

speed + green + yellow car-len space thresh acc

if space \geq thresh:

$$i \cdot d_{\text{hood-to-hood}} = d_{\text{total}}$$

$$i = \frac{d_{\text{total}}}{d_{\text{hood}}}$$

$$\text{let } \sqrt{i}$$

$$t_{\text{total}} = t_{\text{green}} + t_{\text{yellow}}$$

$$t_{\text{to-limit}} = \text{speed} / \text{acc}$$

$$t_{\text{acc}} = \text{min}(t_{\text{total}}, t_{\text{to-limit}})$$

$$t_{\text{limit}} = t_{\text{total}} - t_{\text{acc}}$$

$$d_{\text{hood-to-hood}} = \text{space} + \text{car-len}$$

$$d_{\text{acc}} = \frac{1}{2} \text{acc} \cdot t_{\text{acc}}^2$$

$$d_{\text{to-go-th}} = \text{thresh-space} \quad d_{\text{limit}} = \text{speed limit}$$

if $d_{\text{to-go...}} < d_{\text{acc}}$:

$$t_{\text{delay}} = i \sqrt{2 \frac{d_{\text{to-go}}}{\text{acc}}} \quad (i_{\text{react}} + i_{\text{react}})^2$$

$$t_{\text{to-plane}} =$$

$$\hookrightarrow i(d_{\text{hood...}}) = \frac{1}{2} \text{acc} \cdot t_{\text{acc}}^2$$

$$\sqrt{2 \frac{i(d_{\text{hood...}})}{\text{acc}}} = t$$

$$\text{to plane } t(i) = i \sqrt{2 \frac{d_{\text{to-go}}}{\text{acc}}} + \sqrt{\frac{2i(d_{\text{hood...}})}{\text{acc}}} + (i_{\text{react}}^2 + i_{\text{react}} t_{\text{acc}})$$

$$\max_i t_{\text{total}} \leq \sqrt{2 \frac{i^2(d_{\text{to-go}})}{\text{acc}}} + \sqrt{\frac{2i(d_{\text{hood...}})}{\text{acc}}} + (i_{\text{react}}^2 + i_{\text{react}} t_{\text{acc}})$$

$$\frac{\text{acc} (t_{\text{total}})^2}{2} \geq i^2 (d_{\text{to-go}}) + i(d_{\text{hood...}}) \quad (\text{thresh-space}) \quad (\text{space} + \text{car-len})$$

$$\text{space} = \text{car-len}$$

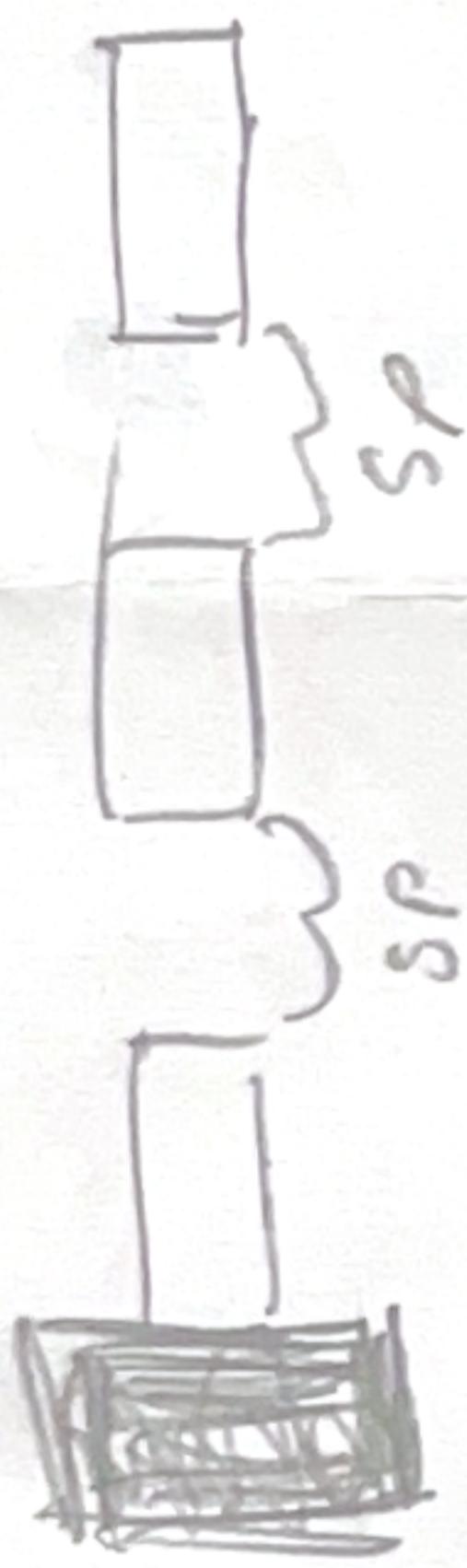
$$\sqrt{\frac{\text{acc} (t_{\text{total}})^2}{2 \text{thresh}}}$$

$$i^2 \text{thresh} - i \text{space} + i \text{car-len}$$

$$i(i_{\text{thresh}} - \text{space} + \text{car-len})$$

~~Diagram~~

$$2\sqrt{(\frac{c^2 T_i + D_i}{2})^2 - D_i^2} = t_{\text{total}}^2$$



$$2\sqrt{(t_{\text{total}}^2 + D_i^2)} = t_{\text{total}}^2 + (t_{\text{h-sp}})$$

wait for the SP

$$\begin{aligned} \frac{a(t_{\text{total}}^2)}{2} &= i^2 T_i + D_i^2 \quad \text{with car till go} \\ A &:= \frac{a \frac{t_{\text{total}}^2}{2}}{2} + t_{\text{h-sp}} \\ 0 &= T_i^2 + D_i^2 + A \\ \text{no } &\text{time to dist: } (c_{\text{len}} + S_p) \end{aligned}$$

time for car to cross plane

$$i \cdot \text{till-go}(i) + \text{to-plane}(i)$$

time to acc ~~acc~~ A

$$i =$$

$$\begin{aligned} \text{to-plane}(i) &:= \\ D &= c_{\text{len}} + S_p \\ \text{time to acc } &D \end{aligned}$$

$$\begin{aligned} i &= \sqrt{\frac{2}{a} + \sqrt{\frac{2D}{a}}} \\ D &= t_{\text{total}} - (\text{delay} + t(R_i)) \end{aligned}$$

$$\sqrt{\frac{2T}{a} + \sqrt{\frac{2D_i}{a}}} = t_{\text{total}}^2$$

$$\sqrt{2D_i} = \frac{2T}{a} t^2$$

$$\frac{t_{acc} t_{total}^2}{\sqrt{d_{car}}}$$

$$= i^2 d_{stop} + i d_{head}$$

$$t_{total} = \begin{cases} \text{if } dec > d_{stop} : i \sqrt{\frac{2(d_{stop})}{acc}} \\ \text{else} : i(t_{acc} + \frac{(d_{stop} - d_{acc})}{\text{Speed limit}}) \end{cases}$$

$$\begin{cases} \text{if } i(d_{car}) < d_{acc} : i \frac{\sqrt{2(i)d_{car}}}{acc} \\ \text{else} : t_{acc} + \frac{(i(d_{car}) - d_{acc})}{\text{Speed limit}} \end{cases}$$

$$t_{total}^2 = \frac{i^2 2 d_{stop}}{acc} \text{ or } i^2 (t_{acc} + \frac{d_{stop} - d_{acc}}{\text{Speed limit}})^2$$

$$t_{acc}^2 + \frac{2 t_{acc} \left(\frac{(i d_{car}) - d_{acc}}{sp} \right)^2}{acc} + \frac{(t_{acc} + \frac{(i d_{car}) - d_{acc}}{sp})^2}{acc} =$$

$$t_{acc}^2 + \frac{2 t_{acc} \left(\frac{(i d_{car}) - d_{acc}}{sp} \right)^2}{acc} + \frac{(sp(t_{acc}) + (i d_{car}) - d_{acc})^2}{acc}$$

$$\frac{222}{150 + p_1} = 9 \quad \frac{222}{150 + p_2} = 2$$

$$F_0 = \frac{d}{dt} \frac{d}{dt} \frac{d}{dt}$$

time

way

$$\int \frac{2 d_{\text{to-go}}}{acc} \quad \text{acc} \rightarrow \frac{t_{\text{tot}}}{acc}$$

~~$\frac{2(d_{\text{to-go}})}{acc}$~~

~~$\frac{acc}{2acc}$~~

$$\left. \begin{aligned} & acc(1) - t_{\text{tot}} \text{ go-thresh} \\ & acc(2) + t_{\text{tot}} \text{ plane} \end{aligned} \right\}$$

$$acc(1) - t_{\text{tot}} \text{ go}$$

$$acc(2) + t_{\text{tot}} \text{ plane}$$

0 ..

$$time := \sqrt{\frac{2 d_{\text{to-go}} + \cancel{\frac{acc}{acc}}}{acc}}$$

~~total time~~

~~total time~~

$$\theta = \frac{2 i^2 (d_{\text{to-go}}) + 2 (l d_{\text{to-go}})}{acc} - t_{\text{tot}} l^2$$

$$a = \frac{2 d_{\text{to-go}}}{acc} \quad b = \frac{2 d_{\text{to-go}}}{acc} \quad c = \frac{t_{\text{tot}} l^2}{acc}$$

$$t_{\text{total}} = \sqrt{\frac{2d_{\text{to-go}}}{a_{\text{acc}}} + \frac{2i_{\text{d_car}}}{a_{\text{acc}}}}$$

$$\frac{d_{\text{acc}} - d_{\text{to-go}}}{a_{\text{acc}}} = \frac{(d_{\text{car}}) - d_{\text{acc}}}{\text{limit}}$$

$$\Leftrightarrow i \left(t_{\text{acc}} + \frac{d_{\text{to-go}} - d_{\text{acc}}}{\text{limit}} \right) + \sqrt{\frac{2i_{\text{d_car}}}{a_{\text{acc}}}}$$

$$\Leftrightarrow i \left(t_{\text{acc}} + \frac{d_{\text{to-go}} - d_{\text{acc}}}{\text{limit}} \right) + \left(t_{\text{acc}} + \frac{i_{\text{d_car}} - d_{\text{acc}}}{\text{limit}} \right)$$

$$i A + t_{\text{acc}} + \frac{i_{\text{d_car}} - d_{\text{acc}}}{\text{limit}}$$

$$i \left(\min \left(\sqrt{\frac{2d_{\text{to-go}}}{a_{\text{acc}}}}, t_{\text{acc}} \right) + \max (0, \frac{d_{\text{to-go}} - d_{\text{acc}}}{\text{limit}}) \right)$$

$$\min \left(\sqrt{\frac{2i_{\text{d_car}}}{a_{\text{acc}}}}, t_{\text{acc}} \right) + \max (0, \frac{i_{\text{d_car}} - d_{\text{acc}}}{\text{limit}})$$

$d_{\text{to-go acc}}$

t_{acc}

$d_{\text{car total}} / \text{init}$

d_{acc}

22 2 10 30 | 22

6 36

$$T(x) = \frac{x}{\cancel{r_{\text{acc}}} + \frac{\cancel{r_{\text{acc}}}}{2 + \frac{r_{\text{acc}}}{2}} + \frac{\cancel{r_{\text{acc}}}}{\cancel{r_{\text{acc}}} - \frac{r_{\text{acc}}}{2}}} + \frac{\cancel{r_{\text{acc}}}}{\cancel{r_{\text{acc}}} - \frac{r_{\text{acc}}}{2}} x = (x) + Q^s + r_{\text{acc}} x$$

cargo to
total time

what is time at

burned

rest



$d_{\text{to-go}} - ($

2

0

1

$$\Rightarrow a = \frac{2 d_{-to-go}}{\text{acc}} \quad b = \frac{2 d_{-car}}{\text{acc}} \quad c = -t_{\text{total}}^2$$

$$\Rightarrow m = \sqrt{\frac{2 d_{-to-go}}{\text{acc}} + \frac{d_{-car}}{\text{limit}}} \quad b = -t_{\text{total}} + t_{\text{acc}} - \frac{d_{-acc}}{\text{limit}}$$

$$\left\langle \begin{array}{l} \\ \end{array} \right. a = \left(t_{\text{acc}} + \frac{d_{-to-go} - d_{\text{acc}}}{\text{limit}} \right)^2 \quad b = \frac{2 d_{-car}}{\text{acc}} \quad c = -t_{\text{total}}^2$$

$$\left\langle \begin{array}{l} \\ \end{array} \right. M = \left(t_{\text{acc}} + \frac{d_{-to-go} - d_{\text{acc}}}{\text{limit}} \right) + \frac{d_{-car}}{\cancel{\text{limit}}} \quad b = -t_{\text{total}} + t_{\text{acc}} - \frac{d_{\text{acc}}}{\text{limit}}$$

$$O = m \times b \quad x = \frac{-b}{m}$$

$$O = ax^2 + bx + c \quad x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

$$d_{\text{acc}} \square d_{\text{to-go}}$$

$$d_{\text{acc}} \square i \neq d_{\text{car}} \Rightarrow i \boxed{\square} \frac{d_{\text{acc}}}{d_{\text{car}}}$$

$$\frac{\frac{1}{2} \text{acc } t_{\text{acc}}^2}{\text{space} + \text{carlen}}$$

