

Introduction of Perceptron

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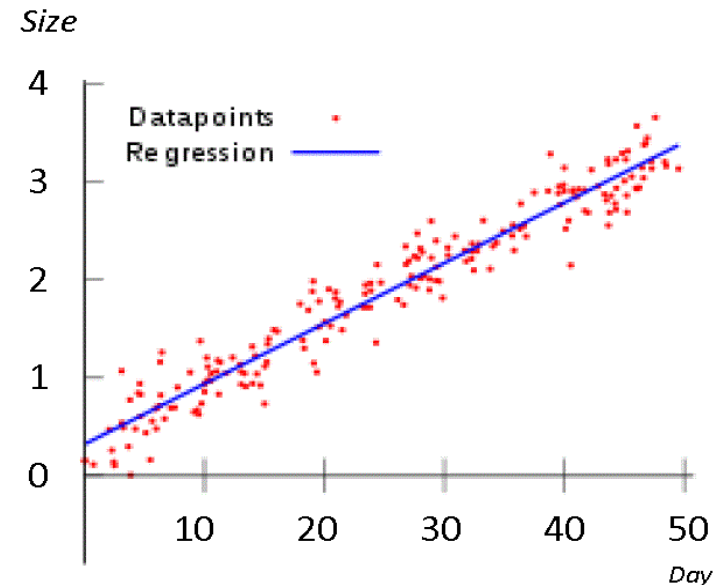
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Basic Concepts of Perceptron

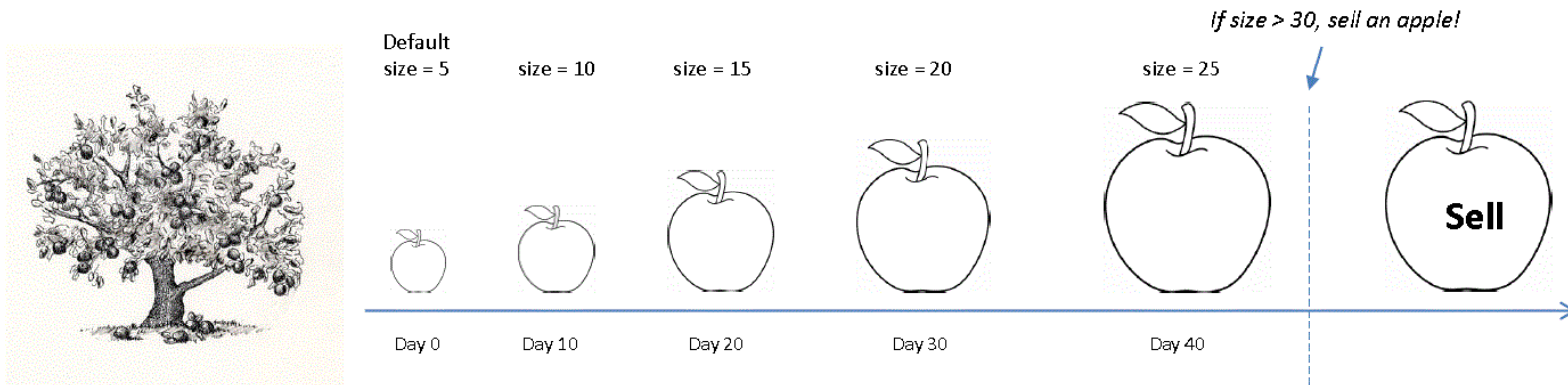
❖ Illustration Example (Apple Tree)



- “어떤 사과나무에 대해서 몇 년에 걸쳐 날짜 별로 사과들의 크기를 측정, 기록”
- 농부는 **특정 크기**가 넘을 때만 시장에 사과를 내다 팔 수 있다고 할 때,
- Q: 올해 Day -50 에 사과를 내다 팔 수 있을까? 없을까?
- The farmer has measured the size of apples produced from an apple tree.
- He can buy his apples when their sizes are larger than a particular size.

Basic Concepts of Perceptron

❖ Illustration Example (Apple Tree)



상황 1 : 작년까지 이 사과나무는 위의 경향대로 사과 열매를 맺었다.
조건 : 사과 크기가 30이 넘으면 팔 수 있다.

Question : 올해 Day-50 에 사과를 팔 수 있을까?

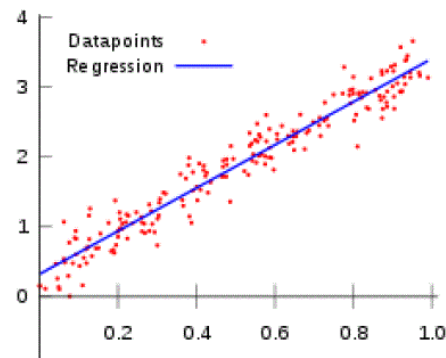


Very Typical **Regression Problem**

Situation 1: Until last year, this apple tree has produced apples according to the above trend.

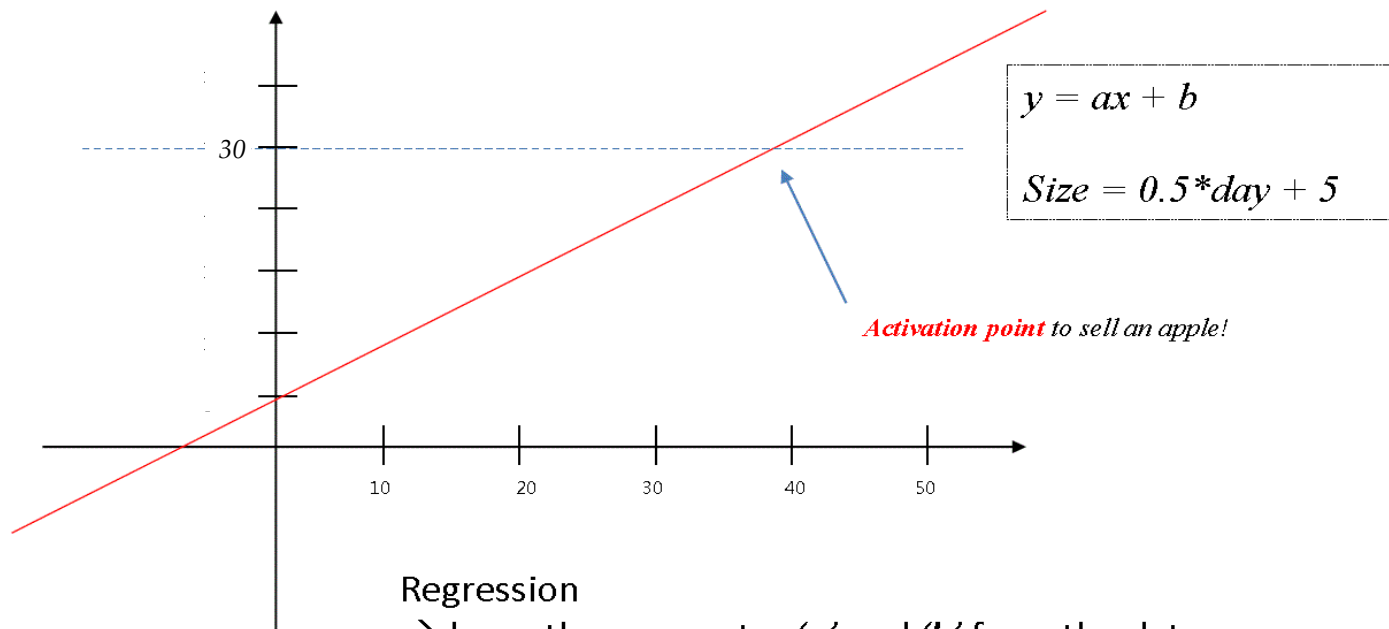
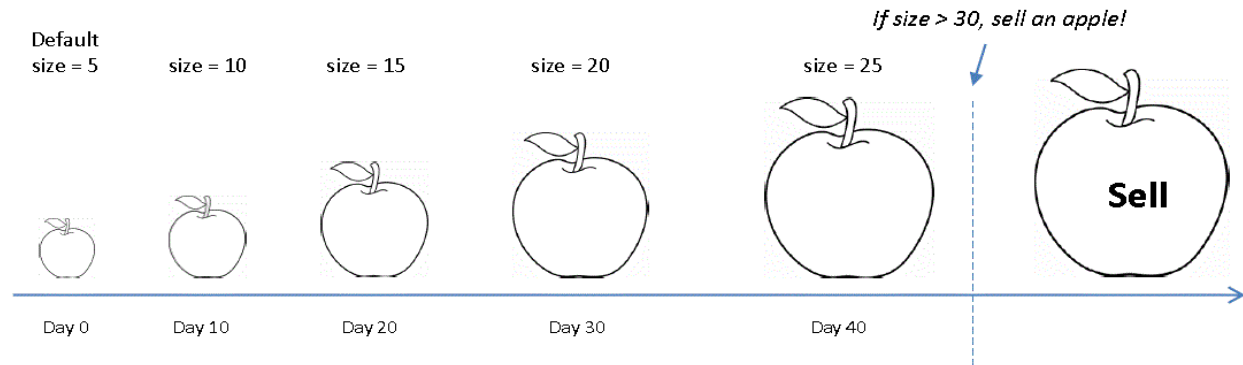
Condition : The farmer can buy them when their sizes are larger than 30.

Question : Can he buy his apples on Day-50.



Basic Concepts of Perceptron

❖ Illustration Example (Apple Tree)

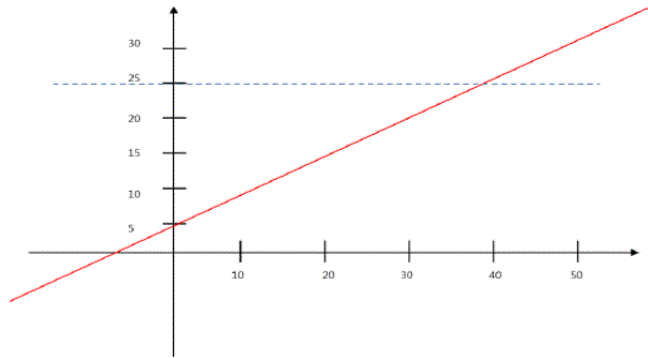


Regression

→ learn the parameter ' a ' and ' b ' from the data

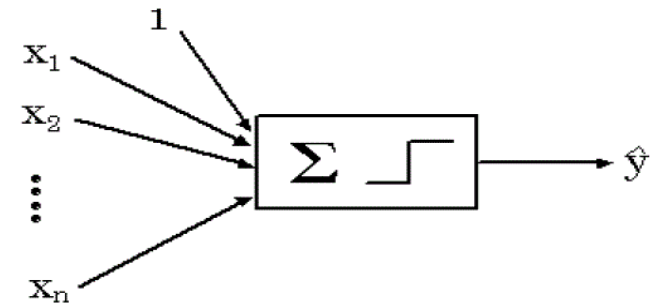
Basic Concepts of Perceptron

❖ Illustration Example (Apple Tree)



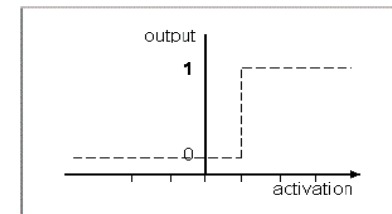
$$y = ax + b$$

If $y > 30 \rightarrow \text{sell an apple}$



$$Y = WX + b$$

Activation function

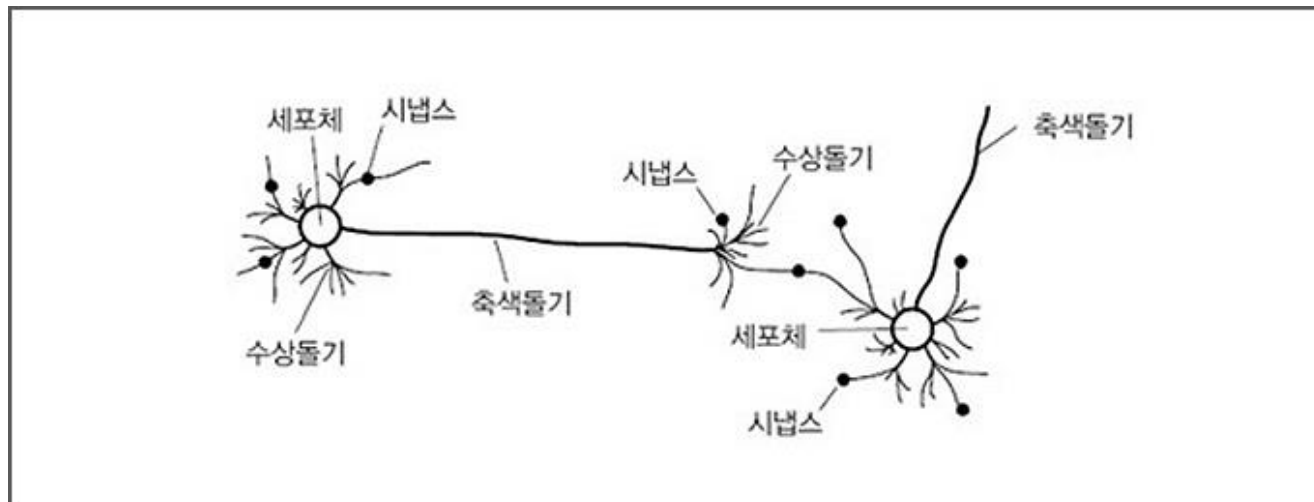


Step Function

Bio-inspired Perceptron

❖ Bio-inspired Learning

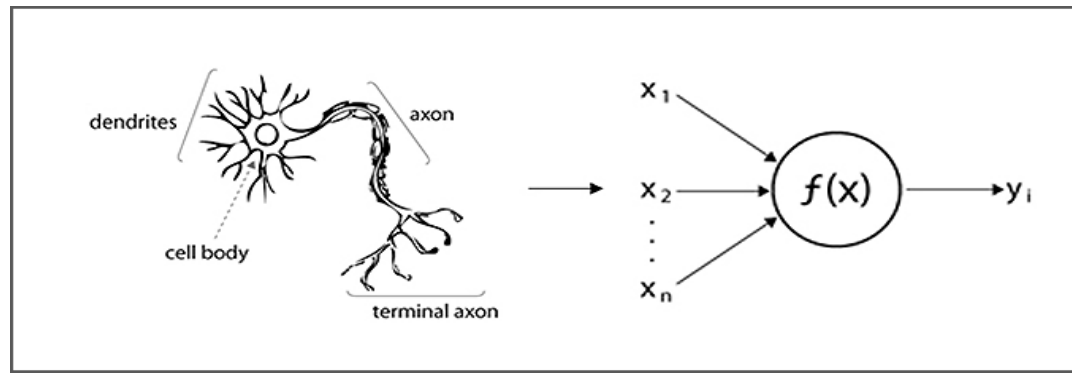
- Our brains are made up of a bunch of little units, called **neurons**, that send electrical signals to one another
 - The **rate** of firing tells up how “activated” a neuron is
 - The incoming neurons are firing at **different rates** (i.e., have **different activations**)
- The Goal is that we are going to think of our learning algorithm as a **single neuron**.



Bio-inspired Perceptron

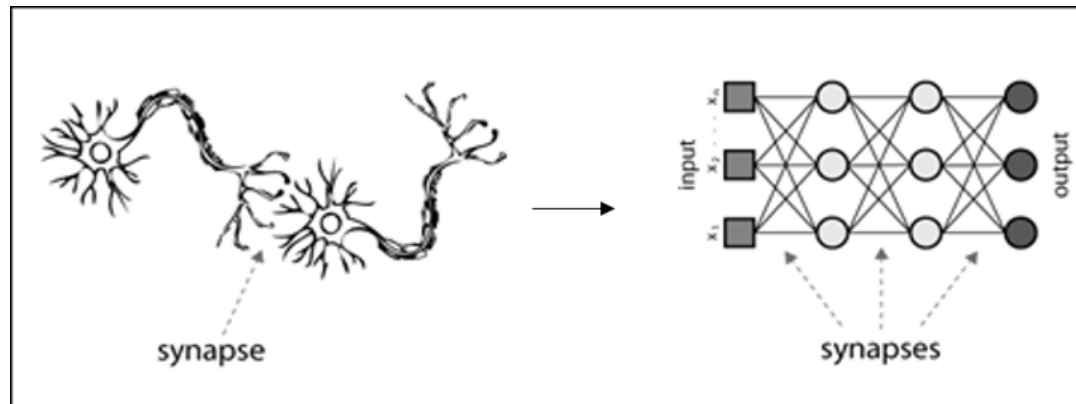
❖ Processing Unit

➤ Neuron vs. Node



❖ Connection

➤ Synapse vs. Weight

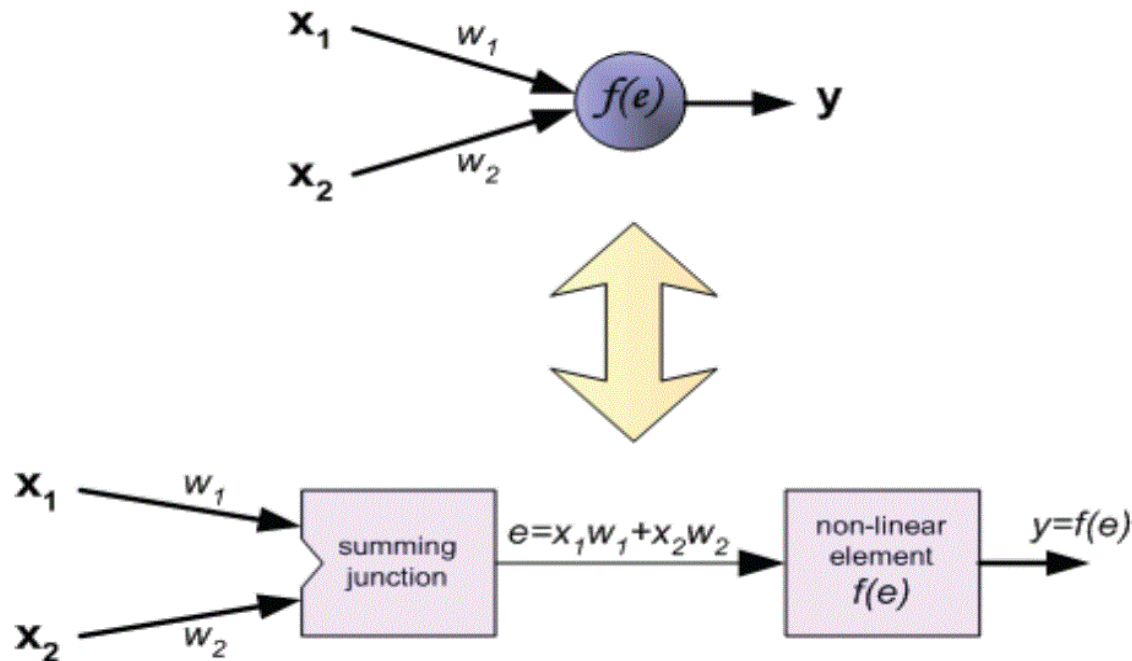


Structure and Computation

❖ Terminology for perceptron

- Layer, Node, Weight, Activation function and Learning

❖ A simple example



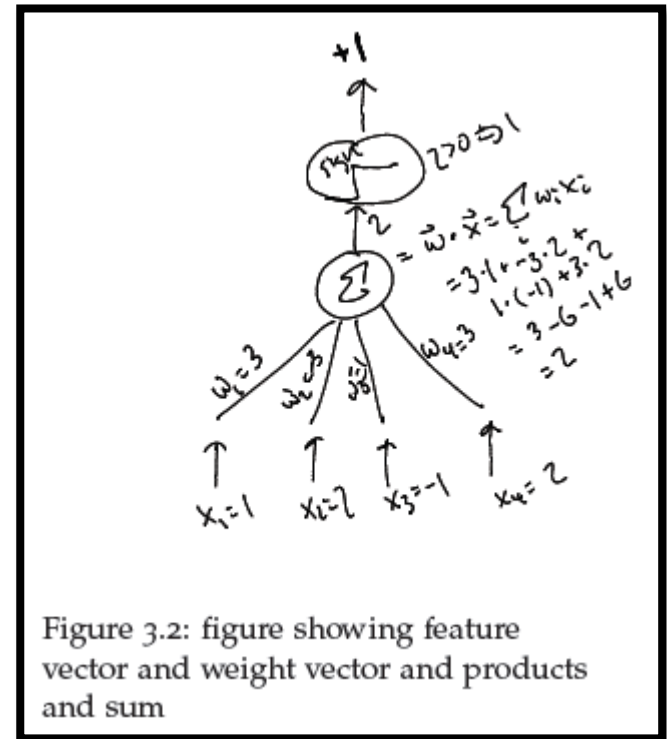
Structure and Computation

❖ The neuron receives input from D -many other neurons

- One for each **input feature**
- The strength of these inputs are the **feature values**

❖ Each incoming connection has a **weight** and the neuron simply **sums up all the weighted inputs**

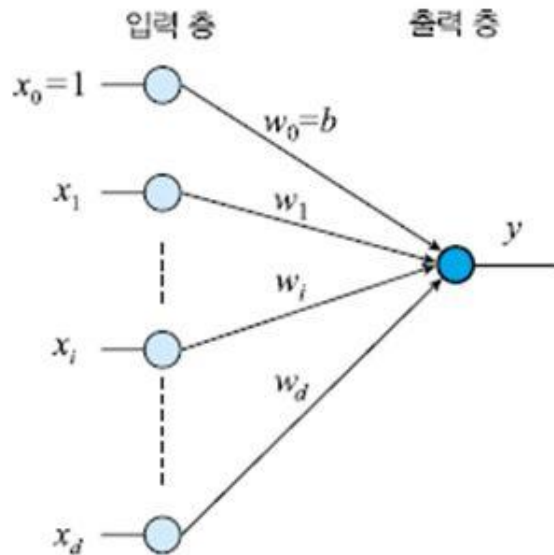
- Based on this sum, it decides whether to “fire” or not
- Firing is interpreted as being a positive example and not Firing is a negative example
 - If the weighted sum is positive, it “fires” and otherwise it doesn’t fire



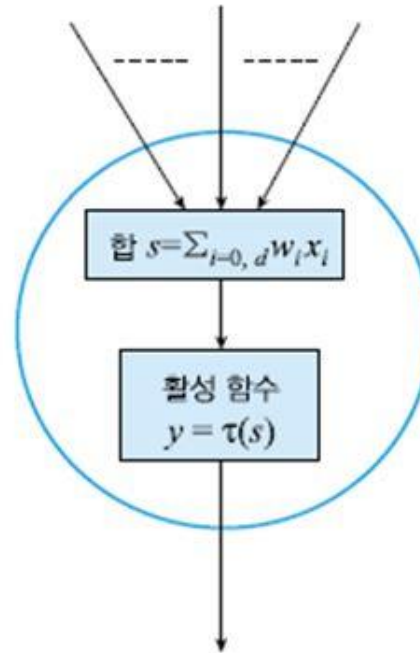
Structure and Computation

❖ Structure of Perceptron

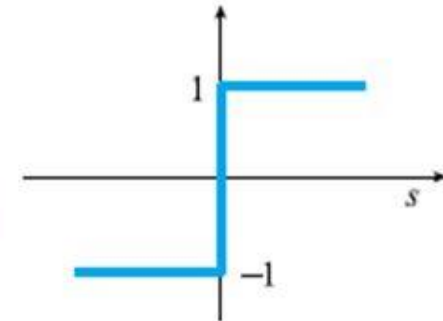
- Input layer: $(d+1)$ nodes (feature vector, $\mathbf{x} = (x_1, \dots, x_d)$)
- Output layer: 1 node (*binary* linear classifier)



(a) 전체 구조



(b) 출력 노드의 연산



(c) 활성화 함수

Structure and Computation

- ❖ The **weights** ($w = (w_0, \dots, w_d)$) of these neurons are fairly easy to interpret
 - Suppose that a feature, for instance “is this a System’s class?” gets a **zero weight**
 - the activation is the same regardless of the value of this feature So features with zero weight are **ignored**
 - Feature with positive weights are indicative of positive examples
 - Because they cause the activation to **increase**
 - Feature with negative weights are indicative of negative examples
 - Because they cause the activation to **decrease**

Structure and Computation

❖ Computation of Perceptron

- Input layer: *Just transfer*
- Output layer: *summation and activation function*

$$\left. \begin{aligned} y = \tau(s) &= \tau\left(\sum_{i=1}^d w_i x_i + b\right) = \tau(\mathbf{w}^T \mathbf{x} + b) \\ \text{or } \tau(s) &= \begin{cases} +1, & s \geq 0 \\ -1, & s < 0 \end{cases} \end{aligned} \right\}$$

- Binary Linear Classifier

$$\left. \begin{aligned} d(\mathbf{x}) = \mathbf{w}^T \mathbf{x} + b > 0 \text{ 이면 } & \mathbf{x} \in \omega_1 \\ d(\mathbf{x}) = \mathbf{w}^T \mathbf{x} + b < 0 \text{ 이면 } & \mathbf{x} \in \omega_2 \end{aligned} \right\}$$

Structure and Computation

❖ Example of Perceptron Computation

➤ *OR classification*

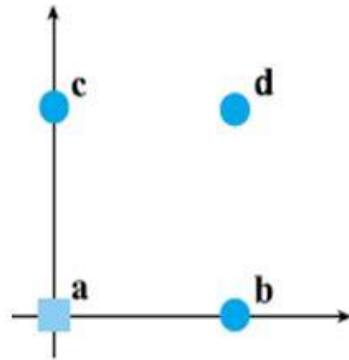
➤ $d(x) = x_1 + x_2 - 0.5$

$$\mathbf{a} = (0,0)^T, t_a = -1$$

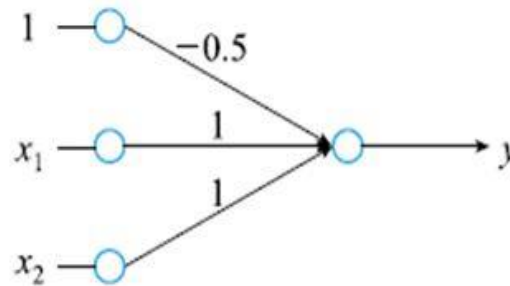
$$\mathbf{b} = (1,0)^T, t_b = 1$$

$$\mathbf{c} = (0,1)^T, t_c = 1$$

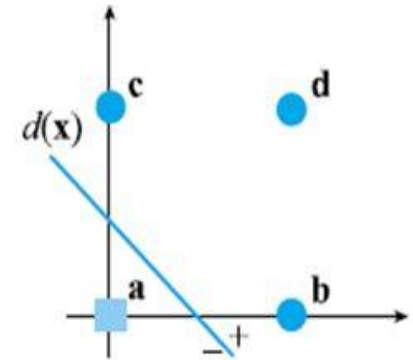
$$\mathbf{d} = (1,1)^T, t_d = 1$$



(a) OR 분류 문제



(b) OR 분류기로서 퍼셉트론



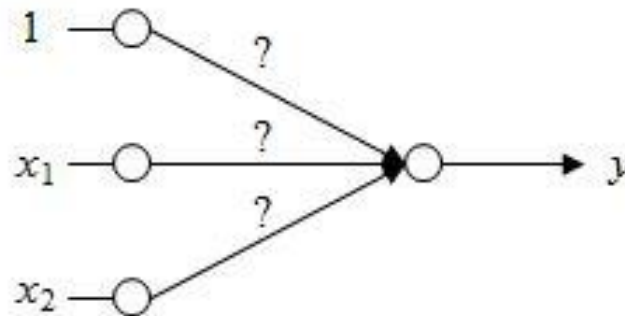
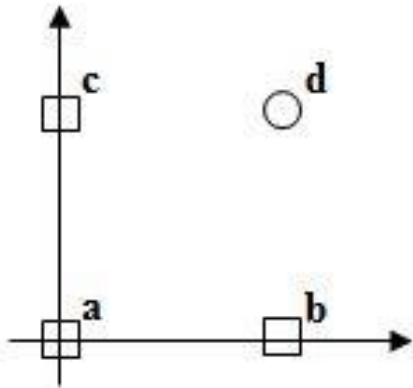
(c) 퍼셉트론은 선형 분류기

Learning of Perceptron

❖ Perceptron Learning

- Training set: $\mathbf{X} = \{ (x_1, t_1), (x_2, t_2), \dots (x_N, t_N) \}$, $t_i = 1$ or -1
- Try to look for $\mathbf{w} = (w_0, \dots, w_d)$ and b
- *Ex) And Problem*

$$\begin{array}{cccc} \mathbf{a}=(0,0)^T & \mathbf{b}=(1,0)^T & \mathbf{c}=(0,1)^T & \mathbf{d}=(1,1)^T \\ t_a=-1 & t_b=-1 & t_c=-1 & t_d=1 \end{array}$$



Learning of Perceptron

❖ General Designing Steps for Learning in Pattern Recognition

- Step 1: Building up Classification Model
 - Step 2: Cost function, $J(\theta)$
 - Step 3: Finding θ to optimize $J(\theta)$
-
- This problem is changed into an Optimization Problem !

Learning of Perceptron

❖ Step 1

- Parameter Set: $\theta = \{w, b\}$

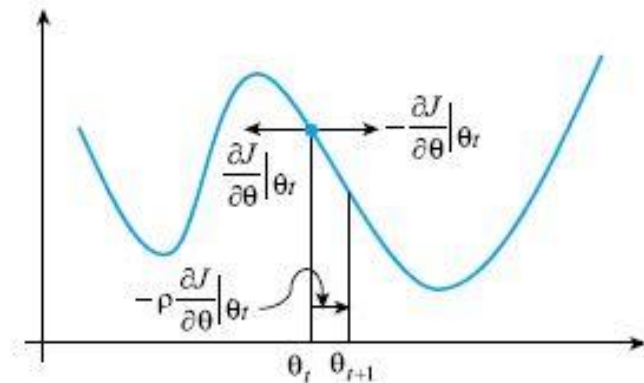
❖ Step 2

- Cost Function: Y is a set of error training examples

$$J(\Theta) = \sum_{\mathbf{x}_k \in Y} (-t_k)(\mathbf{w}^T \mathbf{x}_k + b)$$

❖ Step 3

- *Gradient Descent Method*
- Move $-\frac{\partial J}{\partial \theta}$ direction
- *Learning Rate:*



Learning of Perceptron

❖ Sketch of algorithm

- Setting up Initial Parameters for $\theta = \{w, b\}$

$$\Theta(h+1) = \Theta(h) - \rho(h) \frac{\partial J(\Theta)}{\partial \Theta}$$

$$\left. \begin{aligned} \frac{\partial J(\Theta)}{\partial \mathbf{w}} &= \sum_{\mathbf{x}_k \in Y} (-t_k) \mathbf{x}_k \\ \frac{\partial J(\Theta)}{\partial b} &= \sum_{\mathbf{x}_k \in Y} (-t_k) \end{aligned} \right\}$$

$$\left. \begin{aligned} \mathbf{w}(h+1) &= \mathbf{w}(h) + \rho(h) \sum_{\mathbf{x}_k \in Y} t_k \mathbf{x}_k \\ b(h+1) &= b(h) + \rho(h) \sum_{\mathbf{x}_k \in Y} t_k \end{aligned} \right\}$$

또는

$$\hat{\mathbf{w}}(h+1) = \hat{\mathbf{w}}(h) + \rho(h) \sum_{\mathbf{x}_k \in Y} t_k \hat{\mathbf{x}}_k$$

Learning of Perceptron

❖ Perceptron Learning in Batch Mode

입력: 훈련 집합 $X = \{(x_1, t_1), (x_2, t_2), \dots, (x_N, t_N)\}$, 학습률 ρ

출력: 퍼셉트론 가중치 w , b

알고리즘:

1. w 와 b 를 초기화한다.
2. **repeat** {
3. $Y = \emptyset$;
4. **for** ($i = 1$ to N) {
5. $y = \tau(w^T x_i + b)$; // (4.2)로 분류를 수행함
6. **if** ($y \neq t_i$) $Y = Y \cup x_i$; // 오분류된 샘플 수집
7. }
8. $w = w + \rho \sum_{x_k \in Y} t_k x_k$; // (4.7)로 가중치 갱신
9. $b = b + \rho \sum_{x_k \in Y} t_k$;
10. } **until** ($Y = \emptyset$);
11. w 와 b 를 저장한다.

Learning of Perceptron

❖ Perceptron Learning in Pattern Mode

Algorithm 5 PERCEPTRONTRAIN(\mathbf{D} , $MaxIter$)

```
1:  $w_d \leftarrow 0$ , for all  $d = 1 \dots D$  // initialize weights
2:  $b \leftarrow 0$  // initialize bias
3: for  $iter = 1 \dots MaxIter$  do
4:   for all  $(x, y) \in \mathbf{D}$  do
5:      $a \leftarrow \sum_{d=1}^D w_d x_d + b$  // compute activation for this example
6:     if  $ya \leq 0$  then
7:        $w_d \leftarrow w_d + yx_d$ , for all  $d = 1 \dots D$  // update weights
8:        $b \leftarrow b + y$  // update bias
9:     end if
10:  end for
11: end for
12: return  $w_0, w_1, \dots, w_D, b$ 
```

Algorithm 6 PERCEPTRONTEST($w_0, w_1, \dots, w_D, b, \hat{x}$)

```
1:  $a \leftarrow \sum_{d=1}^D w_d \hat{x}_d + b$  // compute activation for the test example
2: return SIGN( $a$ )
```

Learning of Perceptron

❖ An Example

$$\mathbf{w}(0) = (-0.5, 0.75)^T, b(0) = 0.375$$

$$\textcircled{1} d(\mathbf{x}) = -0.5x_1 + 0.75x_2 + 0.375$$
$$Y = \{\mathbf{a}, \mathbf{b}\}$$

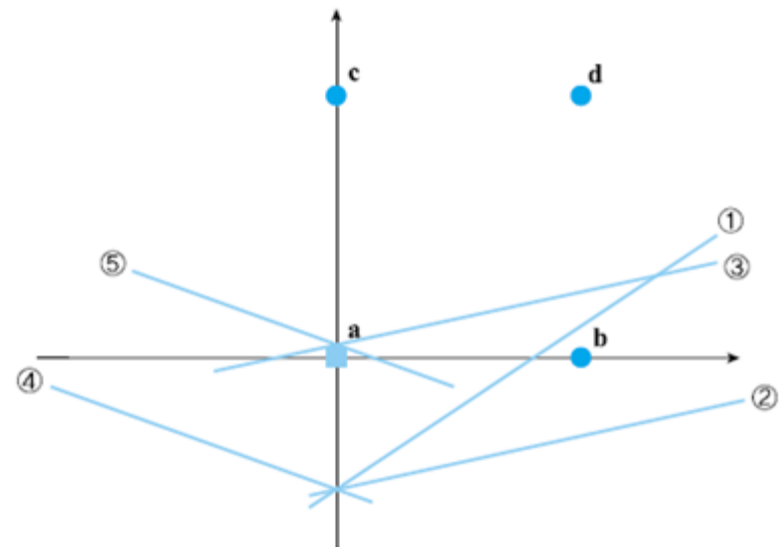
$$\mathbf{w}(1) = \mathbf{w}(0) + 0.4(t_a \cdot \mathbf{a} + t_b \cdot \mathbf{b}) = \begin{pmatrix} -0.5 \\ 0.75 \end{pmatrix} + 0.4 \left[-\begin{pmatrix} 0 \\ 0 \end{pmatrix} + \begin{pmatrix} 1 \\ 0 \end{pmatrix} \right] = \begin{pmatrix} -0.1 \\ 0.75 \end{pmatrix}$$

$$b(1) = b(0) + 0.4(t_a + t_b) = 0.375 + 0.4 * 0 = 0.375$$

$$\textcircled{2} d(\mathbf{x}) = -0.1x_1 + 0.75x_2 + 0.375$$
$$Y = \{\mathbf{a}\}$$

$$\mathbf{w}(2) = \mathbf{w}(1) + 0.4(t_a \mathbf{a}) = \begin{pmatrix} -0.1 \\ 0.75 \end{pmatrix} + 0.4 \left[-\begin{pmatrix} 0 \\ 0 \end{pmatrix} \right] = \begin{pmatrix} -0.1 \\ 0.75 \end{pmatrix}$$

$$b(2) = b(1) + 0.4(t_a) = 0.375 - 0.4 = -0.025$$



Learning of Perceptron

❖ Why this particular update achieves **better job**

- Some current set of parameters \mathbf{w}, \mathbf{b}
- An example (\mathbf{x}_i, t_i) , suppose this is a positive example, so $t_i = 1$
- compute an activation \mathbf{a} , and make an error ($\mathbf{a} < 0$)

$$\begin{aligned} a' &= \sum_{d=1}^D w'_d x_d + b' \\ &= \sum_{d=1}^D (w_d + x_d) x_d + (b + 1) \\ &= \sum_{d=1}^D w_d x_d + b + \sum_{d=1}^D x_d x_d + 1 \\ &= a + \sum_{d=1}^D x_d^2 + 1 > a \end{aligned}$$

Geometric Interpretation

❖ What does the decision boundary of a perceptron look like?

- The sign of the activation, a , changes from -1 to +1
- The set of points \mathbf{x} achieves **zero activation**
 - The points are not clearly positive nor negative

❖ Consider the case where there is no “bias” term

- The decision boundary \mathcal{B} is :

$$\mathcal{B} = \left\{ \mathbf{x} : \sum_d w_d x_d = 0 \right\}$$

- If two vectors have a zero dot product, they are **perpendicular**
- The decision boundary: the plane perpendicular to \mathbf{w}

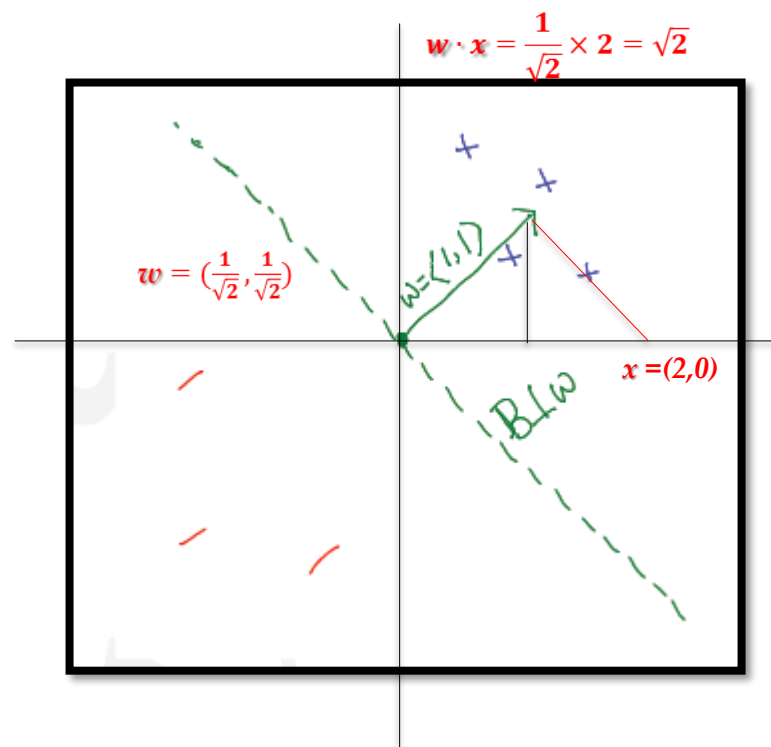
Geometric Interpretation

- ❖ The scale of the weight vector is irrelevant from the perspective of classification

- Work with normalized weight vector w , $\|w\| = 1$

- ❖ The value $w \cdot x$ is just **the distance** of x from the origin when projected onto the vector w

- ❖ This distance along w is exactly the **activation** of that example, with no bias



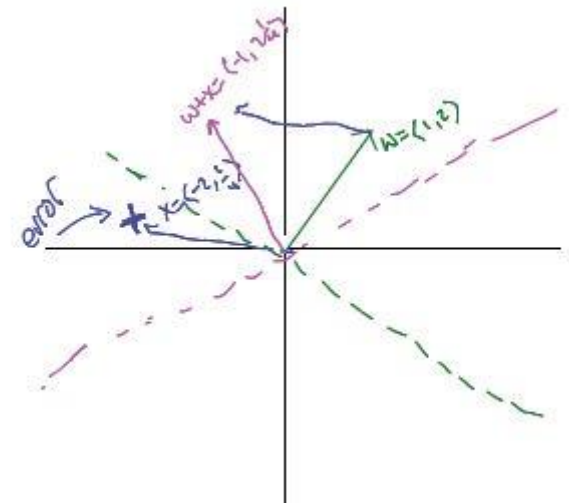
Geometric Interpretation

❖ The role of the bias term

- Previously, the **threshold** would be at zero
- The bias simply moves this threshold
- Bias term **b** is added to get the overall activation
 - The projection plus **b** is then compared against **zero**
- From a geometric perspective, the role of the bias is to **shift** the decision boundary away from the origin, in the direction of **w**
- It is shifted exactly **b** units
 - **b** is positive, the boundary is shifted away from **w**
 - **b** is negative, the boundary is shifted toward **w**
- A positive bias means that more examples should be classified positive
 - By moving the decision boundary in the negative direction, more space yields a positive classification

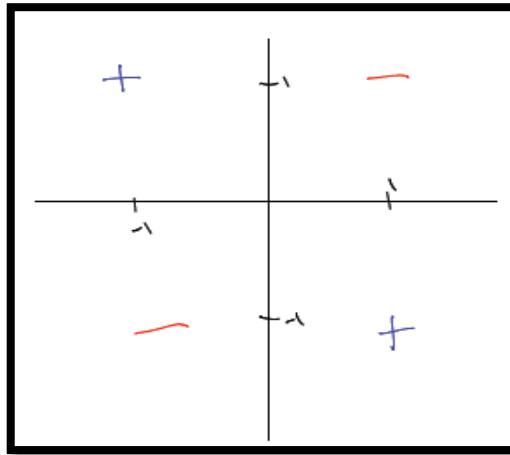
Geometric Interpretation

- ❖ The perceptron update can also be considered geometrically
- ❖ Here, we have a current guess as to the hyperplane, and positive example comes in that is currently mis-classified
- ❖ The weights are updated : $w = w + xt$
 - The weight vector is **changed enough** so this training example is now correctly classified



Limitations of Perceptron

- ❖ The limitation is that its decision boundaries can **only be linear**
 - XOR problem
- ❖ You might ask is: “Do XOR-like problems exist in the real world?”
 - The answer is “**YES**.”



- ❖ An alternative approaches to taking key ideas from the perceptron and generating classifiers with **non linear decision boundaries**
 - **Neural Networks**: combine multi-layer perceptrons in a single framework

Thank you for your attention!

고 영 중