# Learning Unitary Operators with Help From $\mathfrak{u}(n)$

## ETHzürich

#### Introduction

- Training deep neural networks can be difficult due to the problem of vanishing/exploding gradients
- In recurrent neural networks, repeated application of the state evolution operator can be responsible
- Using a norm-preserving operator can help!
  - focus on unitary/orthogonal matrices
- Gradient updates in general break unitarity: use
  parametrisation closed under additive updates
- Idea: use **Lie group-Lie algebra correspondence** to define parametrisation

## Parametrisation with $\mathfrak{u}(n)$

- Unitary  $n \times n$  matrices form a continuous group, U(n) (a **Lie group**), closed under matrix multiplication
- The tangent space to a Lie group at the identity is its Lie
  algebra: a vector space closed under addition
  - U(n)'s Lie algebra is  $\mathfrak{u}(n)$ , the space of  $n \times n$  skew-Hermitian matrices  $(A^{\dagger} = -A)$
- The **exponential map** associates elements of the Lie group and Lie algebra:
  - for matrix groups like U(n), the map is the matrix exponential (expm)
  - $L \in \mathfrak{u}(n) \Rightarrow \exp(L) \in U(n)$
  - as *U*(*n*) is compact and connected, the map is **surjective** (not true for the orthogonal group)
- Given a basis  $\{T_i\}$  of  $\mathfrak{u}(n)$ ,  $L \in \mathfrak{u}(n)$  is defined by its coefficients  $\lambda_i \in \mathbb{R}$
- Thus U is parametrised by these  $n^2$  coefficients:

$$U(\lambda_1, \dots, \lambda_{n^2}) = \exp\left(\sum_{i=1}^{n^2} \lambda_i T_i\right)$$
 Thus: we do gradient descent in the **Lie algebra**

- Choice of basis  $\{T_i\}$  is arbitrary: we choose them to be **sparse** (1 or 2 non-zero elements):
  - *n* diagonal imaginary
  - n(n-1)/2 symmetric imaginary
  - n(n-1)/2 skew-symmetric real

## Stephanie L. Hyland, Gunnar Rätsch ETH Zürich, Weill Cornell Medicine

#### **Learning the Operator**

- Discard the rest of RNN machinery (for now!)
- Simple supervised learning task:
  - sample random ground truth U, many random  $\mathbf{x}$
  - $\mathbf{y} = U\mathbf{x} + \epsilon$  , where  $\epsilon \sim \mathcal{N}(0, \sigma^2)$
  - minimise mean  $\|\hat{U}\mathbf{x} \mathbf{y}\|^2$  over batches
- Approaches for learning *U*:
  - 1. **projection**: after gradient update, project *U* back to closest unitary matrix
  - 2. **composition**: *U* is a product of parametrisable unitary operators; (with *7n* free parameters) from *Arjovsky, Shah & Bengio (ICLR 2016)*
  - 3. lie algebra: U is defined by the n<sup>2</sup> coefficients of an element of the Lie algebra (my method)

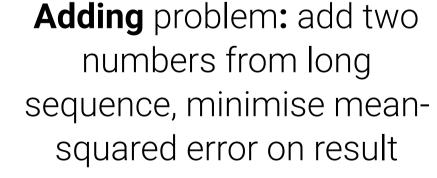
### **General Unitary RNN**

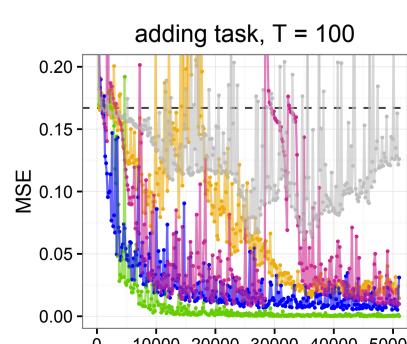
• Define (general) unitary recurrent neural network, with:

$$\mathbf{h}_t = f\left(U\mathbf{h}_{t-1} + V\mathbf{x}_t + \mathbf{b}\right)$$

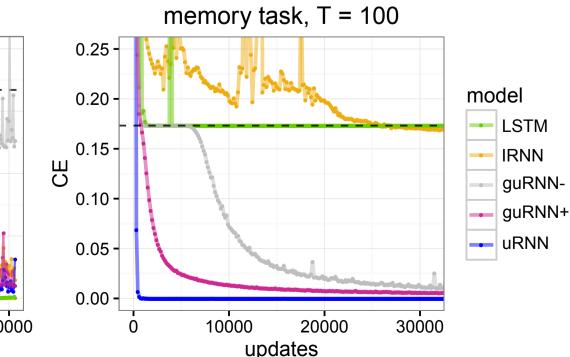
• f is a nonlinearity, **h** is hidden state, U is a **unitary** matrix

Tasks: (classic long-memory RNN problems)





**Memory** problem: 'remember' a sequence for a long time, minimise categorical crossentropy over whole sequence



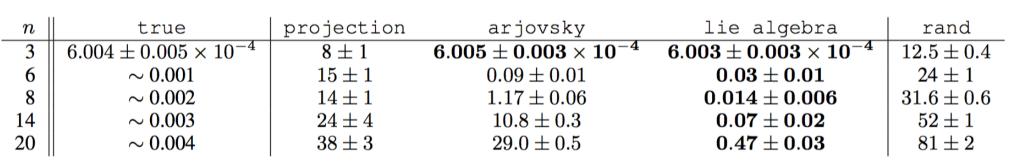
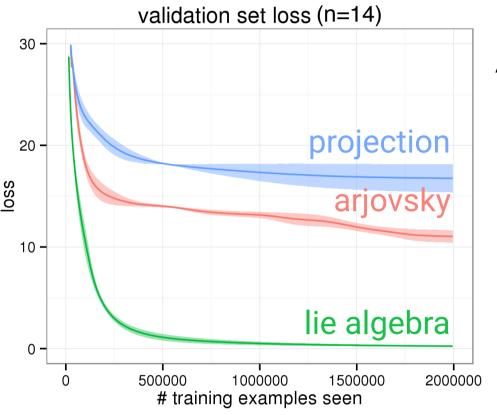


Table: Mean squared I2 distance between true **y** and predicted **y** 



Additional experiments:

- **restricted**: restrict lie algebra to have 7*n* learnable parameters
- basis: change the basis used by lie algebra with random uniform matrix (e.g. between -5 and 5)

## **†** Further Questions **†**

- · Geometry:
  - Casting the learning problem directly as optimisation on the Lie group (manifold)
  - How does exponential map change cost surface?
- Deep learning:
- understanding relative performance of models
- nonlinearity has a large role in vanishing gradients consider it alongside transition operator

#### Conclusions

- Parametrisation using the Lie algebra enables the learning of arbitrary unitary operators with simple gradient descent
- We've used our parametrisation to define a general unitary RNN and demonstrated it on standard tasks
- The parametrisation of Arjovksy *et al.* struggles to learn matrices for n > 7, but still works well in an RNN setting, somehow
- Code: https://github.com/corcra/uRNN
- Paper: accepted at AAAI-17, available on arXiv:

