

Corey Koehler

(626) 664-0629 | coreyskoehler@gmail.com | coreyskoehler.com | linkedin.com/in/coreyskoehler

Work Experience

KBR (formerly LinQuest): Senior Software Engineer

August 2023 — Present

Albuquerque, NM

- Led team of 3 developers in an 8-month C++ plugin development to deliver higher-fidelity GPS modeling tools to government customer, enabling study of state-of-the-art GPS receivers in defense simulations
- Implemented 40+ API commands to expand the plugin's configuration options beyond customer expectations, leading to open-source community release and adoption by 4 government research teams
- Optimized simulation architecture to achieve 100+ GPS location computations per second, a 6x improvement over baseline AFSIM (aerospace simulation software), enabling real-time processing for large-scale government simulations
- Developed C++ and Python data processing pipelines to visualize 100 million GPS data point metrics across multiple simulation projects
- Redesigned government customer's SysML-to-simulation development workflow, reducing development errors and cutting project timelines by 3 weeks (50% faster delivery)
- Increased data transfer rates by 10x and message routing coverage by 150% over legacy methods in satellite communication simulation by developing custom communication routing protocols

NASA Jet Propulsion Laboratory (JPL): Software Developer Intern

June 2020 — August 2020

Pasadena, CA

- Developed full-stack laboratory management system using Python (Flask, SQLite3, and Bootstrap) to streamline equipment scheduling and logistics coordination in 20+ research laboratories
- Built real-time monitoring dashboard with 100+ live-updating Matplotlib visualizations, displaying insights from user-collected data and enabling proactive lab environment management

Acubit 3D-SensIR Inc: Software Developer Intern

June 2019 — August 2019

Santa Clarita, CA

- Engineered C++ visualization and object detection pipeline using PCL and ROS for proprietary LIDAR camera system, enabling real-time 3D point cloud processing and analysis
- Integrated computer vision algorithms with the Trinity Robotics automated pallet system to eliminate the need for manual technician calibration, achieving 95% keypoint detection accuracy during setup routines

Education

University of California, Berkeley

August 2019 — August 2023

B.A. Computer Science, B.A. Applied Mathematics

Technical Skills

Programming

C++, Python, C, SQL, JavaScript

Libraries:

Matplotlib, Pandas, GoogleTest, Node.js

Tools:

Visual Studio, CMake, Jira, Git

Clearance

TS/SCI

(Top Secret/Sensitive Compartmented Information)

June 2024— Present