## ListPlot examples

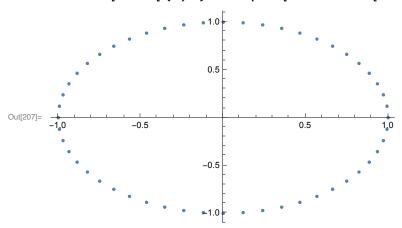
To plot a function, you use Plot. To plot a collection of points, you use ListPlot.

Here are examples of plotting all of the points given by (A^k)X, where A is a 2x2 matrix, and X is an initial point in the xy plane. We will let "mat" be our matrix, and we will obtain a list of points by using the Table command. By plugging this into the ListPlot command, we can get a graph of the points of the form A^k X.

(Note that in order to switch back and forth between row/column matrices, I am using the Transpose command, along with the fact that (AB)^T = B^T A^T.)

$$In[206] = mat = N \left[ \begin{pmatrix} Cos[2Pi*(1/52)] & -Sin[2Pi(1/52)] \\ Sin[2Pi(1/52)] & Cos[2Pi(1/52)] \end{pmatrix} \right];$$

ListPlot[Table[ {0, 1}.Transpose[MatrixPower[mat, k]], {k, 0, 200} ]]



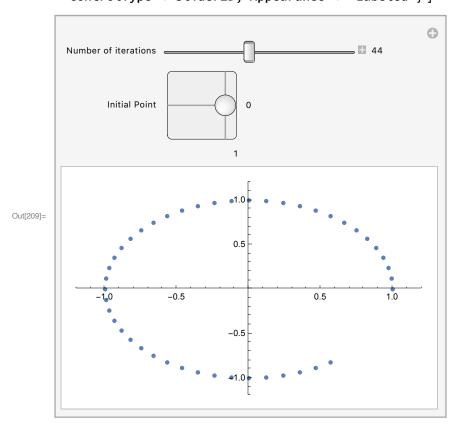
By combining the above with the Manipulate command, we can get a nice picture showing us how a

point evolves along progressive iterations along with how things change as the initial point changes.

$$ln[208]:= mat1 = N \left[ \begin{pmatrix} Cos[2Pi*(1/52)] & -Sin[2Pi(1/52)] \\ Sin[2Pi(1/52)] & Cos[2Pi(1/52)] \end{pmatrix} \right];$$

## Manipulate[

```
ListPlot[Table[x.Transpose[MatrixPower[mat1, k]], {k, 0, n}],
 PlotRange \rightarrow \{\{-1.2, 1.2\}, \{-1.2, 1.2\}\}\}
{{n, 0, "Number of iterations"}, 0, 100, 1, Appearance → "Labeled"},
{{x, {1, 0}, "Initial Point"}, -1, 1,
 ControlType → Slider2D, Appearance → "Labeled"} ]
```

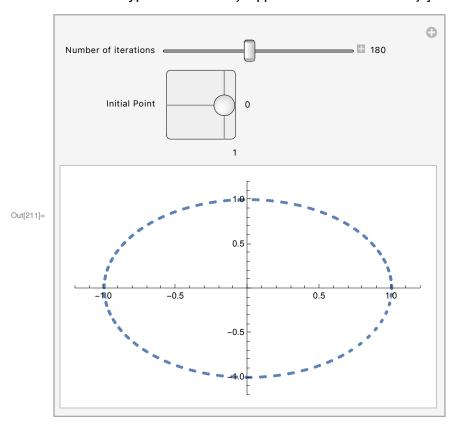


Here's another example, but the matrix has been changed slightly.

```
ln[210]:= mat2 = N \left[ \begin{pmatrix} Cos[.1] & -Sin[.1] \\ Sin[.1] & Cos[.1] \end{pmatrix} \right];
```

## Manipulate[

```
ListPlot[Table[x.Transpose[MatrixPower[mat2, k]], {k, 0, n}],
 PlotRange \rightarrow \{\{-1.2, 1.2\}, \{-1.2, 1.2\}\}\}
\{\{n, 0, "Number of iterations"\}, 0, 400, 1, Appearance \rightarrow "Labeled"\},
{{x, {1, 0}, "Initial Point"}, -1, 1,
 ControlType → Slider2D, Appearance → "Labeled"} ]
```



Here is a visualization of the example we did at the beginning of class, where the linear transformation satisfied

T(2,1) = 2(2,1) and T(0,1) = .5(0,1).

$$ln[212]:=$$
 mat3 =  $N\left[\begin{pmatrix} 2 & 0 \\ 3/4 & 1/2 \end{pmatrix}\right]$ ;

## Manipulate[

```
ListPlot[Table[ x.Transpose[MatrixPower[mat3, k]], \{k, 0, n\}], PlotRange \rightarrow \{\{-10, 10\}, \{-5, 5\}\}], \{\{n, 0, "Number of iterations"\}, 0, 20, 1, Appearance <math>\rightarrow "Labeled"}, \{\{x, \{0, 1\}, "Initial Point"\}, -1, 1, ControlType <math>\rightarrow Slider2D, Appearance \rightarrow "Labeled"}]
```

