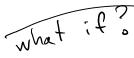
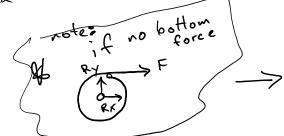


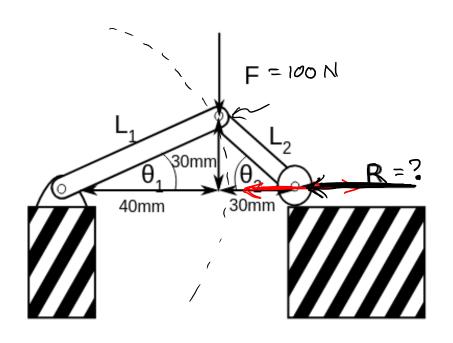
$$F = Y = IQ$$

$$T = moment of inertia$$

$$\begin{bmatrix} mR^2 \\ 2 \end{bmatrix}$$





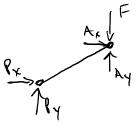


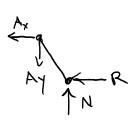
## quasistatic

$$\sum F_{\gamma} = 0$$

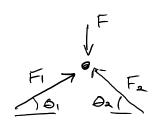
$$\sum F_x = R_x - R = 0$$
  
 $\sum F_y = R_y + N - F = 0$ 

$$R_{x} = R$$





$$ZF_y = P_y + N - F = 0$$



$$R-P_{x}$$
 $P_{y}+N=F$ 

