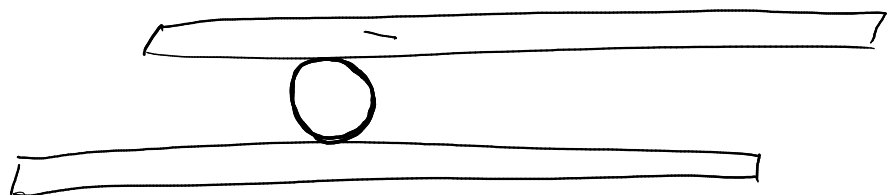
Fixed \rightarrow 3 constraints

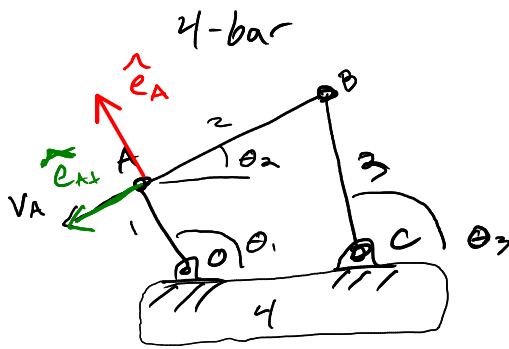


prismatic constraint



ball bearings \rightarrow 1 DOF





$$l_1 = 0.25 \text{ m}, l_2 = 1 \text{ m}, l_3 = 1 \text{ m}$$

$$dx = 1 \text{ m and } dy = 0 \text{ m}$$

at time, t , link 1 (OA) is rotating at 10 rad/s. The positions of the pins are as follows

$$r_0 = 0\hat{i} + 0\hat{j} [\text{m}]$$

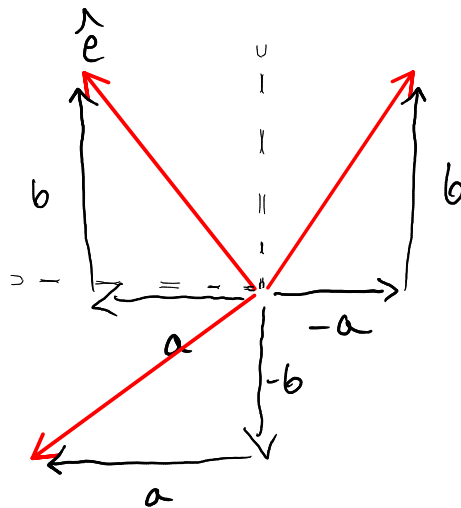
$$r_A = -0.203\hat{i} + 0.1459\hat{j} [\text{m}]$$

$$r_B = 0.494\hat{i} + 0.863\hat{j} [\text{m}]$$

$$r_C = 1\hat{i} + 0\hat{j} [\text{m}]$$

What are the rotation rates for links 2 and 3 (AB and BC, respectively)

$$\dot{\theta}_2 \quad \dot{\theta}_3$$



$$\bar{V}_A = 2.5 \text{ m/s} \left(-\frac{0.1459}{0.25} \hat{i} - \frac{0.203}{0.25} \hat{j} \right)$$

$$\bar{V}_C = 0\hat{i} + 0\hat{j} \text{ m/s}$$

piston-crank

know

$$\dot{\theta}_1 = 10 \text{ rad/s}$$

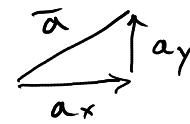
$$\bar{r}_A = -0.203\hat{i} + 0.1459\hat{j} \text{ m}$$

$$|\bar{r}_A| = 0.25 \text{ m}$$

$$\checkmark V_A = 2.5 \text{ m/s} = l_1 \dot{\theta}_1 \text{ m/s}$$

$$\hat{e}_A = \frac{-0.203}{0.25} \hat{i} + \frac{0.1459}{0.25} \hat{j}$$

$$\hat{e}_{A\perp} = -\frac{0.1459}{0.25} \hat{i} - \frac{0.203}{0.25} \hat{j}$$

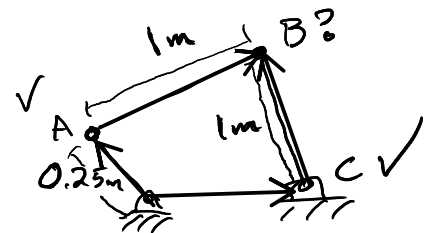


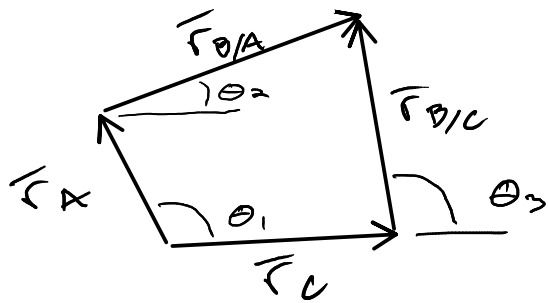
$$\cos\theta = \frac{a_x}{|\bar{a}|}$$

$$\sin\theta = \frac{a_y}{|\bar{a}|}$$

$$\hat{e} = \cos\theta \hat{i} + \sin\theta \hat{j}$$

$$\hat{e}_\perp = -\sin\theta \hat{i} + \cos\theta \hat{j}$$





$$v_A = l_1 \dot{\theta}_1 \hat{e}_A'$$

$$\bar{v}_{B/A} = l_2 \dot{\theta}_2 \hat{e}_{B/A}'$$

$$\bar{v}_{B/C} = l_3 \dot{\theta}_3 \hat{e}_{B/C}'$$

$$\frac{d}{dt} \left(\bar{r}_A + \bar{r}_{B/A} = \bar{r}_C + \bar{r}_{B/C} \right)$$

$$\bar{v}_A + \bar{v}_{B/A} = \cancel{\bar{v}_C} + \bar{v}_{B/C}$$

$$\bar{v}_A = 2.5 \text{ m/s} \left(-\frac{0.1459}{0.25} \hat{i} - \frac{0.203}{0.25} \hat{j} \right)$$

$$\bar{v}_C = 0 \hat{i} + 0 \hat{j} \text{ m/s}$$