

Camera in OpenGL

Computer Graphics
Instructor: Sungkil Lee

Today

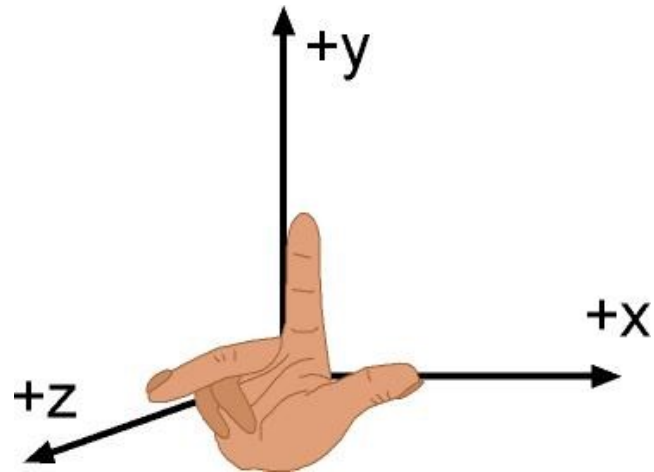
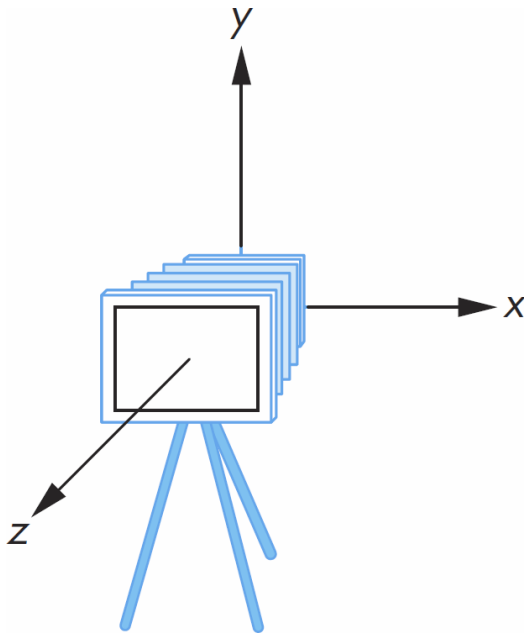
- **Viewing and Projection in OpenGL**
 - How to implement `look_at()` and `perspective()` functions.
 - The full details are covered in the theory lecture.
- **Virtual Trackball**
 - How to implement mouse-based interaction
- **Virtual Trackball Extension**
 - Hints for panning and zooming



Prerequisites Revisited

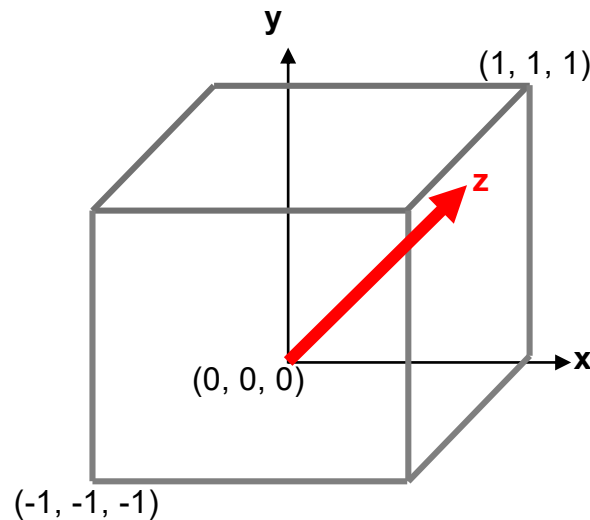
Recall: OpenGL Default Camera

- **Located at origin and directs in the negative z direction.**
 - camera coordinate systems (frames) use RHS convention.
 - Initially the object and camera frames are identical.
 - Default model-view matrix is an identity.



Recall: Canonical View Volume in NDC

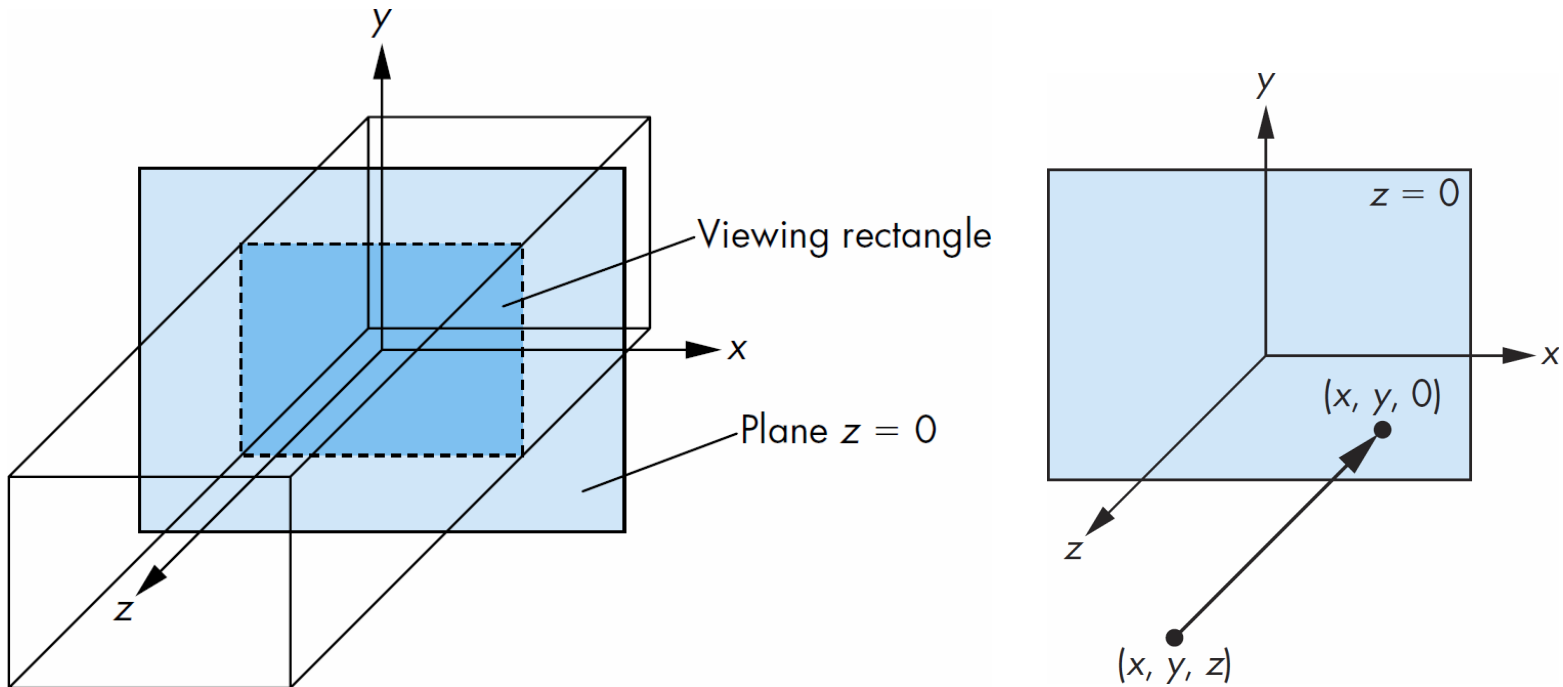
- **Canonical view volume in normalized device coordinates:**
 - Default view volume: cube with sides of length 2 centered at the origin
 - $right = top = far = 1$
 - $left = bottom = near = -1$
 - Default projection matrix is an identity matrix.
 - However, we need to negate z for correct depth test.



OpenGL Default Camera

- **Default projection:**

- *orthographic projection* to $z = 0$ (but, actually we don't set $z=0$)
- Objects outside the default view volume get invisible (clipped out).



Viewing in OpenGL

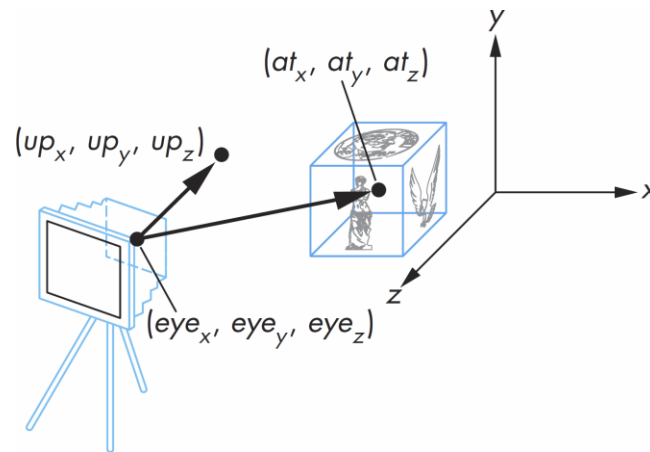
Recall: look_at() Method

- **look_at ()** method

```
mat4 look_at(eye, at, up)
```

- **Viewing specification with (eye, at, up)**

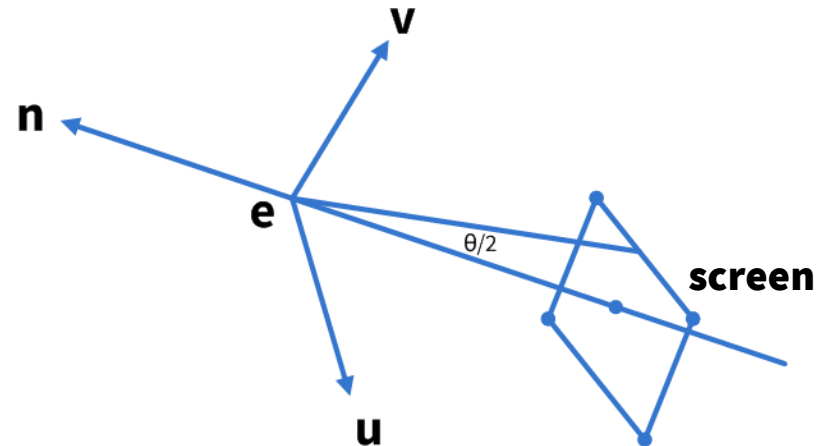
- eye: a camera's location
- at: the center of the destination position to be viewed
- up: upward direction of the camera frame



Recall: look_at() Method

- **eye, at, and up** can define a camera *frame*, which has
 - the origin at eye
 - three basis vectors, \mathbf{n} , \mathbf{u} , and \mathbf{v} , defined as:
- **Thus, the viewing transformation can be a *change of frame*,**
 - which changes from a world frame to a camera frame.
 - We can do the view transformation with **4×4 lookat matrix**.

$$\begin{aligned}\mathbf{n} &= \text{normalize}(\mathbf{eye} - \mathbf{at}) \\ \mathbf{u} &= \text{normalize}(\mathbf{up} \times \mathbf{n}) \\ \mathbf{v} &= \text{normalize}(\mathbf{n} \times \mathbf{u})\end{aligned}$$



look_at() implementation

$$\mathbf{RT}(-eye) = \begin{bmatrix} u1 & u2 & u3 & 0 \\ v1 & v2 & v3 & 0 \\ n1 & n2 & n3 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & -eye.x \\ 0 & 1 & 0 & -eye.y \\ 0 & 0 & 1 & -eye.z \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

```
static mat4 look_at( const vec3& eye, const vec3& at, const vec3& up )
{
    return mat4().set_look_at(eye, at, up);
}

mat4& set_look_at(vec3 eye, vec3 at, vec3 up)
{
    set_identity();
    // define camera frame.
    vec3 n = (eye - at).normalize();
    vec3 u = up.cross(n).normalize();
    vec3 v = n.cross(u).normalize();
    // calculate lookAt matrix: a combined form of RT(-eye)
    _11 = u.x;  _12 = u.y;  _13 = u.z;  _14 = -u.dot(eye);
    _21 = v.x;  _22 = v.y;  _23 = v.z;  _24 = -v.dot(eye);
    _31 = n.x;  _32 = n.y;  _33 = n.z;  _34 = -n.dot(eye);
    return *this;
};
```

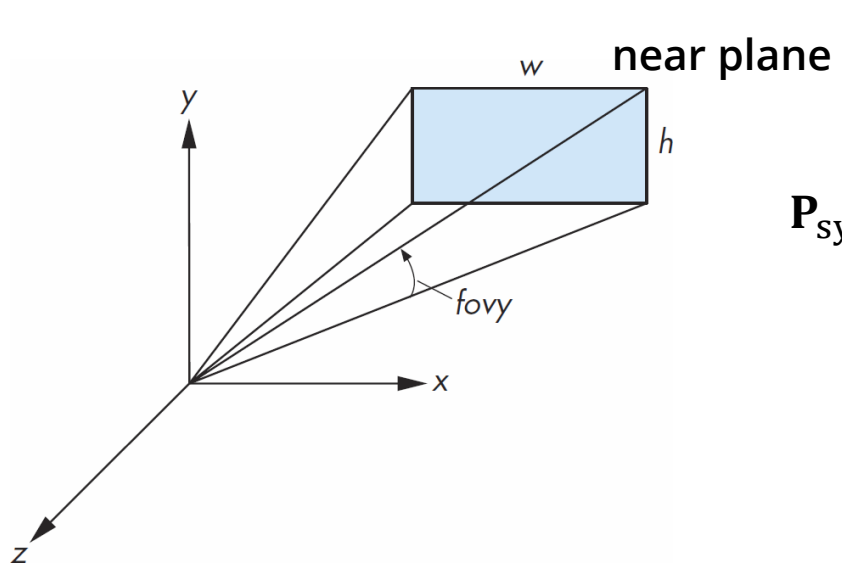
Perspective Projection in OpenGL

Perspective Projection in OpenGL

- We can apply projection using matrix multiplication.

```
mat4 perspective(fovy, aspect_ratio, near, far)
```

- perspective() returns a matrix for **symmetric** perspective projection.
- **fovy** (field of view) and **aspect_ratio** (width/height of sensor/window):



The diagram illustrates the geometry of perspective projection. It shows a 3D coordinate system with x, y, and z axes. A rectangular 'near plane' is positioned at a distance 'n' from the origin along the z-axis. The plane has a width 'w' and height 'h'. Lines of projection originate from the origin and extend through the corners of the near plane. The angle between the z-axis and these projection lines is labeled 'fovy' (field of view). The width 'w' is also labeled as 'r'.

$$\mathbf{P}_{\text{sym}} = \begin{bmatrix} \cot\left(\frac{fovx}{2}\right) & 0 & 0 & 0 \\ 0 & \cot\left(\frac{fovy}{2}\right) & 0 & 0 \\ 0 & 0 & \frac{n+f}{n-f} & \frac{2nf}{n-f} \\ 0 & 0 & -1 & 0 \end{bmatrix}$$
$$t = n * \tan\left(\frac{fovy}{2}\right) \quad r = t * aspect_ratio \quad \cot\left(\frac{fovx}{2}\right) = \cot\left(\frac{fovy}{2}\right) / aspect_ratio$$

perspective()

- **Note:**

- We cannot use reserved 'near' and 'far' for variable names in C++.

```
static mat4 perspective(float fovy, float aspect, float dnear, float dfar)
{
    return mat4().set_perspective(fovy, aspect, dNear, dFar);
}

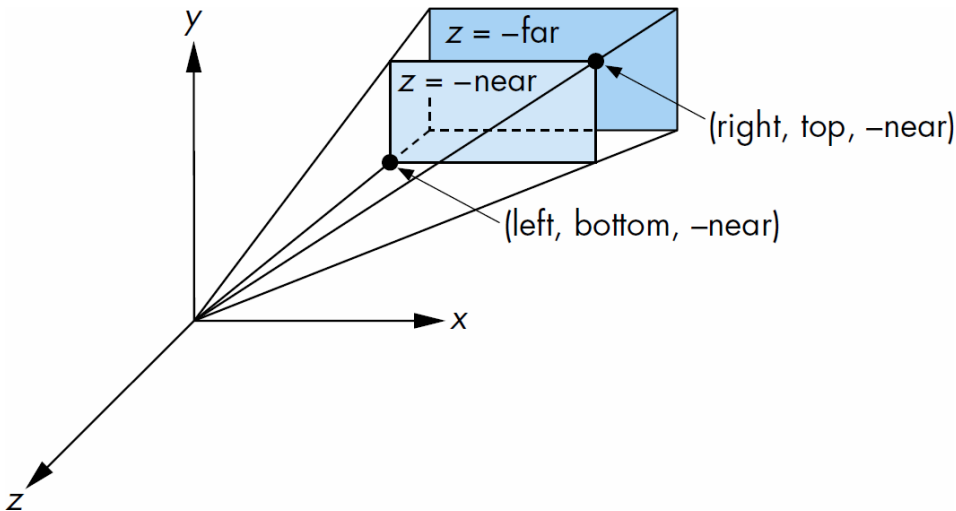
mat4& set_perspective(float fovy, float aspect, float dnear, float dfar)
{
    set_identity();
    _22 = 1 / tan(fovy / 2.0f);
    _11 = _22 / aspect;
    _33 = (dnear + dfar) / (dnear - dfar);
    _34 = (2 * dnear * dfar) / (dnear - dfar);
    _43 = -1;
    _44 = 0;
    return *this;
}
```

frustum() for General Perspective Projection

- The general perspective projection matrix

```
mat4 frustum(left, right, bottom, top, near, far)
```

- Parameters: r (right), l (left), b (bottom), t (top), n (near), f (far)



$$\mathbf{P} = \begin{bmatrix} \frac{2n}{r-l} & 0 & \frac{r+l}{r-l} & 0 \\ 0 & \frac{2n}{t-b} & \frac{t+b}{t-b} & 0 \\ 0 & 0 & \frac{n+f}{n-f} & \frac{2nf}{n-f} \\ 0 & 0 & -1 & 0 \end{bmatrix}$$

Camera in OpenGL: Programming Example

Example of Camera Structure

- **Structure for camera**

```
struct camera
{
    vec3 eye = vec3( 0, 30, 300 ); // position of camera.
    vec3 at = vec3( 0, 0, 0 );      // position where the camera looks at
    vec3 up = vec3( 0, 1, 0 );
    mat4 view_matrix;               // result of look_at function.

    float fovy = PI/4.0f;           // in radian
    float aspect_ratio;              // window_size.x / window_size.y
    float dnear = 1.0f;
    float dfar = 1000.0f;
    mat4 projection_matrix;
};
```


Update()

```
void update()
{
    // update projection matrix
    cam.aspect_ratio = window_size.x/float(window_size.y);
    cam.projection_matrix = mat4::perspective(
        cam.fovy, cam.aspect_ratio, cam.dnear, cam.dfar );
    camera.fovy = PI/6.0f;

    ...

    // update uniform variables in vertex/fragment shaders
    GLint uloc;
    uloc = glGetUniformLocation( program, "view_matrix" );
    if(uloc>-1) glUniformMatrix4fv( uloc,1,GL_TRUE, cam.view_matrix );
    uloc = glGetUniformLocation( program, "projection_matrix" );
    if(uloc>-1) glUniformMatrix4fv( uloc,1,GL_TRUE, cam.projection_matrix
);
}
```

Vertex Shader: trackball.vert

```
// vertex attributes and output
in vec3 position;
in vec3 normal;
in vec2 texcoord;
out vec3 norm;

// matrices
uniform mat4 model_matrix;
uniform mat4 view_matrix;
uniform mat4 projection_matrix;

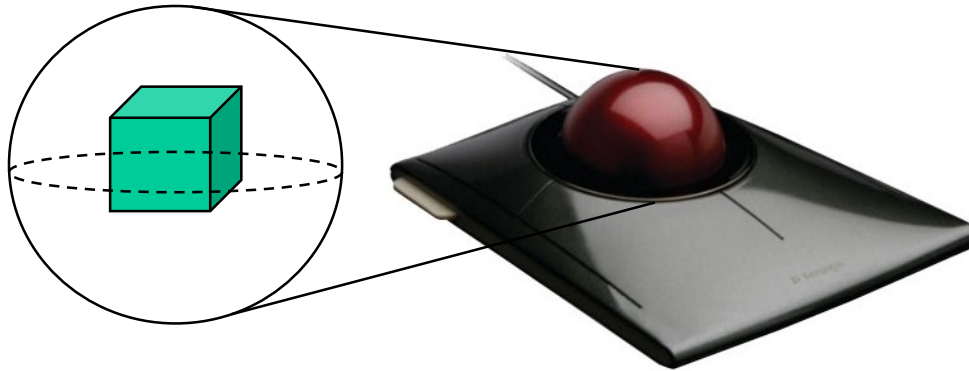
void main()
{
    vec4 wpos = model_matrix * vec4(position,1); // w: world
    vec4 epos = view_matrix * wpos; // e: eye or camera
    gl_Position = projection_matrix * epos;

    // pass eye-space normal to fragment shader
    norm = normalize(mat3(view_matrix*model_matrix)*normal);
}
```

Virtual Trackball

Physical Trackball

- **Trackball is an “upside down” mouse.**
 - Imagine the objects are rotated along with an imaginary sphere.



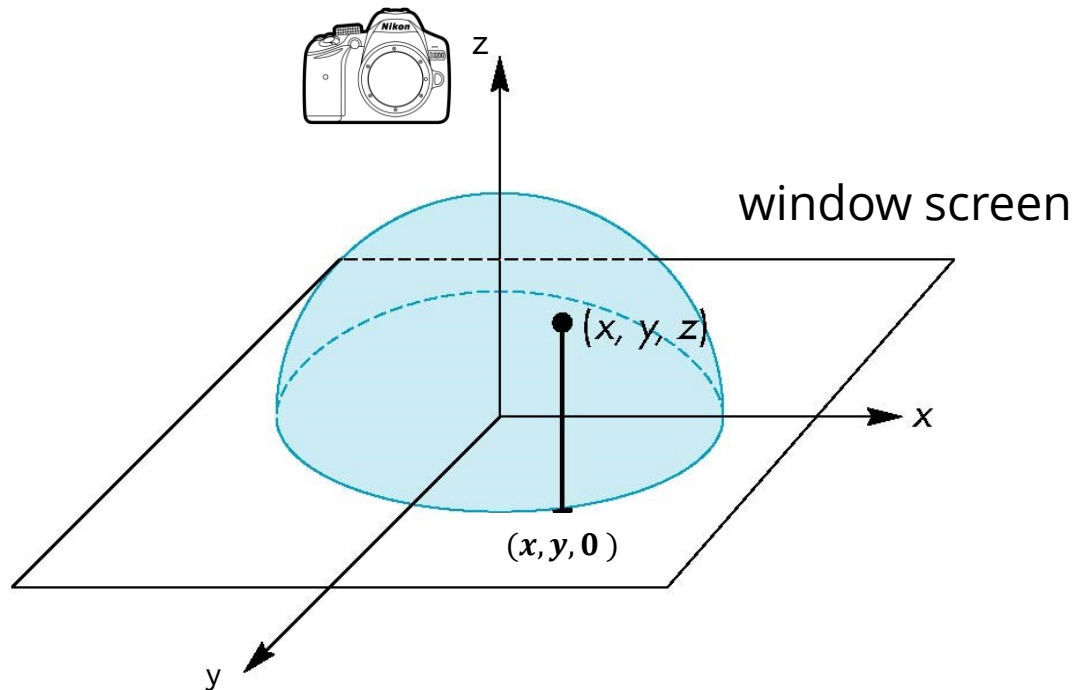
- Allow a user to define 3D rotation using touch (mouse clicks) in window.
 - When the input occurs, the camera location is changed.

Virtual Trackball

- **A 2D point (x, y) on the window corresponds to:**
 - the 3D point (x, y, z) on the upper hemisphere where

$$r^2 = x^2 + y^2 + z^2$$

$$z = \sqrt{r^2 - x^2 - y^2}, \text{ if } r \geq |x|, |y| \geq 0$$



Virtual Trackball Source Code

- **Class for virtual trackball**

- Here's an interface for trackball class.

```
struct trackball
{
    bool    b_tracking = false;
    float   scale;        // controls how much rotation is applied
    mat4    view_matrix0; // initial view matrix
    vec2    m0;           // the last mouse position

    trackball( float rot_scale=1.0f ):scale(rot_scale){}
    bool is_tracking() const { return b_tracking; }

    void begin( const mat4& view_matrix, vec2 m );
    void end();
    void update( vec2 m );
}
```

Callback: mouse()

- **mouse():**

- When the button is pressed, call begin(). Otherwise call end().
- Retrieve a mouse position, and pass to tb.begin() with view matrix.

```
void mouse( GLFWwindow* window, int button, int action, int mods )
{
    if(button==GLFW_MOUSE_BUTTON_LEFT)
    {
        dvec2 pos; glfwGetCursorPos(window,&pos.x,&pos.y);
        vec2 npos = cursor_to_ndc( pos, window_size );

        if(action==GLFW_PRESS) tb.begin( cam.view_matrix, npos );
        else if(action==GLFW_RELEASE) tb.end();
    }
}
```

cursor_to_ndc()

- **cursor_to_ndc():**

- Converts a position in window coordinates to normalized coordinates.
- Here, we first normalize to $[0,1]^2$

```
vec2 cursor_to_ndc( dvec2 cursor, ivec2 window_size )
{
    // normalize window pos to [0,1]^2
    vec2 npos = vec2( float(cursor.x)/float(window_size.x-1),
                     float(cursor.y)/float(window_size.y-1) );
    ...
}
```


cursor_to_ndc()

- **cursor_to_ndc():**

- **Vertical flipping** is applied while normalizing to $[-1,1]^2$
 - Window/GLFW systems define y from top to bottom, while our virtual trackball (and OpenGL) defines y from bottom to top

```
vec2 cursor_to_ndc( dvec2 cursor, ivec2 window_size )
{
    ...

    // normalize window pos to [-1,1]^2 with vertical flipping
    // vertical flipping: window coordinate system defines y from
    // top to bottom, while the trackball from bottom to top
    return vec2(npos.x*2.0f-1.0f, 1.0f-npos.y*2.0f);
}
```

Virtual Trackball Source Code

- **Methods for trackball class**

- At begin(), we mark we are tracking the mouse movements.
- Also, we record the initial mouse position and view matrix.

```
void begin( const mat4& view_matrix, vec2 m )
{
    b_tracking = true;           // enable trackball tracking
    m0 = m;                      // save current mouse position
    view_matrix0 = view_matrix;  // save current view matrix
}
```

- At end(), we just disable tracking, and do not need to touch others.

```
void end(){ b_tracking = false; }
```

Callback: `motion()`

- **`motion()`:**

- if not tracking, return
- otherwise, calls `update()` when tracking

```
void motion( GLFWwindow* window, double x, double y )
{
    if(!tb.is_tracking()) return;
    vec2 npos = cursor_to_ndc( dvec2(x,y), window_size );
    cam.view_matrix = tb.update( npos );
}
```

Virtual Trackball Source Code

- **update():**

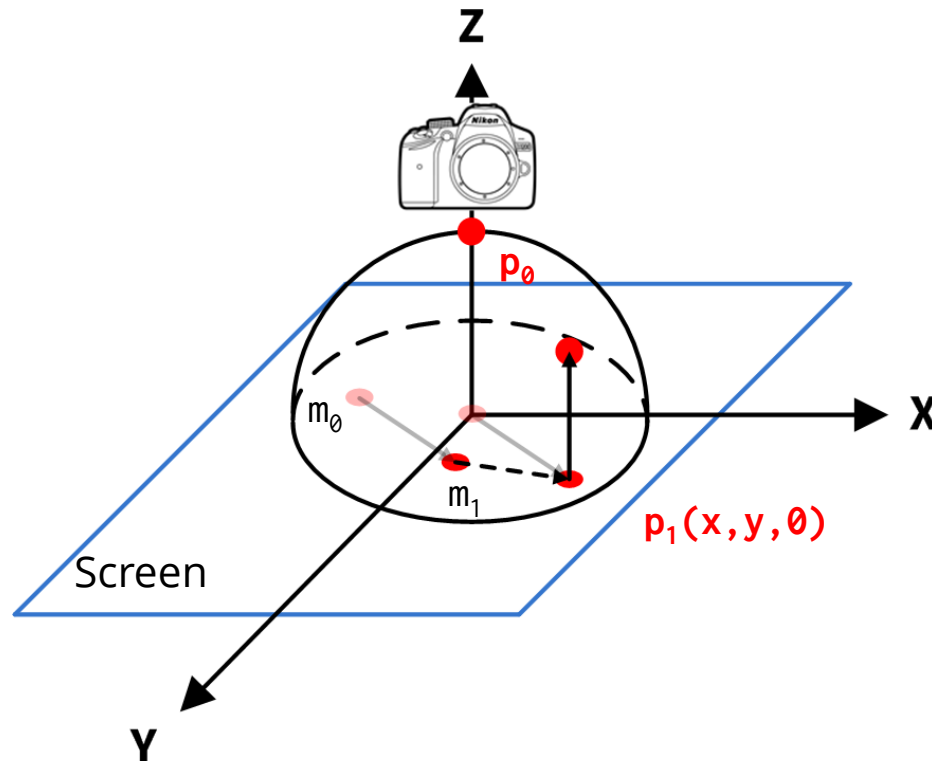
```
mat4 update( vec2 m )
{
    // project a 2D mouse position to a unit sphere
    vec3 p0 = vec3(0,0,1.0f); // reference position on sphere
    vec3 p1 = vec3(m-m0,0);    // displacement
```

- We then define the reference point **p0** on the virtual sphere.
- Then, define **p1** as a displacement of mouse position.

Virtual Trackball Source Code

- **update():**
 - Visualization of p_0 and p_1 on the unit sphere

```
vec3 p0 = vec3(0,0,1.0f); // reference position on sphere  
vec3 p1 = vec3(m-m0,0);   // displacement
```



Virtual Trackball Source Code

- **update():**

- Then, we detect a subtle/trivial movement, and ignore it.

```
// ignore subtle movement
if( !b_tracking || length(p1)<0.001f ) return view_matrix0;
...
```

- Then, apply rotational scale

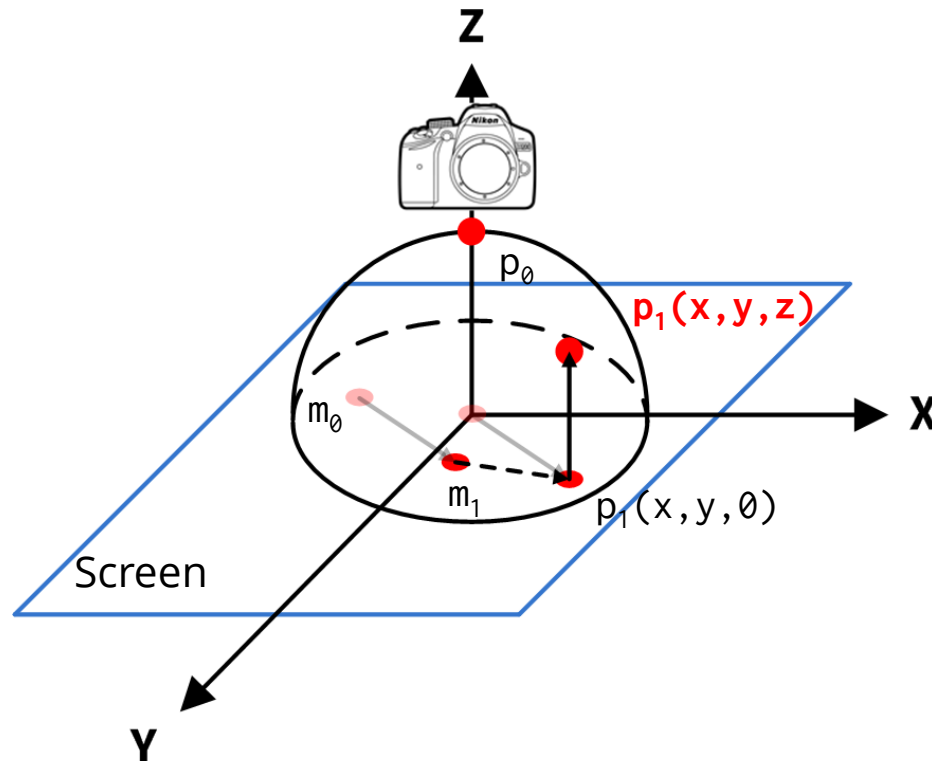
```
// apply rotation scale
p1 *= scale;
```

Virtual Trackball Source Code

- **update():**

- Then, back-project $z=0$ to the unit sphere.

```
// back-project z=0 onto the unit sphere:  $z^2 = 1 - (x^2 + y^2)$   
p1.z = sqrtf(max(0,1.0f-length2(p1)));  
p1 = p1.normalize();
```

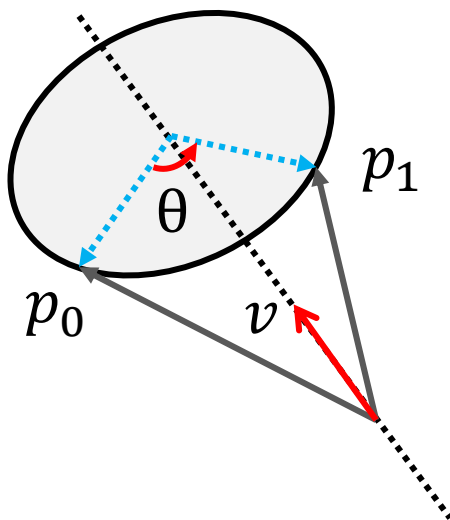


Virtual Trackball Source Code

- **update():**
 - Find the rotation axis and angle

```
// find rotation axis and angle in world space
// - trackball self-rotation should be done at first in the world space
// - mat3(view_matrix0): rotation-only view matrix
// - mat3(view_matrix0).transpose(): inverse view-to-world matrix
```

```
vec3 v = mat3(view_matrix0).transpose()*p0.cross(p1);
float theta = asin( min(v.length(),1.0f) );
```



Virtual Trackball Source Code

- **update():**
 - Return the rotation with the initial view transformation

```
mat4 update( float x, float y )
{
    ...

    // resulting view matrix, which first applies
    // trackball rotation in the world space
    return view_matrix0 * mat4::rotate(v.normalize(),theta);
}
```

Virtual Trackball Extension

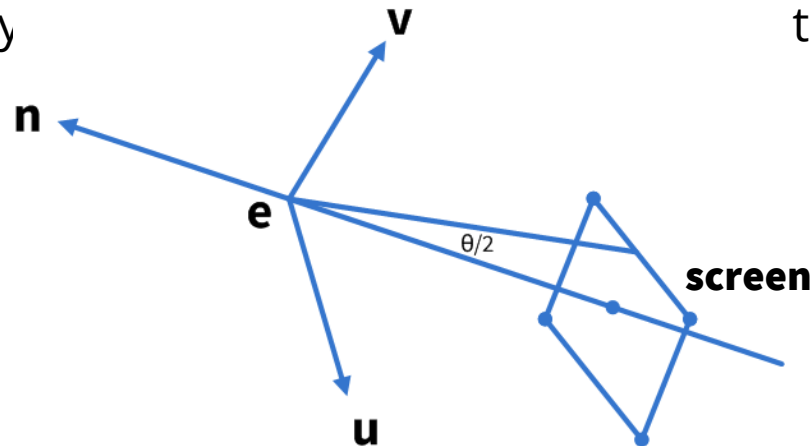
Extending Virtual Trackball: Hints!

- **How to implement panning**

- The mouse displacement is mapped to **translation along uv plane**.
- Then, move eye and at using the displacement, and rebuild your view matrix using `look_at()`.
- It is good to scale the amount of eye's panning based on distance to the scene center (or at).

- **How to implement zooming**

- The mouse displacement is mapped to **translation along n axis**.
- Displace only ey the view matrix.



Extending Virtual Trackball: Hints!

- **Changes in your mouse and motion():**

```
void mouse( GLFWwindow* window, int button, int action, int mods ){
{
    ...
    tb.button = button;
    tb.mods = mods;
}

void motion( GLFWwindow* window, double x, double y )
{
    ...
    if(button==GLFW_MOUSE_BUTTON_LEFT&&mods==0)
        tb.update(npos);
    else if(button==GLFW_MOUSE_BUTTON_MIDDLE ||
            (button==GLFW_MOUSE_BUTTON_LEFT&&(mods&GLFW_MOD_CONTROL)))
        tb.update_pan(npos);
    else if(button==GLFW_MOUSE_BUTTON_RIGHT ||
            (button==GLFW_MOUSE_BUTTON_LEFT&&(mods&GLFW_MOD_SHIFT)))
        tb.update_zoom(npos);
}
```