

Stochastic

Final Study Guide

Basics

What is a Stochastic Process?

A probability model that describes the evolution of a system evolving randomly in time.

We describe a Stochastic Process by describing its...



RV Review

We'll need some basic RVs for when we start exploring CTMCs...

Exponential Distribution

pdf: $f(x) = \lambda e^{-\lambda x}, x \geq 0$
 cdf: $F(x) = P(X \leq x) = 1 - e^{-\lambda x}, x \geq 0$
 expected value: $E[X] = \frac{1}{\lambda}$
 variance: $Var(X) = \frac{1}{\lambda^2}$

the exponential distribution has the memoryless property which means the distribution does not depend on what has happened previously in the distribution.

Long Distribution

pdf: $f(x) = \lambda e^{-\lambda x} \frac{(\lambda x)^{n-1}}{(n-1)!}$
 cdf: $F(x) = 1 - \sum_{r=0}^{n-1} e^{-\lambda x} \frac{(\lambda x)^r}{r!}$
 expected value: $E[X] = \frac{n}{\lambda}$
 variance: $Var(X) = \frac{n}{\lambda^2}$

Poisson Distribution

pmf: $P_k = e^{-\lambda} \frac{\lambda^k}{k!}$
 expected value: $E[X] = \lambda$
 variance: $Var(X) = \lambda$

properties

Sum of exponentials
 X_i are iid $Exp(\lambda)$ RVs and $Z_n = X_1 + X_2 + \dots + X_n$, then...
 $Z_n \sim Erl(n, \lambda)$

Minimum of exponentials
 X_i are iid $Exp(\lambda_i)$ RVs and $X = \min\{X_1, X_2, \dots, X_n\}$
 $X \sim Exp(\lambda)$, $\lambda = \sum_{i=1}^n \lambda_i$

Distribution of (Z, X)
 The Z and X above are ind RVs w/ dist...
 $P(Z=1)P(X>0) = \frac{\lambda}{\lambda} e^{-\lambda}$

Sum of Poisson
 X_i are iid $Po(\lambda_i)$ RVs and $Z_n = X_1 + X_2 + \dots + X_n$
 $Z_n \sim Po(\lambda)$, $\lambda = \sum_{i=1}^n \lambda_i$

DTMC

Discrete Time Markov Chain

X_n is the state of a system at time n for $n=0, 1, 2, \dots$
 n is discrete

$\{X_n, n \geq 0\}$

what do we need to describe X_n ...
 time homo. DTMC
 $ES = \{1, 2, \dots, N\}$
 $P = [p_{ij}]$ = transition prob. matrix
 $\vec{a} = [a_1, \dots, a_N]$ = initial dist.
 $\vec{c} = [c(1), \dots, c(N)]$ = cost incurred at state n .

DTMC

X_n is a discrete time Markov chain if for $\forall i, j \in ES$...
 $P(X_{n+1}=j | X_n=i, X_{n-1}, \dots, X_0) = P(X_{n+1}=j | X_n=i)$
 X_n is also time homogeneous if...
 $P(X_{n+1}=j | X_n=i) = P(X_1=j | X_0=i)$

lets define these...

jumping off: eg. a 1-step transition prob. we can make an n -step transition probability

$p_{ij}^{(n)} = P(X_n=j | X_0=i)$
 $P^{(n)} = [p_{ij}^{(n)}] = P^n$

one step transition probability: $P = [p_{ij}]$
 there exists a matrix containing all p_{ij}

we could also make transient dist. aka $P(X_n=j) = \vec{a}^{(n)}$
 aka $P(X_n=j) = \vec{a}^{(n)}$

Chapman-Kolmogorov Eq.
 $p_{ij}^{(n+m)} = \sum_k p_{ik}^{(n)} p_{kj}^{(m)}$

Applications

Occupancy Time: $m_{ij}(n)$
 = expected # of times system visits state j over $[0, \dots, n]$ if it starts in i
 $M(n) = [m_{ij}(n)] = \sum_{r=0}^n P^r$

expected total cost over finite n if you start in state i
 $g(i, n) = \vec{g}(n) \cdot M(n) \cdot \vec{c}$
 long run expected cost per unit time
 $\bar{g} = \vec{g} \cdot \vec{\pi} = \sum_{j=1}^N \pi_j g(j)$

First Passage Time
 time when a system first passes into/enters a given state or subset of states
 A = subset of states
 $m_i(A)$ = expected first passage time into subset A
 $\vec{1} = \sum_{j \in A} p_{ij} m_j(A)$, for $i \notin A$
 $\vec{a}(A) = \vec{c} \cdot P(A) \vec{a}(A)$

Limiting Dist.
 $\vec{\pi} = [\pi_1, \pi_2, \dots, \pi_N]$
 $\pi_j = \lim_{n \rightarrow \infty} p_{ij}^{(n)}$
 the limiting dist is how the system evolves as time goes to a steady state. we find it by solving $\vec{\pi} = \vec{\pi} P$
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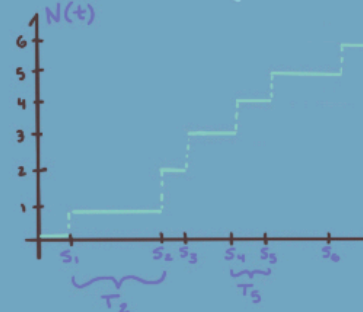
Limiting Behavior
 Stationary Dist.
 $\vec{\pi} = [\pi_1, \pi_2, \dots, \pi_N]$
 if you choose the $\vec{\pi}$ as your initial dist the dist. will remain the same for all n if $\vec{\pi}$ exists then $\vec{\pi} = \vec{\pi} P$

Occupancy Dist.
 $\vec{\pi} = [\pi_1, \pi_2, \dots, \pi_N]$
 the fraction of the time a system spends in state j
 if $\vec{\pi}$ exists then $\vec{\pi} = \vec{\pi} P$

CTMC

Continuous Time Markov Chain

this system is tracking occurrences that occur 1 after the other according to a RV...



Poisson Process

$N(t)$ = total # of events over $(0, t]$
 S_n = occurrence time of n th event
 $T_n = S_n - S_{n-1}$ = time between $(n-1)$ th and n th event

$\{X(t), t \geq 0\}$

$X(t)$ = state of a system at time t

starts in state i → stays in state i for $Exp(\mu_i)$

then transitions to state j w/ prob p_{ij}

stays in state j for $Exp(\mu_j)$ amount of time...

$p_{ij}(t) = P(X(t)=j | X(0)=i)$
 $P(t) = [p_{ij}(t)]$

The process as defined above is a CTMC, because the time between occurrences are exp. and therefore memoryless.

NOTE: We can use a PP to describe the time to a CTMC system (since a PP is made up of exp RVs)

many of these are very similar to their DTMC definitions

expected total cost up to finite time T starting from state i
 $\vec{g}(T) = M(T) \cdot \vec{c}$

long run cost per unit time
 $\bar{g} = \sum_{j=1}^N \pi_j g(j)$

Applications

Parameter describing the system stays in i
 μ_i = amount of time the system stays in i
 p_{ij} = prob of system moving to state j right after state i
 $R = [r_{ij}]$ = the rate matrix
 $r_{ij} = \mu_i p_{ij}$
 $r_{ii} = -\sum_{j \neq i} \mu_i p_{ij}$

what we will use most of the time to describe $X(t)$ is...

$r_{ij} = \mu_i p_{ij}$

$r_{ii} = -\sum_{j \neq i} \mu_i p_{ij}$

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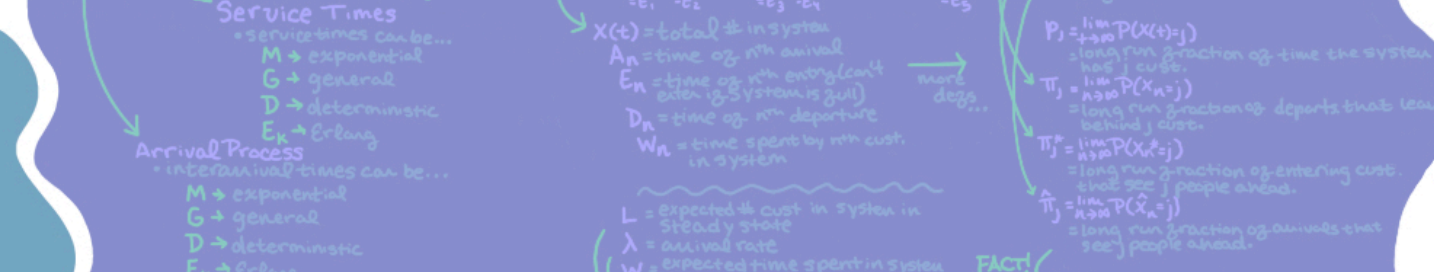
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QUEUES

One common type of CTMC is a queueing model...

How do we talk about queues?
 Attributes...
 Capacity: K (if blank, assume ∞)
 # of Servers: M
 Service Times: M = exponential, G = general, D = deterministic, E_k = Erlang
 Arrival Process: M = exponential, G = general, D = deterministic, E_k = Erlang



Little's Law
 $L = \lambda W$

Limiting prob. = $P_i(K)$
 $P_i(K) = \frac{P_i}{\sum_{j=0}^K P_j}$

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Applications

First passage times
 time when system first passes into a set of states A solve $\vec{r}_i m_i(A) = \sum_{j \in A} r_{ij} m_j(A)$ for $i \notin A$

expected total cost up to finite time T starting from state i
 $\vec{g}(T) = M(T) \cdot \vec{c}$

long run cost per unit time
 $\bar{g} = \sum_{j=1}^N \pi_j g(j)$

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