Arduino PMBus

Power System Prototyping by Michael Jones Linear Technology

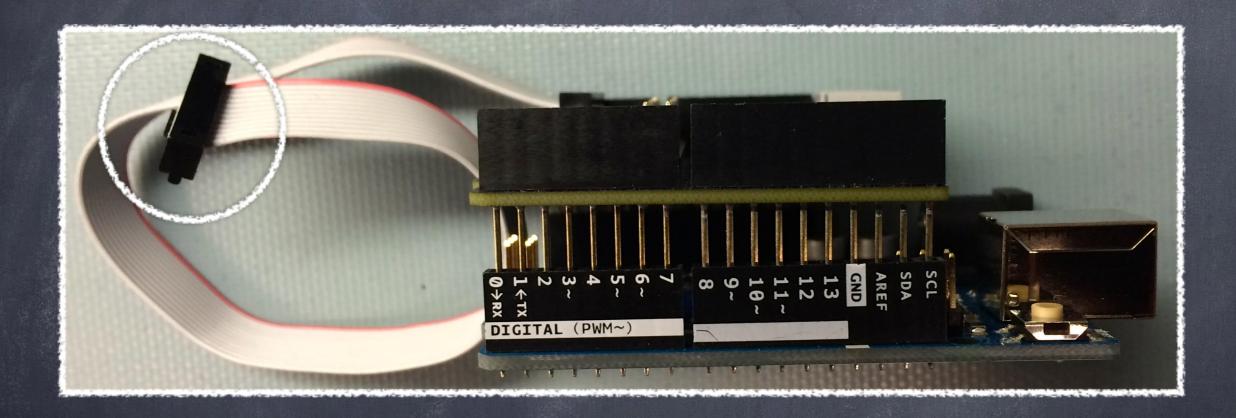
Topics

- What is Arduino?
- How do I connect my PMBus devices?
- Is there a PMBus API I can use?
- How do I organize the code for an API?
- Can it handle block commands and PEC?
- Examples
- Cool Stuff
- Getting Started



Arduino Uno





Connecting

Wires or Shield and Cable

Connecting

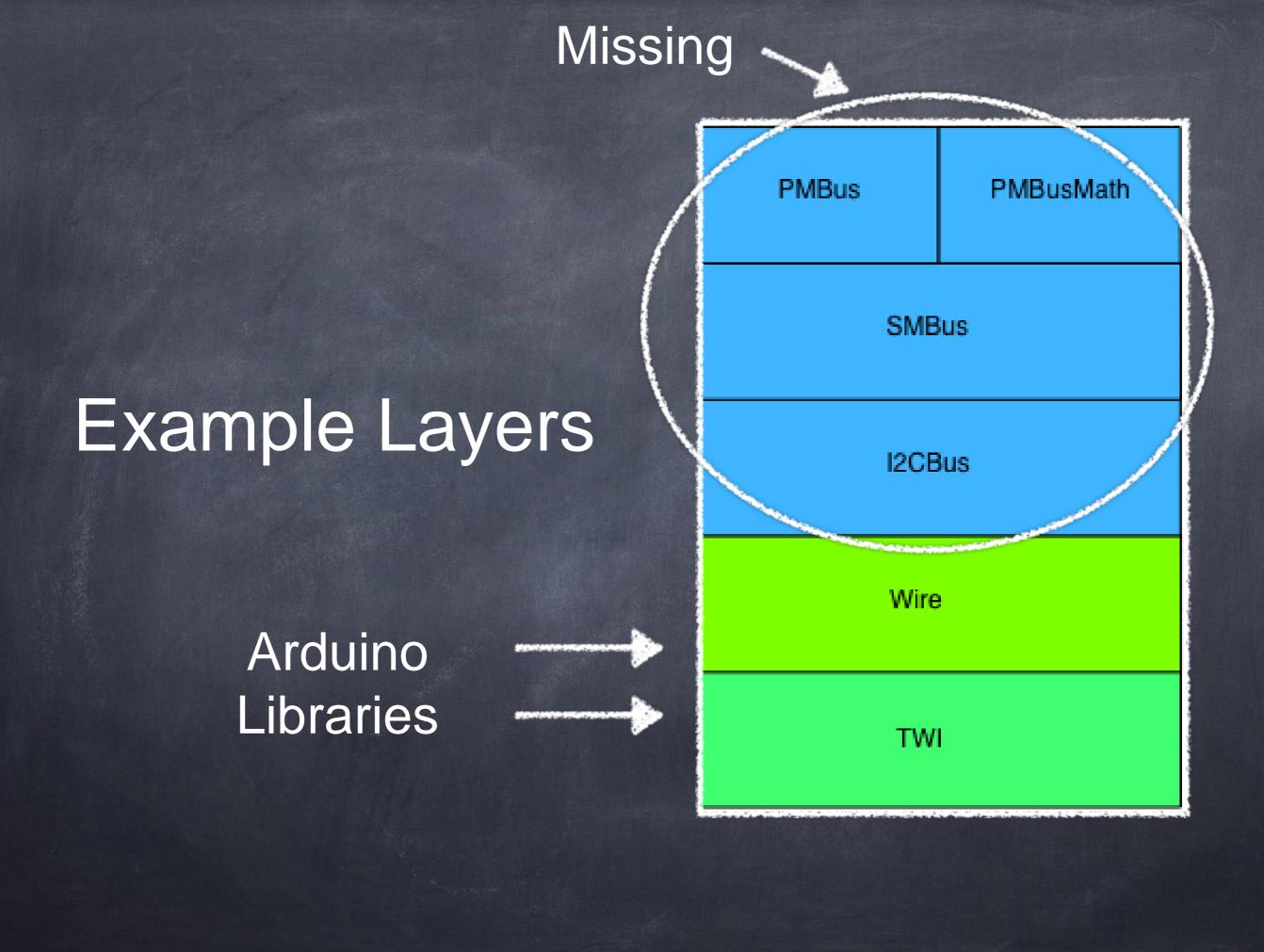
- Long cables add capacitance and/or inductance
- Capacitance limits bus speed
- Inductance and bus accelerators cause communication errors
- Isolation may be desired to break ground loops and protect laptop

PMBus API?

- Arduino has an I2C library, but...
- Arduino does not have SMBus or PMBus API
- Arduino hardware does support SMBus and PMBus protocol

Code Organization

- Layers are your friend
- Makes code portable
- Enables reuse
- Eases maintenance



Arduino Challenges

- Block read/write limited to 32 bytes
- Block API count limited to byte
- TWI not quite an I2C API
- 2K RAM

TWI/Wire Patching

- Pass in buffer for block commands
 - Only use buffer size required
 - Allow deletion of buffer after use
- Allow larger count

Wire Code Changes

Original

Fixed Size

```
#define BUFFER_LENGTH 32
```

```
class TwoWire : public Stream
```

private:

```
static uint8_t rxBuffer[];
static uint8_t rxBufferIndex;
```

static uint8_t rxBufferLength;

uint8_t requestFrom(uint8_t address,

```
8bitint8_t quantity,
uint8_t sendStop
):
```

Modifed

Dynamic Size

I2C/SMBus/PMBus Layers

- SMBus Layer adds:
 - SMB Alert
 - Wait for ACK
 - Bus probe
 - PEC support

- PMBus Layer adds:
 - set commands
 - read commands
 - Hides command codes
 - Data conversion

SMBus API

readAlert writeByte writeBytes readByte writeWord readWord writeBlock writeReadBlock readBlock sendByte waitForAck probe

PMBus API

```
void setVoutWithPage(uint8_t address, //!< Slave address</pre>
                        float voltage, //!< Voltage
                                           //!< PAGE PLUS PAGE
                        uint8_t page
void setVout(uint8_t address, //!< Slave address</pre>
               float voltage
                               //!< Output voltage
void setVoutWithSupervisionWithPage(uint8_t address,
                                                             //!< Slave address
                                           float voltage,
                                                             //!< Voltage
                                           float margin_percent, //!< Amount to margin
                                           float warn_percent, //!< Amount of warning limit
                                           float fault_percent, //!< Amount of fault limit
                                           uint8_t page
                                                                 //!< PAGE PLUS PAGE
void setVoutWithSupervision(uint8_t address,
                                                  //!< Slave address
                                                  //!< Voltage
                                 float voltage,
                                 float margin_percent, //!< Amount to margin
                                 float warn_percent, //!< Amount of warning limit
                                 float fault_percent //!< Amount of fault limit
                                 );
```

PMBus Code

```
void LT_PMBus::setVout(uint8_t address, float voltage)
{
    uint16_t vout;

    LT_PMBusMath::lin16_t exp;
    exp = (int8_t)(smbus_.readByte(address, VOUT_MODE) & 0x1F);
    vout = math_.float_to_lin16(voltage, exp);

smbus_.writeWord(address, VOUT_COMMAND, vout);
}
```

Generic code has cost

Programmers like float

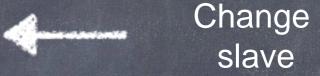
What should application code look like?

```
void print_all_voltages()
 float voltage;
 uint8_t page;
 for (page = 0; page < 2; page++)
  pmbus->setPage(ltc3830_i2c_address, page);
  voltage = pmbus->readVout(ltc3880_12c_address, false);
  Serial.print(F("LTC3880 VOUT"));
  Serial.println(voltage, DEC);
```

Hide the details

What can C++ do?

```
case 2:
    pmbus->enablePec(ltc3880_i2c_address);
    pmbus->enablePec(ltc2974_i2c_address);
    pmbus->enablePec(ltc2977_i2c_address);
  delete smbus;
  delete pmbus;
    smbus = new LT_SMBusPec();
    pmbus = new LT_PMBus(smbus);
    break;
   case 3:
    pmbus->disablePec(ltc3880_i2c_address);
    pmbus->disablePec(ltc2974_i2c_address);
    pmbus->disablePec(ltc2977_i2c_address);
  delete smbus;
  delete pmbus;
    smbus = new LT_SMBusNoPec();
    pmbus = new LT_PMBus(smbus);
    break;
```





API unaffected by PEC mode

What is a Sketch?

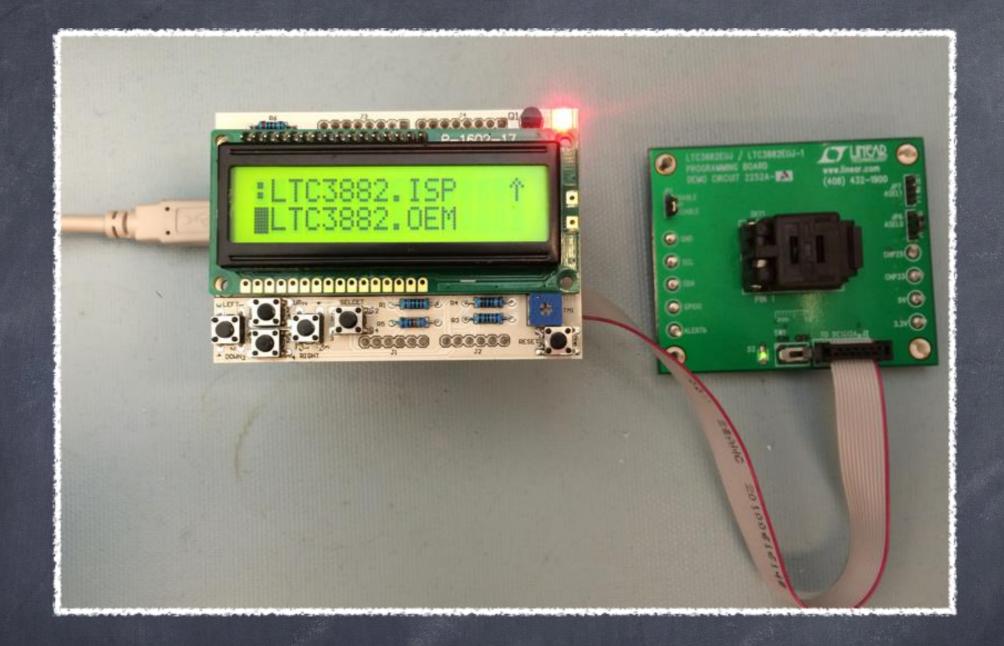
- Application code with main(...)
- Example to study and copy
- Cool tool...

```
hello_world | Arduino 1.0.6
  hello world
static uint8_t ltc3880_i2c_address;
static uint8_t ltc2974_i2c_address;
static uint8_t ltc2977_i2c_address;
static LT_SMBus *smbus = new LT_SMBusPec();
static LT_PMBus *pmbus = new LT_PMBus(smbus);
//! Initialize Linduino
void setup()
 Serial begin(115200);
                                //! Initialize the serial port to the PC
 print_title();
 ltc3880_i2c_address = LTC3880_I2C_ADDRESS;
 ltc2974_i2c_address = LTC2974_I2C_ADDRESS;
 ltc2977_i2c_address = LTC2977_I2C_ADDRESS;
 print_prompt();
//! Repeats Linduino Loop
void loop()
 uint8_t user_command;
 uint8_t res;
 uint8_t model[7];
 uint8_t revision[10];
 uint8_t *addresses = NULL;
  if (Serial.available())
                                                    //! Checks for user input
                                      Arduino Robot Control on /dev/tty.usbmodem1411
```

Init statics
Called once
Runs forever

Sketch

Arduino Sketch Editor with PMBus Code



Cool Stuff

Device EEPROM Programmer

"Classic engineering relies on a strict process for getting from A to B; the Arduino Way delights in the possibility of getting lost on the way and finding C instead."

-Arduino Way

How to Get Lost...

http://arduino.cc/en/Guide/HomePage