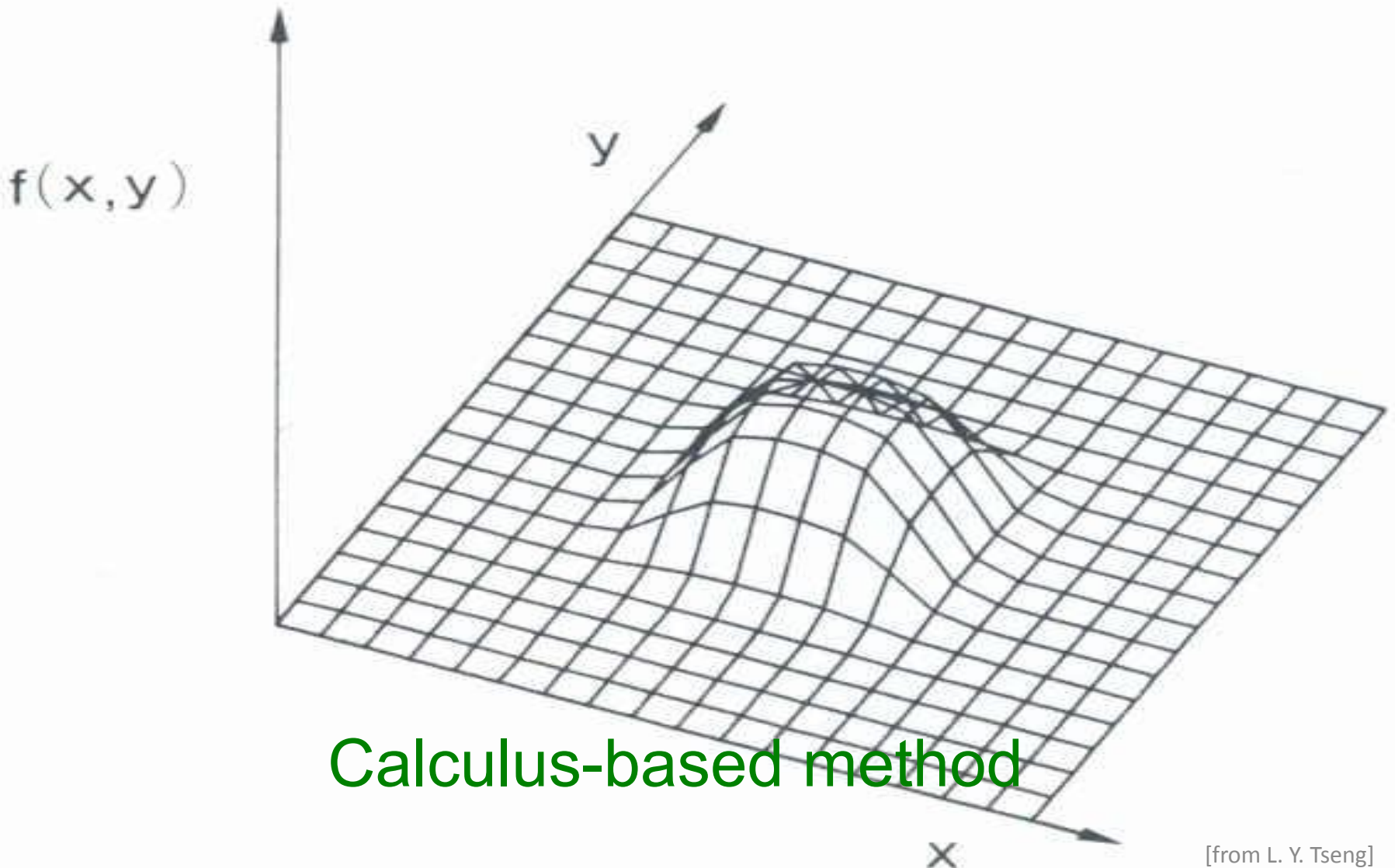


Session 8

Local Search and Metaheuristics

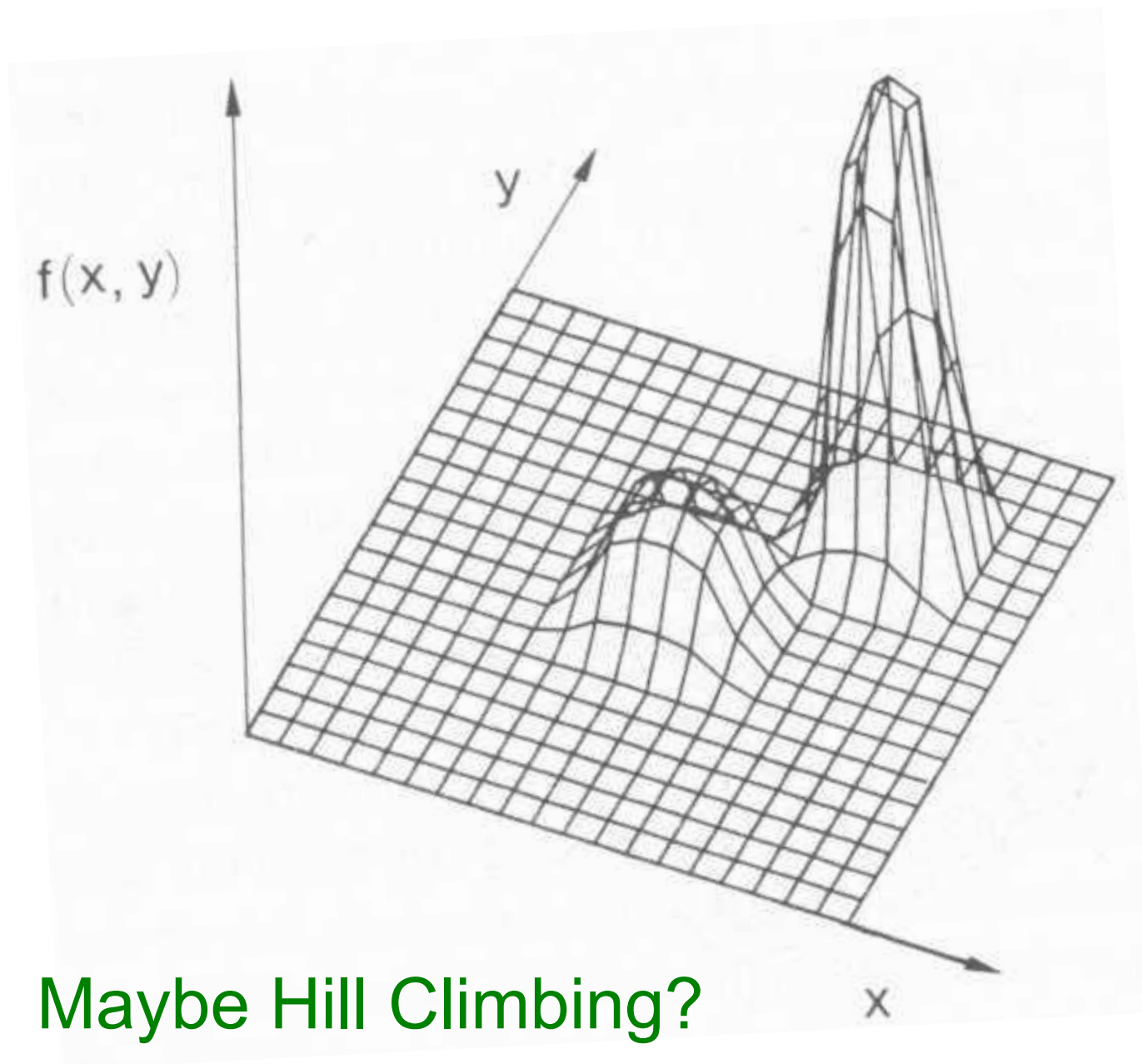
Daniel Diaz
Philippe Codognet
Salvador Abreu

Optimization problems



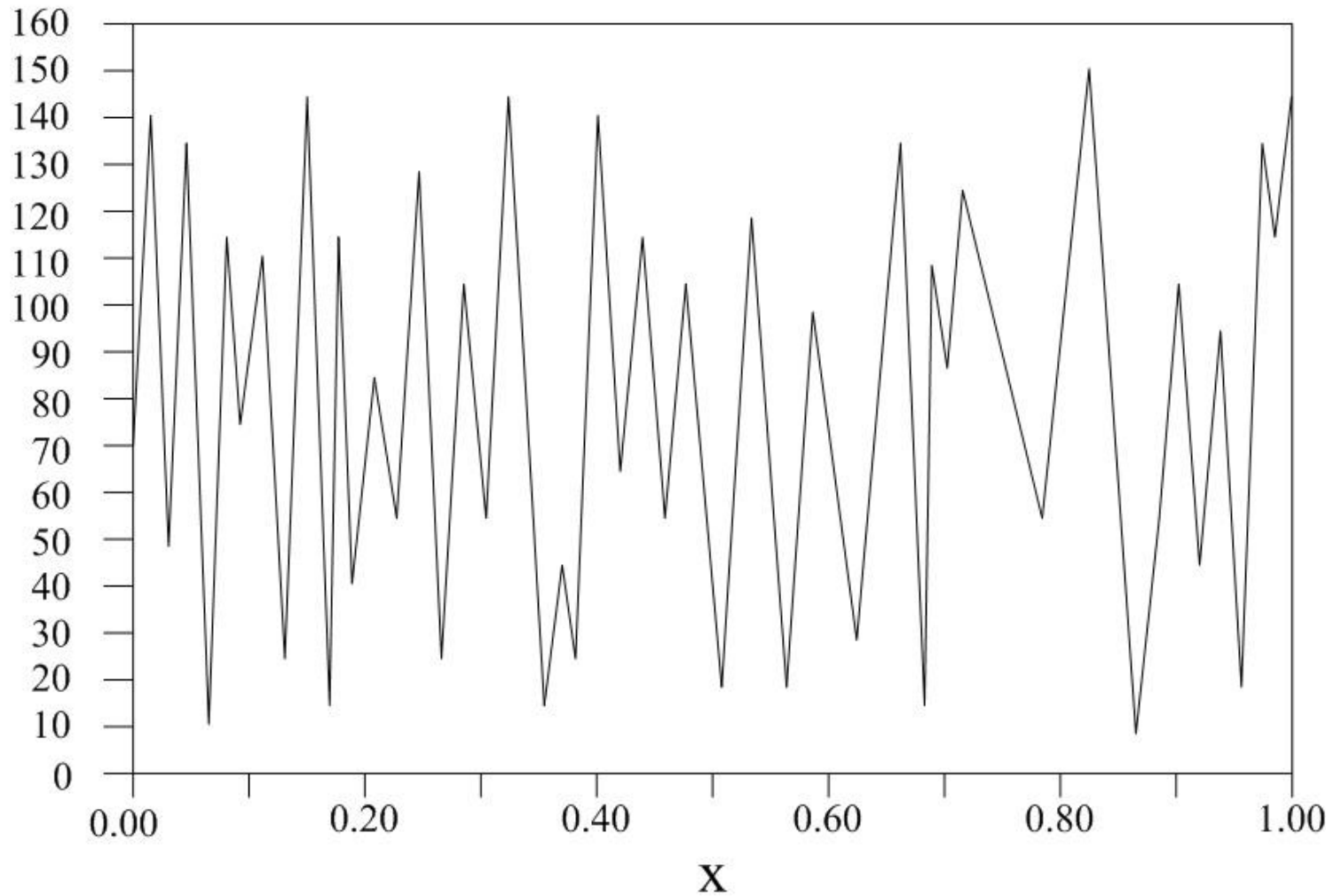
Calculus-based method

[from L. Y. Tseng]



Maybe Hill Climbing?

How about this?



[from L. Y. Tseng]

COP: Motivation for Heuristic Methods

- NP-complete problems (most of the time, but not all)
- Optimization at least as hard as decision
- NP-complete decision problem \rightarrow NP-hard optimization problem
- For NP-hard COP there is probably no exact method where computing time is limited by a polynomial (in the instance size)
- Different choices
 - Exact methods (enumerative)
 - Approximation method (polynomial time)
 - Heuristic method (no a priori guarantees)
- In the real world:
 - Often requirements on response time
 - Optimization only one aspect
 - Problem size and response time requirements often rules out exact solution methods

Heuristics & Metaheuristics

- From ancient greek *εὕρισκω* : « I find »
- current meaning: “a technique to guide the search toward the solution”
- Basic idea: should exploit problem knowledge
- The term *heuristic* was introduced in the book “How to solve it” [Polya 1957] (A guide for solving math problems)
- *meta* is from ancient greek *μετά* : above, beyond
 - e.g. metaphysics ...
- Meta-heuristics are higher-level strategies to guide the search
- In particular to avoid getting trapped in local optima

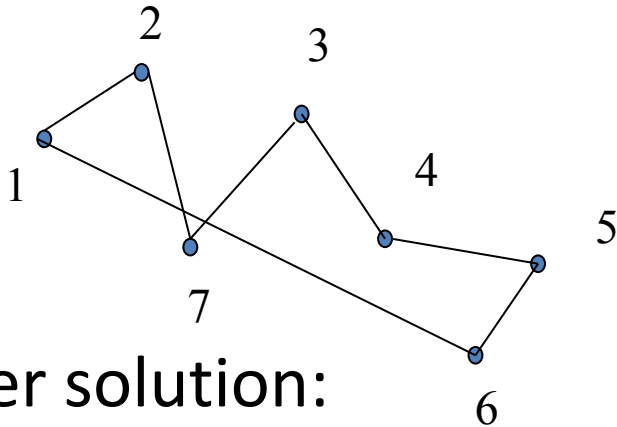
How to Guide the Search ?

1. Find a solution
 - Random configuration
 - Greedy solution
 - ...
2. Check “how good” this solution is
e.g. use the value of the objective function
3. Try to find a better solution
i.e. try to identify best direction to go to
4. continue

Given a Solution, How to Find a Better One?

- Modification of a given solution gives a “neighbor solution”
- A certain set of **operations** on a solution yields a set of neighbor solutions, called a **neighborhood**
- Evaluations of neighbors
 - Objective function value
 - Feasibility ?

Example of TSP



Earlier solution:

1 2 7 3 4 5 6 1 (184)

Trivial solution:

1 2 3 4 5 6 7 1 (288)

Greedy construction:

1 3 5 7 6 4 2 1 (160)

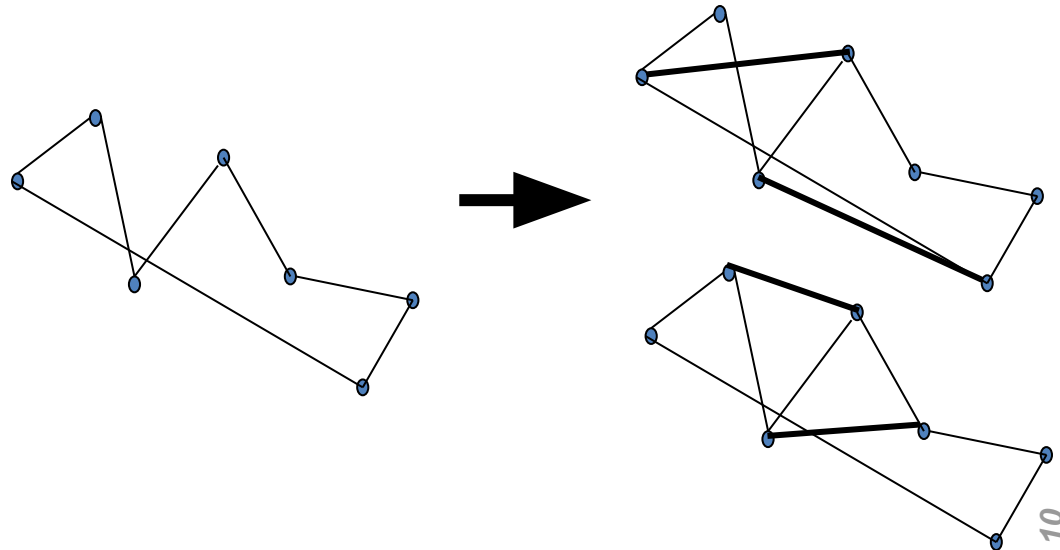
	1	2	3	4	5	6	7
1	0	18	17	23	23	23	23
2	2	0	88	23	8	17	32
3	17	33	0	23	7	43	23
4	33	73	4	0	9	23	19
5	9	65	6	65	0	54	23
6	25	99	2	15	23	0	13
7	83	40	23	43	77	23	0

... Better solutions ?

Example of TSP (2)

- Operator: 2-opt

- choose 2 edges
 $\{a1,b1\}$ & $\{a2,b2\}$
- replace by
 $\{a1,a2\}$ & $\{b1,b2\}$



- Operator: 1-opt

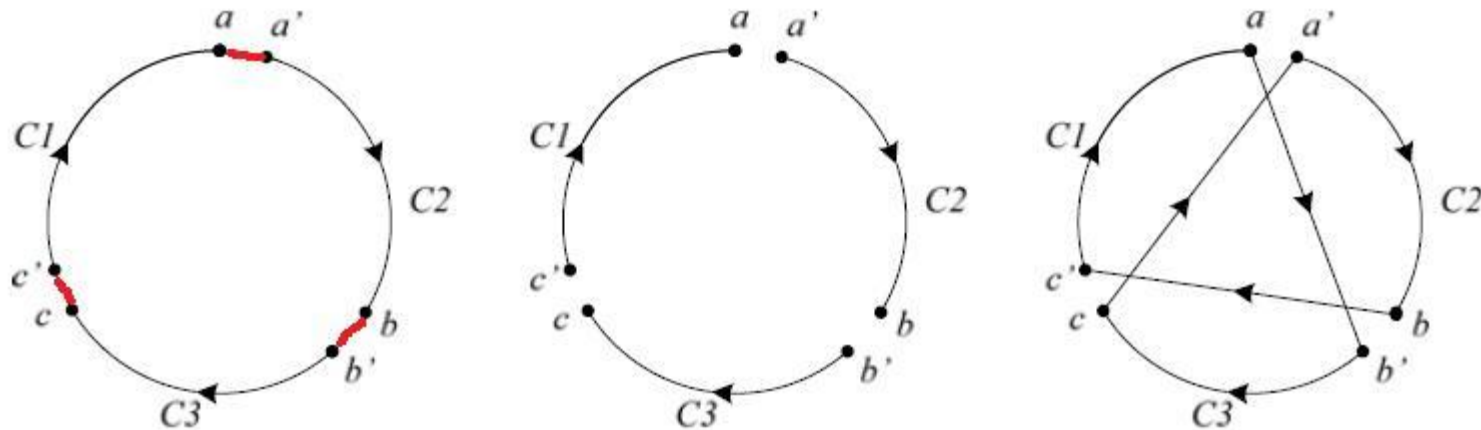
- swap 2 cities in the tour

$(c_1, c_2, \dots, c_i, \dots, c_j, \dots, c_n)$

becomes $(c_1, c_2, \dots, c_j, \dots, c_i, \dots, c_n)$

Example of TSP (3)

- Operator: 3-opt



- size of neighborhood ?
 - $O(n^k)$ for k-opt
 - Can become quite big for large problem instances

Example of Knapsack Problem

- Knapsack with capacity 101
- 10 items: 1,...,10
- Trivial solution: empty backpack, value 0
- Greedy solution, assign the items after value:
 - (0000010000), value 85
 - Better solutions?

	1	2	3	4	5	6	7	8	9	10
Value	79	32	47	18	26	85	33	40	45	59
Size	85	26	48	21	22	95	43	45	55	52

Example of Knapsack Problem (2)

- Greedy 0000010000 value 85
- Another solution 0010100000 value 73
- Natural operator: "Flip" a bit
 - If the item is in the knapsack, take it out
 - If the item is not in the knapsack, include it
- Some Neighbors of 0010100000 :
 - 0110100000 value 105
 - 1010100000 value 152, not feasible
 - 0010000000 value 47

	1	2	3	4	5	6	7	8	9	10
Value	79	32	47	18	26	85	33	40	45	59
Size	85	26	48	21	22	95	43	45	55	52
	0	0	1	0	1	0	0	0	0	0

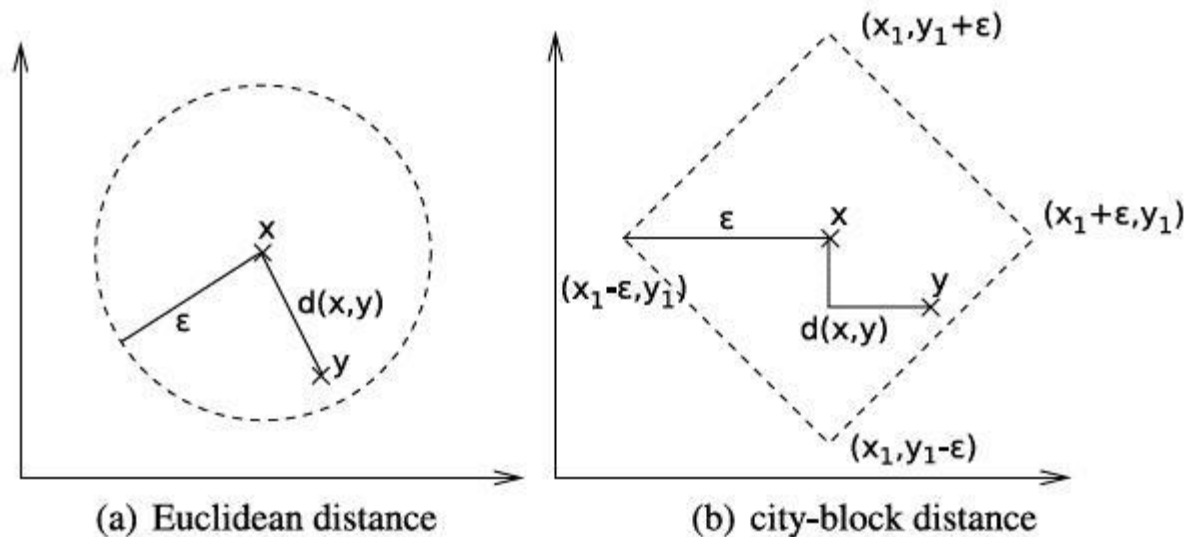
[From A. Løkketangen]

Definition: Neighborhood

- Let (S, f) be a COP-instance
- A *neighborhood function* is a mapping from solutions to the set of possible solutions (i.e., reached by a move) $N : S \rightarrow 2^S$
- For a given solution $s \in S$, N defines a *neighborhood* of solutions: $N(s) \subseteq S$ i.e., solutions in some sense "near" s
- $t \in N(s)$ is a *neighbor* of s

Neighborhood

- A neighborhood somehow define a notion of proximity, thus *distance* between solutions
- It can be any type of distance, not only Euclidian
- e.g. Manhattan distance or Hamming distance



[From F. Rothlauf]

Neighborhood Operators

- Neighborhoods are most often defined by a given operation on solutions
- e.g. simple operations
 - Remove/Add an element (cf knapsack)
 - Interchange two or more elements of a solution, e.g. swap two elements (cf TSP)
 - changing the value of one or a few elements in solutions defined as vectors of decision variables

Different neighborhoods

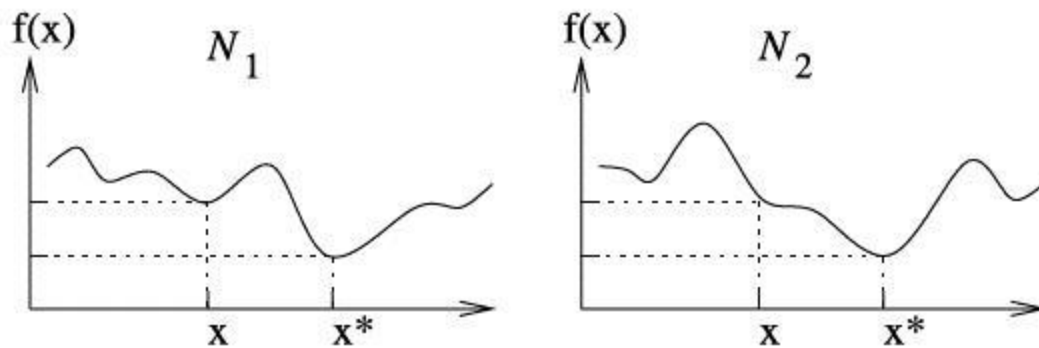
- Different neighborhood operators for same problem:

$$N_{\sigma}(s), \sigma \in \Sigma$$

- e.g. 1-opt and 2-opt for the TSP

- Idea: change dynamically between them

- change in the shape of the “landscape”
 - can help avoiding local minima



Changing the neighborhood from N_1 to N_2

(recall) Terminology: Optima

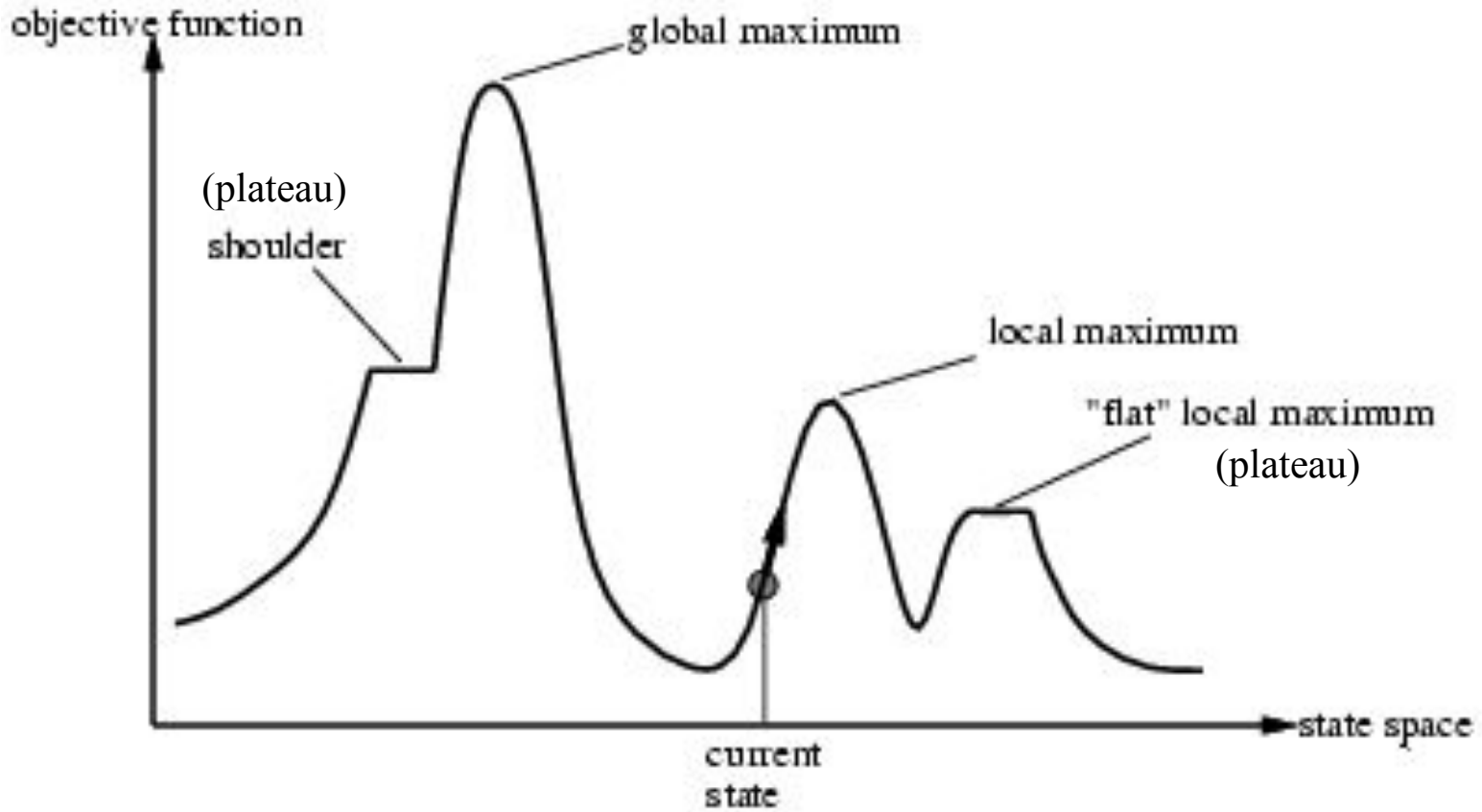
- Assume we want to solve $\max_{x \in \mathcal{F} \subseteq \mathcal{S}} f(x)$
- Let \mathbf{x} be our current (incumbent) solution in a local search
- If $f(\mathbf{x}) \geq f(\mathbf{y})$ for all \mathbf{y} in \mathbf{F} , then we say that \mathbf{x} is a **global optimum** (of f)

(new) Terminology: Optima

- assume that \mathbf{N} is a neighborhood operator, so that $\mathbf{N}(\mathbf{x})$ is the set of neighbors of \mathbf{x}
- If $f(\mathbf{x}) \geq f(\mathbf{y})$ for all \mathbf{y} in $\mathbf{N}(\mathbf{x})$, then we say that \mathbf{x} is a **local optimum**
(of f , with respect to neighborhood operator \mathbf{N})

A neighborhood function \mathbf{N} is **exact** if every local optima w.r.t. \mathbf{N} is also a global optima

Graphically



[from Russell & Norvig 2010]

Example of Local Search : Sorting

- Problem: sort a sequence of numbers from 1 to n
- Consider sequences of numbers in $\{1, \dots, n\}$ as solutions
- Objective function: $f(\pi) = \sum i * \pi_i$ (to maximize)
- This function guarantees that the optimum is the configuration sorted in increasing order
- *K-exchange neighborhood*:
 - Exchanging k elements in a given sequence or partition
- K-exchange neighborhood is exact for sorting
- 1-exchange neighborhood restricted to adjacent pairs

Example of Local Search : Sorting

- Problem: sort a sequence of numbers from 1 to n
- Consider sequences of numbers in $\{1, \dots, n\}$ as solutions
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- *K-exchange neighborhood*:
 - Exchanging k elements in a given sequence or partition
- K-exchange neighborhood is exact for sorting
- 1-exchange neighborhood restricted to adjacent pairs
- This is bubble sort !

(Basic) Bubble Sort Algorithm

`Swapped = false`

`Repeat`

`For i=1 to n-1`

`if (A[i] > A[i+1])`

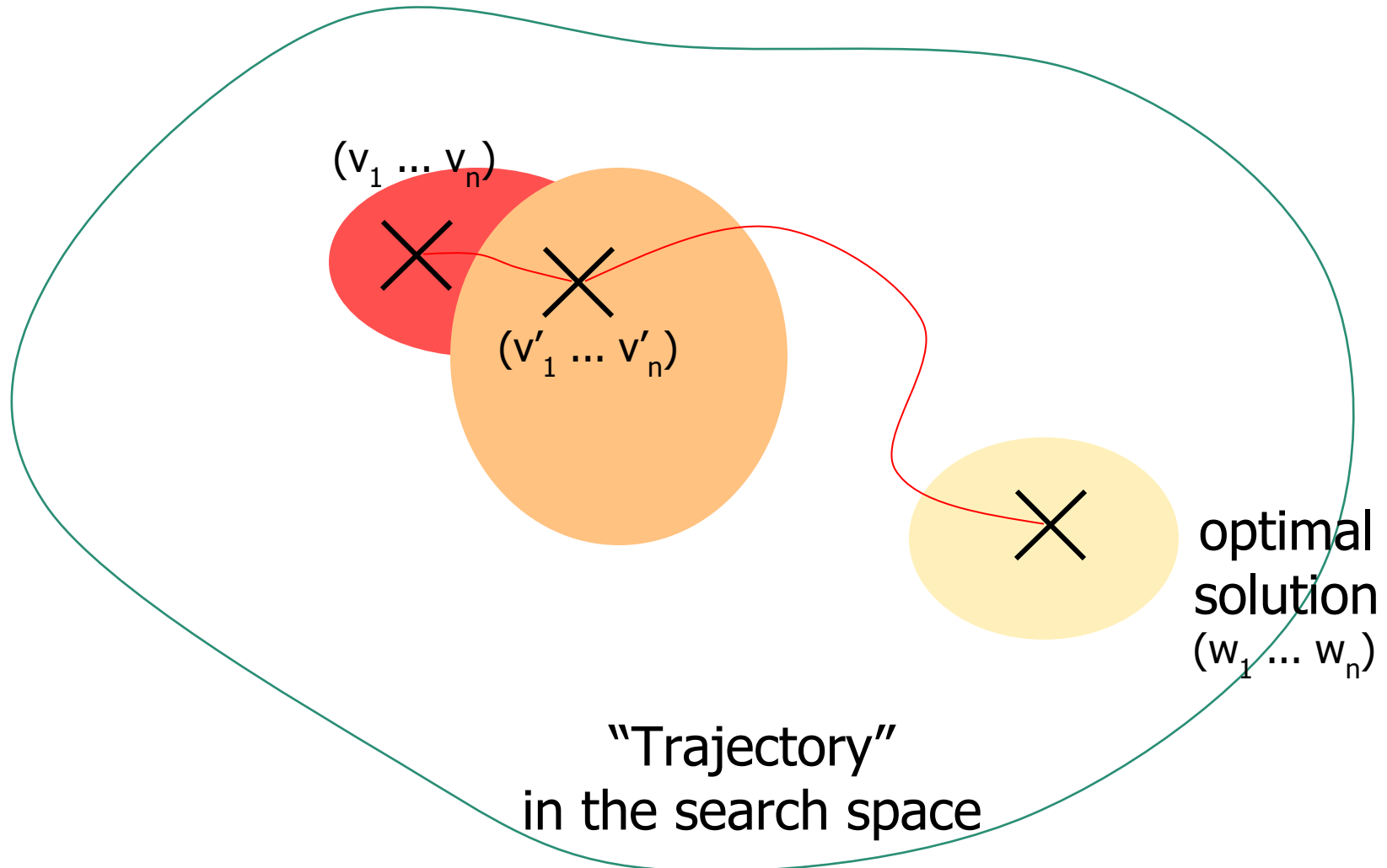
`swap(A[i], A[i+1])`

`swapped = true`

`Until not swapped`

1	2	3	4	5	6
77	42	35	12	101	5

Iterative Improvement



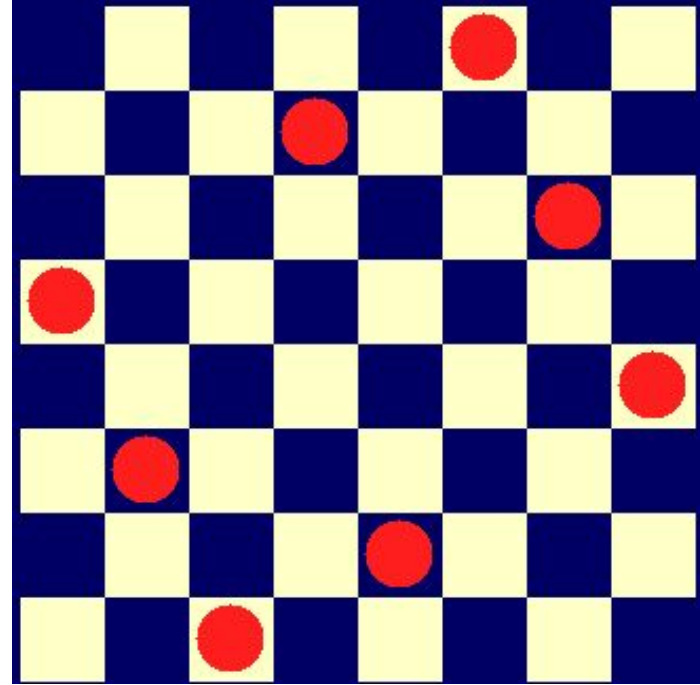
Basic Local Search : Iterative Improvement

```
 $s \leftarrow \text{GenerateInitialSolution()}$   
repeat  
     $s \leftarrow \text{Improve}(\mathcal{N}(s))$   
until no improvement is possible
```

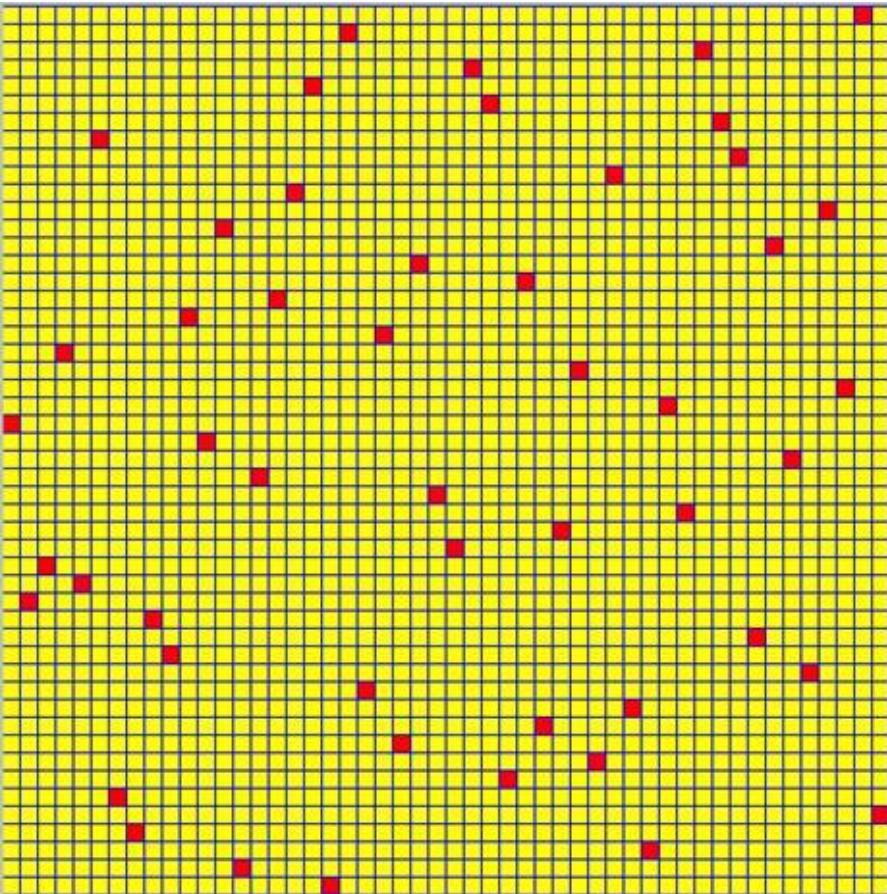
- $\text{Improve}(\mathcal{N}(S))$ can be :
 1. First improvement
 2. Best improvement
 3. Intermediate option, e.g. “Best among n ”
- observation: stops in local optimum

God save the Queens

- Place 8 queens on a chessboard so that no two queens attack each other
- Generalized to NxN chessboard

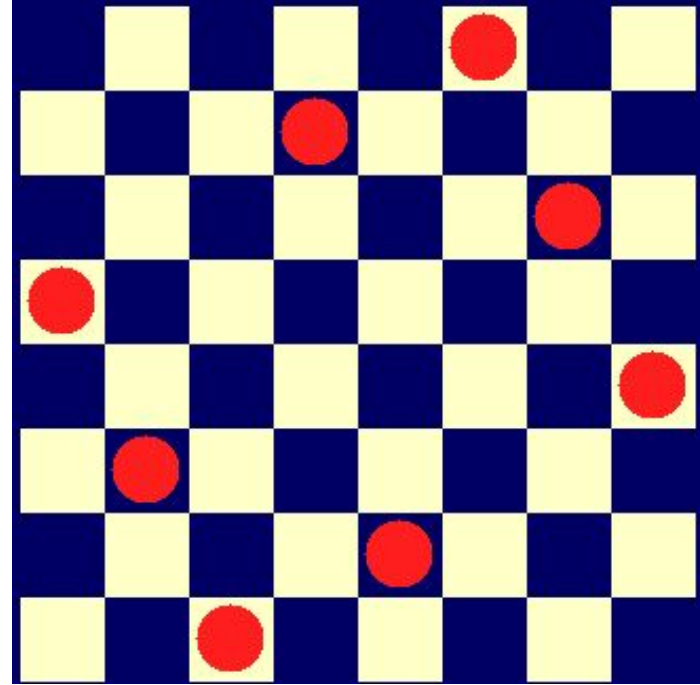


one solution for 50 x 50 chessboard



God save the Queens

- Place 8 queens on a chessboard so that no two queens attack each other
- Generalized to NxN chessboard



one solution for 50 x 50 chessboard

Can we solve this problem
by Local Search ?

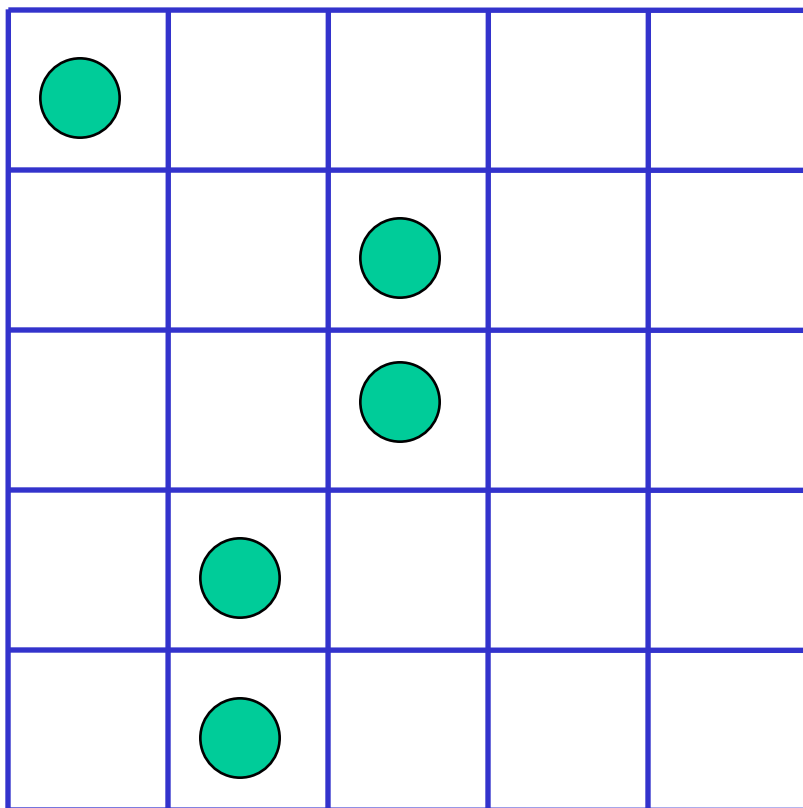
Local Search for N-Queens

- Configuration: (Q_1, \dots, Q_n)
 $Q_i = j$ means queen on row i and column j
- Objective function :
minimize the number of attacks
(= 2 x number of violated disequation constraints)
- Neighborhood operator 1: change the position of one queen (i.e. change value of one Q_i)
- Size of neighborhood: $n \cdot (n-1)$
- At each step there is a quadratic number of neighbors to evaluate...

Local Search for N-Queens (2)

- Neighborhood operator 2:
 - compute for each queen the number of other queens attacking it
 - select the most conflicting queen
 - Consider only its alternative positions as neighbors
- Neighborhood of size $n-1$
- Each step of local search is thus faster
- But... is this a good heuristic?

Example



1

1

3

2






1

8

← cost
for each
queen

← Global cost






Example

				
				
6	7		6	2
				
				

Queen 3 will be selected

Alternative values gives
Other global costs

Example

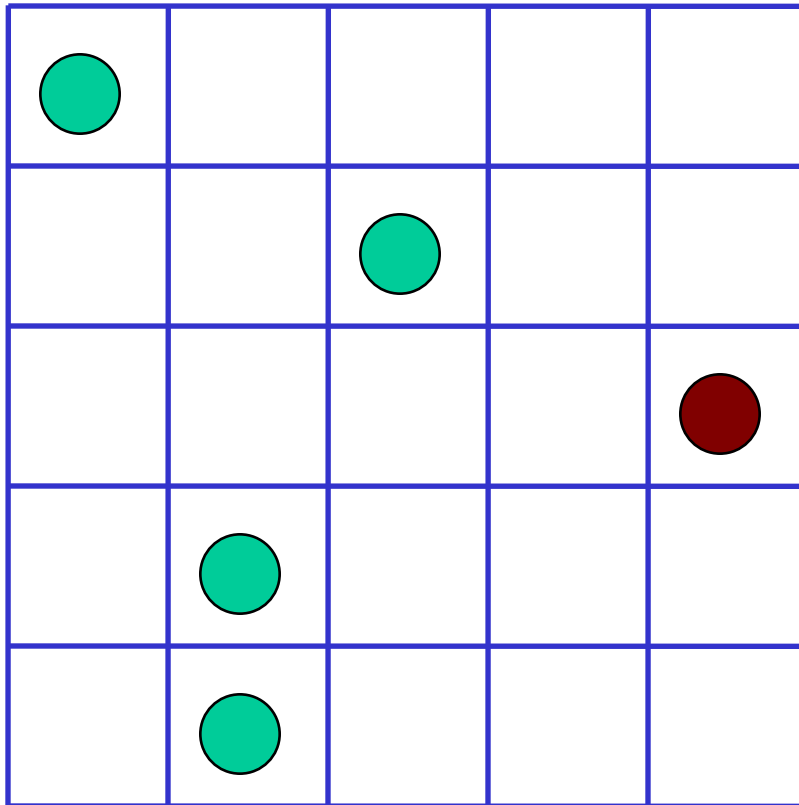
				
				
6	7		6	2
				
				

Queen 3 will be selected

Alternative values gives
Other global costs






Move to row 5 is the best

Example








... and continue !






Example

					0
					0
					0
					1
					1
					<hr/>
					2

Example

					0
					0
					0
					1
1		1	0	1	1

Example

					0
					0
					0
					0
					0
<hr/>					

SOLVED !

Another Model for N-Queens LS

- Another model by considering:
 - permutation of $\{1, \dots, n\}$ as configurations
 - objective function: minimize conflicting queens (diagonals only)
 - Neighborhood: all possible swaps of 2 values

Local Search / Neighborhood Search

- a Combinatorial Optimization Problem (COP)
- an initial solution (e.g. random)
- a defined search neighborhood (neighboring solutions)
- a move operator (e.g. flip a variable), going from one solution to a neighboring solution
- an evaluation function for moves (rating possibilities)
 - often *myopic*
- a neighborhood evaluation strategy (first, best, etc)
 - i.e. a move selection strategy
- a stopping criterion
 - e.g. local optimum

Advantages of Local Search

- For many problems, it is quite easy to design a local search
 - i.e., LS can be applied to almost any problem
- The idea of improving a solution by making small changes is easy to understand
- The use of neighborhoods sometimes makes the optimal solution seem "close", e.g.:
 - A knapsack has n items
 - The search space has 2^n members
 - From *any* solution, no more than n flips are required to reach an optimal solution!

Disadvantages of Local Search

- Some neighborhoods can become very large (time consuming to examine all the neighbors)
- The search stops when no improvement can be found: *local* optimum
- Restarting the search might help, but is often not very effective in itself – needs a strategy!
- How can we **avoid** getting stuck in a **local optimum**?

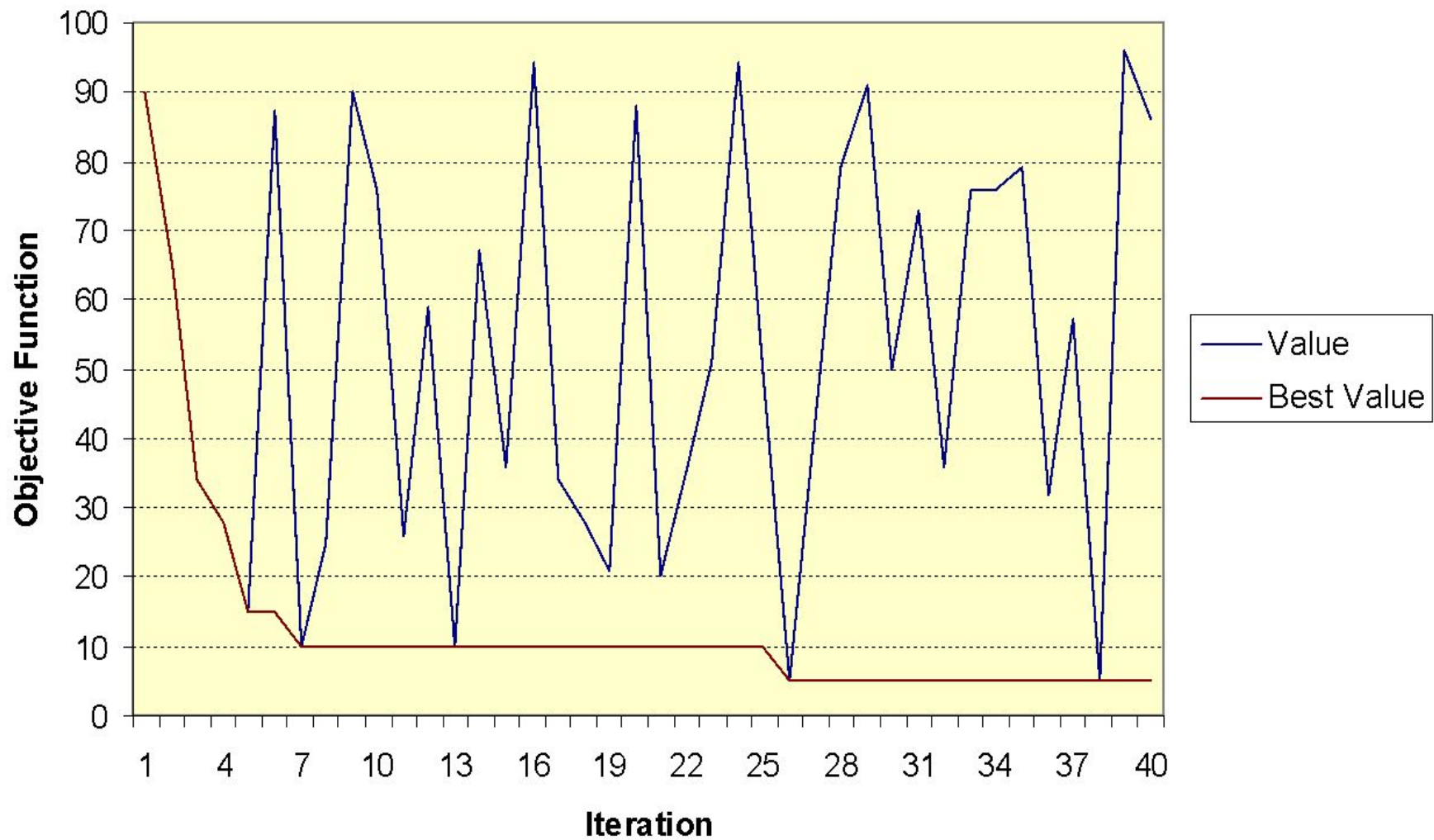
Metaheuristics (1)

- Concept introduced by Glover (1986)
- Generic heuristic solution approach designed to control and guide specific problem-oriented heuristics
- Often inspired by analogy with natural processes
- Rapid development over the last 15 years

Metaheuristics (2)

- Main point is to escape local minima
- Many different ideas:
 - Random restart
 - Accept “bad moves” (i.e. worse w.r.t. objective function)
 - Use memory to record “bad solutions” to be avoided
 - Use a population of solutions
 - Mix any of the above
- This gives a lot of different methods!

Typical Search Trajectory



[From A. Løkketangen]

Some well-known Metaheuristics

- Simulated Annealing (SA)
- Tabu Search (TS)
- Genetic Algorithms (GA)
- Scatter Search (SS)

Other Metaheuristics

- Iterative Local Search (ILS)
- Guided Local Search (GLS)
- Adaptive Memory Procedures (AMP)
- Variable Neighborhood Search (VNS)
- Threshold Acceptance methods (TA)
- Ant Colony Optimization (ACO)
- Greedy Randomized Adaptive Search Procedure (GRASP)
- Evolutionary Algorithms (EA)
- Memetic Algorithms (MA)
- And many others:
 - Particle Swarm, The Harmony Method, The Great Deluge Method, Shuffled Leaping-Frog Algorithm, Squeaky Wheel Optimization, Artificial Bee Colony, Cuckoo Search, Firefly Optimization ...

Metaheuristic Classification

- x/y/z Classification
 - x = A (adaptive memory) or M (memoryless)
 - y = N (systematic neighborhood search)
or S (random sampling)
 - z = 1 (one current solution)
or P (population of solutions)
- Examples
 - Tabu search (A/N/1)
 - Simulated Annealing (M/S/1)
 - Genetic Algorithms (M/S/P)
 - Scatter Search (M/N/P)

Single Solution vs Population-based

- Single-solution based algorithms
 - Hill Climbing
 - Simulated Annealing
 - Tabu Search
- Population based algorithms
 - Genetic Algorithm
 - Ant Colony Optimization
 - Particle Swarm Optimization

Nature inspired vs Non-nature inspired

- Genetic Algorithms
- Swarm Intelligence
 - Ant Colony Optimization
 - Particle Swarm Optimization
- Also
 - Bee Colony Optimization
 - Firefly Optimization
 - Cuckoo Search