Artificial Intelligence

Ko, Youngjoong

Index

1. What is Machine Learning?

2. SOTA ML Applications

3. Learning Types

4. Framing a Learning Problem

5. A Brief History of Machine Learning

- What is the Machine Learning?
 - ➤ **Herbert Simon**: "Leaning is any process by which a system improves performance from experience."
 - > Tom Mitchell (1998):

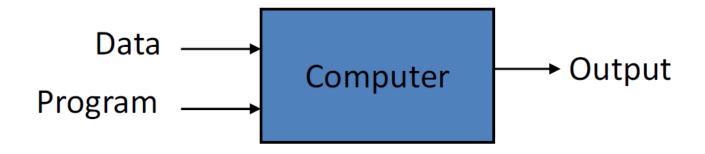
Machine Learning is the study of algorithms that

- improve their performance, P
- at some task, **T**
- with experience, **E**

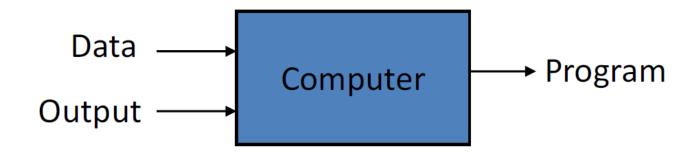
A well-defined learning task is given by {**P**, **T**, **E**}

Traditional Programming vs. Machine Learning

Traditional Programming



Machine Learning



When do we use Machine Learning?

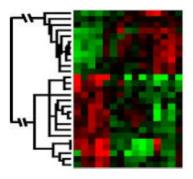
ML is used when:

- Human expertise does not exist (navigating on Mars)
- Humans can't explain their expertise (speech recognition)
- Models must be customized (personalized medicine)
- Models are based on huge amounts of data (genomics)





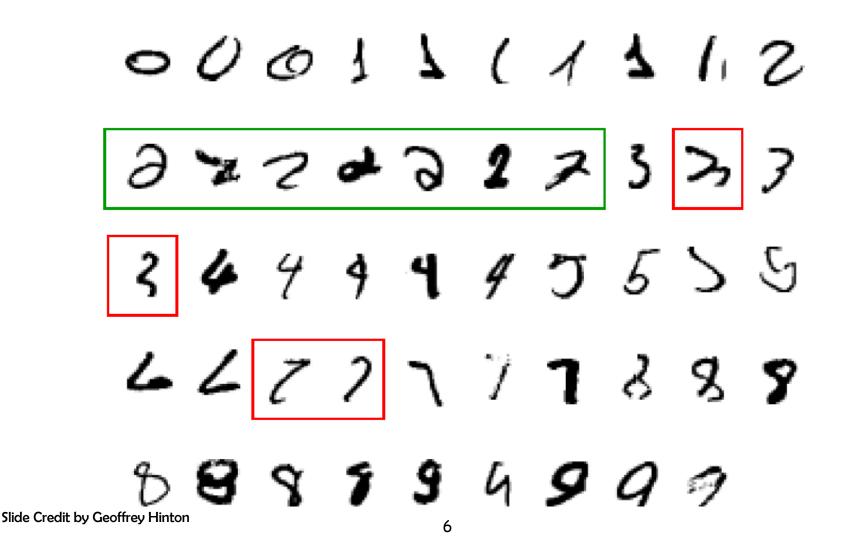




Learning isn't always useful:

There is no need to "learn" to calculate payroll

A classic example of a task that requires machine learning: It is very hard to say what makes a 2



Some more examples of tasks that are best solved by using a learning algorithm

- Recognizing patterns:
 - Facial identities or facial expressions
 - Handwritten or spoken words
 - Medical images
- Generating patterns:
 - Generating images or motion sequences
- Recognizing anomalies:
 - Unusual credit card transactions
 - Unusual patterns of sensor readings in a nuclear power plant
- Prediction:
 - Future stock prices or currency exchange rates

Samuel's Checkers-Player

"Machine Learning: Field of study that gives computers the ability to learn without being explicitly programmed." -Arthur Samuel (1959)



Defining the Learning Task

Improve on task T, with respect to performance metric P, based on experience E

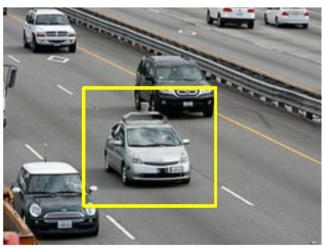
- T: Playing checkers
- P: Percentage of games won against an arbitrary opponent
- E: Playing practice games against itself
- T: Recognizing hand-written words
- P: Percentage of words correctly classified
- E: Database of human-labeled images of handwritten words
- T: Driving on four-lane highways using vision sensors
- P: Average distance traveled before a human-judged error
- E: A sequence of images and steering commands recorded while observing a human driver.
- T: Categorize email messages as spam or legitimate.
- P: Percentage of email messages correctly classified.
- E: Database of emails, some with human-given labels

Autonomous Cars



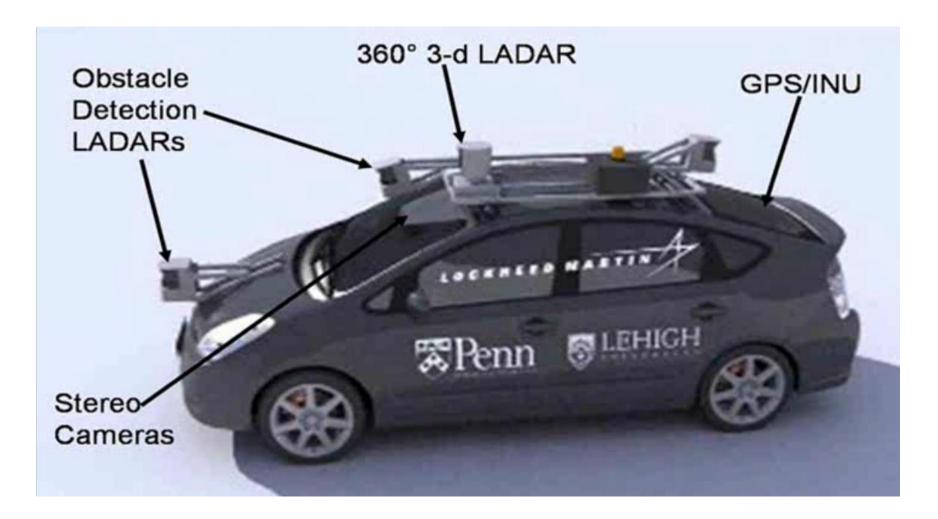
- Nevada made it legal for autonomous cars to drive on roads in June 2011
- As of 2013, four states (Nevada, Florida, California, and Michigan) have legalized autonomous cars

Penn's Autonomous Car → (Ben Franklin Racing Team)





Autonomous Car Sensors



Deep Learning in the Headlines

BUSINESS NEWS



Is Google Cornering the Market on Deep Learning?

A cutting-edge corner of science is being wooed by Silicon Valley, to the dismay of some academics.

By Antonio Regalado on January 29, 2014



How much are a dozen deep-learning researchers worth? Apparently, more than \$400 million.

This week, Google reportedly paid that much to acquire DeepMind Technologies, a startup based in





GEAR SCIENCE ENTERTAINMENT BUSINESS SECURITY DESIGNATION

INNOVATION INSIGHTS



Deep Learning's Role in the Age of Robots

BY JULIAN GREEN, JETPAC 05.02.14 2:56 PM



BloombergBusinessweek Technology

Acquisitions

The Race to Buy the Human Brains Behind Deep Learning Machines

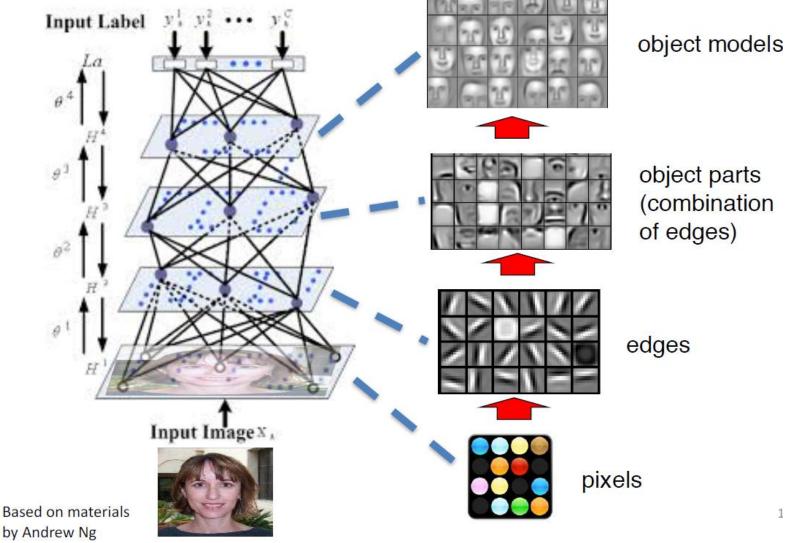
By Ashlee Vance Vanuary 27, 2014

intelligence projects. "DeepMind is bona fide in terms of its research capabilities and depth," says Peter Lee, who heads Microsoft Research.

According to Lee, Microsoft, Facebook (FB), and Google find themselves in a battle for deep learning talent. Microsoft has gone from four full-time deep learning experts to 70 in the past three years. "We would have more if the talent was there to

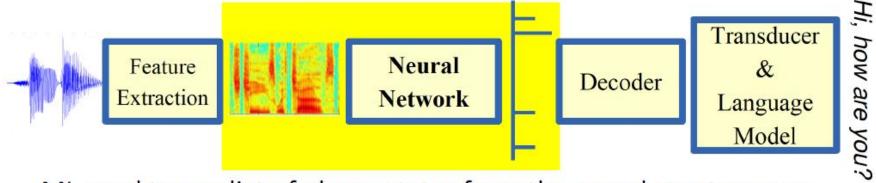


Deep Belief Net on Face Images

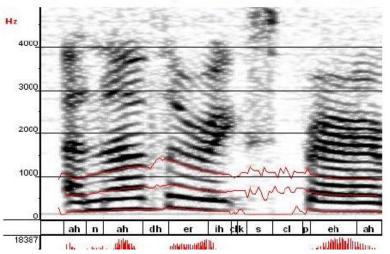


Machine Learning in Automatic Speech Recognition

A Typical Speech Recognition System



ML used to predict of phone states from the sound spectrogram



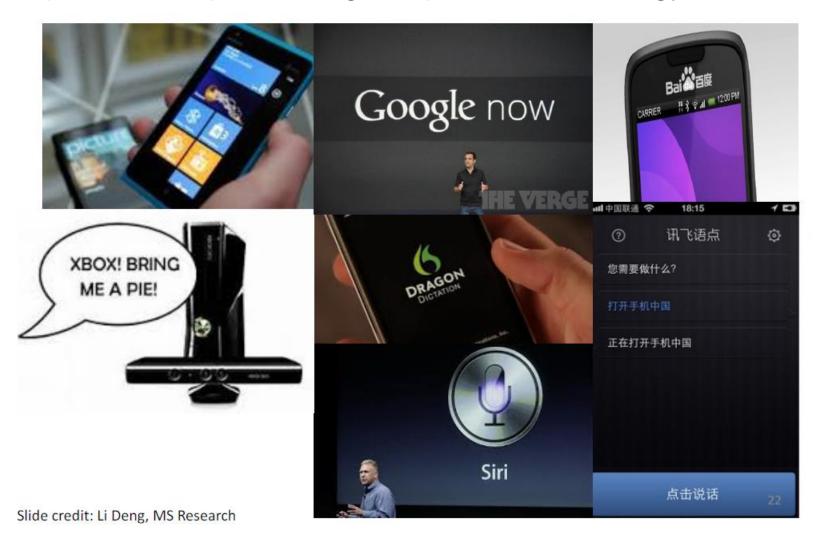
Deep learning has state-of-the-art results

# Hidden Layers	1	2	4	8	10	12
Word Error Rate %	16.0	12.8	11.4	10.9	11.0	11.1

Baseline GMM performance = 15.4%

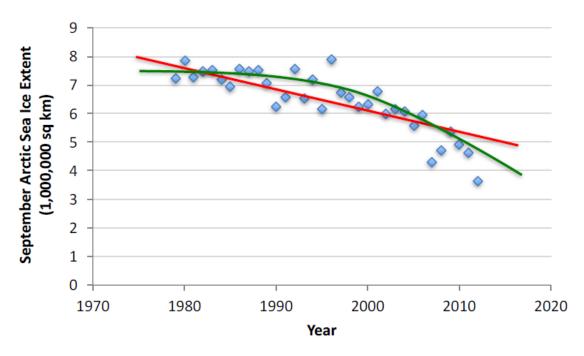
[Zeiler et al. "On rectified linear units for speech recognition" ICASSP 2013]

Impact of Deep Learning in Speech Technology



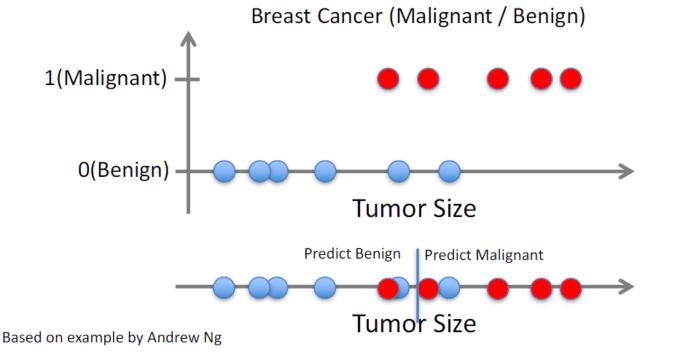
- Supervised (inductive) learning
 - Given: training data + desired outputs (labels)
- Unsupervised learning
 - Given: training data (without desired outputs)
- Semi-supervised learning
 - Given: training data + a few desired outputs
- Reinforcement learning
 - Rewards from sequence of actions

- Supervised Learning: Regression
 - Given (x_1, y_1) , (x_2, y_2) , ..., (x_n, y_n)
 - Learn a function f(x) to predict y given x
 - -y is real-valued == regression

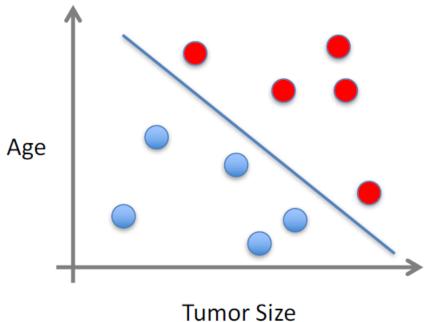


Data from G. Witt. Journal of Statistics Education, Volume 21, Number 1 (2013)

- Supervised Learning: Classification
 - Given (x_1, y_1) , (x_2, y_2) , ..., (x_n, y_n)
 - Learn a function f(x) to predict y given x
 - -y is categorical == classification



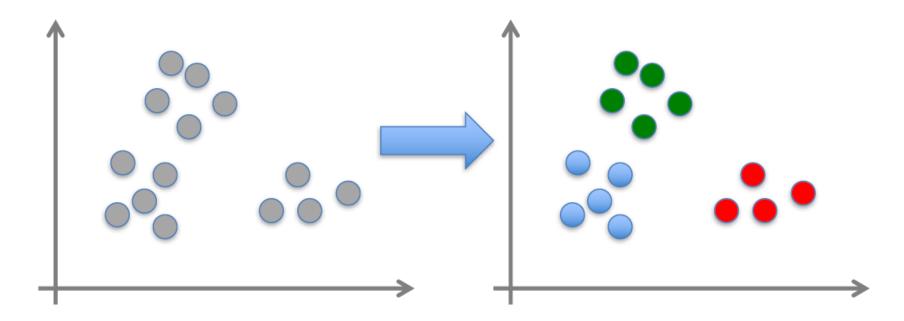
- Supervised Learning:
 - x can be multi-dimensional
 - Each dimension corresponds to an attribute



- Clump Thickness
- Uniformity of Cell Size
- Uniformity of Cell Shape

• •

- Unsupervised Learning
 - Given $x_1, x_2, ..., x_n$ (without labels)
 - Output hidden structure behind the x's
 - E.g., clustering



- Unsupervised Learning
 - Independent component analysis separate a combined signal into its original sources

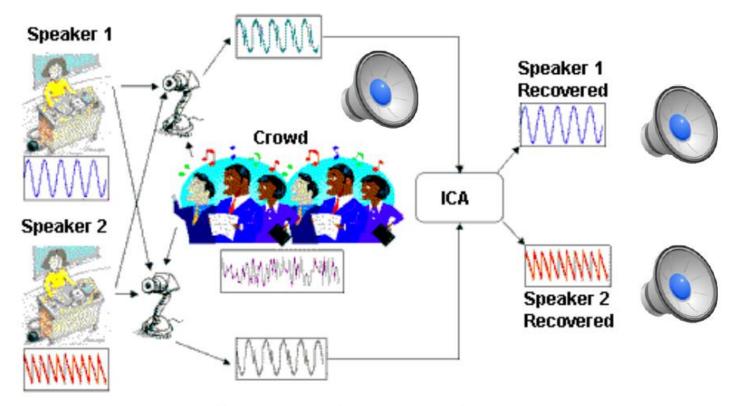
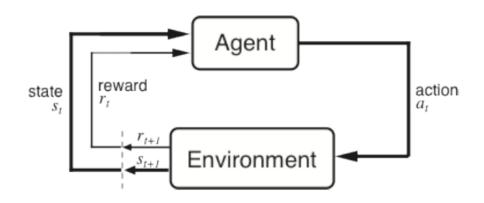


Image credit: statsoft.com Audio from http://www.ism.ac.jp/~shiro/research/blindsep.html

- Reinforcement Learning
 - Given a sequence of states and actions with (delayed) rewards, output a policy
 - Policy is a mapping from states

 actions that tells you what to do in a given state
 - Examples:
 - Credit assignment problem
 - Game playing
 - Robot in a maze
 - Balance a pole on your hand

The Agent-Environment Interface



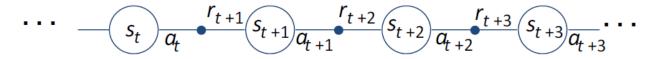
Agent and environment interact at discrete time steps : t = 0, 1, 2, K

Agent observes state at step t: $s_t \in S$

produces action at step t: $a_t \in A(s_t)$

gets resulting reward: $r_{t+1} \in \Re$

and resulting next state: s_{t+1}



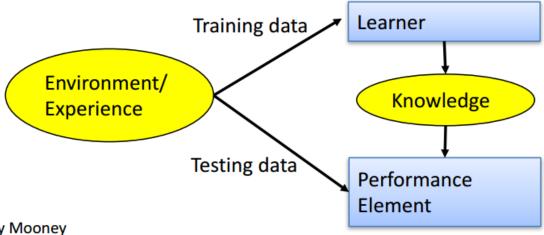
Slide credit: Sutton & Barto

Reinforcement Learning



https://www.youtube.com/watch?v=4cgWya-wjgY

- Designing a Learning System
 - Choose the training experience
 - Choose exactly what is to be learned
 - i.e. the target function
 - Choose how to represent the target function
 - Choose a learning algorithm to infer the target function from the experience



Based on slide by Ray Mooney

- Training vs. Test Distribution
 - We generally assume that the training and test examples are independently drawn from the same overall distribution of data
 - We call this "i.i.d" which stands for "independent and identically distributed"
 - ➤ If test distribution is different, requires *Transfer Learning*
- Tree Components in ML
 - > Representation
 - Optimization
 - Evaluation

Various Function Representations

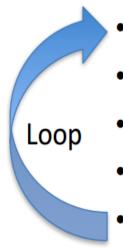
- Numerical functions
 - Linear regression
 - Neural networks
 - Support vector machines
- Symbolic functions
 - Decision trees
 - Rules in propositional logic
 - Rules in first-order predicate logic
- Instance-based functions
 - Nearest-neighbor
 - Case-based
- Probabilistic Graphical Models
 - Naïve Bayes
 - Bayesian networks
 - Hidden-Markov Models (HMMs)
 - Probabilistic Context Free Grammars (PCFGs)
 - Markov networks

- Various Search/Optimization Algorithms
 - Gradient descent
 - Perceptron
 - Backpropagation
 - Dynamic Programming
 - HMM Learning
 - PCFG Learning
 - Divide and Conquer
 - Decision tree induction
 - Rule learning
 - Evolutionary Computation
 - Genetic Algorithms (GAs)
 - Genetic Programming (GP)
 - Neuro-evolution

Evaluation

- Accuracy
- Precision and recall
- Squared error
- Likelihood
- Posterior probability
- Cost / Utility
- Margin
- Entropy
- K-L divergence
- etc.

ML in Practice



- Understand domain, prior knowledge, and goals
- Data integration, selection, cleaning, pre-processing, etc.
- Learn models
- Interpret results
- Consolidate and deploy discovered knowledge

A Brief History of Machine Learning

1950s

- Samuel's checker player
- Selfridge's Pandemonium

1960s:

- Neural networks: Perceptron
- Pattern recognition
- Learning in the limit theory
- Minsky and Papert prove limitations of Perceptron

1970s:

- Symbolic concept induction
- Winston's arch learner
- Expert systems and the knowledge acquisition bottleneck
- Quinlan's ID3
- Michalski's AQ and soybean diagnosis
- Scientific discovery with BACON
- Mathematical discovery with AM

A Brief History of Machine Learning

1980s:

- Advanced decision tree and rule learning
- Explanation-based Learning (EBL)
- Learning and planning and problem solving
- Utility problem
- Analogy
- Cognitive architectures
- Resurgence of neural networks (connectionism, backpropagation)
- Valiant's PAC Learning Theory
- Focus on experimental methodology

1990s

- Data mining
- Adaptive software agents and web applications
- Text learning
- Reinforcement learning (RL)
- Inductive Logic Programming (ILP)
- Ensembles: Bagging, Boosting, and Stacking
- Bayes Net learning

A Brief History of Machine Learning

2000s

- Support vector machines & kernel methods
- Graphical models
- Statistical relational learning
- Transfer learning
- Sequence labeling
- Collective classification and structured outputs
- Computer Systems Applications (Compilers, Debugging, Graphics, Security)
- E-mail management
- Personalized assistants that learn
- Learning in robotics and vision

• 2010s

- Deep learning systems
- Learning for big data
- Bayesian methods
- Multi-task & lifelong learning
- Applications to vision, speech, social networks, learning to read, et
- ????